

## CS4620/5620: Lecture 25

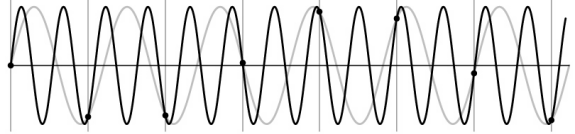
### Sampling and Antialiasing

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## Undersampling

- What if we “missed” things between the samples?
- Simple example: undersampling a sine wave
  - unsurprising result: information is lost
  - surprising result: indistinguishable from lower frequency
  - also was always indistinguishable from higher frequencies
  - *aliasing*: signals “traveling in disguise” as other frequencies

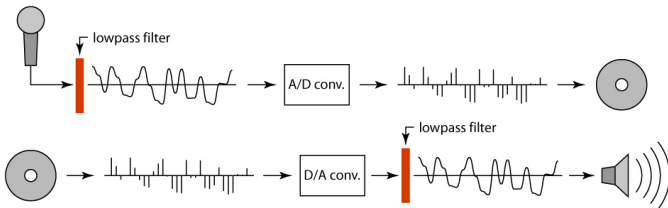


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## Preventing aliasing

- Introduce lowpass filters:
  - remove high frequencies leaving only safe, low frequencies
  - choose lowest frequency in reconstruction (disambiguate)

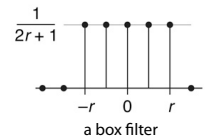


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## Filters

- Sequence of weights  $a[j]$  is called a *filter*
- Filter is nonzero over its *region of support*
  - usually centered on zero: support radius  $r$
- Filter is *normalized* so that it sums to 1.0
  - this makes for a weighted average, not just any old weighted sum
- Most filters are symmetric about 0
  - since for images we usually want to treat left and right the same

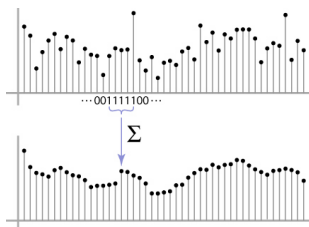


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## Convolution and filtering

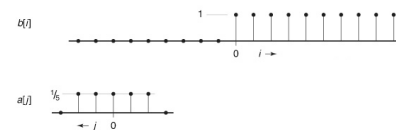
- Can express sliding average as convolution with a *box filter*
- $a_{\text{box}} = [\dots, 0, 1, 1, 1, 1, 0, \dots]$



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## Example: box and step

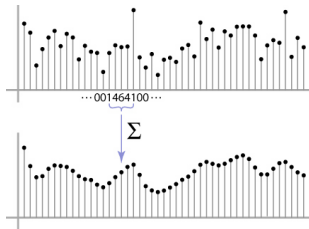


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## Convolution and filtering

- Convolution applies with any sequence of weights
- Example: Bell curve (Gaussian-like) [..., 1, 4, 6, 4, 1, ...]/16



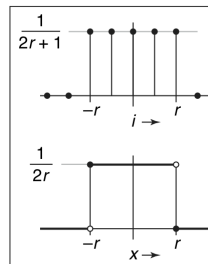
## A gallery of filters

- Box filter
  - Simple and cheap
- Tent filter
  - Linear interpolation
- Gaussian filter
  - Very smooth antialiasing filter
- B-spline cubic
  - Very smooth
- ...

