

CS 611 Advanced Programming Languages

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Lecture 34
Type inference & ML polymorphism
18 Nov 01

Type inference

Simple typed language:

$e ::= x \mid b \mid \lambda x:\tau. e \mid e_1 e_2 \mid e_1 \oplus e_2$
 $\mid \text{if } e_0 \text{ then } e_1 \text{ else } e_2 \mid \text{let } x=e_1 \text{ in } e_2$
 $\mid \text{rec } y:\tau_1 \rightarrow \tau_2. (\lambda x. e)$
 $\tau ::= \text{unit} \mid \text{bool} \mid \text{int} \mid \tau_1 \rightarrow \tau_2$

- Question: Do we really need to write type declarations?

$e ::= \dots \mid \lambda x. e \mid \dots \mid \text{rec } y. (\lambda x. e)$

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Typing rules

$e ::= x \mid b \mid \lambda x. e \mid e_1 e_2 \mid e_1 \oplus e_2$
 $\mid \text{if } e_0 \text{ then } e_1 \text{ else } e_2 \mid \text{let } x=e_1 \text{ in } e_2 \mid \text{rec } y. \lambda x. e$

$$\frac{\Gamma, x:\tau \vdash e : \tau'}{\Gamma \vdash \lambda x. e : \tau \rightarrow \tau'}$$

Problem: how does type checker construct proof?

$$\frac{\Gamma, y:\tau \rightarrow \tau', x:\tau \vdash e : \tau'}{\Gamma \vdash \text{rec } y. \lambda x. e : \tau \rightarrow \tau'}$$

Guess τ ?

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Example

let square = $\lambda z. z^*z$ in
 $(\lambda f. \lambda x. \lambda y.$
 $\text{if } (f \ x \ y)$
 $\text{then } (f \ (\text{square } x) \ y)$
 $\text{else } (f \ x \ (f \ x \ y)))$

What is the type of this program?

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Example

let square = $\lambda z. z^*z$ in
 $(\lambda f. \lambda x. \lambda y.$
 $\text{if } (f \ x \ y)$
 $\text{then } (f \ (\text{square } x) \ y)$
 $\text{else } (f \ x \ (f \ x \ y)))$

$z : \text{int}$
 $s, \text{square} : \text{int} \rightarrow \text{int}$
 $f : \tau_x \rightarrow \tau_y \rightarrow \text{bool}$
 $y : \tau_y = \text{bool}$
 $x : \tau_x = \text{int}$

Answer:
 $(\text{int} \rightarrow \text{bool} \rightarrow \text{bool}) \rightarrow \text{int} \rightarrow \text{bool} \rightarrow \text{bool}$

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Type inference

- Goal: reconstruct types even after erasure
- Idea: run ordinary type-checking algorithm, generate *type equations* on *type variables*

$f:T2, x:T5 \vdash f : \text{int} \rightarrow T6 \quad f:T2, x:T5 \vdash 1 : \text{int}$

$f:T2, x:T5 \vdash f \ 1 : T6$

$f:T2 \vdash \lambda x. f \ 1 : T1 \ (=T5 \rightarrow T6) \quad y:T3 \vdash y : T4 \quad (T3=T4)$

$\vdash \lambda f. \lambda x. f \ 1 : T2 \rightarrow T1 \quad \vdash (\lambda y. y) : T2 \quad (T2=T3 \rightarrow T4)$

$\vdash (\lambda f. \lambda x. (f \ 1)) (\lambda y. y) : T1$

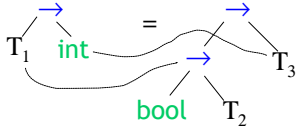
$T2 = T3 \rightarrow T4, T3 = T4, T1 = T5 \rightarrow T6, T2 = \text{int} \rightarrow T6$

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Unification

- How to solve equations?
- Idea: given equation $\tau_1 = \tau_2$, *unify* type expressions to solve for variables in both
- Example: $T_1 \rightarrow \text{int} = (\text{bool} \rightarrow T_2) \rightarrow T_3$
- Result: *substitution* $T_1 \mapsto \text{bool} \rightarrow T_2, T_3 \mapsto \text{int}$



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Robinson's algorithm (1965)

- *Unification* produces *weakest substitution* that equates two trees
 - $T_1 \rightarrow \text{int} = (\text{bool} \rightarrow T_2) \rightarrow T_3$ equated by any $T_1 \mapsto \text{bool} \rightarrow T_2, T_3 \mapsto \text{int}, T_2 \mapsto \tau$
 - **Defn.** S_1 is weaker than S_2 if $S_2 = S_3 \circ S_1$ for S_3 a non-identity substitution
- **Unify**(E) where E is set of equations gives weakest equating substitution: define recursively

Unify($T = \tau, E$) = **Unify**($E\{\tau/T\}$) $\circ [T \mapsto \tau]$
(if $T \notin \text{FTV}[\tau]$)

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Rest of algorithm

Unify($T = \tau, E$) = **Unify**($E\{\tau/T\}$) $\circ [T \mapsto \tau]$
(if $T \notin \text{FTV}[\tau]$)

Unify(\emptyset) = \emptyset

Unify($B = B, E$) = **Unify**(E)

Unify($B_1 = B_2, E$) = ?

