

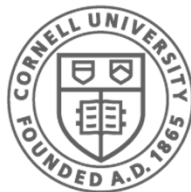


# Pipelining

**Hakim Weatherspoon**

**CS 3410**

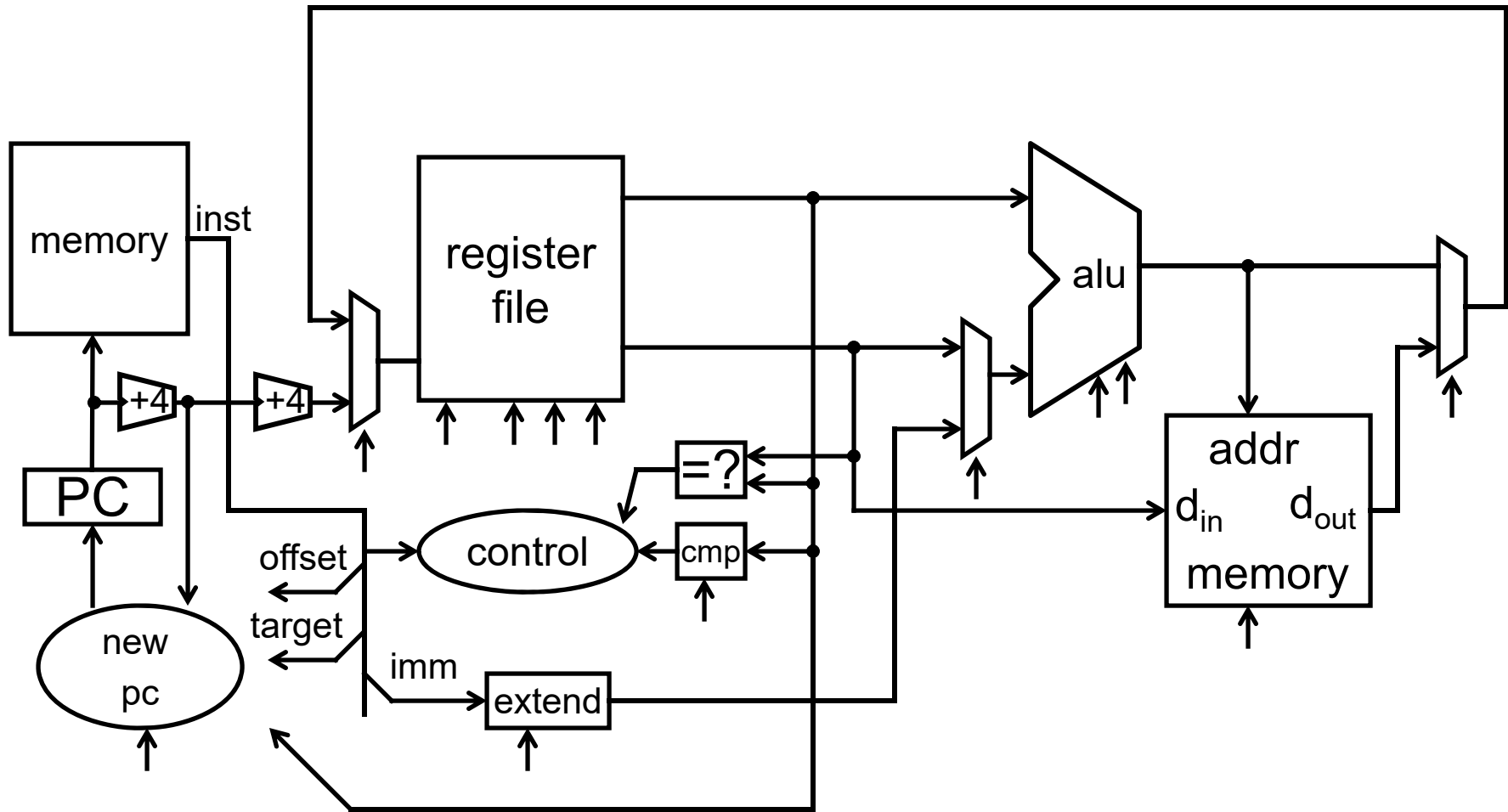
Computer Science  
Cornell University



**Cornell CIS**  
COMPUTING AND INFORMATION SCIENCE

[Weatherspoon, Bala, Bracy, McKee, and  
Sirof]

# Review: Single Cycle Processor



# Review: Single Cycle Processor

- Advantages
  - Single cycle per instruction make logic and clock simple
- Disadvantages
  - Since instructions take different time to finish, memory and functional unit are not efficiently utilized
  - Cycle time is the longest delay
    - Load instruction
  - Best possible CPI is 1 (actually  $< 1$  w parallelism)
    - However, lower MIPS and longer clock period (lower clock frequency); hence, lower performance

# Review: Multi Cycle Processor

- Advantages
  - Better MIPS and smaller clock period (higher clock frequency)
  - Hence, better performance than Single Cycle processor
- Disadvantages
  - Higher CPI than single cycle processor
- Pipelining: Want better Performance
  - want small CPI (close to 1) with high MIPS and short clock period (high clock frequency)

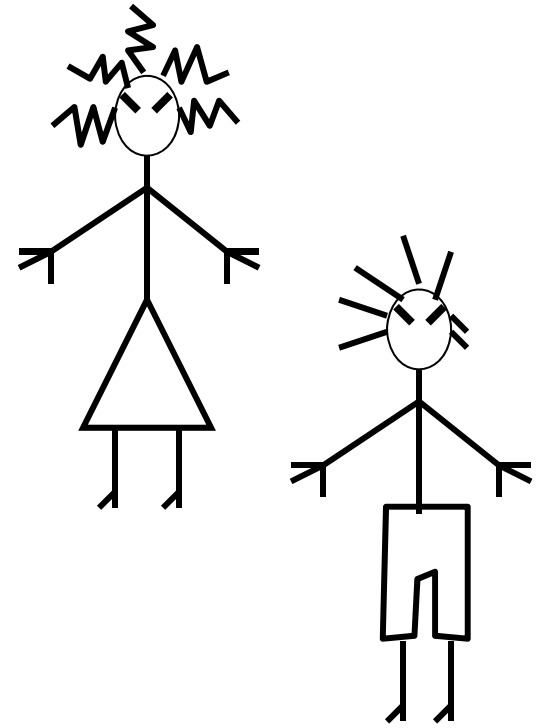
# Improving Performance

- Parallelism
- Pipelining
- Both!

# The Kids

Alice

Bob



They don't always get along...

# The Bicycle



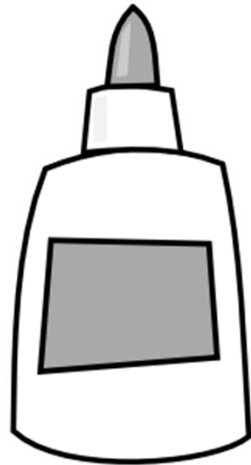
# The Materials



Saw



Drill



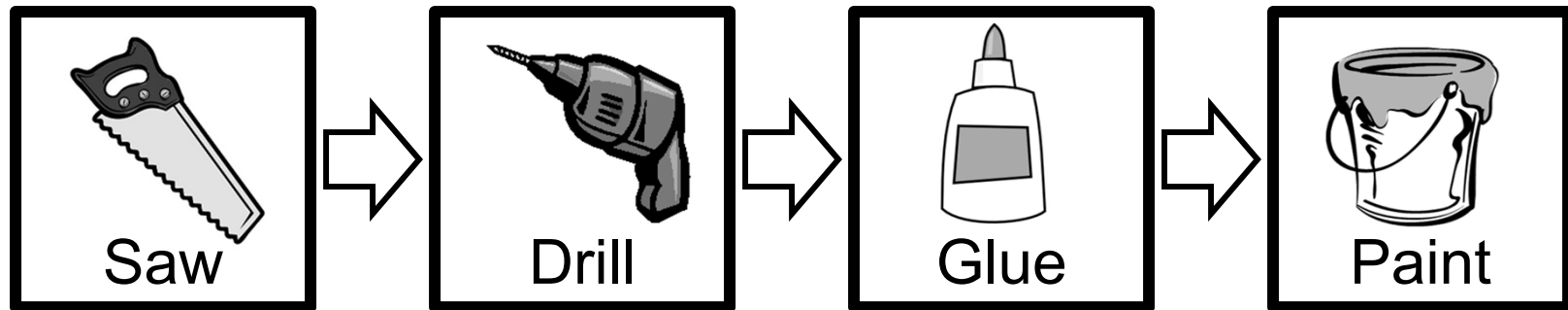
Glue



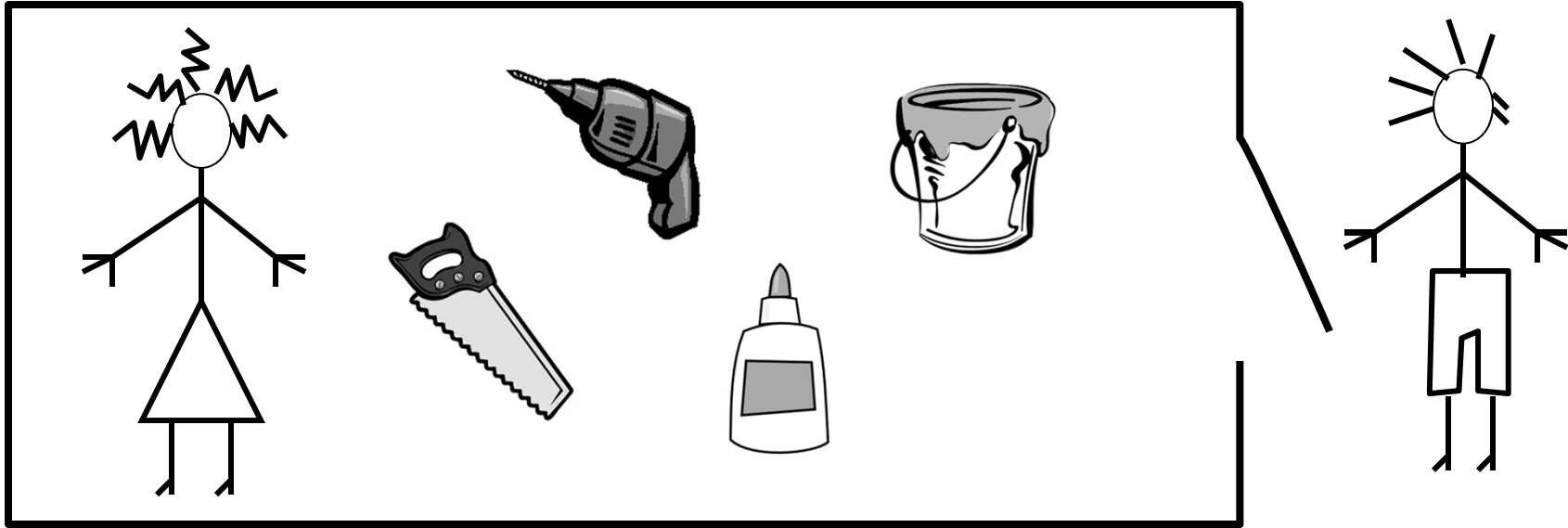
Paint

# The Instructions

N pieces, each built following same sequence:



# Design 1: Sequential Schedule



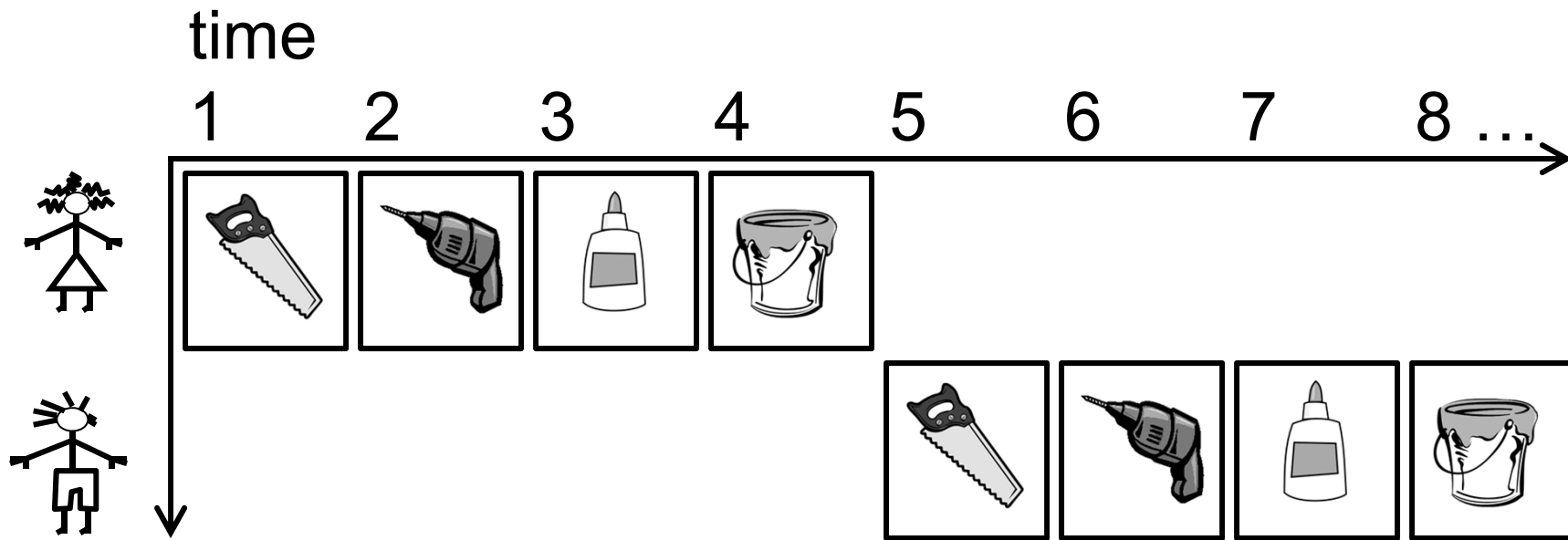
Alice owns the room

Bob can enter when Alice is finished

Repeat for remaining tasks

No possibility for conflicts

# Sequential Performance



Latency: 4 hours/task

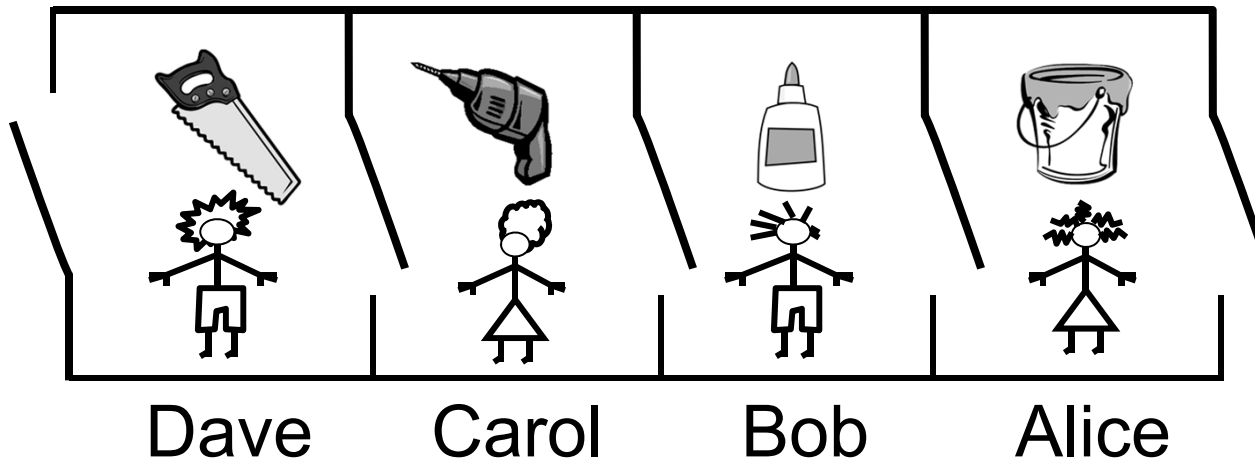
Throughput: 1 task/4 hrs

Concurrency: 1

$$\text{CPI} = 4$$

# Design 2: Pipelined Design

Partition room into *stages* of a *pipeline*



One person owns a stage at a time

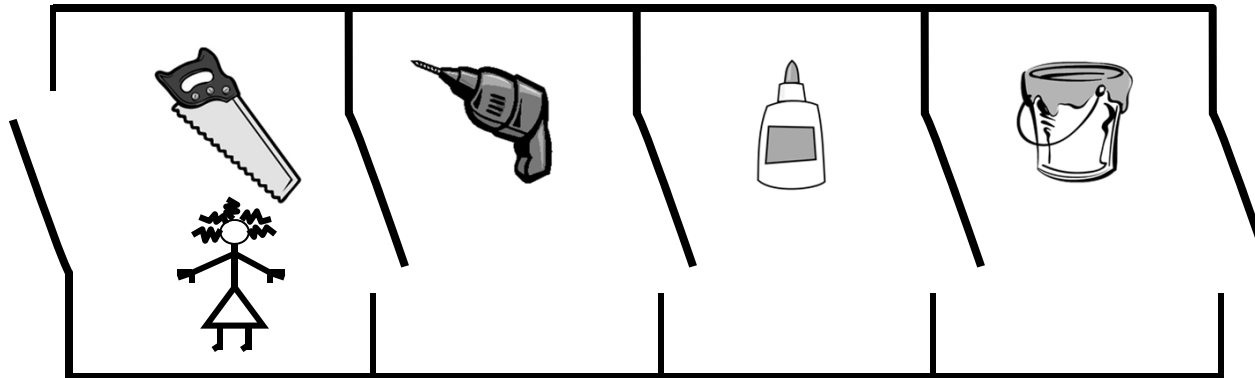
4 stages

4 people working simultaneously

Everyone moves right in lockstep

# Design 2: Pipelined Design

Partition room into *stages* of a *pipeline*



Alice

One person owns a stage at a time

4 stages

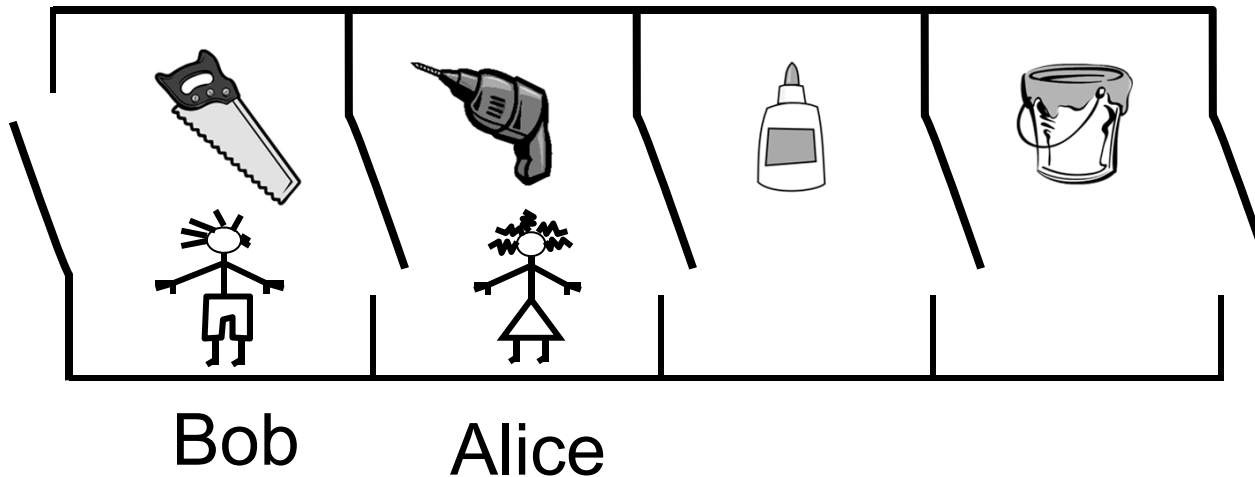
4 people working simultaneously

Everyone moves right in lockstep

It still takes all four stages for one job to complete

# Design 2: Pipelined Design

Partition room into *stages* of a *pipeline*



One person owns a stage at a time

4 stages

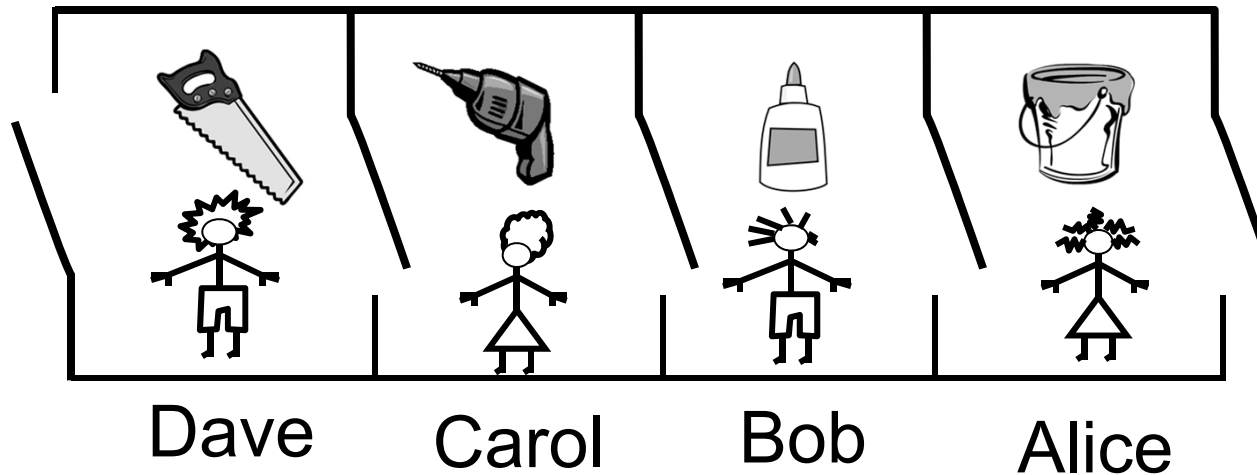
4 people working simultaneously

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It still takes all four stages for one job to complete

