CS412/413

Introduction to Compilers
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Lecture 16: Intermediate Representation
24 Feb 03

## Record Subtyping

- Width Subtyping: types of inherited fields must match in the subtype

$$\frac{n \le m}{A \vdash \{a_1: T_1, \ldots, a_m: T_m\} <: \{a_1: T_1, \ldots, a_n: T_n\}}$$

- Depth subtyping: corresponding immutable fields may be subtypes; exact match not required

$$\frac{A \vdash T_i <: T_i' \ (i \in 1..n)}{A \vdash \{a_1: T_1 \ldots a_n: T_n\} <: \{a_1: T_1' \ldots a_n: T_n'\}}$$



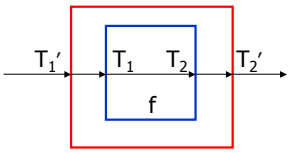
## Depth Subtyping

- Depth subtyping for objects:
  - Mutable components must be type invariant
  - Immutable components may be type covariant
- Immutable components:
  - Methods (but Java is conservative)
  - Constant fields: final in Java



## Function Subtyping

- Function subtyping: $T_1 \to T_2 <: T_1' \to T_2'$
- Consider function f of type $T_1 \to T_2$:






## Contravariance/Covariance

- Function argument types may be contravariant
- Function result types may be covariant

$$\frac{T_1' <: T_1 \quad T_2 <: T_2'}{T_1 \to T_2 <: T_1' \to T_2'}$$



## Java Array Subtyping

- Java has array type constructor: for any type T, T [ ] is an array of T's
- Java also has subtype rule:

$$\frac{T_1 <: T_2}{T_1[] <: T_2[]}$$

- Is this rule safe?

## Java Array Subtyping

- Example:

```
Elephant <: Animal
Animal [ ] x;
Elephant [ ] y;
x = y;
x[0] = new Rhinoceros(); // oops!
```

- Covariant modification: unsound
- Java does run-time check!



## Unification

- Some rules more problematic: if
- Rule:

$$\frac{A \vdash E : \text{bool} \quad A \vdash S_1 : T \quad A \vdash S_2 : T}{A \vdash \text{if } (E)\ S_1 \text{ else } S_2 : T}$$

- Problem: if $S_1$ has type $T_1$, $S_2$ has type $T_2$. Old check: $T_1 = T_2$ . New check: need type T. How to unify $T_1$ , $T_2$ ?
- Occurs in Java: ?: operator



## General Typing Derivation

$$\frac{A \vdash E : \text{bool} \quad \dfrac{A \vdash S_1 : T_1 \quad T_1 <: T}{A \vdash S_1 : T} \quad \dfrac{A \vdash S_2 : T_2 \quad T_2 <: T}{A \vdash S_2 : T}}{A \vdash \text{if } (E)\ S_1 \text{ else } S_2 : T}$$

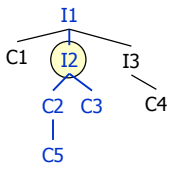
How to pick T ?



## Unification

- Idea: unified type is least common ancestor in type hierarchy (least upper bound)
- Partial order of types must be a lattice

if (b) new C5() else new C3() : I2




LUB(C3, C5) = I2

Logic: I2 must be same as or a subtype of any type (e.g. I1) that could be the type of both a value of type C3 and a value of type C5

What if no LUB?



## Summary: Semantic Analysis

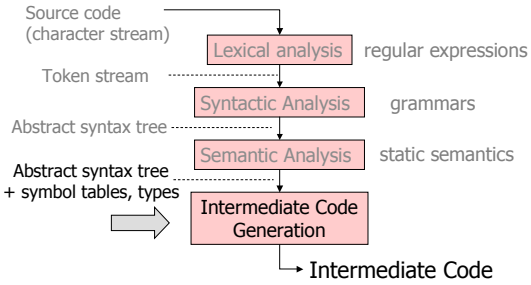
- Check errors not detected by lexical or syntax analysis
- Scope errors:
  - Variables not defined
  - Multiple declarations
- Type errors:
  - Assignment of values of different types
  - Invocation of functions with different number of parameters or parameters of incorrect type
  - Incorrect use of return statements



## Semantic Analysis

- Type checking
  - Use type checking rules
  - Static semantics = formal framework to specify type-checking rules
- There are also control flow errors:
  - Must verify that a break or continue statement is always enclosed by a while (or for) statement
  - Java: must verify that a break X statement is enclosed by a for loop with label X
  - Can easily check control-flow errors by recursively traversing the AST

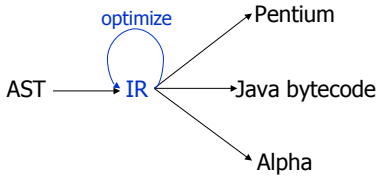
## Where We Are






## Intermediate Code

- IR = Intermediate Representation
- Allows language-independent, machine-independent optimizations and transformations






## What Makes a Good IR?

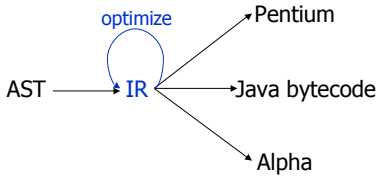
- Easy to translate from AST
- Easy to translate to assembly
- Narrow interface: small number of node types (instructions)
  - Easy to optimize
  - Easy to retarget

AST (>40 node types)
↓
IR (13 node types)
↓
Pentium (>200 opcodes)



## Multiple IRs

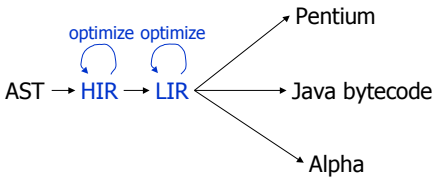
- Some optimizations require high-level structure
- Others more appropriate on low-level code