Unify($T = T, E$) = **Unify**(E)

Unify($\tau_1 \rightarrow \tau_2 = \tau_3 \rightarrow \tau_4, E$)
= **Unify**($\tau_1 = \tau_3, \tau_2 = \tau_4, E$)

Termination?

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Type inference algorithm

- $\mathcal{R}(e, \Gamma, S) = \langle \tau, S' \rangle$ means
“Reconstructing the type of e in typing context Γ with respect to substitution S yields type τ , identical or stronger substitution S' or
“ S' is weakest substitution no weaker than than S such that $S'(\Gamma) \vdash e : S'(\tau)$ ”

Define: **Unify**(E, S) = **Unify**(SE) $\circ S$

- solve substituted equations E and fold in new substitutions

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Inductive defn of inference

- $\mathcal{R}(e, \Gamma, S) = \langle \tau, S' \rangle \Leftrightarrow$ “ S' is weakest substitution stronger than (or same as) S such that $S'(\Gamma) \vdash e : S'(\tau)$ ”
- **Unify**(E, S) = **Unify**(SE) $\circ S$

$\mathcal{R}(n, \Gamma, S) = \langle \text{int}, S \rangle$ $\mathcal{R}(\#t, \Gamma, S) = \langle \text{bool}, S \rangle$

$\mathcal{R}(x, \Gamma, S) = \langle \Gamma(x), S \rangle$

$\mathcal{R}(e_1 e_2, \Gamma, S) = \text{let } \langle T1, S1 \rangle = \mathcal{R}(e_1, \Gamma, S) \text{ in}$
 $\text{let } \langle T2, S2 \rangle = \mathcal{R}(e_2, \Gamma, S1) \text{ in}$
 $\langle T_f, \text{Unify}(T1=T2 \rightarrow T_f, S2) \rangle$

$\mathcal{R}(\lambda x.e, \Gamma, S) = \text{let } \langle T1, S1 \rangle = \mathcal{R}(e, \Gamma[x \mapsto T1], S) \text{ in}$
 $\langle T_f \rightarrow T1, S1 \rangle$

where T_f is “fresh” (not mentioned anywhere in e, Γ, S)

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Example

$\mathcal{R}((\lambda x.x) 1, \emptyset, \emptyset) =$
 $\text{let } \langle T1, S1 \rangle = \mathcal{R}(\lambda x.x, \emptyset, \emptyset) \text{ in}$
 $\text{let } \langle T2, S2 \rangle = \mathcal{R}(1, \emptyset, S1) \text{ in}$
 $\langle T3, \text{Unify}(T1 \rightarrow T3 = T2, S2) \rangle$
 $\mathcal{R}(\lambda x.x, \emptyset, \emptyset) = \text{let } \langle T1, S1 \rangle = \mathcal{R}(x, \Gamma[x \mapsto T4], \emptyset) \text{ in}$
 $\langle T4 \rightarrow T1, S1 \rangle$
 $= \langle T4 \rightarrow T4, \emptyset \rangle$
 $= \text{let } \langle T2, S2 \rangle = \mathcal{R}(1, \emptyset, \emptyset) \text{ in}$
 $\langle T3, \text{Unify}(T2 \rightarrow T3 = T4 \rightarrow T4, \emptyset) \rangle$
 $= \langle T3, \text{Unify}(\text{int} \rightarrow T3 = T4 \rightarrow T4, \emptyset) \rangle$
 $= \langle T3, \text{Unify}(\text{int} = T4, T3 = T4, \emptyset) \rangle$
 $= \langle T3, \text{Unify}(T3 = \text{int}, [T4 \mapsto \text{int}]) \rangle$
 $= \langle T3, [T3 \mapsto \text{int}, T4 \mapsto \text{int}] \rangle$

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Polymorphism

$\mathcal{R}(\lambda x.x, \emptyset, \emptyset) = \text{let } \langle T_1, S_1 \rangle = \mathcal{R}(x, \Gamma[x \rightarrow T_4], \emptyset) \text{ in}$
 $\langle T_4 \rightarrow T_1, S_1 \rangle$
 $= \langle T_4 \rightarrow T_4, \emptyset \rangle$

