CS5740: Natural Language Processing

Computation Graphs

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Computation Graphs

- The descriptive language of deep learning models
- Functional description of the required computation
- Can be instantiated to do two types of computation:
 - Forward computation
 - Backward computation

 \mathbf{X}

graph:

A node is a {tensor, matrix, vector, scalar} value



An **edge** represents a function argument (and also data dependency). They are just pointers to nodes.

A **node** with an incoming **edge** is a **function** of that edge's tail node.

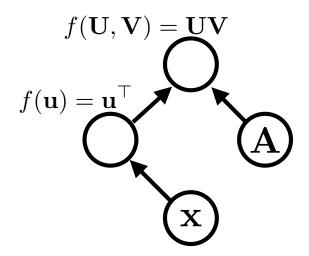
A **node** knows how to compute its value and the value of its derivative w.r.t each argument (edge) times a derivative of an arbitrary input $\frac{\partial \mathcal{F}}{\partial f(\mathbf{u})}$.

$$\frac{\partial f(\mathbf{u}) = \mathbf{u}^{\top}}{\partial \mathbf{u}} \frac{\partial f(\mathbf{u})}{\partial f(\mathbf{u})} = \left(\frac{\partial \mathcal{F}}{\partial f(\mathbf{u})}\right)^{\top}$$

$$\mathbf{x}^{\top}\mathbf{A}$$

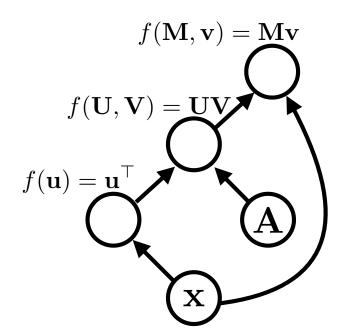
graph:

Functions can be nullary, unary, binary, ... *n*-ary. Often they are unary or binary.



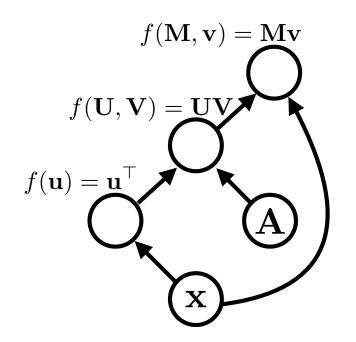
$$\mathbf{x}^{ op}\mathbf{A}\mathbf{x}$$

graph:



Computation graphs are directed and acyclic (usually)

$$\mathbf{x}^{ op}\mathbf{A}\mathbf{x}$$

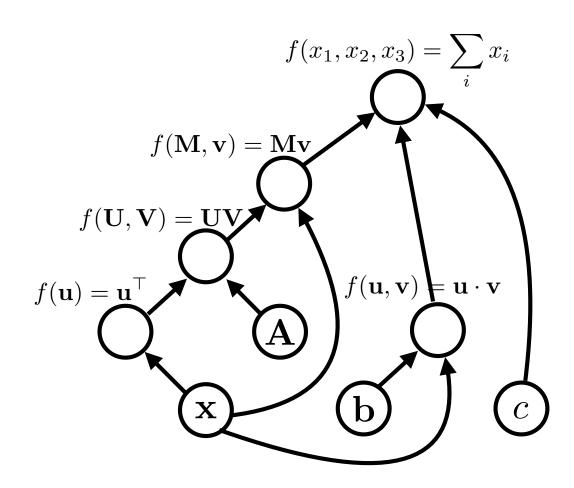


$$f(\mathbf{x}, \mathbf{A}) = \mathbf{x}^{\top} \mathbf{A} \mathbf{x}$$

$$\mathbf{A}$$

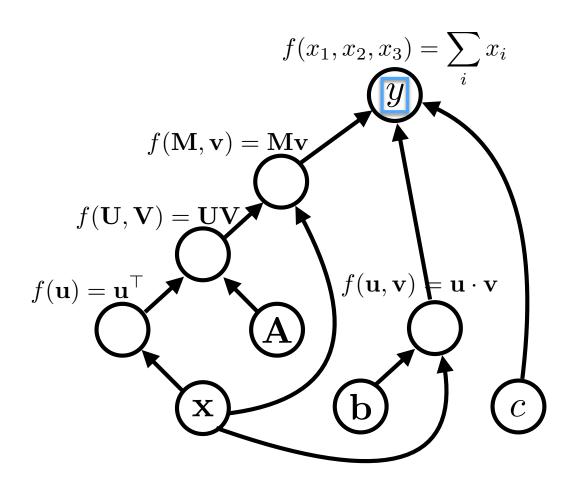
$$\frac{\partial f(\mathbf{x}, \mathbf{A})}{\partial \mathbf{x}} = (\mathbf{A}^{\top} + \mathbf{A})\mathbf{x}$$
$$\frac{\partial f(\mathbf{x}, \mathbf{A})}{\partial \mathbf{A}} = \mathbf{x}\mathbf{x}^{\top}$$

