

Evaluating Relational Operations: Part I

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Relational Operators



- ❖ Select
- Project
- Join
- Set operations (union, intersect, except)
- $\ \, \textbf{Aggregation} \\$

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Select Operator



SELECT *

FROM Sailor S

WHERE S.Age = 25 AND S.Salary > 100K

Select Operator

- Three cases
- * Case 1: No index on any selection attribute
- Case 2: Have "matching" index on all selection attributes
- Case 3: Have "matching" index on some (but not all) selection attributes

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Case 1: No index on any selection attribute

- $\boldsymbol{\div}$ Assume that select operator is applied over a relation with N tuples stored in P data pages
- What is the cost of select operation in this case (in terms of # I/Os)?

Select Operator

* Three cases

- Case 1: No index on any selection attribute
- Case 2: Have "matching" index on all selection attributes
- Case 3: Have "matching" index on some (but not all) selection attributes

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Case 2: Example

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SELECT *

FROM Sailor S

WHERE S.Age = 25 AND S.Salary > 100K

Have B+-tree index on (Age, Salary)

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Case 2: Cost Components



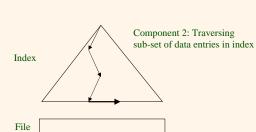


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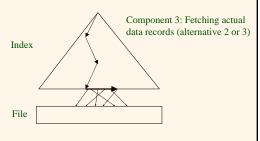
Case 2: Cost Components





Case 2: Cost Components





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Cost of Component 1



- ❖ D is cost of reading/writing one page to disk (using random disk I/O)
- ❖ Hash index
 - Cost = D
- ❖ B+-tree
 - Cost = D * (height of tree)

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Cost of Component 2



- ❖ N data entries (= # data tuples if alternative 2)
- Hash index
 - Linear hashing
 - B hash buckets
 - Average cost = D * (N/B 1)
- ❖ B+ tree index
 - L = average number of entries per leaf page
 - S = Selectivity (fraction of tuples satisfying selection)
 - Average cost = D * ((S * N/L) 1)

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Cost of Component 3

- ❖ S*N data entries satisfy selection condition
 - S is selectivity, N is total number of data entries
- T is number of data tuples per page
- ❖ Hash index
 - Worst-case cost = D * S * N (if unclustered index)

D * S * N / T (if clustered index)

- ❖ B+ tree index
 - Worst-case cost = Same as hash index

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Putting it all together

- Total cost of select operations using unclustered B+ tree index
 - D * (Height + (S * N/L 1) + S * N)
- Should we always use index in this case?
 - •Depends on selectivity of selection condition!
 - D^* (Height + (S * N/L 1) + S * N) < D * P
 - ${}^{\bullet}S < (P Height + 1) * L / N(L + 1)$
 - •Simple optimization!
- * What about a clustered index?

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Component 3: Optimization

- Alternative 2 or 3, unclustered index
- Find qualifying data entries from index
- * Sort the rids of the data entries to be retrieved
 - Remember rid = (page ID, slot #)
- ❖ Fetch rids in order
 - Ensures each data page is read from disk just once!
 - Although number of data pages retrieved still likely to be more than with clustering

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Select Operator

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Case 3: Example



SELECT *

FROM Sailor S

WHERE S.Age = 25 AND S.Salary > 100K

* Have Hash index on Age

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Evaluation Alternatives



- ❖ Alternative 1
 - Use available index (on Age) to get superset of relevant data entries
 - Retrieve the tuples corresponding to the set of data entries
 - Apply remaining predicates on retrieved tuples
 - Return those tuples that satisfy all predicates
- ❖ Alternative 2
 - Sequential scan! (always available)
 - May be better depending on selectivity

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Case 3: Example



SELECT *

FROM Sailor S

WHERE S.Age = 25 AND S.Salary > 100K

- Have Hash index on Age
- * Have B+ tree index on Salary

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Evaluation Alternatives



- ❖ Alternative 1
 - Choose most selective access path (index)
 - Could be index on Age or Salary, depending on selectivity of the corresponding predicates
 - Use this index to get superset of relevant data entries
 - Retrieve the tuples corresponding to the set of data entries
 - Apply remaining predicates on retrieved tuples
 - Return those tuples that satisfy all predicates

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Evaluation Alternatives



- Alternative 2
 - Get rids of data records using each index
 - Use index on Age and index on Salary
 - Intersect the rids
 - We'll discuss intersection soon
 - Retrieve the tuples corresponding to the rids
 - Apply remaining predicates on retrieved tuples
 - Return those tuples that satisfy all predicates
- ❖ Alternative 3
 - Sequential scan!