# Design 2: Pipelined Design

Partition room into *stages* of a *pipeline*



One person owns a stage at a time

4 stages

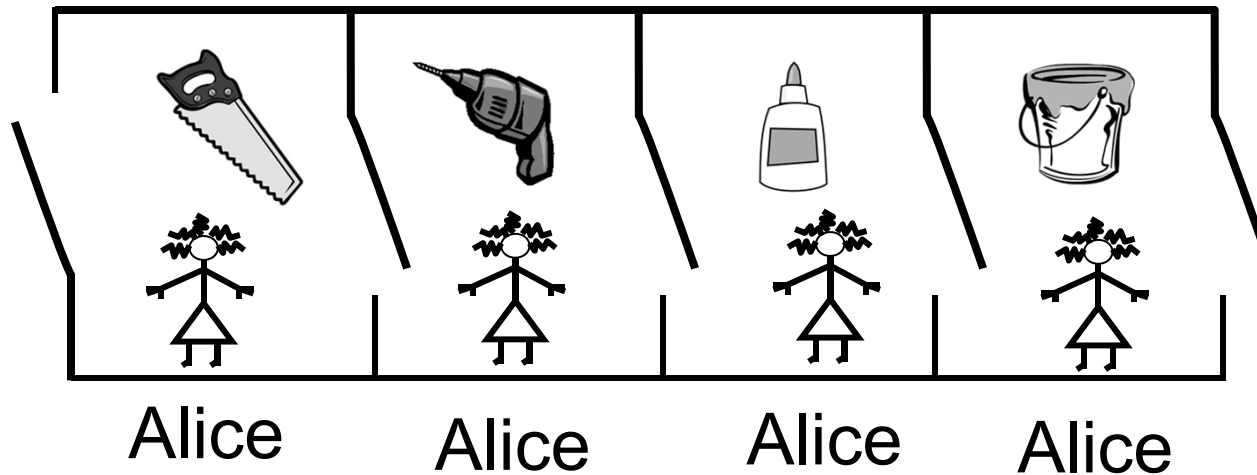
4 people working simultaneously

Everyone moves right in lockstep

It still takes all four stages for one job to complete

# Design 2: Pipelined Design

Partition room into *stages* of a *pipeline*



One person owns a stage at a time

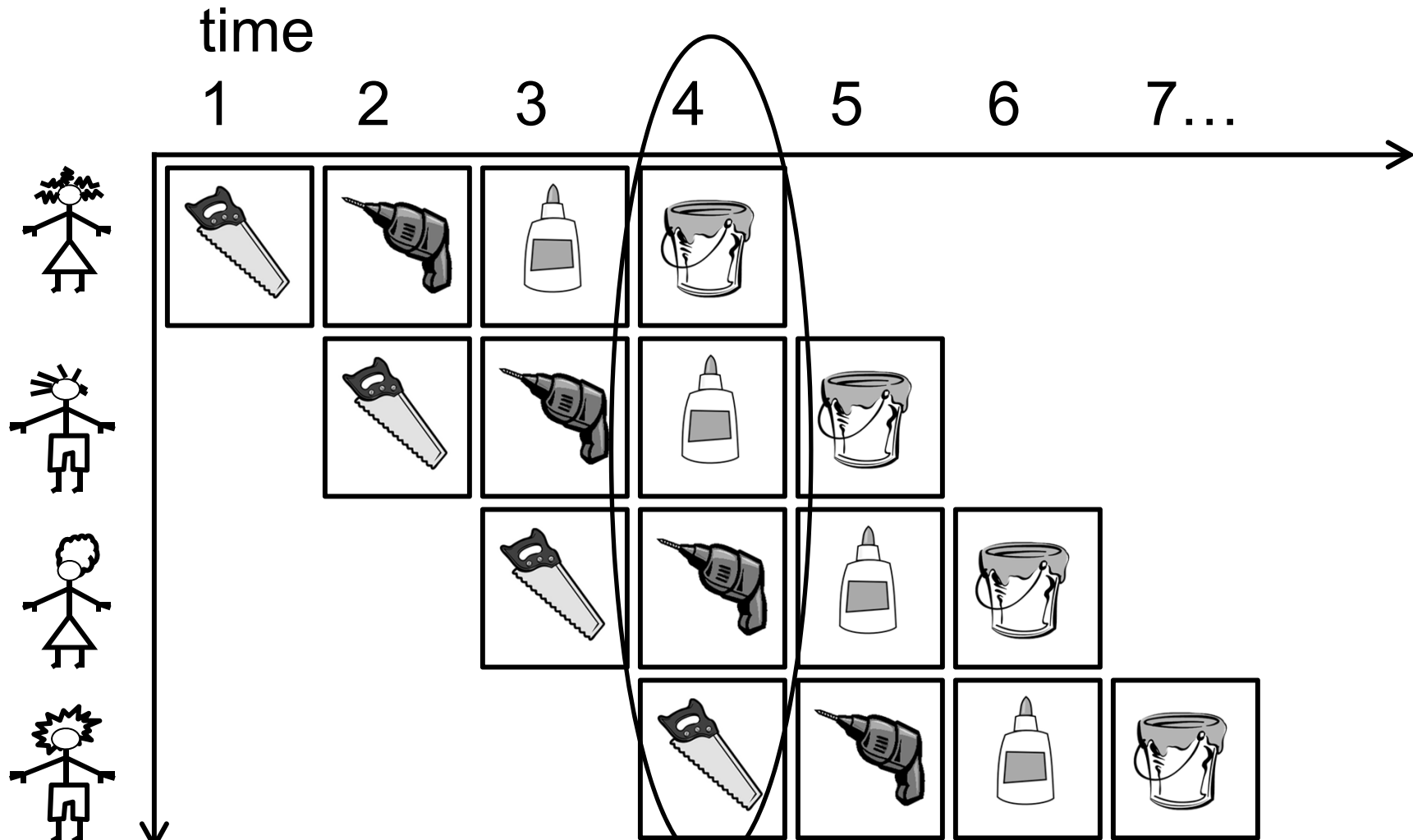
4 stages

4 people working simultaneously

Everyone moves right in lockstep

It still takes all four stages for one job to complete

# Pipelined Performance



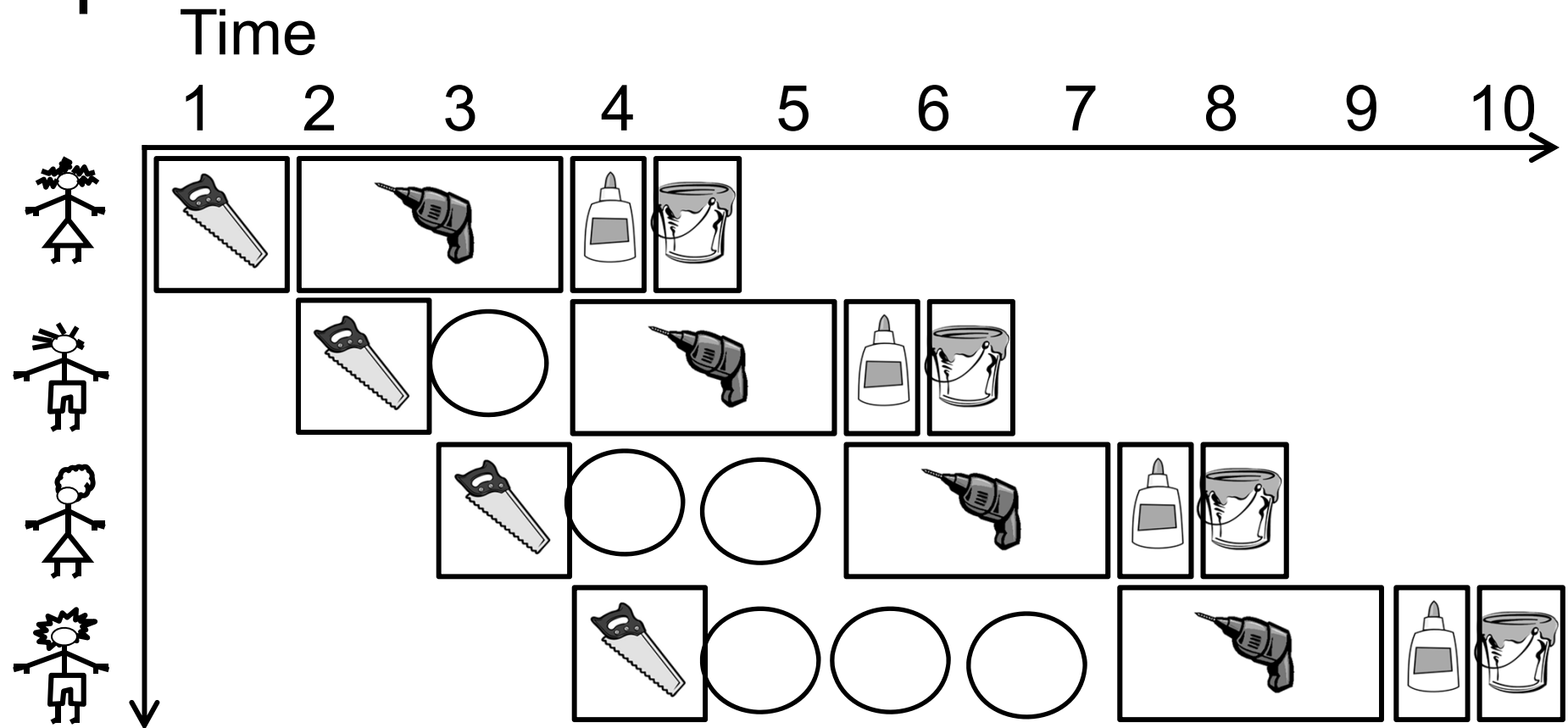
Latency: 4 hrs/task

Throughput: 1 task/hr

Concurrency: 4

CPI = 1

# Pipelined Performance



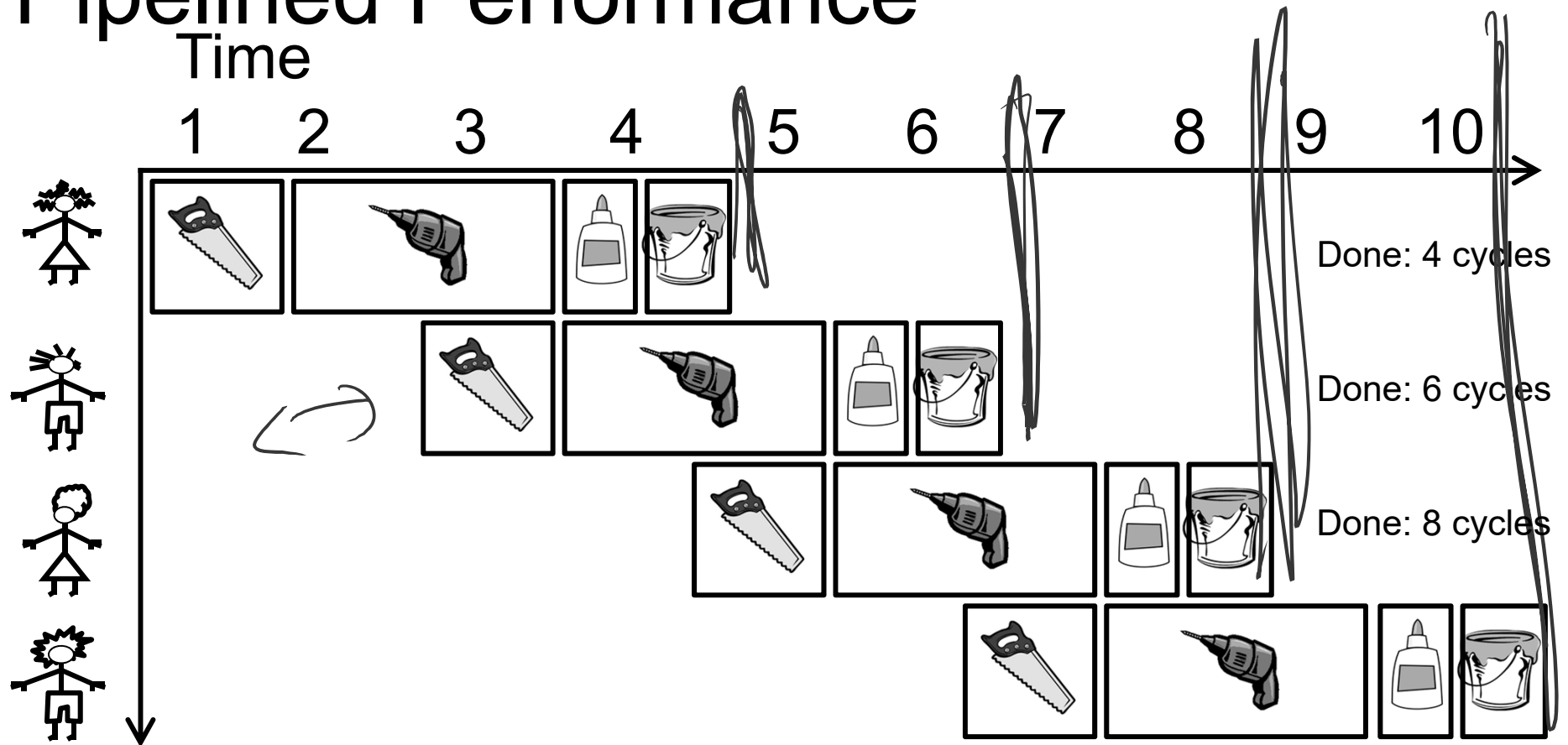
What if drilling takes twice as long, but gluing and paint take  $\frac{1}{2}$  as long?

Latency:

Throughput:

CPI =

# Pipelined Performance



What if drilling takes twice as long, but gluing and paint take  $\frac{1}{2}$  as long

Latency: 4 cycles/task

Throughput: 1 task/2 cycles      CPI = 2

# Lessons

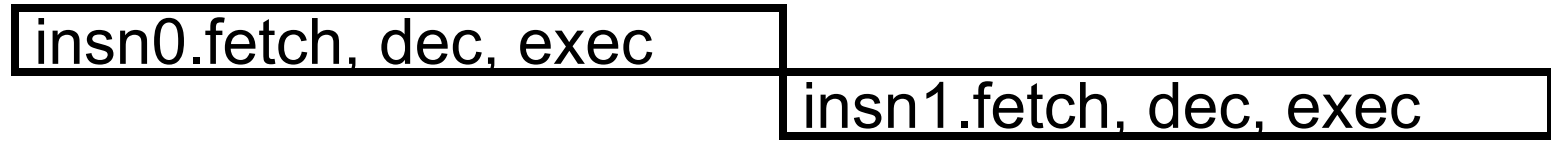
- Principle:
  - Throughput increased by parallel execution
  - Balanced pipeline very important
    - Else slowest stage dominates performance
- Pipelining:
  - Identify *pipeline stages*
  - Isolate stages from each other
  - Resolve pipeline *hazards* (next lecture)

# Single Cycle vs Pipelined Processor

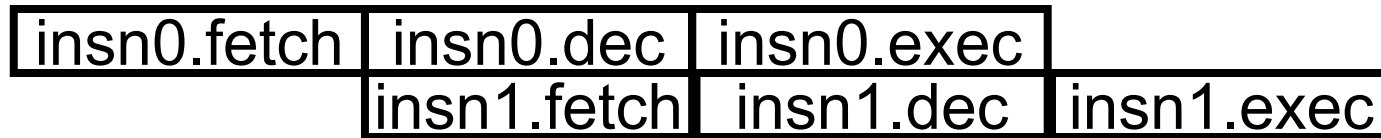


# Single Cycle → Pipelining

## Single-cycle

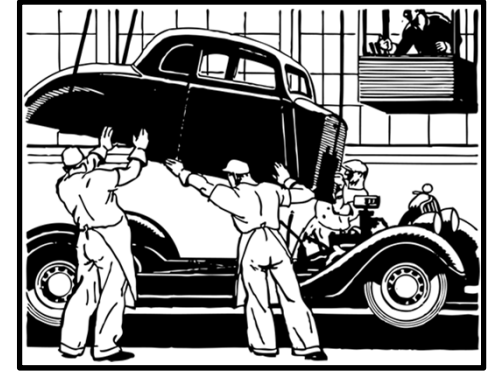
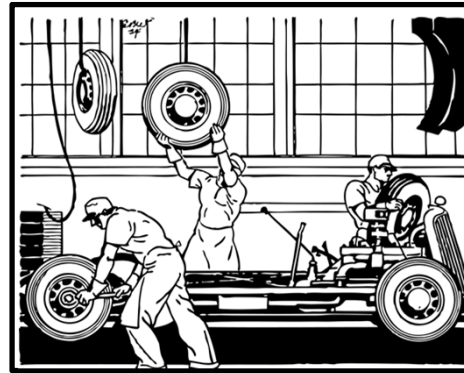


## Pipelined



# Agenda

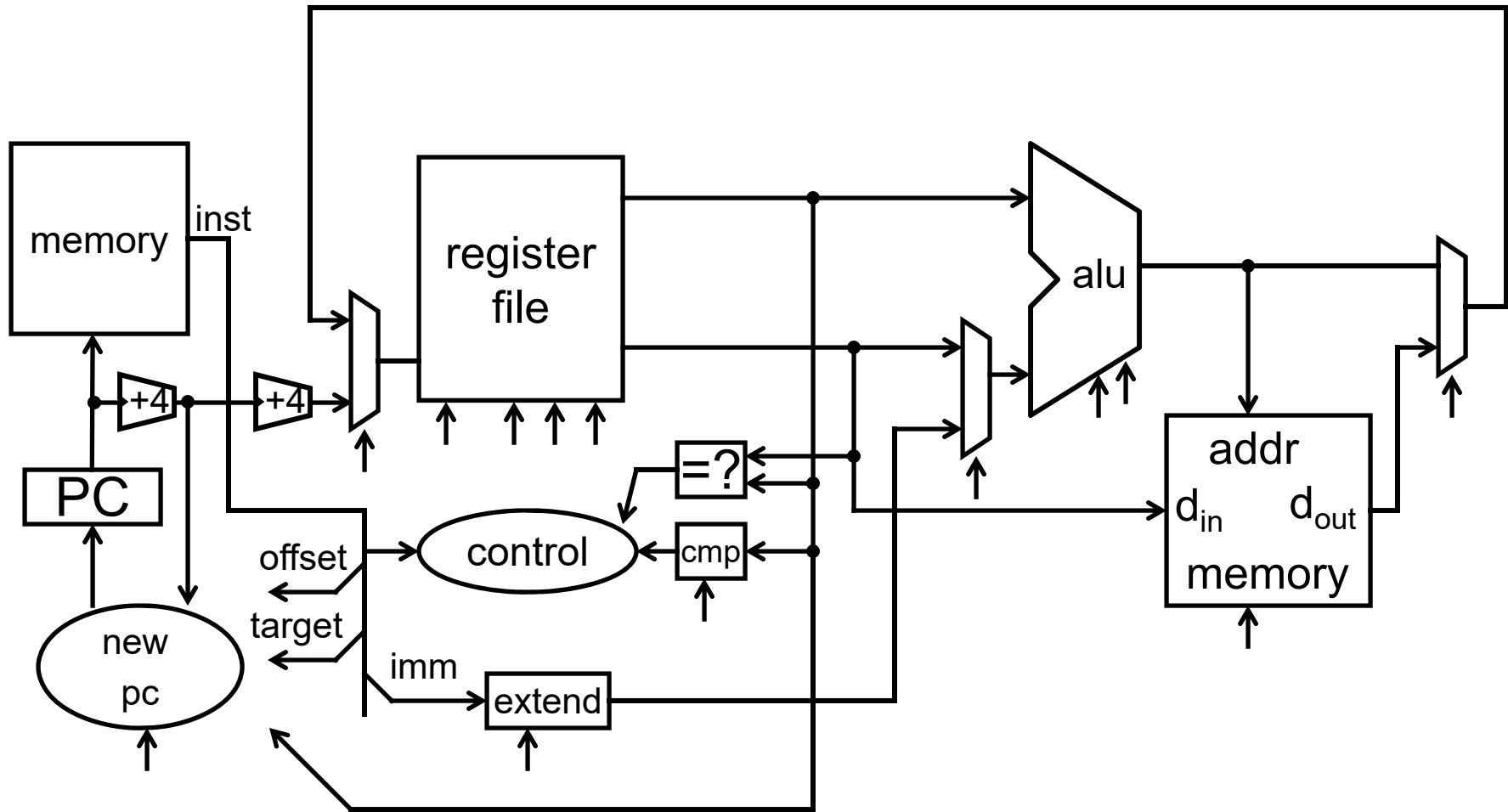
- 5-stage Pipeline
- Implementation
- Working Example



