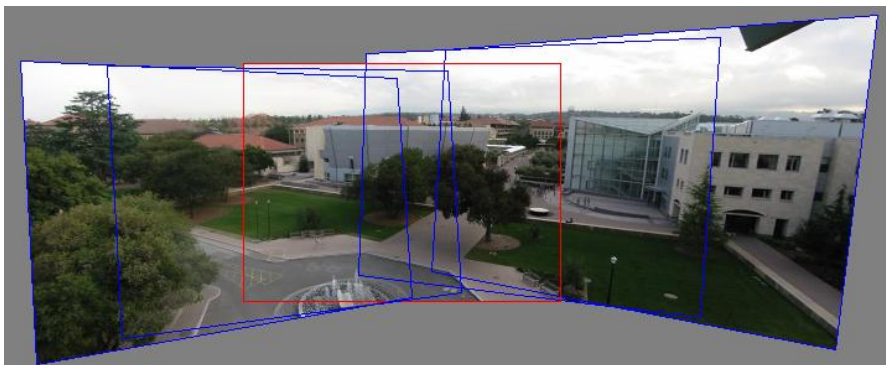


Panoramas

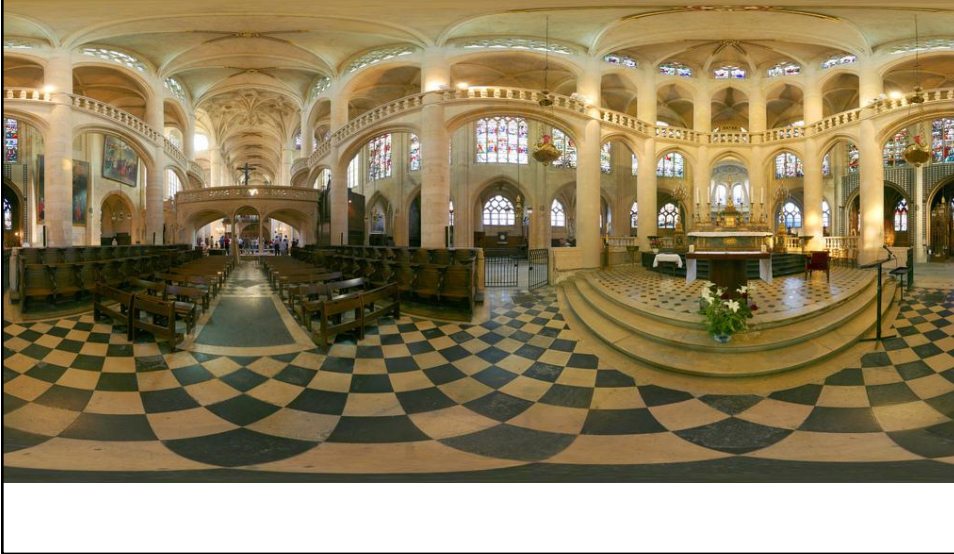
- Now we know how to create panoramas!
- Given two images:
 - Step 1: Detect features
 - Step 2: Match features
 - Step 3: Compute a homography using RANSAC
 - Step 4: Combine the images together (somehow)
- What if we have more than two images?

Can we use homographies to create a 360 panorama?



- In order to figure this out, we need to learn what a **camera** is

360 panorama



CS4670 / 5670: Computer Vision

Noah Snavely

Lecture 13: Cameras

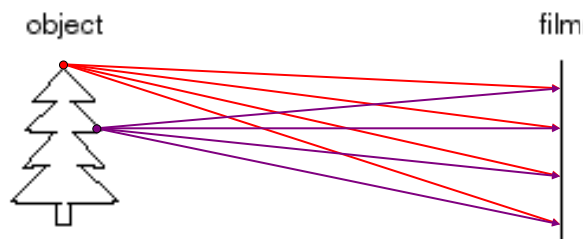


Source: S. Lazebnik

Reading

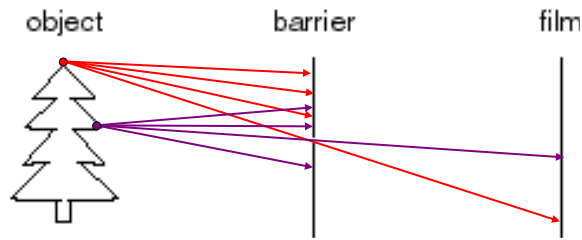
- Szeliski 2.1.3-2.1.6

Image formation



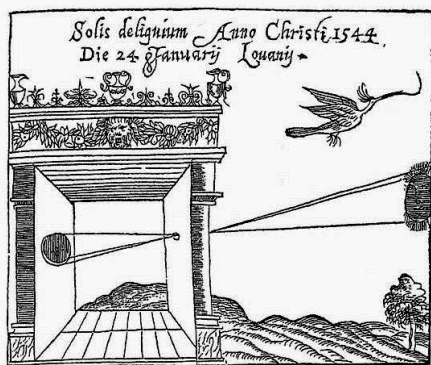
- Let's design a camera
 - Idea 1: put a piece of film in front of an object
 - Do we get a reasonable image?

