

Lecture 19: Many Lights

Fall 2004
Kavita Bala
Computer Science
Cornell University

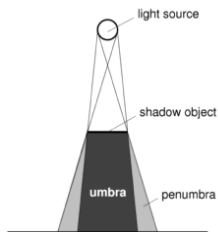
Announcements

- HW 3 out
 - Due next Friday

© Kavita Bala, Computer Science, Cornell University

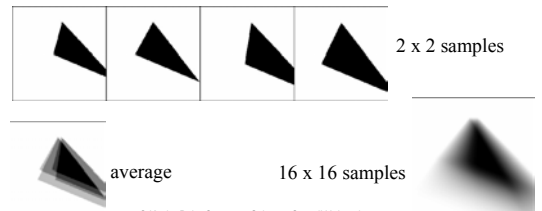
Soft Shadows

- Soft shadows appear natural
- Hard to get soft shadows in hardware
- Slow in software



Heckbert and Herf

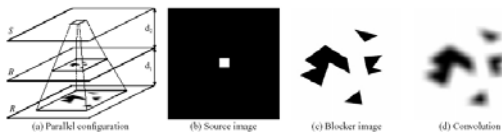
- Use accumulation buffer
- Render shadows from multiple point lights over the area light (like MC)
- Accumulate shadows



© Kavita Bala, Computer Science, Cornell University

Soler and Sillion

- Shadows as convolution



© Kavita Bala, Computer Science, Cornell University

Penumbra Maps

- Wyman and Hansen
- Use shadow map and Haines technique for soft shadows on arbitrary surfaces
- Penumbra map
- Stores intensity of shadow
- Overall:
 - 3 pass: shadow map and penumbra map
 - Render image using depth from shadow map and intensity from penumbra map

© Kavita Bala, Computer Science, Cornell University

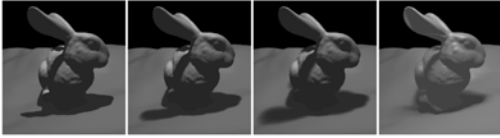


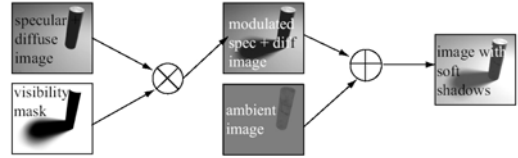
Figure 7: Comparison of the Stanford Bunny with shadow maps (left), penumbra maps with two different sized lights (center), and a pathtraced shadow using the larger light (right). For this data set, we generate shadows using a 10k polygon model and render the shadows onto the full (~70k polygon) model.



Figure 8: Using a standard shadow map results in hard shadows (left), add a penumbra map to get soft shadows (right). Using a 10k polygon dragon model for the shadows and a 50k polygon model to render, we get 14.5 fps at 1024x1024.

Geometry-Based Soft Shadow Volume

- Assarsson and Moller
- Shadow volume approach

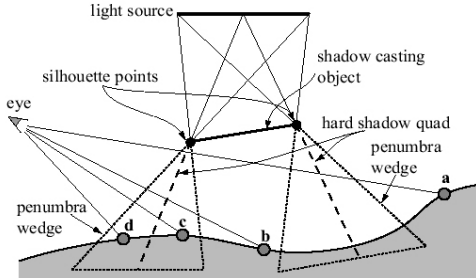


V-buffer stores visibility factor [0,1]

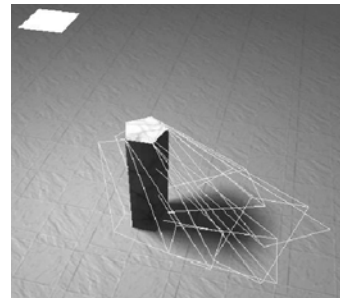
© Kavita Bala, Computer Science, Cornell University

Computing Visibility: 2 passes

- Shadow volume quads are rendered into the V-buffer: overestimates umbra
- Penumbra wedges are rendered to compensate



Method Details: Wedge Example



512 x 512 at 5 FPS (software)

© Kavita Bala, Computer Science, Cornell University

Visibility Passes

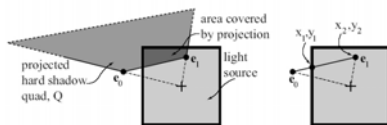
Pass 1: Render shadow volume quads

Pass 2: Compute visibility for each pixel inside the shadow wedges:

