

# **CS4620/5620: Lecture 16**

## **Programmable Shading and Meshes**

## **Announcements**

- Prelim next Thursday
  - In the evening, closed book
  - Including material of this week

## Putting it together

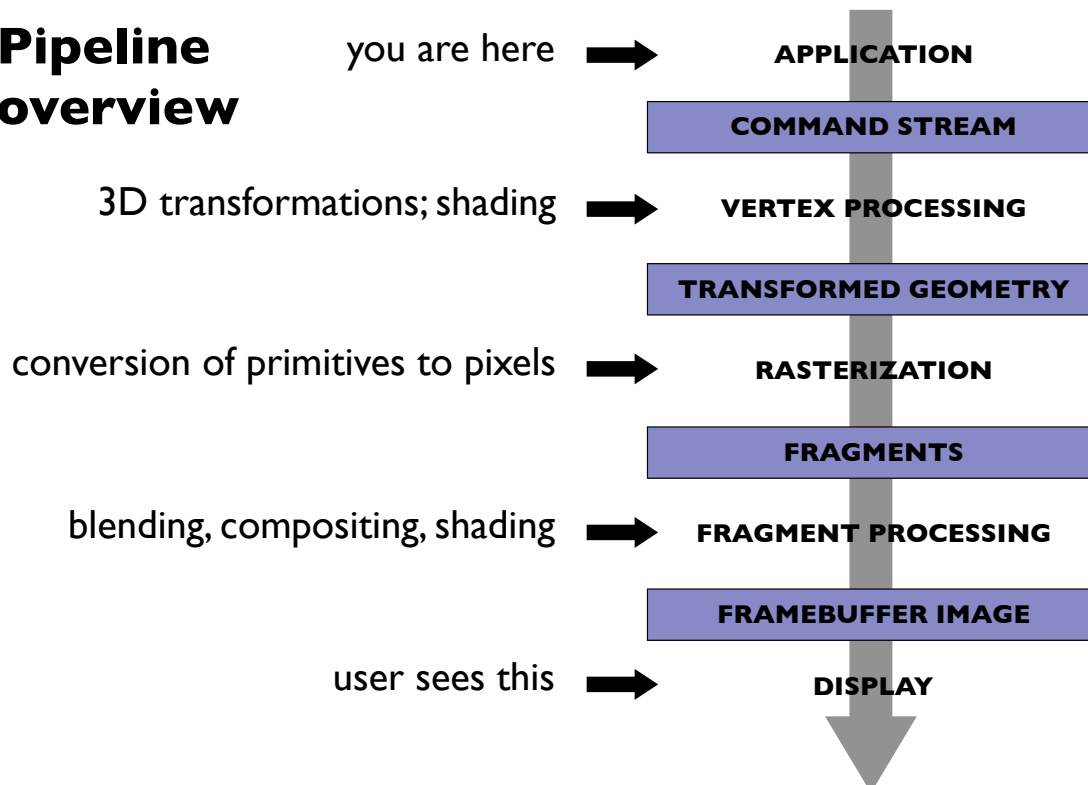
- Usually include ambient, diffuse, Phong in one model

$$\begin{aligned} L &= L_a + L_d + L_s \\ &= k_a I_a + k_d I \max(0, \mathbf{n} \cdot \mathbf{l}) + k_s I \max(0, \mathbf{n} \cdot \mathbf{h})^n \end{aligned}$$

- The final result is the sum over many lights

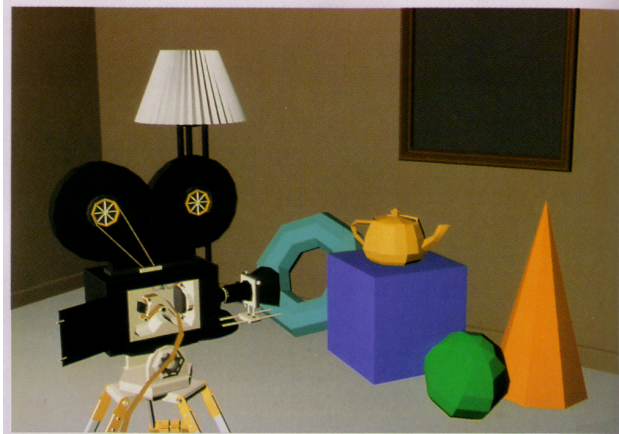
$$\begin{aligned} L &= L_a + \sum_{i=1}^N [(L_d)_i + (L_s)_i] \\ L &= k_a I_a + \sum_{i=1}^N [k_d I_i \max(0, \mathbf{n} \cdot \mathbf{l}_i) + k_s I_i \max(0, \mathbf{n} \cdot \mathbf{h}_i)^n] \end{aligned}$$

