

1 Trouble with **while**

If we try to define $\mathcal{C}[\mathbf{while\ } b \mathbf{ do\ } c]$ in the obvious manner, we get

$$\begin{aligned} \mathcal{C}[\mathbf{while\ } b \mathbf{ do\ } c]\sigma &= \text{if } \neg\mathcal{B}[b] \text{ then } \sigma \\ &\quad \text{else if } \mathcal{C}[c]\sigma = \perp \text{ then } \perp \\ &\quad \text{else } \mathcal{C}[\mathbf{while\ } b \mathbf{ do\ } c](\mathcal{C}[c]\sigma) \end{aligned}$$

However, $\mathcal{C}[\mathbf{while\ } b \mathbf{ do\ } c]$ appears on both sides—this is really an equation, not a definition¹. Looking at this more generally, $\mathcal{C}[\mathbf{while\ } b \mathbf{ do\ } c]$ is a solution to the equation

$$x = F(x)$$

where

$$F = \lambda f \in \Sigma \rightarrow \Sigma_{\perp}. \lambda \sigma \in \Sigma_{\perp}. \text{if } \neg\mathcal{B}[b] \text{ then } \sigma \text{ else } f(\mathcal{C}[c]\sigma).$$

(F is simplified here slightly, by ignoring the case where c fails to terminate.) What we would like to do is define

$$\begin{aligned} \mathcal{C}[\mathbf{while\ } b \mathbf{ do\ } c] &= \text{fix}(F) \\ &= \text{fix}(\lambda f \in \Sigma \rightarrow \Sigma_{\perp}. \lambda \sigma \in \Sigma. \text{if } \neg\mathcal{B}[b]\sigma \text{ then } \sigma \text{ else } f(\mathcal{C}[c]\sigma)) \end{aligned}$$

But which fixed point of F do we want? We would like to take the “least” fixed point, in the sense that we want $\mathcal{C}[\mathbf{while\ } b \mathbf{ do\ } c]$ to give a non- \perp result only when required by the intended semantics. (For example, we want $\mathcal{C}[\mathbf{while\ true\ do\ skip}]\sigma = \perp$ for all σ .) The rest of this lecture will expand on this notion of least fixed point, with a look at the underlying theory of *partial orders*.

Iterating F applied to some “minimal” function $f_{\perp} = \lambda \sigma. \perp$ allows us to create a sequence of successively better approximations for $\mathcal{C}[\mathbf{while\ } b \mathbf{ do\ } c]$:

$$\begin{aligned} f_0 &= f_{\perp} \\ f_1 &= F(f_{\perp}) \\ &= \lambda \sigma. \text{if } \neg\mathcal{B}[b] \text{ then } \sigma \text{ else } \perp \\ f_2 &= F(F(f_{\perp})) \\ &= \lambda \sigma. \text{if } \neg\mathcal{B}[b]\sigma \text{ then } \sigma \text{ else} \\ &\quad \text{if } \neg\mathcal{B}[b]\mathcal{C}[c]\sigma \text{ then } \mathcal{C}[c]\sigma \text{ else } \perp \\ f_3 &= F(F(F(f_{\perp}))) \\ &= \lambda \sigma. \text{if } \neg\mathcal{B}[b]\sigma \text{ then } \sigma \text{ else} \\ &\quad \text{if } \neg\mathcal{B}[b]\mathcal{C}[c]\sigma \text{ then } \mathcal{C}[c]\sigma \text{ else} \\ &\quad \text{if } \neg\mathcal{B}[b]\mathcal{C}[c]\mathcal{C}[c]\sigma \text{ then } \mathcal{C}[c]\mathcal{C}[c]\sigma \text{ else } \perp \\ &\quad \vdots \\ f_n &= F^n(f_{\perp}) \\ &\quad \vdots \end{aligned}$$

The “limit” of this sequence will be the denotation of **while** b **do** c . To take this “limit”, we will consider the approximations as an increasing sequence $f_0 \leq f_1 \leq f_2 \leq \dots$, and then take the least upper bound. We must first study partial orders to get the needed machinery.

¹It’s important to point out here that our denotations will be defined by structural induction, so that it is okay in this case to assume that $\mathcal{B}[b]$ and $\mathcal{C}[c]$ are defined.

