### Processes (Chapters 3-6)

CS 4410 Operating Systems



[R. Agarwal, L. Alvisi, A. Bracy, M. George Fred B. Schneider, E. Sirer, R. Van Renesse]

#### Before we start

- Registers
  - general-purpose vs device
- Interrupts in user space
  - what happens to the PC?
- kernel stack == interrupt stack
- zoom recordings
- tooth
- Harmony installation

#### Process vs Program

- A program consists of code and data
  - specified in some programming language
- Typically stored in a file on disk
- "Running a program" = creating a process
  - you can run a program multiple times!
    - one after another or even concurrently

#### What is an "Executable"?

#### An executable is a file containing:

- executable code
  - CPU instructions
- data
  - information manipulated by these instructions

- Obtained by compiling a program
  - and linking with libraries

#### What is a "Process"?

- An executable running on an abstraction of a computer:
  - Address Space (memory) +Execution Context (registers incl. PC and SP)
    - manipulated through machine instructions
  - Environment (clock, files, network, ...)
    - manipulated through system calls

#### A good abstraction:

- is portable and hides implementation details
- has an intuitive and easy-to-use interface
- can be instantiated many times
- is efficient to implement

#### Process ≠ Program

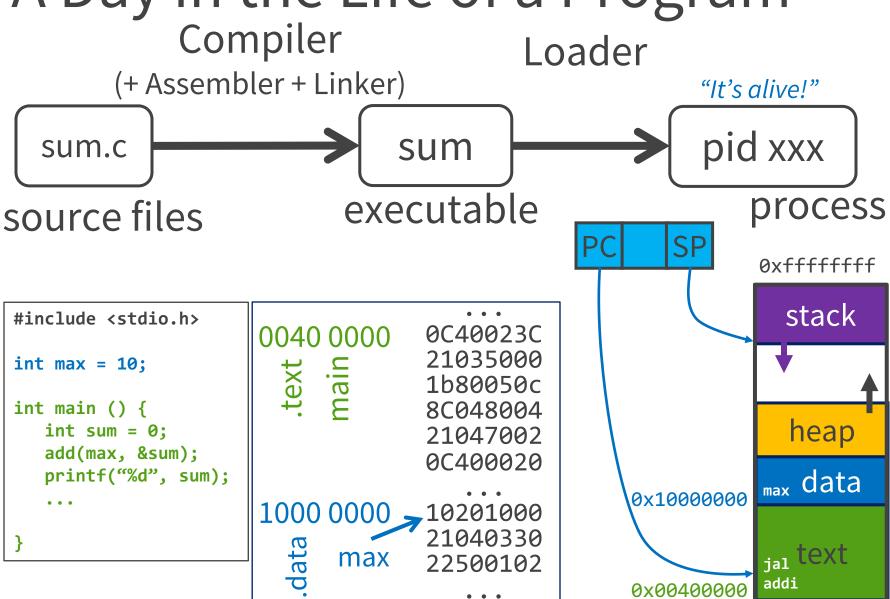
A program is passive: code + data

```
A process is alive:
mutable data + registers + files + ...
```

Same program can be run multiple time simultaneously (1 program, 2 processes)

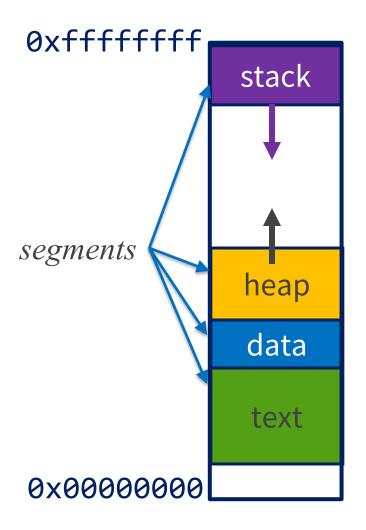
- > ./program &
- > ./program &

# A Day in the Life of a Program



0x00000000

### Logical view of process memory



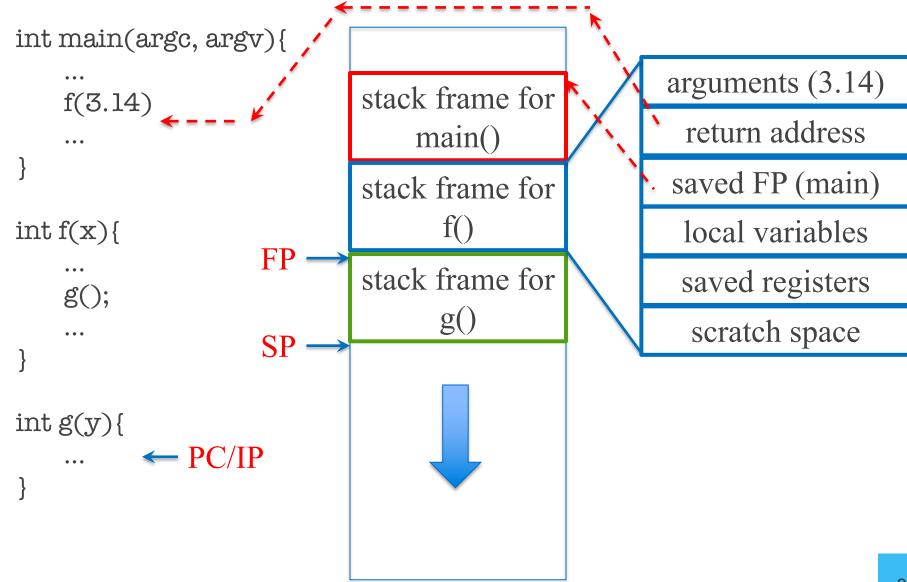
call stack

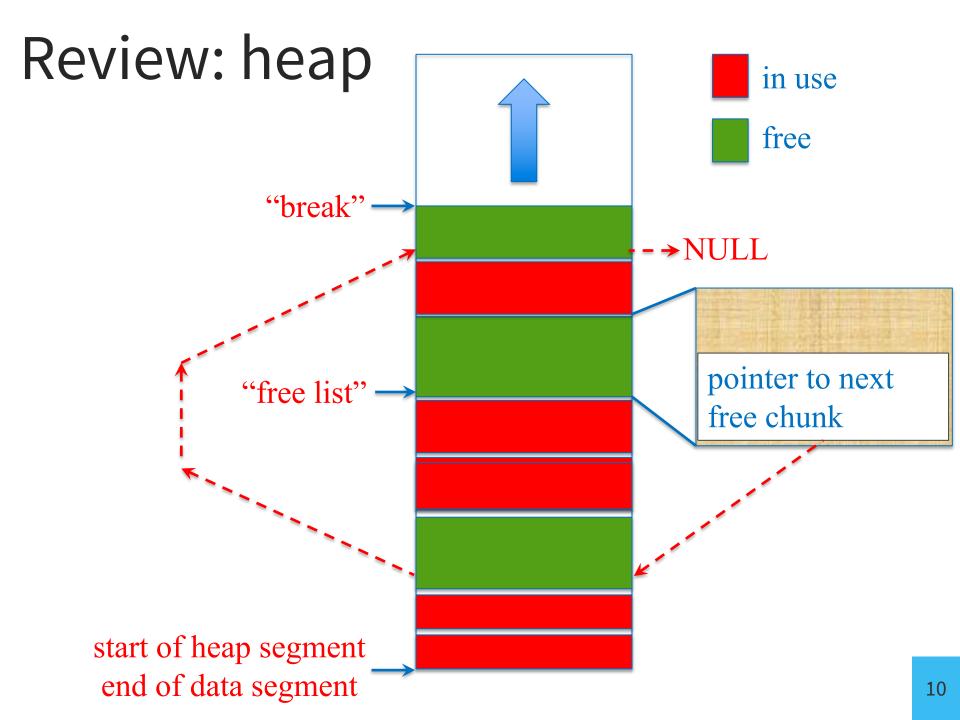
heap used for memory allocation (malloc)

data segment contains global variables read-only text segment contains code and constants

How many bits in an address for this CPU? Why is address 0 not mapped?

### Review: stack (aka call stack)





#### Environment

- CPU, registers, memory allow you to implement algorithms
- But how do you
  - ☐ read input / write to screen
  - create/read/write/delete files
  - create new processes
  - ☐ send/receive network packets
  - ☐ get the time / set alarms
  - ☐ terminate the current process



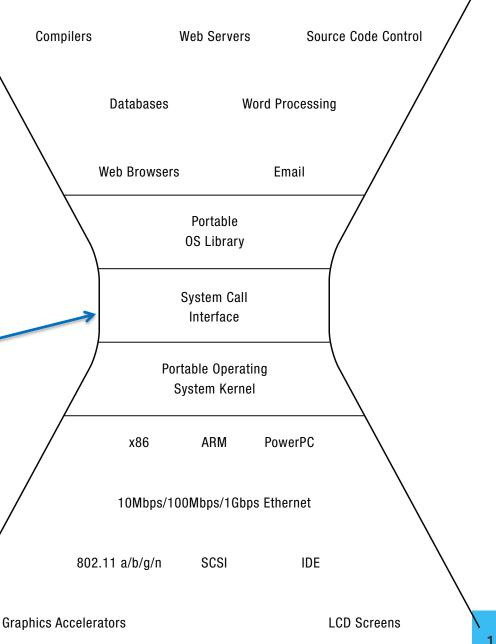
# System Calls

A process runs on CPU

 Can access O.S. kernel through "system calls"

Skinny interface

- Why?