## Multiple IRs

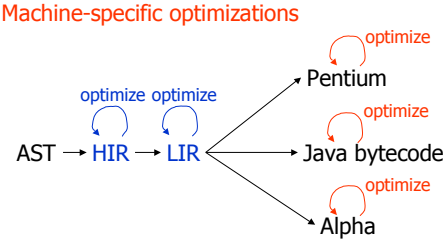
- Some optimizations require high-level structure
- Others more appropriate on low-level code
- Solution: use multiple IR stages





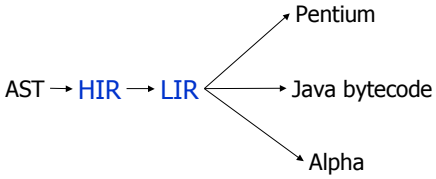

## Machine Optimizations

- … some other optimizations take advantage of the features of the target machine
- Machine-specific optimizations



## Next Lectures

- Next few lectures: intermediate representation
- Optimizations covered later



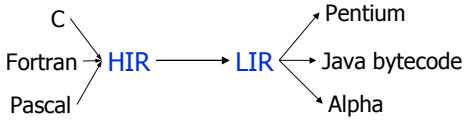



## Multiple IRs

- Usually two IRs:

High-level IR
Language-independent
(but closer to language)

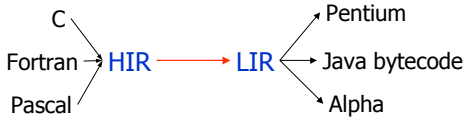
Low-level IR
Machine independent
(but closer to machine)






## Multiple IRs

- Another benefit: a significant part of the translation from high-level to low-level is
  - Language-independent
  - Machine-independent






## High-Level IR

- High-level intermediate representation is essentially the AST
  - Must be expressive for all input languages
- Preserves high-level language constructs
  - Structured control flow: if, while, for, switch, etc.
  - variables, methods
- Allows high-level optimizations based on properties of source language (e.g. inlining)



## Low-Level IR

- Low-level representation is essentially an abstract machine
- Has low-level constructs
  - Unstructured jumps, instructions
- Allows optimizations specific to these constructs (e.g. register allocation, branch prediction)



## Low-Level IR

- Alternatives for low-level IR:
  - Three-address code or quadruples (Dragon Book):
    a = b OP c
  - Tree representation (Tiger Book)
  - Stack machine (like Java bytecode)
- Advantages:
  - Three-address code: easier dataflow analysis
  - Tree IR: easier instruction selection
  - Stack machine: easier to generate

## Three-Address Code

- In this class: three-address code
  a = b OP c
- Has at most three addresses (may have fewer)
- Also named quadruples because can be represented as: (a, b, c, OP)
- Example:
  a = (b+c)*(-e);

  t1 = b + c
  t2 = – e
  a = t1 * t2



## Low IR Instructions

- Assignment instructions:
  - Binary operations: a = b OP c
    - Arithmetic, logic, comparisons
  - Unary operation a = OP b
    - Arithmetic, logic
  - Copy instruction: a = b
  - Load /store: a = *b, *a = b
  - Other data movement instructions



## Low IR Instructions (Ctd)

- Flow of control instructions:
  - label L : label instruction
  - jump L : Unconditional jump
  - cjump a L : conditional jump
- Function call
  - call $f(a_1, ...., a_n)$
  - a = call $f(a_1, ...., a_n)$
  - Is an extension to quads
- … IR describes the Instruction Set of an abstract machine



## Temporary Variables

- The operands in the quadruples can be:
  - Program variables
  - Integer constants
  - Temporary variables
- Temporary variables = new locations
  - Use temporary variables to store intermediate values



## Arithmetic / Logic Instructions

- Abstract machine supports a variety of different operations

  a = b OP c  a = OP b
- Arithmetic operations: ADD, SUB, DIV, MUL
- Logic operations: AND, OR, XOR
- Comparisons: EQ, NEQ, LE, LEQ, GE, GEQ
- Unary operations: MINUS, NEG



## Data Movement

- Copy instruction: a = b
- Load/store instructions:

  a = *b  *a = b
  - Models a load/store machine
- Address-of instruction: a = &b
- Array accesses:

  a = b[i]  a[i] = b
- Field accesses:

  a = b.f  a.f = b

## Branch Instructions

- Label instruction:
  label L
- Unconditional jump: go to statement after label L
  jump L
- Conditional jump: test condition variable a; if true, jump to label L
  cjump a L
- Alternative: two conditional jumps:
  tjump a L  fjump a L



## Call Instruction

- Supports function call statements
  call $f(a_1, \ldots, a_n)$
- … and function call assignments:
  $a$ = call $f(a_1, \ldots, a_n)$
- No explicit representation of argument passing, stack frame setup, etc.



## Example

```
n = 0;
while (n < 10)  {
   n = n + 1
}
```

```
n = 0
label test
t2 = n < 10
t3 = not t2
cjump t3 end
label body
n = n + 1
jump test
label end
```



## Another Example

```
m = 0;
if (c  == 0) {
   m = m+ n*n;
} else {
   m = m + n;
}
```

```
m = 0
t1 = c == 0
cjump t1 trueb
m = m+n
jump end
label trueb
t2 = n * n
m = m + t2
label end
```



## How To Translate?

- May have nested language constructs
  - Nested if and while statements
- Need an algorithmic way to translate
- Solution:
  - Start from the AST representation
  - Define translation for each node in the AST
  - Recursively translate nodes in the AST