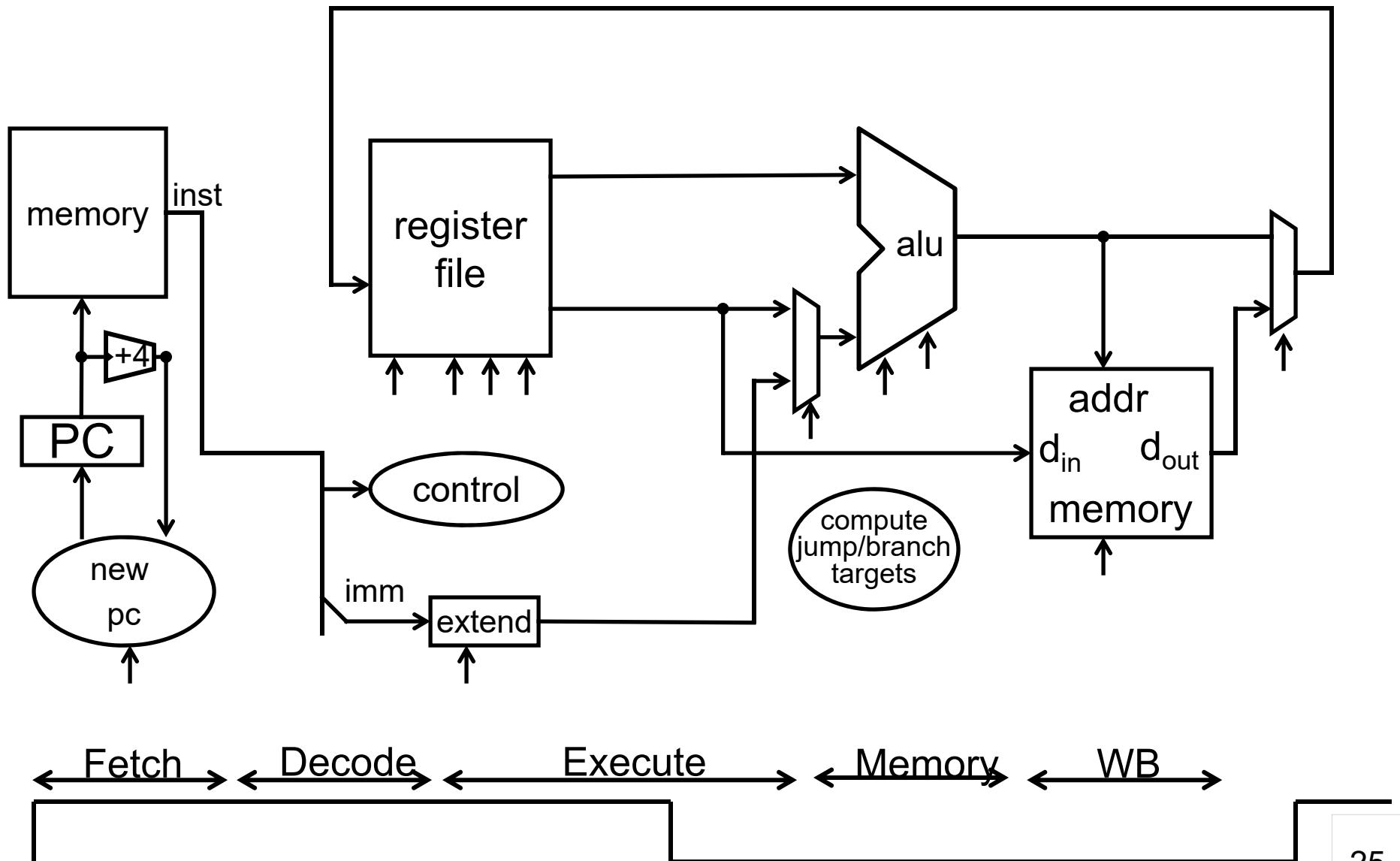
## Hazards

- Structural
- Data Hazards
- Control Hazards

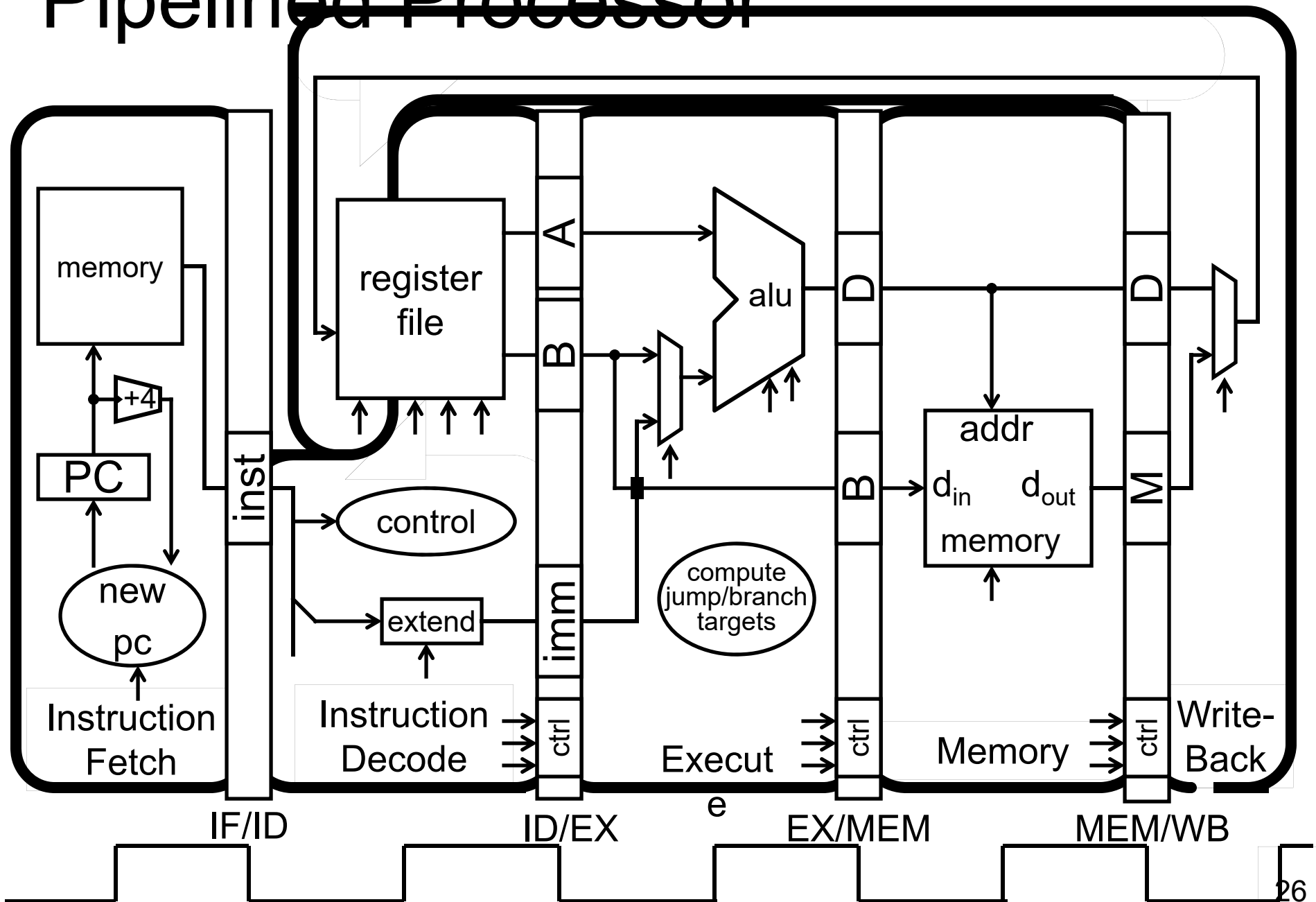
# Review: Single Cycle Processor



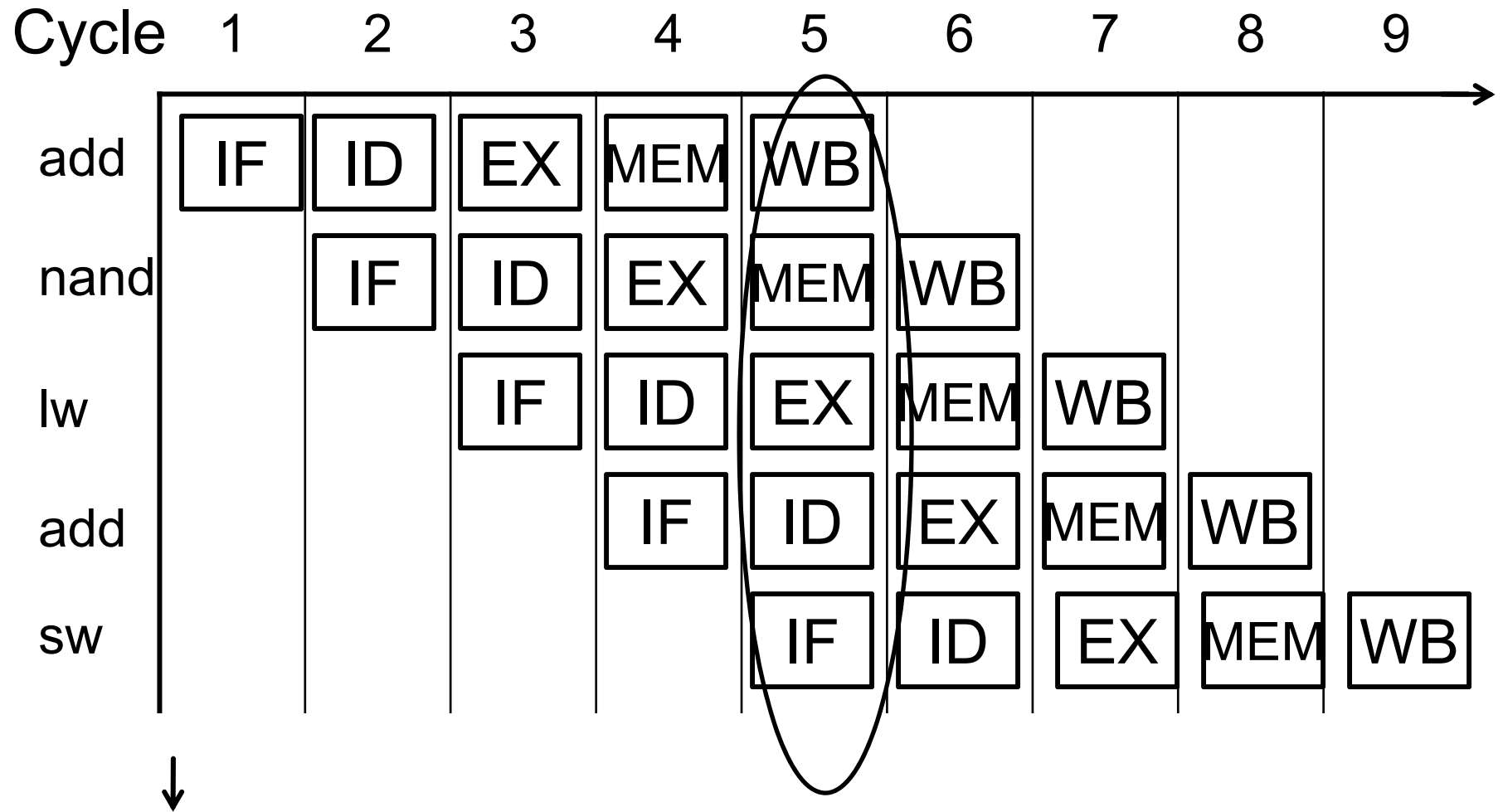
# Pipelined Processor



# Pipelined Processor



# Time Graphs



↓  
Latency:            5 cycles

Throughput:    1 insn/cycle

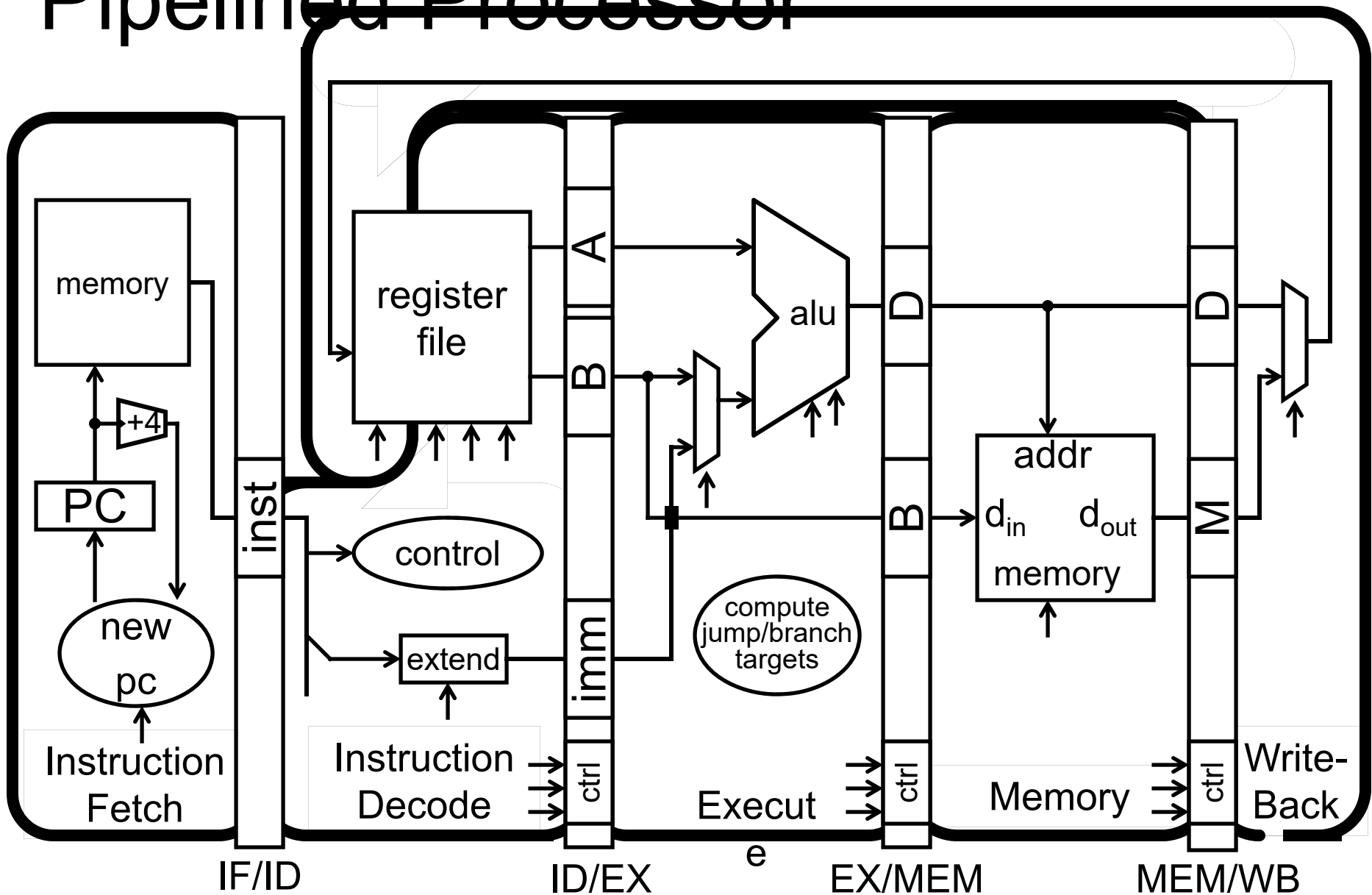
Concurrency: 5

CPI = 1

# Principles of Pipelined Implementation

- Break datapath into multiple cycles (here 5)
  - Parallel execution increases throughput
  - Balanced pipeline very important
    - Slowest stage determines clock rate
    - Imbalance kills performance
- Add pipeline registers (flip-flops) for isolation
  - Each stage begins by reading values *from* latch
  - Each stage ends by writing values *to* latch
- Resolve hazards

# Pipelined Processor



# Pipeline Stages

Stage	Perform Functionality	Latch values of interest
<b>Fetch</b>	Use PC to index Program Memory, increment PC	Instruction bits (to be decoded) PC + 4 (to compute branch targets)
<b>Decode</b>	Decode instruction, generate control signals, read register file	Control information, Rd index, immediates, offsets, register values (Ra, Rb), PC+4 (to compute branch targets)
<b>Execute</b>	Perform ALU operation Compute targets (PC+4+offset, etc.) in case this is a branch, decide if branch taken	Control information, Rd index, <i>etc.</i> Result of ALU operation, value in case this is a store instruction
<b>Memory</b>	Perform load/store if needed, address is ALU result	Control information, Rd index, <i>etc.</i> Result of load, pass result from execute
<b>Writeback</b>	Select value, write to register file	

# Instruction Fetch (IF)

## Stage 1: Instruction Fetch

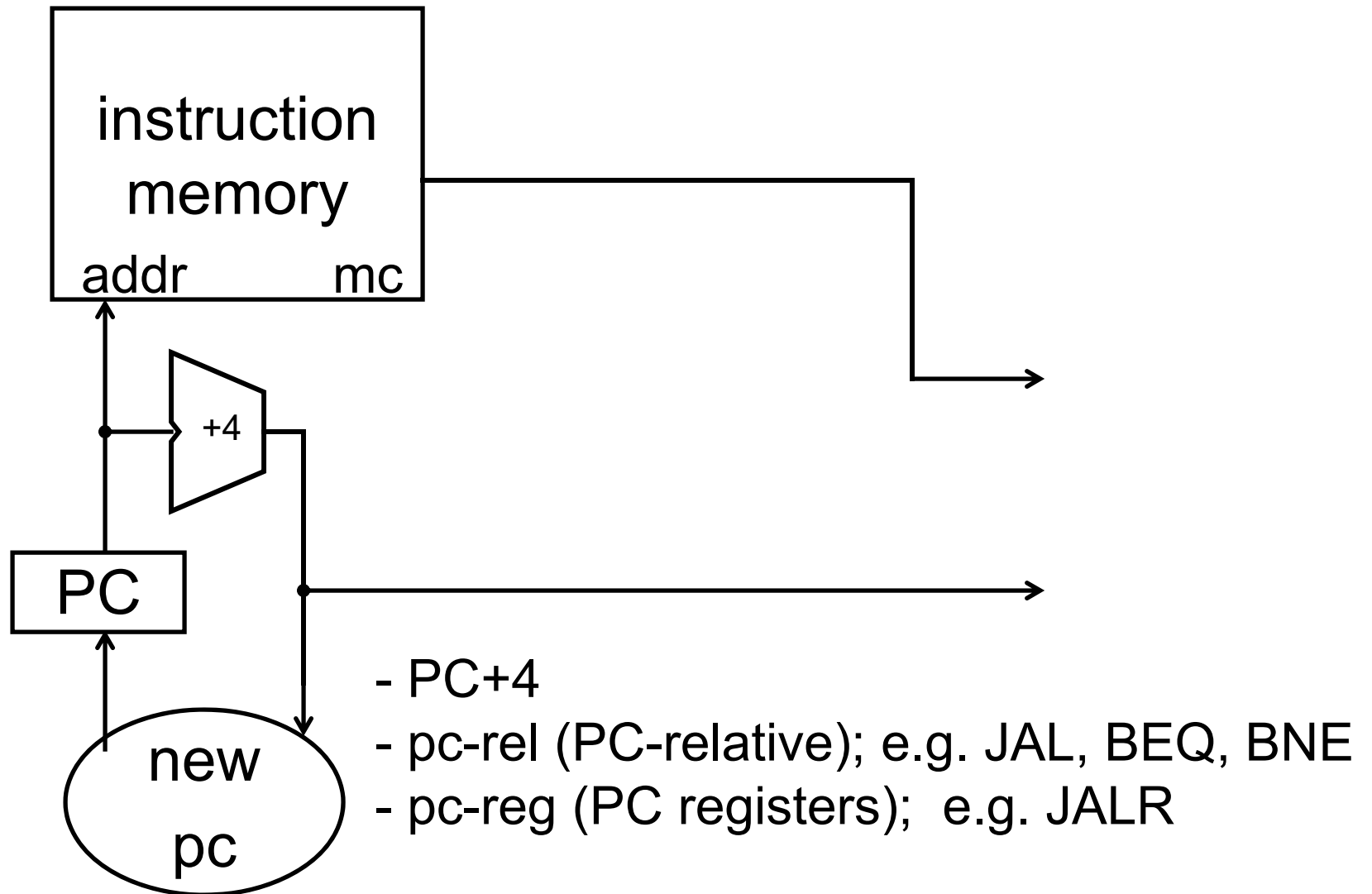
Fetch a new instruction every cycle

- Current PC is index to instruction memory
- Increment the PC at end of cycle (assume no branches for now)

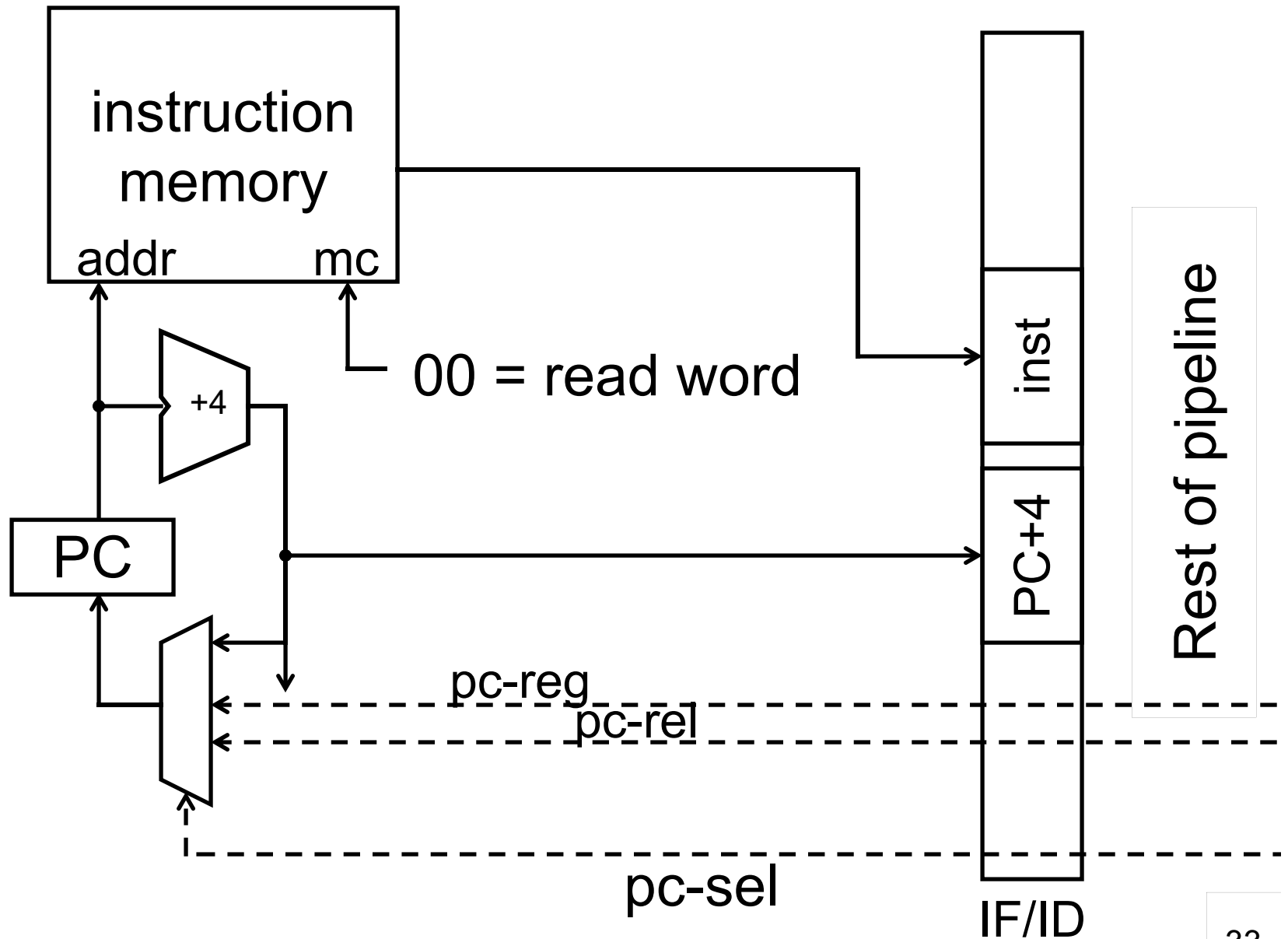
Write values of interest to pipeline register (IF/ID)

- Instruction bits (for later decoding)
- PC+4 (for later computing branch targets)