### Why a "skinny" interface?

#### Portability

- easier to implement and maintain
- e.g., many implementations of "Posix" interface

#### Security

 - "small attack surface": easier to protect against vulnerabilities

not just the O.S. interface. Internet "IP" layer is another good example of a skinny interface

### Executing a system call

#### **Process:**

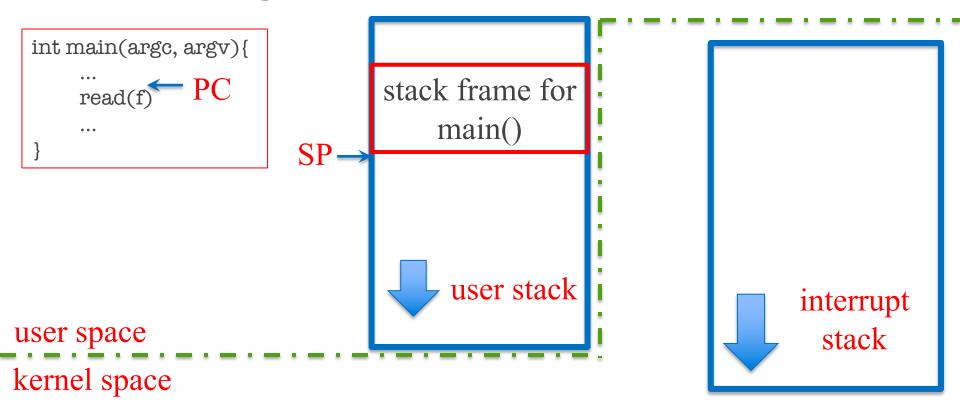
- 1. Calls system call function in library
- Places arguments in registers and/or pushes them onto user stack
- 3. Places syscall type in a dedicated register
- 4. Executes syscall machine instruction

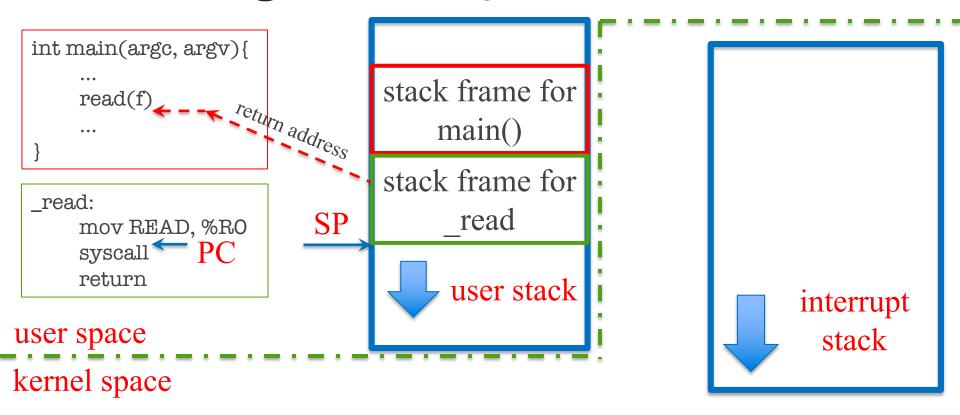
#### **Kernel**:

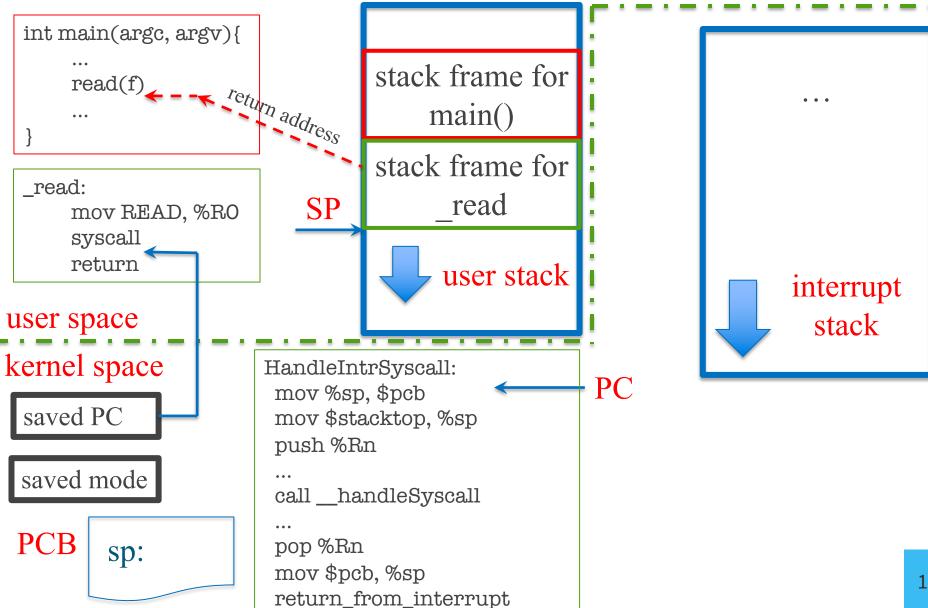
- 5. Executes syscall interrupt handler
- 6. Places result in dedicated register
- 7. Executes return\_from\_interrupt