## Box filter

$$a_{\text{box},r}[i] = \begin{cases} 1/(2r+1) & |i| \leq r, \\ 0 & \text{otherwise.} \end{cases}$$

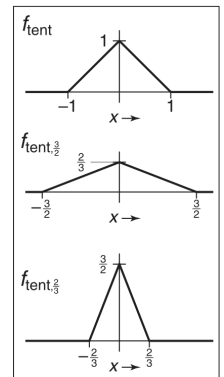
$$f_{\text{box},r}(x) = \begin{cases} 1/(2r) & -r \leq x < r, \\ 0 & \text{otherwise.} \end{cases}$$



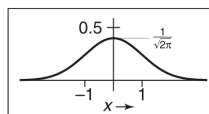
## Tent filter

$$f_{\text{tent}}(x) = \begin{cases} 1 - |x| & |x| < 1, \\ 0 & \text{otherwise;} \end{cases}$$

$$f_{\text{tent},r}(x) = \frac{f_{\text{tent}}(x/r)}{r}.$$



## Gaussian filter



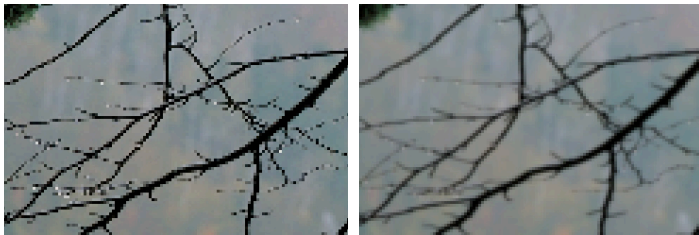
$$f_g(x) = \frac{1}{\sqrt{2\pi}} e^{-x^2/2}.$$

## Resampling

- Changing the sample rate
  - in images, this is enlarging and reducing
- Creating more samples:
  - increasing the sample rate
  - “upsampling”
  - “enlarging”
- Ending up with fewer samples:
  - decreasing the sample rate
  - “downsampling”
  - “reducing”

## Reducing and enlarging

- Very common operation
  - devices have differing resolutions
  - applications have different memory/quality tradeoffs
- Also very commonly done poorly
- Simple approach: drop/replicate pixels
- Correct approach: use resampling



[Philip Greenspun]

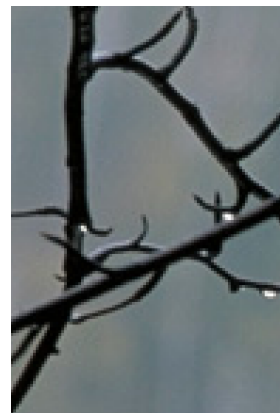


by dropping pixels

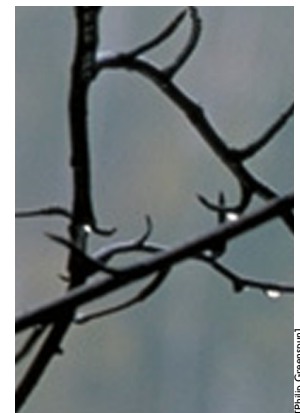


gaussian filter

250 pixel width



box reconstruction filter



bicubic reconstruction filter

[Philip Greenspun]

4000 pixel width

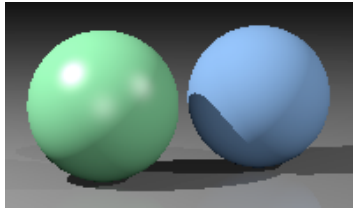
## Types of artifacts

- Garden variety
  - what we saw in this natural image
  - fine features become jagged or sparkle
- Moiré patterns
  - caused by repetitive patterns in input
  - produce large-scale artifacts; highly visible
- These artifacts are *aliasing* just like in the audio example earlier
- How do I know what filter is best at preventing aliasing?
  - practical answer: experience
  - theoretical answer: there is another layer of cool math behind all this

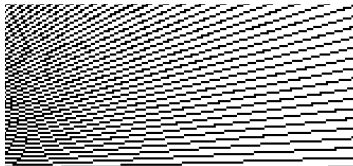
## Antialiasing

## Aliasing

point sampling a  
continuous image:



continuous image defined  
by ray tracing procedure



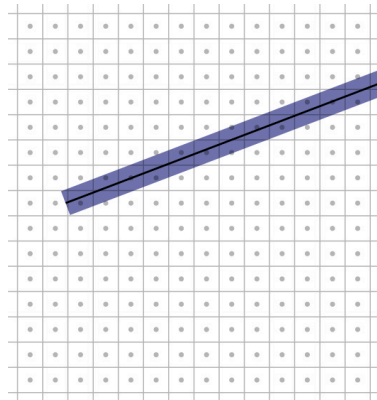
continuous image defined  
by a bunch of black rectangles

