

Delaunay Mesh Generation and Parallelization

January 31st, 2006

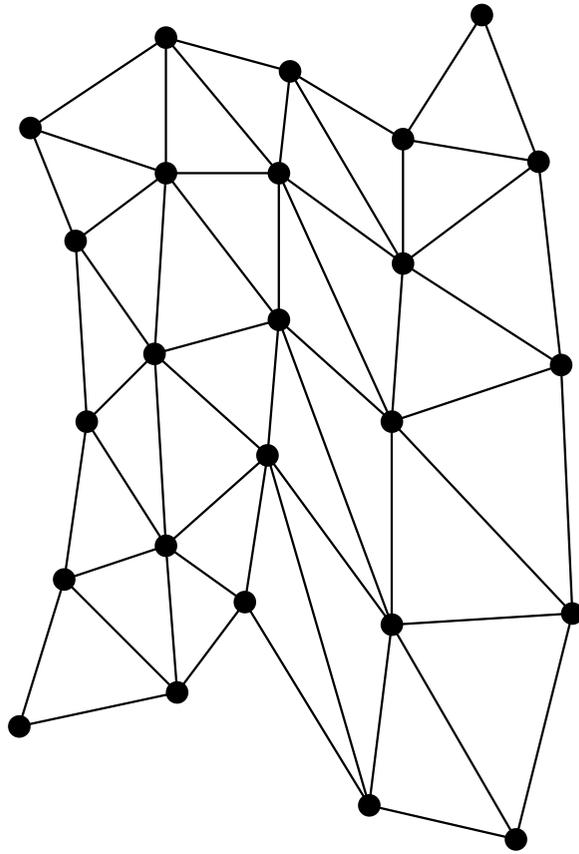
Context

- ▶ **Mesh generation useful for**
 - ▶ Finite element method
 - ▶ Determines basis functions
 - ▶ Graphics
 - ▶ Tessellation of surface into polygons for rendering

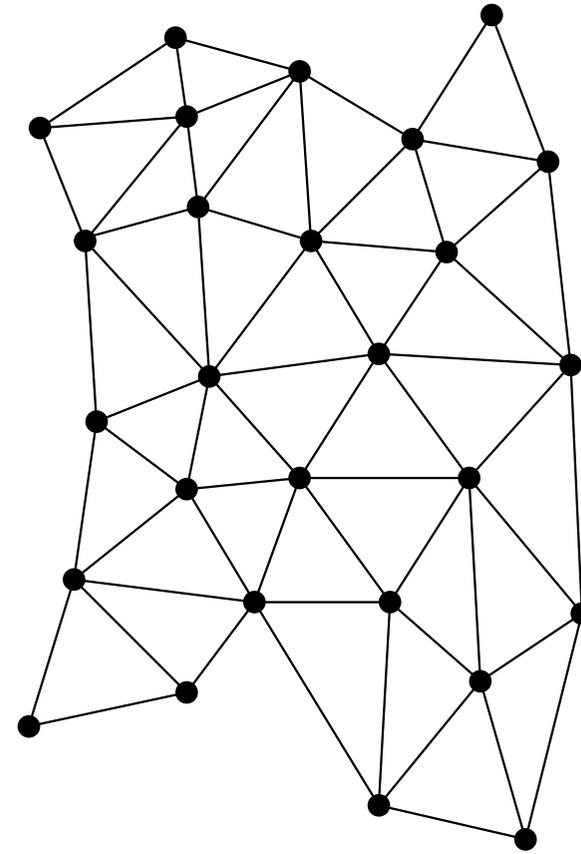
Mesh Quality

- ▶ **Why is mesh quality important?**
 - ▶ Can impact solution of linear systems
 - ▶ Angles too large can lead to errors
 - ▶ Angles too small lead to ill-conditioned systems
 - ▶ Tradeoffs regarding number of elements
 - ▶ More elements for better accuracy
 - ▶ Fewer elements for better speed