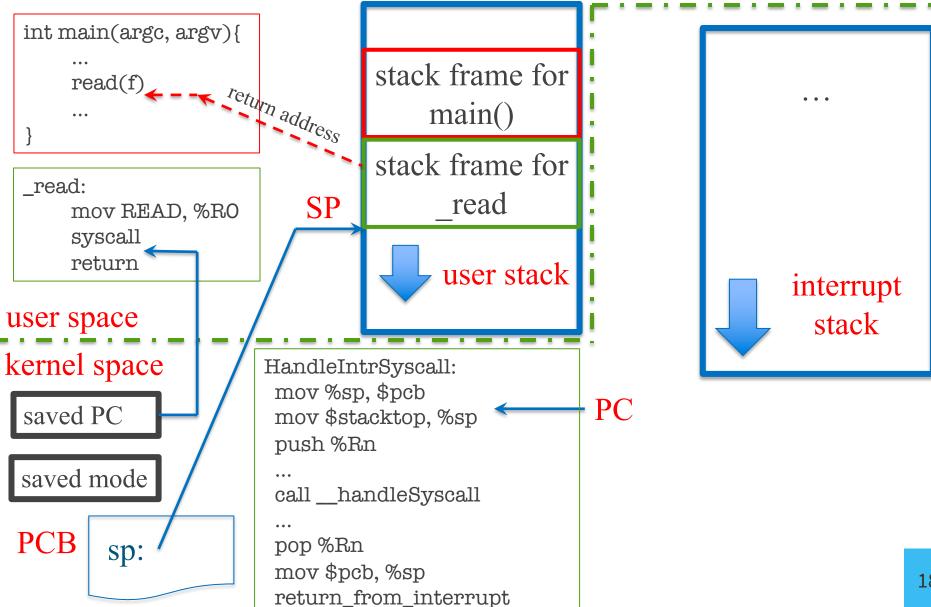
#### **Process:**

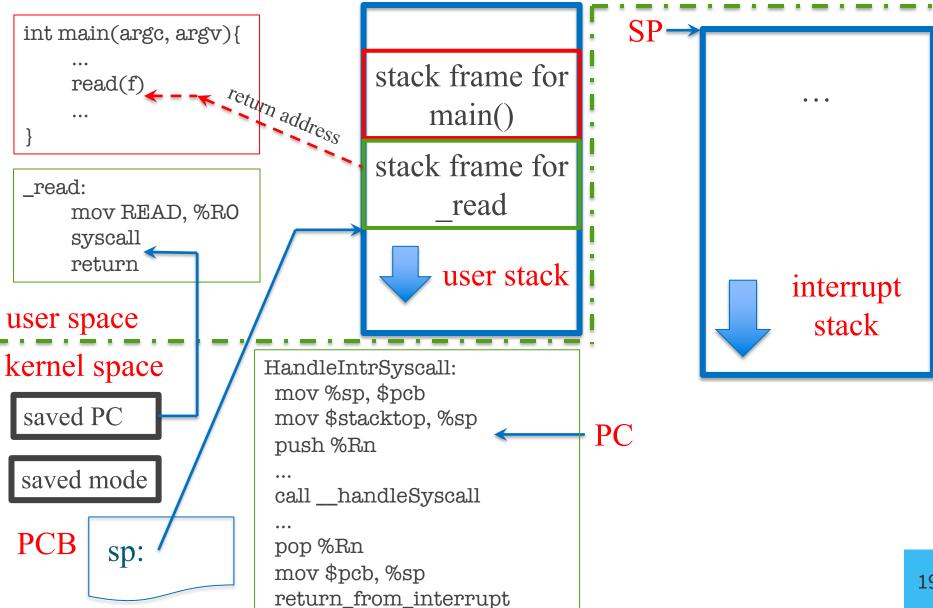
8. Executes return\_from\_function

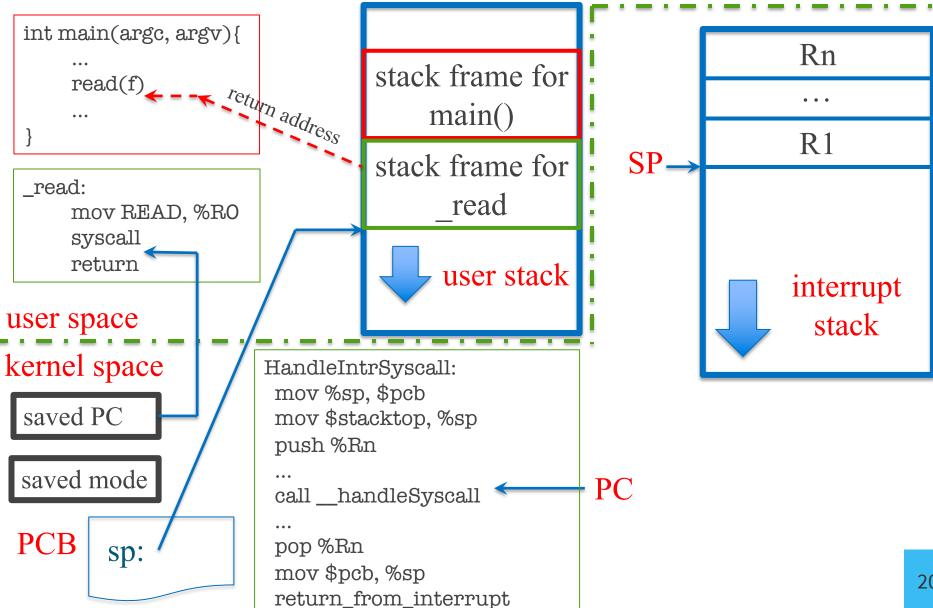


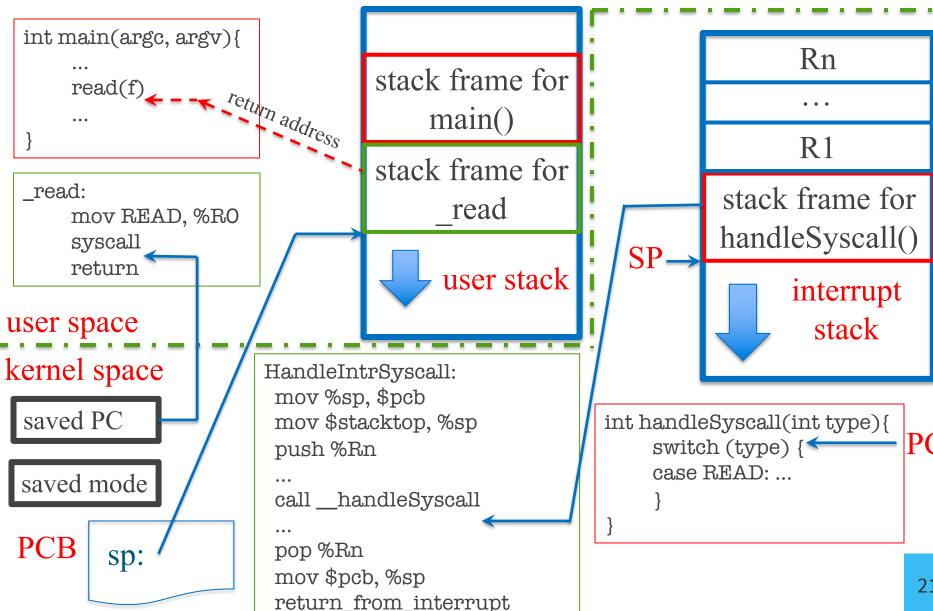


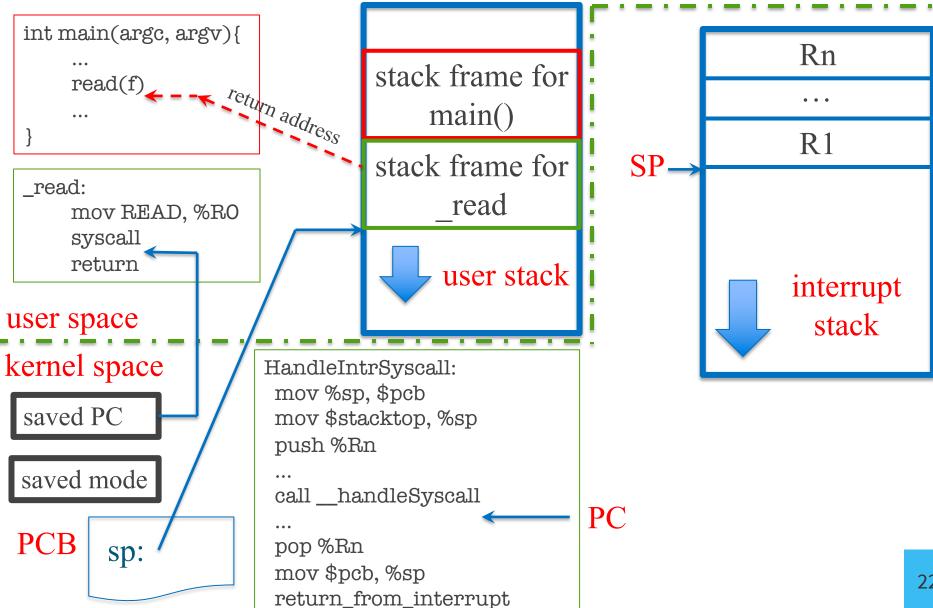


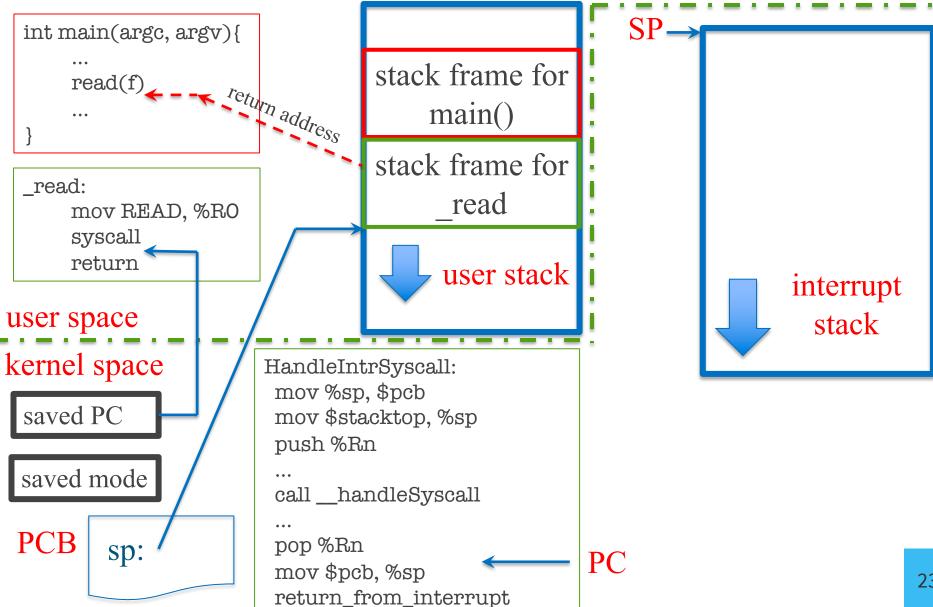


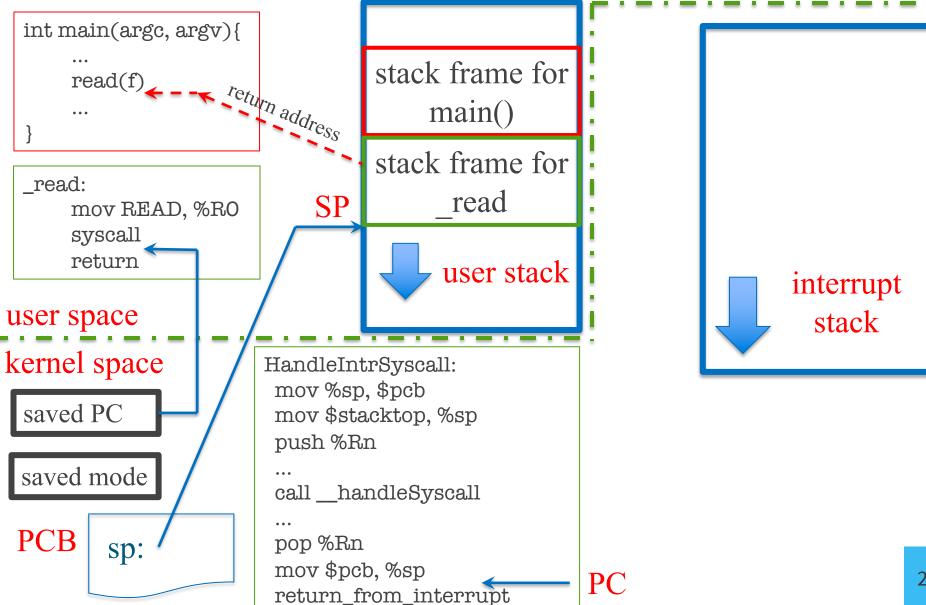


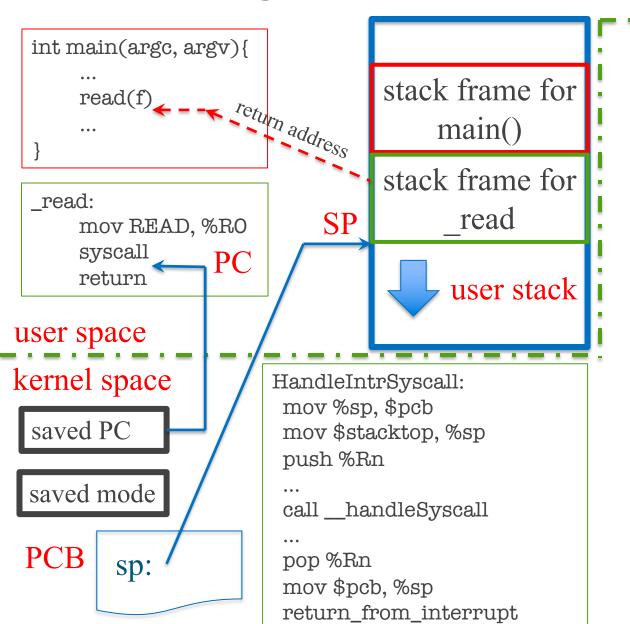


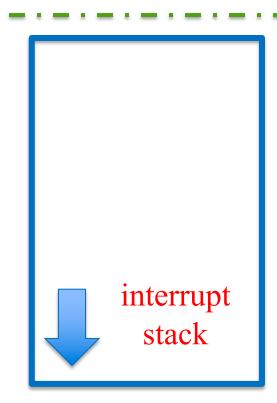


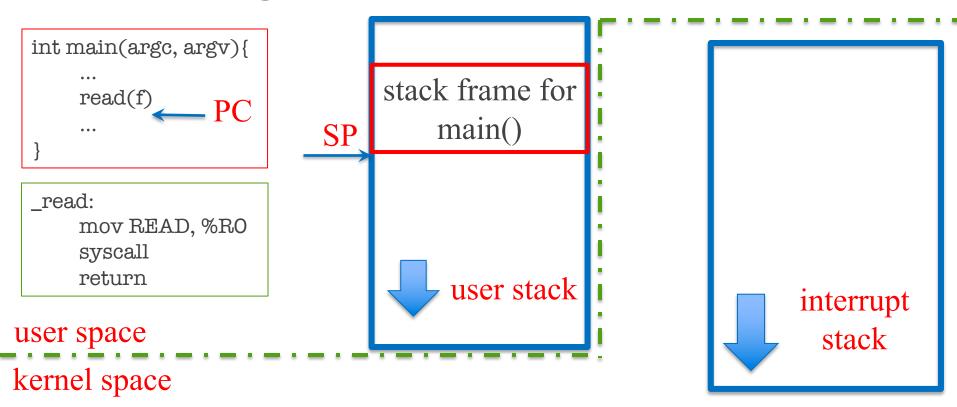












#### What if read needs to "block"?

- read may need to block if
  - > reading from terminal
  - reading from disk and block not in cache
  - > reading from remote file server

should run another process!

### How to run multiple processes?

(on a single core)

#### A process physically runs on the CPU

#### But somehow each process has its own:

- Registers
- Memory
- ◆ I/O resources
- "thread of control"
- even though there are usually more processes than the CPU has cores
