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26 Jan 2022

## Vector Spaces

Def. A vector space (over  $\mathbb{R}$ ) is a nonempty set with two operations

- vector addition  $V \times V \rightarrow V$   
 $(x, y) \mapsto x + y$

- scalar multiplication  $\mathbb{R} \times V \rightarrow V$   
 $(a, x) \mapsto ax$

These satisfy:

(i) Associative

$$(x + y) + z = x + (y + z)$$

$$a(bx) = (ab)x$$

(ii) Commutative

$$x + y = y + x$$

(iii) Distributive

$$(a + b)x = ax + bx$$

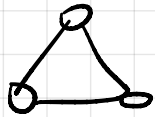
$$a(x + y) = ax + ay$$

(iv) Identity  $1 \cdot x = x$ .

The axioms imply that  $\forall x$  the vector  $\vec{0} \triangleq 0 \cdot x$  is an identity for addition.

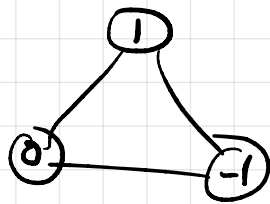
Ex. For any set  $S$ ,  $\mathbb{R}^S$  denotes the set of real-valued functions on  $S$ . This is a vector space under pointwise addition & mult.

Eg.  $(f+g)(s) = f(s) + g(s)$   
 $(a \cdot f)(s) = a \cdot f(s)$

Ex. Consider the graph  $G =$    $V(G)$  is a 3-element set.

$\mathbb{R}^{V(G)}$  is the vector space of real-valued labelings of  $V(G)$ .

E.g.



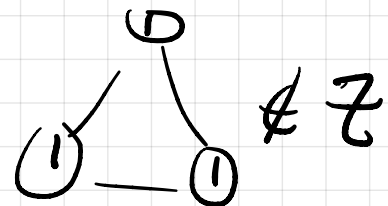
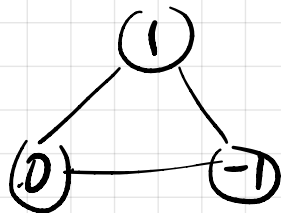
could be represented by

$$\begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \text{ in } \mathbb{R}^3.$$

A different representation could be  $\begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$ .

Ex. Consider  $Z \subset \mathbb{R}^{V(G)}$  consisting of functions on  $V(G)$  that sum to zero.

E.g.



The 3-fold symmetry of  $Z$  is most apparent when one rotates elements of  $Z$  as 3-tuples, not 2-tuples.

An isomorphism of vector spaces  $V, W$  is a bijection between the elements of  $V$  and  $W$ ,  $V \xrightarrow{T} W$ , that respects the vector space operations.

$$T(x+y) = T(x) + T(y)$$

$$T(ax) = aT(x).$$

E.g. the 6 orderings of  $V(G)$  yield 6 different isomorphisms  $\mathbb{R}^{V(G)} \rightarrow \mathbb{R}^3$ .

A vector space is finite dimensional iff it is isomorphic to  $\mathbb{R}^n$  for some  $n \in \mathbb{N}$ .

(BTW,  $\mathbb{R}^0$  is a one-element set  $\{\vec{0}\}$ .)

Fact: If  $V \cong \mathbb{R}^n$  then  $V \not\cong \mathbb{R}^m$  for any  $m \neq n$ .

The unique  $n$  such that  $V \cong \mathbb{R}^n$  is called the dimension of  $V$ .

(See lecture notes for proof of uniqueness.)

Def. If  $V$  is a vect space and  $S \subseteq V$   
a linear combination of elements of  $S$   
is a finite sum of the form

$$a_1 x_1 + a_2 x_2 + \dots + a_m x_m$$

where  $a_i \in \mathbb{R}$ ,  $x_i \in S$  for  $i=1, \dots, m$ .

The linear comb. is trivial if  $a_i = 0 \forall i$   
otherwise non-trivial.

$S$  is linearly independent if all the  
non-trivial lin combinations of its  
elements are  $\neq 0$ .

A basis of  $V$  is a maximal  
linearly independent set.

The dimension of  $V$  is the cardinality  
of any basis.

(Proving all bases have same cardinality  
takes work.)

If  $V$  is a vector space and  $B$  is a  
basis, then the function  $T: \mathbb{R}^B \rightarrow V$   
defined by  $T(f) = \sum_{b \in B} f(b) \cdot b$   
is an isomorphism.