Point $p = (x, y, z)$: find visibility of p

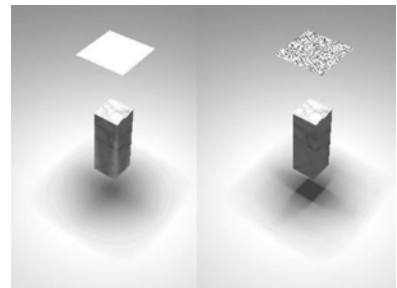
Precompute 4D coverage textures to accelerate visibility computation

Can handle textured lights, video textures



Assumptions

- Silhouettes are constant
- Overlapping objects



Results

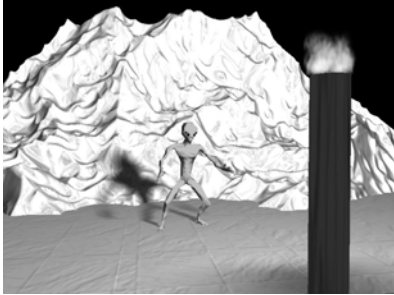


Image of fire used as light source

© Kavita Bala, Computer Science, Cornell University

Results



Soft Shadow Volume

256 Samples

1024 Samples

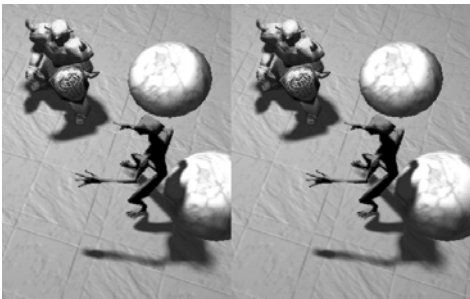
Resolution: 512 x 512 @ 0.14 FPS

100 x 100 @ 3.00 FPS

256 x 256 @ 0.51 FPS

© Kavita Bala, Computer Science, Cornell University

Results



Software Implementation

Hardware Implementation

© Kavita Bala, Computer Science, Cornell University

Summary

- Hard shadows
 - Adaptive shadow maps
 - Edge-and-point rendering
 - Silhouette shadow maps
 - ...
- Soft shadows
 - Accumulation Buffer
 - Convolution
 - Penumbra Maps
 - Penumbra Wedges
 - ...

© Kavita Bala, Computer Science, Cornell University

Many Lights

Motivation

- Most techniques work for single light source
- Many light sources
 - Treat it as a single integration domain
 - Importance sample lights
 - Importance sampling (with visibility) still hard problem

© Kavita Bala, Computer Science, Cornell University

Research on many lights

- Ward '91
- Shirley, Wang, Zimmerman '94
- Fernandez, Bala, Greenberg '02
- Wald and Slusallek '03
- Environment Map Sampling...

© Kavita Bala, Computer Science, Cornell University

Ward '91

- Many lights in RADIANCE
- But all contributions not important
 - Ignore some lighting at a point
 - User-defined cutoff: $x\%$
 - Sort lights according to potential contribution
 - Include G , cosine, L
 - EXCLUDE visibility

© Kavita Bala, Computer Science, Cornell University

Ward '91

- Go through sorted list from the biggest potential contribution
 - Keep running count of visible contribution: V
 - Remainder of list (if fully visible) = R
 - Stop if $R < x\%$ of V



© Kavita Bala, Computer Science, Cornell University

Ward '91

- But just can't ignore remainder R
- Estimate remainder using visibility statistics from previous shadow tests: hack!
- Performance: 2x to 5x
- But, requires computing all potential contributions
 - Can be expensive for many lights

© Kavita Bala, Computer Science, Cornell University

Shirley, Wang, Zimmerman '94

- Try to avoid linear cost of evaluating lights
- Separate lights into
 - Set of important lights (a small set)
 - Set of "dim" lights (large set)
- Construct pdf using:
 - all important lights
 - 1 out of all the dim lights
- Importance sample these lights

© Kavita Bala, Computer Science, Cornell University

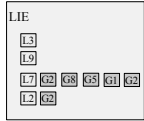
Shirley, Wang, Zimmerman '94

- Region of influence for important lights
 - Octree cells in region of influence have light in important set
- However, the partitioning into important and dim sets remains hard
- Also, still are not taking visibility into account

© Kavita Bala, Computer Science, Cornell University

Fernandez, Bala, Greenberg '02

- Local Illumination Environment (LIE): lights and blockers that affect octree cell

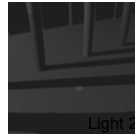
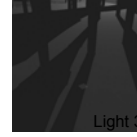


Takes visibility into consideration!