  - need to multiplex, schedule, ... to create virtual CPUs for each process

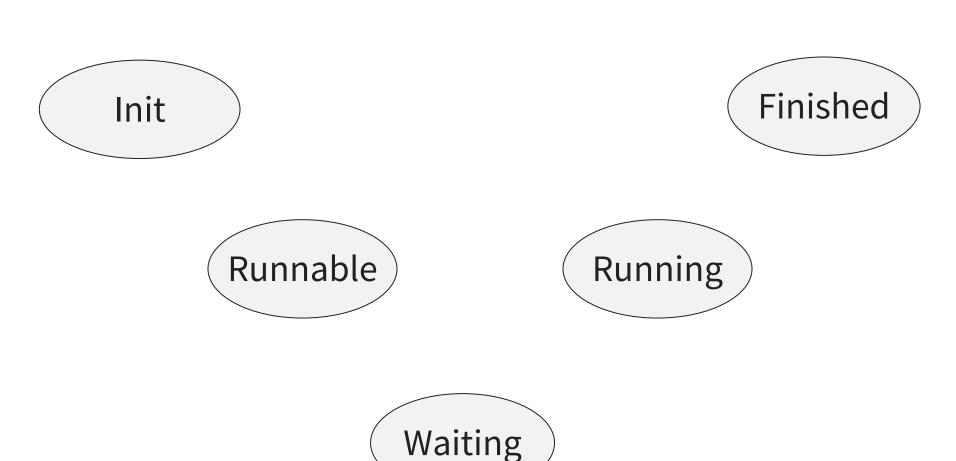
For now, assume we have a single core CPU

#### Process Control Block (PCB)

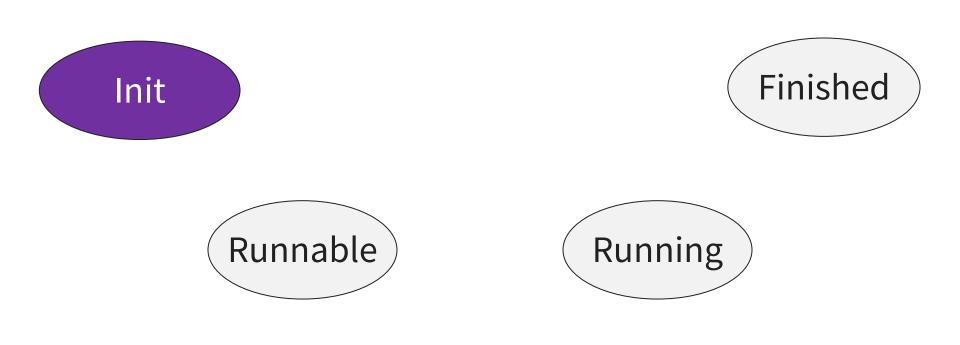
#### For each process, the OS has a PCB containing:

- location in memory (page table)
- location of executable on disk
- which user is executing this process (uid)
- process identifier (pid)
- process status (running, waiting, finished, etc.)
- scheduling information
- interrupt stack
- saved user SP
  - points into user stack
- saved kernel SP
  - points into interrupt stack
  - interrupt stack contains saved registers and kernel call stack for this process
- ... and more!

## Process Life Cycle



#### Process creation

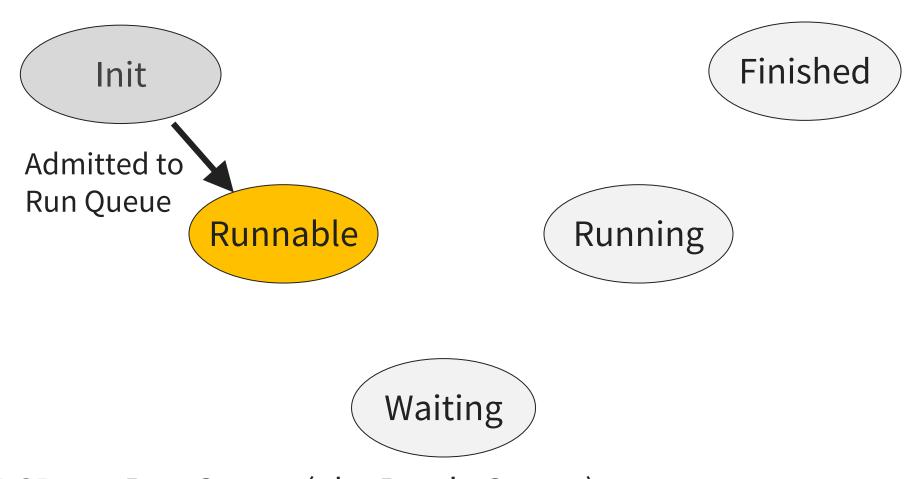


Waiting

PCB status: being created

Registers: uninitialized

### Process is Ready to Run

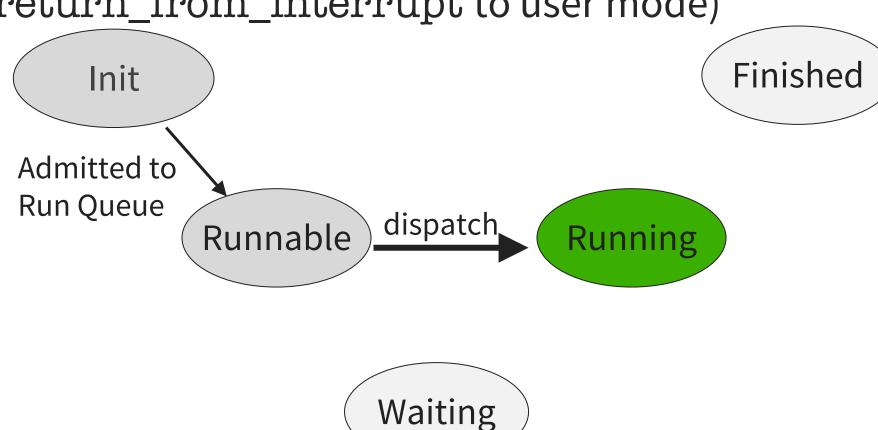


PCB: on Run Queue (aka Ready Queue)

