CS4450

Computer Networks: Architecture and Protocols

Lecture 7
"Why" Frames
"Why" Switched Ethernet
Spanning Tree Protocol

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Announcements

• Problem Set 2 is out (course webpage)

Goals for Today's Lecture

- Dive deep into Link layer design
 - Redo CSMA/CD
 - Why Frames? Implementing Link Layer on top of Physical Layer
 - Why Switched Ethernet? Understanding scalability problems
- Introduction to Switched Ethernet: THE Spanning Tree Protocol

Recap from last lecture

Recap: Data Link Layer

- Communication Medium
 - Point-to-point
 - The high-level ideas discussed so far were for point-to-point
 - Broadcast
 - Original design of Link layer protocols
 - More recent versions have moved to point-to-point
 - We will discuss why so!
- Network Adapters (e.g., NIC network interface card)
 - The hardware that connects a machine to the network
 - Has a "name" MAC (Medium access control) address







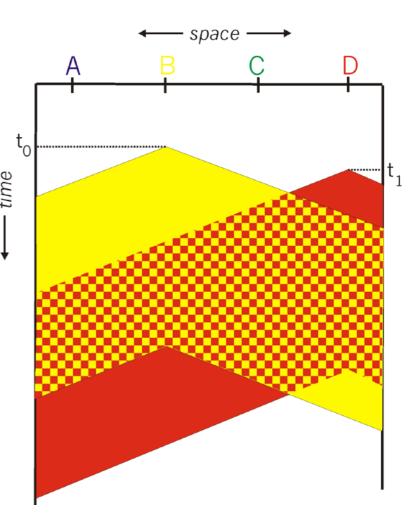


Recap: Sharing a broadcast channel

- Context: a shared broadcast channel
 - Must avoid/handle having multiple sources speaking at once
 - Otherwise collisions lead to garbled data
 - Need distributed algorithm for sharing channel
 - Algorithm determines when and which source can transmit
- Three classes of techniques
 - Frequency-division multiple access: coordinated sharing in space
 - Time-division multiple access: coordinated sharing in time
 - Random access: uncoordinated sharing
 - Detect collisions, and if needed, recover from collisions
 - Carrier Sense Multiple Access (CSMA)

Recap: CSMA (Carrier Sense Multiple Access)

- CSMA: listen before transmit
 - If channel sensed idle: transmit entire frame
 - If channel sensed busy: defer transmission
- Does this eliminate all collisions?
 - No, because of nonzero propagation delay
- Solution:
 - Include a Collision Detection (CD) mechanis
 - If a collision detected
 - Retransmit
 - When to retransmit?



Recap: Once a collision is detected ...

- When should the frame be retransmitted?
- Immediately?
 - Every NIC would start sending immediately
 - Collision again!
- Take turns?
 - Back to time division multiplexing
 - Problem?
 - Underutilization

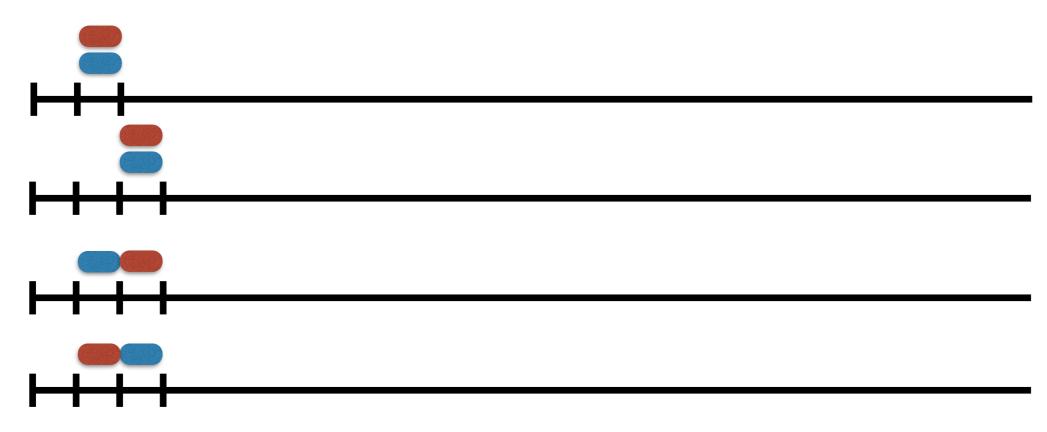
Recap: CSMA/CD in one slide!

- Carrier Sense: continuously listen to the channel
 - If idle: start transmitting
 - If busy: wait until idle
- Collision Detection: listen while transmitting
 - No collision: transmission complete
 - Collision: abort transmission
- When to retransmit?: exponential back off
 - After collision, transmit after "waiting time"
 - After k collisions, choose "waiting time" from {0, ..., 2^k-1)
 - Exponentially increasing waiting times
 - But also, exponentially larger success probability

Recap: Exponential Back-off: An example



Attempt 1: Suppose a collision happens



Attempt 2: Four possibilities

Success with Probability = 0.5

Group Exercise:

What is the success probability in attempt 3?

Answer: **0.75**

Questions?

Why Frames?

(Layering: Link Layer on top of Physical Layer)

Building Link Layer on top of Physical Layer

- Physical layer sends/receives bits on a link, and forwards to link layer
- View at the destination side physical layer:

01010110011111111111111111111110010101000111

Challenge: how to take the above bits and convert to:

- **Problem**: how does the link layer separate data into correct "chunks"?
 - Chunks belonging to different applications
- Data link layer interfaces with physical layer using frames
 - Implemented by the network adaptor
 - Finally: What are these frames?