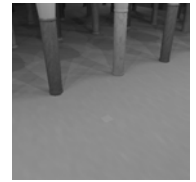
© Kavita Bala, Computer Science, Cornell University

Fernandez, Bala, Greenberg '02

- All lights/shadows are not visually important
- Weber's law: 2% cutoff



...



© Kavita Bala, Computer Science, Cornell University

Using Masking

- Bright lights can mask out shadow details
- Weber's Law: variations in lighting are not visible if ambient lighting is bright enough
 - Conservative: 2% cutoff
- LIE: remove relatively dim lights (fully/partially visible)
 - Cheaper shading
 - Maximum light contribution < 2% of dimmest point in cell
 - Actually, cumulative maximum light contribution < 2% of dimmest point in cell

© Kavita Bala, Computer Science, Cornell University

Using Masking

Remove from LIE if cumulative maximum light contribution < 0.02x40

| | Light 1 | Light 2 | Light 3 | Light 4 | Light 5 | Total |
|---------|----------------|----------------|---------|---------|---------|-------|
| Point 1 | 0 | 0.1 | 16 | 30 | 20 | 66.1 |
| Point 2 | 0 | 0 | 17 | 0 | 25 | 42 |
| Point 3 | 0.1 | 0.1 | 9.8 | 12 | 18 | 40 |
| Point 4 | 0.1 | 0.5 | 14 | 32 | 23 | 69.6 |
| Max | 0.1 | 0.5 | 17 | 32 | 25 | |
| Sorted | 0.1 | 0.5 | 17 | 25 | 32 | |

© Kavita Bala, Computer Science, Cornell University

Fernandez, Bala, Greenberg '02

Without Masking With Masking



Image

Cost

Cheap Expensive

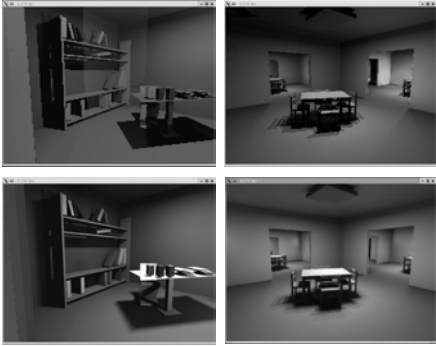
© Kavita Bala, Computer Science, Cornell University

Wald Slusallek '03

- PDF for sampling visible lights in interactive setting
 - Assume significant occlusion
 - Each room influenced by few lights
- 2-step algorithm (every frame)
- 1st step: Determine important (unoccluded) lights by crude path tracing
- 2nd step: Importance samples these lights
 - Completely ignore (probably) occluded lights

© Kavita Bala, Computer Science, Cornell University

Wald Slusallek '03



© Kavita Bala, Computer Science, Cornell University

Rendering w/ Environment Maps

- High lighting complexity



- Rich: captures real world

© Kavita Bala, Computer Science, Cornell University

Ambient Occlusion

- Interactive hardware rendering with many lights?
- Traditionally “fake” diffuse illumination using an ambient term
- But this just results in a constant addition
- Ambient occlusion adds some visibility to the fake diffuse illumination

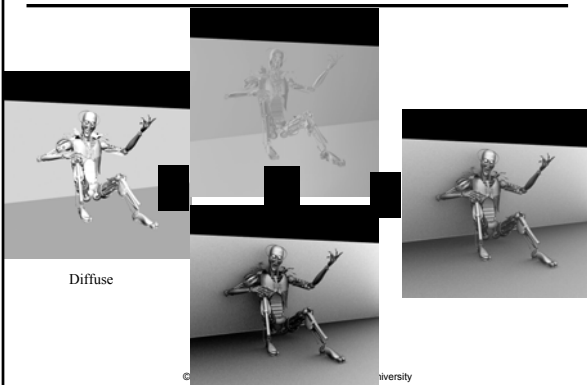
© Kavita Bala, Computer Science, Cornell University

Ambient Occlusion

- Pre-compute the ambient term
- At each vertex, shoot rays over hemisphere (cosine weighted)
 - MC sampling: sample hemisphere
- Does it hit a surface or escape? Compute average visibility ($V = 1 - \text{hits/samples}$)
- Ambient Out = Ambient In * V

© Kavita Bala, Computer Science, Cornell University

Ambient Occlusion Example



© Kavita Bala, Computer Science, Cornell University

Problem

- Can move object around without deforming it
- But, slow!
- How to render interactively with many lights?
 - Open question

© Kavita Bala, Computer Science, Cornell University