2 Partial Orders

A *partial order* (also known as a *partially ordered set* or *poset*) is a pair (S, \sqsubseteq) , where

- S is a set of elements.
- \sqsubseteq is a relation on S which is:
 - i. reflexive: $x \sqsubseteq x$
 - ii. transitive: $(x \sqsubseteq y \wedge y \sqsubseteq z) \Rightarrow x \sqsubseteq z$
 - iii. antisymmetric: $(x \sqsubseteq y \wedge y \sqsubseteq x) \Rightarrow x = y$

Examples:

- (\mathbf{Z}, \leq) , where \mathbf{Z} is the integers and \leq is the usual ordering.
- $(\mathbf{Z}, =)$ (Note that unequal elements are incomparable in this order. Partial orders ordered by the identity relation, $=$, are called *discrete*.)
- $(2^S, \subseteq)$ (Here, 2^S denotes the powerset of S , the set of all subsets of S , often written $\mathcal{P}(S)$, and in Winskel, $\mathcal{Pow}(S)$.)
- $(2^S, \supseteq)$
- (S, \supseteq) , if we are given that (S, \sqsubseteq) is a partial order.
- $(\omega, |)$, where $\omega = \{0, 1, 2, \dots\}$ and $a|b \Leftrightarrow (a \text{ divides } b) \Leftrightarrow (b = ka \text{ for some } k \in \omega)$. Note that for any $n \in \omega$, we have $n|0$; we call 0 an upper bound for ω (but only in this ordering, of course!).

Non-examples:

- $(\mathbf{Z}, <)$ is not a partial order, because $<$ is not reflexive.
- $(\mathbf{Z}, \sqsubseteq)$, where $m \sqsubseteq n \Leftrightarrow |m| \leq |n|$, is not a partial order because \sqsubseteq is not anti-symmetric: $-1 \sqsubseteq 1$ and $1 \sqsubseteq -1$, but $-1 \neq 1$.

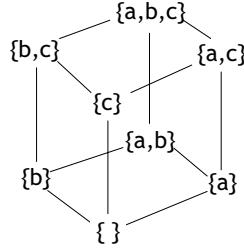
The “partial” in partial order comes from the fact that our definition does not require these orders to be total; *e.g.*, in the partial order $(2^{\{a,b\}}, \subseteq)$, the elements $\{a\}$ and $\{b\}$ are incomparable: neither $\{a\} \subseteq \{b\}$ nor $\{b\} \subseteq \{a\}$ hold.

Hasse diagrams Partial orders can be described pictorially using *Hasse diagrams*². In a Hasse diagram, each element of the partial order is displayed as a (possibly labeled) point, and lines are drawn between these points, according to these rules:

1. If x and y are elements of the partial order, and $x \sqsubseteq y$, then the point corresponding to x is drawn lower in the diagram than the point corresponding to y .
2. A line is drawn between the points representing two elements x and y iff $x \sqsubseteq y$ and $\neg \exists z$ in the partial order, distinct from x and y , such that $x \sqsubseteq z$ and $z \sqsubseteq y$ (*i.e.*, the ordering relation between x and y is not due to transitivity).

An example of a Hasse diagram for the partial order on the set $2^{\{a,b,c\}}$ using \subseteq as the binary relation is:

²Named after Helmut Hasse, 1898-1979. Hasse published fundamental results in algebraic number theory, including the Hasse (or “local-global”) principle. He succeeded Hilbert and Weyl as the chair of the Mathematical Institute at Göttingen.



Least upper bounds Given a partial order (S, \sqsubseteq) , and a subset $B \subseteq S$, y is an *upper bound* of B iff $\forall x \in B. x \sqsubseteq y$. In addition, y is a *least upper bound* iff y is an upper bound and $y \sqsubseteq z$ for all upper bounds z of B . We may abbreviate “least upper bound” as LUB or lub. We shall notate the LUB of a subset B as $\sqcup B$. We may also make this an infix operator, as in $\sqcup\{x_1, \dots, x_m\} = x_1 \sqcup \dots \sqcup x_m$.

Chains A *chain* is a pairwise comparable sequence of elements from a partial order (*i.e.*, elements $x_0, x_1, x_2 \dots$ such that $x_0 \sqsubseteq x_1 \sqsubseteq x_2 \sqsubseteq \dots$). For any finite chain, its LUB is its last element (*e.g.*, $\sqcup\{x_0, x_1, \dots, x_n\} = x_n$). Infinite chains (Winskel: ω -chains) may also have LUBs.

