Lecture 17: Shadows

Fall 2004 Kavita Bala Computer Science Cornell University

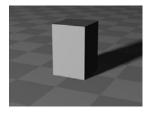
Projects

- · Proposals due today
- · I will mail out comments
- Grading HW 1: will email comments asap

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Why Shadows?

· Crucial for spatial and depth perception



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Shadows

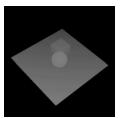
Methods for fast shadows:

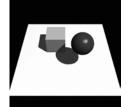
- · Shadow Maps
- · Shadow Volumes

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Shadow Maps

- Introduced by Lance Williams (SIGGRAPH 1978)
- · Render scene from light's view
 - black is close, white is far

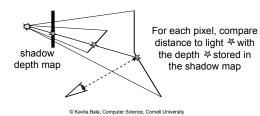




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Using the Shadow Map

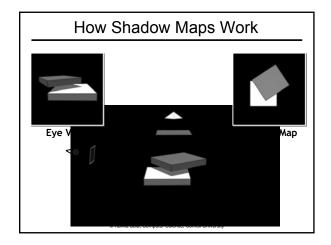
- When scene is viewed, check viewed location in light's shadow buffer
 - If point's depth is (epsilon) greater than shadow depth, object is in shadow



Shadow Mapping: Pass 1

- Depth testing from light's point-of-view
 - Two pass algorithm
- First, render depth buffer from light's point-of-view
 - Result is a "depth map" or "shadow map"
 - A 2D function indicating the depth of the closest pixels to the light
 - This depth map is used in the second pass

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How Shadow Maps Work Eye V Map

Shadow Mapping: 2nd pass

- Second, render scene from the eye's point-ofview
- · For each rasterized fragment
 - determine fragment's XYZ position relative to the light
 - this light position should be setup to match the frustum used to create the depth map
 - compare the depth value at light position XY in the depth map to fragment's light position Z

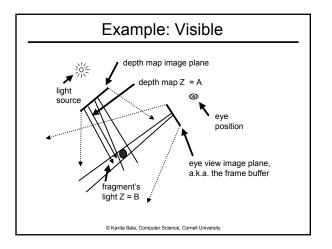
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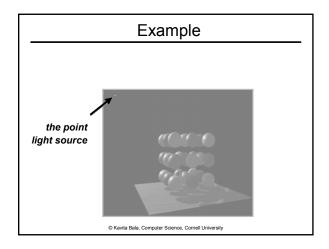
Shadow Mapping: Comparison

- Two values
 - A = Z value from depth map at fragment's light XY position
 - -B = Z value of fragment's XYZ light position
- If (B > A),
 - There must be something closer to the light than the fragment
 - So, fragment is shadowed
- If A and B are approximately equal, the fragment is lit

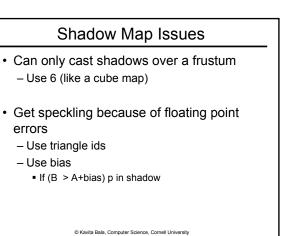
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Example: Shadowed The A < B shadowed fragment case depth map image plane depth map Z = A eye yeview image plane, a.k.a. the frame buffer fragment's light Z = B © Kavita Bala, Computer Science, Cornell University

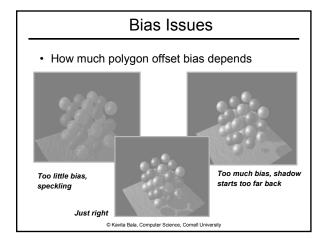




Example with shadows Without shadows © Kavita Bala, Computer Science, Cornell University



Shadow Map Issues • Use triangle Ids - Meshes? • Bias - If (B > A+bias) p in shadow - If b is large? - If b is small?



Shadow Maps on Hardware

- · Shadow Maps use projective textures
- Treat texture as a light source (slide projector)
 - Do not need to specify texture coordinates explicitly
 - Spotlights

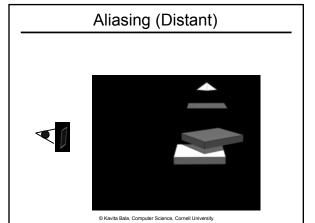


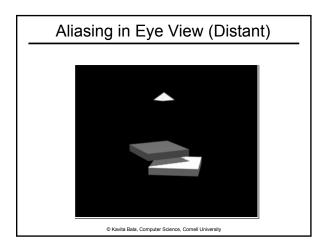
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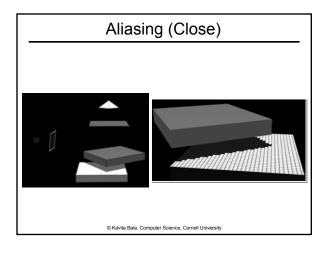
Properties of Shadow Maps

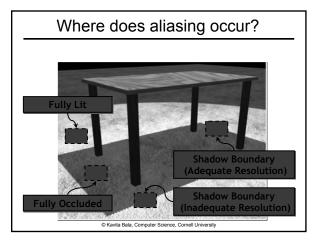
- · One shadow map per light
- · Render scene twice per frame
 - If static, can reuse
- Advantages
 - Fast
 - Easy to implement
- Disadvantages
 - Bias
 - Aliasing
 - Hard shadows

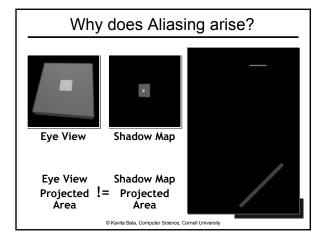
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Shadows

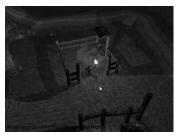
Methods for fast shadows:

