

### 3: Processes

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-1

### Programs vs Processes

- ❑ A program is passive
  - Sequence of commands waiting to be run
- ❑ A process is active
  - An instance of program being executed
  - There may be many processes running the same program
  - Also called job or task

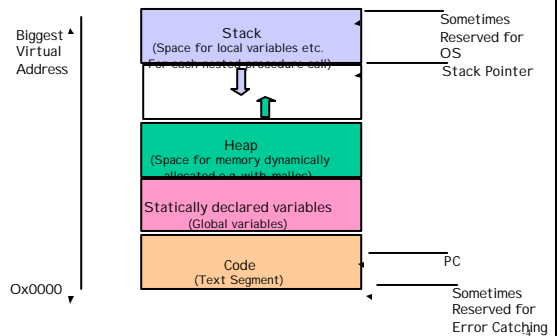
-2

### What makes up a process?

- ❑ Address space
- ❑ Code
- ❑ Data
- ❑ Stack (nesting of procedure calls made)
- ❑ Register values (including the PC)
- ❑ Resources allocated to the process
  - Memory, open files, network connections

-3

### Address Space Map



### What kinds of processes are there?

- ❑ Compute bound/ I/O bound
- ❑ Long-running/short-running
- ❑ Interactive/batch
- ❑ Large/small memory footprint
- ❑ Cooperating with other processes?
- ❑ ...
- ❑ How does the OS categorize processes?

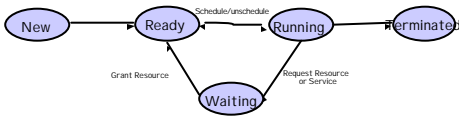
-5

### Process States

- ❑ During their lifetime, processes move between various states
  - Ready - waiting for a turn to use the CPU
  - Running - currently executing on the CPU
    - How many processes can be in this state?@
  - Waiting - Unable to use the CPU because blocked waiting for an event
  - Terminated/Zombie - Finished executing but state maintained until parent process retrieves state

-6

## State Transitions



-7

## State Queues

- OSes often maintain a number of queues of processes that represent the state of the processes
  - All the runnable processes are linked together into one queue
  - All the processes blocked (or perhaps blocked for a particular class of event) are linked together
  - As a process changes state, it is unlinked from one queue and linked into another

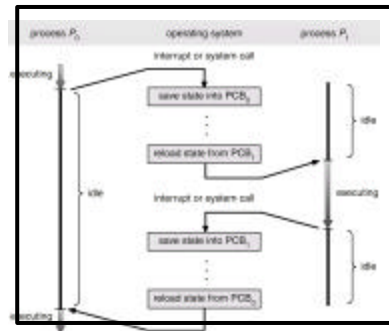
-8

## Context Switch

- When a process is running, some of its state is stored directly in the CPU (register values, etc.)
- When the OS stops a process, it must save all of this hardware state somewhere (PCB) so that it can be restored again
- The act of saving one process's hardware state and restoring another's is called a context switch
  - 100s or 1000s per second!

-9

## Context Switch



-10

## Schedulers

- Long-term scheduler (or job scheduler) - selects which processes should be brought into the ready queue.
- Short-term scheduler (or CPU scheduler) - selects which process should be executed next and allocates CPU.

-11

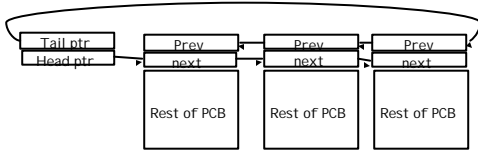
## Schedulers (cont)

- Short-term scheduler is invoked very frequently (milliseconds) ⇒ (must be fast).
- Long-term scheduler is invoked very infrequently (seconds, minutes) ⇒ (may be slow).
- The long-term scheduler controls the *degree of multiprogramming*.
- Processes can be described as either:
  - *I/O-bound process* - spends more time doing I/O than computations, many short CPU bursts.
  - *CPU-bound process* - spends more time doing computations; few very long CPU bursts.

-12



## State Queues



Ready queue, queues per device, queue of all processes, ...

-19

## Context Switch

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-20

## UNIX process creation

- Fork() system call
  - Creates a new PCB and a new address space
  - Initializes the new address space with a \*copy\* of the parent's address space
  - Initializes many other resources to copies of the parents (e.g. same open files)
  - Places new process on the queue of runnable processes
- Fork() returns twice: to parent and child
  - Returns child's process ID to the parent
  - Returns 0 to the child

-21

## Example Code Snippet

```
int main (int argc, char **argv)
{
    int childPid;
    childPid = fork();
    if (childPid == 0){
        printf("Child running\n");
    } else {
        printf("Parent running: my child is %d\n",
            childPid);
    }
}
```

