1 Introduction

In this lecture, we add constructs to the typed \( \lambda \)-calculus that allow working with more complicated data structures, such as pairs, tuples, records, sums and recursive functions. We also provide denotational semantics for these new constructs.

2 Recap—The Typed \( \lambda \)-Calculus \( \lambda \rightarrow \)

2.1 Syntax

\[
\begin{align*}
\text{terms} & \\
\quad e & ::= n \mid \text{true} \mid \text{false} \mid \text{null} \mid x \mid e_1 e_2 \mid \lambda x : \tau. e \\
\text{types} & \\
\quad \tau & ::= \text{int} \mid \text{bool} \mid \text{unit} \mid \tau_1 \rightarrow \tau_2 \\
\text{values} & \\
\quad v & ::= n \mid \text{true} \mid \text{false} \mid \text{null} \mid \lambda x : \tau. e \quad \text{closed}
\end{align*}
\]

Previously, with the untyped \( \lambda \)-calculus, we encoded integers and Booleans as \( \lambda \)-terms. In \( \lambda \rightarrow \), we are taking them as primitive constructs.

2.2 Typing Rules

\[
\begin{align*}
\Gamma \vdash n : \text{int} & \\
\Gamma \vdash \text{true} : \text{bool} & \\
\Gamma \vdash \text{false} : \text{bool} & \\
\Gamma \vdash \text{null} : \text{unit} & \\
\Gamma, x : \tau \vdash x : \tau & \\
\frac{\Gamma \vdash e_0 : \sigma \rightarrow \tau \quad \Gamma \vdash e_1 : \sigma}{\Gamma \vdash e_0 e_1 : \tau} & \\
\frac{\Gamma, x : \sigma \vdash e : \tau}{\Gamma \vdash (\lambda x : \sigma. e) : \sigma \rightarrow \tau}
\end{align*}
\]

3 Simple Data Structures

Each data structure can be added by extending the syntax of expressions \( (e) \), types \( (\tau) \) and values \( (v) \). The evaluation contexts \( (E) \) will also need to be extended, and evaluation and type derivation rules added to work with the new syntax.

3.1 Pairs

Syntax:

\[
\begin{align*}
\text{terms} & \\
\quad e & ::= \cdots \mid (e_1, e_2) \mid \#1 e \mid \#2 e \\
\text{types} & \\
\quad \tau & ::= \cdots \mid \tau_1 \ast \tau_2 \\
\text{values} & \\
\quad v & ::= \cdots \mid (v_1, v_2) \\
\text{evaluation contexts} & \\
\quad E & ::= \cdots \mid ([\cdot], e) \mid (v, [\cdot]) \mid \#1 [\cdot] \mid \#2 [\cdot]
\end{align*}
\]

For every added syntactic form, we observe that we have expressions that introduce the form, and expressions that eliminate the form. In the case of pairs, the introduction expression is \( (e_1, e_2) \), and the elimination expressions are \( \#1 e \) and \( \#2 e \).
Evaluation rules:

\[ #1(v_1, v_2) \rightarrow v_1 \quad #2(v_1, v_2) \rightarrow v_2 \]

Note that these rules define \textit{eager} evaluation, because we only select from a pair when both elements are already evaluated to a value.

Typing rules:

\[
\begin{align*}
\Gamma &\vdash e_1 : \tau_1 \quad \Gamma \vdash e_2 : \tau_2 & \Gamma &\vdash e : \tau_1 \ast \tau_2 \\
\Gamma &\vdash (e_1, e_2) : \tau_1 \ast \tau_2 \\
\Gamma &\vdash #\, e : \tau_1 \\
\Gamma &\vdash #\, 2 \, e : \tau_2 
\end{align*}
\]

3.2 Tuples

Syntax:

\[
\begin{align*}
e &::= \cdots \mid (e_1, \ldots, e_n) \mid #\, n \, e \\
\tau &::= \cdots \mid \tau_1 \ast \cdots \ast \tau_n \\
v &::= \cdots \mid (v_1, \ldots, v_n) \\
E &::= \cdots \mid (v_1, \ldots, v_{i-1}, [\cdot], e_{i+1}, \ldots, e_n) \mid #\, n \, [\cdot]
\end{align*}
\]

Evaluation rules:

\[ #\, m \,(v_1, \ldots, v_n) \rightarrow v_m, \quad 1 \leq m \leq n \]