Structured vs. Unstructured



Structured Mesh

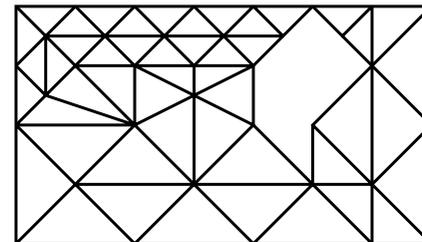
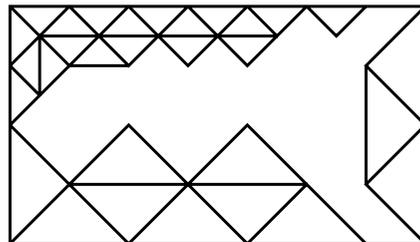
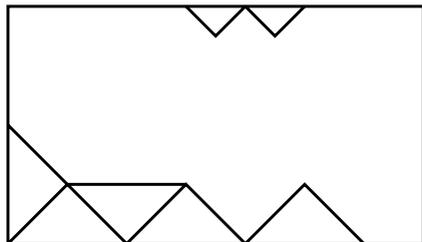


Unstructured Mesh

Some diagrams taken from Jonathan Shewchuk's lecture notes: <http://www.cs.berkeley.edu/~jrs/mesh/>

Different Types of Meshing

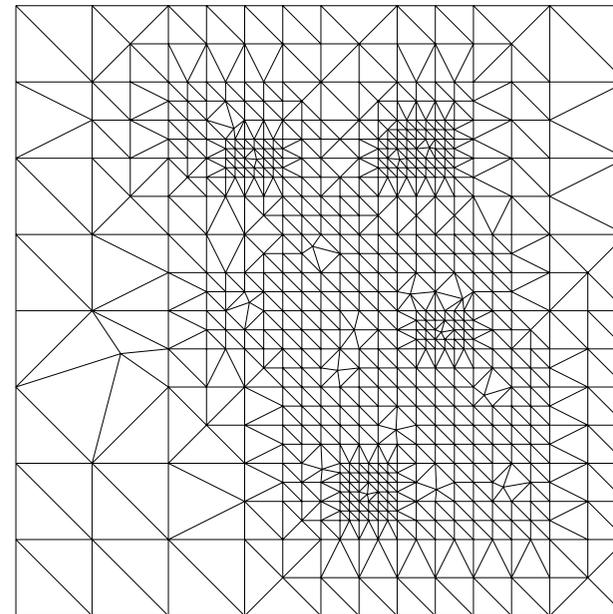
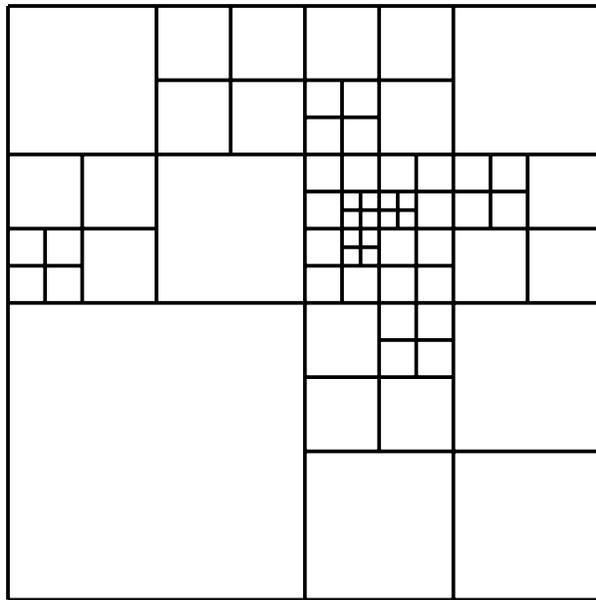
- ▶ **Advancing Front**
 - ▶ Starts at boundary of mesh
 - ▶ Uses heuristics to “grow” mesh inwards



From JS lecture notes

Different Types of Meshing

- ▶ **Quadtree based meshes**
 - ▶ Subdivide plane using quadtree structure
 - ▶ Warp quadtree to match vertices
 - ▶ Triangulate resulting grid