Frames



Identifying start/end of frames: Sentinel Bits

- Delineate frame with special "sentinel" bit pattern
 - e.g., 01111110 -> start, 01111111 -> end

01111110 Frame contents **01111111**

- Problem: what if the sentinel occurs within the frame?
- Solution: bit stuffing
 - Sender always inserts a **0** after five **1**s in the frame content
 - Receiver always removes a 0 appearing after five 1s

When Receiver sees five 1s...

01111110 Frame contents **01111111**

- If next bit is 0, remove it, and begin counting again
 - Because this must be a stuffed bit
 - we can't be at beginning/end of frame (those had six/seven 1s)
- If next bit is 1 (i.e., we have six 1s) then:
 - If following bit is 0, this is the start of the frame
 - Because the receiver has seen 011111110
 - If following bit is 1, this is the end of the frame
 - Because the receiver has seen 01111111

Example: Sentinel Bits

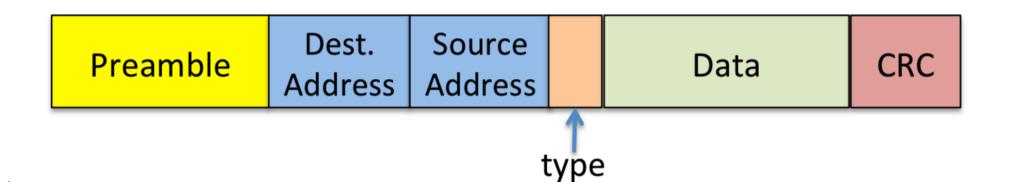
Original data, including start/end of frame:

- Sender rule: five 1s -> insert a 0
- After bit stuffing at the sender:

Receiver rule: five 1s and next bit 0 -> remove 0

<u>01111110011111</u>10<u>11111</u>0<u>11111</u>00101111111

Ethernet "Frames"



Preamble:

- 7 bytes for clock synchronization
- 1 byte to indicate start of the frame
- Names: 6 + 6 bytes (MAC names/addresses)
- Protocol type: 2 bytes, indicating higher layer protocol (e.g., IP)
- Data payload: max 1500 bytes, minimum 46 bytes
- CRC: 4 bytes for error detection

What about source/destination Addresses?

- Frames are at Layer-2
 - Thus, use Layer-2 addresses (MAC names/addresses)
- MAC name/address
 - Numerical address associated with the network adapter
 - Flat namespace of 6 bytes (e.g., 00-15-C5-49-04-A9 in HEX)
 - Unique, hard coded in the adapter when it is built

Hierarchical Allocation

- Blocks: assigned to vendors (e.g., Dell) by IEEE
 - First 24 bits (e.g., 00-15-C5-**-**)
- Adapter: assigned by the vendor from its block
 - Last 24 bits

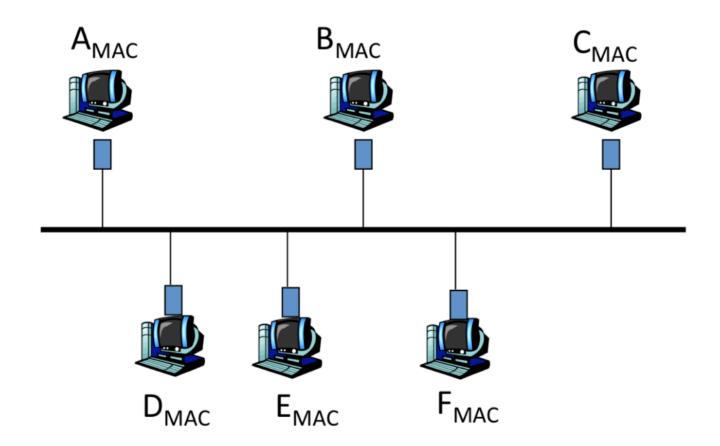
Questions?

Putting it all together (Traditional Ethernet)

Traditional Ethernet

- (Source) Link layer receives data from the network layer (more later)
- (Source) Link layer divides data into frames
 - How does it know source/destination MAC names?
 - Source name is easy ... destination name is tricky (more later)
- (Source) Link layer passes the frame to physical layer
 - Frames up the frames (using sentinel bits)
 - And broadcasts on the broadcast Ethernet
- (EACH) physical layer regenerates the frame...
 - And sends it up to the (destination) link layer
 - Which sends the data to the network layer If and only if:
 - destination name matches the receiver's MAC name
 - Or, the destination name is the broadcast address (FF:FF:FF:FF:FF)