Pinhole camera



- Add a barrier to block off most of the rays
 - This reduces blurring
 - The opening known as the **aperture**
 - How does this transform the image?

Camera Obscura

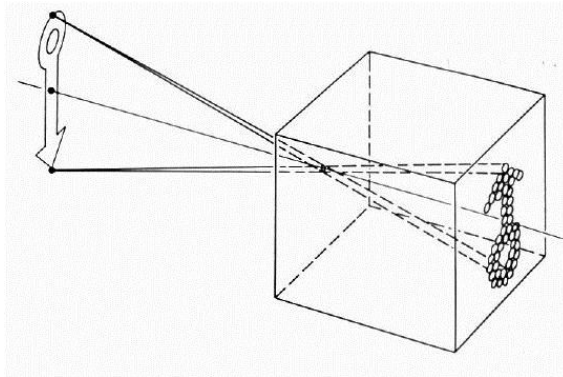


Gemma Frisius, 1558

- Basic principle known to Mozi (470-390 BC), Aristotle (384-322 BC)
- Drawing aid for artists: described by Leonardo da Vinci (1452-1519)

Source: A. Efros

Camera Obscura

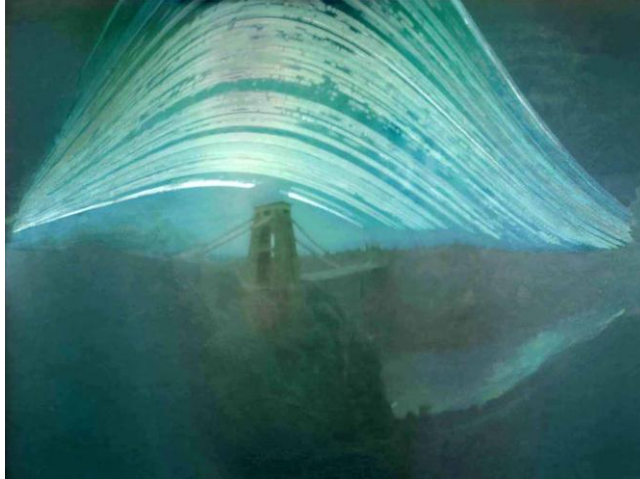


Home-made pinhole camera



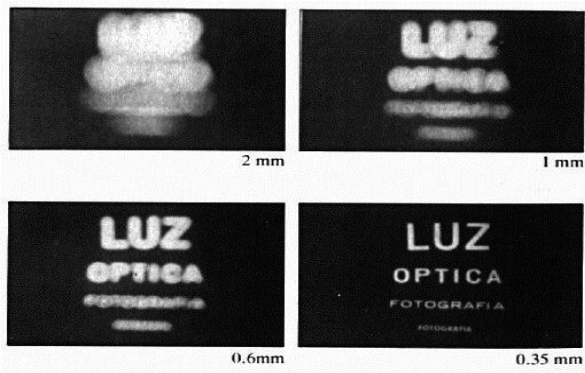
Why so
blurry?

Pinhole photography



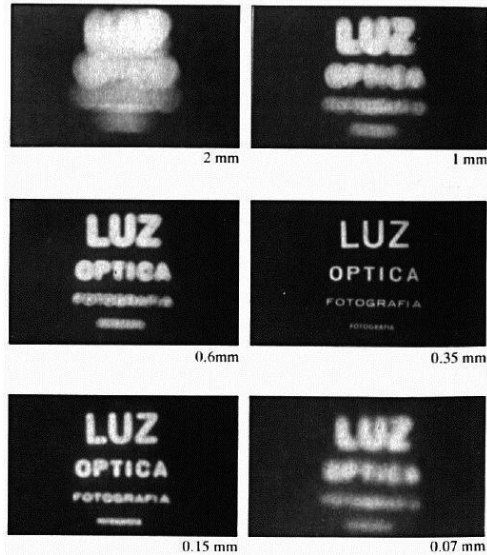
Justin Quinnell, The Clifton Suspension Bridge. December 17th 2007 - June 21st 2008
6-month exposure