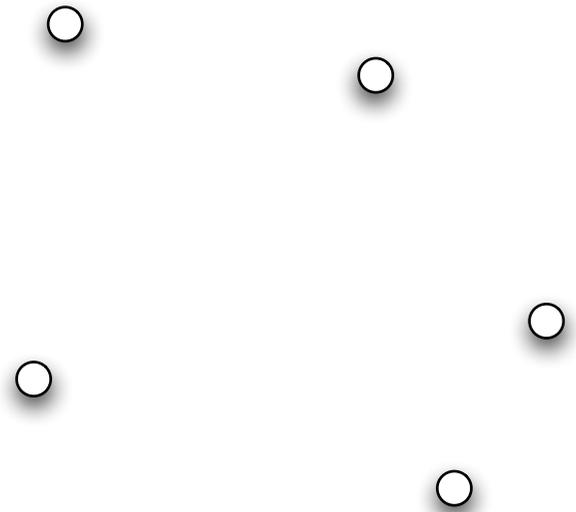


From JS lecture notes

Delaunay Meshes

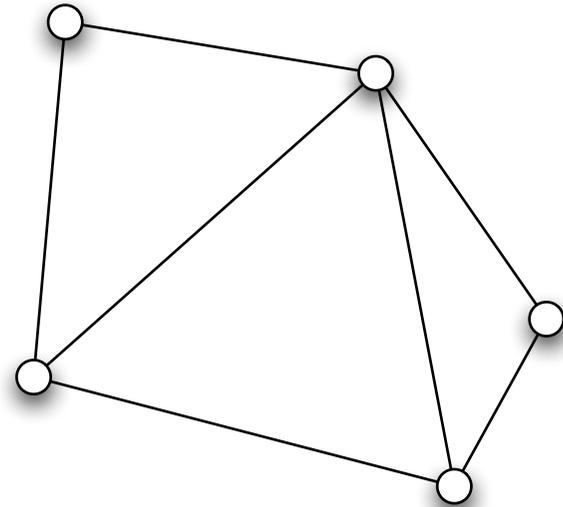
Delaunay Mesh Generation

- ▶ **What is a Delaunay mesh?**
 - ▶ Tessellation of a surface given vertices



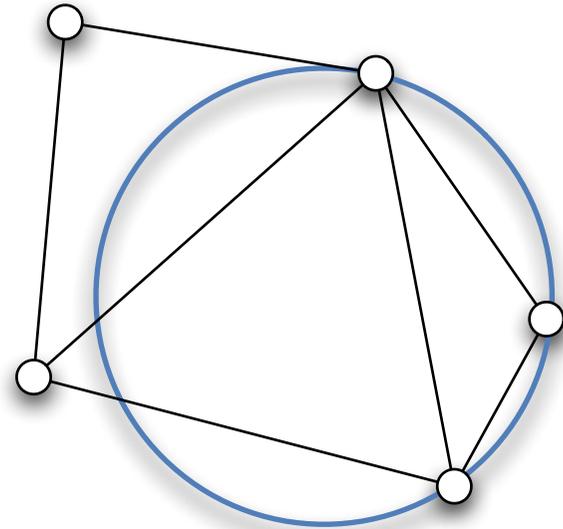
Delaunay Mesh Generation

- ▶ **What is a Delaunay mesh?**
 - ▶ Tessellation of a surface given vertices



Delaunay Mesh Generation

- ▶ **What is a Delaunay mesh?**
 - ▶ Tessellation of a surface given vertices
 - ▶ Satisfies the **Delaunay property**
 - ▶ Circumcircle of any triangle does not contain another point in the mesh

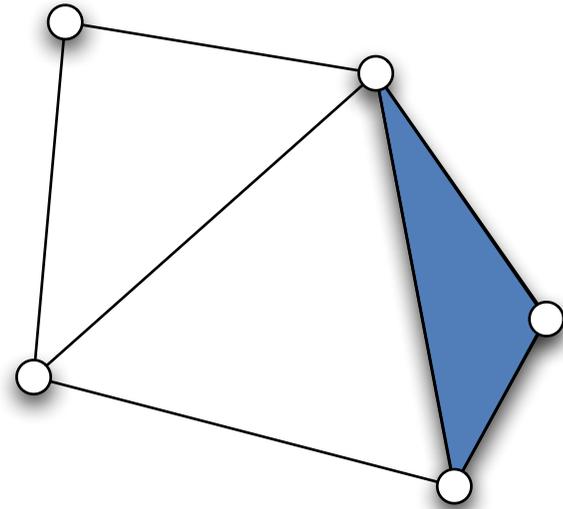


Why Delaunay Meshes?

