## CS5740: Natural Language Processing Spring 2018

## Computation Graphs

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## Computation Graphs

- The descriptive language of deep learning models
- Functional description of the required computation
- Can be instantiated to do two types of computation:
  - Forward computation
  - Backward computation

 $\mathbf{X}$ 

graph:

A node is a {tensor, matrix, vector, scalar} value



An **edge** represents a function argument (and also data dependency). They are just pointers to nodes.

A **node** with an incoming **edge** is a **function** of that edge's tail node.

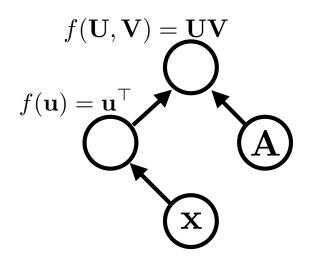
A **node** knows how to compute its value and the value of its derivative w.r.t each argument (edge) times a derivative of an arbitrary input  $\frac{\partial \mathcal{F}}{\partial f(\mathbf{u})}$ .

$$\frac{\partial f(\mathbf{u}) = \mathbf{u}^{\top}}{\partial \mathbf{u}} \frac{\partial f(\mathbf{u})}{\partial f(\mathbf{u})} = \left(\frac{\partial \mathcal{F}}{\partial f(\mathbf{u})}\right)^{\top}$$

$$\mathbf{x}^{\top}\mathbf{A}$$

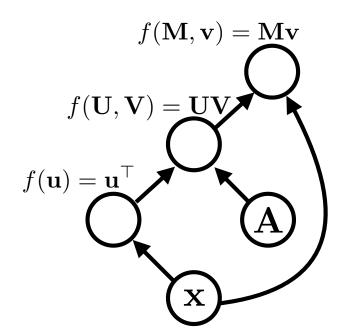
graph:

Functions can be nullary, unary, binary, ... *n*-ary. Often they are unary or binary.



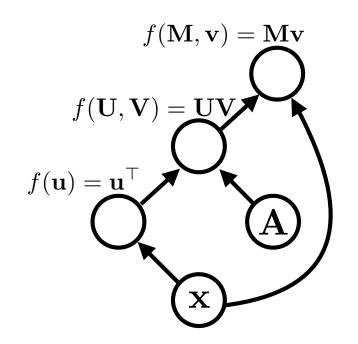
$$\mathbf{x}^{ op}\mathbf{A}\mathbf{x}$$

graph:



Computation graphs are directed and acyclic (usually)