## Pipeline overview



# Flat shading

- Shade using the real normal of the triangle
- Leads to constant shading and faceted appearance
  - truest view of the mesh geometry



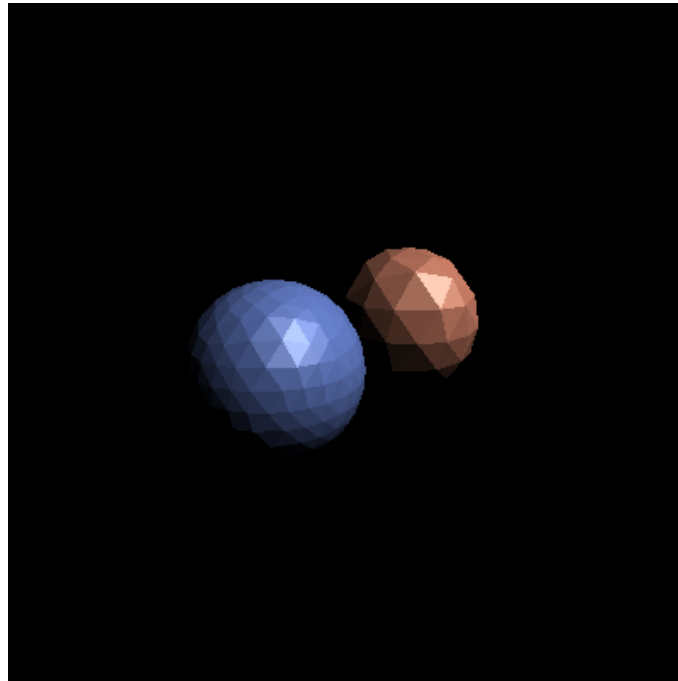
**Plate II.29** *Shutterbug*. Individually shaded polygons with diffuse reflection (Sections 14.4.2 and 16.2.3). (Copyright © 1990, Pixar. Rendered by Thomas Williams and H.B. Siegel using Pixar's PhotoRealistic RenderMan™ software.)

[Foley et al.]

## Pipeline for flat shading

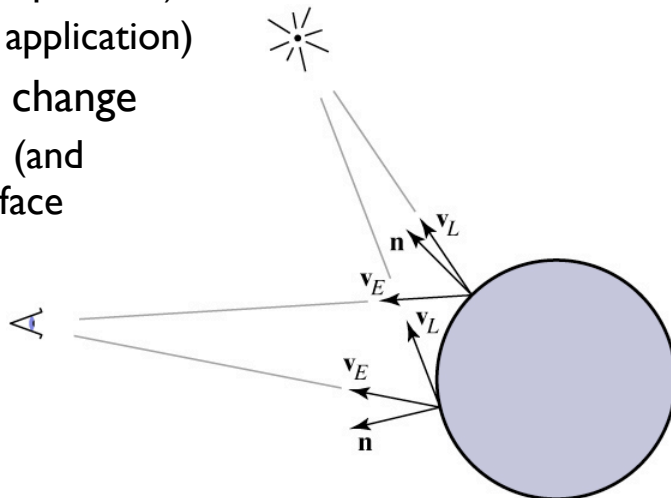
- Vertex stage (input: position / vtx; color and normal / tri)
  - transform position and normal (object to eye space)
  - compute shaded color per triangle using normal
  - transform position (eye to screen space)
- Rasterizer
  - interpolated parameters:  $z'$  (screen  $z$ )
  - pass through color
- Fragment stage (output: color,  $z'$ )
  - write to color planes only if interpolated  $z' < \text{current } z'$

## Result of flat-shading pipeline



## Local vs. infinite viewer, light

- Phong illumination requires geometric information:
  - light vector (function of position)
  - eye vector (function of position)
  - surface normal (from application)
- Light and eye vectors change
  - need to be computed (and normalized) for each face