$$\mathbf{x}^{\top} \mathbf{A} \mathbf{x} + \mathbf{b} \cdot \mathbf{x} + c$$



$$y = \mathbf{x}^{\top} \mathbf{A} \mathbf{x} + \mathbf{b} \cdot \mathbf{x} + c$$

graph:



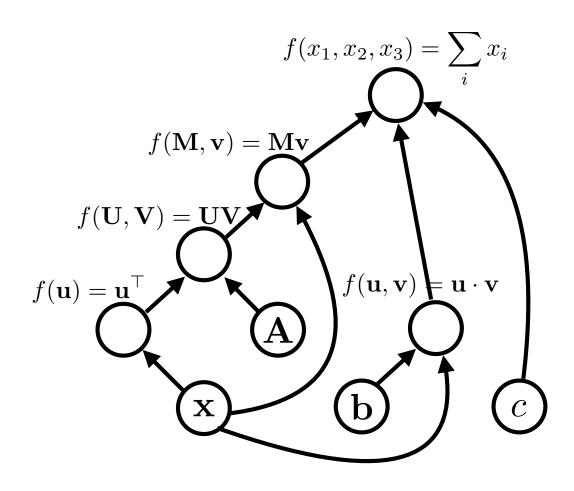
variable names are just labelings of nodes.

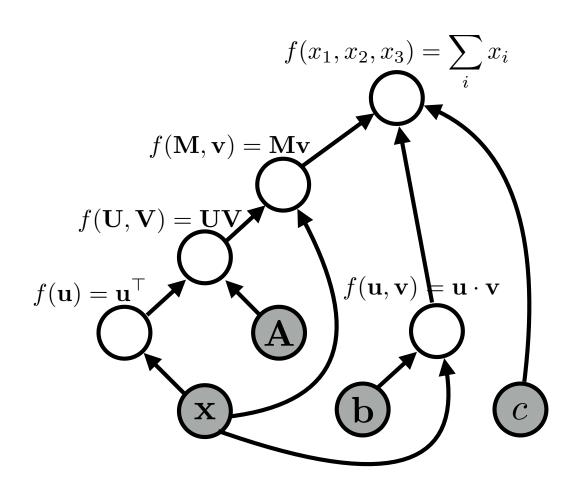
Algorithms

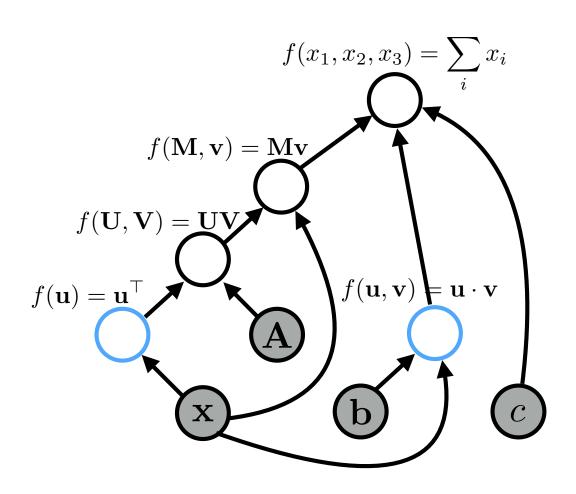
- Graph construction
- Forward propagation
 - Loop over nodes in topological order
 - Compute the value of the node given its inputs
 - Given my inputs, make a prediction (or compute an "error" with respect to a "target output")