Complete partial orders A *complete partial order* (cpo or CPO) is a partial order in which every chain has a LUB. Note that the requirement for *every* chain is trivial for finite chains (and thus finite partial orders) – it is the infinite chains that can cause trouble.

Some examples of cpos:

- $(2^S, \subseteq)$ Here S itself is the LUB for the chain of all elements.
- $(\omega \cup \{\infty\}, \leq)$ Here ∞ is the LUB for any infinite chain: $\forall w \in \omega. w \leq \infty$.
- $([0, 1], \leq)$ where $[0, 1]$ is the closed continuum, and 1 is a LUB for infinite chains. Note that making the continuum open at the top – $[0, 1)$ – would cause this to no longer be a cpo, since there would be no LUB for infinite chains such as $\frac{1}{2}, \frac{2}{3}, \frac{3}{4}, \dots$
- $(S, =)$ This is a discrete cpo, just as it is a discrete partial order. The only infinite chains are of the sort $x_i \sqsubseteq x_i \sqsubseteq x_i \dots$, of which x_i is itself a LUB.

Even if (S, \sqsubseteq) is a cpo, (S, \supseteq) is not necessarily a cpo. Consider $([0, 1], \leq)$, which is a cpo. Reversing its binary relation yields $([0, 1], \geq)$ which is not a cpo, just as $([0, 1], \leq)$ above was not.

CPOs can also have a least element, written \perp , such that $\forall x. \perp \sqsubseteq x$. We call a cpo with such an element a *pointed cpo*. Winskel instead uses *cpo with bottom*.

3 Least fixed points of functions

Recall that at the end of the last lecture we were attempting to define the least fixed point operator *fix* over the domain $(\Sigma \rightarrow \Sigma_{\perp})$ so that we could determine calculate fixed points of $F : (\Sigma \rightarrow \Sigma_{\perp}) \rightarrow (\Sigma \rightarrow \Sigma_{\perp})$. It was unclear, however, what the “least” fixed point of this domain would be – how is one function from states to states “less” than another? We’ve now developed the theory to answer that question.

We define the ordering of states by *information content*: $\sigma \sqsubseteq \sigma'$ iff σ gives less (or at most as much) information than σ' . Non-termination is defined to provide less information than any other state: $\forall \sigma \in \Sigma. \perp \sqsubseteq \sigma$. In addition, we have that $\sigma \sqsubseteq \sigma$. No other pairs of states are defined to be comparable. The lifted set of possible states Σ_{\perp} can now be characterized as a flat cpo (a lifted discrete cpo):

- Its elements are elements of $\Sigma \cup \{\perp\}$.
- The ordering relation \sqsubseteq satisfies the reflexive, transitive, and anti-symmetric properties.

- There are three types of infinite chains, each with a LUB:

1. $\perp \sqsubseteq \perp \sqsubseteq \dots$, LUB = \perp
2. $\sigma \sqsubseteq \sigma \sqsubseteq \dots$, LUB = σ
3. $\perp \sqsubseteq \perp \sqsubseteq \dots \sqsubseteq \sigma \sqsubseteq \sigma \sqsubseteq \dots$, LUB = σ

4 Functions

We are now ready to define an ordering relation on functions. Functions will be ordered using a *pointwise ordering* on their results. Given a cpo E , a domain D , $f \in D \rightarrow E$, and $g \in D \rightarrow E$:

$$f \sqsubseteq_{D \rightarrow E} g \stackrel{def}{\iff} \forall x \in D. f(x) \sqsubseteq_E g(x)$$

Note that we are defining a new partial order over $D \rightarrow E$, and that this cpo is pointed if E is pointed, since $\perp_{D \rightarrow E} = \lambda x \in D. \perp_E$.

As an example, consider two functions $\mathbf{Z} \rightarrow \mathbf{Z}_\perp$:

$$\begin{aligned} f &= \lambda x \in \mathbf{Z}. \text{if } x = 0 \text{ then } \perp \text{ else } x \\ g &= \lambda x \in \mathbf{Z}. x \end{aligned}$$

We conclude $f \sqsubseteq g$ because $f(x) \sqsubseteq g(x)$ for all x ; in particular, $f(0) = \perp \sqsubseteq 1 = g(0)$.