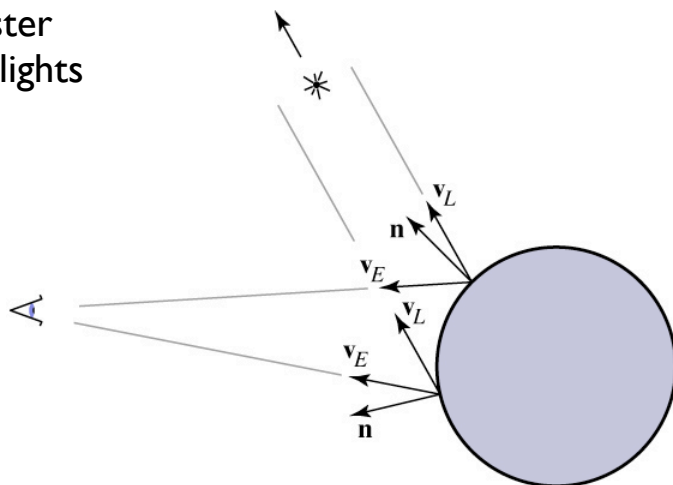


## Local vs. infinite viewer, light

- Look at case when eye or light is far away:
  - distant light source: nearly parallel illumination
  - distant eye point: nearly orthographic projection
  - in both cases, eye or light vector changes very little
- Optimization: approximate eye and/or light as infinitely far away

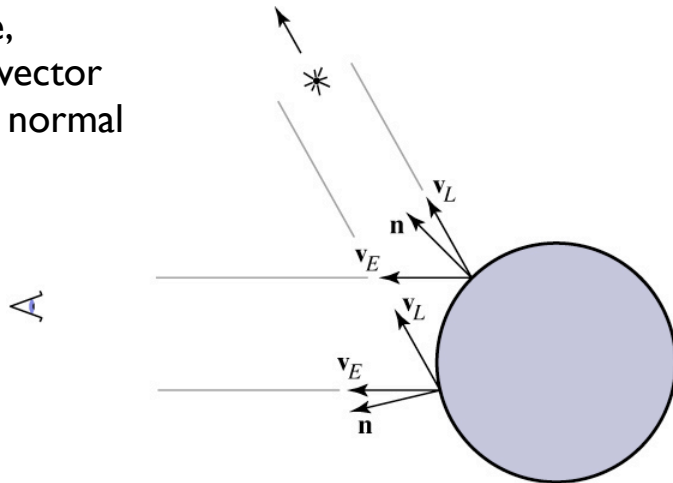
## Directional light

- Directional (infinitely distant) light source
  - light vector always points in the same direction
  - often specified by  $[x \ y \ z \ 0]$
  - many pipelines are faster if you use directional lights



# Infinite viewer

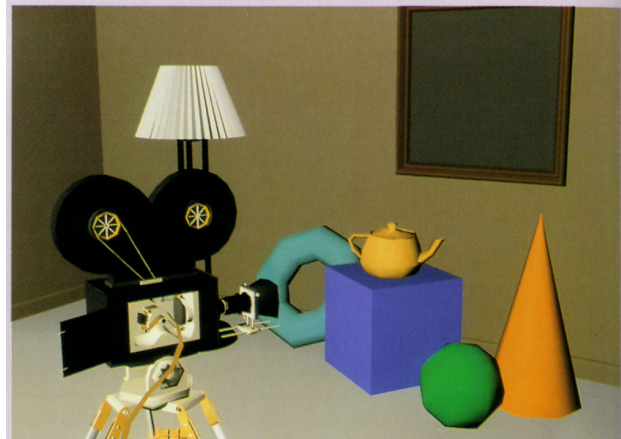
- Orthographic camera
  - projection direction is constant
- “Infinite viewer”
  - even with perspective, can approximate eye vector using the image plane normal
  - can produce weirdness for wide-angle views
  - Blinn-Phong: light, eye, half vectors all constant!



# Gouraud interpolation

- Often we’re trying to draw smooth surfaces, so facets are an artifact
  - compute colors at vertices using vertex normals
  - interpolate colors across triangles
  - “Gouraud shading”
    - **Gouraud interpolation**
  - “Smooth shading”
    - **Phong interpolation**

**Plate II.30** Shutterbug. Gouraud shaded polygons with diffuse reflection (Sections 14.4.3 and 16.2.4). (Copyright © 1990, Pixar. Rendered by Thomas Williams and H.B. Siegel using Pixar’s PhotoRealistic RenderMan™ software.)



