Byzantine Techniques

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Michael George Byzantine Techniques

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Reliability and Failure

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- We want reliable systems
- Until now, we've assumed that failures are fail-stop
- What happens if failures are arbitrary?

Reliability and Failure

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- We want reliable systems
- Until now, we've assumed that failures are fail-stop
- What happens if failures are arbitrary?
- ... or even malicious?

Today's Presentation

We will discuss two papers that address this worst-case scenario:

- The Byzantine General's Problem [Lamport et. al. 1982]
 - Phrases the problem in terms of Byzantine Generals
 - Shows a tight upper bound on fault tolerance
 - Explores bounds under modified assumptions

Overview

Byzantine Techniques

The Byzantine General's Problem Practical Byzantine Fault Tolerance Conclusion

Today's Presentation

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- The Byzantine General's Problem [Lamport et. al. 1982]
 - Phrases the problem in terms of Byzantine Generals
 - Shows a tight upper bound on fault tolerance
 - Explores bounds under modified assumptions
- Practical Byzantine Fault Tolerance [Castro and Liskov 1999]
 - Implements fault-tolerant state-machine replication
 - Aggressively optimizes the implementation
 - Layers replicated NFS over state-machine
 - Shows performance penalty is reasonable

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The Basic Problem Impossibility Results An Optimal Algorithr Extensions

The Basic Problem

A group of Byzantine Generals are surrounding an enemy city.

- They need to jointly decide whether to attack or retreat.
- But some of them might be traitors.
- Want them to agree on a decision.

The Basic Problem Impossibility Results An Optimal Algorithm Extensions

The Basic Problem

A group of Byzantine Generals are surrounding an enemy city.

- They need to jointly decide whether to attack or retreat.
- But some of them might be traitors.
- Want them to agree on a decision.
- Decision must be good.

The Basic Problem Impossibility Results An Optimal Algorithm Extensions

Reducing Decision Making to Information Propogation

- IC1 All loyal lieutenants recieve the same value
- IC2 If commander is loyal, then all lieutenants recieve value she sent

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Reducing Decision Making to Information Propogation

If a single commander can send information to some lieutenants such that:

- IC1 All loyal lieutenants recieve the same value
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The *Byzantine General's Problem* is to send information in a way that satisfies IC1 and IC2.

The Basic Problem Impossibility Results An Optimal Algorithm Extensions

Impossibility With Three Generals

Consider the following:



Commander saysLieutenant 2 saysLieutenant 1 concludes"attack""attack""attack"

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The Basic Problem Impossibility Results An Optimal Algorithm Extensions

Impossibility With 3m Generals

What if we can solve for 3m Albanian generals with m failures?



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The Basic Problem Impossibility Results An Optimal Algorithm Extensions

Impossibility With 3*m* Generals

What if we can solve for 3m Albanian generals with m failures?



Then we can implement three Byzantine generals with one failure!

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Impossibility With Approximate Agreement

Can we do approximate (within a given $\delta)$ agreement?

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No - just have general choose points further then 2δ apart.

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The Basic Problem Impossibility Results An Optimal Algorithm Extensions

Impossibility With Approximate Agreement

Can we do approximate (within a given δ) agreement?



No - just have general choose points further then 2δ apart. Now we've solved the exact problem.

Oral Messages

The Basic Problem Impossibility Results An Optimal Algorithm Extensions

Some assumptions:

- A1 Every message that is sent is delivered correctly
- A2 The reciever of a message knows who sent it
- A3 The absence of a message can be detected

A (10) < (10) </p>

Oral Messages

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implicit Only the sender and reciever can read a message Also need a *majority* function:

- If a majority of v_i 's are v then $majority(\vec{v}) = v$
- Can use the "majority or default" function or the median function

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The Basic Problem Impossibility Results An Optimal Algorithm Extensions

The Oral Messages Algorithm

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The Basic Problem Impossibility Results An Optimal Algorithm Extensions

With Signed Messages (or broadcast)

Impossibility proof assumes that lieutenants can lie

- Can be prevented with digitial signatures
- Also with broadcast

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The Basic Problem Impossibility Results An Optimal Algorithm Extensions

With Signed Messages (or broadcast)

Impossibility proof assumes that lieutenants can lie

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- Also with broadcast
- Authors provide *m* + 2 general algorithm that thwarts *m* traitors

A (1) < (1) < (1) < (1) </p>

The Basic Problem Impossibility Results An Optimal Algorithm Extensions

With Restricted Communications

What if generals can only talk to certain (nearby) generals? Under certain connectivity hypotheses:

- Almost the same basic algorithm works (add forwarding)
- Same bounds on number of traitors/generals
- Signed version also goes through as long as loyal generals connected

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The Basic Problem Impossibility Results An Optimal Algorithm Extensions

"Certain Connectivity Hypotheses"

Definition:

- A set N of neighbors of v is regular if for all $n \in N$ and all $v' \neq v$ there is a path $\gamma_{nv'}$ from n to v' not passing through v or $\gamma_{n'v''}$
- A graph is *p*-regular if every node has a regular set of *p* neighbors

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Overview The Algorithm Performance

Problems With Lamport et. al.