# Instruction Fetch (IF)



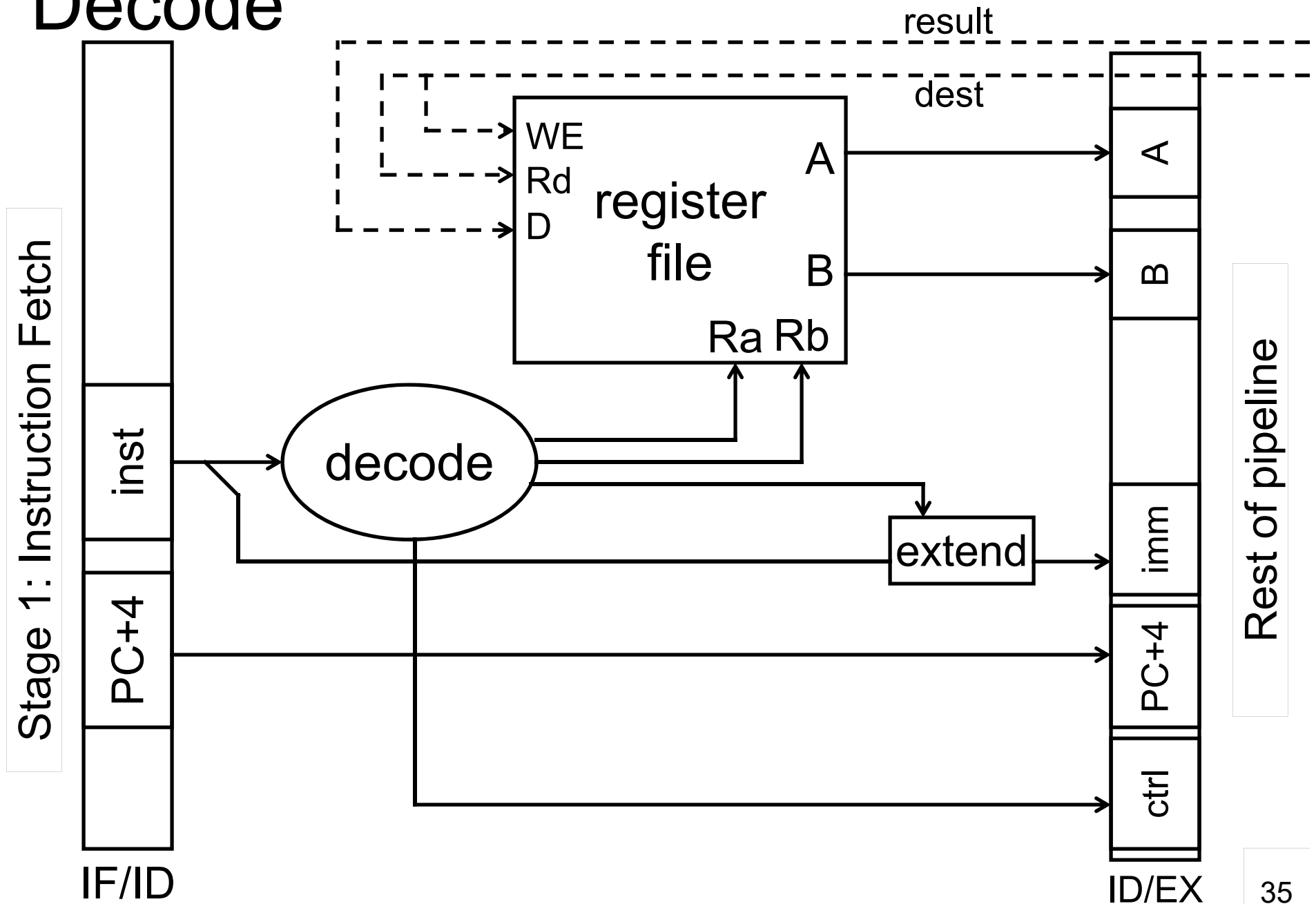
# Instruction Fetch (IF)



# Decode

- Stage 2: Instruction Decode
- On every cycle:
  - Read IF/ID pipeline register to get instruction bits
  - Decode instruction, generate control signals
  - Read from register file
- Write values of interest to pipeline register (ID/EX)
  - Control information, Rd index, immediates, offsets, ...
  - Contents of Ra, Rb
  - PC+4 (for computing branch targets later)

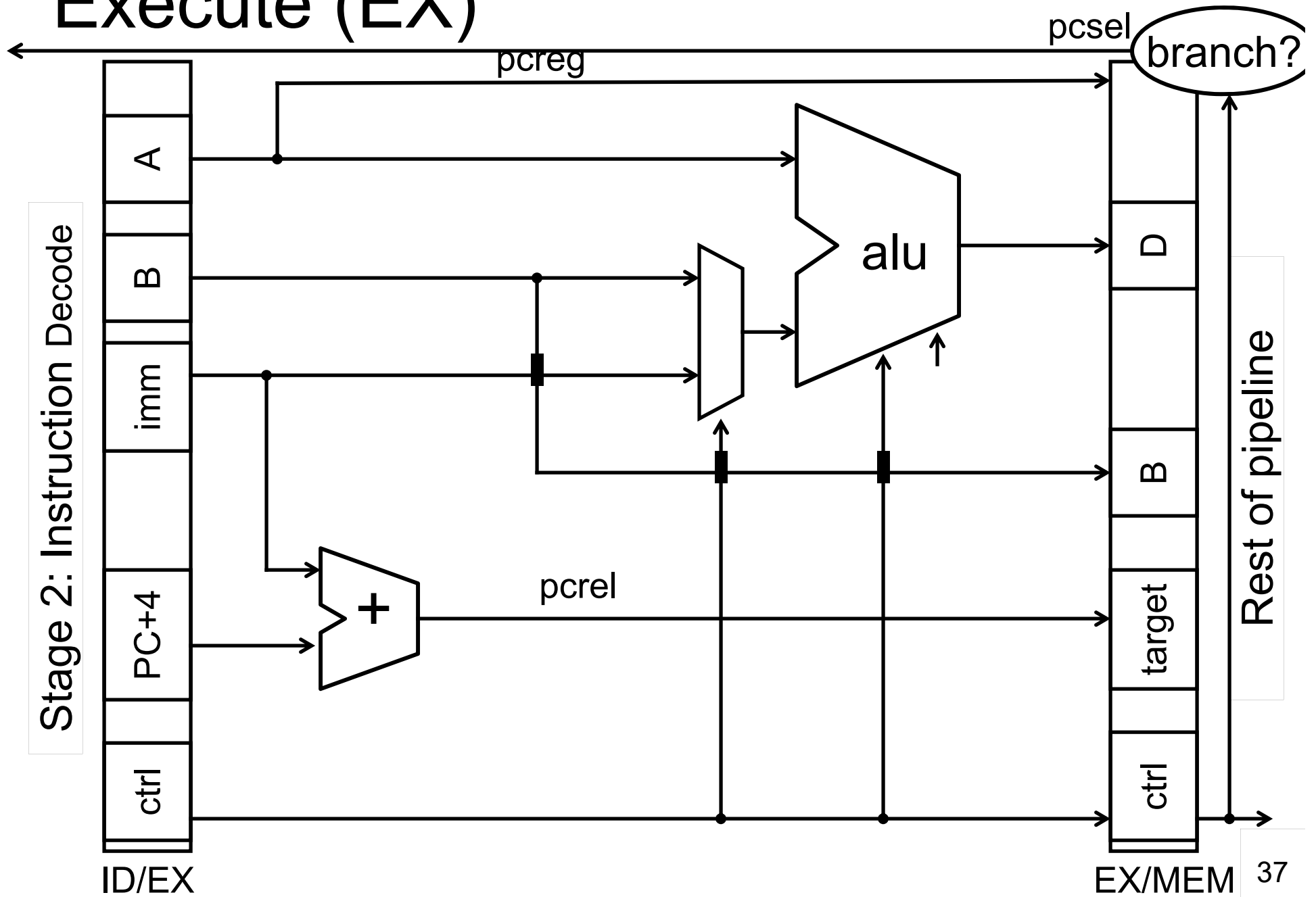
# Decode



# Execute (EX)

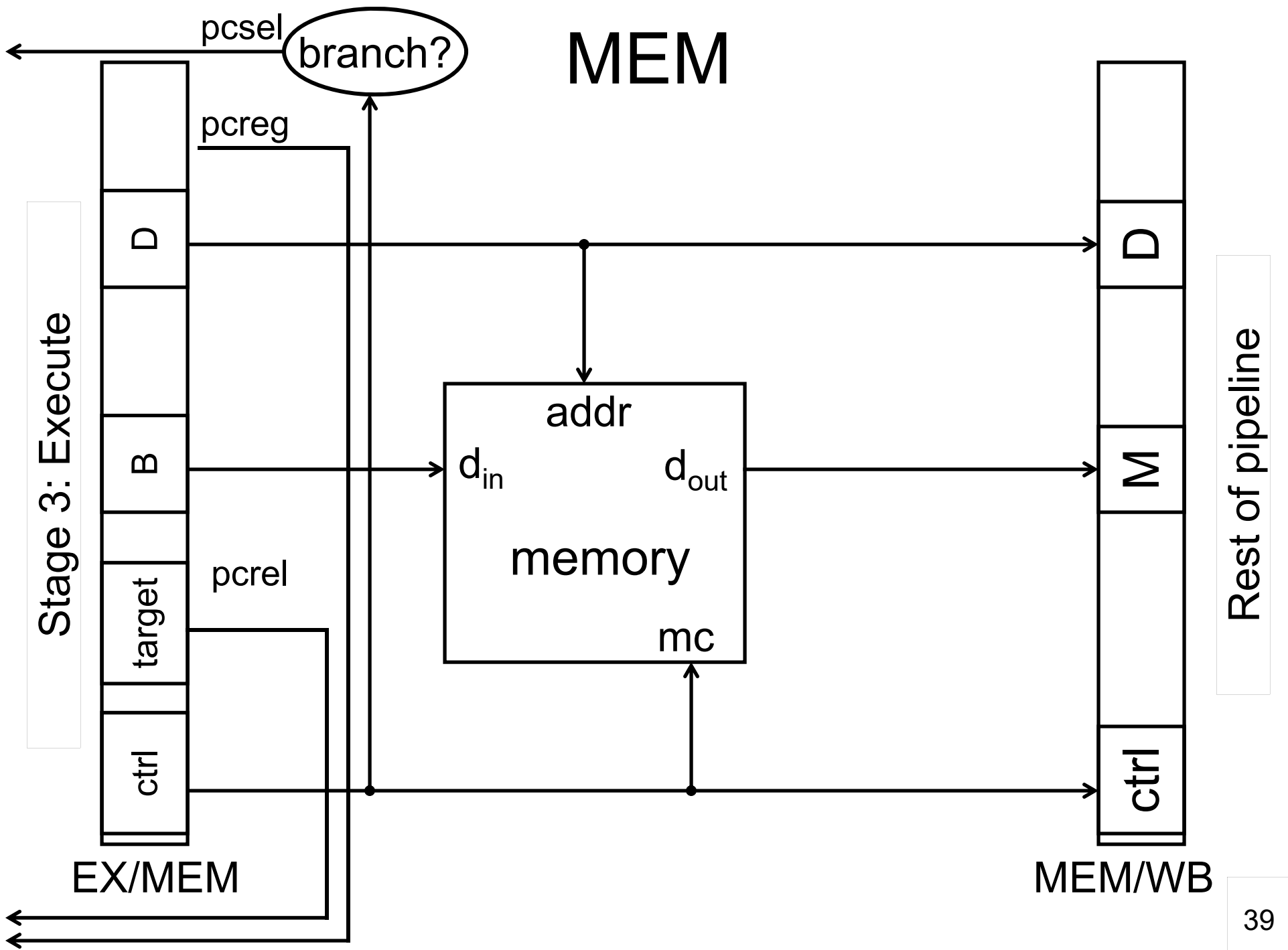
- Stage 3: Execute
- On every cycle:
  - Read ID/EX pipeline register to get values and control bits
  - Perform ALU operation
  - Compute targets (PC+4+offset, etc.) *in case* this is a branch
  - Decide if jump/branch should be taken
- Write values of interest to pipeline register (EX/MEM)
  - Control information, Rd index, ...
  - Result of ALU operation
  - Value *in case* this is a memory store instruction

# Execute (EX)



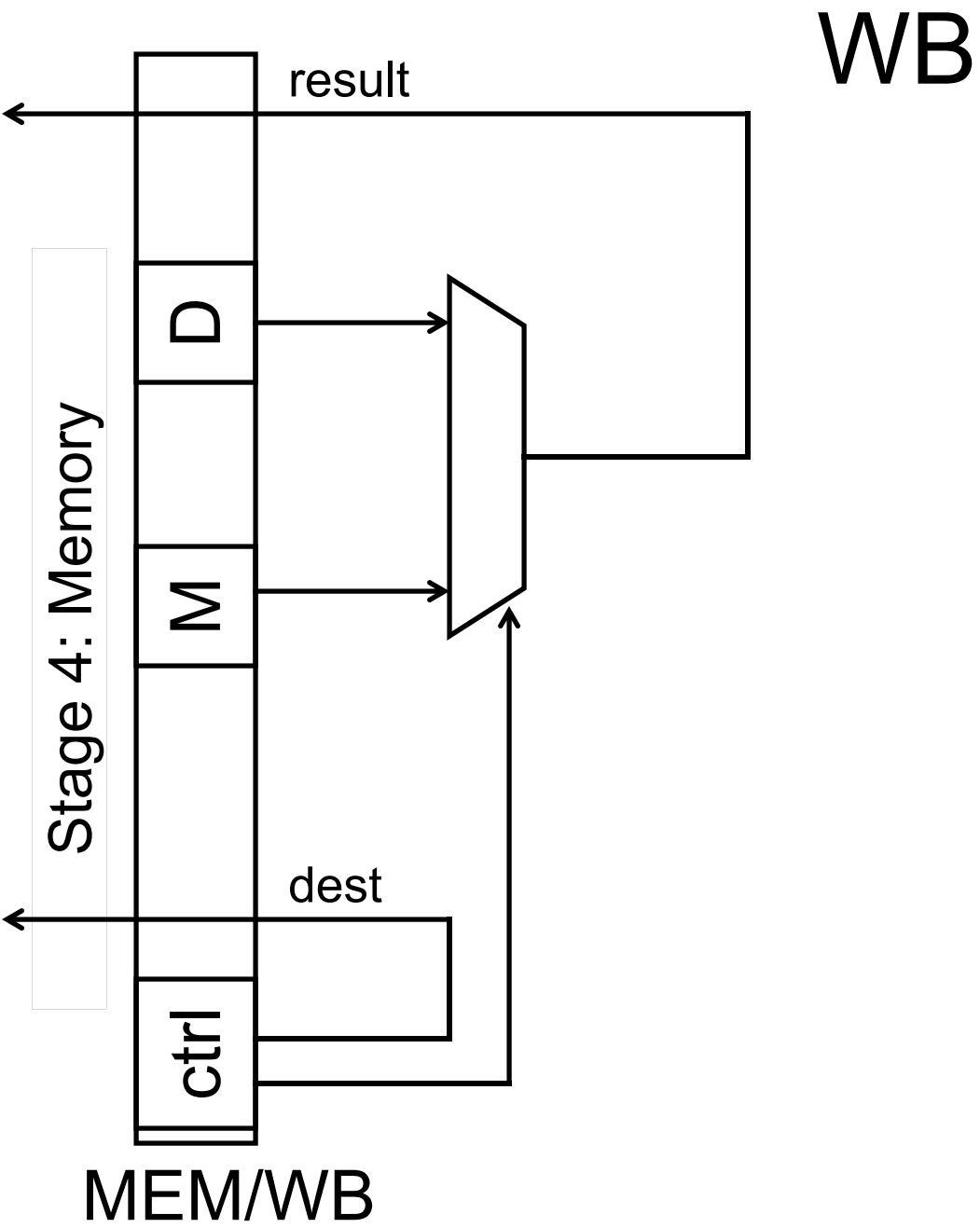
# MEM

- Stage 4: Memory
- On every cycle:
  - Read EX/MEM pipeline register to get values and control bits
  - Perform memory load/store if needed
    - address is ALU result
- Write values of interest to pipeline register (MEM/WB)
  - Control information, Rd index, ...
  - Result of memory operation
  - Pass result of ALU operation

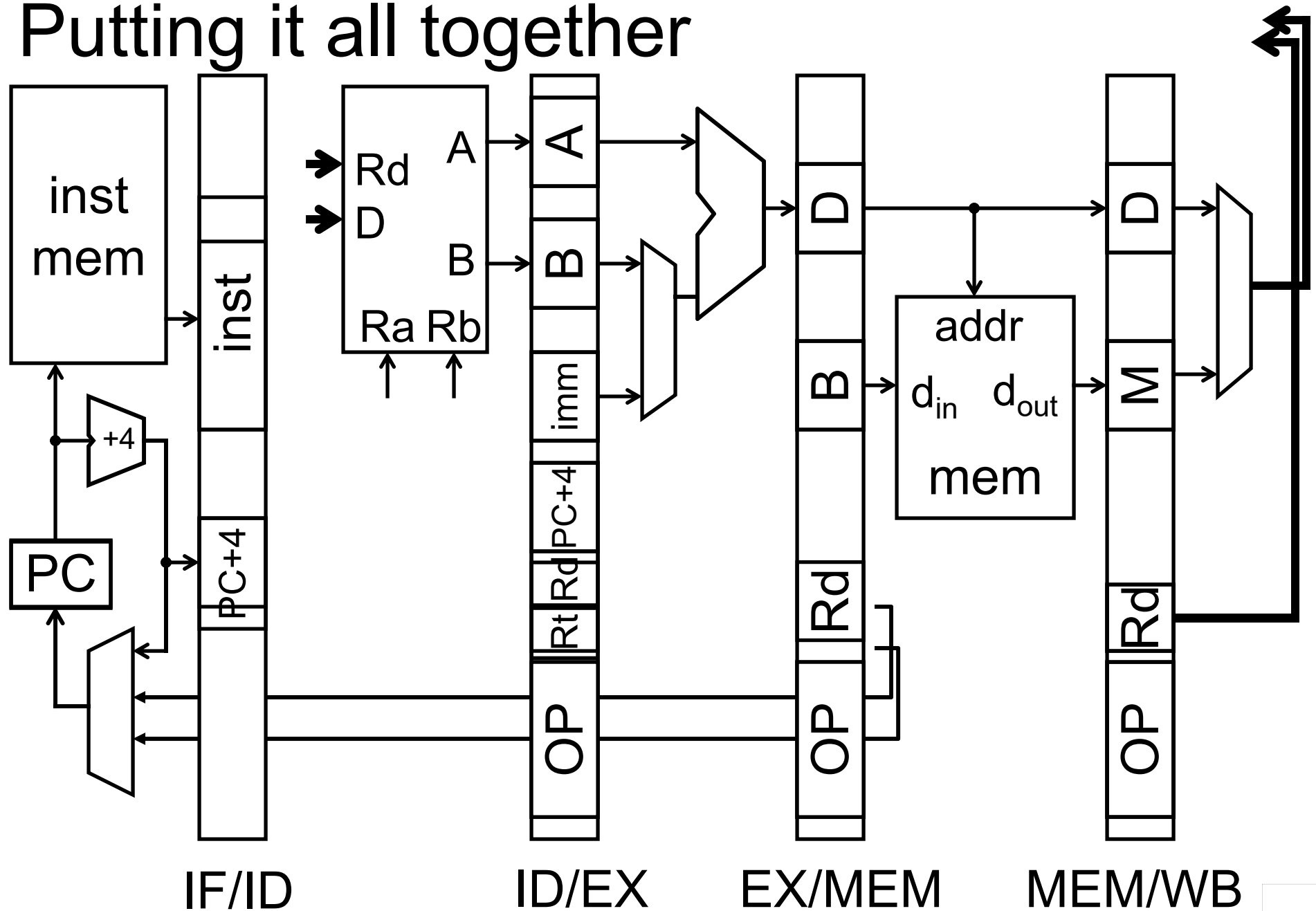


# WB

- Stage 5: Write-back
- On every cycle:
  - Read MEM/WB pipeline register to get values and control bits
  - Select value and write to register file



# Putting it all together



# iClicker Question

Consider a non-pipelined processor with clock period  $C$  (e.g., 50 ns). If you divide the processor into  $N$  stages (e.g., 5), your new clock period will be:

- A.  $C$
- B.  $N$
- C. less than  $C/N$
- D.  $C/N$
- E. greater than  $C/N$

# iClicker Question

Consider a non-pipelined processor with clock period  $C$  (e.g., 50 ns). If you divide the processor into  $N$  stages (e.g., 5), your new clock period will be:

A.  $C$

B.  $N$

C. less than  $C/N$

D.  $C/N$

E. greater than  $C/N$

# Takeaway

- Pipelining is a powerful technique to mask latencies and increase throughput
  - Logically, instructions execute one at a time
  - Physically, instructions execute in parallel
    - Instruction level parallelism
- Abstraction promotes decoupling
  - Interface (ISA) vs. implementation (Pipeline)



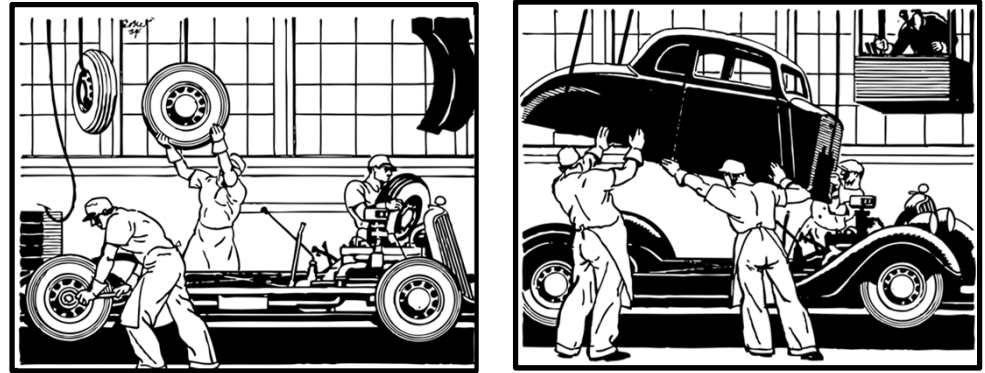
# RISC-V is *designed* for pipelining

- Instructions same length
  - 32 bits, easy to fetch and then decode
- 4 types of instruction formats
  - Easy to route bits between stages
  - Can read a register source before even knowing what the instruction is
- Memory access through lw and sw only
  - Access memory after ALU

