Lecture 15: Hardware Rendering

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Announcements

• Project discussion this week
  – Proposals: Oct 26

• Exam moved to Nov 18 (Thursday)
**Bounding Volume vs. Spatial Hierarchy**

<table>
<thead>
<tr>
<th>Object subdivision</th>
<th>Spatial subdivision</th>
</tr>
</thead>
<tbody>
<tr>
<td>– Hierarchical object representation</td>
<td>– Hierarchical spatial representation</td>
</tr>
<tr>
<td>– Hierarchically cluster objects</td>
<td>– Hierarchically cluster space</td>
</tr>
<tr>
<td><strong>• Siblings could overlap</strong></td>
<td><strong>• Siblings distinct</strong></td>
</tr>
<tr>
<td><strong>• Object in single leaf</strong></td>
<td><strong>• Object in &gt;1 leaf (higher)</strong></td>
</tr>
<tr>
<td><strong>• Ray marches down</strong></td>
<td><strong>• Ray marches across</strong></td>
</tr>
<tr>
<td><strong>• AABB, OBB, Spheres</strong></td>
<td><strong>• Octree, kd-tree, Grid</strong></td>
</tr>
</tbody>
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**Culling of Complex Scenes**

- Remove geometry that is not visible … cull it away
  - View Frustum Culling
  - Hierarchical z-buffer
  - Cell-portal visibility
  - Many others….
Hierarchical View Frustum Culling

• Use an octree/BVH

• Start at o = root of octree/BVH

• Test(Node o) {
  – Check 6 planes of frustum for intersection with bbox(o)
  – If in or out, terminate testing
  – If it intersects
    • For each child c = child[i], Test (c)

Occlusion Culling

• Occlusion Culling/Visibility Culling
• Don’t send all polygons to hardware
  – Remove polygons that are not visible
  – Conservative: find visible superset
Occlusion Culling

• On-line
  – Remove geometry on-the-fly

• Off-line
  – Determine potentially visible set (PVS)
  – When rendering only display PVS

Hierarchical Z-buffer

• On-line
• Use nearby polygons to remove far polygons
• Construct an octree subdivision of scene
  – Could use other data structures as well

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Off-line

- Interactive walkthroughs of very complex systems
  - Radiosity systems
  - Too many polygons
- Teller: Cell/Portal for indoor scenes
  - Used in games: Doom, Descent

Cell Portal Architecture

- Internal architectural scene
- Cells: Rooms
- Portals: Doors and Windows

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First Idea

- Find all cells visible from current cell
- Recursively propagate visibility
- Problem: Too conservative

Stab Tree

- Form a stab tree
- Check if a line exists that stabs all portals
  - Use linear programming
More Recent Work

• How to deal with non-architectural scenes
  – Cityscapes
  – Small Blockers: add up to large occlusion

More Recent Work

• But forests? Not really… Not yet!

• What about dynamic scenes?
Summary

• Acceleration structures for:
  – Ray Tracing
  – Collision detection
  – Point finding
  – Visibility culling
  – View frustum culling
  – ...

CS 665

Hardware Rendering

Images from Real-Time Rendering
Courtesy Eric Haines
Strengths of Hardware

- High throughput
  - Lots of polygons/second or pixels/second
- In the past:
  - Fixed functionality
  - Shading, transformations, clipping, etc.

- Hardware has been transformed
  - Programmable

Review: Graphics Pipeline

1. Application
2. Transform & Lighting
3. Projection & Clipping
4. Triangle Setup
5. Rasterization
6. Display
Why is Hardware Fast

- Pipelined and parallel
- No branching/looping (??)
- Aggressive prefetching from memory
- Pixel arithmetic is usually 8 bit fixed-point (this has changed)

This is the traditional “fixed-function pipeline”

Traditional OpenGL

Vertices

Transform & Lighting
- Transformed vertices

Rasterization
- Fragments

Texturing
- Textured fragments

Fragment?! Basically, pixel

Composite
- Frame Buffer

Texture Memory

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Brief History

The dark ages (early-mid 1990’s), when there were only frame buffers for normal PC’s.

Some accelerators were no more than a simple chip that sped up linear interpolation along a single span, so increasing fill rate.

This is where pipelines start for PC commodity graphics, prior to Fall of 1999.

This part of the pipeline reaches the consumer level with the introduction of the NVIDIA GeForce256.

Hardware today is moving traditional application processing (surface generation, occlusion culling) into the graphics accelerator.

New OpenGL

Vertices

Vertex Program

Transformed vertices

Vertex Shader

Rasterization

Fragments

Fragment Shader

Composite

Fragment Program

Texture Memory

Frame Buffer
New Programmable GPUs

• Pipelined and parallel
  – Current pipeline 600-800 stages deep!

• Branching/looping??