Traditional Ethernet



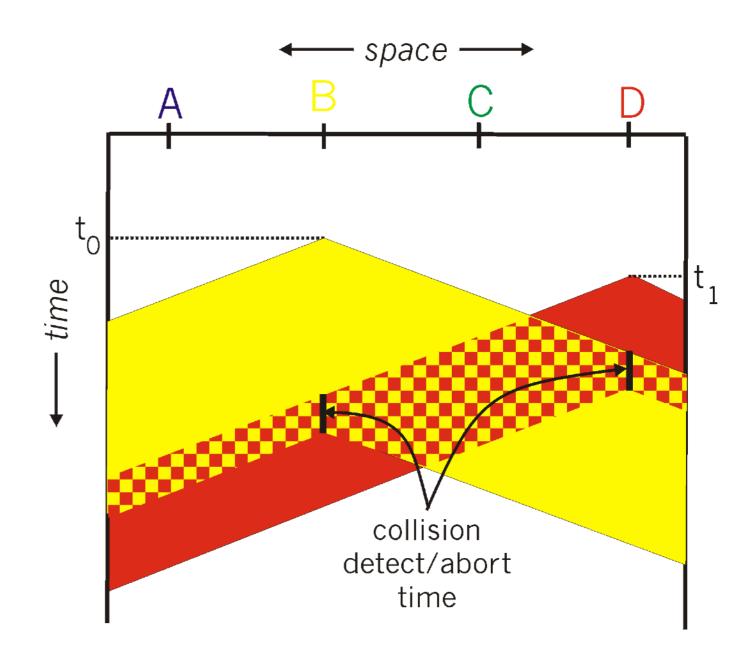
- Ethernet is "plug-n'play"
 - A new host plugs into the Ethernet is good to go
 - No configuration by users or network operators
 - Broadcast as a means of bootstrapping communication

Questions?

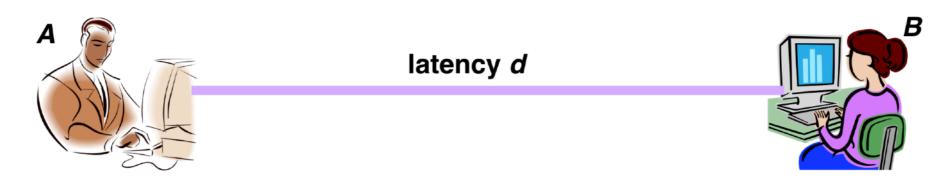
WHY Switched Ethernet?

Collision Detection limits Ethernet scalability

- B and D can tell that collision occurred
- However, need restrictions on
 - Minimum frame size
 - Maximum distance

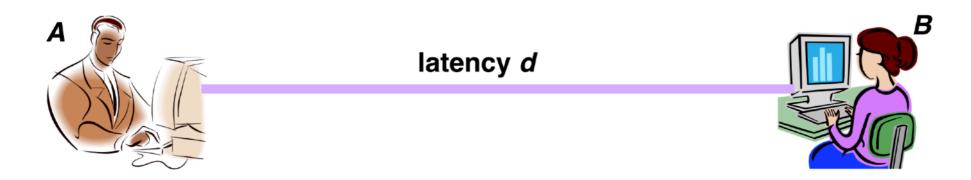


Limits on Traditional Ethernet Scalability



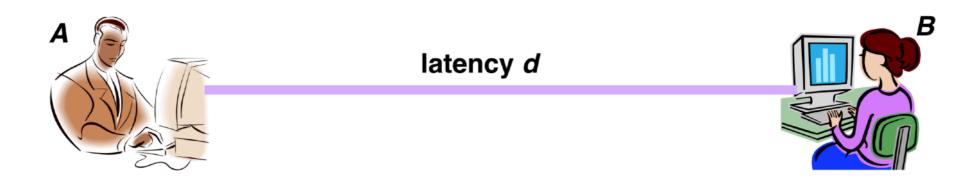
- Latency depends on physical length of link
 - Propagation delay
- Suppose A sends a packet at time 0
 - B sees an idle line at all times before d
 - ... so B happily starts transmitting a packet
- B detects a collision at time d
 - But A can't see collision until 2d
 - A must have a frame size such that transmission time > 2d
 - Need transmission time > 2 * propagation delay

Limits on Traditional Ethernet Scalability



- Transmission time > 2 * propagation delay
- Requires either very large frames (underutilization) or small scale.
 - Example: consider 100 Mbps Ethernet
 - Suppose minimum frame length: 512 bits (64 bytes)
 - Transmission time = $5.12 \mu sec$
 - Thus, propagation delay < 2.56 μsec
 - Length < 2.56 μsec * speed of light
 - Length < 768m
- Cannot scale beyond ~76.8m for 1Gbps and beyond ~7.68m for 10Gbps

Limits on Traditional Ethernet Scalability



- Transmission time > 2 * propagation delay
- Cannot scale beyond ~76.8m for 1Gbps and beyond ~7.68m for 10Gbps
- This is WHY modern Ethernet networks are "switched"

Performance of CSMA/CD

- Time spent transmitting a frame (collision)
 - Proportional to distance d; why?
- Time spent transmitting a frame (no collision)
 - Frame length p divided by bandwidth b
- Rough estimate for efficiency (K some constant)

$$E \sim \frac{\frac{p}{b}}{\frac{p}{b} + Kd}$$

- Observations:
 - For large frames AND small distances, E ~ 1
 - Right frame length depends on b, K, d
 - As bandwidth increases, E decreases
 - That is why high-speed LANs are switched