- · Shadow Maps
- · Shadow Volumes

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Shadow Volumes

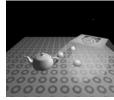
- Crow 1977
- · Accurate shadows

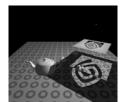


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Shadow Volumes

- Clever counting method using stencil buffer
- Can cast shadows onto curved surfaces

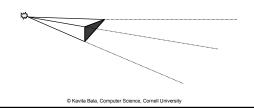




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Mark Kilgard, NVIDIA In

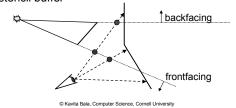
Volume Concept

- Create volumes of space in shadow from light
- Each triangle creates 3 projecting quads



Using the Volume

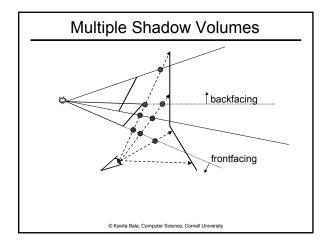
- To test a point, count the number of polygons between it and eye
- If more frontfacing than backfacing polygons, then in shadow
- Done with clever counting method using the stencil buffer



Algorithm

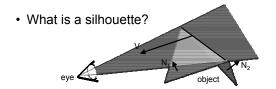
- · Finding volumes
 - Project out shadow volumes
- Rendering
 - Render scene into z-buffer, freeze z-buffer
 - Draw front-facing volumes in front of pixel
 - increment stencil
 - Draw back-facing volumes in front of pixel
 - decrement stencil
 - If (cnt == 0) lit else shadow

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Shadow Volumes Properties

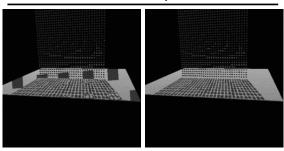
Performance: Use the silhouette for speed



 $N_1 \cdot V > 0$ (forward facing) $N_2 \cdot V < 0$ (backward facing)

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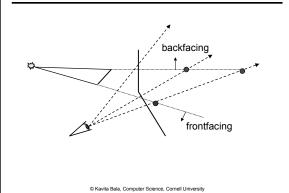
Near Plane Clip Issues



• Near plane clip discards part of shadow volume, messes up count

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Z-fail Approach



But

- · Far clipping plane problems?
- Use homogeneous coordinate to map to infinity

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Performance

- Have to render lots of huge polygons
 - Front face increment
 - Back face decrement
 - Possible capping pass
- · Uses a LOT fill rate
- · Gives accurate shadows
 - IF implemented correctly
- Need access to geometry if want to use silhouette optimization

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Summary

- Shadow maps
 - Render scene twice per frame
 - If static, can reuse
 - Uses projective texturing, requires hardware support/shaders
- · Shadow volumes
 - Use stencil buffers

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Comparison

- · Shadow Maps
 - Adv: Fixed resolution, fast, simple
 - Disadv: Bias, aliasing
- Shadow Volumes
 - Adv: Accurate, high-quality
 - Disadv: Fill-rate limited, hard to implement robustly

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Approaches to Improve Shadows

- Hard Shadows
 - Adaptive Shadow Maps [Fernando, Fernandez, Bala, Greenberg]
 - Shadow Silhouette Maps[Sen, Cammarano, Hanrahan]
- · Hard and Soft Shadows
 - Edge-and-Point Rendering [Bala, Walter Greenberg]
- · Soft Shadows
 - Next time

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Adaptive Shadow Maps: Motivation

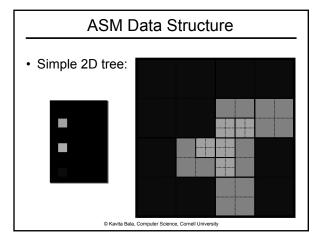
- Fernando, Fernandez, Bala, Greenberg [SIG01]
- · Shadow maps require too much tweaking
 - Where to place light?
 - What resolution to use?
- Goals:
 - Address the aliasing problem
 - No user intervention
 - Interactive frame rate

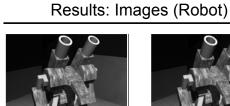
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Adaptive Shadow Maps

- · Idea:
 - Refine shadow map on the fly
- Goal:
 - Shade each eye pixel with a different shadow map pixel
- Implementation:
 - Use hierarchical structure for shadow map
 - Create/delete pieces of shadow map as needed
 - Exploit fast rendering and frame buffer read-backs

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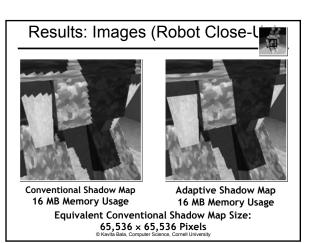


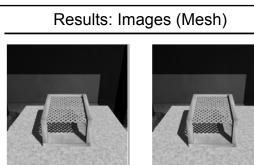


Conventional Shadow Map (2048 x 2048 pixels) 16 MB Memory Usage

Adaptive Shadow Map (Variable Resolution) 16 MB Memory Usage

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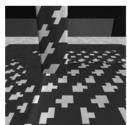


Conventional Shadow Map (2048 x 2048 pixels) 16 MB Memory Usage

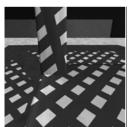
Adaptive Shadow Map (Variable Resolution) 16 MB Memory Usage

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Results: Images (Mesh Close-Up)



Conventional Shadow Map 16 MB Memory Usage



Adaptive Shadow Map 16 MB Memory Usage Equivalent Conventional Shadow Map Size:

65,536 × 65,536 Pixels
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