<u>CS 485 Lecture 19</u> 6 March 2006

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## Four generating functions from previous lecture

Deg:  $g_0, g_1$ Size:  $h_0, h_1$ 

$$h_0'(1) = 1 + g_0'(1)h_1'(1)$$
 (I)  
 $h_1'(1) = 1 + g_1'(1)h_1'(1)$  (II)

From (II), we have 
$$h_1'(1) = 1 / [1 + g_1'(1)]$$
 (III)

Plugging (III) back to (I)  $h_0'(1) = 1 + g_0'(1) / [1 - g_1'(1)]$ 

Therefore, point at which the giant components appears when  $g_1'(1) = 1$ 

We also know that:

$$g_1'(1) = g_0''(1) / g_0'(1) = 1 \rightarrow g_0''(1) = g_0'(1)$$

By definition:

$$g_0(x) = \sum P_k x^k$$

$$g_0'(x) = \sum k P_k x^{k-1}$$

$$g_0''(x) = \sum k (k-1) P_k x^{k-2}$$

Since 
$$g_0$$
''(1) =  $g_0$ '(1), let x = 1  

$$\sum kP_k = \sum k(k-1)P_k$$

$$\sum (k^2-2k)P_k = 0$$

$$\sum k(k-2)P_k = 0$$

This is the end of random graph materials.

## **High Dimensional Data**

10<sup>6</sup> papers

25,000 dimensional vector to represent the words used in the papers

This is a very large dimension, so we can randomly select a 300 dimensional subspace and project all the data points to such subspace. In fact, we can pick a subspace such that we minimize the error between data and its projection.

## **SVD: Singular Value Decomposition**

Let **A** be the  $10^6 \times 25000$  matrix of data from your set of papers. Any matrix **A** can be rewritten as  $\mathbf{A} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^{\mathrm{T}}$  where **U** and **V** are orthonormal and  $\mathbf{\Sigma}$  is diagonalised:

$$\Sigma = \begin{pmatrix} \sigma_1 & 0 \\ \sigma_2 & \\ \vdots & \sigma_N \end{pmatrix} \quad \text{with } \sigma_1 \geq \sigma_2 \geq \sigma_3 \geq \ldots \geq \sigma_N$$

Create a new matrix  $\Sigma^{(k)}$  by keeping only the *k* largest  $\sigma$ 's in  $\Sigma$ :

Then write  $\mathbf{A}^{(k)} = \mathbf{U} \mathbf{\Sigma}^{(k)} \mathbf{V}^{\mathrm{T}}$ .

What is the error between **A** and  $A^{(k)}$ ?

## **Norms**

- Frobenius norm:  $|\mathbf{A}|_F^2 = \sum_{i} a_{ij}^2 = \text{sum of squares of all of the elements of } \mathbf{A}$ .

Let  $a_i$  be the ith column of **A**. Then  $(\mathbf{A}^T\mathbf{A})_{ij} = (a_i)^Ta_j$ .

So  $\text{Tr}(\mathbf{A}^{T}\mathbf{A}) = \Sigma_{i}(a_{i})^{T}a_{i} = \Sigma_{i}|a_{i}|^{2} = \text{sum of squares of elements of } \mathbf{A} = |\mathbf{A}|_{E}^{2}$ 

- 2-norm:

For a vector 
$$\mathbf{x} = (x_1, x_2, \dots x_n), \ |\mathbf{x}|_2 = \sqrt{x_1 + x_2 + x_3 + \dots}$$

For a matrix, 
$$|\mathbf{A}|_2 = \max_{|\mathbf{x}|=1} |\mathbf{A}\mathbf{x}|_2$$

- It turns out that the 2-norm of A is the maximum eigenvalue of A, and the Frobenius norm squared is the sum of the squares of the eigenvalues. To see this, take the 2-norm and Frobenius norm of a diagonalised matrix and note the 2<sup>nd</sup> lemma below.

<u>Lemma</u>:  $|\mathbf{A}\mathbf{B}|_2 \leq |\mathbf{A}|_2 |\mathbf{B}|_2$ 

Pf: Let **y** be the value of **x** that maximises  $|\mathbf{A}|_2 = \max_{|\mathbf{x}|=1} |\mathbf{A}\mathbf{x}|_2$ .

Let z = By.

Then 
$$|\mathbf{A}\mathbf{B}|_2 = |\mathbf{A}\mathbf{z}|_2 = |\mathbf{A}\frac{\mathbf{z}}{|\mathbf{z}|}|_2 |\mathbf{z}|_2 \le |\mathbf{A}|_2 |\mathbf{z}|_2 \le |\mathbf{A}|_2 |\mathbf{B}|_2 \text{ since } |\mathbf{z}|_2 \le |\mathbf{B}|_2$$

Lemma: Let Q be an orthonormal matrix. For all 
$$\mathbf{x}$$
,  $|\mathbf{Q}\mathbf{x}|_2 = |\mathbf{x}|_2$ .  
Pf:  $|\mathbf{Q}\mathbf{x}|_2^2 = \mathbf{x}^T\mathbf{Q}^T\mathbf{Q}\mathbf{X} = \mathbf{x}^T\mathbf{x} = |\mathbf{x}|_2^2$  because  $\mathbf{Q}^T = \mathbf{Q}^{-1}$ , so  $\mathbf{Q}^T\mathbf{Q} = \mathbf{1}$ .

Lemma: Let Q be an orthonormal matrix. For all A,  $|\mathbf{Q}\mathbf{A}|_2 = |\mathbf{A}|_2$ .

Pf: This follows directly from the previous lemma.

These lemmas also hold for the Frobenius norm as well.

It is straightforward from this to show that for  $A=U\Sigma V^T$ ,  $|A|=|\Sigma|$  for both norms.

 $\underline{\text{Thm}}: \ \left| \mathbf{A} - \mathbf{A}^{(k)} \right| \leq \min_{\text{rank}(\mathbf{B}) \leq k} \left| \mathbf{A} - \mathbf{B} \right|. \ \text{In other words, } \mathbf{A}^{(k)} \text{ is the best rank-k approximation to } \mathbf{A} \text{ in }$ 

terms of total error (but not necessarily error of a given element, so this is not always "best" in every application). Proof next lecture. This is easy to prove for the 2-norm but very difficult for the Frobenius norm.