The first paper was theoretical:

- Algorithms provided only as proof of existence
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The second paper aims for *practicality*.

- Algorithm is implemented as general-purpose library
- Assumptions model reality better
- Implementation is optimized and benchmarked

Overview The Algorithm Performance

Theoretical Limitations

Some hard limitations:

• Previous paper: need 3m + 1 generals

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Overview The Algorithm Performance

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Theoretical Limitations

Some hard limitations:

- Previous paper: need 3m + 1 generals
- FLP result: need synchrony

• Can't avoid failures that are correct according to protocol Given these limitations, the authors design a state machine replication protocol

Overview The Algorithm Performance

State Machine Replication

Replicated state machines are an abstract framework for distributed systems

- There is a shared global "state" of the system
- Events modify the state in a *deterministic* way
 - Client requests
 - Membership changes / failure

Overview The Algorithm Performance

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- Replicated servers maintain local copy of state
 - Can act on state transitions

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 - Client requests
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- Replicated servers maintain local copy of state
 - Can act on state transitions
- If all replicas start in same state and all events propogated, then all replicas remain in the same state

Overview The Algorithm Performance

Normal Operation

- Client sends request to primary
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- When a replica recieves 2f PREPARE messages, it sends a COMMIT message
- When a replica recieves 2f + 1 commit messages, it changes its' local state

Overview The Algorithm Performance

View Changes

Like Paxos, we maintain a view of primary

- When a replica thinks current primary has failed, broadcasts a VIEW-CHANGE message
 - Contains its best estimate of primary's state upon failure

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View Changes

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- When a replica thinks current primary has failed, broadcasts a VIEW-CHANGE message
 - Contains its best estimate of primary's state upon failure
- When the new primary recieves 2f VIEW-CHANGE messages it broadcasts NEW-VIEW to all other replicas
 - \bullet Contains proof that it really recieved $\mathrm{ViEW\text{-}CHANGE}$ messages

Overview The Algorithm Performance

Optimizations

Some optimizations to reduce communication delay:

• Client designates single server for reply; others send digest

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Optimizations

Some optimizations to reduce communication delay:

- Client designates single server for reply; others send digest
- Client can accept 2f + 1 tentative replies instead of waiting for f + 1 actual replies
- Reduced interaction in read-only case

Also use message authentication codes instead of public-key crypto for common case.

Overview The Algorithm Performance

Micro-Benchmarks

arg./res.		replica	without			
(KB)	read-write		read-only		replication	
0/0	3.35	(309%)	1.62	(98%)	0.82	(0%)
4/0	14.19	(207%)	6.98	(51%)	4.62	(0%)
0/4	8.01	(72%)	5.94	(27%)	4.66	(0%)

For the "worst-case scenario":

- Tests measure null operations
- Without replication is just "best-effort" (UDP)

The worst is about four times as slow

Overview The Algorithm Performance

Cost of Replication

	BFS					
phase	strict		r/o lookup		BFS-nr	
1	0.55	(57%)	0.47	(34%)	0.35	(0%)
2	9.24	(82%)	7.91	(56%)	5.08	(0%)
3	7.24	(18%)	6.45	(6%)	6.11	(0%)
4	8.77	(18%)	7.87	(6%)	7.41	(0%)
5	38.68	(20%)	38.38	(19%)	32.12	(0%)
total	64.48	(26%)	61.07	(20%)	51.07	(0%)

This benchmark measures the cost of replication:

- BFS-nr is the same as BFS but performs no replication
- It is unsafe because reports that result is stable before it is

Overview The Algorithm Performance

Cost of Fault Tolerance

	BFS					
phase	strict		r/o lookup		NFS-std	
1	0.55	(-69%)	0.47	(-73%)	1.75	(0%)
2	9.24	(-2%)	7.91	(-16%)	9.46	(0%)
3	7.24	(35%)	6.45	(20%)	5.36	(0%)
4	8.77	(32%)	7.87	(19%)	6.60	(0%)
5	38.68	(-2%)	38.38	(-2%)	39.35	(0%)
total	64.48	(3%)	61.07	(-2%)	62.52	(0%)

This test measures the cost of fault tolerance:

- NFS-std is the standard implementation of NFS
- Some numbers are negative (!)
- Best numbers (r/o lookup) not quite fair

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Take-home Messages

First paper:

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- Not possible with fewer

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Second paper:

- Byzantine techniques are reasonable to use in practice
- Can even improve performance by replacing slow disk with fast distributed processors

Thoughts for Discussion

- Are byzantine assumptions worthwhile?
 - Who does *n*-version programming anyway?
 - Does it really help?

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 - Need to be careful to avoid circularity

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 - Who does *n*-version programming anyway?
 - Does it really help?
- Can this be done better at a lower level (e.g. broadcast)?
 - Lamport et. al. say no
 - Need to be careful to avoid circularity
- What about graceful failure?