# Agenda

## 5-stage Pipeline

- Implementation
- Working Example



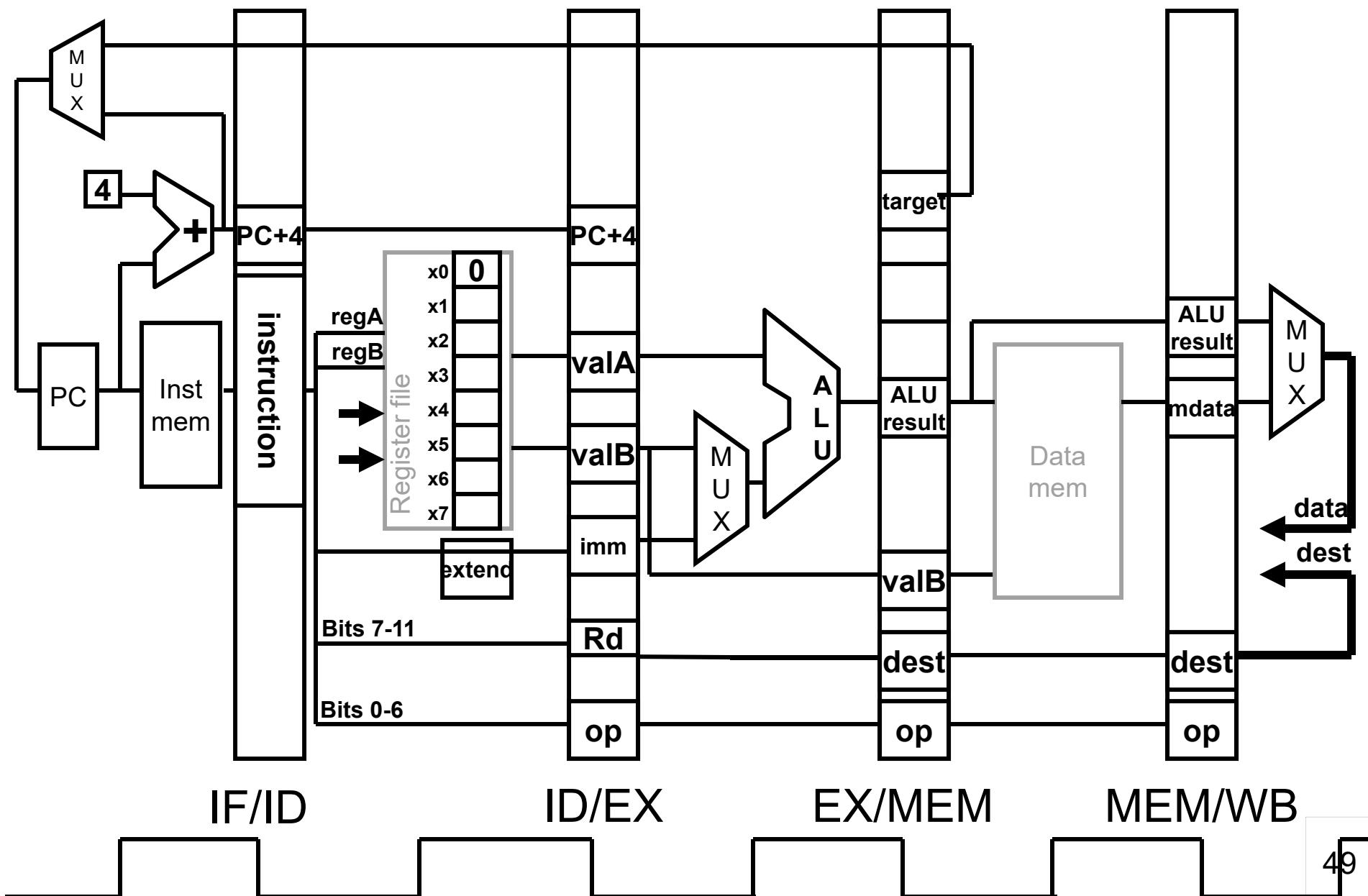
## Hazards

- Structural
- Data Hazards
- Control Hazards

## Example: Sample Code (Simple)

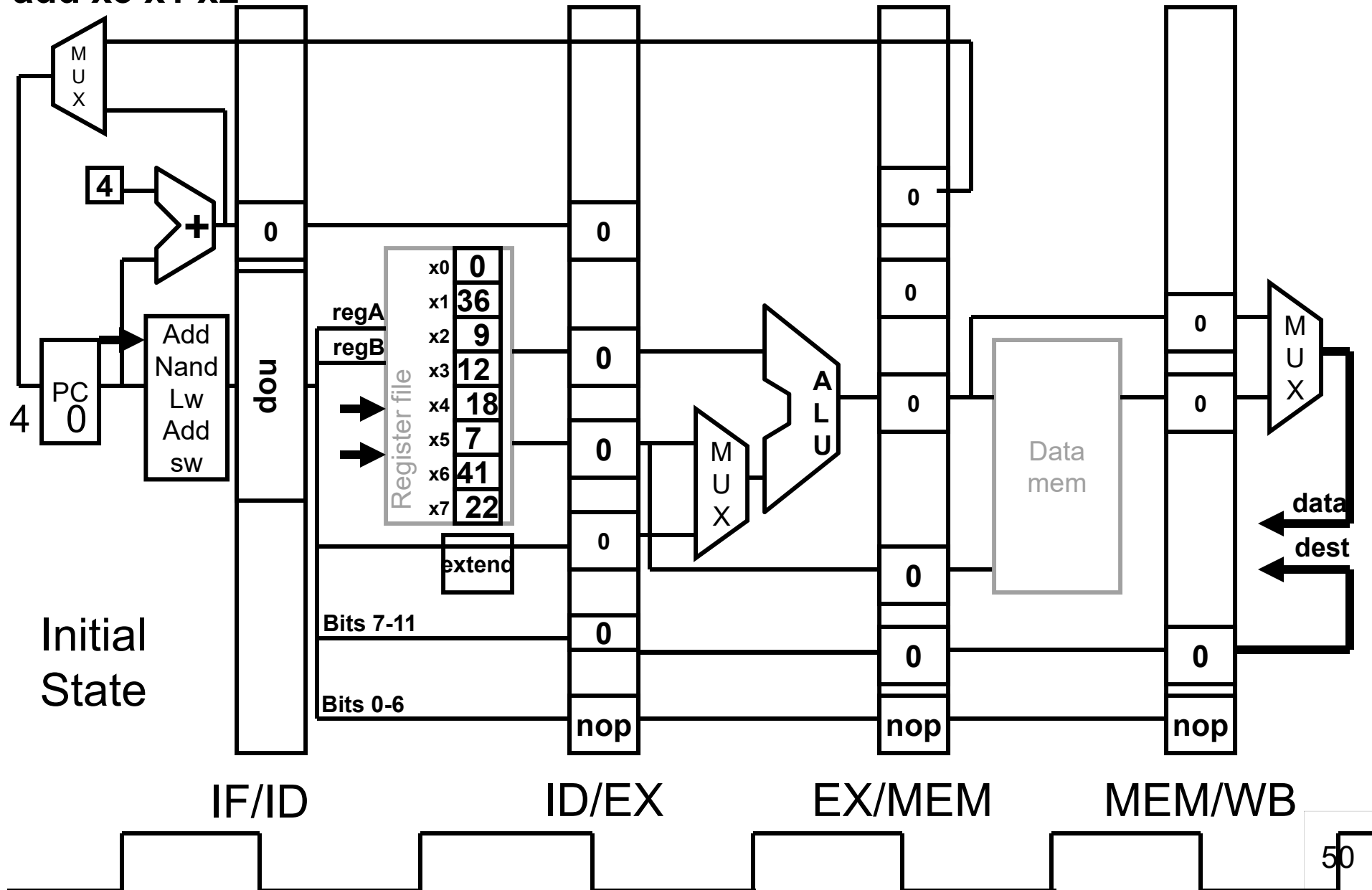
```
add    x3 ← x1, x2
nand   x6 ← x4, x5
lw     x4 ← x2, 20
add    x5 ← x2, x5
sw     x7 → x3, 12
```

Assume 8-register machine



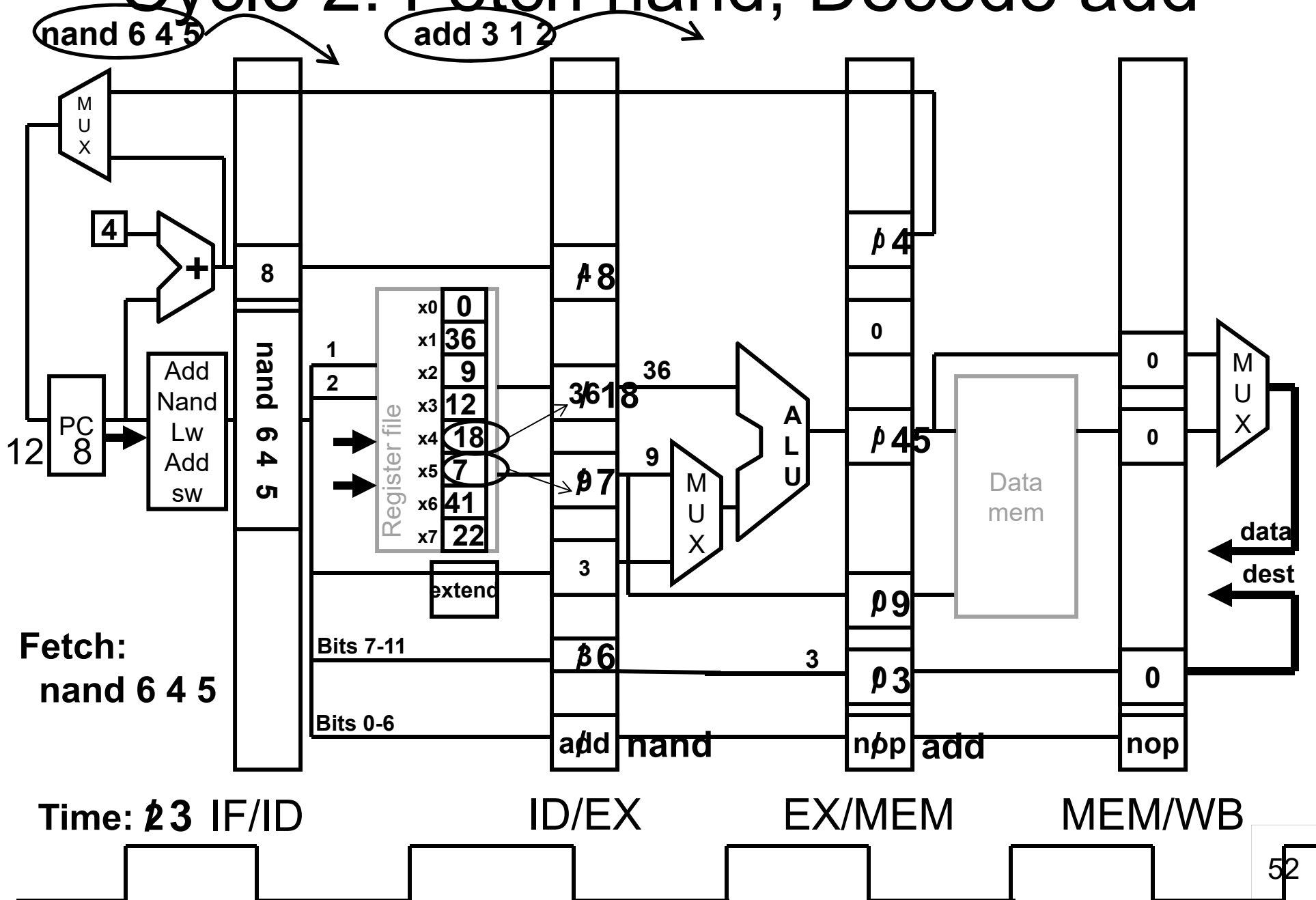
At time 1,  
Fetch  
add x3 x1 x2

# Example: Start State @ Cycle 0





# Cycle 2: Fetch nand, Decode add



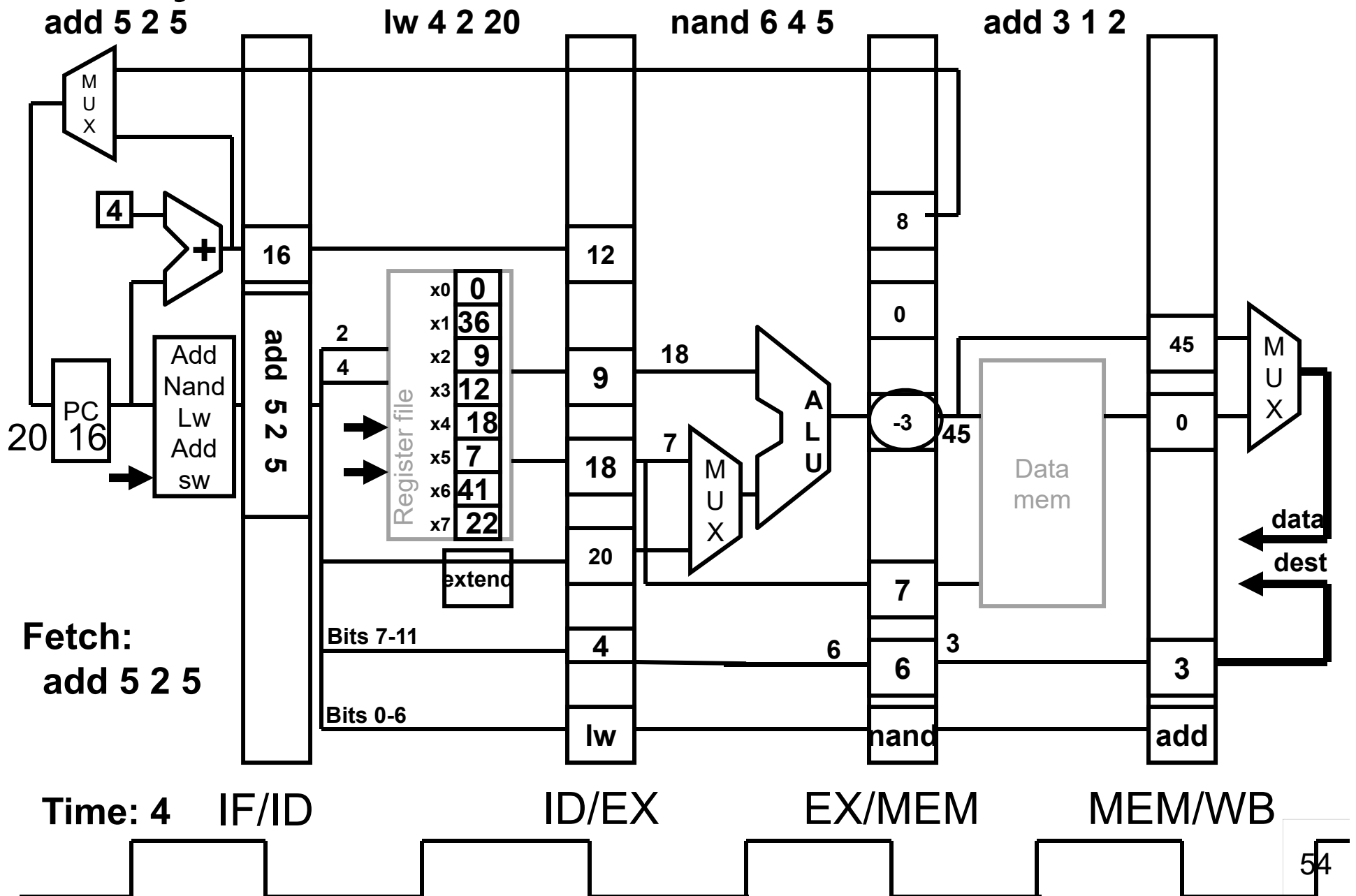
## lw 4 2 20

**nand 6 4 5**

**add 3 1 2**



# Cycle 4: Fetch add, Decode lw, ...



# Cycle 5: Fetch sw, Decode add, ...

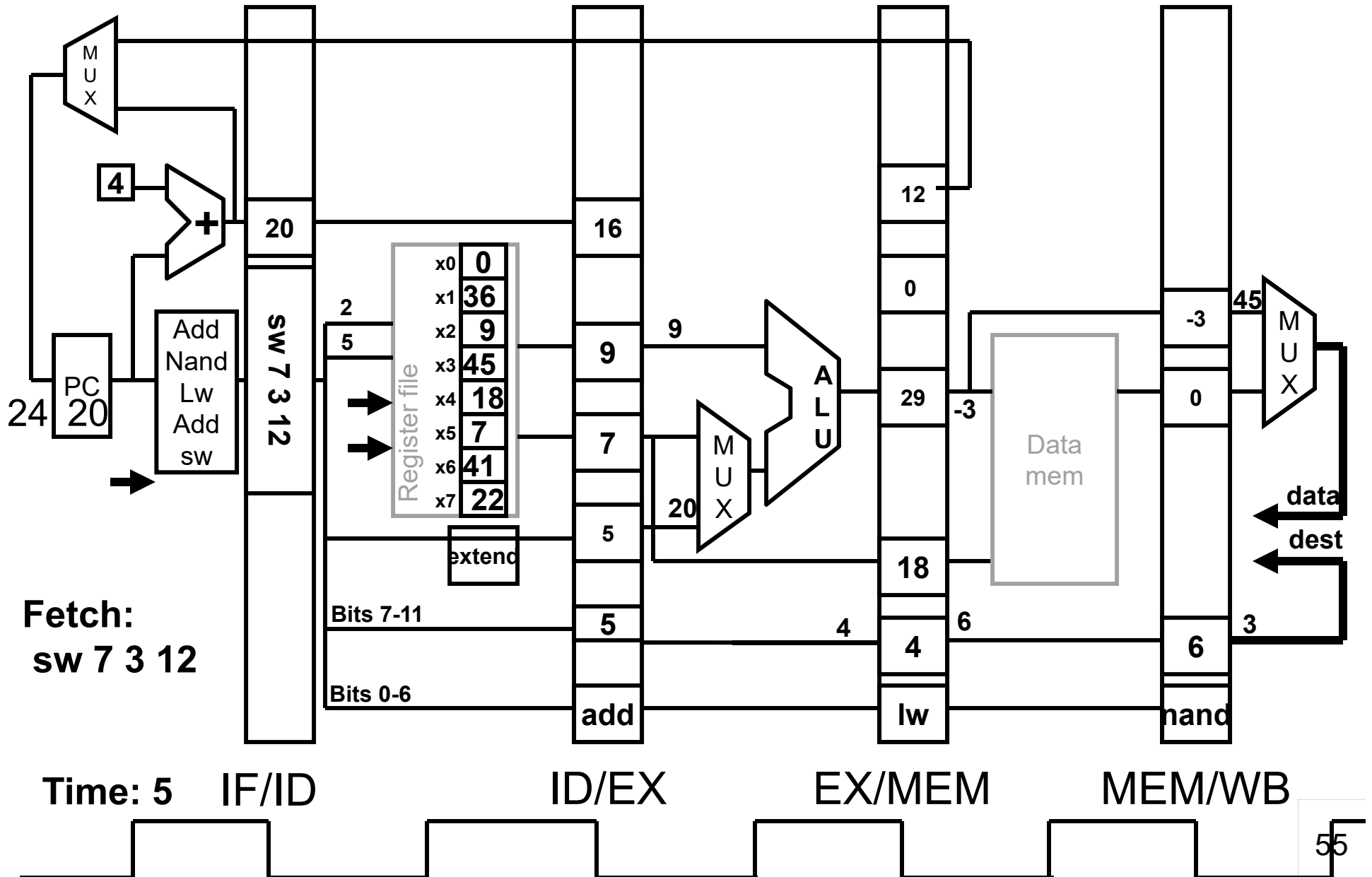
sw 7 3 12

add 5 2 5

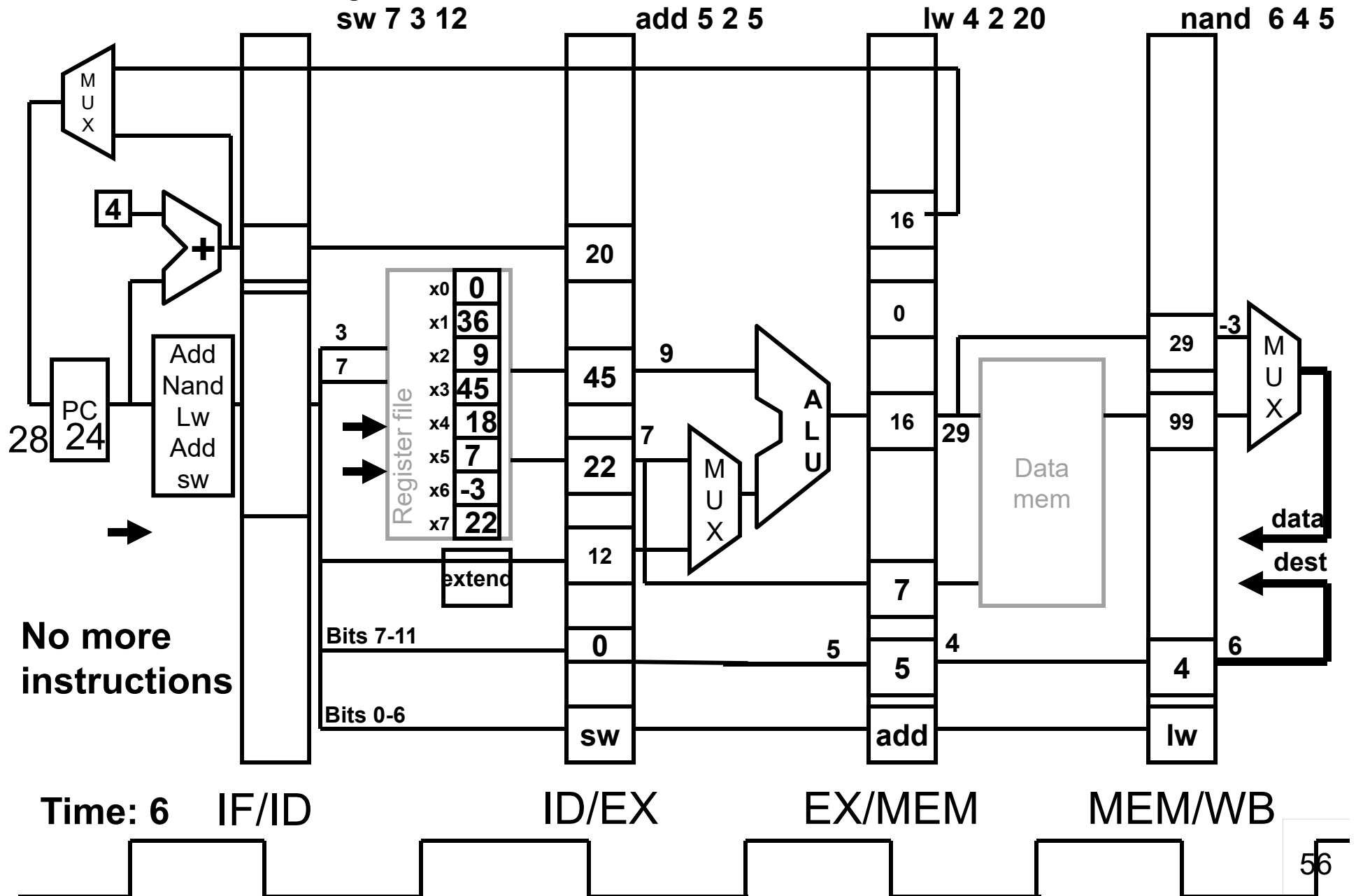
lw 4 20 (2)