$$\mathbf{x}^{ op}\mathbf{A}\mathbf{x}$$

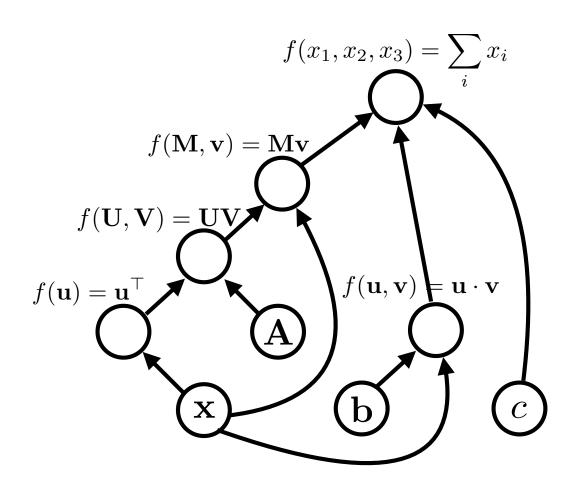


$$f(\mathbf{x}, \mathbf{A}) = \mathbf{x}^{\top} \mathbf{A} \mathbf{x}$$

$$\mathbf{A}$$

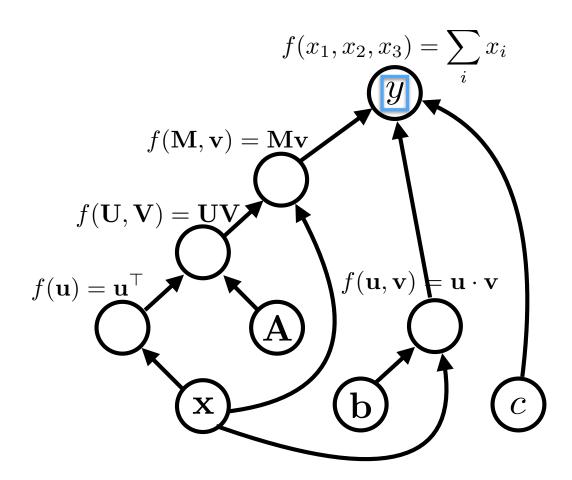
$$\frac{\partial f(\mathbf{x}, \mathbf{A})}{\partial \mathbf{x}} = (\mathbf{A}^\top + \mathbf{A})\mathbf{x}$$
$$\frac{\partial f(\mathbf{x}, \mathbf{A})}{\partial \mathbf{A}} = \mathbf{x}\mathbf{x}^\top$$

$$\mathbf{x}^{\top} \mathbf{A} \mathbf{x} + \mathbf{b} \cdot \mathbf{x} + c$$



$$y = \mathbf{x}^{\mathsf{T}} \mathbf{A} \mathbf{x} + \mathbf{b} \cdot \mathbf{x} + c$$

graph:



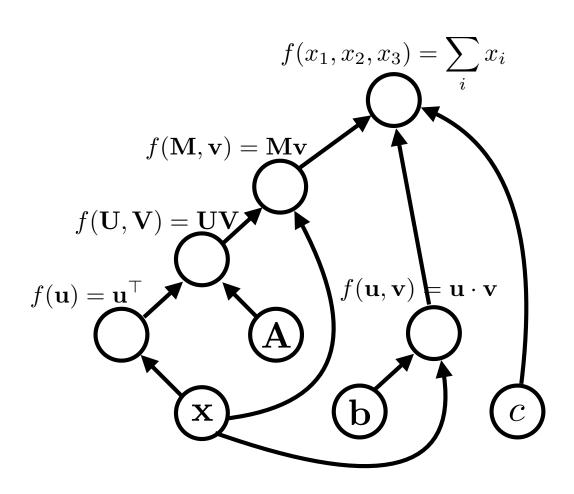
variable names are just labelings of nodes.

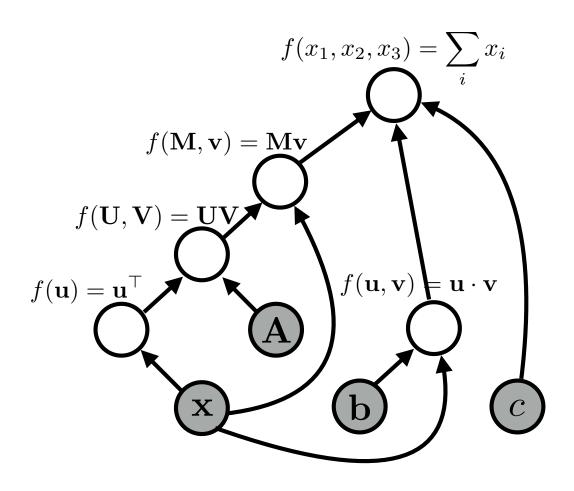
# Algorithms

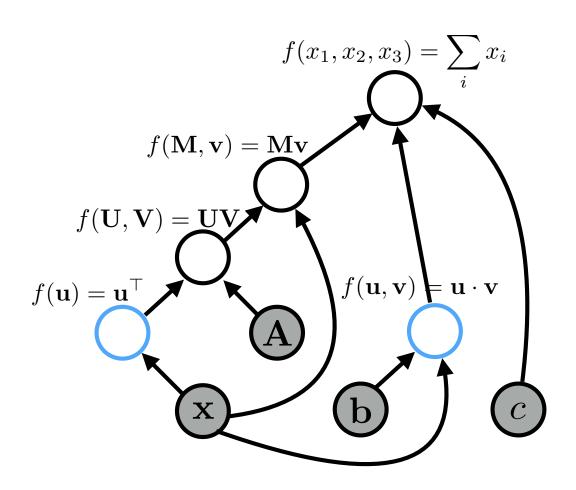
- Graph construction
- Forward propagation
  - Loop over nodes in topological order
    - Compute the value of the node given its inputs
  - Given my inputs, make a prediction (or compute an "error" with respect to a "target output")