**Registers:** pushed by kernel code onto interrupt stack

### Process is Running

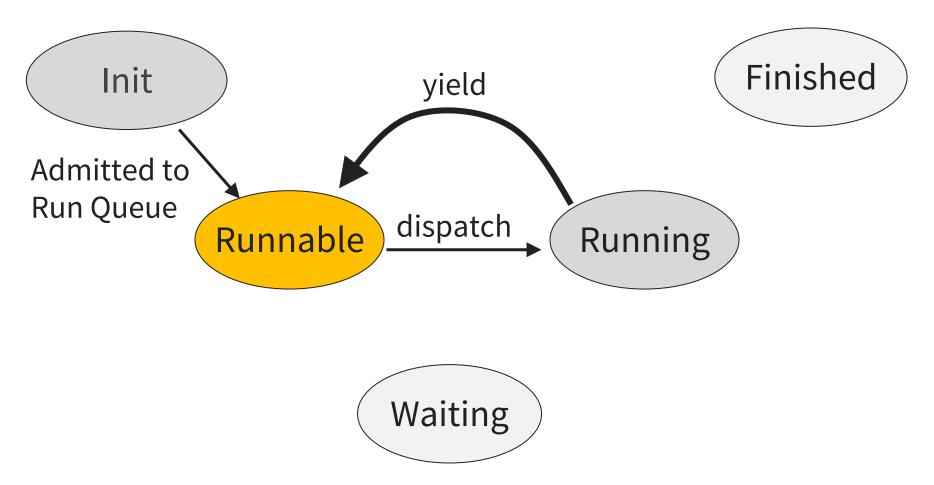
(in supervisor mode, but may return\_from\_interrupt to user mode)



**PCB:** currently executing

Registers: popped from interrupt stack into CPU

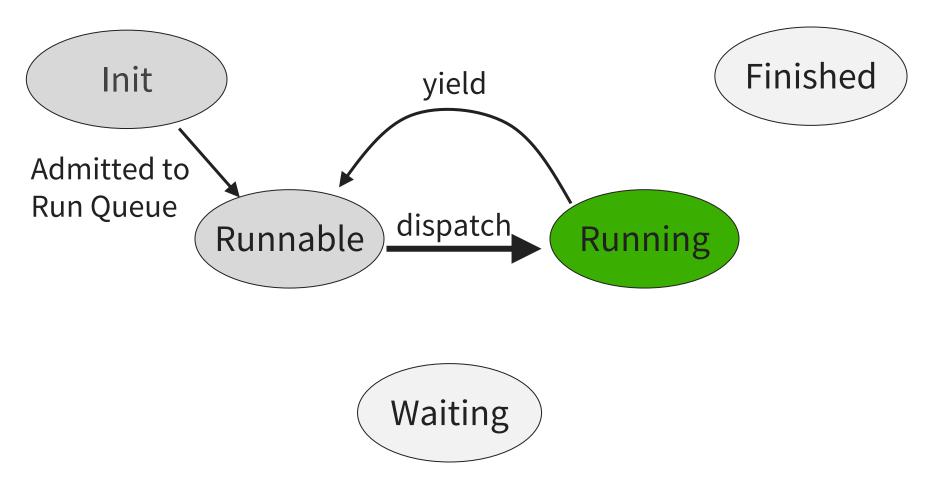
### Process Yields (on clock interrupt)



PCB: on Run queue

**Registers:** pushed onto interrupt stack (sp saved in PCB)

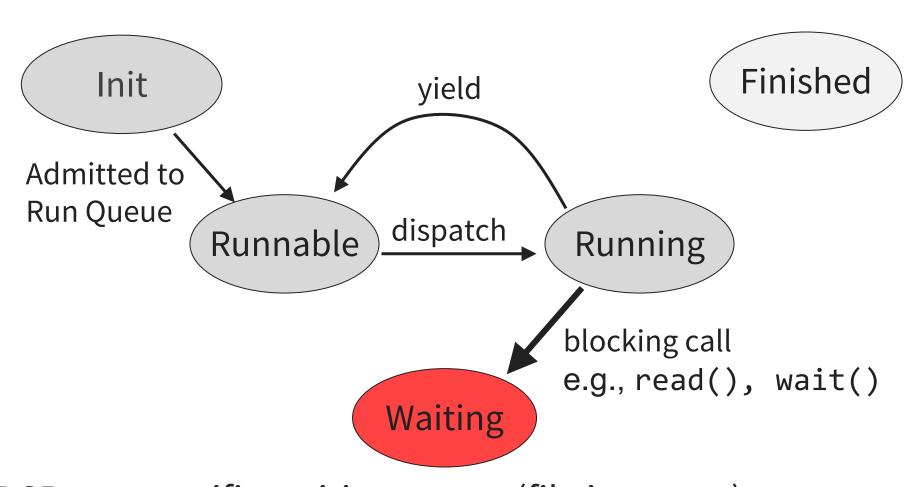
### Process is Running Again!



**PCB:** currently executing

**Registers:** sp restored from PCB; others restored from stack

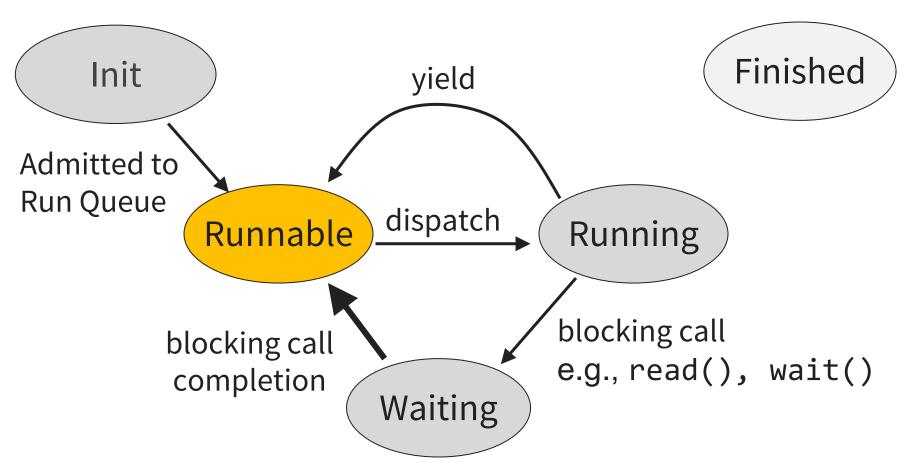
# Process is Waiting



**PCB:** on specific waiting queue (file input, ...)

Registers: on interrupt stack

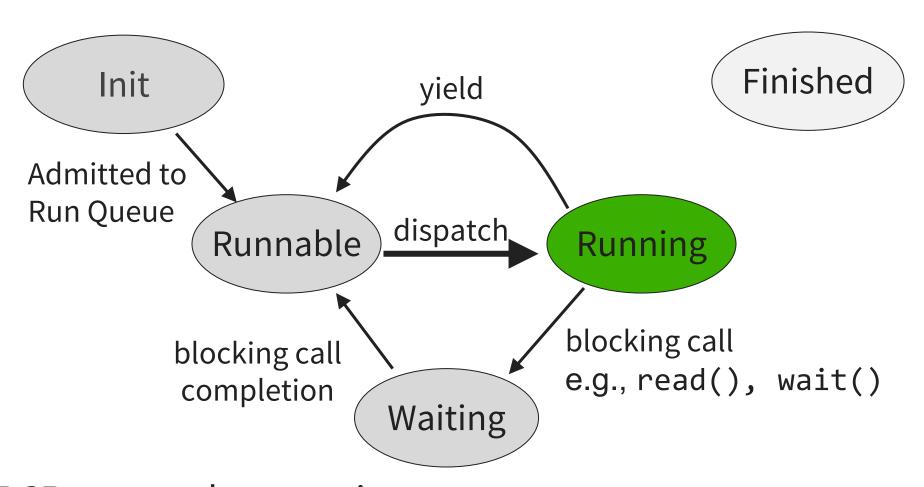
# Process is Ready Again!