nand 6 4 5

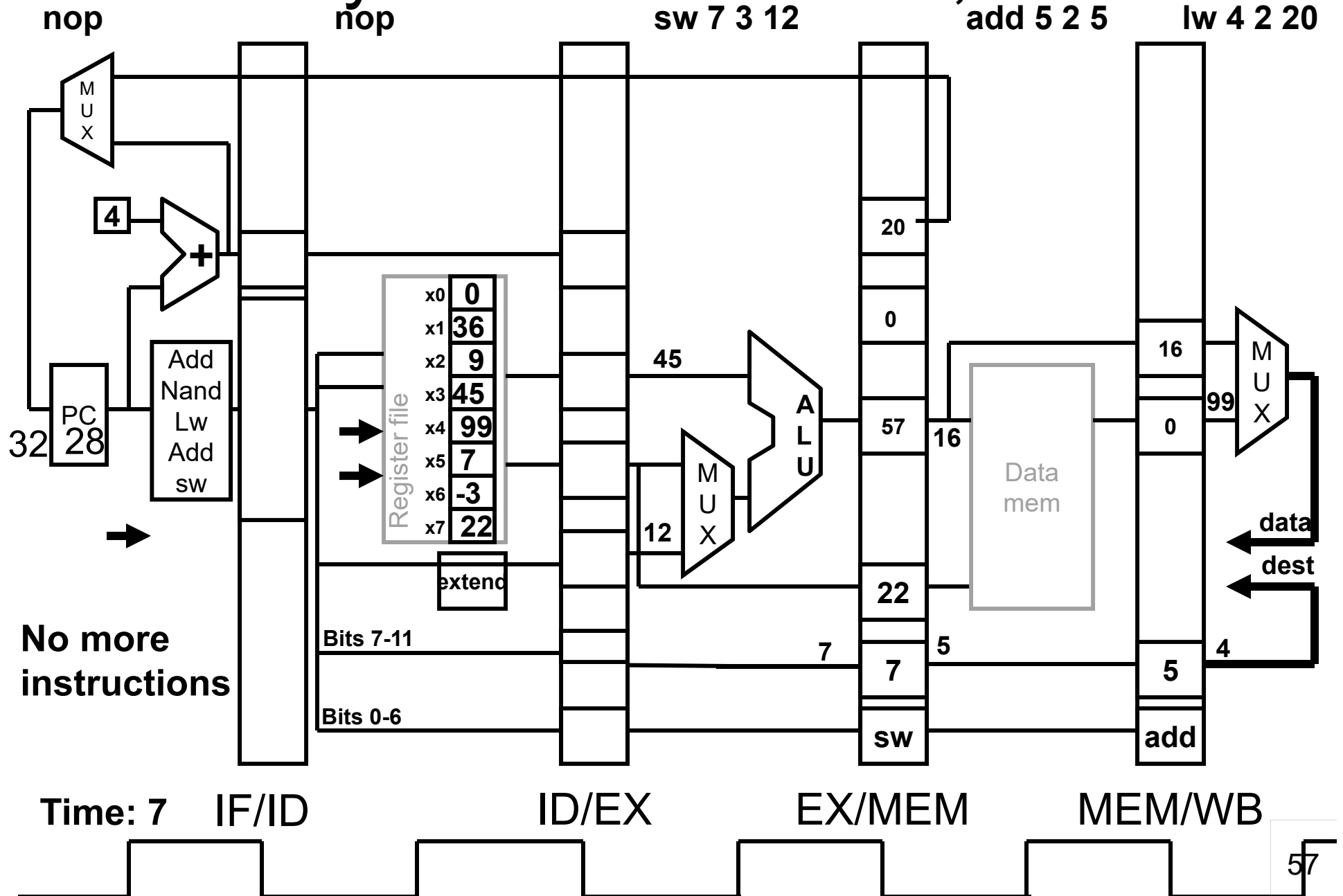
add 3 1 2



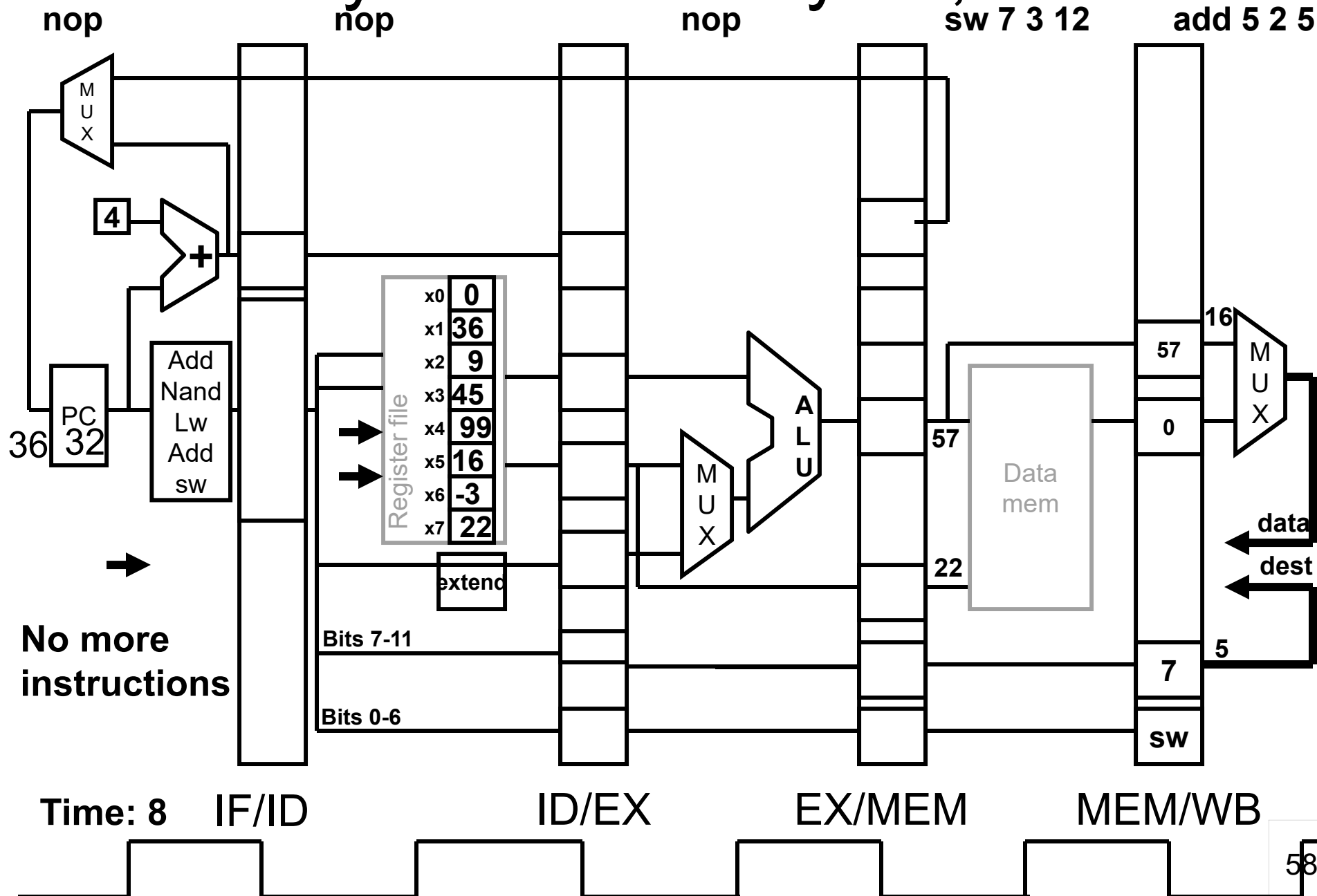
# Cycle 6: Decode sw, ...



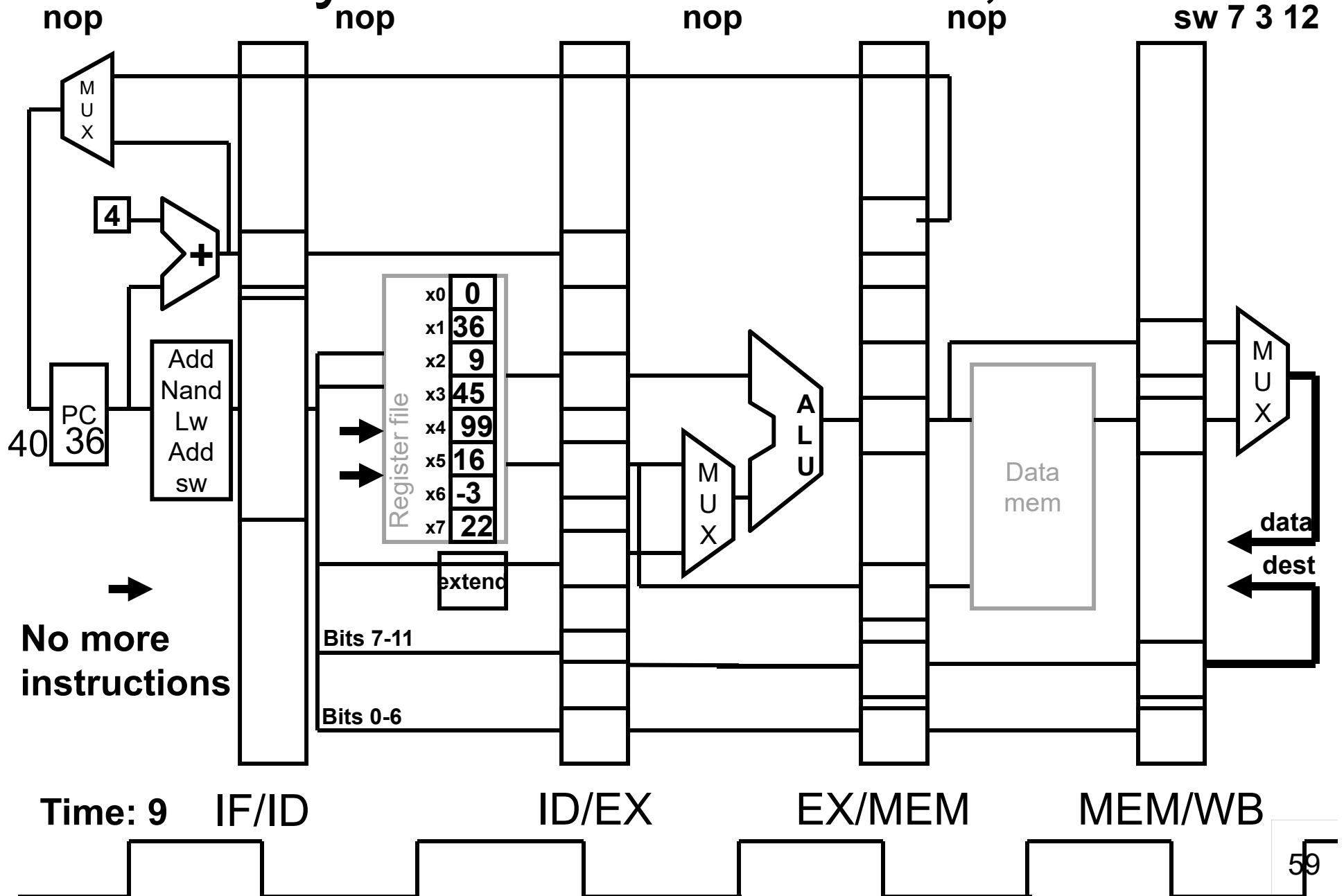
# Cycle 7: Execute sw, ...



# Cycle 8: Memory sw, ...



# Cycle 9: Writeback sw, ...



# iClicker Question

Pipelining is great because:

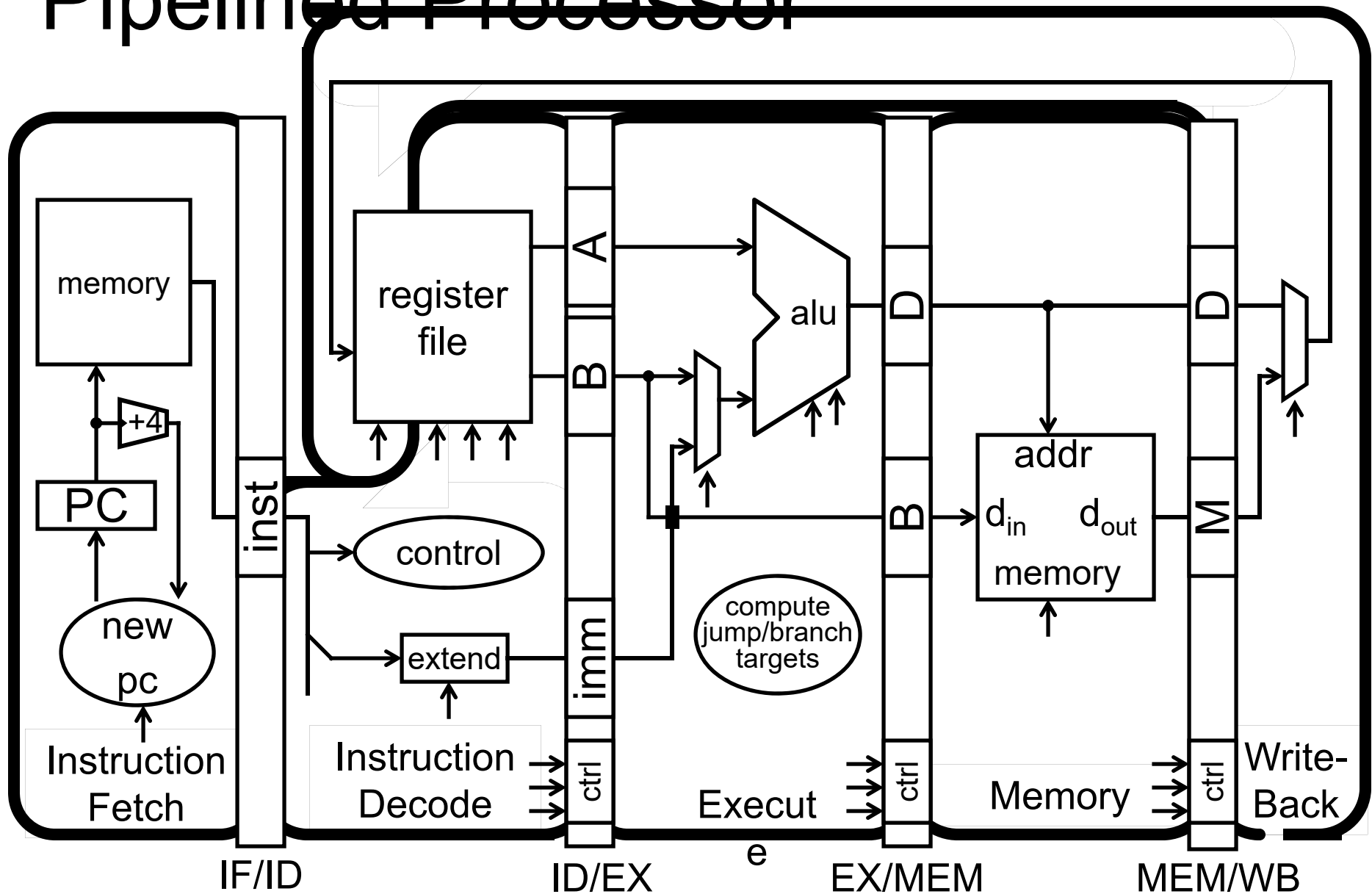
- A. You can fetch and decode the same instruction at the same time.
- B. You can fetch two instructions at the same time.
- C. You can fetch one instruction while decoding another.
- D. Instructions only need to visit the pipeline stages that they require.
- E. C and D

# iClicker Question

Pipelining is great because:

- A. You can fetch and decode the same instruction at the same time.
- B. You can fetch two instructions at the same time.
- C. You can fetch one instruction while decoding another.
- D. Instructions only need to visit the pipeline stages that they require.
- E. C and D

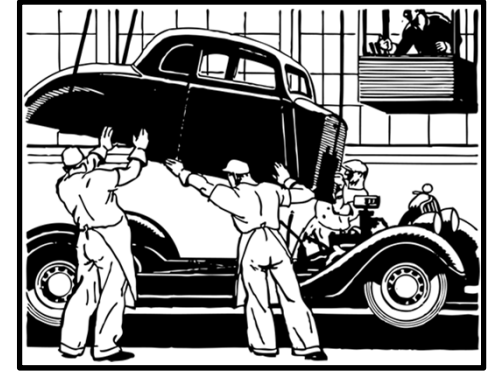
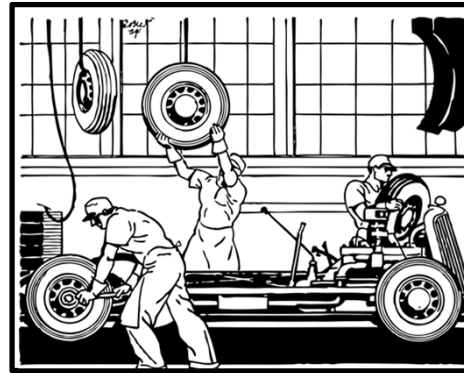
# Pipelined Processor



# Agenda

## 5-stage Pipeline

- Implementation
- Working Example



## Hazards

- Structural
- Data Hazards
- Control Hazards

# Hazards

Correctness problems associated w/ processor design

1. Structural hazards

Same resource needed for different purposes at the same time (Possible: ALU, Register File, Memory)

2. Data hazards

Instruction output needed before it's available

3. Control hazards

Next instruction PC unknown at time of Fetch

# Dependences and Hazards

**Dependence:** relationship between two insns

- **Data:** two insns use same storage location
- **Control:** 1 insn affects whether another executes at all
- *Not a bad thing*, programs would be boring otherwise
- Enforced by making older insn go before younger one
  - Happens naturally in single-/multi-cycle designs
  - But not in a pipeline

**Hazard:** dependence & possibility of wrong insn order

- Effects of wrong insn order cannot be externally visible
- *Hazards are a bad thing:* most solutions either complicate the hardware or reduce performance

# iClicker Question

## Data Hazards

- register file (RF) reads occur in stage 2 (ID)
- RF writes occur in stage 5 (WB)
- RF written in  $\frac{1}{2}$  half, read in second  $\frac{1}{2}$  half of cycle

x10:      add x3  $\leftarrow$  x1, x2

x14:      sub x5  $\leftarrow$  x3, x4

1. Is there a dependence?

2. Is there a hazard?

A) Yes

B) No

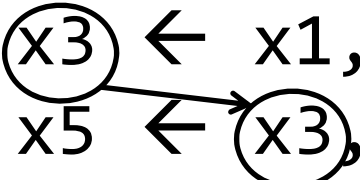
C) Cannot tell with the information given.

# iClicker Question

## Data Hazards

- register file (RF) reads occur in stage 2 (ID)
- RF writes occur in stage 5 (WB)
- RF written in 1/2 half, read in second 1/2 half of cycle

x10:      add (x3) ← x1, x2  
x14:      sub x5 ← (x3), x4



1. Is there a dependence?

2. Is there a hazard?

- ☒ A) Yes for both  
☐ B) No  
☐ C) Cannot tell with the information given.

# iClicker Follow-up

Which of the following statements is true?

- A. Whether there is a data dependence between two instructions depends on the machine the program is running on.
- B. Whether there is a data hazard between two instructions depends on the machine the program is running on.
- C. Both A & B
- D. Neither A nor B

# iClicker Follow-up

Which of the following statements is true?

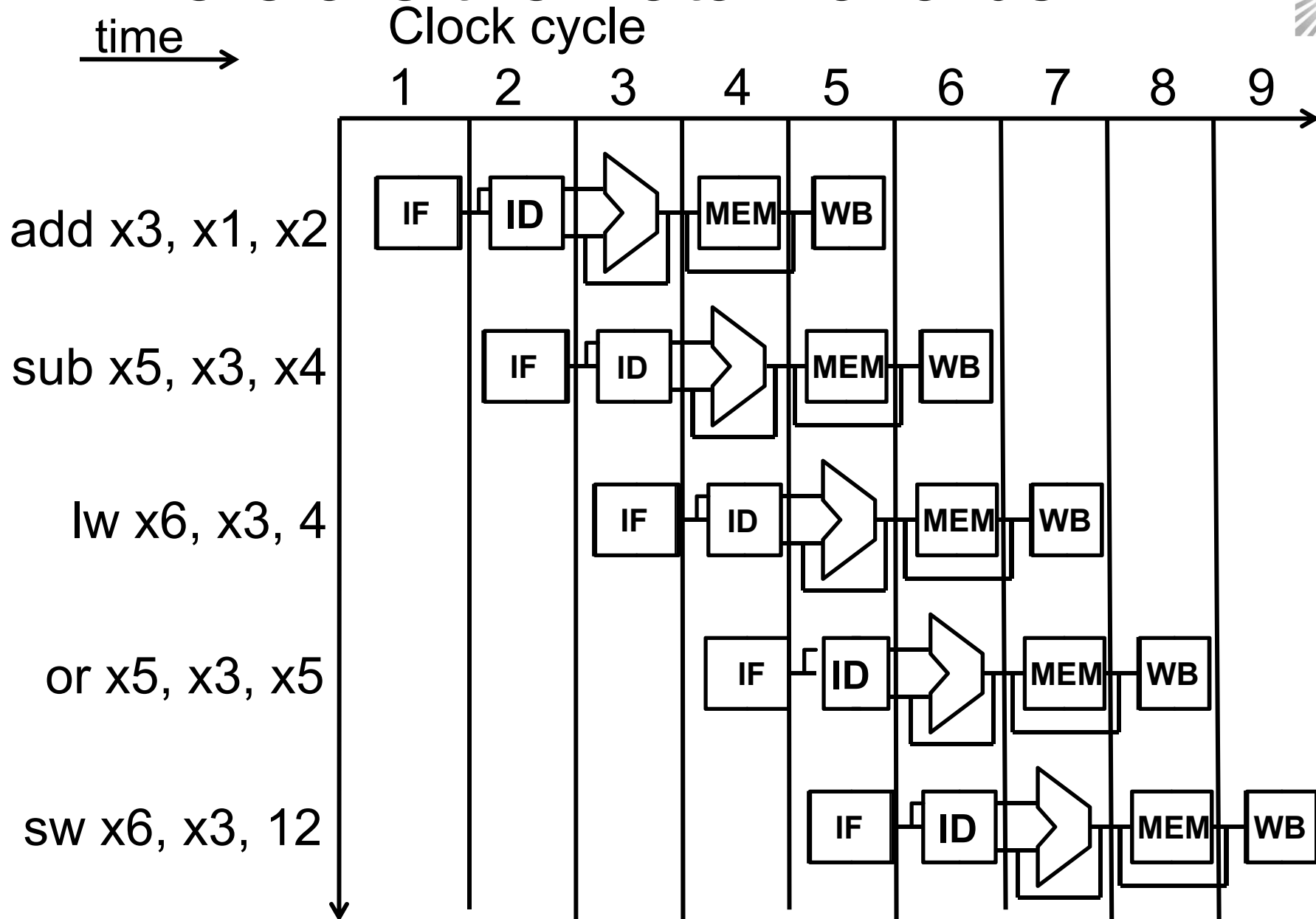
A. Whether there is a data dependence between two instructions depends on the machine the program is running on.