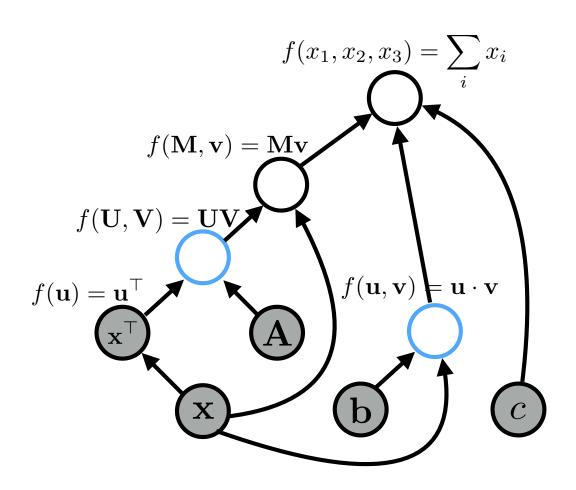
#### Backward propagation

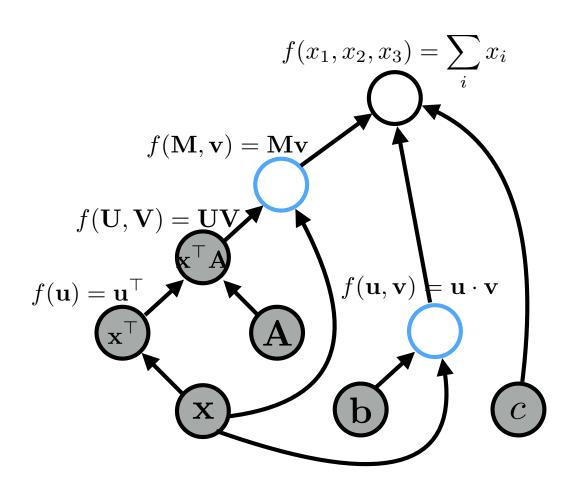
- Loop over the nodes in reverse topological order starting with a final goal node
  - Compute derivatives of final goal node value with respect to each edge's tail node
- How does the output change if I make a small change to the inputs?