PCB: on run queue

Registers: on interrupt stack

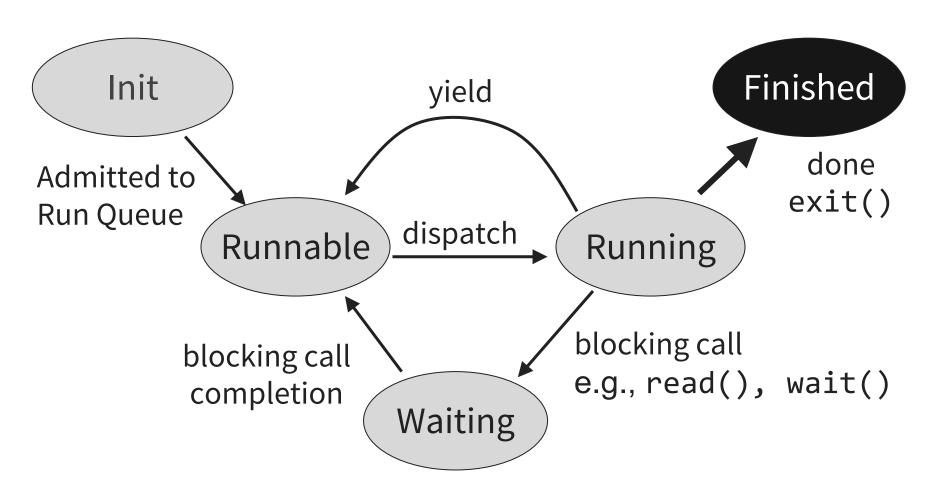
# Process is Running Again!



**PCB:** currently executing

Registers: restored from interrupt stack into CPU

### Process is Finished (Process = Zombie)



**PCB:** on Finished queue, ultimately deleted **Registers:** no longer needed

# Invariants to keep in mind

- At most 1 process is RUNNING at any time (per core)
- When CPU is in user mode, current process is RUNNING and its interrupt stack is empty
- If process is RUNNING
  - its PCB is not on any queue
  - however, not necessarily in user mode
- If process is RUNNABLE or WAITING
  - its interrupt stack is non-empty and can be switched to
    - i.e., has its registers saved on top of the stack
  - its PCB is either
    - on the run queue (if RUNNABLE)
    - on some wait queue (if WAITING)
- If process is FINISHED
  - its PCB is on finished queue

# Cleaning up zombies

- Process cannot clean up itself WHY NOT?
- Process can be cleaned up
  - either by any other process
    - check for zombies just before returning to RUNNING state
  - or by parent when it waits for it
    - but what if the parent dies first?
  - or by dedicated "reaper" process
- Linux uses combination:
  - usually parent cleans up child process when waiting
  - if parent dies before child, child process is inherited by the initial process, which is continually waiting



# How To Yield/Wait?

# Switching from executing the current process to another runnable process

- Process 1 goes from RUNNING → RUNNABLE/WAITING
- Process 2 goes from RUNNABLE → RUNNING
- 1. save kernel registers of process 1 on its interrupt stack
- 2. save kernel sp of process 1 in its PCB
- 3. restore kernel sp of process 2 from its PCB
- 4. restore kernel registers from its interrupt stack

# ctx\_switch(&old\_sp, new\_sp)

```
ctx switch:
    addi sp,sp,-64 // reserve frame
    sw s0,4(sp)
    sw s1,8(sp)
    sw s2, 12(sp)
    sw s3,16(sp)
    sw s4,20(sp)
    sw s5, 24(sp)
    sw s6,28(sp)
    sw s7,32(sp)
    sw s8,36(sp)
    sw s9,40(sp)
    sw s10,44(sp)
    sw s11,48(sp)
    sw ra,52(sp) // save return addr
    sw sp.0(a0) // save old sp
    mv sp, a1
                  // set new sp
    lw s0, 4(sp)
    lw s1,8(sp)
    lw s2, 12(sp)
    lw s3,16(sp)
    lw s4,20(sp)
    lw s5, 24(sp)
    lw s6, 28(sp)
    lw s7,32(sp)
    lw s8,36(sp)
    lw s9.40(sp)
    lw s10,44(sp)
    lw s11,48(sp)
    lw ra,52(sp) // return addr
    addi sp,sp,64 // free frame
    ret
                   // return
```

(author: Yunhao Zhang)

```
USAGE:
struct pcb *current, *next;
void yield(){
    assert(current->state == RUNNING);
    current->state = RUNNABLE;
    runQueue.add(current);
    next = scheduler();
    next->state = RUNNING;
    ctx_switch(&current->sp, next->sp)
    current = next;
```

#### What if there are no more RUNNABLE processes?

- scheduler() would return NULL and things blow up
- solution: always run a low priority process that sits in an infinite loop executing the RISC-V WFI (Wait For Interrupt) or x86 HLT instruction or ... (fill in your favorite CPU)
  - which waits for the next interrupt, saving energy when there's nothing to do

## Three "kinds" of context switches

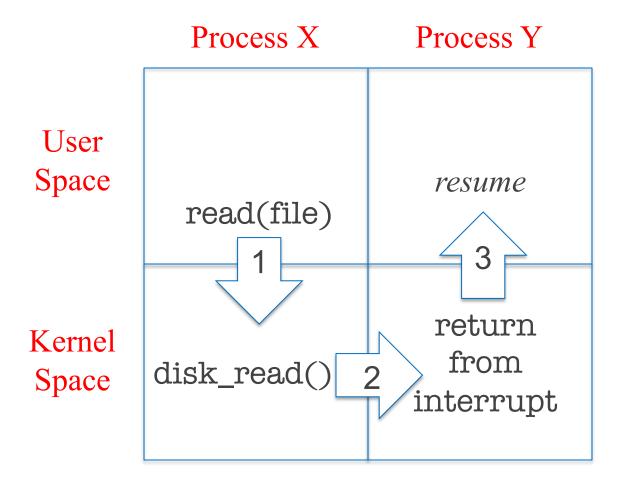
- 1. Interrupt: From user to kernel space
  - system call, exception, or interrupt
- 2. Yield: In kernel space, between two processes
  - happens inside the kernel, switching from one PCB/interrupt stack to another
- 3. Return-From-Interrupt: From kernel space to user space
  - Through a return\_from\_interrupt instruction

#### Note that each involves a stack switch:

- 1. Px user stack → Px interrupt stack
- 2. Px interrupt stack → Py interrupt stack
- 3. Py interrupt stack → Py user stack

A *context* is "the CPU state," which is captured in its registers. By context switching, the CPU can play different roles at different times

## Example switch between processes



- 1. save process X user registers
- 2. save process X kernel registers and restore process Y kernel registers
- 3. restore process Y user registers

before step 2: scheduler picks a runnable process

## A word on "abstraction"

- We manage complexity through abstraction
- When I say "tea water," I mean the water that is used for tea
  - but it's just water
  - that same water will serve different purposes in its existence
- When I say "kernel memory," I mean the memory that is used for the kernel
  - but it's just memory
  - it's the same kind of memory that is used for processes
- Actors in a play: same actors can play multiple roles in their lives, sometimes even in the same play
  - actors are time multiplexed, same as registers of a CPU
  - the kernel SP is just the SP that is used by the kernel
  - when you're watching "Woman King," you're supposed to imagine seeing Nanisca, not Viola Davis

# A "process" is an abstraction

- Abstract computer with abstract memory, registers, and peripherals
- Some "hardware" computer can be multiplexed to run multiple processes
  - time multiplexed: registers
  - space multiplexed: disk

### Review

- A process is an abstraction of a computer
- A context captures the state of the processor:
  - registers (including PC and SP)
- The implementation uses two contexts:
  - user context
  - kernel (supervisor) context
- A *Process Control Block (PCB)* is a kernel data structure that saves contexts and has other information about the process

# System calls to create a new process

```
Windows:
    CreateProcess(...);

UNIX (Linux):
    fork() + exec(...)
```

# CreateProcess (Simplified)

#### **System Call:**

```
if (!CreateProcess(
   NULL, // No module name (use command line)
   argv[1],// Command line
   NULL, // Process handle not inheritable
   NULL, // Thread handle not inheritable
   FALSE, // Set handle inheritance to FALSE
   0, // No creation flags
   NULL, // Use parent's environment block
   NULL, // Use parent's starting directory
   &si, // Pointer to STARTUPINFO structure
   &pi ) // Ptr to PROCESS INFORMATION structure
```

# CreateProcess (Simplified) fork (actual form)

```
int pid = fork( void ©
  NULL, // No module name (use command line)
  argv[1],// Command line
  NULL, // Process handle not inheritable
  NULL, // Thread handle not inheritable
  -FALSE, // Set handle inheritance to FALSE
  0, // No creation flags
  NULL, // Use parent's environment block
  NULL, // Use parent's starting directory
  &si, // Pointer to STARTUPINFO structure
  &pi )
                    pid = process identifier
```

## Kernel actions to create a process

#### fork():

- Allocate ProcessID
- Create & initialize PCB
- Create and initialize a new address space
- Inform scheduler that new process is ready to run

#### exec(program, arguments):

- Load the program into the address space
- Copy arguments into memory in address space
- Initialize h/w context to start execution at "start"