B. Whether there is a data hazard between two instructions depends on the machine the program is running on.

C. Both A & B

D. Neither A nor B

# Where are the Data Hazards?



# iClicker

How many data hazards due to x3 only

add x3, x1, x2

sub x5, x3, x4

lw x6, x3, 4

or x5, x3, x5

sw x6, x3, 12

A) 1

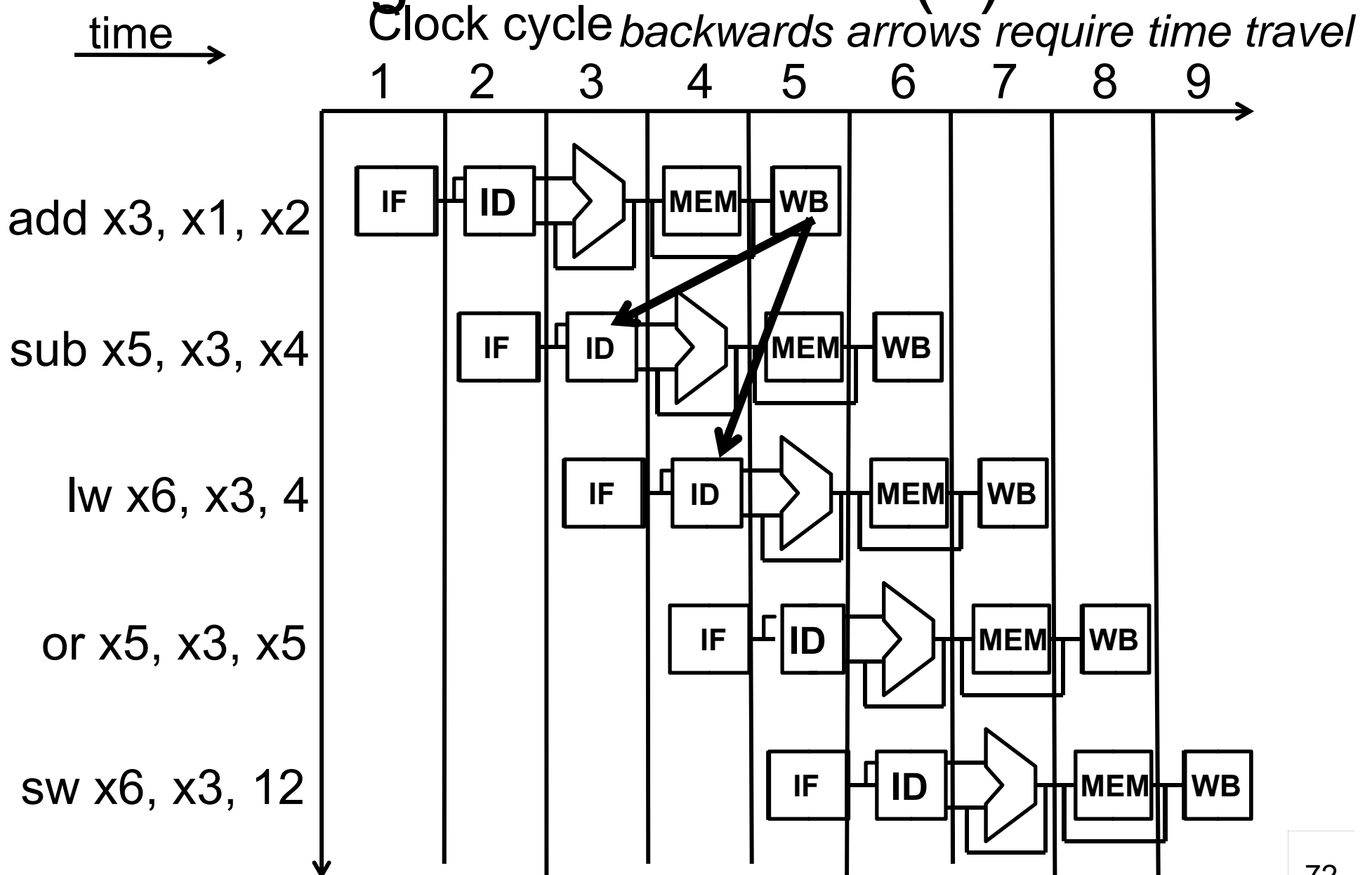
B) 2

C) 3

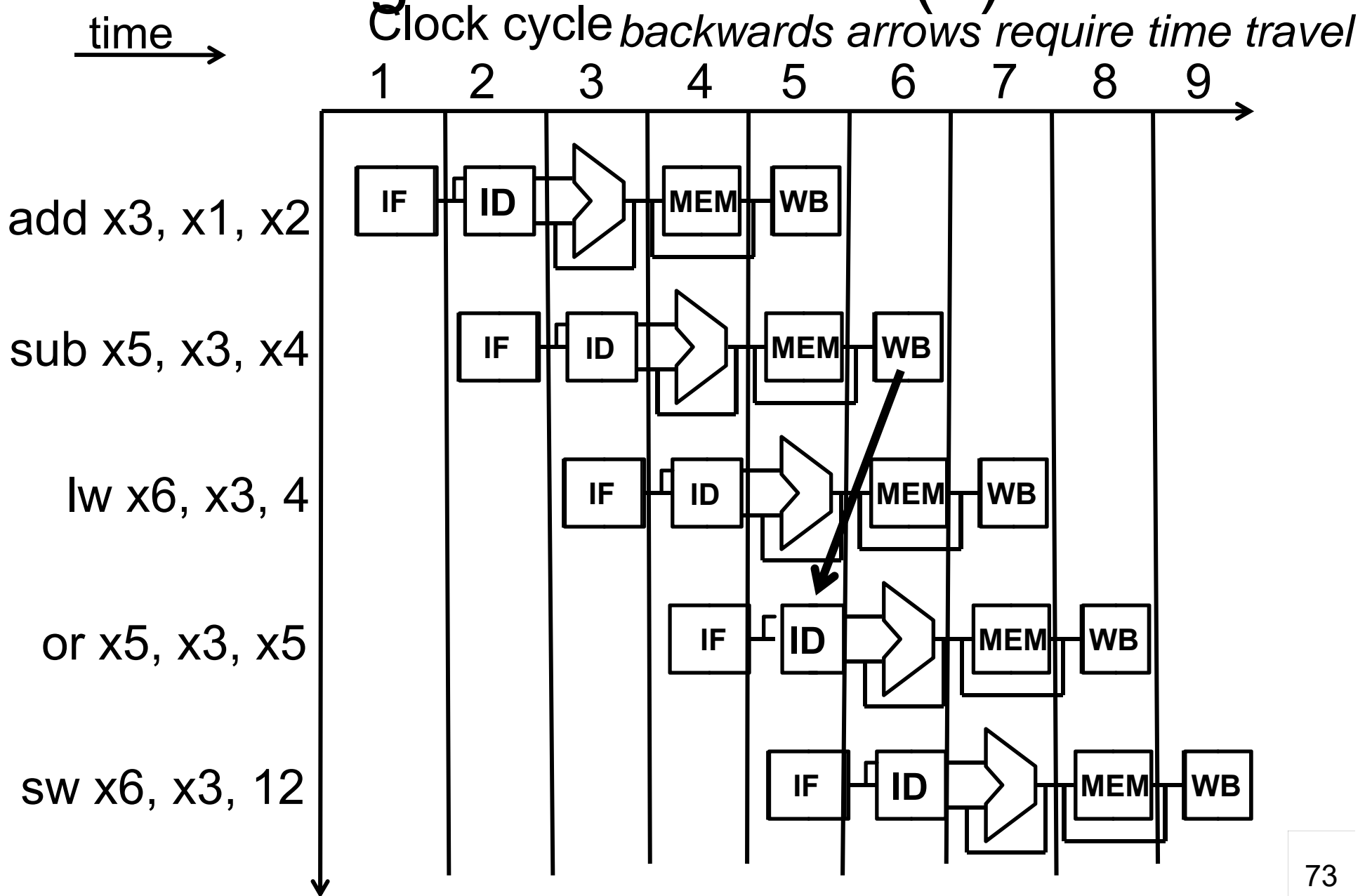
D) 4

E) 5

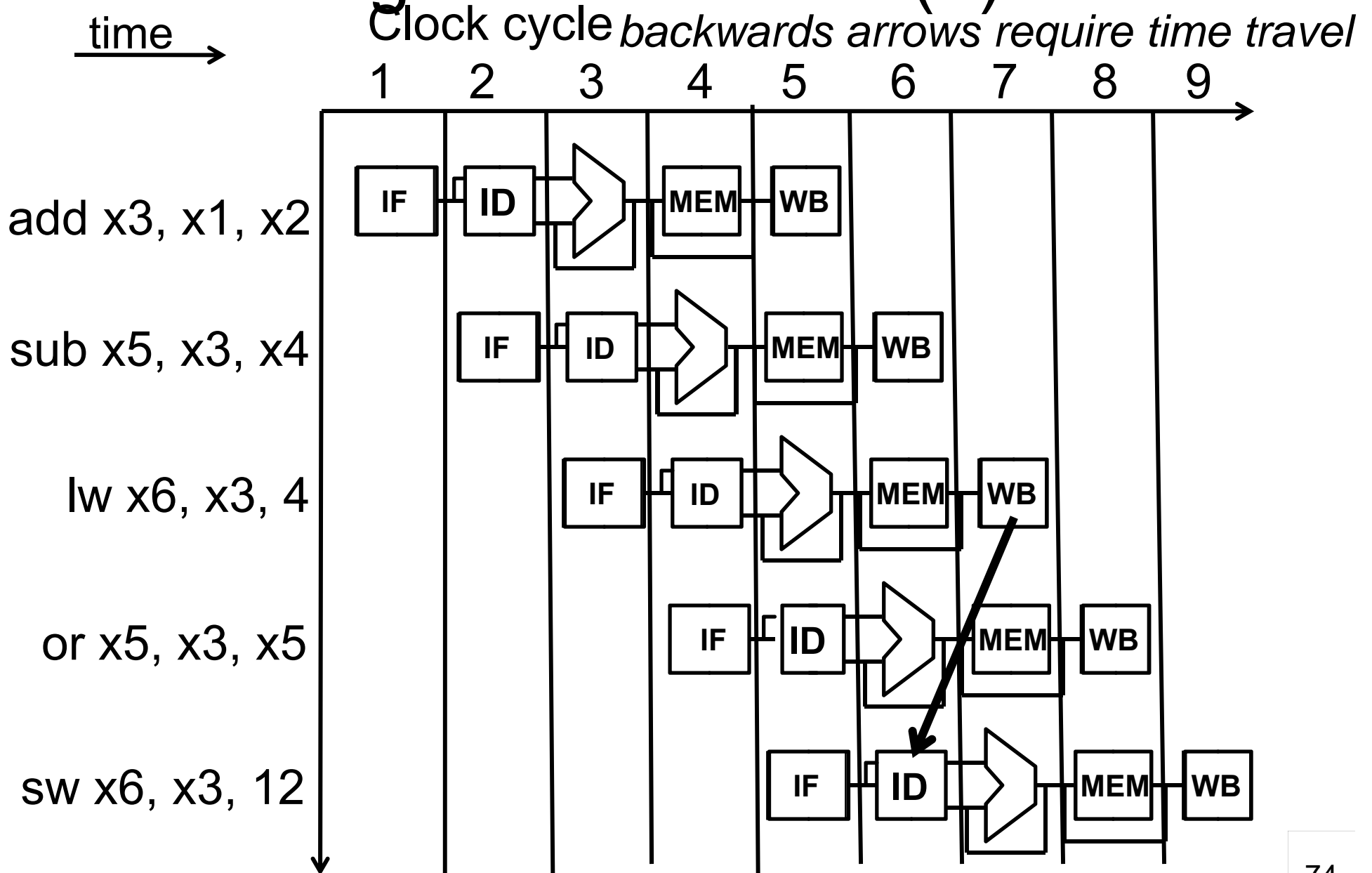
# Visualizing Data Hazards (1)



# Visualizing Data Hazards (2)



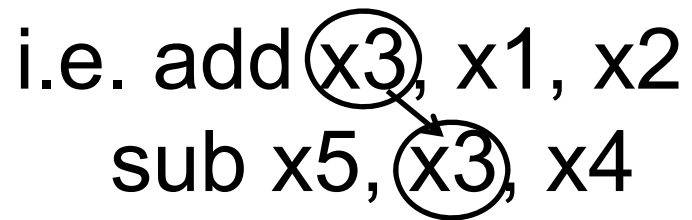
# Visualizing Data Hazards (3)



# Data Hazards

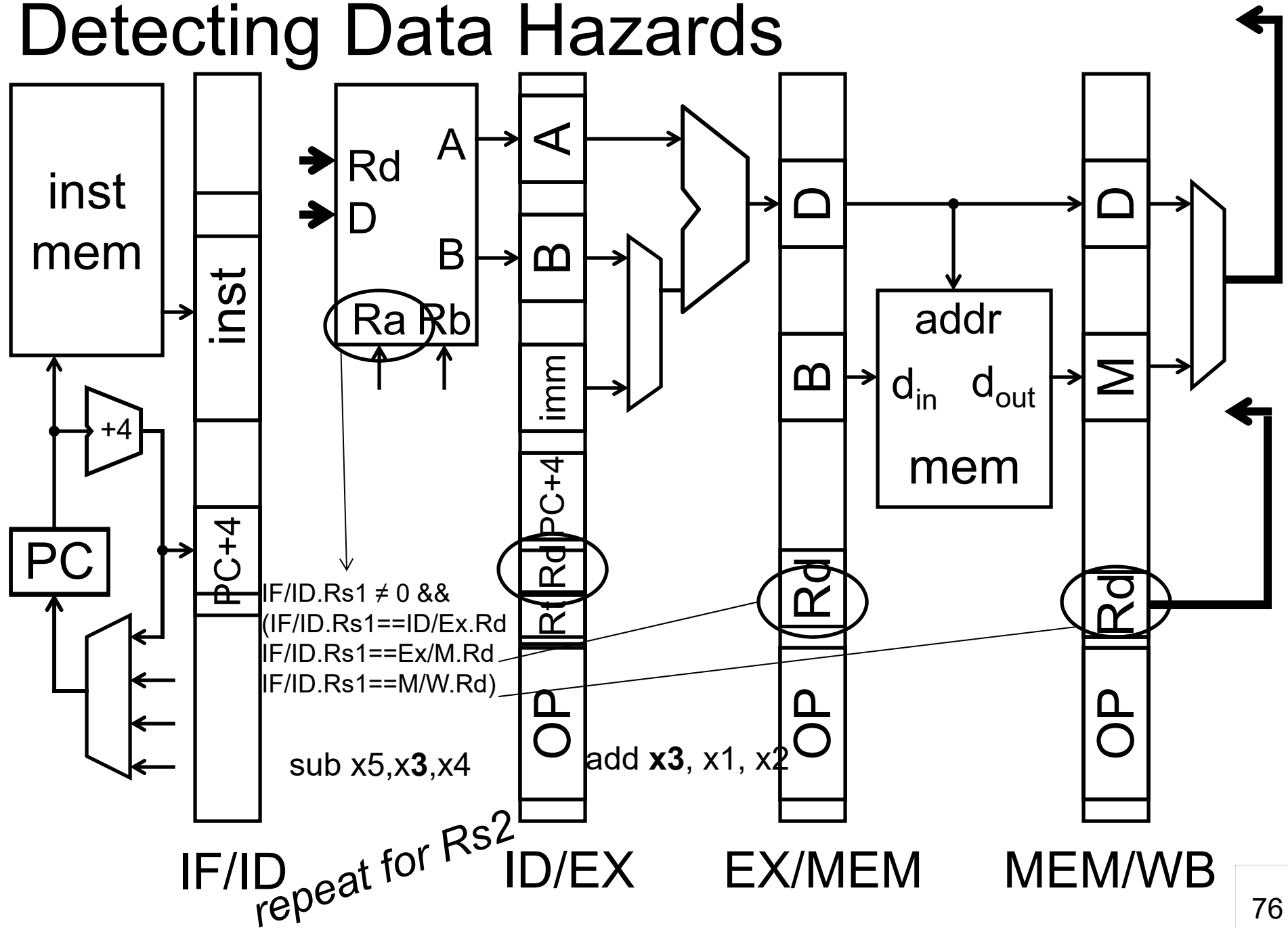
- register file reads occur in stage 2 (ID)
- register file writes occur in stage 5 (WB)
- next instructions may read values about to be written

i.e. add x3, x1, x2  
sub x5, x3, x4



How to detect?

# Detecting Data Hazards



# Data Hazards

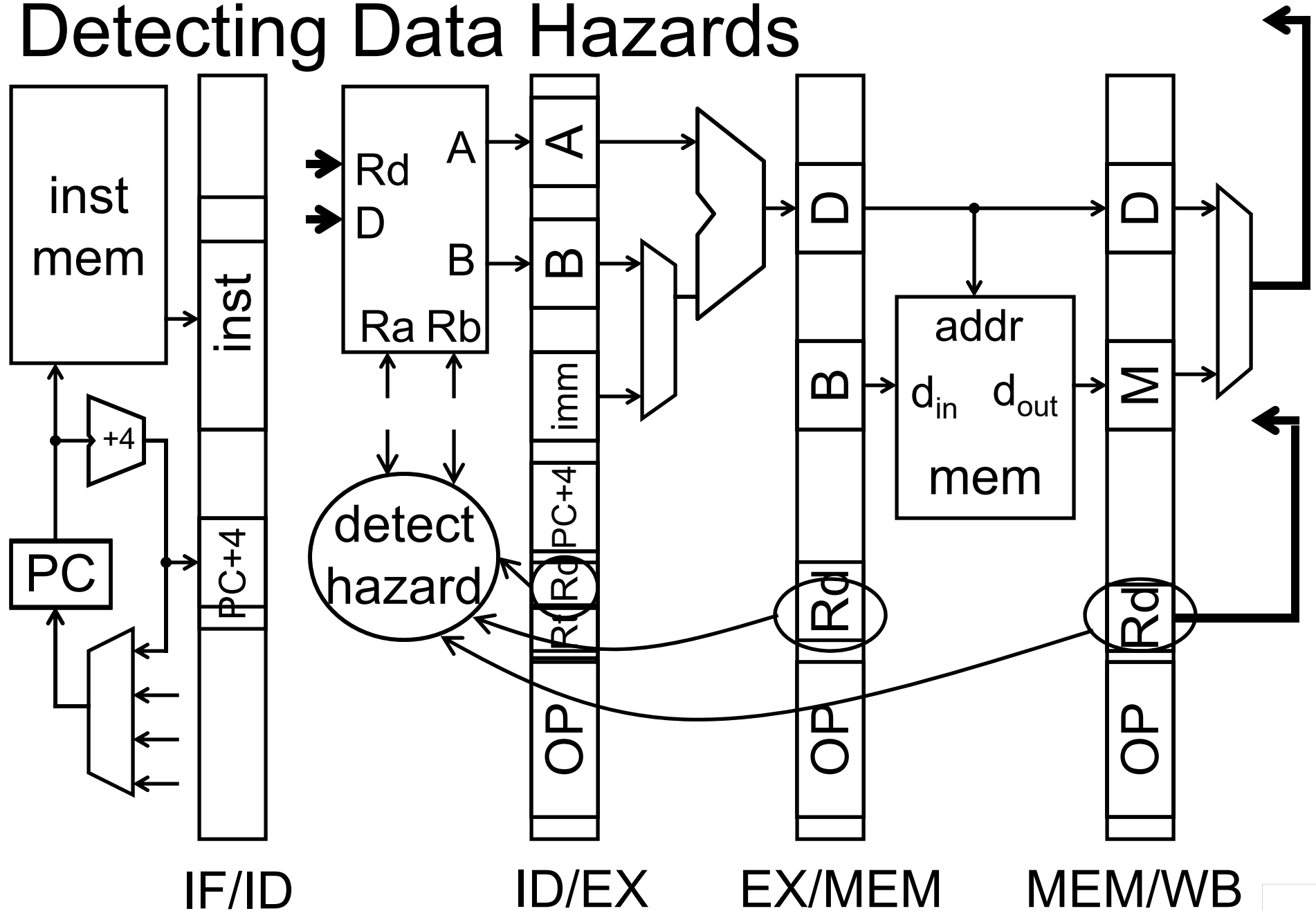
## Data Hazards

- register file reads occur in stage 2 (ID)
- register file writes occur in stage 5 (WB)
- next instructions may read values about to be written

How to detect? Logic in ID stage:

```
stall = (IF/ID.Rs1 != 0 &&  
        (IF/ID.Rs1 == ID/EX.Rd ||  
         IF/ID.Rs1 == EX/M.Rd ||  
         IF/ID.Rs1 == M/WB.Rd))  
        || (same for Rs2)
```

# Detecting Data Hazards



# Takeaway

Data hazards occur when an operand (register) depends on the result of a previous instruction that may not be computed yet. A pipelined processor needs to detect data hazards.



# Next Goal

What to do if data hazard detected?



# iClicker

What to do if data hazard detected?

A) Wait/Stall

B) Reorder in Software (SW)

C) Forward/Bypass

D) All the above

E) None. We will use some other method

# Possible Responses to Data Hazards

## 1. Do Nothing

- Change the ISA to match implementation
- “Hey compiler: don’t create code w/data hazards!”