• Floating point arithmetic

• Programmable Vertex and Shader programs

• Essentially writing assembly/C code

Fixed-Function vs. Programmable

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Xbox Architecture

UMA (Unified Memory Architecture)

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GeForce 4 Vertex Shaders

- Sets of 4 word registers
- Data passed in through v, c registers
- Data out through o registers to next stage
- Vertex attribute registers
  - v[POS], v[NML], …
  - position, normal, …
  - Programmer loads data
- Result registers
- Temporary registers
- Constant registers

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Vertex Program Assembly

• Instructions operate on scalar or 4 vector
• Result is 4 vector or scalar (replicated)

• Examples
  – MOV v : Out v
  – DP4 v, v: ssss
  – Swizzle, .wxyz

• glLoadProgramNV

Shading Languages

• Assembly hard to program

• In 2002, many shading languages
  – e.g. Cg from NVIDIA, HLSL in DirectX 9

• Benefits:
  – Ease of use
  – Hardware independence
  – Reusable code
Cg Example

Vertout main (… uniform float4 LightVec)
{
vertout Out;
Out.Hposition = …

float 4 light = normalize (LightVec)
float diffuse = dot (normal, light);
…
return Out;
}

What’s New Since 1999

• Vertex Shader
• Pixel/Fragment Shader
• And much faster, of course
  – Peak fill rates
  – 1999 GeForce256: 0.35 Gigapixel
  – 2001 GeForce3: 0.8 Gigapixel
  – 2003 GeForceFX Ultra: 2 Gigapixel
  – ATI Radeon 9800 Pro: 3 Gigapixel
Faster than Moore’s Law

Programmable GPU Shading

- Multithreaded SIMD organization
- Multiple parallel units
- Same instructions executed on \( n \) vertices or fragments in parallel
Performance Issues

- Pipeline: bottleneck analysis
- Parallelism: load balancing
- Memory bandwidth limits
  - Texture reads
  - Z-Buffering
  - Host interface

GPU Parallelism

- GPUs exploit both
  - Task parallelism: pipeline
  - Data (vertex, triangle, fragment) parallelism
    - Process $k$ triangles in parallel, $m$ fragments in parallel
    - But, some triangles generate more fragments, some parts of screen written to more than others

- Various approaches to load balancing
  - FIFO buffering

- Pipeline in GeForce3 up to 800 clocks long (compare to 10-20 on CPUs)
Bandwidth

- Bandwidth scales with perimeter
- Computation scales with area
- Memory, buses MUCH slower than internal processing
- CPUs: use lots and lots and lots of caches to match memory speeds
- GPUs: exploit streaming computation, prefetching, block transfers, coherence

Texture Cache

- Prefetch texture block
- Texture data spatially organized to maximize coherence
- May reorder texture lookups to improve temporal coherence
Current/Future

• Faster
  – More parallelism

• More generalized shading languages
  – Fewer constraints in programs

Key Hardware Capabilities

• Z-Buffering
• Accumulation Buffer
• Antialiasing
• Transparency/Compositing
• Stencil Buffer
• Filtered Texturing
Accumulation Buffer

- Render a scene a number of times, making small variations
- Blend the results to make a single image.

Effects produced include:
- Anti-aliasing
- Depth of Field
- Motion Blur
- Soft Shadows

- Needs more precision than ordinary buffers
Stereo Buffers

- Render left and right eye views
  - Both front and back left and right buffers

- Display hardware alternates frames
- Controls shutter glasses
- May also
  - use head or eye tracking
  - use head-mounted-display (HMD) and multiple parallel outputs instead

Stencil Buffers

- 1 to 8 bitplanes
  - Usually “leftover” bits in depth buffer
  - May need to use 24-bit depth to use
- Stencil test used
  - Tests: ==, <, <=, >, >= ref value
- Operations can modify stencil value:
  - Ex: increment stencil if passes depth test
  - Different ops for fail, zfail, zpass
- Can mask out parts of stencil to modify
- Used for shadow volumes, reflections, etc.
Reflections

Planar: flip object through mirror

Reflection & Stencil Buffer

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Reflection Example - Castle

![Reflection Example - Castle](image1)

Castle’s Geometry

![Castle’s Geometry](image2)
### P-Buffers

- Permit rendering to off-screen target
  - Addresses dimension limitations
  - Example, used for shadow maps

- P-buffer in one context can be associated with texture in another

- ATI Radeon 9700:
  - fragment shader can write to up to four output buffers simultaneously
  - potentially useful for multipass algorithms

### Key Hardware Capabilities

- Z-Buffering
- Accumulation Buffer
- Antialiasing
- Transparency/Compositing
- Stencil Buffer
- Filtered Texturing
Texture Mapping

Mipmapping Filtering
Fast Texture Map Lookup

• Very powerful feature of hardware
• Most flexible part of graphics hardware
  – Surface texturing
  – Bump mapping: normals
  – Reflection mapping
  – Shadow mapping
  – Even arbitrary BRDF approximations

• Cheap anti-aliasing & anisotropic filtering

Many types of Texture Maps

• Texture modulates diffuse coefficients in shading model

• Textures can modulate
  – Normals: bump mapping and normal mapping
  – Positions: displacement mapping
  – Lighting: environment mapping
Environment Map

- Want to compute reflections of environment on surfaces
  - Planar surfaces?
  - Curved surfaces

- Assumptions:
  - Environment Map represents objects at infinity

- Index into EM using reflection vector

Environment Mapping

- EM gives reflections in curved surfaces
  - Not very good for flat surfaces
Env Map Algorithm

• Generate 2D environment map
  – Spherical, cubical, paraboloid

• For each pixel on a reflective object
  – Find N on surface of object
  – Compute R from V and N: \( R = V - 2(N \cdot V)N \)
  – Index into EM using R
  – Modulate pixel color

Types of Mappings

- Sphere mapping
- Cube mapping