-22

## Output

```
% ./tryfork
Parent running: my child is 707
Child running
%
```

-23

## Experiments

- Try putting an infinite loop in the child's portion (do you return to the command shell?) and then looking for it in the ps output
- Try putting an infinite loop in the parent's portion (do you return to the command shell?)
- Put an infinite loop in both
  - try killing the child (look in the ps output for the child and the parent)
  - Try killing the parent - what happens to the child?
- **WARNING: DO NOT PUT THE FORK COMMAND ITSELF IN AN INFINITE LOOP!!! YOU WILL CRASH THE SYSTEM!**

-24

## Fork and Exec

- ❑ How do we get a brand new process not just a copy of the parent?
  - Exec () system call
  - `int exec (char * prog, char ** argv)`
- ❑ Exec:
  - Stops the current process
  - Loads the program, prog, into the address space
  - Passes the arguments specified in argv
  - Places the PCB back on the ready queue
- ❑ Exec “takes over” the process
  - There is no going back to it when it returns
  - Try to exec something in your shell (example: exec ls) – when ls is done your shell is gone because ls replaced it!

-25

## UNI X Shell

```
int main (int argc, char **argv)
{
    while (1){
        int childPid;
        char * cmdLine = readCommandLine();

        if (userChooseExit(cmdLine)){
            wait for all background jobs
        }

        childPid = fork();
        if (childPid == 0){
            setSTDOUT_STDIN_STDErr(cmdLine);
            exec ( getCommand (cmdLine));
        } else {
            if (runInPoreground(cmdLine)){
                wait (childPid);
            }
        }
    }
}
```

-26

## Windows Process Creation

### **BOOL CreateProcess(**

**LPCTSTR** lpApplicationName, // name of executable module  
**LPTSTR** lpCommandLine, // command line string  
**LPSECURITY\_ATTRIBUTES** lpProcessAttributes, // SD  
**LPSECURITY\_ATTRIBUTES** lpThreadAttributes, // SD  
**BOOL** bInheritHandles, // handle inheritance option  
**DWORD** dwCreationFlags, // creation flags  
**LPVOID** lpEnvironment, // new environment block  
**LPCTSTR** lpCurrentDirectory, // current directory name  
**LPSTARTUPINFO** lpStartupInfo, // startup information  
**LPPROCESS\_INFORMATION** lpProcessInformation // information );

-27

## Windows vs Unix

- ❑ Windows doesn't maintain the same relationship between parent and child
  - ❑ Later versions of Windows have concept of “job” to mirror UNI X notion of parent and children (process groups)
- ❑ Waiting for a process to complete?
  - ❑ WaitForSingleObject to wait for completion
  - ❑ GetExitCodeProcess ( will return STILL\_ALIVE until process has terminated)

-28

## Cooperating Processes

- ❑ Processes can run independently of each other or processes can coordinate their activities with other processes
- ❑ To cooperate, processes must use OS facilities to communicate
  - One example: parent process waits for child
  - Many others
    - Shared Memory
    - Files
    - Sockets
    - Pipes
    - Signals
    - Events
    - Remote Procedure Call

-29

## Sockets

- ❑ A socket is an end-point for communication over the network
- ❑ Create a socket
  - `int socket(int domain, int type, int protocol)`
  - Type = SOCK\_STREAM for TCP
- ❑ Read and write socket just like files
- ❑ Can be used for communication between two processes on same machine or over the network

-30

## Pipes

- ❑ Bi-directional data channel between two processes on the same machine
- ❑ Created with:
  - `int pipe (int fildes[2])`
- ❑ Read and write like files

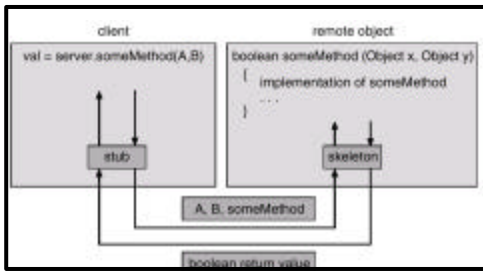
-31

## Signals

- ❑ Processes can register to handle signals with the signal function
  - `void signal (int signum, void (*proc) (int))`
- ❑ Processes can send signals with the kill function
  - `kill (pid, signum)`
- ❑ System defined signals like SIGHUP (0), SIGKILL (9), SIGSEGV(11)
  - In UNIX shell, try:  
"kill -9 pidOfProcessYouDontReallyCareAbout"
- ❑ Signals not used by system like SIGUSR1 and SIGUSR2
- ❑ Note: sigsend/sigaction similar to kill/signal

-32

## Remote Procedure Call (RPC)



-33

## Processes

- ❑ What is a process?
- ❑ Process States
- ❑ Switching Between Processes
- ❑ Process Creation
- ❑ PCBs
- ❑ Communication/Cooperation between processes

-34

## Outtakes

- ❑ Could spend more time on things in Process Creation and Signal chapter of Stevens

-35