- ▶ **Provides specific guarantees**
 - ▶ “The Delaunay triangulation of a point set minimizes the maximum angle over all possible triangulations”
 - ▶ Fewer skinny triangles
- ▶ **Additional points can be inserted to meet certain quality constraints**
 - ▶ Angle constraints
 - ▶ Triangle size constraints

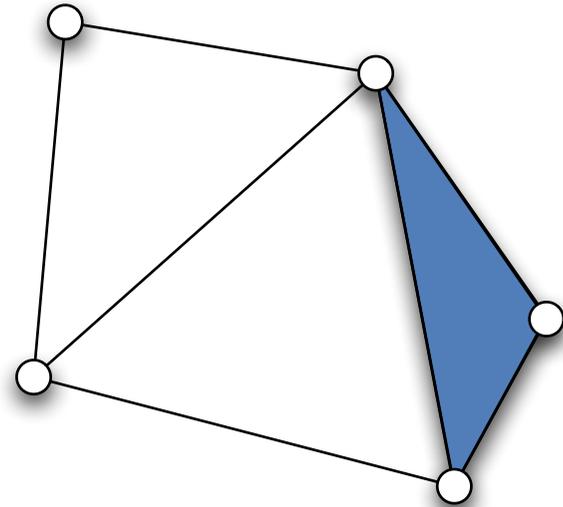
Delaunay Mesh Generation

- ▶ Want all triangles in mesh to meet quality constraints
 - ▶ No angle $< 30^\circ$
- ▶ Fix bad triangles through **iterative refinement**
 - ▶ Add new vertices to mesh and retriangulate