Typing rules:

\[
\begin{align*}
\Gamma &\vdash e_i : \tau_i, \; 1 \leq i \leq n & \Gamma &\vdash e : \tau_1 \ast \cdots \ast \tau_n \\
\Gamma &\vdash (e_1, \ldots, e_n) : \tau_1 \ast \cdots \ast \tau_n \\
\Gamma &\vdash #\, m \, e : \tau_m \\
\end{align*}
\]

3.3 Records

Syntax:

\[
\begin{align*}
e &::= \cdots \mid \{ x_1 = e_1, \ldots, x_n = e_n \} \mid e.\!x \\
\tau &::= \cdots \mid \{ x_1 : \tau_1, \ldots, x_n : \tau_n \} \\
v &::= \cdots \mid \{ x_1 = v_1, \ldots, x_n = v_n \} \\
E &::= \cdots \mid \{ x_1 = v_1, \ldots, x_{i-1} = v_{i-1}, x_i = [\cdot], x_{i+1} = e_{i+1}, \ldots, x_n = e_n \} \mid [\cdot].\!x
\end{align*}
\]

Note that the names of the fields \( x_i \) are included as part of the type.

Evaluation rule: 

\[ \{ x_1 = v_1, \ldots, x_n = v_n \}.\!x_i \rightarrow v_i, \quad 1 \leq i \leq n \]

Typing rules:

\[
\begin{align*}
\Gamma &\vdash e_i : \tau_i, \; 1 \leq i \leq n & \Gamma &\vdash e : \{ x_1 : \tau_1, \ldots, x_n : \tau_n \} \\
\Gamma &\vdash \{ x_1 = e_1, \ldots, x_n = e_n \} : \{ x_1 : \tau_1, \ldots, x_n : \tau_n \} \\
\Gamma &\vdash e.\!x_i : \tau_i \end{align*}
\]

3.4 Sums

Sums are useful for representing datatypes that can have multiple forms. For example, a tail of a list can either be another nonempty list or \texttt{null}.
Syntax:

\[
e ::= \cdots | \text{inL}_{\tau_1 + \tau_2} e | \text{inR}_{\tau_1 + \tau_2} e \mid \text{match } e_0 \text{ with } e_1 | e_2
\]

\[
\tau ::= \cdots | \tau_1 + \tau_2
\]

\[
v ::= \cdots | \text{inL}_{\tau_1 + \tau_2} v | \text{inR}_{\tau_1 + \tau_2} v
\]

\[
E ::= \cdots | \text{inL} [\cdot] | \text{inR} [\cdot] \mid \text{match } [\cdot] \text{ with } e_1 | e_2
\]

The \text{inL} and \text{inR} constructs are called \textit{left injection} and \textit{right injection}, respectively.

Evaluation rules:

\[
\text{match } (\text{inL}_{\tau_1 + \tau_2} v) \text{ with } e_1 | e_2 \rightarrow e_1 v \quad \text{match } (\text{inR}_{\tau_1 + \tau_2} v) \text{ with } e_1 | e_2 \rightarrow e_2 v
\]

Here \(e_1\) and \(e_2\) are functions and must have the same codomain type in order for the whole \text{match} expression to have a type. This formulation allows us to have heterogeneous sums. Note also that the evaluation of \(e_1\) and \(e_2\) are lazy: only one of them will be evaluated, and only after the choice has been made.

Typing rules:

\[
\begin{align*}
\Gamma \vdash e : \tau_1 & \quad & \Gamma \vdash e : \tau_2 \quad & \Gamma \vdash \text{inL}_{\tau_1 + \tau_2} e : \tau_1 + \tau_2 \quad & \Gamma \vdash \text{inR}_{\tau_1 + \tau_2} e : \tau_1 + \tau_2 \quad & \Gamma \vdash \text{match } e_0 \text{ with } e_1 | e_2 : \tau_3 \quad & \Gamma \vdash e_1 : \tau_1 \rightarrow \tau_3 \quad & \Gamma \vdash e_2 : \tau_2 \rightarrow \tau_3
\end{align*}
\]

To give an example of the sum type, consider the sum of two unit types, \textit{unit} + \textit{unit}. This type has exactly two elements, namely \text{inL} \text{null} and \text{inR} \text{null}. We could take this as a definition of the type \textit{bool} with elements \(\text{true} \triangleq \text{inL} \text{null}\) and \(\text{false} \triangleq \text{inR} \text{null}\). The lazy conditional statement \(\text{if } b \text{ then } e_1 \text{ else } e_2\) could then be written as \text{match } b \text{ with } \lambda z. e_1 | \lambda z. e_2.