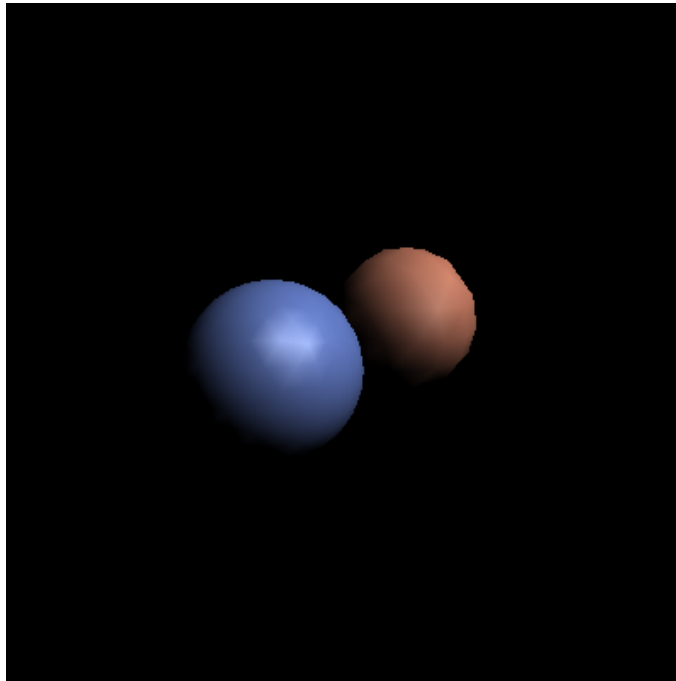
## Aside: naming

- Historical
  - Gouraud interpolation, Phong interpolation
    - Different types of smooth shading
  - Phong shading
    - Actually Phong reflectance model (diffuse, specular)
- Bad naming
  - Gouraud shading: not really shading
  - Phong shading: ambiguous
- Correct
  - Gouraud interpolation/shading, per-pixel shading

## Pipeline for Gouraud interpolation

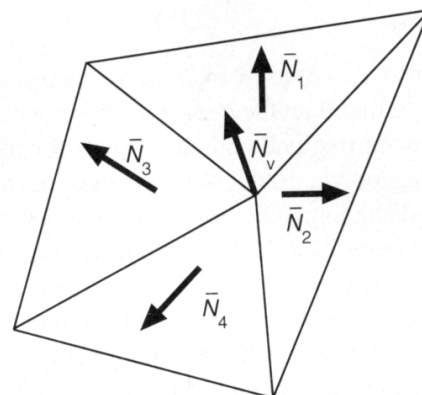
- Vertex stage (input: position, color, and normal / vtx)
  - transform position and normal (object to eye space)
  - compute shaded color per vertex
  - transform position (eye to screen space)
- Rasterizer
  - interpolated parameters:  $z'$  (screen  $z$ );  $r, g, b$  color
- Fragment stage (output: color,  $z'$ )
  - write to color planes only if interpolated  $z' < \text{current } z'$

## Result of Gouraud shading pipeline



## Vertex normals

- Need normals at vertices to compute Gouraud interpolation
- Best to get vtx. normals from the underlying geometry
  - e. g. spheres example
- Otherwise have to infer vtx. normals from triangles
  - simple scheme: average surrounding face normals



[Foley et al.]

$$N_v = \frac{\sum_i N_i}{\|\sum_i N_i\|}$$



## Non-diffuse Gouraud interpolation

- Can apply Gouraud interpolation to any illumination model
  - it's just an interpolation method
- Results are not so good with fast-varying models like specular ones
  - problems with any highlights smaller than a triangle

