CS5670: Computer Vision Noah Snavely

Optimization for machine learning



Slides from Fei-Fei Li, Justin Johnson, Serena Yeung http://vision.stanford.edu/teaching/cs231n/

Readings

- Image classification:
 - <u>http://cs231n.github.io/classification/</u>
- Linear classification and loss functions: — http://cs231n.github.io/linear-classify/
- Optimization
 - http://cs231n.github.io/optimization-1/
 - http://cs231n.github.io/optimization-2/

Announcements

Project 4 (Stereo) is out, due Thursday, April 26, 2018, by 11:59pm
To be done in groups of two

 Quiz 3 in class, Monday, 4/30, first 10 minutes of class

• Final exam in class, May 9

The story so far

$$egin{aligned} s &= f(x;W) = Wx & ext{scores function} \ L_i &= \sum_{j
eq y_i} \max(0, s_j - s_{y_i} + 1) & ext{SVM loss} \ L &= rac{1}{N} \sum_{i=1}^N L_i + \sum_k W_k^2 & ext{data loss + regularization} \end{aligned}$$

We also learned about other data losses, e.g. the "softmax" loss



3.2

5.1

-1.7

cat

car

frog



3.2

5.1

-1.7

cat

car

frog

Want to interpret raw classifier scores as probabilities

$$s = f(x_i; W)$$
 P(

$$P(Y=k|X=x_i)=rac{e^{s_k}}{\sum_i e^{s_j}}$$

Softmax Function



cat

car

frog



probabilities

$$P(Y=k|X=x_i)=rac{e^{s_k}}{\sum_j e^{s_j}}$$
 Softmax Function

cat

car

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Computation graphs





Figure copyright Alex Krizhevsky, Ilya Sutskever, and Geoffrey Hinton, 2012. Reproduced with permission.

(a much bigger computation graph)

How do we set the weights?

- Need to solve an optimization problem:
 Find the weights W that minimize the training loss L
- In general this is a non-linear, non-convex problem
 - Closed-form solvers do not generally exist, unlike with e.g. least squares problems
 - Might not find the globally optimal weights
- (Side note: some learning problems, such as linear SVMs, do have convex loss functions)

Strategy #1: A bad idea: Random search

```
# assume X train is the data where each column is an example (e.g. 3073 x 50,000)
# assume Y train are the labels (e.g. 1D array of 50,000)
# assume the function L evaluates the loss function
bestloss = float("inf") # Python assigns the highest possible float value
for num in xrange(1000):
  W = np.random.randn(10, 3073) * 0.0001 # generate random parameters
  loss = L(X train, Y train, W) # get the loss over the entire training set
  if loss < bestloss: # keep track of the best solution
    bestloss = loss
    bestW = W
  print 'in attempt %d the loss was %f, best %f' % (num, loss, bestloss)
# prints:
# in attempt 0 the loss was 9.401632, best 9.401632
# in attempt 1 the loss was 8.959668, best 8.959668
# in attempt 2 the loss was 9.044034, best 8.959668
# in attempt 3 the loss was 9.278948, best 8.959668
# in attempt 4 the loss was 8.857370, best 8.857370
# in attempt 5 the loss was 8.943151, best 8.857370
# in attempt 6 the loss was 8.605604, best 8.605604
# ... (trunctated: continues for 1000 lines)
```

Lets see how well this works on the test set...

```
# Assume X_test is [3073 x 10000], Y_test [10000 x 1]
scores = Wbest.dot(Xte_cols) # 10 x 10000, the class scores for all test examples
# find the index with max score in each column (the predicted class)
Yte_predict = np.argmax(scores, axis = 0)
# and calculate accuracy (fraction of predictions that are correct)
np.mean(Yte_predict == Yte)
# returns 0.1555
```

15.5% accuracy! not bad! (SOTA is ~95%)

Strategy #2: Follow the slope (aka Gradient Descent)





negative gradient direction

Gradient descent: walk in the direction opposite gradient

- **Q**: How far?
- A: Step size: *learning rate*
- Too big: will miss the minimum
- Too small: slow convergence

Strategy #2: Follow the slope

In 1-dimension, the derivative of a function:

$$rac{df(x)}{dx} = \lim_{h o 0} rac{f(x+h) - f(x)}{h}$$

In multiple dimensions, the **gradient** is the vector of (partial derivatives) along each dimension