## Antialiasing

- A name for techniques to prevent aliasing
- In image generation, we need to lowpass filter
  - Sampling the convolution of filter & image
  - Boils down to averaging the image over an area
  - Weight by a filter
- Methods depend on source of image
  - Rasterization (lines and polygons)
  - Point sampling (e.g. ray tracing)
  - Texture mapping

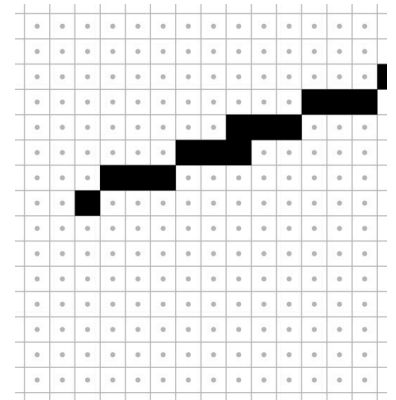
## Rasterizing lines

- Define line as a rectangle
- Specify by two endpoints
- Ideal image: black inside, white outside

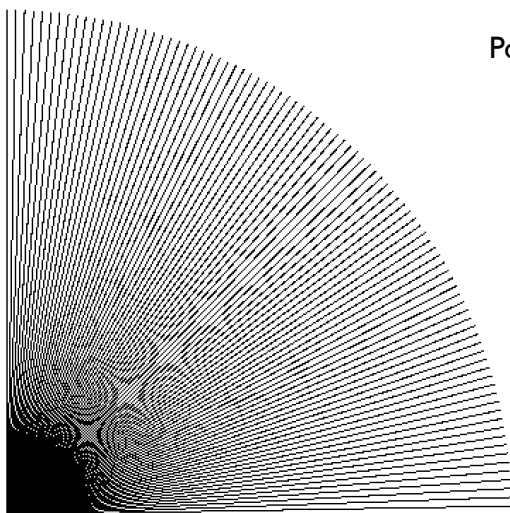


## Point sampling

- Approximate rectangle by drawing all pixels whose centers fall within the line
- Problem: all-or-nothing leads to jaggies
  - this is sampling with no filter (aka. point sampling)

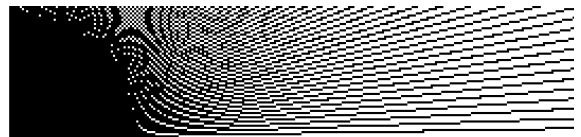


## Point sampling in action



## Aliasing

- Point sampling is fast and simple
- But the lines have stair steps and variations in width
- This is an aliasing phenomenon
  - Sharp edges of line contain high frequencies
- Introduces features to image that are not supposed to be there!



## Antialiasing

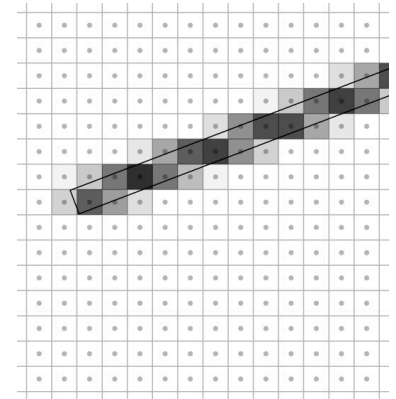
- Point sampling makes an all-or-nothing choice in each pixel
  - therefore steps are inevitable when the choice changes
  - discontinuities are bad
- On bitmap devices this is necessary
  - hence high resolutions required
  - 600+ dpi in laser printers to make aliasing invisible
- On continuous-tone devices we can do better

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## Antialiasing

- Basic idea: replace “is the image black at the pixel center?” with “how much is pixel covered by black?”
- Replace yes/no question with quantitative question.