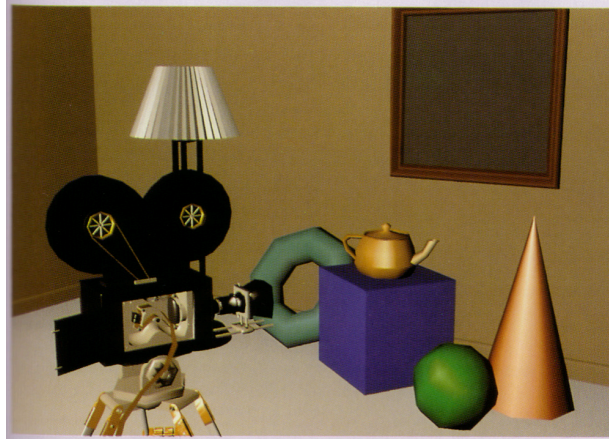
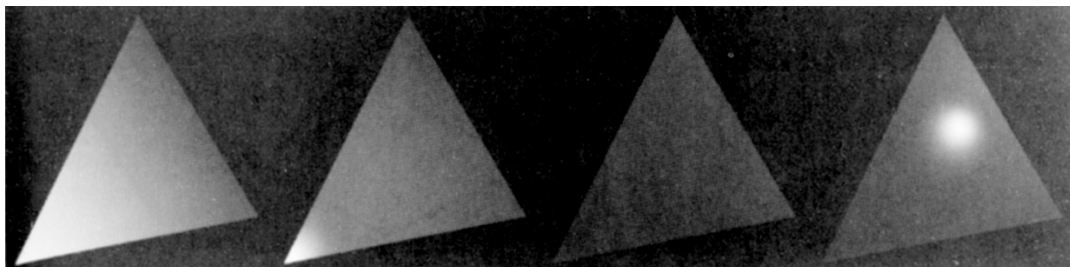


Plate II.31 Shutterbug. Gouraud shaded polygons with specular reflection (Sections 14.4.4 and 16.2.5). (Copyright © 1990, Pixar. Rendered by Thomas Williams and H.B. Siegel using Pixar's PhotoRealistic RenderMan™ software.)

[Foley et al.]

## Per-pixel (Phong) interpolation

- Get higher quality by interpolating the normal
  - just as easy as interpolating the color
  - but now we are evaluating the illumination model per pixel rather than per vertex (and normalizing the normal first)
  - in pipeline, this means we are moving illumination from the vertex processing stage to the fragment processing stage



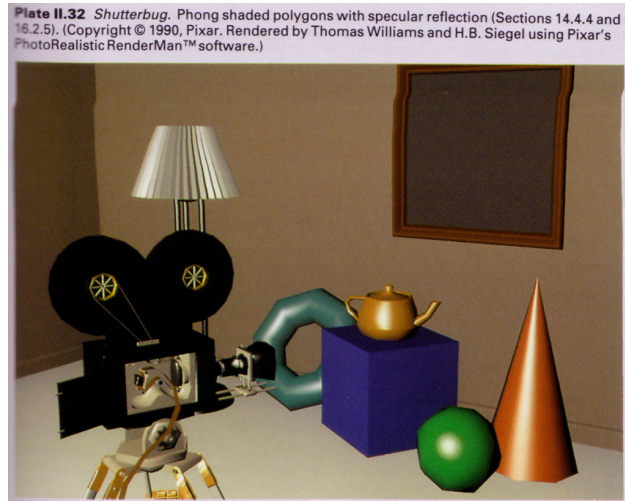
# Phong (per-pixel) interpolation

- Bottom line: produces much better highlights



Shutterbug. Gouraud shaded polygons with specular reflection (Sections 14.4.4 and 16.2.5). (Copyright © 1990, Pixar. Rendered by Thomas Williams and H.B. Siegel using Pixar's PhotoRealistic RenderMan™ software.)

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[Foley et al.]

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(with previous instructors James/Marschner)

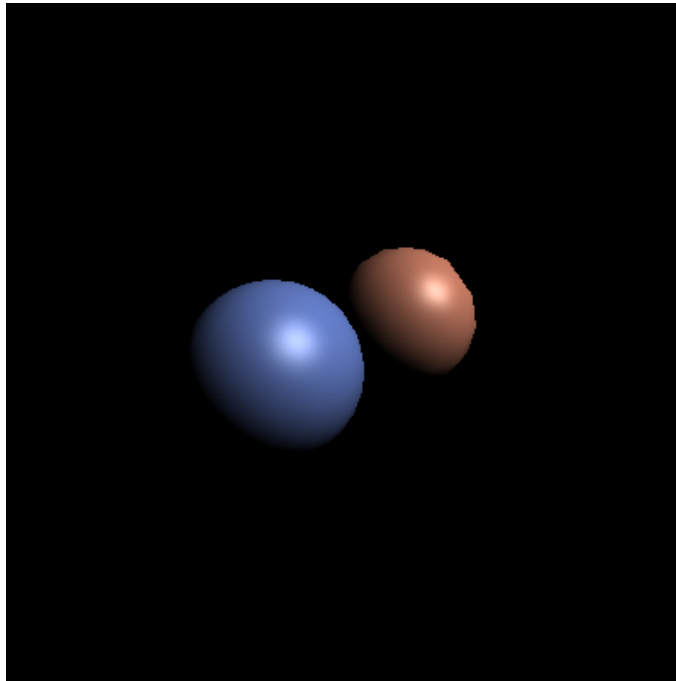
## Pipeline for per-pixel (Phong) interpolation