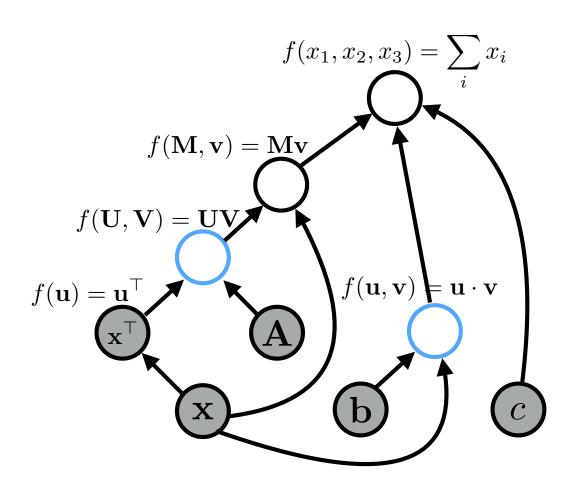
Backward propagation

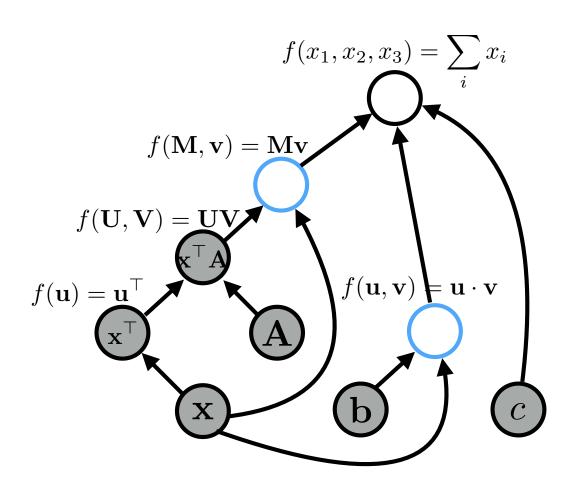
- Loop over the nodes in reverse topological order starting with a final goal node
 - Compute derivatives of final goal node value with respect to each edge's tail node
- How does the output change if I make a small change to the inputs?

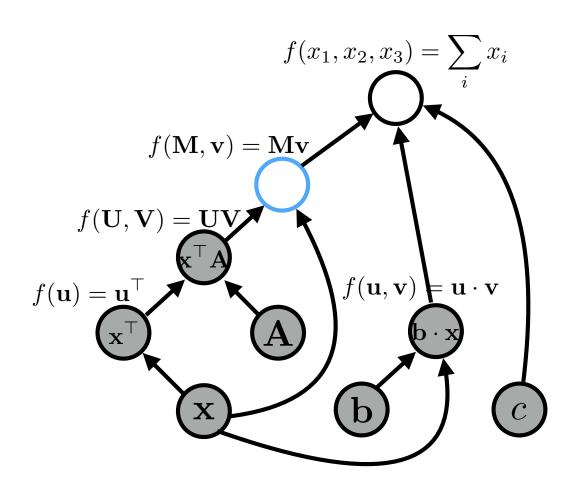


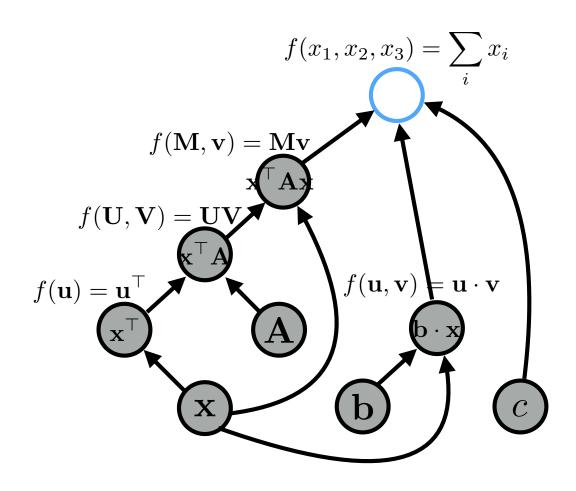


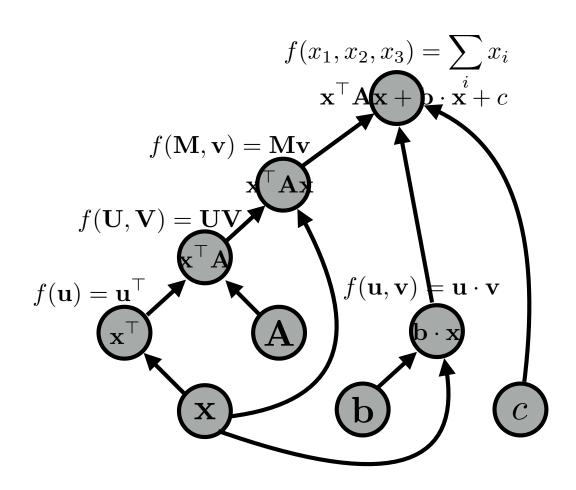












Draw an MLP ComputationGraph

$$\mathbf{h}^{1} = \sigma([\phi(x_{l}); \phi(x_{r})]\mathbf{W}^{1} + \mathbf{b}^{1})$$