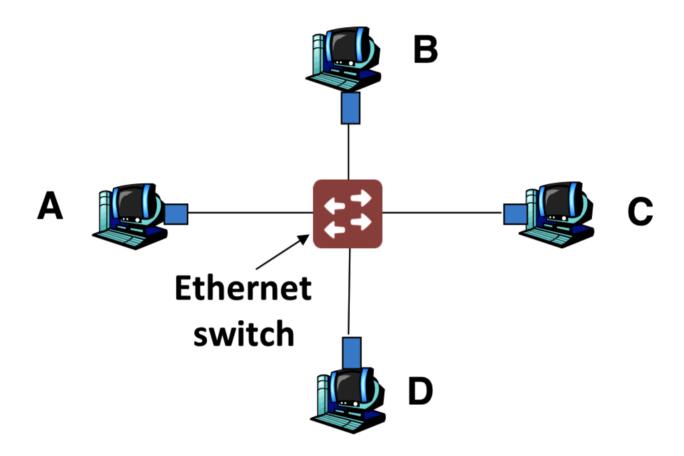
Evolution

- Ethernet was invented as a broadcast technology
 - Hosts share channel
 - Each packet received by all attached hosts
 - CSMA/CD for access control
- Current Ethernets are "switched"
 - Point-to-point medium between switches;
 - Point-to-point medium between each host and switch
 - Sharing only when needed (using CSMA/CD)

Questions?