- Vertex stage (input: position, color, and normal / vtx)
  - transform position and normal (object to eye space)
  - transform position (eye to screen space)
  - pass through color
- Rasterizer
  - interpolated parameters:  $z'$  (screen  $z$ );  $r, g, b$  color;  $x, y, z$  normal
- Fragment stage (output: color,  $z'$ )
  - compute shading using interpolated color and normal
  - write to color planes only if interpolated  $z' < \text{current } z'$

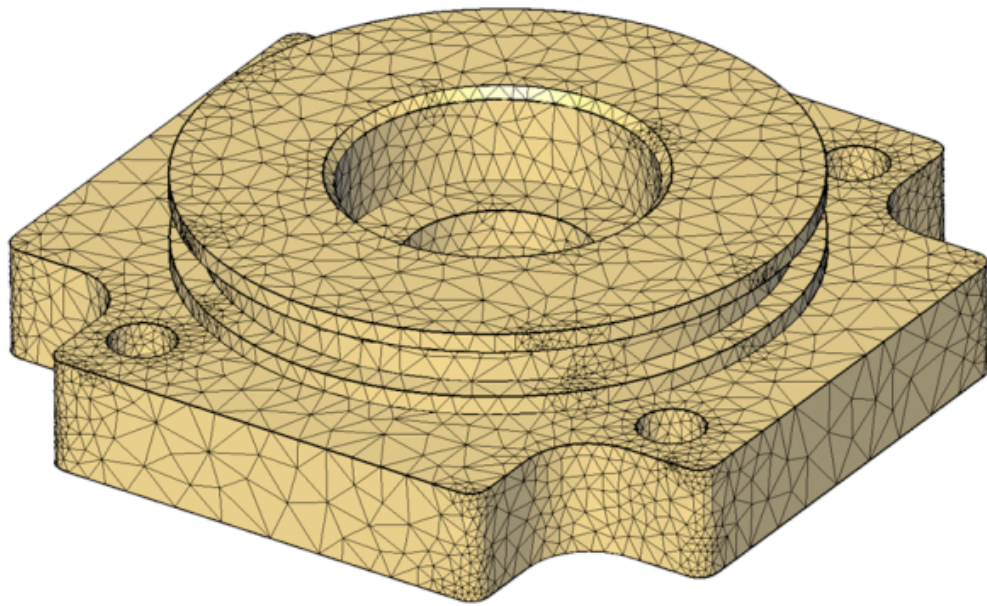
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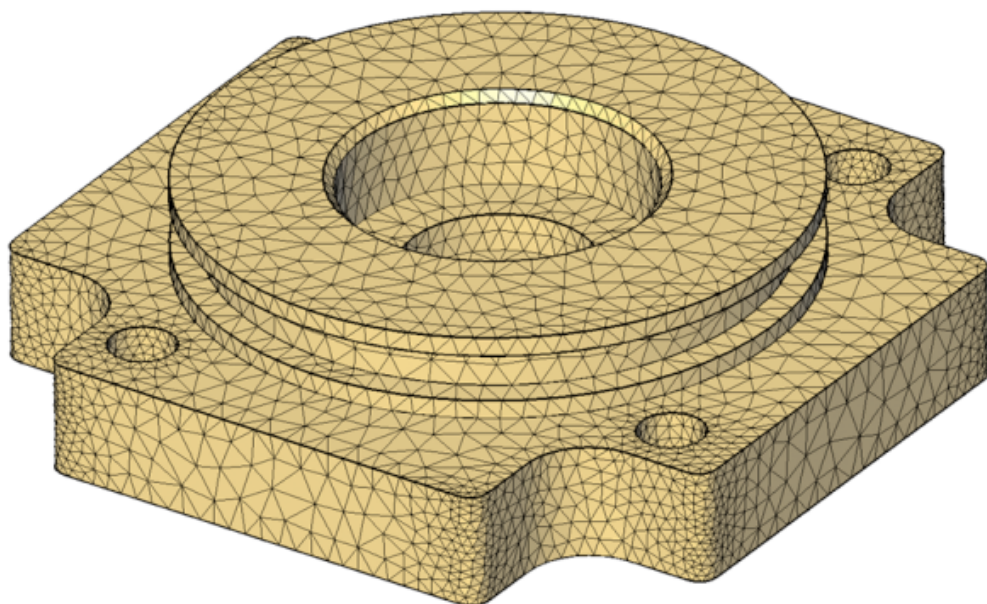
## Result of per-pixel shading pipeline