If E is a cpo, then the function space $D \rightarrow E$ is also a cpo. We show that given a chain of functions $f_1 \sqsubseteq f_2 \sqsubseteq f_3 \dots$, the function $\lambda d \in D. \bigsqcup_{n \in \omega} f_n(d)$ is a least upper bound for this chain. Consider any function g that is an upper bound for all the f_n . In that case, we have:

$$\begin{aligned} &\forall n \in \omega. \forall d \in D. f_n(d) \sqsubseteq g(d) \\ \iff &\forall d \in D. \forall n \in \omega. f_n(d) \sqsubseteq g(d) \end{aligned}$$

Because the f_n form a chain, so do the $f_n(d)$, and because E is a cpo, it has a least upper bound that is necessarily less than the upper bound $g(d)$:

$$\begin{aligned} \Rightarrow &\forall d \in D. (\bigsqcup_{n \in \omega} f_n(d)) \sqsubseteq g(d) \\ \iff &\forall d \in D. (\bigsqcup_{n \in \omega} f_n)(d) \sqsubseteq g(d) \\ \iff &\bigsqcup_{n \in \omega} f_n \sqsubseteq g \end{aligned}$$

Therefore, $D \Rightarrow E$ is a cpo under the pointwise ordering.

5 Back to **while**

It's now time to unify our dual understanding of the denotation of **while** as both a limit and a fixed point. We previously defined the denotation of **while** as both:

$$\begin{aligned} \mathcal{C}[\mathbf{while } b \text{ do } c] &= \text{fix}(F) \\ &= \text{limit of } F^n(\perp) \end{aligned}$$

However, we did not know how to define the *fix* operator over the range of F , nor did we have a definition for the least fixed point of F to take as its limit. CPOs have given us the machinery to handle these definitions now.

We assert that:

$$\mathcal{C}[\mathbf{while\ } b \mathbf{ do\ } c] = \bigsqcup_{n \in \omega} F^n(\perp)$$

As an example to give us confidence that this is the correct definition, we see that:

$$\begin{aligned} \mathcal{C}[\mathbf{while\ true\ do\ skip}] &= \bigsqcup_{n \in \omega} F^n(\perp) \\ &= \perp_{\Sigma \rightarrow \Sigma} \perp \\ &= \lambda \sigma \in \Sigma. \perp \end{aligned}$$

As we begin to construct a proof that this denotation is correct, we want to show that this limit, or LUB, is a least fixed point of F . That is, we want to show that

$$\bigsqcup_{n \in \omega} F^n(\perp)$$

is the least solution to

$$x = F(x)$$

This will not be true for arbitrary F ! We need F to be both monotonic and continuous. Consider a non-monotonic F :

$$\begin{aligned} F(x) &= \mathbf{if\ } x = \perp \mathbf{ then\ } 1 \\ &\quad \mathbf{else\ if\ } x = 1 \mathbf{ then\ } \perp \\ &\quad \mathbf{else\ if\ } x = 0 \mathbf{ then\ } 0 \end{aligned}$$

Although 0 is clearly a fixed point of this F , $F^n(\perp)$ is not a chain (the elements cycle between \perp and 1), and so we cannot take the LUB of it. Monotonicity would avoid this problem.

Even monotonicity is not enough. Consider a monotonic but non-continuous F defined over the complete partial order $(\mathbf{R} \cup \{-\infty, \infty\}, \leq)$:

$$F(x) = \mathbf{if\ } x < 0 \mathbf{ then\ } \tan^{-1}(x) \mathbf{ else\ } 1$$

The least fixed point of this F is 1. However,

$$\begin{aligned} F^1(\perp) &= \tan^{-1}(-\infty) = -\frac{\pi}{2} \\ F^2(\perp) &= \tan^{-1}\left(-\frac{\pi}{2}\right) = \dots \end{aligned}$$

For $x < 0$, $F(x) > x$ and $F(x) < 0$: $F^n(\perp)$ is a chain that approaches 0 arbitrarily closely: its LUB is 0. But $F(0) = 1$, so the LUB is not a fixed point! The least fixed point of this monotonic function is actually $1 = F(1)$. The problem with this function F is that it is not continuous at 0. In general, we will look for some form of *continuity* in F for *fix* to guarantee that the LUB formula gives us a (least) fixed point.