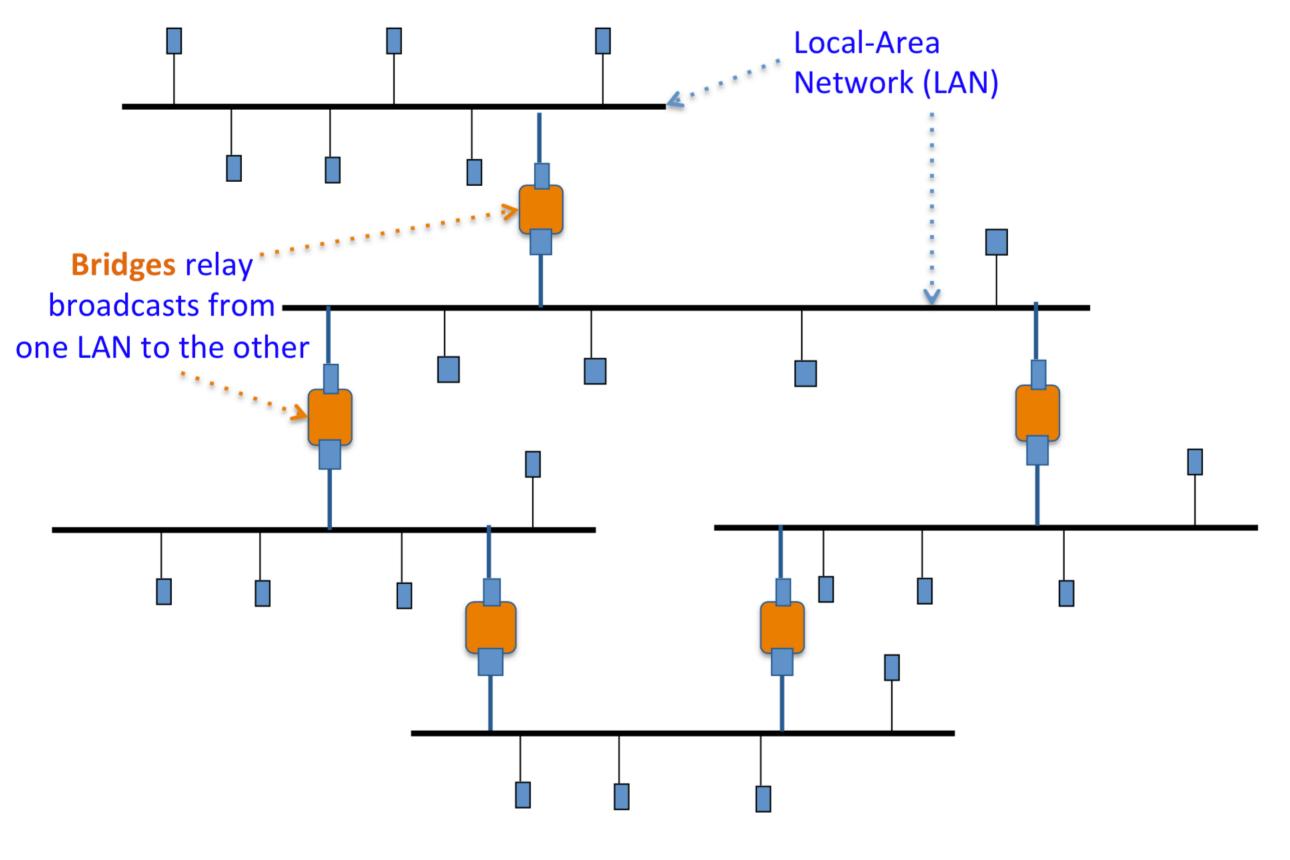
Switched Ethernet

Switched Ethernet

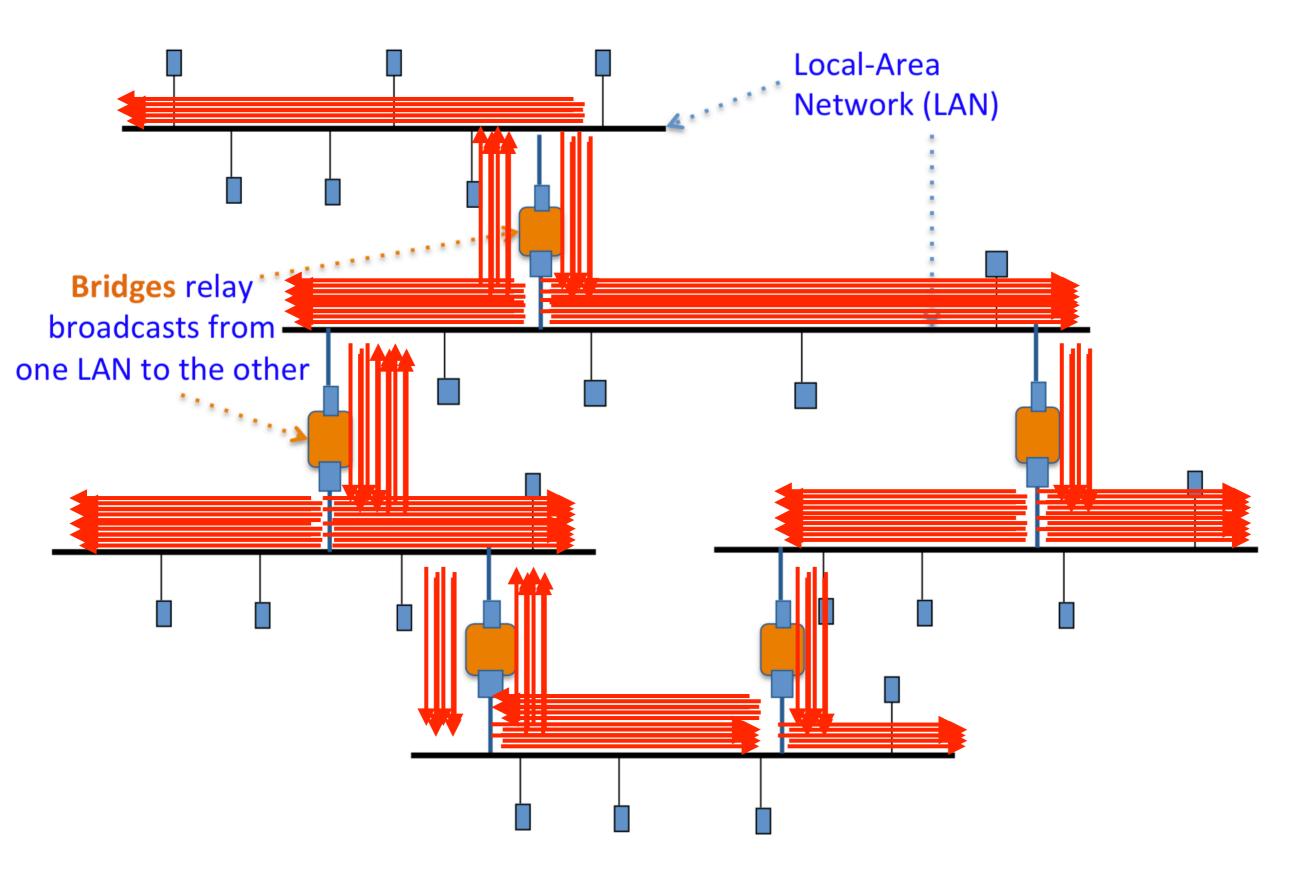


- Enables concurrent communication
 - Host A can talk to C, while B talks to D
 - No collisions -> no need for CSMA, CD
 - No constraints on link lengths or frame size

Routing in Switched Ethernet (Extended LANs)



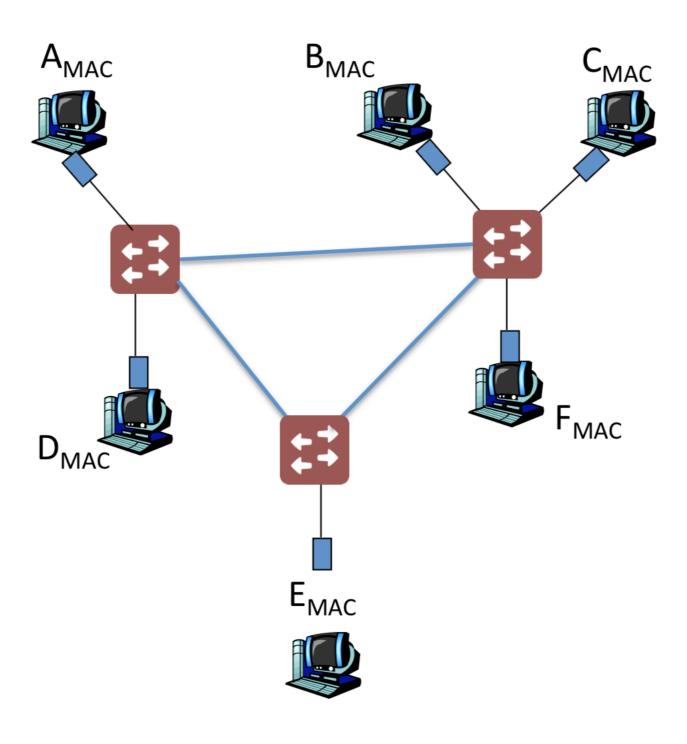
Naïvely Routing in "Extended LANs": Broadcast storm



How to avoid the Broadcast Storm Problem?

Get rid of the loops!