## Meshes



<http://rallyx.inria.fr/2008/Raweb/geometrica/uid15.html>



<http://rallyx.inria.fr/2008/Raweb/geometrica/uid15.html>

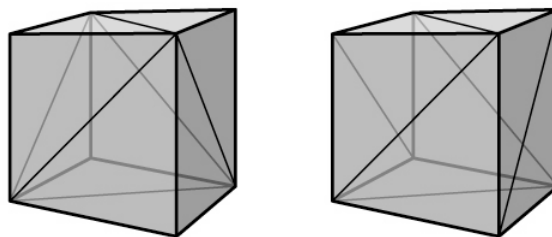


## Aspects of meshes

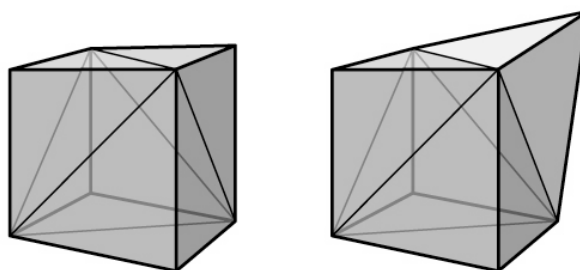
- in many cases we care about the mesh being able to bound a region of space nicely
- in other cases we want triangle meshes to fulfill assumptions of algorithms that will operate on them (and may fail on malformed input)
- two completely separate issues:
  - topology: how the triangles are connected (ignoring the positions entirely)
  - geometry: where the triangles are in 3D space

## Topology/geometry examples

- same geometry, different mesh topology:



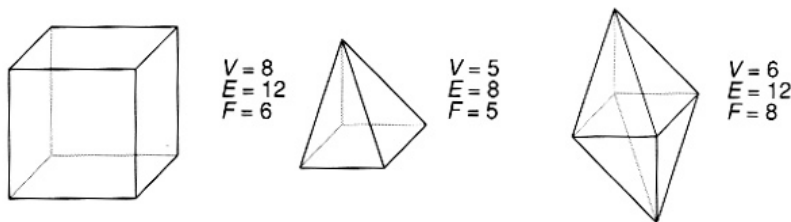
- same mesh topology, different geometry:



# Notation



- $n_T = \#tris; n_V = \#verts; n_E = \#edges$
- Euler:  $n_V - n_E + n_T = 2$  for a simple closed surface  
–and in general sums to small integer



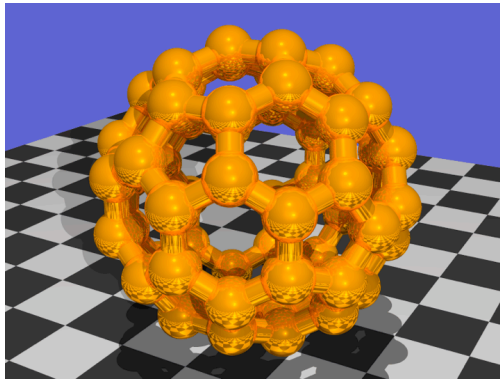
[Foley et al.]