OCaml has a construct that is a generalization of the sum type. The OCaml syntax is

\[
\text{type } t = C_1 \text{ of } t_1 \mid \ldots \mid C_n \text{ of } t_n \mid D_1 \mid \ldots \mid D_m
\]

Such datatypes are also called \textit{variants}. The \(C_i\) and \(D_i\) are \textit{constructors}, and must be globally (across all types) unique to avoid confusion as to which type a particular constructor refers to (in our sum type, the ambiguity is resolved by decorating \text{inL} and \text{inR} with subscripts \(\tau_1 + \tau_2\)).

4 Denotational Semantics

We now give the denotational semantics for type domains of \(\lambda^{++*}\), the strongly-typed \(\lambda\)-calculus with sum and product types.

\[
\begin{align*}
\mathcal{T}[\tau \rightarrow \tau'] & \triangleq \mathcal{T}[\tau] \rightarrow \mathcal{T}[\tau'] \\
\mathcal{T}[\tau \times \tau'] & \triangleq \mathcal{T}[\tau] \times \mathcal{T}[\tau'] \\
\mathcal{T}[\tau + \tau'] & \triangleq \mathcal{T}[\tau] + \mathcal{T}[\tau']
\end{align*}
\]

As before, our contract for this language is:

\[
\rho \models \Gamma \quad \Gamma \vdash e : \tau \quad \Rightarrow \quad \mathcal{C}[e] \in \mathcal{T}[\tau].
\]
The remaining semantic rules are:

\[
\begin{align*}
C[(e_1, e_2)] & \triangleq (C[e_1] \cdot C[e_2]) \\
C[#1 e] & \triangleq \pi_1(C[e]) \\
C[#2 e] & \triangleq \pi_2(C[e]) \\
C[\text{inL}_{\tau_1 + \tau_2} e] & \triangleq \iota_1(C[e]) \\
C[\text{inR}_{\tau_1 + \tau_2} e] & \triangleq \iota_2(C[e])
\end{align*}
\]

\[
\begin{align*}
C[\text{match } e_0 \text{ with } e_1 | e_2] & \triangleq \begin{cases} 
(C[e_1] \cdot \Gamma) v, \text{ if } C[e_0] \cdot \Gamma = \iota_1 v, \\
(C[e_2] \cdot \Gamma) v, \text{ if } C[e_0] \cdot \Gamma = \iota_2 v 
\end{cases}
= \text{match } C[e_0] \cdot \Gamma \text{ with } \iota_1 v \rightarrow (C[e_1] \cdot \Gamma) v \mid \iota_2 v \rightarrow (C[e_2] \cdot \Gamma) v,
\end{align*}
\]

where \(\pi_n\) is the (mathematical) projection operator that selects the \(n\)th element of a product and \(\iota_n\) is the injection operator that injects an element into a coproduct. These meta-operations are also well-typed, but we omit the annotations:

\[
\iota_i : T[\tau_1] \times T[\tau_2] \rightarrow T[\tau_i] \quad \iota_i : T[\tau_i] \rightarrow T[\tau_1] + T[\tau_2]
\]

for \(i \in \{1, 2\}\).

### 5 Adding Recursion

So far this language is not Turing-complete, because there is no way to do unbounded recursion. This is true because there is no possibility of nontermination. The easiest way to add this capability to the language is to add support for recursive functions.

To do this, we first extend the definition of an expression:

\[
e ::= \cdots | \text{rec } f : \sigma \rightarrow \tau.\lambda x : \sigma. e
\]

The new keyword \texttt{rec} defines a recursive function named \(f\) such that both \(x\) and \(f\) are in scope inside \(e\). Intuitively, the meaning of \(\text{rec } f : \sigma \rightarrow \tau.\lambda x : \sigma. e\) is the least fixpoint of the map \(\lambda f \mapsto \lambda x : \sigma. e\), where both \(f\) and \(\lambda x : \sigma. e\) are of type \(\sigma \rightarrow \tau\).