$$\mathbf{h}^{2} = \sigma(\mathbf{h}_{1}\mathbf{W}^{2} + \mathbf{b}^{2})$$

$$\mathbf{p} = \operatorname{softmax}(\mathbf{h}^{2}\mathbf{W}^{3} + \mathbf{b}^{3})$$

Constructing Graphs: Two Software Models

Static declaration

- Phase 1: define an architecture (maybe with some primitive flow control like loops and conditionals)
- Phase 2: run a bunch of data through it to train the model and/or make predictions

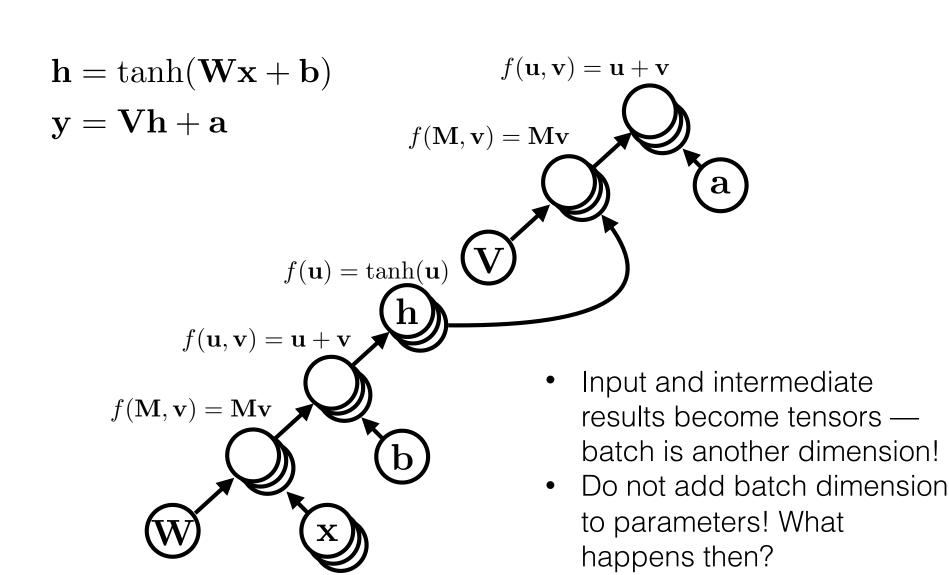
Dynamic declaration

 Graph is defined implicitly (e.g., using operator overloading) as the forward computation is executed

Batching

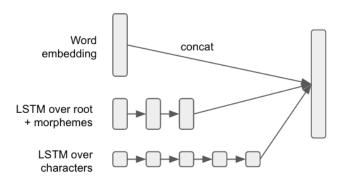
- Packing a few examples together has significant computational benefits
- CPU: helpful
- GPU: you get to use <u>all</u> the GPU cores —> world changing!
- Easy with simple networks, but gets harder as the architecture becomes more complex

The MLP

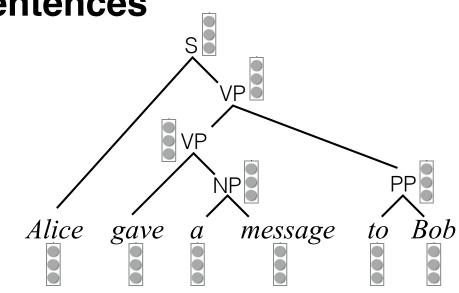


Hierarchical Structure

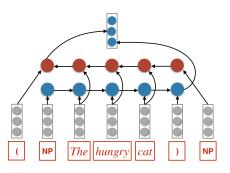
Words



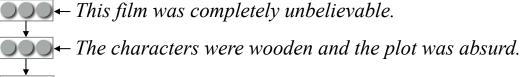




Phrases



Documents



That being said, I liked it.

Batching with Complex Networks

- Complex networks may include different parts with varying length (more about this later)
- It is very hard to batch complete examples this way
- But: you can still batch sub-parts across examples, so you alternate between batched and nonbatched computations