The slope in any direction is the **dot product** of the direction with the gradient The direction of steepest descent is the **negative gradient**

current W:	
[0.34,	
-1.11,	
0.78, 0.12,	
0.55,	
2.81, -3.1	
-1.5,	
0.33,]	
loss 1.25347	

gradient dW:



current W:	W +
[0.34,	[0.3
-1.11, 0.78,	-1.1
0.12,	0.12
0.00, 2.81,	2.8
-3.1,	-3.1
-1.5,	-1.5
0.33,]	0.3
loss 1.25347	los

W + h (first dim):
[0.34 + 0.0001 ,
-1.11, 0.78,
0.12, 0.55,
2.81, -3.1.
-1.5, 0.33 1
loss 1.25322

gradient dW:

[?,

?,

?, ?,

?,

?, ?, ?, ?,...]

current W:	W + h (first dim):	
[0.34, -1.11, 0.78, 0.12, 0.55, 2.81, -3.1, -1.5, 0.33,] Ioss 1.25347	[0.34 + 0.0001 , -1.11, 0.78, 0.12, 0.55, 2.81, -3.1, -1.5, 0.33,] Ioss 1.25322	(1.253) = -2.5 $\frac{df}{d}$



current W:	W + h (secon
[0.34,	[0.34,
-1.11,	-1.11 + 0.000
0.78,	0.78,
0.12,	0.12,
0.55,	0.55,
2.81,	2.81,
-3.1,	-3.1,
-1.5,	-1.5,
0.33,]	0.33,]
loss 1.25347	loss 1.25353

V + h (second dim): 0.34, 1.11 + **0.0001**, .78,

gradient dW:



current W:	N
[0.34,	[C
-1.11,	-1
0.78,	0.
0.12,	0.
0.55,	0.
2.81,	2.
-3.1,	-3
-1.5,	-1
0.33,]	0.
loss 1.25347	Ic

V + h (second dim):).34, 1.11 + **0.0001**, 78, 12, 55, .81, 3.1, .5, .33,...] oss 1.25353



current W:	W + h (third dim):
[0.34,	[0.34,
-1.11,	-1.11,
0.78,	0.78 + 0.0001 ,
0.12,	0.12,
0.55,	0.55,
2.81,	2.81,
-3.1,	-3.1,
-1.5,	-1.5,
0.33,]	0.33,]
loss 1.25347	loss 1.25347

gradient dW:

[-2.5, 0.6, ?, ?, ?, ?, ?, ?, ?,...]

current W:	W + I
[0.34,	[0.34
-1.11,	-1.11
0.78,	0.78
0.12,	0.12,
0.55,	0.55,
2.81,	2.81,
-3.1,	-3.1,
-1.5,	-1.5,
0.33,]	0.33,
loss 1.25347	loss

h (third dim): , 1 + 0.0001, . . . 1.25347



current W:	W + h (third dim):		
[0.34,	[0.34,		
-1.11,	-1.11,		
0.78,	0.78 + 0.0001 ,		
0.12,	0.12,		
0.55,	0.55,		
2.81,	2.81,		
-3.1,	-3.1,		
-1.5,	-1.5,		
0.33,]	0.33,]		
loss 1.25347	loss 1.25347		



But the loss is just a function of W!

$$egin{aligned} L &= rac{1}{N} \sum_{i=1}^N L_i + \sum_k W_k^2 \ L_i &= \sum_{j
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want $\nabla_W L$

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want $\nabla_W L$

Use calculus to compute an analytic gradient



This image is in the public domain

This image is in the public domain



In summary:

- Numerical gradient: approximate, slow, easy to write
- Analytic gradient: exact, fast, error-prone

=>

In practice: Always use analytic gradient, but check implementation with numerical gradient. This is called a gradient check.

Questions?



Gradient descent in action



Analytic Gradient

Single term of SVM (hinge) data loss:

$$L_i = \sum_{j
eq y_i} \left[\max(0, w_j^T x_i - w_{y_i}^T x_i + 1)
ight]$$

$$egin{aligned}
abla_{w_j}L_i &= 1(w_j^Tx_i - w_{y_i}^Tx_i + \Delta > 0)x_i \
abla_{w_{y_i}}L_i &= -\left(\sum_{j
eq y_i}1(w_j^Tx_i - w_{y_i}^Tx_i + \Delta > 0)
ight)x_i \end{aligned}$$

Full gradient is the sum of all L_i s over all training examples x_i

Gradient Descent

Vanilla Gradient Descent

```
while True:
    weights_grad = evaluate_gradient(loss_fun, data, weights)
    weights += - step size * weights grad # perform parameter update
```

Stochastic Gradient Descent (SGD)

$$L(W) = rac{1}{N} \sum_{i=1}^{N} L_i(x_i, y_i, W) + \lambda R(W)$$
 $abla_W L(W) = rac{1}{N} \sum_{i=1}^{N}
abla_W L_i(x_i, y_i, W) + \lambda
abla_W R(W)$

Full sum expensive when N is large!

