CS4620/5620: Lecture 9

Scene Graph

Cornell CS4620/5620 Fall 2011 • Lecture 9

© 2011 Kavita Bala •

Announcements

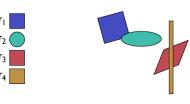
- PA 0
- HW I is due on Friday
 - -On CMS (type it, scan it)
 - -Or drop it off my office (if I am in meeting, just drop it off)
- PA 0 and PA I apply to 5620/4620 (not the practicum)
- Staff list
 - -cs4620-staff-l@cornell.edu

Cornell CS4620/5620 Fall 2011 • Lecture 9

© 2011 Kavita Bala •

Data structures with transforms

- Representing a drawing ("scene")
- · List of objects
- Transform for each object
 - can use minimal primitives: ellipse is transformed circle
 - -transform applies to points of object

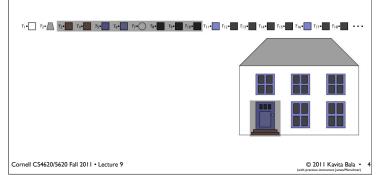


Cornell CS4620/5620 Fall 2011 • Lecture 9

© 2011 Kavita Bala •

Example

- · Can represent drawing with flat list
 - -but editing operations require updating many transforms

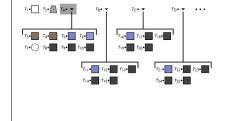


Groups of objects

- Treat a set of objects as one
- Introduce new object type: group
 - -contains list of references to member objects
- This makes the model into a tree
 - -interior nodes = groups
 - -leaf nodes = objects
 - -edges = membership of object in group

Example

- · Add group as a new object type
 - -lets the data structure reflect the drawing structure
 - enables high-level editing by changing just one node





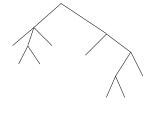
© 2011 Kavita Bala •

© 2011 Kavita Bala • 5 Cornell CS4620/5620 Fall 2011 • Lecture 9

Cornell CS4620/5620 Fall 2011 • Lecture 9

The Scene Graph (tree)

- A name given to various kinds of graph structures (nodes connected together) used to represent scenes
- Simplest form: tree
 - -just saw this
 - every node has one parent
 - leaf nodes are identified with objects in the scene



Cornell CS4620/5620 Fall 2011 • Lecture 9

© 2011 Kavita Bala •

Concatenation and hierarchy

- Transforms associated with nodes or edges
- Each transform applies to all geometry below it
 - -want group transform to transform each member
 - -members already transformed—concatenate
- Frame transform for object is product of all matrices along path from root
 - each object's transform describes relationship between its local coordinates and its group's coordinates
 - frame-to-canonical transform is the result of repeatedly changing coordinates from group to containing group

Cornell CS4620/5620 Fall 2011 • Lecture 9

© 2011 Kavita Bala •

Instances

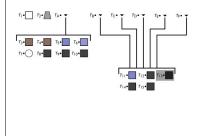
- Simple idea: allow an object to be a member of more than one group at once
 - -transform different in each case
 - -leads to linked copies
 - single editing operation changes all instances

Cornell CS4620/5620 Fall 2011 • Lecture 9

© 2011 Kavita Bala • previous instructors (ames/Marschner)

Example

- Allow multiple references to nodes
 - -allows editing of repeated parts in one operation





© 2011 Kavita Bala •

Cornell CS4620/5620 Fall 2011 • Lecture 9

The Scene Graph (with instances)

- · With instances, there is no more tree
 - -an object that is instanced multiple times has more than one parent
- Transform tree becomes DAG
 - -directed acyclic graph
 - group is not allowed to contain itself, even indirectly
- Transforms still accumulate along path from root
 - now paths from root to leaves are identified with scene objects



© 2011 Kavita Bala • 11

Implementing a hierarchy

- · Object-oriented language is convenient
 - define shapes and groups as derived from single class

```
abstract class Shape {
    void draw();
}
class Square extends Shape {
    void draw() {
        // draw unit square
    }
}
class Circle extends Shape {
    void draw() {
        // draw unit circle
    }
}
```

Cornell CS4620/5620 Fall 2011 • Lecture 9

© 2011 Kavita Bala • 12

Cornell CS4620/5620 Fall 2011 • Lecture 9

Implementing traversal

- · Pass a transform down the hierarchy
 - -before drawing, concatenate

```
abstract class Shape {
    void draw(Transform t_c);
}

class Square extends Shape {
    void draw(Transform t_c) {
        // draw t_c * unit square
    }
}

class Circle extends Shape {
    void draw(Transform t_c) {
        // draw t_c * unit circle
    }
}

class Circle extends Shape {
    void draw(Transform t_c) {
        // draw t_c * unit circle
    }
}
```

© 2011 Kavita Bala • 13

Basic Scene Graph operations

- Editing a transformation
- Getting transform of object in canonical (world) frame
 - -traverse path from root to leaf
- · Grouping and ungrouping
 - can do these operations without moving anything
 - -group: insert identity node
 - -ungroup: remove node, push transform to children
- Reparenting
 - -move node from one parent to another
 - -can do without altering position

Cornell CS4620/5620 Fall 2011 • Lecture 9

© 2011 Kavita Bala • 14

Adding more than geometry

- Objects have properties besides shape
 - -color, shading parameters
 - -approximation parameters (e.g. precision of subdividing curved surfaces into triangles)
 - -behavior in response to user input

– . .

Cornell CS4620/5620 Fall 2011 • Lecture 9

- Setting properties for entire groups is useful
 - -paint entire window green
- Many systems include some kind of property nodes
 - -in traversal they are read as, e.g., "set current color"

Cornell CS4620/5620 Fall 2011 • Lecture 9

© 2011 Kavita Bala • 15

Scene Graph variations

- Where transforms go
 - -in every node
 - on edges
 - in group nodes only
 - in special Transform nodes
- Tree vs. DAG
- Nodes for cameras and lights?

Cornell CS4620/5620 Fall 2011 • Lecture 9

© 2011 Kavita Bala • 16 (with previous instructors James/Marschner)