Shrinking the aperture

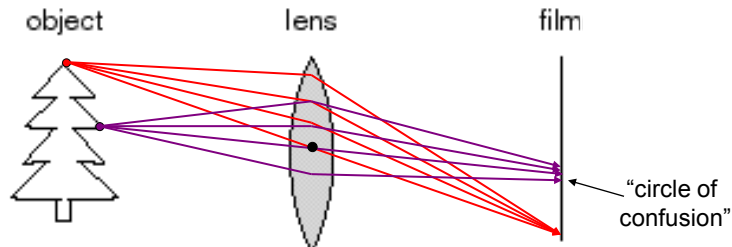


- Why not make the aperture as small as possible?
 - Less light gets through
 - *Diffraction* effects...

Shrinking the aperture



Adding a lens

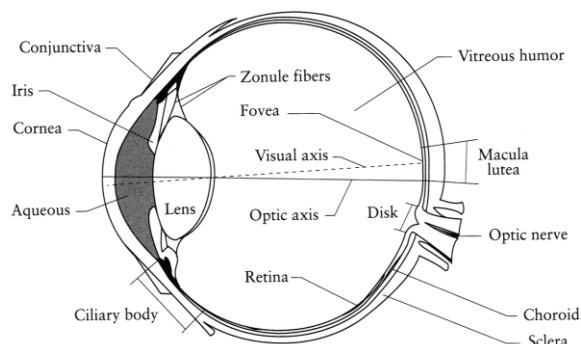


- A lens focuses light onto the film
 - There is a specific distance at which objects are “in focus”
 - other points project to a “circle of confusion” in the image
 - Changing the shape of the lens changes this distance

Lytro Lightfield Camera

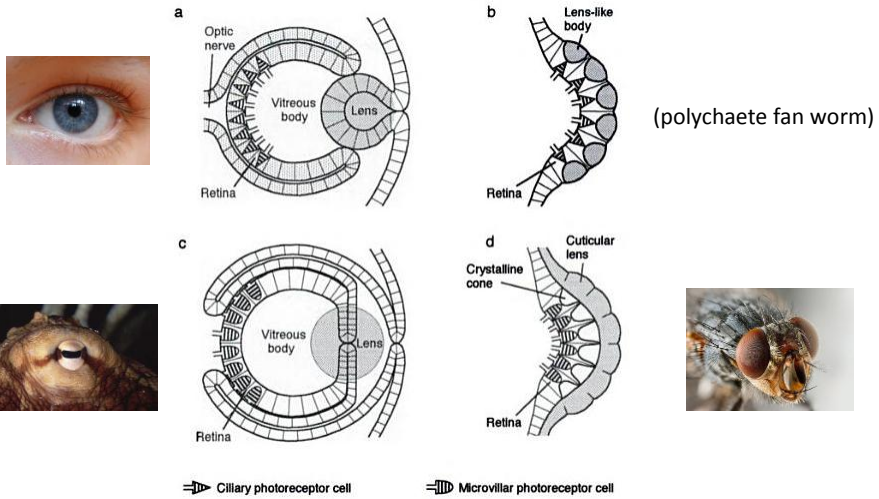


The eye



- The human eye is a camera
 - **Iris** - colored annulus with radial muscles
 - **Pupil** - the hole (aperture) whose size is controlled by the iris
 - What's the "film"?
 - photoreceptor cells (rods and cones) in the **retina**

Eyes in nature



Source: *Animal Eyes*, Land & Nilsson

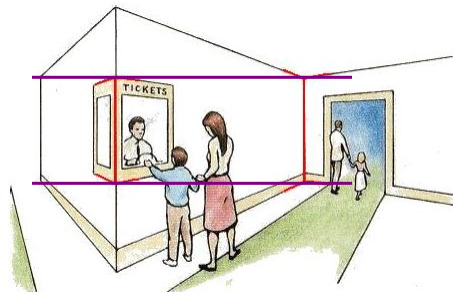
Projection



Projection

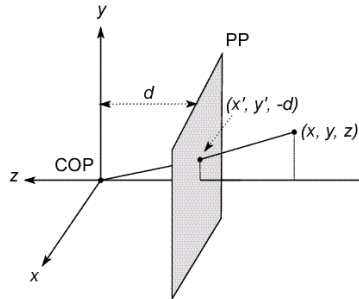


Müller-Lyer Illusion



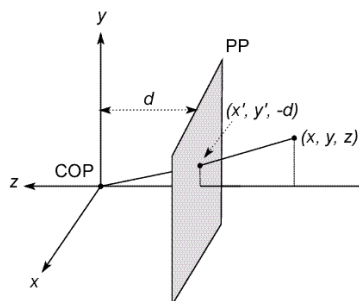
http://www.michaelbach.de/ot/sze_muelue/index.html