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Relational Operators

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Example



SELECT DISTINCT S.Name, S. Age FROM Sailor S

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Evaluation Alternatives



- ❖ Alternative 1
 - Using Indices
- ❖ Alternative 2
 - Based on sorting
- ❖ Alternative 3
 - Based on hashing

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Example

SELECT DISTINCT S.Name, S. Age FROM Sailor S

❖ Have B+ tree index on (Name, Age)

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Evaluation Using "Covering" Index



- * Simply scan leaf levels of index structure
 - No need to retrieve actual data records
 - Index-only scan
- * Works so long as the index search key includes all the projection attributes
 - Extra attributes in search key are okay
 - Best if projection attributes are prefix of search key
 Can eliminate duplicates in single pass of index-only scan
- * Other examples
 - Hash index on (SSN, Name, Age)
 - B+ tree index on (Age, # Dependents, Name)

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Example



SELECT DISTINCT S.Name, S. Age FROM Sailor S

- * Have Hash index on Name
- * Have B+ tree index on Age
- Sailor relation has 100 other attributes!

Evaluation Using RID Joins

- Retrieve (SearchKey1, RID) pairs from first index
- Retrieve (SearchKey2, RID) pairs from second index
- Join these based on RID to get (SearchKey1, SearchKey2, RID) triples
 - We will discuss joins soon!
- Project out the third column to get the desired result

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Evaluation Alternatives



- ❖ Alternative 1
 - Using Indices
- ❖ Alternative 2
 - Based on sorting
- ❖ Alternative 3
 - Based on hashing

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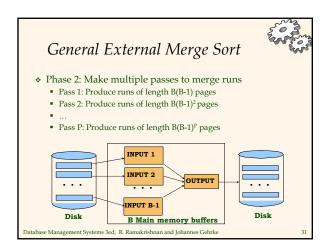
Example

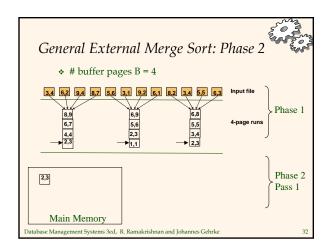


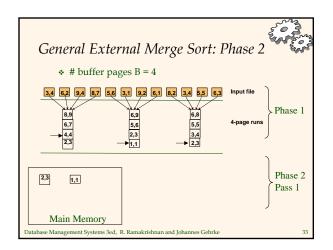
SELECT **DISTINCT** S.Name, S. Age FROM Sailor S

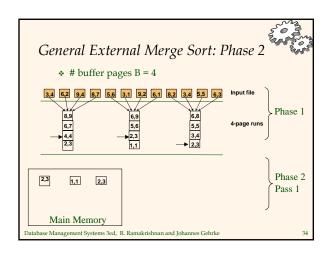
* No indices

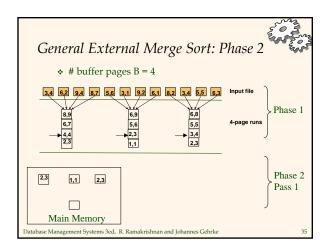
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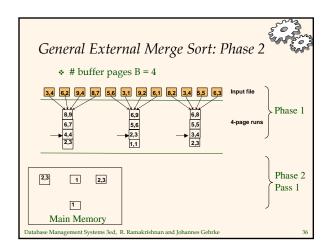