Windows createProcess(...) does both

# Creating and Managing Processes

fork()	Create a child process as a clone of the current process. Returns to both parent and child. Returns child pid to parent process, 0 to child process.
exec (prog, args)	Run the application <b>prog</b> in the current process with the specified arguments ( <i>replacing any code and data that was in the process already</i> )
wait (&status)	Pause until a child process has exited
<b>exit</b> (status)	Tell the kernel the current process is complete and should be garbage collected.
<pre>kill (pid, type)</pre>	Send an interrupt of a specified type to a process. (a bit of a misnomer, no?)



```
Process 1
Program A

PC — child_pid = fork();
if (child_pid==0)
    exec(B);
else
    wait(&status);

child_pid ?
```



fork returns twice!

```
Process 1
     Program A
     child_pid = fork();
PC if (child_pid==0)
       exec(B);
     else
       wait(&status);
     child_pid 42
     Process 42
     Program A
     child_pid = fork();
PC → if (child_pid==0)
       exec(B);
     else
       wait(&status);
     child_pid 0
```

[UNIX]

```
Process 1
     Program A
     child_pid = fork();
     if (child_pid==0)
       exec(B);
     else
    wait(&status);
     child_pid 42
     Process 42
     Program A
     child_pid = fork();
PC → if (child_pid==0)
       exec(B);
     else
       wait(&status);
     child_pid 0
```



Waits until child exits.

```
Process 1
    Program A
    child_pid = fork();
    if (child_pid==0)
      exec(B);
    else
    wait(&status);
    child_pid 42
    Process 42
    Program A
    child_pid = fork();
    if (child_pid==0)
PC \longrightarrow exec(B);
    else
      wait(&status);
    child_pid
```

if and else
both executed!



```
Process 1
Program A
child_pid = fork();
if (child_pid==0)
  exec(B);
else
wait(&status);
child_pid 42
Process 42
Program B
main() {
    exit(3);
```



```
Process 1
Program A

child_pid = fork();
if (child_pid==0)
   exec(B);
else

wait(&status);

child_pid 42

status 3
```



# Code example (fork.c)

```
#include <stdio.h>
#include <unistd.h>
                                     Possible outputs?
int main() {
   int child pid = fork();
  if (child_pid == 0) {     // child process
       printf("I am process %d\n", getpid());
   }
   else {
                             // parent process.
       printf("I am the parent of process %d\n", child_pid);
   return 0;
```

# Threads! (Chapters 25-27)

#### Other terms for threads:

- Lightweight Process
- Thread of Control
- Task

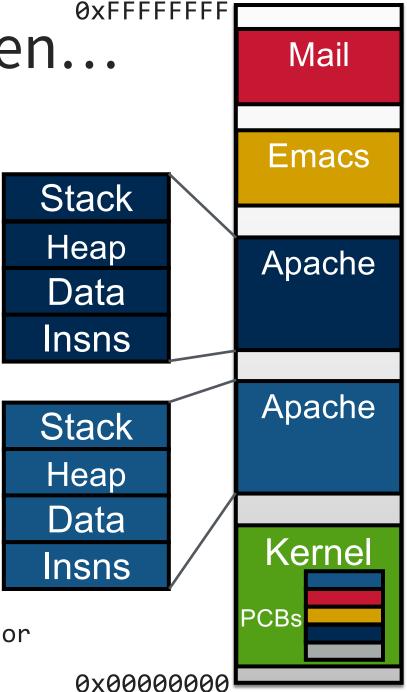
# What happens when...

Apache wants to run multiple concurrent computations?

Two heavyweight address spaces for two concurrent computations

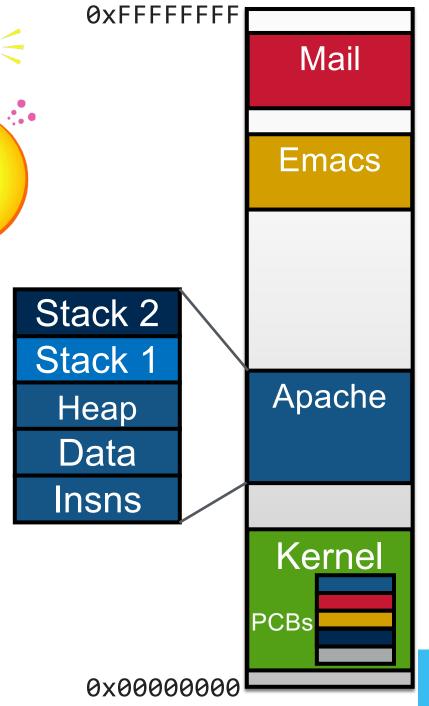
Hard to share cache, etc.

Physical address space Each process' address space by color (shown contiguous to look nicer)



## Idea

Place concurrent computations in the same address space!



### Process vs. Thread Abstraction

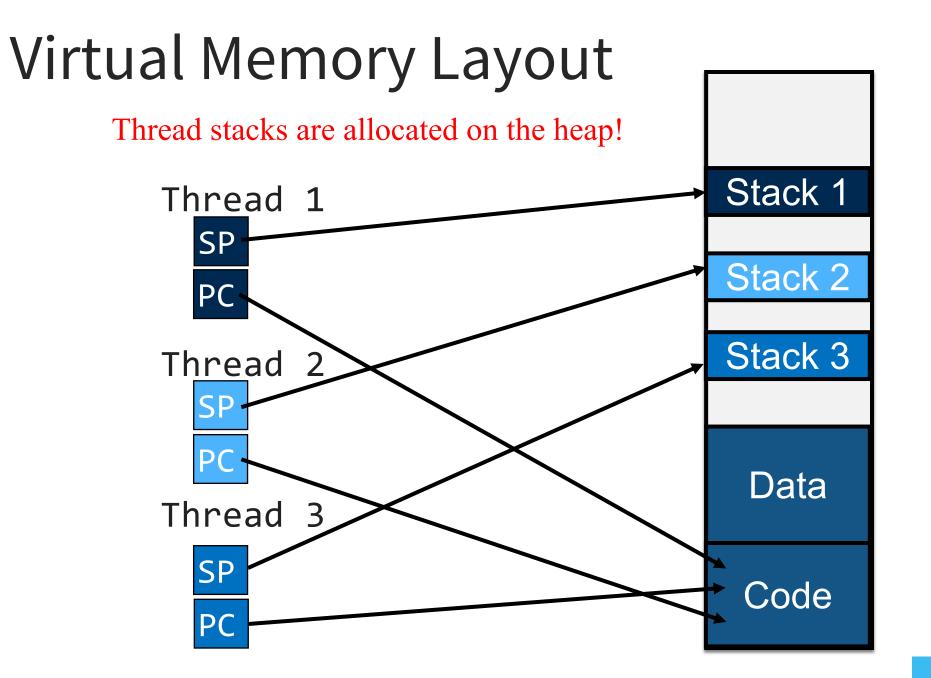
- A process is an abstraction of a computer
  - ➤ CPU, memory, devices
- A thread is an abstraction of a core
  - ➤ registers (incl. PC and SP)

#### Unbounded #computers, each with unbounded #cores

- Different processes typically have their own (virtual) memory, but different threads share virtual memory.
- Different processes tend to be mutually distrusting, but threads must be mutually trusting. Why?

# Nomenclature Warning

• In "concurrency literature", threads are often called "processes" or "processors"



# Why Threads?

#### Concurrency

exploiting multiple CPUs/cores

#### Mask long latency of I/O

doing useful work while waiting

#### Responsiveness

high priority GUI threads / low priority work threads

#### Encourages natural program structure

- Expressing logically concurrent tasks
- update screen, fetching data, receive user input



# Some Thread Examples

```
for (k = 0; k < n; k++) {
   a[k] = b[k] × c[k] + d[k] × e[k]
}</pre>
```

#### Web server:

- 1. get network message (URL) from client
- 2. get URL data from disk
- 3. compose response
- 4. send response

# Simple Thread API

void thread_create (func,arg)	Creates a new thread that will execute function func with the arguments arg
<pre>void thread_yield()</pre>	Calling thread gives up processor. Scheduler can resume running this thread at any point.
void thread_exit()	Finish caller

# Preemption

- Two kinds of threads:
  - Non-preemptive: explicitly yield to other threads
  - Preemptive: yield automatically upon clock interrupts
- Most modern threading systems are preemptive
  - but not 4411 P1 project

# Implementation of Threads

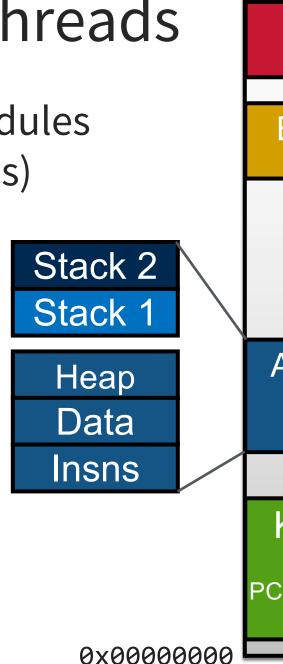
#### One abstraction, two implementations:

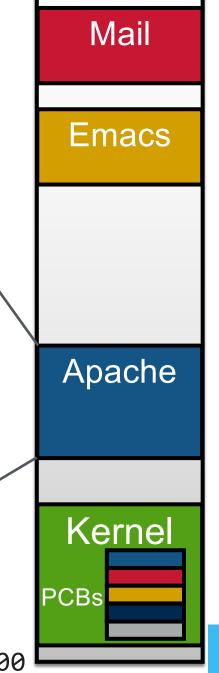
- "kernel threads": each thread has its own PCB in the kernel, but the PCBs point to the same physical memory
- "user threads": one PCB for the process; threads implemented entirely in user space. Each thread has its own Thread Control Block (TCB) and context

# #1: Kernel-Level Threads

Kernel knows about, schedules threads (just like processes)

- Separate PCB for each thread
- PCBs have:
  - **same:** page table base register
  - **different:** PC, SP, registers, interrupt stack





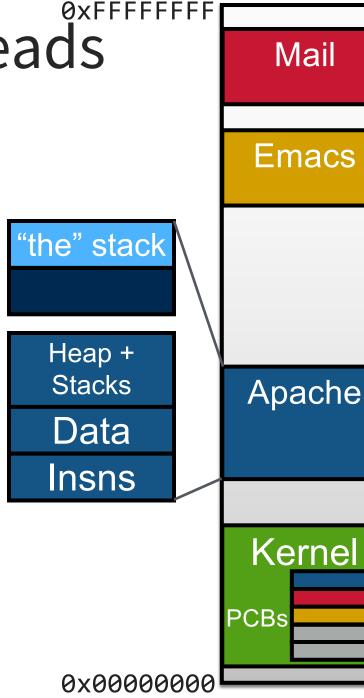
## #2: User-Level Threads

Run mini-OS in user space

- Real OS unaware of threads
- Single PCB
- Thread Control Block (TCB) for each thread

Generally more efficient than kernel-level threads (Why?)

But kernel-level threads simplify system call handling and scheduling (Why?)

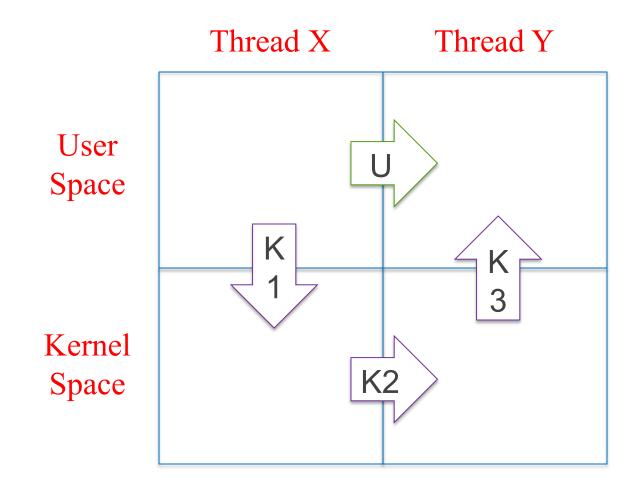


Mail

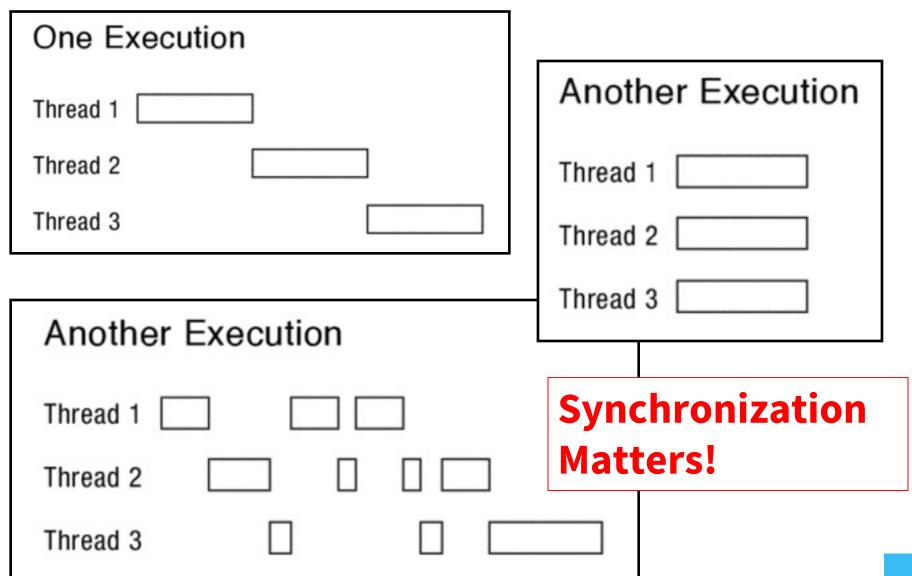
## Kernel- vs User-level Threads

Kernel-Level Threads	User-level Threads
<ul> <li>Easy to implement: just processes with shared page table</li> </ul>	<ul> <li>Requires user-level context switches, scheduler</li> </ul>
<ul> <li>Threads can run blocking system calls concurrently</li> </ul>	<ul> <li>Blocking system call blocks all threads: needs O.S. support for non- blocking system calls</li> </ul>
<ul> <li>Thread switch requires three context switches</li> </ul>	<ul> <li>Thread switch efficiently implemented in user space</li> </ul>

### Kernel vs User Thread Switch



#### Do **not** presume to know the schedule



# Thread- vs Event-Based Programming

## What is "event-based" programming?

- No "blocking" operations
  - No read(), wait(), lock(), etc.
  - (in the extreme case)
- Code is a collection of event handlers
  - Invoked when some event happens
  - Runs to completion
    - Remember, no blocking operations
  - (Similar to I/O interrupt handlers)

# Example: event-based web server

```
handler client_request(client, URI):
 contents := CACHE[URI];
 if contents != None:
   send(client, contents);
 else:
   if PENDING[URI] == { }:
     start_load_file(URI, file_loaded_handler);
   PENDING[URI] U= { client };
handler file_loaded (URI, contents):
 CACHE[URI] := contents;
 for each client in PENDING[URI]:
   send(client, contents);
 PENDING[URI] = { };
```

#### Contrast: thread-based web server

```
thread client_handler():
  for ever:
                                              # blocks
     (client, URI) = receive();
     CACHE.lock();
                                              # may block
     while CACHE[URI] == None:
           NEEDED.lock(); NEEDED U= { URI };
           NEEDED.notify(); NEEDED.unlock();
           CACHE.wait();
                                              # blocks
     send(client, CACHE[URI]);
     CACHE.unlock();
thread file_loader(URI, contents):
  for ever:
                                              # may block
     NEEDED.lock();
     while NEEDED == { }: NEEDED.wait();
                                              # blocks
     uris = NEEDED; NEEDED = { };
     NEEDED.unlock();
     for each URI in uris:
                                              # blocks
           contents = read(URI);
           CACHE.lock(); CACHE[URI] = contents;
           CACHE.notifyAll(); CACHE.unlock();
```

#### Decades old debate...

- Example debate papers
  - 1995: Why Threads are a Bad Idea (for most purposes)
    - J. Ousterhout (UC Berkeley, Sun Labs, now at Stanford)
  - 2003: Why Events are a Bad Idea (for high-concurrency servers)
    - R. van Behren, J. Condit, E. Brewer (UC Berkeley)

- But also known to be logically equivalent:
  - 1978, On the Duality of Operating Systems Structures
    - H.C. Lauer, R.M. Needham

## **Pros and Cons**

<b>Event-Based</b>	Thread-Based
good for I/O-parallelism/GUIs	good for any parallelism
no context switch overhead (contexts are short-lived)	keeps track of control flow
does not need locks	needs locks
code becomes spaghetti	code relatively easy to read
deterministic, easy to debug	hard to debug (Harmony to the rescue :-)

# Shell

#### What is a Shell?

- is an interpreter (i.e., just another program)
- language allows user to create/manage programs
  - sh Original Unix shell (Stephen Bourne, AT&T Bell Labs, 1977)
  - bash "Bourne-Again" Shell

Runs at user-level. Uses syscalls: fork, exec, etc.

#### What is a Shell?

- Reads lines of input
  - command [arg1 ...]
- And executes them
- Full programming language in its own right
- e.g.:

```
$ for x in a b c
```

> do echo \$x

# echo is a print command

> done

#### Shell has state

- Just like other programming languages
- Includes:
  - home directory
  - working directory
  - list of processes that are running
- Commands often modify the state

# Some important commands

```
    echo [args] # print arguments
    ls # list the working directory
    pwd # print working directory
    cd [dir] # change working directory
    default is "home" directory
    ps # list running processes
```

# "flags" (aka options)

- arguments to command that start with '-'
- examples:
  - ls –l # long listing
  - ps –a # print all processes

# "foreground" vs. "background"

#### The shell either

- is reading from standard input
- is waiting for a process to finish
  - this is the *foreground* process
  - other processes are background processes
- To start a background process, add '&'
  - e.g.:
    - (sleep 5; echo hello)&
    - x & y# runs x in background and y in foreground

Background processes should not read from standard input! Why not?

# Pipelines

- x | y
  - runs both x and y in foreground
  - output of x is input to y
  - finishes when both x and y finish
- e.g.:
  - echo robbert | tr b B