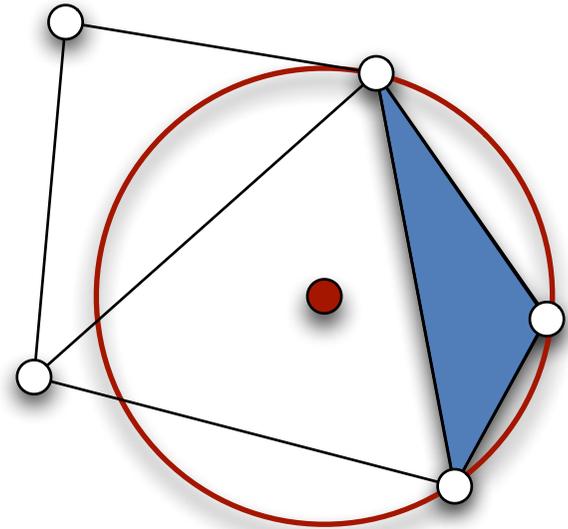
Mesh Refinement

- ▶ Choose “bad” triangle



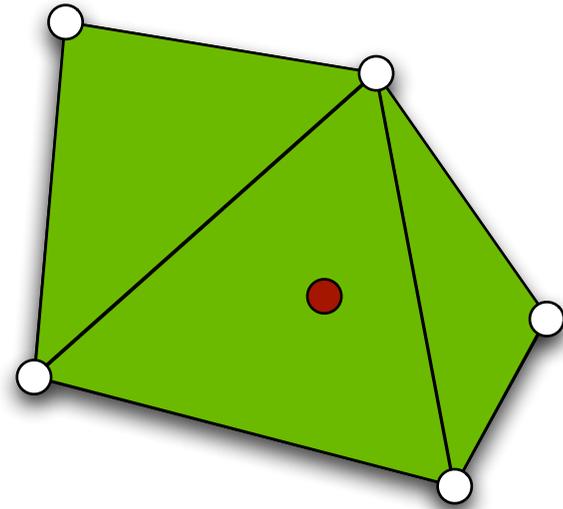
Mesh Refinement

- ▶ Choose “bad” triangle
- ▶ Add **new vertex** at center of **circumcircle**



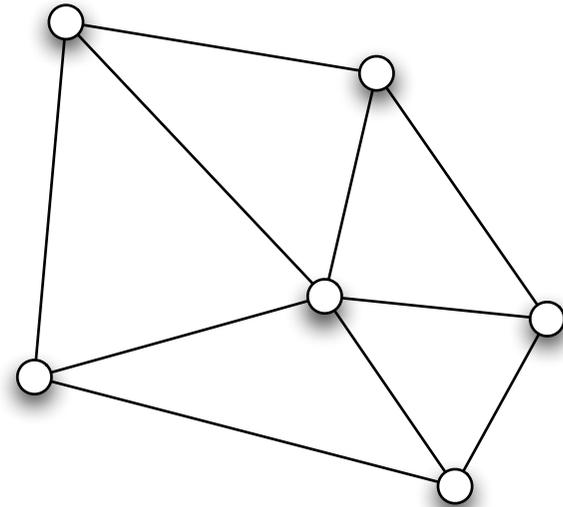
Mesh Refinement

- ▶ Choose “bad” triangle
- ▶ Add **new vertex** at center of circumcircle
- ▶ Gather all triangles that no longer satisfy Delaunay property into **cavity**



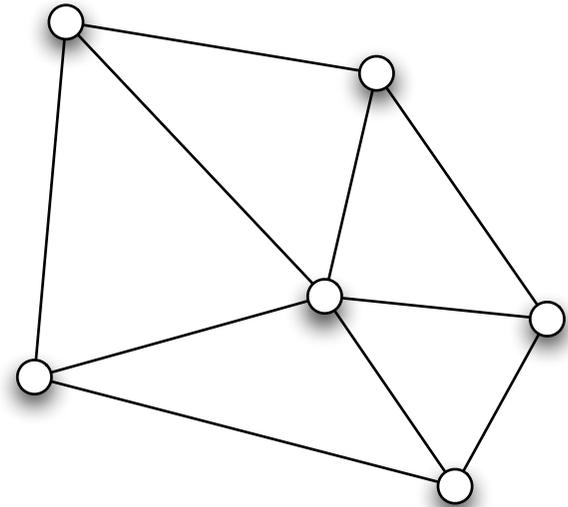
Mesh Refinement

- ▶ Choose “bad” triangle
- ▶ Add new vertex at center of circumcircle
- ▶ Gather all triangles that no longer satisfy Delaunay property into cavity
- ▶ Re-triangulate affected region, including new point



Mesh Refinement

- ▶ Choose “bad” triangle
- ▶ Add new vertex at center of circumcircle
- ▶ Gather all triangles that no longer satisfy Delaunay property into cavity
- ▶ Re-triangulate affected region, including new point
- ▶ Continue until all bad triangles processed



