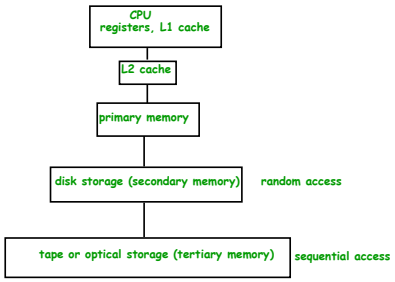
Disks

The Memory Hierarchy

- Each level acts as a cache for the layer below it



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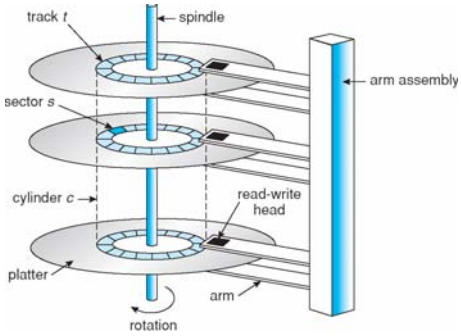
What does the disk look like?



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Some parameters

- 2-30 heads (platters * 2)
  - diameter 14'' to 2.5''
- 700-20480 tracks per surface
- 16-1600 sectors per track
- sector size:
  - 64-8k bytes
  - 512 for most PCs
  - note: inter-sector gaps
- capacity: 20M-100G

- main adjectives: BIG, slow

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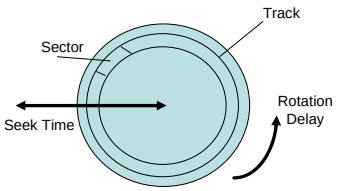
Disk overheads

- To read from disk, we must specify:
  - cylinder #, surface #, sector #, transfer size, memory address
- Transfer time includes:
  - Seek time: to get to the track
  - Latency time: to get to the sector and
  - Transfer time: get bits off the disk



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Modern disks

	Barracuda 180	Cheetah X15 36LP
Capacity	181GB	36.7GB
Disk/Heads	12/24	4/8
Cylinders	24,247	18,479
Sectors/track	~609	~485
Speed	7200RPM	15000RPM
Latency (ms)	4.17	2.0
Avg seek (ms)	7.4/8.2	3.6/4.2
Track-2-track(ms)	0.8/1.1	0.3/0.4

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Disks vs. Memory

- Smallest write: sector
- Atomic write = sector
- Random access: 5ms
  - not on a good curve
- Sequential access: 200MB/s
- Cost $.002MB
- Crash: doesn't matter ("non-volatile")

- (usually) bytes
- byte, word
- 50 ns
  - faster all the time
- 200-1000MB/s
- $.10MB
- contents gone ("volatile")

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Disk Structure

- Disk drives addressed as 1-dim arrays of *logical blocks*
  - the logical block is the smallest unit of transfer
- This array mapped sequentially onto disk sectors
  - Address 0 is 1st sector of 1st track of the outermost cylinder
  - Addresses incremented within track, then within tracks of the cylinder, then across cylinders, from innermost to outermost
- Translation is theoretically possible, but usually difficult
  - Some sectors might be defective
  - Number of sectors per track is not a constant

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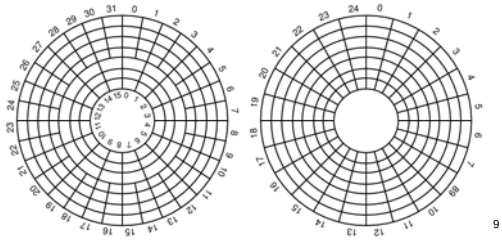
Non-uniform #sectors / track

- Maintain same data rate with Constant Linear Velocity
- Approaches:
  - Reduce bit density per track for outer layers
  - Have more sectors per track on the outer layers (virtual geometry)



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Disk Scheduling

- The operating system tries to use hardware efficiently
  - for disk drives ⇒ having fast access time, disk bandwidth
- Access time has two major components
  - *Seek time* is time to move the heads to the cylinder containing the desired sector
  - *Rotational latency* is additional time waiting to rotate the desired sector to the disk head.
- Minimize seek time
- Seek time ≈ seek distance
- Disk bandwidth is total number of bytes transferred, divided by the total time between the first request for service and the completion of the last transfer.

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Disk Scheduling (Cont.)

- Several scheduling algos exist service disk I/O requests.
- We illustrate them with a request queue (0-199).