For example, we would write the recursive function

\[
f(x) = \text{if } x > 0 \text{ then } 1 \text{ else } f(x + 1)
\]

as

\[
\text{rec } f : \text{int} \rightarrow \text{int}.\lambda x : \text{int}. \text{if } x > 0 \text{ then } 1 \text{ else } f(x + 1).
\]

The small-step operational semantics evaluation rule for \texttt{rec} is:

\[
\text{rec } f : \sigma \rightarrow \tau.\lambda x : \sigma. e \rightarrow \lambda x : \sigma. e\{\text{rec } f : \sigma \rightarrow \tau.\lambda x : \sigma. e/f\}
\]

and the typing rule for \texttt{rec} is

\[
\frac{\Gamma, f : \sigma \rightarrow \tau, x : \sigma \vdash e : \tau}{\Gamma \vdash \text{rec } f : \sigma \rightarrow \tau.\lambda x : \sigma. e : \sigma \rightarrow \tau}.
\]

The denotational semantics is defined in terms of the fix operator on domains:

\[
C[\text{rec } f : \sigma \rightarrow \tau.\lambda x : \sigma. e] \triangleq \text{fix } \lambda g \in T[\sigma \rightarrow \tau].\lambda v \in T[\sigma].C[e] \cdot \Gamma[(\sigma \rightarrow \tau)/f, \sigma/x] \rho[v/x, g/f]
\]
Of course, whenever we take a fixpoint, we have to make sure that a fixpoint exists. We know that the function satisfies continuity and monotonicity because we are writing in the metalanguage. However, for a fixpoint to exist, \( T[J: \sigma \to \tau] \) must be a pointed CPO. But for this to be true, we have to make sure \( \bot \) is in the codomain of the function. We therefore redefine

\[
T[J:int] \triangleq Z \bot \quad T[J:bool] \triangleq 2 \bot \quad T[J:unit] \triangleq \{\text{null}\} \bot
\]

and define the functions and product domains \( T[J: \sigma \to \tau] \) and \( T[J: \sigma * \tau] \) inductively as before, which will now be pointed CPOs.

In the disjoint sum (coproduct) domain construction shown in class, we tagged the elements of the two domains and took the union. This resulted in a non-pointed CPO, even if the two domains were pointed CPOs, so we must add a new bottom element \( \bot \). But this construction is quite unsatisfactory, since iterating it leads to the proliferation of useless bottoms. Instead, we use the following alternative construction. Given pointed CPOs \( D \) and \( E \), form the domain consisting of the set

\[
\{i_1(d) \mid d \in D \land d \neq \bot_D\} \cup \{i_2(e) \mid e \in E \land e \neq \bot_E\} \cup \{\bot\},
\]

where \( \bot \) is a new element, ordered by

\[
x \sqsubseteq y \iff x = \bot \lor (x = i_1(d) \land y = i_1(d') \land d \sqsubseteq_D d') \lor (x = i_2(e) \land y = i_2(e') \land e \sqsubseteq_E e').
\]

This is called the smash sum of \( D \) and \( E \).

We also have to change our contract to account for the possibility of nontermination:

\[
\rho \models \Gamma \land \Gamma \vdash e : \tau \Rightarrow C[J]e \rho \in T[\tau] \bot.
\]

Finally, we have to lift our semantics to take nontermination into account. For example, we should change the denotation of a pair to:

\[
C[J](e_1, e_2) \Gamma \rho \triangleq \begin{cases} (C[J]e_1 \Gamma \rho, C[J]e_2 \Gamma \rho), & \text{if both } C[J]e_1 \Gamma \rho \neq \bot \text{ and } C[J]e_2 \Gamma \rho \neq \bot, \\ \bot, & \text{otherwise.} \end{cases}
\]

We can write this conveniently using our metalanguage let construct:

\[
C[J](e_1, e_2) \Gamma \rho \triangleq \begin{cases} \text{let } v_1 \in T[\tau_1] = C[J]e_1 \Gamma \rho \text{ in } \\ \text{let } v_2 \in T[\tau_2] = C[J]e_2 \Gamma \rho \text{ in } \\ \langle v_1, v_2 \rangle, \end{cases}
\]

where \( \Gamma \vdash (e_1, e_2) : \tau_1 \times \tau_2 \). Recall that mathematical let is defined as:

\[
\text{let } x \in D = e_1 \text{ in } e_2 \triangleq (\lambda x \in D. e_2)^x e_1.
\]