Program

```
Mesh m = /* read in mesh */
WorkQueue wq;
wq.enqueue(mesh.badTriangles());

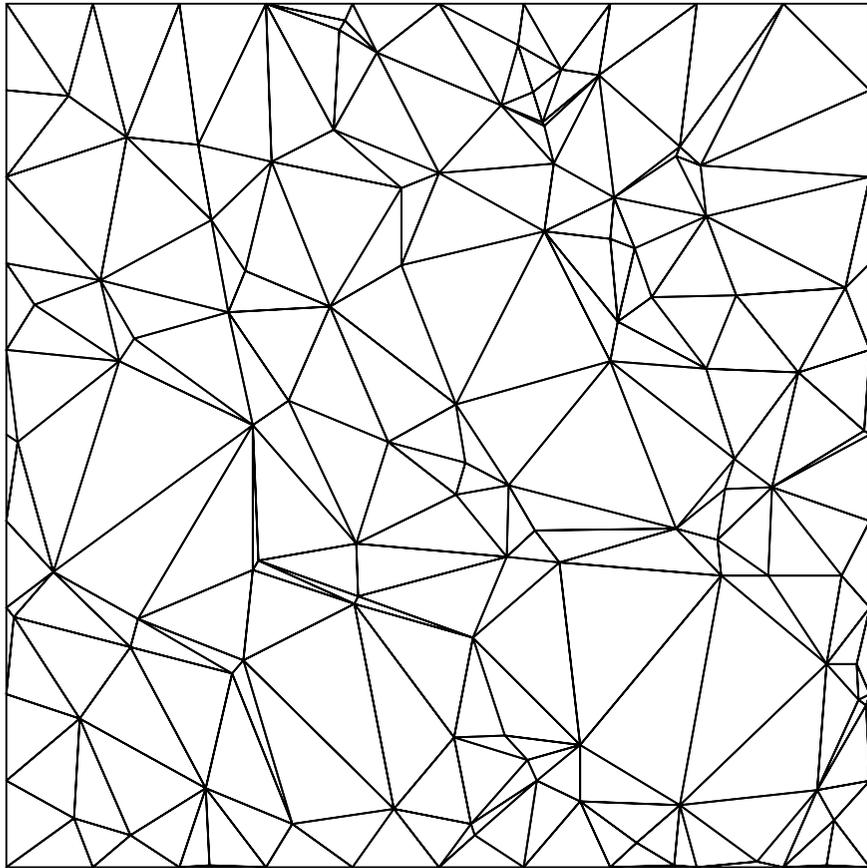
while (!wq.empty()) {
    Triangle t = wq.dequeue();    //choose bad triangle

    Cavity c = new Cavity(t);    //determine new vertex
    c.expand();                  //determine affected triangles
    c.retriangulate();           //re-triangulate region

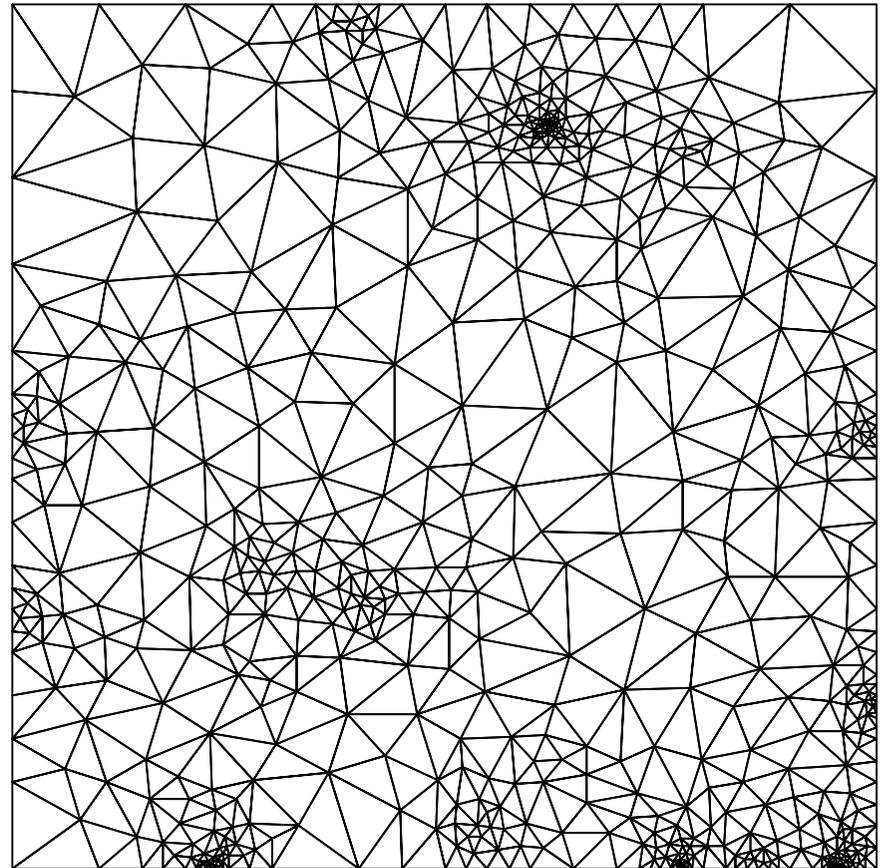
    m.update(c);                 //update mesh

    wq.enqueue(c.badTriangles()); //add new bad triangles to queue
}
```