- Reconstruction algorithm doesn't solve type fully... opportunity!
- $\lambda x.x$ can have type $T_4 \rightarrow T_4$ for any T_4
 - polymorphic (= "many shape") term
 - Could reuse same expression multiple places in program, with different types:

let id = ($\lambda x.x$) in ... (f id) ... (g x id) ... id

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Polymorphic types

- Type expression may have some unsolved type identifiers after type reconstruction
- Type $T_4 \rightarrow T_4$ is a *type schema* that can be instantiated with any T_4 to make a type
- ML idea: let can bind identifiers to polymorphic terms
 - typing context Γ maps variable either to
 - type τ or
 - type schema $\forall T_1, \dots, T_n. \tau$ where $\text{FTV}(\tau) \subseteq \{T_1, \dots, T_n\}$
- Can still do type inference! (ML)

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Typing rules

$\Gamma \in \text{Var} \rightarrow \sigma$

$\sigma ::= \tau \mid \forall T_1, \dots, T_n. \tau$

$\Delta = \{T_1, \dots, T_n\}$ (Δ : set of legal type variables)

$\Delta \vdash \tau$ (judgment: τ is well formed)

$\Delta; \Gamma \vdash e : \tau$

$$\frac{}{\Delta; \Gamma, x:\tau \vdash x : \tau} \quad \frac{\Delta; \Gamma, x:\tau \vdash e : \tau' \quad \Delta \vdash \tau \quad \Delta \vdash \tau'}{\Delta; \Gamma \vdash \lambda x.e : \tau \rightarrow \tau'}$$

$$\frac{\Delta \vdash \tau_i \quad \forall i \in 1..n}{\Delta; \Gamma, x:(\forall T_1, \dots, T_n. \tau) \vdash x : \tau\{T_i/T_i \quad \forall i \in 1..n\}}$$

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More typing rules

$$\frac{\Delta; \Gamma \vdash e_1 : \tau \rightarrow \tau' \quad \Delta; \Gamma \vdash e_2 : \tau \rightarrow \tau' \quad \Delta \vdash \tau, \tau'}{\Delta; \Gamma \vdash e_1 e_2 : \tau'}$$

$$\frac{\Delta \cup \{T_1, \dots, T_n\}; \Gamma \vdash e_1 : \tau \quad \Delta \cup \{T_1, \dots, T_n\} \vdash \tau \quad \Delta; \Gamma, x:\forall T_1, \dots, T_n. \tau \vdash e_2 : \tau'}{\Delta; \Gamma \vdash \text{let } x = e_1 \text{ in } e_2 : \tau'}$$

$$\frac{\emptyset; \text{id} : \forall T_1. T_1 \rightarrow T_1 \vdash \text{id} : \text{int} \rightarrow \text{int} \quad T_1; \emptyset \vdash (\lambda x.x) : T_1 \rightarrow T_1 \quad \emptyset; \text{id} : \forall T_1. T_1 \rightarrow T_1 \vdash \text{id} 2 : \text{int}}{\emptyset; \emptyset \vdash \text{let id} = (\lambda x.x) \text{ in id } 2 : \text{int}}$$

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Algorithm \mathcal{W} (Milner)

- Infers types in language with let-bound type schemas! (& letrec too)
- $\mathcal{W}(e, \Gamma, S) = \langle \tau, S' \rangle$ gives type, subst S' as before, (but Γ can map vars to type schemas)

$\mathcal{W}(x, \Gamma, S) = \text{case } \Gamma(x) \text{ of}$

$\tau \Rightarrow \langle \tau, S \rangle$
 $\mid \forall T_1, \dots, T_n. \tau \Rightarrow \langle \tau\{T_i/T_i\}, S \rangle$

$\mathcal{W}(\text{letrec } x = e_1 \text{ in } e_2, \Gamma, S) =$

let $\Gamma' = \Gamma[x \rightarrow T_1]$ in let $\langle T_1, S_1 \rangle = \mathcal{W}(e_1, \Gamma', S)$ in

let $S_2 = \text{Unify}(\{T_1 = T_1\}, S_1)$ in

let $\Gamma'' = \Gamma[x \rightarrow \text{Generic}(T_1, \Gamma, S_2)]$ in

$\mathcal{W}(e_2, \Gamma'', S_2)$

$\text{Generic}(\tau, \Gamma, S) = \forall T_1, \dots, T_n. S\tau$
 where $\{T_1, \dots, T_n\} = \text{FTV}(S\tau) - \text{FTV}(S\Gamma)$

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