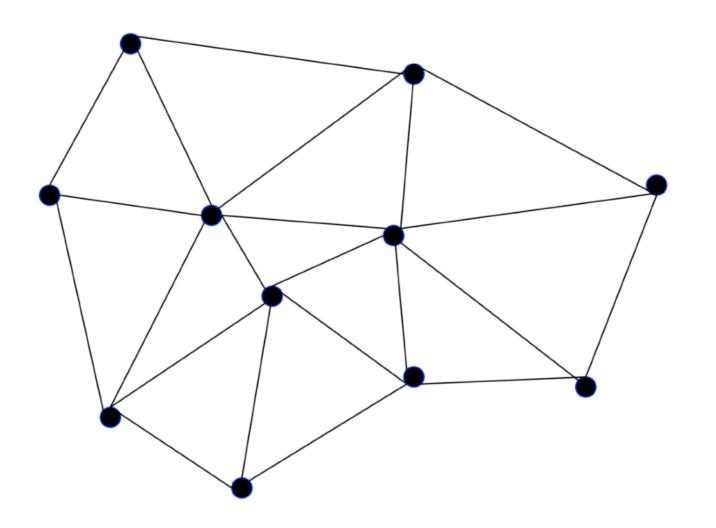
Lets get back to the graph representation!



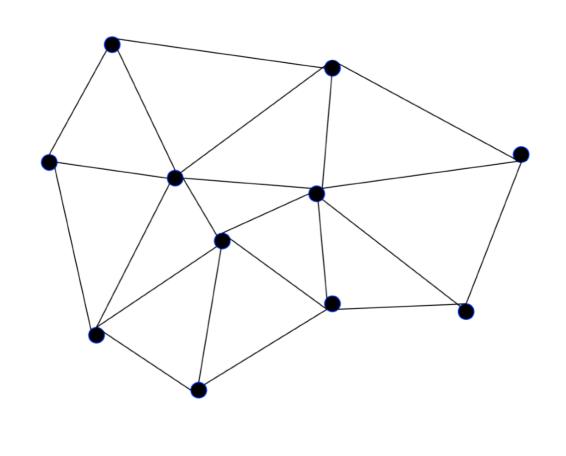
Easiest Way to Avoid Loops

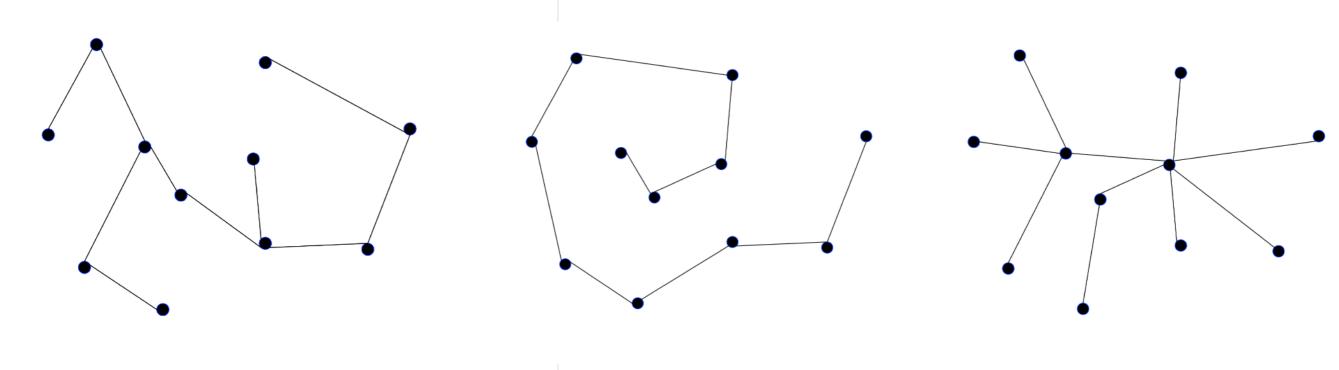
- Use a network topology (graph) where loop is impossible!
- Take arbitrary topology (graph)
- Build spanning tree
 - Subgraph that includes all vertices but contains no cycles
 - Links not in the spanning tree are not used in forwarding frames
- Only one path to destinations on spanning trees
 - So don't have to worry about loops!

Consider Graph



Multiple Spanning Trees





Questions?

Spanning Tree Approach

- Take arbitrary topology
- Pick subset of links that form a spanning tree
- Only forward packets on the spanning tree
 - => No loops
 - => No broadcast storm

Spanning Tree Protocol

- Protocol by which bridges construct a spanning tree
- Nice properties
 - Zero configuration (by operators or users)
 - Self healing
- Still used today
- Constraints for backwards compatibility
 - No changes to end-hosts
 - Maintain plug-n-play aspect
- Earlier Ethernet achieved plug-n-play by leveraging a broadcast medium
 - Can we achieve plug-n-play for a switched topology?

Algorithm has Two Aspects...

- Pick a root:
 - Destination to which the shortest paths go
 - Pick the one with the smallest identifier (MAC name/address)
- Compute the shortest paths to the root
 - No shortest path can have a cycle
 - Only keep the links on the shortest path
 - Break ties in some way
 - so we only keep one shortest path from each node
- Ethernet's spanning tree construction does both with a single algorithm

Breaking Ties

- When there are multiple shortest paths to the root,
 - Choose the path via neighbor switch with the "smallest" identifier
- One could use any tie breaking system
 - This is just an easy one to remember and implement

Constructing a Spanning Tree

- Messages (Y,d,X)
 - Proposing Y as the root
 - From node X
 - And advertising a distance d between X and Y
- Switches elect the node with smallest identifier (MAC address) as root
 - Y in messages
- Each switch determines if a link is on its shortest path to the root
 - If not, excludes it from the tree
 - d to Y in the message is used to determine this