Refinement Example



Original Mesh



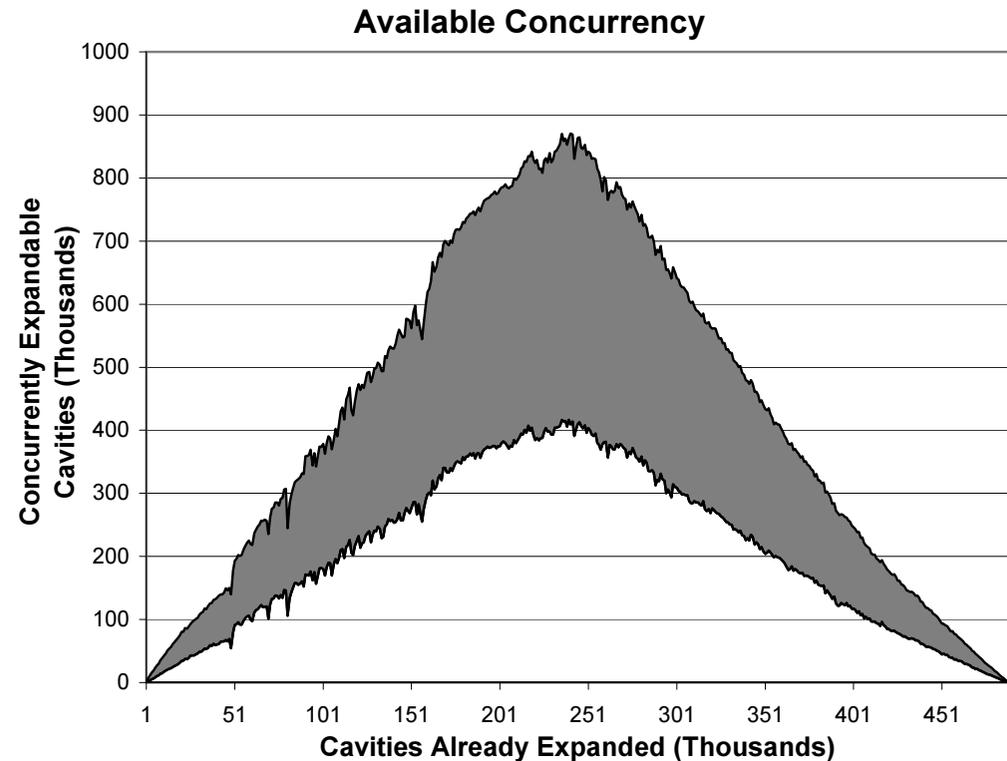
Refined Mesh

Parallelization Opportunities

- ▶ **Multiple bad triangles to be processed**
- ▶ **Algorithm inherently non-deterministic**
 - ▶ Order of processing irrelevant
 - ▶ **Effects of re-triangulation localized**
 - ▶ Update operations mostly independent
- ▶ **Can process multiple triangles in parallel**
 - ▶ Triangles must be sufficiently far apart

Parallelization Opportunities

- ▶ Estimated available parallelism for mesh of IM triangles
- ▶ Actual ability to exploit parallelism dependent on scheduling of processing
- ▶ C. Antonopolous, X. Ding, A. Chernikov, F. Blagojevic, D. Nikolopolous and N. Chrisochoides *Multigrain parallel Delaunay Mesh generation*, ICS05



Program

```
Mesh m = /* read in mesh */
WorkQueue wq;
wq.enqueue(mesh.badTriangles());

while (!wq.empty()) {
    Triangle t = wq.dequeue();    //choose bad triangle

    Cavity c = new Cavity(t);    //determine new vertex
    c.expand();                  //determine affected triangles
    c.retriangulate();           //re-triangulate region

    m.update(c);                //update mesh

    wq.enqueue(c.badTriangles()); //add new bad triangles to queue
}
```