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## Box filtering

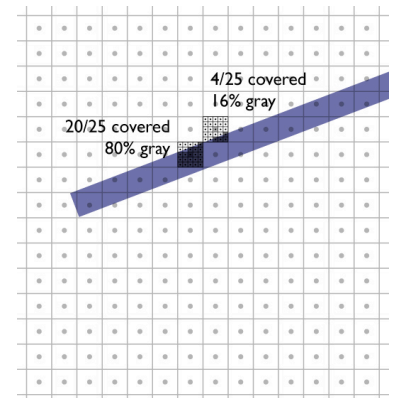
- Pixel intensity is proportional to area of overlap with square pixel area
- Also called “unweighted area averaging”

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## Box filtering by supersampling

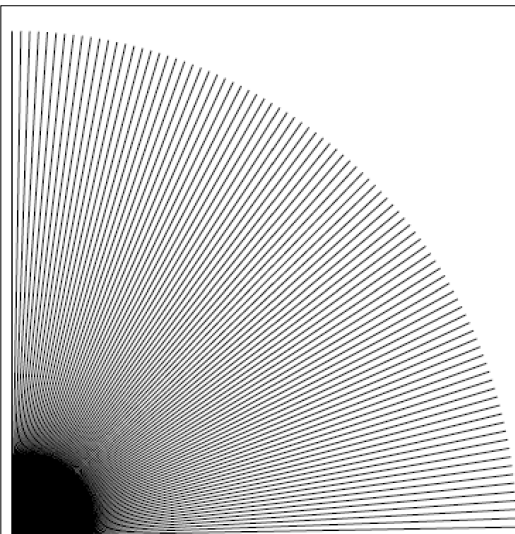
- Compute coverage fraction by counting subpixels
- Simple, accurate
- But slow



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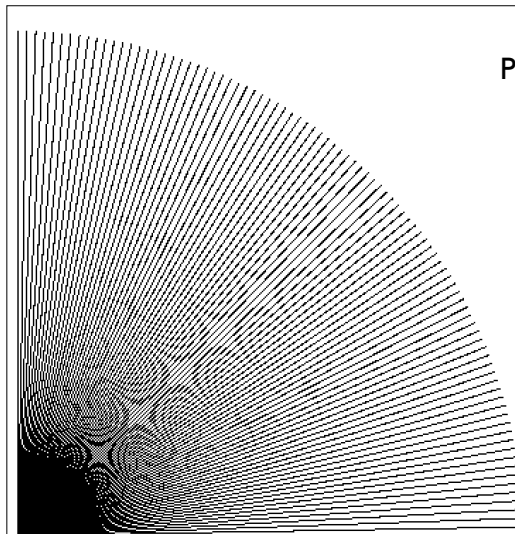
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## Box filtering in action



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## Point sampling in action



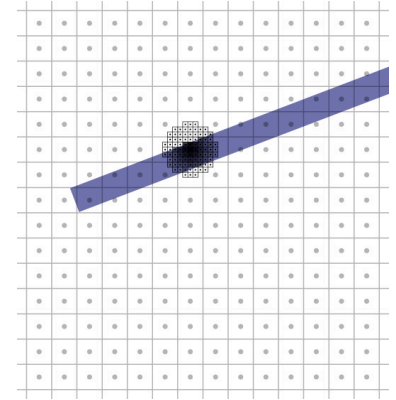
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## Weighted filtering