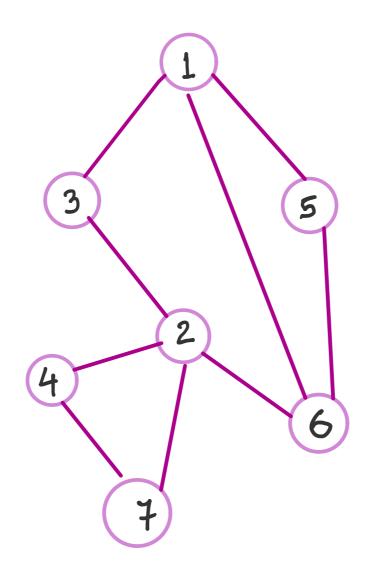
Steps in Spanning Tree Protocol

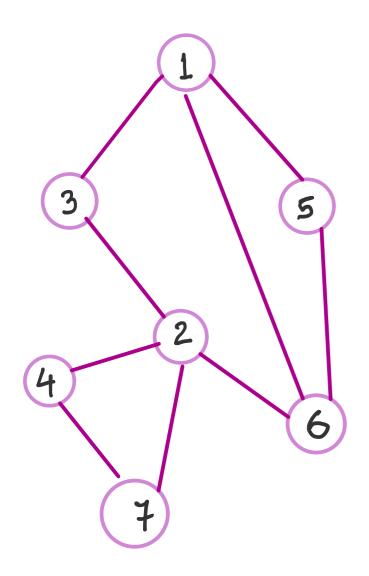
- Messages (Y,d,X)
 - Proposing root Y; from node X; advertising a distance d to Y
- Initially each switch proposes itself as the root
 - that is, switch X announces (X,0,X) to its neighbors
- Switches update their view
 - Upon receiving message (Y,d,Y) from Z, check Y's id
 - If Y's id < current root: set root = Y
 - Set next-hop = Z
- Switches compute their distance from the root
 - Add 1 to the shortest distance received from a neighbor
- If root changed OR shortest distance to the root changed:
 - send neighbors updated message (Y,d+1,X)

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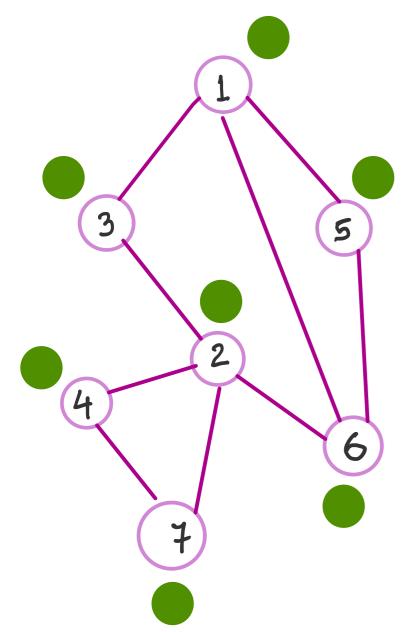
Group Exercise:

Lets run the Spanning Tree Protocol on this example (assume all links have "distance" 1)

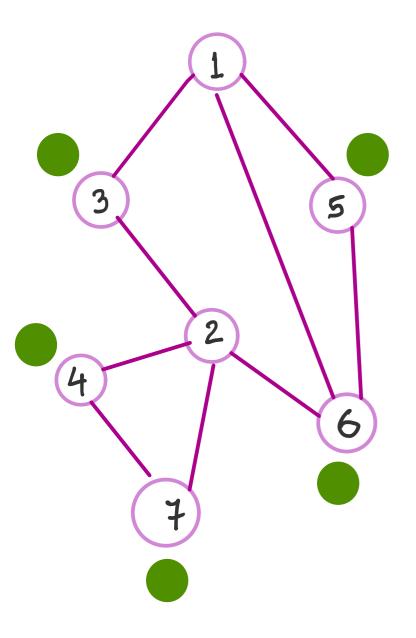




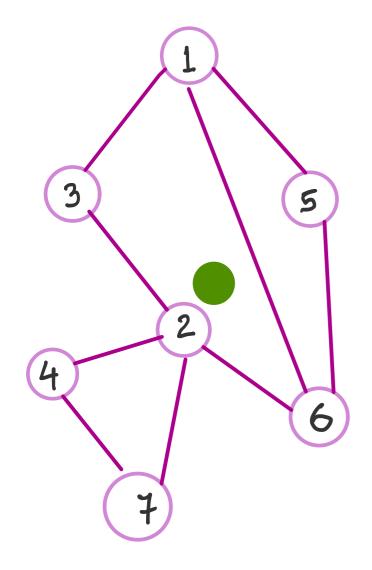
	Receive	Send	Next-hop
1		(1, 0, 1)	1
2		(2, 0, 2)	2
3		(3, 0, 3)	3
4		(4, 0, 4)	4
5		(5, 0, 5)	5
6		(6, 0, 6)	6
7		(7, 0, 7)	7