Approximate sum using a **minibatch** of examples 32 / 64 / 128 common

```
# Vanilla Minibatch Gradient Descent
```

```
while True:
    data_batch = sample_training_data(data, 256) # sample 256 examples
    weights_grad = evaluate_gradient(loss_fun, data_batch, weights)
    weights += - step_size * weights_grad # perform parameter update
```

Interactive Web Demo

Datapoints are shown as circles colored by their class Parameters (red/gree/blue). The background regions are colored by shown below. The value is current weights. Each classifier is visualized by a line that (computed with backprop) indicates its zero score level set. For example, the blue is in *red, italic* below. Click classifier computes scores as $W_{0,0}x_0 + W_{0,1}x_1 + b_0$ and the triangles to control the a single example, L_i . the blue line shows the set of points (x_0, x_1) that give score parameters. of zero. The blue arrow draws the vector $(W_{0,0}, W_{0,1})$, which shows the direction of score increase and its length is proportional to how steep the increase is.

Note: you can drag the datapoints.



W, bare



Visualization of the data loss computation. Each row is loss due to one datapoint. The first three columns are the 2D data x_i and whichever class is most likely at any point according to the in **bold** and its gradient the label y_i . The next three columns are the three class scores from each classifier $f(x_i; W, b) = Wx_i + b$ (E.g. s[0] = x[0] * W[0,0] + x[1] * W[0,1] + b[0]). The last column is the data loss for

					-	
« [0]	x[1]	У	s[0]	s[1]	s[2]	L
0.50	0.40	0	1.13	0.08	0.09	0.00
0.80	0.30	0	1.67	0.26	0.87	0.20
0.30	0.80	0	1.18	-0.44	-1.17	0.00
0.40	0.30	1	-1.01	0.02	-1.38	0.00
0.30	0.70	1	-0.29	-0.44	-2.07	1.15
0.70	0.20	1	-1.80	0.08	-1.72	0.00
0.70	-0.40	2	0.58	1.07	2.23	0.00
0.50	-0.60	2	-0.12	1.27	2.29	0.00
0.40	-0.50	2	-2.00	0.97	0.39	1.59
• •				mean:		
Total data loss: 0.33 Regularization loss: 1.64				0.33		
Total loss: 1.96						



Multiclass SVM loss formulation: Moston Watking 1000

http://vision.stanford.edu/teaching/cs231n-demos/linear-classify/

The dynamics of Gradient Descent

pull some weights up and some down

$$L = rac{1}{N} \sum_i \sum_{j
eq y_i} \left[\max(0, f(x_i; W)_j - f(x_i; W)_{y_i} + \Delta)
ight] + \lambda \sum_k \sum_l W_{k,l}^2$$

$$L = rac{1}{N} \sum_i -\log\left(rac{e^{f_{y_i}}}{\sum_j e^{f_j}}
ight) + \lambda \sum_k \sum_l W_{k,l}^2$$

always pull the weights down



weights_grad = evaluate_gradient(loss_fun, data, weights)
vel = vel * 0.9 - step_size * weights_grad
weights += vel



Many other ways to perform optimization...

- Second order methods that use the Hessian (or its approximation): BFGS, **LBFGS**, etc.
- Currently, the lesson from the trenches is that well-tuned SGD+Momentum is very hard to beat for CNNs.

Questions?

Where are we?

- Classifiers: SVM vs. Softmax
- Gradient descent to optimize loss functions
 - Batch gradient descent, stochastic gradient descent
 - Momentum
 - Numerical gradients (slow, approximate), analytic gradients (fast, error-prone)

Aside: Image Features





Aside: Image Features



Image Features: Motivation



Cannot separate red and blue points with linear classifier

Image Features: Motivation



Cannot separate red and blue points with linear classifier $f(x, y) = (r(x, y), \theta(x, y))$



After applying feature transform, points can be separated by linear classifier

Example: Color Histogram



Example: Histogram of Oriented Gradients (HoG)



Divide image into 8x8 pixel regions Within each region quantize edge direction into 9 bins

Lowe, "Object recognition from local scale-invariant features", ICCV 1999 Dalal and Triggs, "Histograms of oriented gradients for human detection," CVPR 2005



Example: 320x240 image gets divided into 40x30 bins; in each bin there are 9 numbers so feature vector has 30*40*9 = 10,800 numbers

Example: Bag of Words



Aside: Image Features



Image features vs ConvNets



Questions?

Next: Neural networks