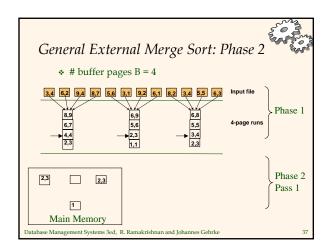


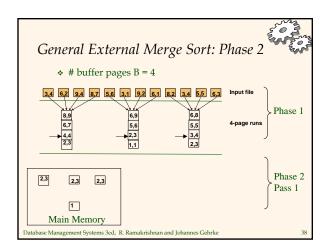


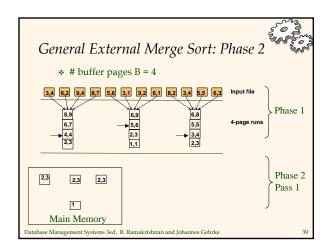


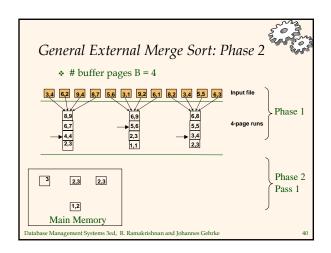


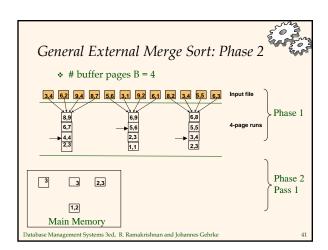


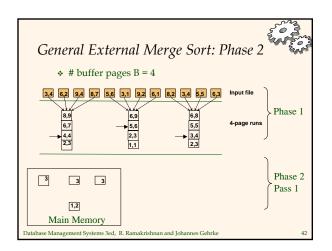


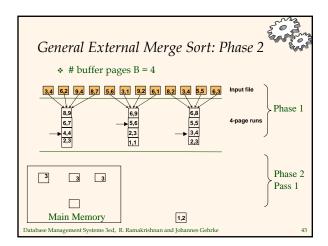












Modifications to External Sorting

- ❖ Phase 1
 - Project out unwanted columns
 - Still produce runs of length B (or 2B) pages
 - But tuples in runs are smaller than input tuples (so smaller runs)
- ❖ Phase 2
 - Eliminate duplicates during merge
 - Smaller runs
- Exercise: Calculate I/O cost assuming certain size of projection columns and certain distribution of duplicates

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Evaluation Alternatives

- ❖ Alternative 1
 - Using Indices
- ❖ Alternative 2
 - Based on sorting
- ❖ Alternative 3
 - Based on hashing

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Projection Based on Hashing Assume relation does not fit in memory Phase 1 Divide relation into partitions No duplicate elimination yet! Original Relation No duplicate elimination yet! Partitions INPUT Partitions Disk B main memory buffers Disk

Phase 1: Analysis

- Erren Pro
- ❖ Number of data pages = N

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- Assume all attributes are projected out
- Cost of reading/writing disk page = D
- ❖ Number of Partitions = B-1
- Length of each partition = N/(B-1)
- ❖ Cost of Phase 1 = 2 * D * N

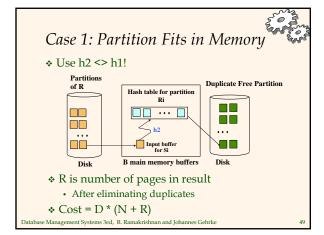
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Two Cases for Each Partition



- ❖ Case 1
 - Partitions fits in memory
- * Case 2
 - Partition does not fit in memory

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Case 2: Partition Doesn't fit in Memory

- * Recursively apply Phase 1 algorithm on the partition!
 - Use hash function h2 <> h1!
- Analysis
 - Size of each partition after P partitioning phases = $N/(B-1)^P$
 - Stop partitioning when : $N/(B-1)^P = B-1$
 - # Partitioning phases = $log_{B-1}(N) 1$
 - Total cost of Phase 1 = $2 * D * (log_{B-1}(N) 1)$

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Comments on Projection

- * Sort-based approach vs. hash-based approach
 - Which one would you choose?
 - Why?
- Sort-based approach!
 - Better handling of skew
 - Results in sorted order

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