

## Modeling Sequence Data: HMMs and Viterbi

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Reading:  
Manning/Schuetze, Sections 9.1-9.3 (except 9.3.1)  
Leeds Online HMM Tutorial (except Forward and Forward/Backward Algorithm)  
([http://www.comp.leeds.ac.uk/roger/HiddenMarkovModels/html\\_dev/main.html](http://www.comp.leeds.ac.uk/roger/HiddenMarkovModels/html_dev/main.html))

## Hidden Markov Model

- States:  $y \in \{s_1, \dots, s_k\}$
  - Outputs symbols:  $x \in \{o_1, \dots, o_m\}$
  - Starting probability  $P(Y_1 = y_1)$ 
    - Specifies where the sequence starts
  - Transition probability  $P(Y_i = y_i \mid Y_{i-1} = y_{i-1})$ 
    - Probability that one states succeeds another
  - Output/Emission probability  $P(X_i = x_i \mid Y_i = y_i)$ 
    - Probability that word is generated in this state
- => Every output+state sequence has a probability

$$P(x, y) = P(x_1, \dots, x_l, y_1, \dots, y_l) \\ = P(y_1)P(x_1|y_1) \prod_{i=2}^l P(x_i|y_i)P(y_i|y_{i-1})$$

## Estimating the Probabilities

- Given: Fully observed data
  - Pairs of emission sequence with their state sequence
- Estimating transition probabilities  $P(Y_i | Y_{i-1})$ 

$$P(Y_i = a | Y_{i-1} = b) = \frac{\# \text{ of times state } a \text{ follows state } b}{\# \text{ of times state } b \text{ occurs}}$$
- Estimating emission probabilities  $P(X_i | Y_i)$ 

$$P(X_i = a | Y_i = b) = \frac{\# \text{ of times output } a \text{ is observed in state } b}{\# \text{ of times state } b \text{ occurs}}$$
- Smoothing the estimates
  - Laplace smoothing -> uniform prior
  - See naïve Bayes for text classification
- Partially observed data
  - Expectation Maximization (EM)

## Viterbi Example

$P(X_i   Y_i)$	I	bank	at	CFCU	go	to	the
DET	0.01	0.01	0.01	0.01	0.01	0.01	0.94
PRP	0.94	0.01	0.01	0.01	0.01	0.01	0.01
N	0.01	0.4	0.01	0.4	0.16	0.01	0.01
PREP	0.01	0.01	0.48	0.01	0.01	0.47	0.01
V	0.01	0.4	0.01	0.01	0.55	0.01	0.01

$P(Y_i)$		$P(Y_i   Y_{i-1})$	DET	PRP	N	PREP	V
DET	0.3	DET	0.01	0.01	0.96	0.01	0.01
PRP	0.3	PRP	0.01	0.01	0.01	0.2	0.77
N	0.1	N	0.01	0.2	0.3	0.3	0.19
PREP	0.1	PREP	0.3	0.2	0.3	0.19	0.01
V	0.2	V	0.2	0.19	0.3	0.3	0.01

## HMM Decoding: Viterbi Algorithm

- Question: What is the most likely state sequence given an output sequence
  - Given fully specified HMM:
    - $P(Y_i = y_i)$ ,
    - $P(Y_i = y_i \mid Y_{i-1} = y_{i-1})$ ,
    - $P(X_i = x_i \mid Y_i = y_i)$
  - Find  $y^* = \operatorname{argmax}_{y \in \{y_1, \dots, y_l\}} P(x_1, \dots, x_l, y_1, \dots, y_l)$ 

$$= \operatorname{argmax}_{y \in \{y_1, \dots, y_l\}} \left\{ P(y_1)P(x_1|y_1) \prod_{i=2}^l P(x_i|y_i)P(y_i|y_{i-1}) \right\}$$
  - “Viterbi” algorithm has runtime linear in length of sequence
  - Example: find the most likely tag sequence for a given sequence of words

## HMM's for POS Tagging

- Design HMM structure (vanilla)
  - States: one state per POS tag
  - Transitions: fully connected
  - Emissions: all words observed in training corpus
- Estimate probabilities
  - Use corpus, e.g. Treebank
  - Smoothing
  - Unseen words?
- Tagging new sentences
  - Use Viterbi to find most likely tag sequence

## Experimental Results

Tagger	Accuracy	Training time	Prediction time
HMM	96.80%	20 sec	18.000 words/s
TBL Rules	96.47%	9 days	750 words/s

- Experiment setup
  - WSJ Corpus
  - Trigram HMM model
  - Lexicalized
  - from [Pla and Molina, 2001]

## Discriminative vs. Generative

- Bayes Rule 
$$h_{\text{bayes}}(x) = \underset{y \in Y}{\operatorname{argmax}} [P(Y = y|X = x)]$$
$$= \underset{y \in Y}{\operatorname{argmax}} [P(X = x|Y = y)P(Y = y)]$$
- Generative:
  - Make assumptions about  $P(X = x|Y = y)$  and  $P(Y = y)$
  - Estimate parameters of the two distributions
- Discriminative:
  - Define set of prediction rules (i.e. hypotheses)  $H$
  - Find  $h$  in  $H$  that best approximates the classifications made by 
$$h_{\text{bayes}}(x) = \underset{y \in Y}{\operatorname{argmax}} [P(Y = y|X = x)]$$
- Question: Can we train HMM's discriminately?
  - Later in semester: discriminative training of HMM and general structured prediction.