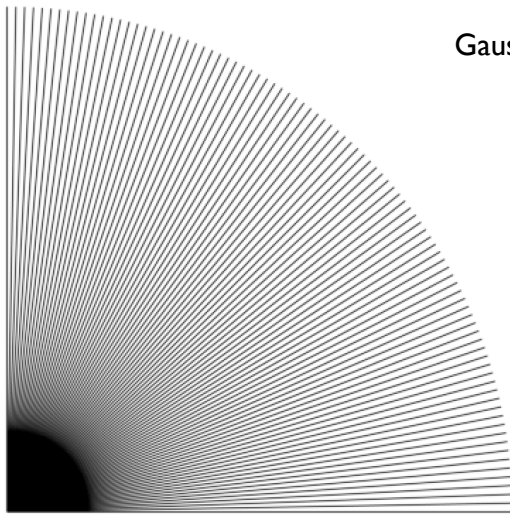
- Box filtering problem: treats area near edge same as area near center
  - results in pixel turning on “too abruptly”
- Alternative: weight area by a smoother filter
  - unweighted averaging corresponds to using a box function
  - sharp edges mean high frequencies
    - so want a filter with good extinction for higher freqs.
  - a Gaussian is a popular choice of smooth filter
  - important property: normalization (unit integral)

## Weighted filtering by supersampling

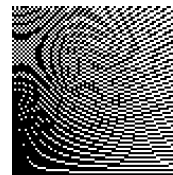
- Compute filtering integral by summing filter values for covered subpixels
- Simple, accurate
- But really slow



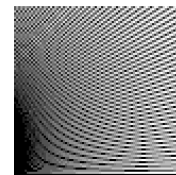
## Gaussian filtering in action



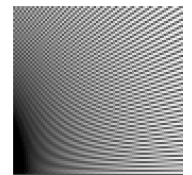
## Filter comparison



Point sampling

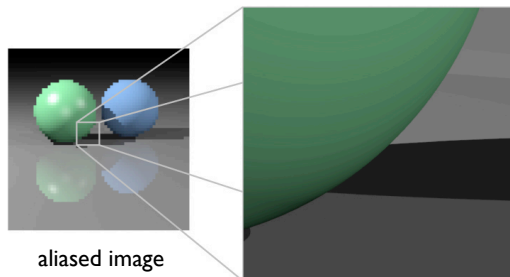


Box filtering



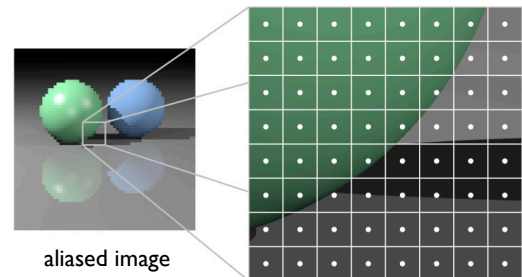
Gaussian filtering

## Antialiasing in ray tracing



aliased image

## Antialiasing in ray tracing

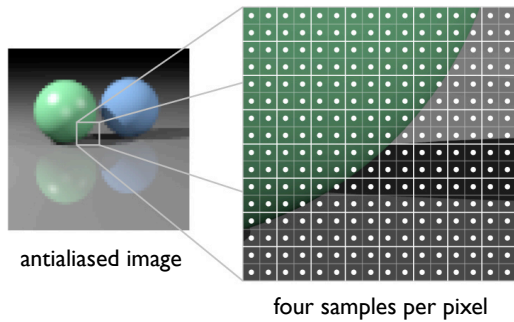


aliased image

one sample per pixel



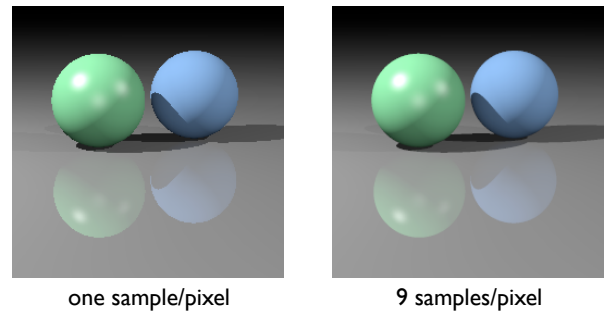
## Antialiasing in ray tracing



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## Antialiasing in ray tracing