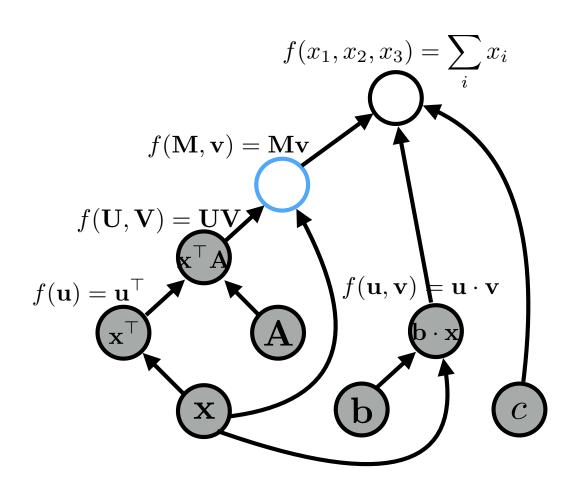


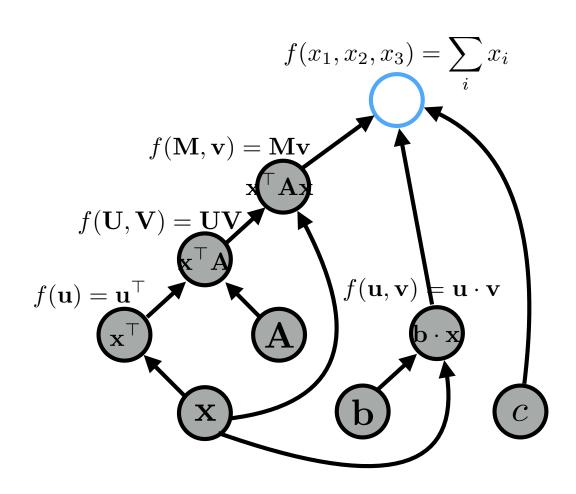


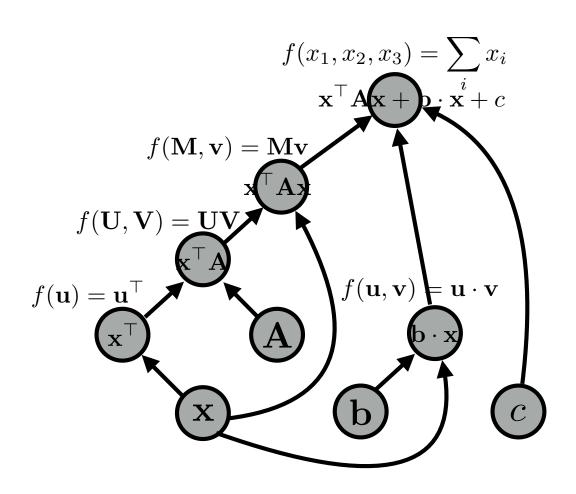












## The MLP

$$\mathbf{h} = \tanh(\mathbf{W}\mathbf{x} + \mathbf{b})$$
  
 $\mathbf{y} = \mathbf{V}\mathbf{h} + \mathbf{a}$ 

## The MLP

$$\mathbf{h} = \tanh(\mathbf{W}\mathbf{x} + \mathbf{b})$$
  $f(\mathbf{u}, \mathbf{v}) = \mathbf{u} + \mathbf{v}$   $\mathbf{y} = \mathbf{V}\mathbf{h} + \mathbf{a}$   $f(\mathbf{M}, \mathbf{v}) = \mathbf{M}\mathbf{v}$   $\mathbf{a}$   $f(\mathbf{u}, \mathbf{v}) = \mathbf{u} + \mathbf{v}$   $\mathbf{b}$   $f(\mathbf{M}, \mathbf{v}) = \mathbf{M}\mathbf{v}$   $\mathbf{b}$ 

# Constructing Graphs

## Two Software Models

#### Static declaration

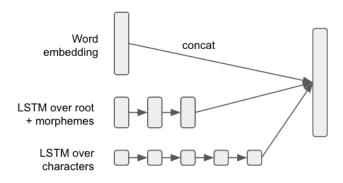
- Phase 1: define an architecture (maybe with some primitive flow control like loops and conditionals)
- Phase 2: run a bunch of data through it to train the model and/or make predictions

### Dynamic declaration

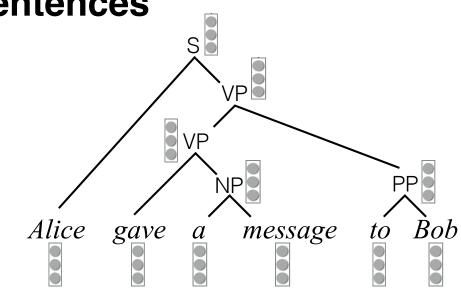
 Graph is defined implicitly (e.g., using operator overloading) as the forward computation is executed

## Hierarchical Structure

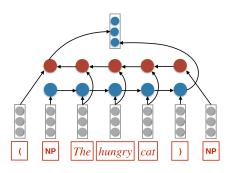
### Words



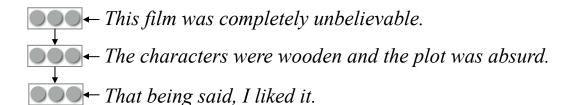
### **Sentences**



### **Phrases**



### **Documents**



## Static Declaration

#### Pros

- Offline optimization/scheduling of graphs is powerful
- Limits on operations mean better hardware support

#### Cons

- Structured data (even simple stuff like sequences), even variablesized data, is complex
- You effectively learn a new programming language ("the Graph Language") and you write programs in that language to process data.
- Examples: Torch, Theano, TensorFlow

## Dynamic Declaration

#### Pros

- Library is less invasive
- The forward computation is written in your favorite programming language with all its features, using your favorite algorithms
- Interleave construction and evaluation of the graph

#### Cons

- Little time for graph optimization
- If the graph is static, effort can be wasted
- Examples: Chainer, most automatic differentiation libraries, **DyNet**

## Dynamic Structure?

- Hierarchical structures exist in language
  - We might want to let the network reflect that hierarchy
  - Hierarchical structure is easiest to process with traditional flow-control mechanisms in your favorite languages
- Combinatorial algorithms (e.g., dynamic programming)
  - Exploit independencies to compute over a large space of operations tractably