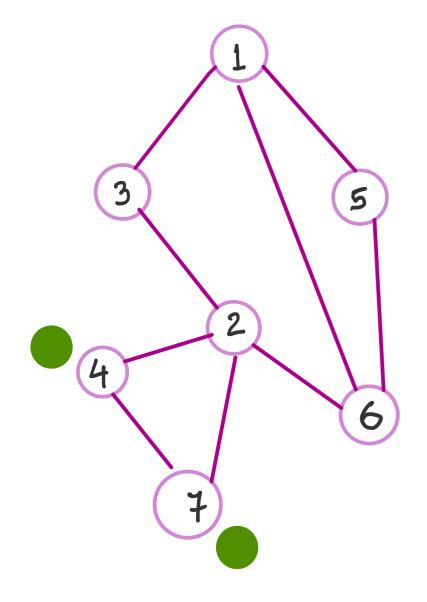
	Receive	Send	Next hop
1 (1, 0, 1)	(3, 0, 3), (5, 0, 5), (6, 0, 6)		1
2 (2, 0, 2)	(3, 0, 3), (4, 0, 4), (6, 0, 6), (7, 0, 7)		2
3 (3, 0, 3)	(1, 0, 1), (2, 0, 2)	(1, 1, 3)	1
4 (4, 0, 4)	(2, 0, 2), (7, 0, 7)	(2, 1, 4)	2
5 (5, 0, 5)	(1, 0, 1), (6, 0, 6)	(1, 1, 5)	1
6 (6, 0, 6)	(1, 0, 1), (2, 0, 2), (5, 0, 5)	(1, 1, 6)	1
7 (7, 0, 7)	(2, 0, 2), (4, 0, 4)	(2, 1, 7)	2



	Receive	Send	Next hop
1 (1, 0, 1)	(1, 1, 3), (1, 1, 5), (1, 1, 6)		1
2 (2, 0, 2)	(1, 1, 3), (2, 1, 4), (1, 1, 6), (2, 1, 7)	(1, 2, 2)	3 (or 6)
3 (1, 1, 3)			1
4 (2, 1, 4)	(2, 1, 7)		2
5 (1, 1, 5)	(1, 1, 6)		1
6 (1, 1, 6)	(1, 1, 5)		1
7 (2, 1, 7)	(2,1, 4)		2



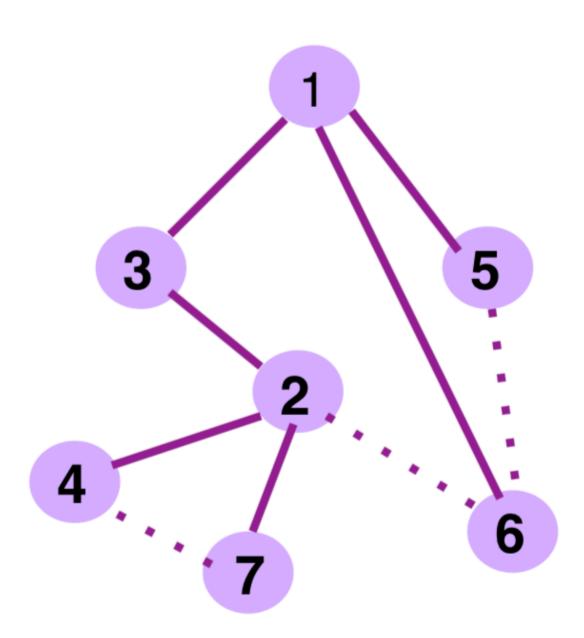
	Receive	Send	Next hop
1 (1, 0, 1)			1
2 (1, 2, 2)			3
3 (1, 1, 3)	(1, 2, 2)		1
4 (2, 1, 4)	(1, 2, 2)	(1, 3, 4)	2
5 (1, 1, 5)			1
6 (1, 1, 6)	(1, 2, 2)		1
7 (2, 1, 7)	(1, 2, 2)	(1, 3, 7)	2



	Receive	Send	Next hop
1 (1, 0, 1)			1
2 (1, 2, 2)	(1, 3, 4), (1, 3, 7)		3
3 (1, 1, 3)			1
4 (1, 3, 4)	(1, 3, 7)		2
5 (1, 1, 5)			1
6 (1, 1, 6)			1
7 (1, 3, 7)	(1, 3, 4)		2

After Round 5: We have our Spanning Tree

- 3-1
- 5-1
- 6-1
- 2-3
- 4-2
- 7-2



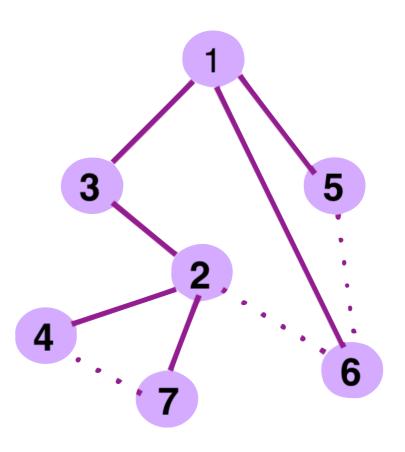
Questions?

Spanning Tree Protocol ++ (incorporating failures)

- Protocol must react to failures
 - Failure of the root node
 - Failure of switches and links
- Root node sends periodic announcement messages
 - Few possible implementations, but this is simple to understand
 - Other switches continue forwarding messages
- Detecting failures through timeout (soft state)
 - If no word from root, time out and send a (Y, O, Y) message to all neighbors (in the graph)!
- If multiple messages with a new root received, send message (Y, d, X) to the neighbor sending the message

Suppose link 2-4 fails

- 4 will send (4, 0, 4) to all its neighbors
 - 4 will stop receiving announcement messages from the root
 - Why?
- At some point, 7 will respond with (1, 3, 7)
- 4 will now update to (1, 4, 4) and send update message
- New spanning tree!



Questions?

The end of Link Layer

And the beginning of network layer :- D