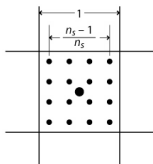
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## Details of supersampling

- For image coordinates with integer pixel centers:

```
// one sample per pixel
for iy = 0 to (ny-1) by 1
  for ix = 0 to (nx-1) by 1 {
    ray = camera.getRay(ix, iy);
    image.set(ix, iy, trace(ray));
  }
```



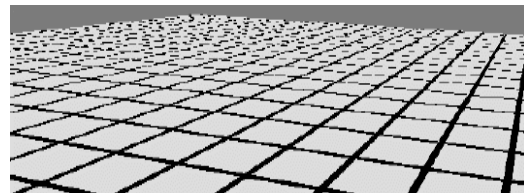
```
// ns^2 samples per pixel
for iy = 0 to (ny-1) by 1
  for ix = 0 to (nx-1) by 1 {
    Color sum = 0;
    for dx = -(ns-1)/2 to (ns-1)/2 by 1
      for dy = -(ns-1)/2 to (ns-1)/2 by 1 {
        x = ix + dx / ns;
        y = iy + dy / ns;
        ray = camera.getRay(x, y);
        sum += trace(ray);
      }
    image.set(ix, iy, sum / (ns*ns));
  }
```

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## Antialiasing in textures

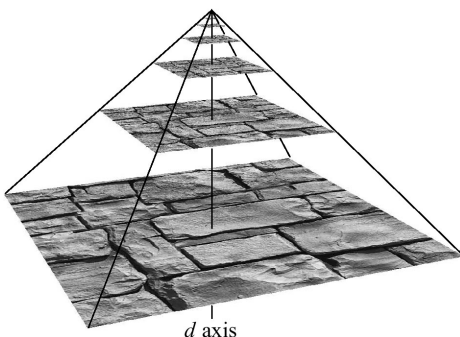
- Would like to render textures with one (or few) s/p
- Need to filter first!
  - perspective produces very high image frequencies



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## Mipmap image pyramid

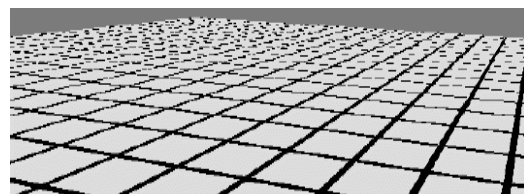


[Akenine-Möller & Haines 2002]

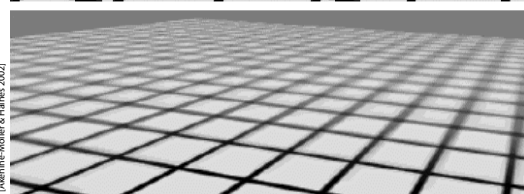
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## Texture minification



point  
sampled  
minification



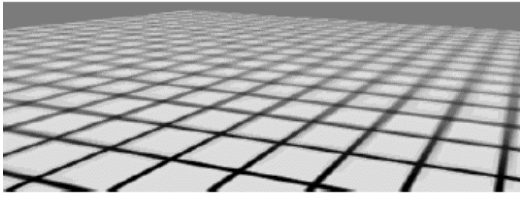
mipmap  
minification

[Akenine-Möller & Haines 2002]

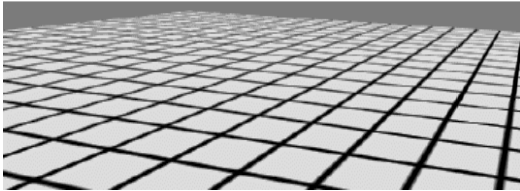
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## Texture minification



mipmap  
minification



higher  
quality  
minification

(Aurion-Miller & Haines, 2002)