Modeling projection



- The coordinate system
 - We will use the pinhole model as an approximation
 - Put the optical center (**C**enter **O**f **P**rojection) at the origin
 - Put the image plane (**P**rojection **P**lane) *in front* of the COP
 - Why?
 - The camera looks down the *negative* z axis
 - we need this if we want right-handed-coordinates

Modeling projection



- Projection equations
 - Compute intersection with PP of ray from (x,y,z) to COP
 - Derived using similar triangles (on board)

$$(x, y, z) \rightarrow \left(-d\frac{x}{z}, -d\frac{y}{z}, -d\right)$$
 - We get the projection by throwing out the last coordinate:

$$(x, y, z) \rightarrow \left(-d\frac{x}{z}, -d\frac{y}{z}\right)$$

Modeling projection

- Is this a linear transformation?
 - no—division by z is nonlinear

Homogeneous coordinates to the rescue!

$$(x, y) \Rightarrow \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

homogeneous image
coordinates

$$(x, y, z) \Rightarrow \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

homogeneous scene
coordinates

Converting *from* homogeneous coordinates

$$\begin{bmatrix} x \\ y \\ w \end{bmatrix} \Rightarrow (x/w, y/w)$$

$$\begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} \Rightarrow (x/w, y/w, z/w)$$

Perspective Projection

Projection is a matrix multiply using homogeneous coordinates:

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1/d & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} x \\ y \\ -z/d \end{bmatrix} \Rightarrow \left(-d\frac{x}{z}, -d\frac{y}{z}\right)$$

divide by third coordinate

This is known as **perspective projection**

- The matrix is the **projection matrix**
- (Can also represent as a 4x4 matrix – OpenGL does something like this)

Perspective Projection

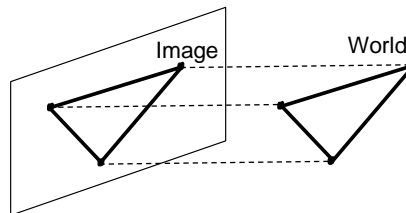
- How does scaling the projection matrix change the transformation?

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1/d & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} x \\ y \\ -z/d \end{bmatrix} \Rightarrow \left(-d\frac{x}{z}, -d\frac{y}{z}\right)$$

$$\begin{bmatrix} -d & 0 & 0 & 0 \\ 0 & -d & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} -dx \\ -dy \\ z \end{bmatrix} \Rightarrow \left(-d\frac{x}{z}, -d\frac{y}{z}\right)$$

Orthographic projection

- Special case of perspective projection
 - Distance from the COP to the PP is infinite



$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} x \\ y \\ 1 \end{bmatrix} \Rightarrow (x, y)$$

Variants of orthographic projection

- Scaled orthographic
 - Also called “weak perspective”

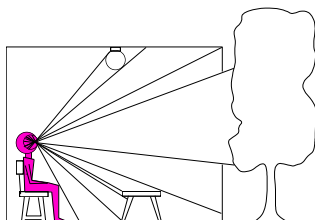
$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1/d \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} x \\ y \\ 1/d \end{bmatrix} \Rightarrow (dx, dy)$$

- Affine projection
 - Also called “paraperspective”

$$\begin{bmatrix} a & b & c & d \\ e & f & g & h \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

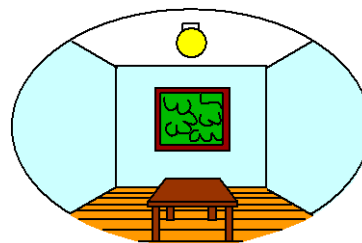
Dimensionality Reduction Machine (3D to 2D)

3D world



Point of observation

2D image



What have we lost?

- Angles
- Distances (lengths)

Projection properties

- Many-to-one: any points along same ray map to same point in image
- Points \rightarrow points
- Lines \rightarrow lines (collinearity is preserved)
 - But line through focal point projects to a point
- Planes \rightarrow planes (or half-planes)
 - But plane through focal point projects to line

Projection properties

- Parallel lines converge at a vanishing point
 - Each direction in space has its own vanishing point
 - But parallels parallel to the image plane remain parallel