98, 183, 37, 122, 14, 124, 65, 67

Head pointer 53

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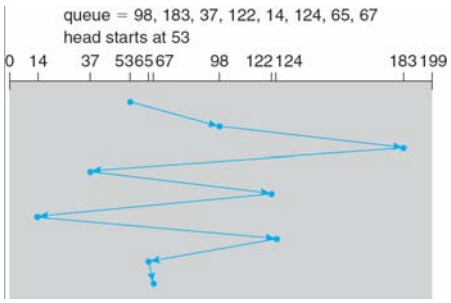
FCFS (First come first serve)

Illustration shows total head movement of 640 cylinders.



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SSTF (Shortest seek-time first)

- Selects request with minimum seek time from current head position
- SSTF scheduling is a form of SJF scheduling
  - may cause starvation of some requests.
- Illustration shows total head movement of 236 cylinders.

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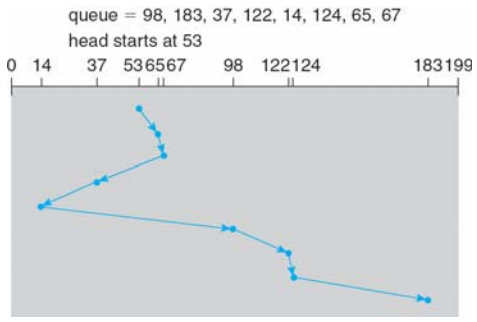
SSTF (Cont.)



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SCAN

- The disk arm starts at one end of the disk,
  - moves toward the other end, servicing requests
  - head movement is reversed when it gets to the other end of disk
  - servicing continues.
- Sometimes called the *elevator algorithm*.
- Illustration shows total head movement of 208 cylinders.

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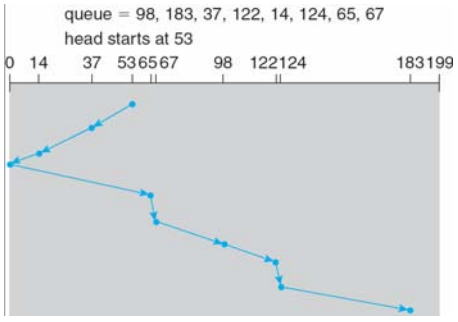
SCAN (Cont.)



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C-SCAN

- Provides a more uniform wait time than SCAN.
- The head moves from one end of the disk to the other.
  - servicing requests as it goes.
  - When it reaches the other end it immediately returns to beginning of the disk
    - No requests serviced on the return trip.
- Treats the cylinders as a circular list
  - that wraps around from the last cylinder to the first one.

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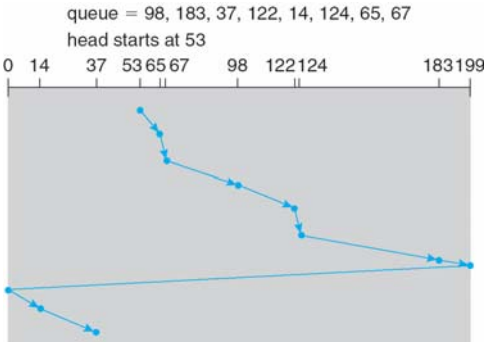
C-SCAN (Cont.)



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C-LOOK

- Version of C-SCAN
- Arm only goes as far as last request in each direction,
  - then reverses direction immediately,
  - without first going all the way to the end of the disk.

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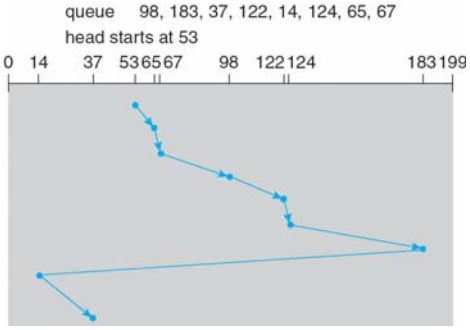
C-LOOK (Cont.)



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Selecting a Good Algorithm

- SSTF is common and has a natural appeal
- SCAN and C-SCAN perform better under heavy load
- Performance depends on number and types of requests
- Requests for disk service can be influenced by the file-allocation method.
- Disk-scheduling algo should be a separate OS module
  - allowing it to be replaced with a different algorithm if necessary.
- Either SSTF or LOOK is a reasonable default algo

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