## Examples of simple convex polyhedra

Name	Image	Vertices $V$	Edges $E$	Faces $F$	Euler characteristic: $V - E + F$
Tetrahedron		4	6	4	2
Hexahedron or cube		8	12	6	2
Octahedron		6	12	8	2
Dodecahedron		20	30	12	2
Icosahedron		12	30	20	2

[http://en.wikipedia.org/wiki/Euler\\_characteristic](http://en.wikipedia.org/wiki/Euler_characteristic)

# Examples of simple convex polyhedra



<http://idav.ucdavis.edu/~okreylos/BuckyballStick.gif>

## Buckyball

$$V = 60$$

$$E = 90$$

$$F = 32 \text{ (12 pentagons + 20 hexagons)}$$

$$V - E + F = 60 - 90 + 32 = 2$$



## Examples (nonconvex polyhedra!)

Name	Image	Vertices $V$	Edges $E$	Faces $F$	Euler characteristic: $V - E + F$
Tetrahemihexahedron		6	12	7	1
Octahemioctahedron		12	24	12	0
Cubohemioctahedron		12	24	10	-2
Great icosahedron		12	30	20	2

[http://en.wikipedia.org/wiki/Euler\\_characteristic](http://en.wikipedia.org/wiki/Euler_characteristic)

## Euler's Formula

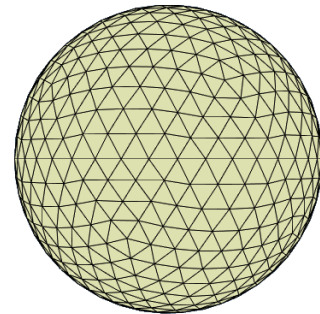
- $n_V = \# \text{verts}$ ;  $n_E = \# \text{edges}$ ;  $n_F = \# \text{faces}$

- Euler's Formula for a convex polyhedron:

$$n_V - n_E + n_F = 2$$

- Other meshes often sum to small integer

– argument for implication that  $n_V:n_E:n_F$  is about 1:3:2



## Representation of triangle meshes

- Compactness
- Efficiency for rendering
  - enumerate all triangles as triples of 3D points
- Efficiency of queries
  - all vertices of a triangle
  - all triangles around a vertex
  - neighboring triangles of a triangle
  - (need depends on application)
    - finding triangle strips
    - computing subdivision surfaces
    - mesh editing

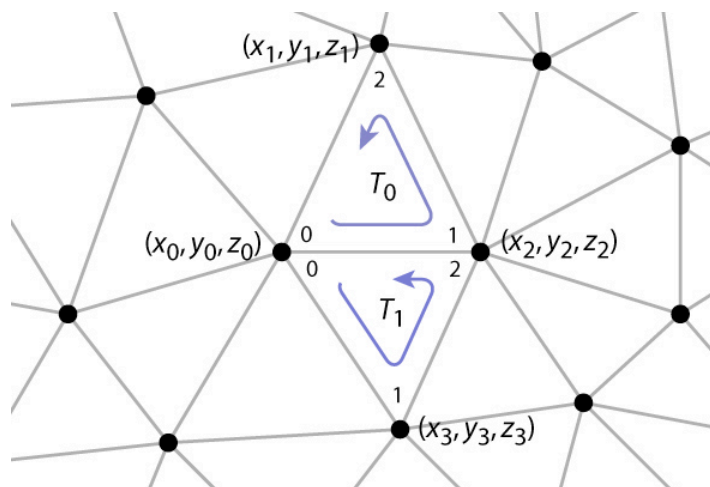


# Representations for triangle meshes

- Separate triangles
- Indexed triangle set
  - shared vertices
- Triangle strips and triangle fans
  - compression schemes for transmission to hardware
- Triangle-neighbor data structure
  - supports adjacency queries
- Winged-edge data structure
  - supports general polygon meshes

## Separate triangles

	[0]	[1]	[2]
tris[0]	$x_0, y_0, z_0$	$x_2, y_2, z_2$	$x_1, y_1, z_1$
tris[1]	$x_0, y_0, z_0$	$x_3, y_3, z_3$	$x_2, y_2, z_2$
	$\vdots$	$\vdots$	$\vdots$



## Separate triangles

- array of triples of points
  - `float[nT][3][3]`: about 72 bytes per vertex
    - 2 triangles per vertex (on average)
    - 3 vertices per triangle
    - 3 coordinates per vertex
    - 4 bytes per coordinate (float)
- various problems
  - wastes space (each vertex stored 6 times)
  - cracks due to roundoff
  - difficulty of finding neighbors at all