

# Outline

- Announcements:
  - Homework I: Solutions on web
  - Homework II: on web--due Wed.
- Homework I
- Performance Issues

# **Homework I**

- Grades & comments are waiting in your mailboxes

  - PASS--you passed!try to learn from your mistakes
  - PROVISIONAL--you passed, but I'm watching
  - 2 or more provisional passes will make it difficult for me to let you pass
    FAIL--you're failing and need to see me ASAP
  - - No one yet!

#### **Homework I**

- Most everyone did well on 1-4 – check the comments I sent
- 5 and 6 gave people fits
- Need to understand the solutions in order to solve next assignment.

#### **Homework**

- "Essential knowledge" questions should be fairly easy
  - just the basics covered in lecture
- "Programming" questions will be harder – apply what we've talked about to a real problem
- The goal of the problem sets is to build your skill and confidence
  - I don't intend for this to be painful
  - If you find that you're spending several hours on a problem, please see me.

### Fourier Series--Problems 5-6

- We can represent a function x(t) by sines & cosines
- Define a vector of times t for which we want to know the value of x.
  t and x are vectors of the same size.
- The jth entry in x will be its value at time t(j) is given by:

$$x(j) = \sum_{k=1}^{N/2+1} a_k \cos(\frac{2\pi(k-1)t(j)}{Ndt}) + b_k \sin(\frac{2\pi(k-1)t(j)}{Ndt})$$



• To keep things simple, let's ignore sine terms and pretend the cosines don't exist:

$$x(j) = \sum_{k=1}^{N/2+1} a_k \frac{2\pi(k-1)t(j)}{Ndt}$$

• Can implement this as a double loop:

$$\label{eq:n=length} \begin{split} n = & length(a); \, N = 2*n-2; \, p = length(t); \\ x = & zeros(p,1); \, f = 2*pi/(N*dt); \\ & for \, j = 1:p \end{split}$$
for k=1:n x(j)=x(j) + a(k)\*f\*(k-1)\*t(j);end end

**Fourier Series--Problems 5-6** 

• Inner loop looks a lot like a vector product c=a'\*b:

c=0; for k=1:n c=c + a(k)\*b(k);end

• Can eliminate inner loop:

n=length(a); N=2\*n-2; p=length(t); x=zeros(p,1); f=2\*pi/(N\*dt); K=[1:n]-1; for j=1:p  $x(j)=f^{*}t(j)^{*}K^{*}a(:);$ end

# **Fourier Series--Problems 5-6**

If we can use vector \* to eliminate one loop, why not the other?

. t(p)\*K ]

- If we multiply this matrix by a, we get the desired form for x

 $\begin{array}{l} t(k)^{*}\mathsf{K}^{*}\mathsf{a}(:) = [t(1)^{*}\mathsf{K}^{*}\mathsf{a}); \\ t(2)^{*}\mathsf{K}^{*}\mathsf{a}; \end{array}$ 

. t(p)\*K\*a ]

#### **Problem Set II**

- You must implement the scheme we developed as a function
  - Inputs: a, b, t
  - Outputs: x
- You will create another function that will solve for a and b
  - Inputs: x, t
  - Outputs: a, b, f

# So what's the point?

- Matrix operators in Matlab are much faster than loops
- Example developed above:
  - TwoLoop.m
  - OneLoop.m
  - NoLoop.m
- Fast Matlab code uses \* and avoids loops

### **Some Performance Tips**

- Use built-in functions as they are often heavily optimized
- vectorization is the epitome of this
- Minimize division

   x/2 takes longer than 0.5\*x
- Do computations outside loop
  - f and K in TwoLoop.m
- Pre-allocate arrays
  - for j=1:n;a(j)=<something>;end
  - Setting a=zeros(1,n) before the loop speeds things
  - up

# **Other Options**

• subfunctions file fname.m: function O=fname(I)

function O2=fname2(I2)

- Implement in a compiled language - mapping to C and Fortran is straightforward
- Look into Matlab compiler
- Stop being so impatient

# Some comments on performance

- The Three "E's"
  - Effective
  - Efficient
  - Elegant
- Efficiency (speed) is only one goal.
- Time spent tuning code should be factored
  - Spending 2 hours improving runtime from 10 min to 5 min only makes sense if you will use the code a lot or on much larger problems