Deadlock

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Deadlock

- <u>Deadlock</u> is a problem that can exist when a group of processes compete for access to fixed resources.
- Def: deadlock exists among a set of processes if every process is waiting for an event that can be caused only by another process in the
- Example: two processes share 2 resources that they must request (before using) and release (after using). Request either gives access or causes the proc. to block until the resource is available.

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4 Conditions for Deadlock

- Deadlock can exist if and only if 4 conditions hold simultaneously:
 - mutual exclusion; at least one resource must be held in a nonsharable mode.
 - 2. hold and wait; there must be a process holding one resource and
 - 3. no preemption; resources cannot be preempted.
 - description of the control of t

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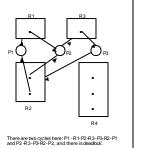
[p1, p2, ..., pn] such that p1 is waiting for p2, p2 for p3, and so on and pn waits for p1....

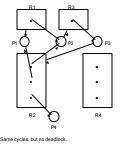
Resource Allocation Graph

- Deadlock can be described through a resource allocation graph
- The RAG consists of a set of vertices P={P₁,P₂,...,P_n} of processes and R={R₁,R₂,...,R_m} of resources.
- A directed edge from a processes to a resource, $P_r\!>\!R_p$ implies that P_i has requested R_p
- A directed edge from a resource to a process, R_f>P_p implies that R_i has been allocated by P_p
- If the graph has no cycles, deadlock cannot exist. If the graph has a cycle, deadlock may exist.

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Resource Allocation Graph Example





Dealing with Deadlocks

- Deadlock Prevention & Avoidance: Ensure that the system will never enter a deadlock
- Deadlock Detection & Recovery: Detect that a deadlock has occurred and recover
- Deadlock Ignorance: Pretend that deadlocks will never occur

Deadlock Prevention

- · Deadlock Prevention: ensure that at least one of the necessary conditions cannot exist.
 - Mutual exclusion: make resources shareable
 - Not possible for some resources
 - Hold and wait: guarantee that a process cannot hold a resource when it requests another, or, make processes request all needed resources at once, or, make it release all resources before requesting a new set
 - Low utilization, starvation
 - Preemption: take resources back if there is contention
 - Not always possible, hard model to write applications for
 - Circular wait: impose an ordering (numbering) on the resources and request them in order

Deadlock Prevention

- · Most real systems use deadlock prevention through resource ordering
- The resource order is a convention that the OS designers must know and follow
 - These conventions complicate system programming
- · E.g. must always acquire a buffer cache lock before acquiring the file system lock, before acquiring the disk lock
- · What happens when you get a page fault?

Problems with Deadlock Prevention

- Prevention works by restraining how requests are made
- · Might yield low utilization and low throughput
 - Certain resource request sequences are not allowed, limiting functionality
- With sufficient information about future behavior, we could allow any process to perform any set of resource accesses
- As long as their actions would not lead to a deadlock in the future

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Deadlock Avoidance

- Deadlock Avoidance
 - general idea: provide info in advance about what resources will be needed by processes to guarantee that deadlock will not exist.
- E.g., define a set of processes < P₁, P₂.... P_n> as <u>safe</u> if for each P_i, the resources that P_i can still request can be satisfied by the currently available resources plus the resources held by all P_j, where j < i.
 - this avoids circular waiting
 - when a process requests a resource, the system grants or forces it to wait, depending on whether this would be an unsafe state
- All deadlock states are unsafe. An unsafe state may lead to deadlock. By avoiding unsafe states, we avoid deadlock

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Example:

• Processes p0, p1, and p2 compete for 12 tape drives

	max need	current usage	could ask for
p0	10	5	5
p1	4	2	2
p2	9	2	7
	3 dri	ves remain	

 current state is safe because a safe sequence exists: <p1,p0,p2>

p1 can complete with current resources p0 can complete with current+p1 p2 can complete with current +p1+p0

 if p2 requests 1 drive, then it must wait because that state would be unsafe.

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The Banker's Algorithm

 Banker's algorithm decides whether to grant a resource request. Define data structures.

n: integer # of processes
m: integer # of resources
available[1..m] avail[0] is # of avail resources of type i
max[1..n,1..m] max demand of each Pi for each Ri
allocation[1..n,1..m] current allocation of resource Rj to Pi
need[1..n,1..m] max # of resource Rj that Pi may still request

let request[i] be a vector of the # of instances of resource Rj that Process Pi

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The Basic Algorithm

- 1. If request[i] > need[i] then error (asked for too much)
- 2. If request[i] > available[i] then wait (can't supply it now)
- 3. Resources are available to satisfy the request: Let's assume that we satisfy the request. Then we would

available = available - request[i] allocation[i] = allocation [i] + request[i] need[i] = need [i] - request [i]

Now, check if this would leave us in a safe state; if yes, grant the request, if no, then leave the state as is and cause process to wait.

Safety Check

- 1. free[1..m] = available ; how many resources are available finish[1..n] = false (for all i); none finished yet
- 2. Find an i s.t. finish[i]=false and need[i] <= work (find a proc that can complete its request now) if no such i exists, go to step 4 (we're done)
- 3. Found an i:

finish [i] = true ; done with this process free = free + allocation [i] (assume this process were to finish, and its allocation back to the available list) go to step 2

4. If finish[i] = true for all i, the system is safe.

Deadlock Detection

- If there is neither deadlock prevention nor avoidance, then deadlock may occur.
- In this case, we must have:
 - an algorithm that determines whether a deadlock has occurred - an algorithm to recover from the deadlock
- . This is doable, but it's costly

Deadlock Detection Algorithm

available[1..m]; # of available resources allocation[1..n,1..m];# of resource of each Ri allocated to Pi request[1..n,1..m]; # of resources of each Ri requested by Pj

1. work=available for all i < n, if allocation [i] not 0 then finish[i]=false else finish[i]=true

2. find an index i such that: finish[i]=false; request[i]<=work

if no such i exists, go to 4. 3. work=work+allocation[i]

finish[i] = true, go to 2
4. if finish[i] = false for some i, then system is deadlocked with Pi in deadlock

Deadlock

- Deadlock detection algorithm is expensive. How often we invoke it depends on:
 - how often or likely is deadlock
 - how many processes are likely to be affected when deadlock occurs
- Running the deadlock detection algorithm often will catch deadlock cycles early
 - Few processes will be affected
 - Note: there is no single process that caused the deadlock
 - May incur large overhead

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Deadlock Recovery

- Once a deadlock is detected, there are two choices:
 - abort all deadlocked processes (which will cause some computations to be repeated)
 - abort one process at a time until cycle is eliminated (which requires re-running the detection algorithm after each abort)
- Or, could do process preemption: release resources until system can continue. Issues:
 - selecting the victim (could be clever based on resources allocated)
 - rollback (must rollback the victim to a previous state, may require a transactional programming model, or functional apps)
 - starvation (must not always pick same victim)

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