Abstractions

- ▶ **WorkSet abstraction**
 - ▶ Replaces queue of bad triangles
 - ▶ Queue introduces loop carried dependence
- ▶ **getAny operation**
 - ▶ Does not make ordering guarantees
 - ▶ Removes dependence between iterations
 - ▶ In the absence of interference, iterations can execute in parallel

Abstractions

- ▶ **Graph abstraction**
 - ▶ Mesh can be viewed as an undirected graph
 - ▶ Nodes in Graph represent triangles in mesh
 - ▶ Edges in Graph capture triangle adjacency
- ▶ **Subgraph abstraction**
 - ▶ Collection of affected triangles is a Subgraph of overall Graph
- ▶ **replaceSubgraph operation**
 - ▶ Updating mesh after re-triangulation is replacing one Subgraph with another

Rewritten Program

```
Graph g = /* read in mesh */
WorkSet ws;
ws.add(g.badNodes());

while (!ws.empty()) {
    Node n = ws.getAny();           //choose bad node

    Subgraph s1 = expandCavity(n); //determine affected nodes
    Subgraph s2 = reTriangulate(s1); //re-triangulate region

    g.replaceSubgraph(s1, s2);     //update graph

    ws.add(s2.badNodes());        //add new bad nodes to set
}
```

Automatic Parallelization

- ▶ Can now exploit “getAny” to parallelize loop
 - ▶ Can try to expand cavities in parallel
 - ▶ Expansions can still conflict
- ▶ How do we deal with this?
 - ▶ Ideally, automatically

Automatic Parallelization

- ▶ Most automatic parallelization focuses on “regular” data structures
 - ▶ arrays, matrices
- ▶ Parallelization for irregular data structures much trickier
 - ▶ Why?

Automatic Parallelization

- ▶ **Must ensure no dependences between parallel code**
 - ▶ Static detection of possible dependences
 - ▶ If dependence exists, parallel execution not possible

Automatic Parallelization

- ▶ **Must ensure no dependences between parallel code**
 - ▶ Static detection of possible dependences
 - ▶ If dependence exists, parallel execution not possible
- ▶ **Analysis harder for irregular data structures**
- ▶ **Static determination of dependences intractable**

Optimistic Parallelization

- ▶ In practice, most cavities can be expanded in parallel safely
 - ▶ No way to know this *a priori*
 - ▶ Only guaranteed safe approach is serialization
- ▶ What if we perform parallelization without prior guarantee of safety?

Optimistic Parallelization

- ▶ Expand cavities in parallel
- ▶ Perform run time checks to ensure that expansions do not conflict
 - ▶ If check fails, roll back expansion process, try again

Parallelization Issues

- ▶ Must ensure that run-time checks are efficient
- ▶ How to perform roll backs
- ▶ Would like to minimize conflicts
 - ▶ Scheduling becomes important
 - ▶ Number of available cavities for expansion exceeds computational resources
 - ▶ Choose cavities to expand to minimize conflicts
 - ▶ Empirical testing: ~30% of cavity expansions conflict

Distributed Memory

- ▶ Elements of mesh now distributed among processors
 - ▶ Accessing elements on different processors high latency
 - ▶ Expanding cavity whose elements are on multiple processors is slow
 - ▶ Want to hide latency
- ▶ Perform multiple expansions *per processor*.

Summary

- ▶ **Mesh generation is an important algorithm**
 - ▶ Delaunay mesh generation is a particularly useful variant of this algorithm
- ▶ **Delaunay mesh generation intuitively parallelizable**
 - ▶ In practice (especially automatically) not so easy
 - ▶ Must determine that loop can be parallelized
 - ▶ Must ensure that cavities do not conflict
- ▶ **Several challenges to effective parallelization**
 - ▶ Dynamic dependence checking
 - ▶ Scheduling
 - ▶ Distributed memory model