*(We can do better than this)*

## 2. Stall

- Pause current and subsequent instructions till safe

## 3. Forward/bypass

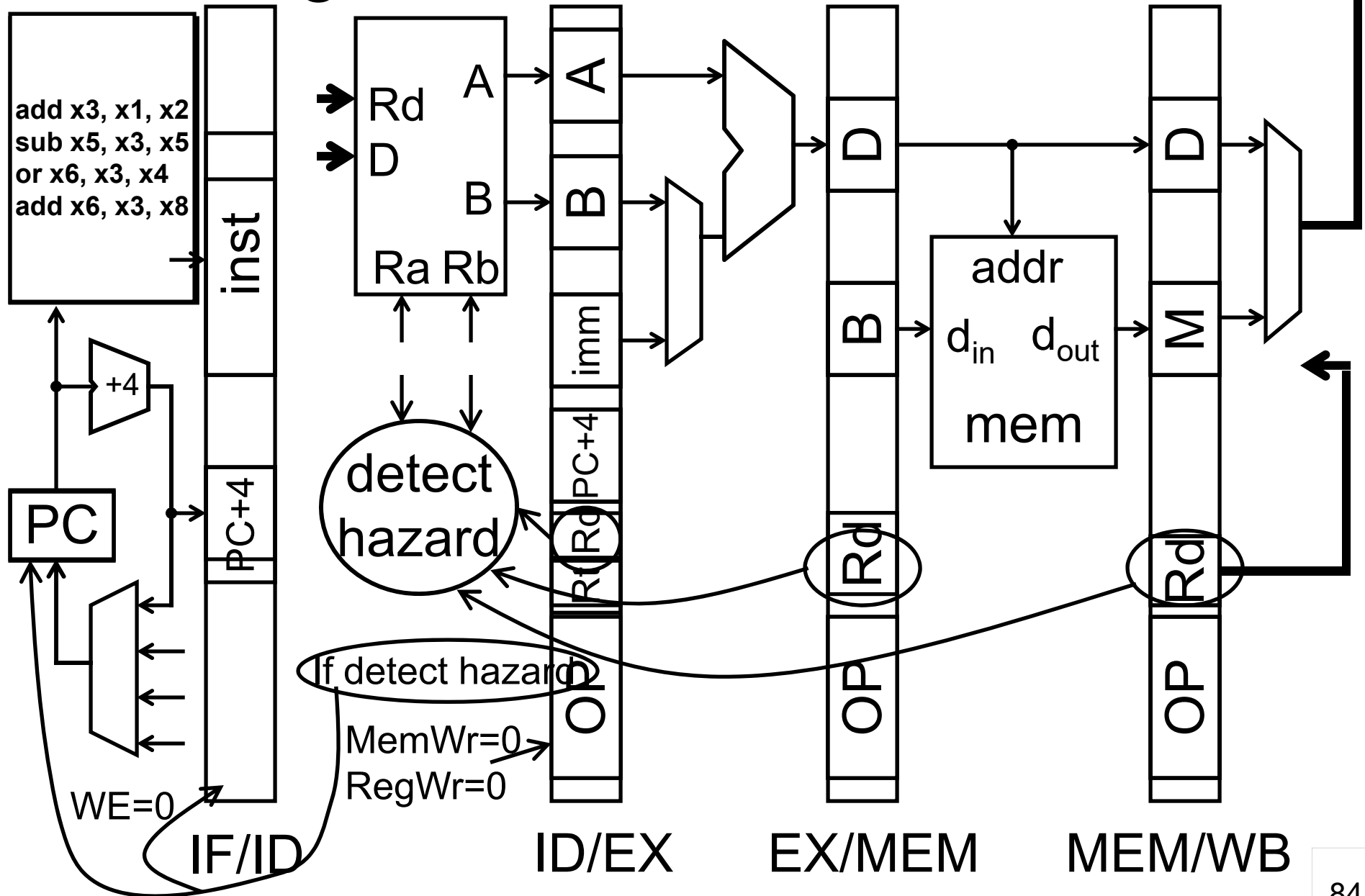
- Forward data value to where it is needed  
*(Only works if value actually exists already)*

# Stalling

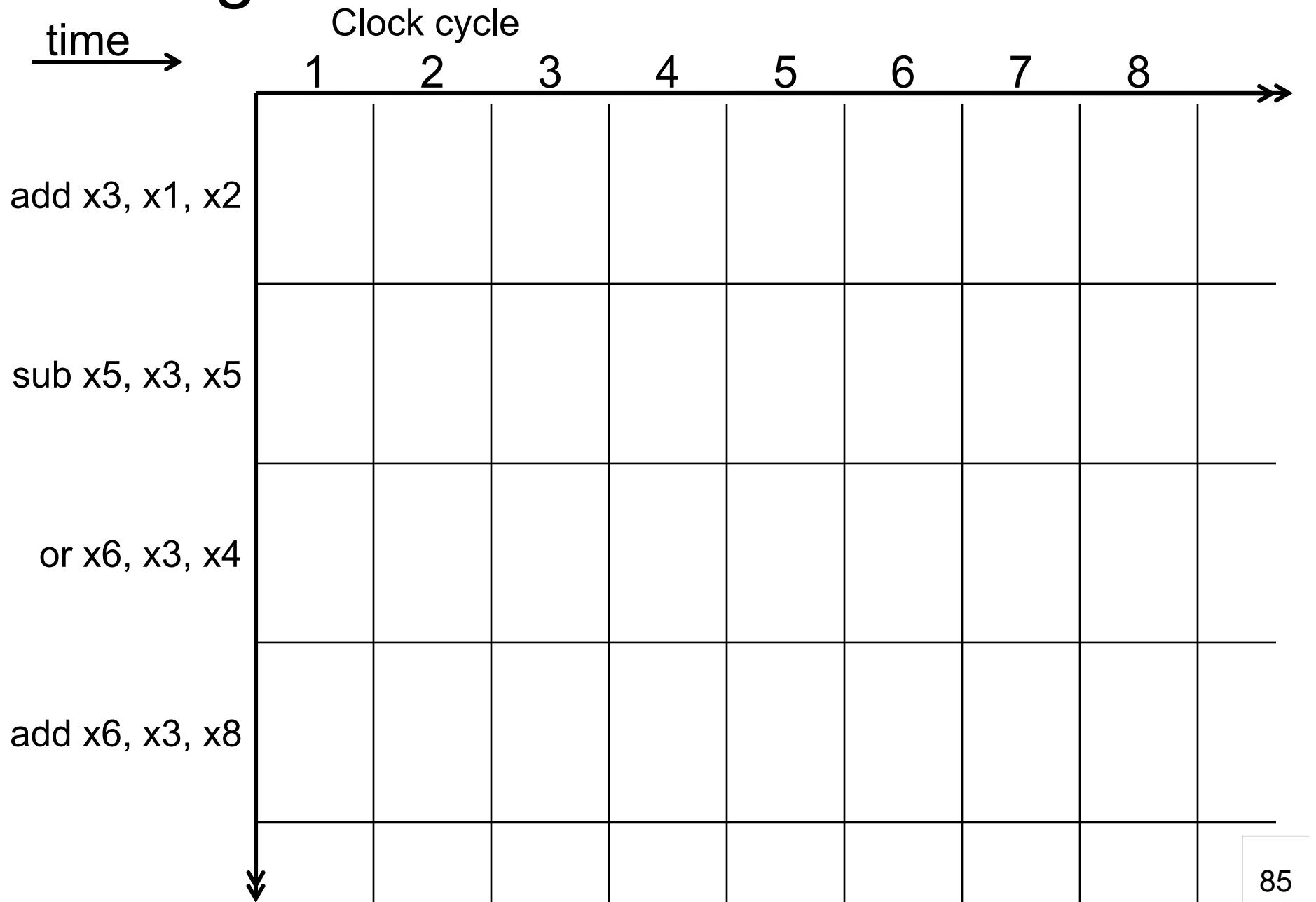
## How to stall an instruction in ID stage

- prevent IF/ID pipeline register update
  - stalls the ID stage instruction
- convert ID stage instr into nop for later stages
  - innocuous “bubble” passes through pipeline
- prevent PC update
  - stalls the next (IF stage) instruction

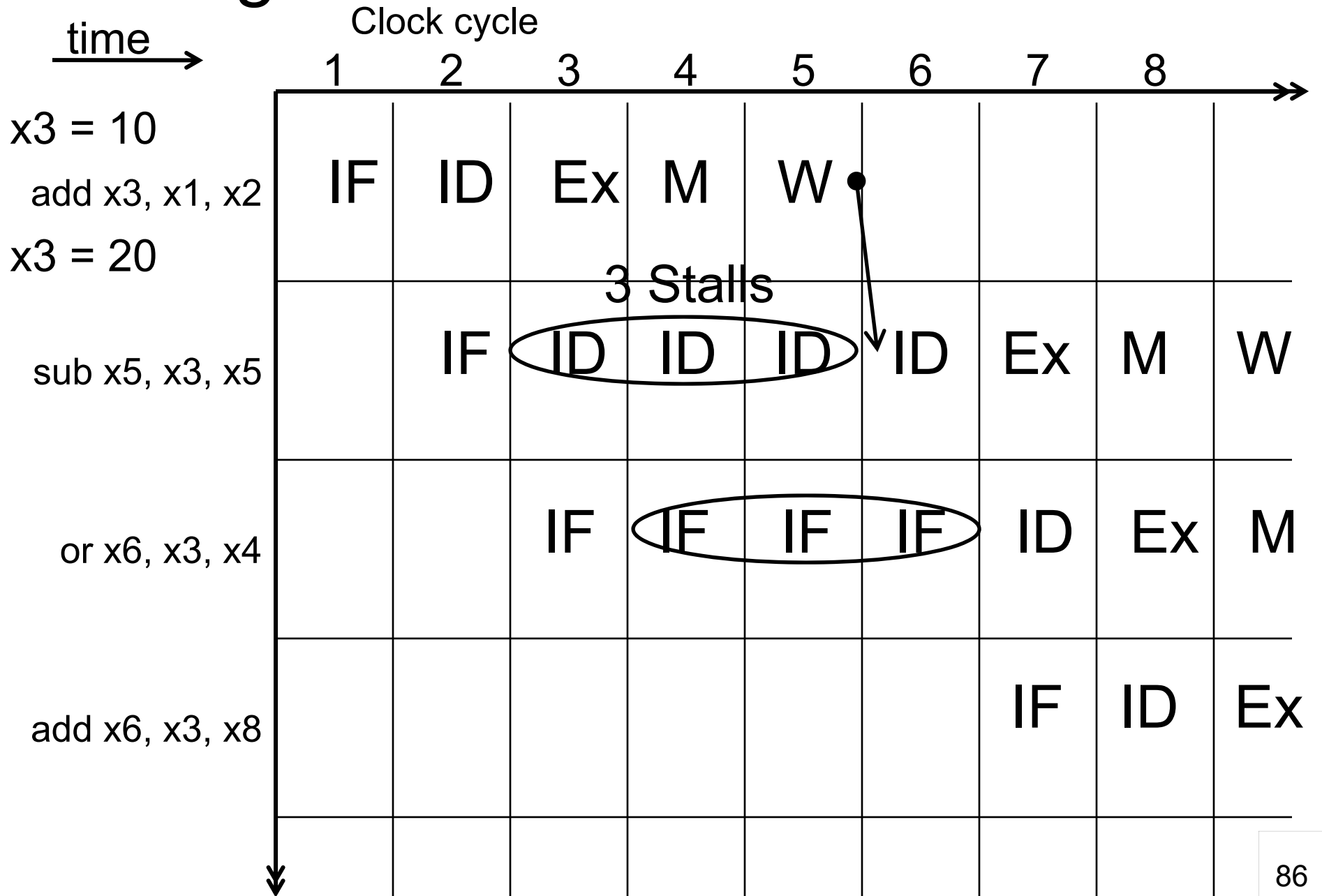
# Detecting Data Hazards



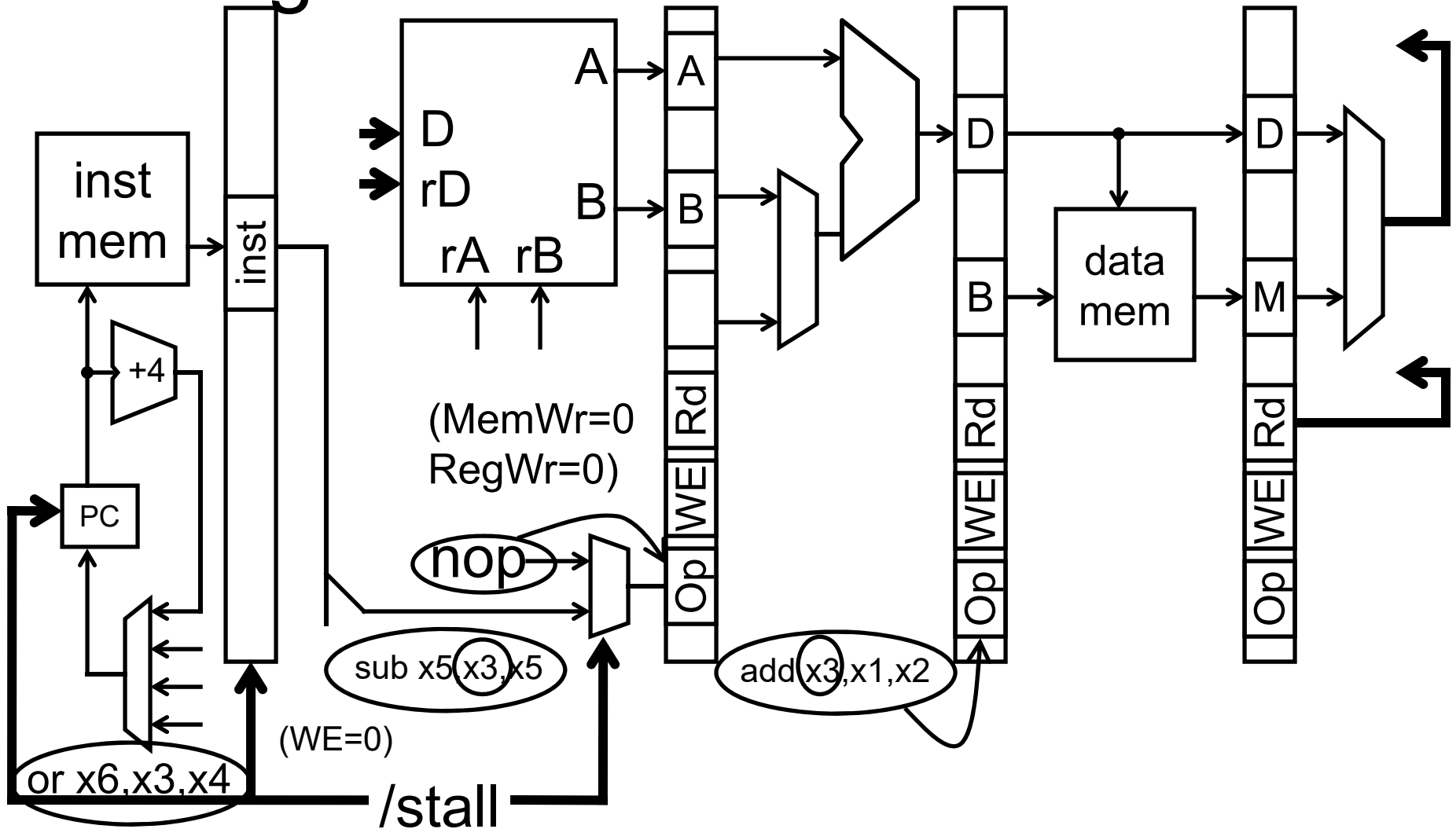
# Stalling



# Stalling



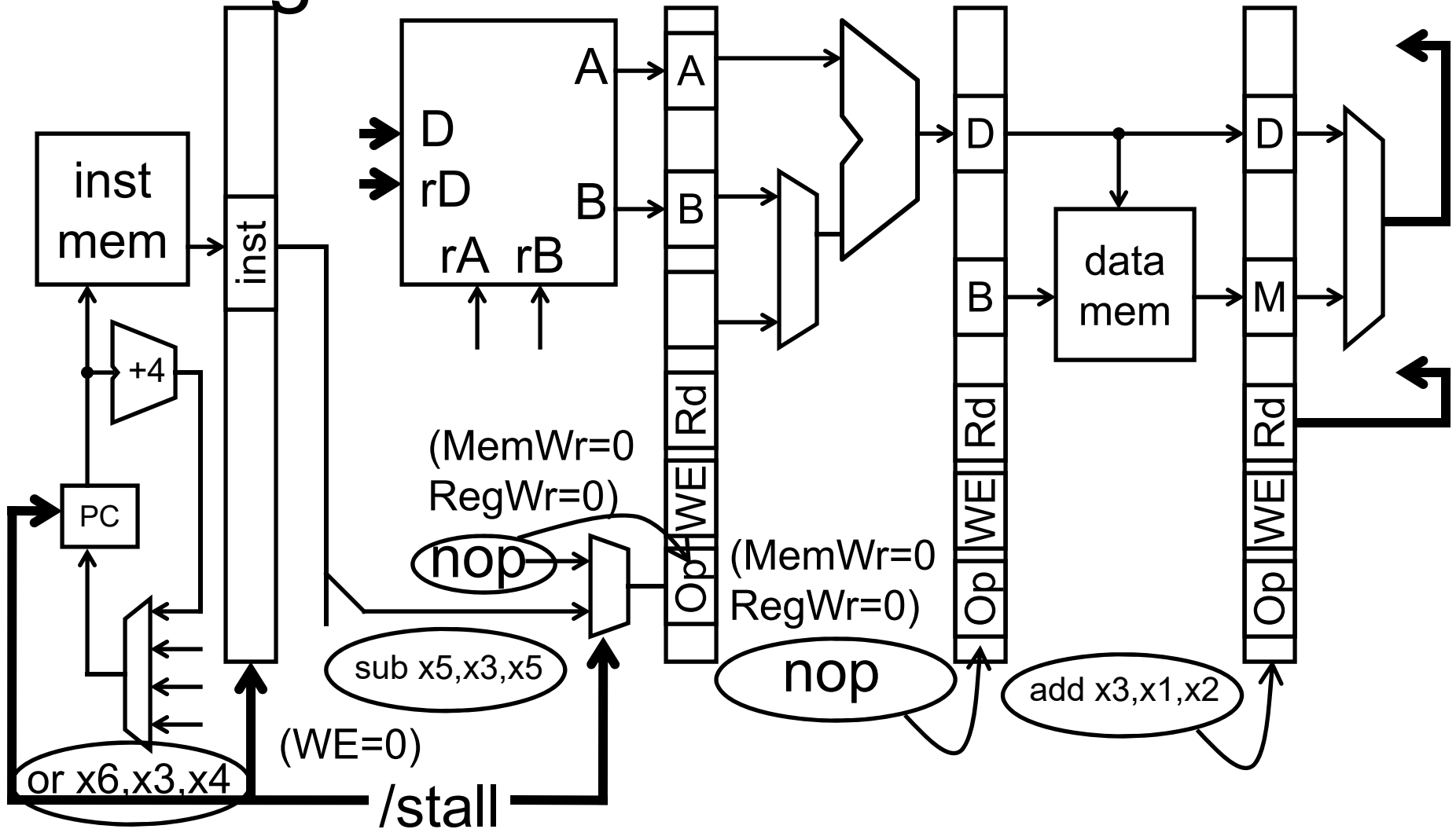
# Stalling



NOP = If(IF/ID.Rs1 ≠ 0 &&  
 (IF/ID.Rs1==ID/Ex.Rd &&  
 IF/ID.Rs1==Ex/M.Rd &&  
 IF/ID.Rs1==M/W.Rd))

← STALL CONDITION MET

# Stalling



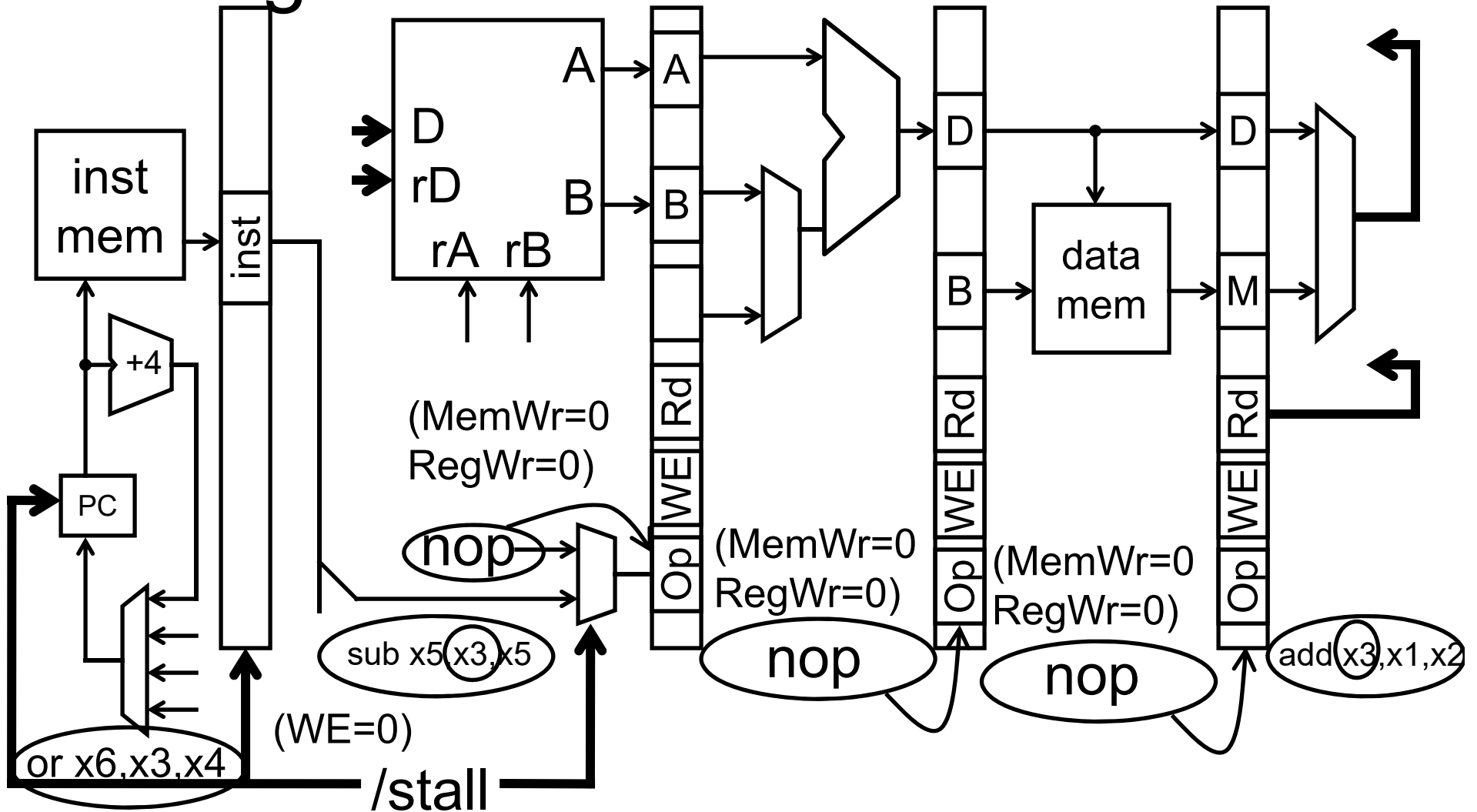
NOP = If(IF/ID.Rs1  $\neq$  0 &&

(IF/ID.Rs1==ID/Ex.Rd

IF/ID.Rs1==Ex/M.Rd) ← STALL CONDITION MET

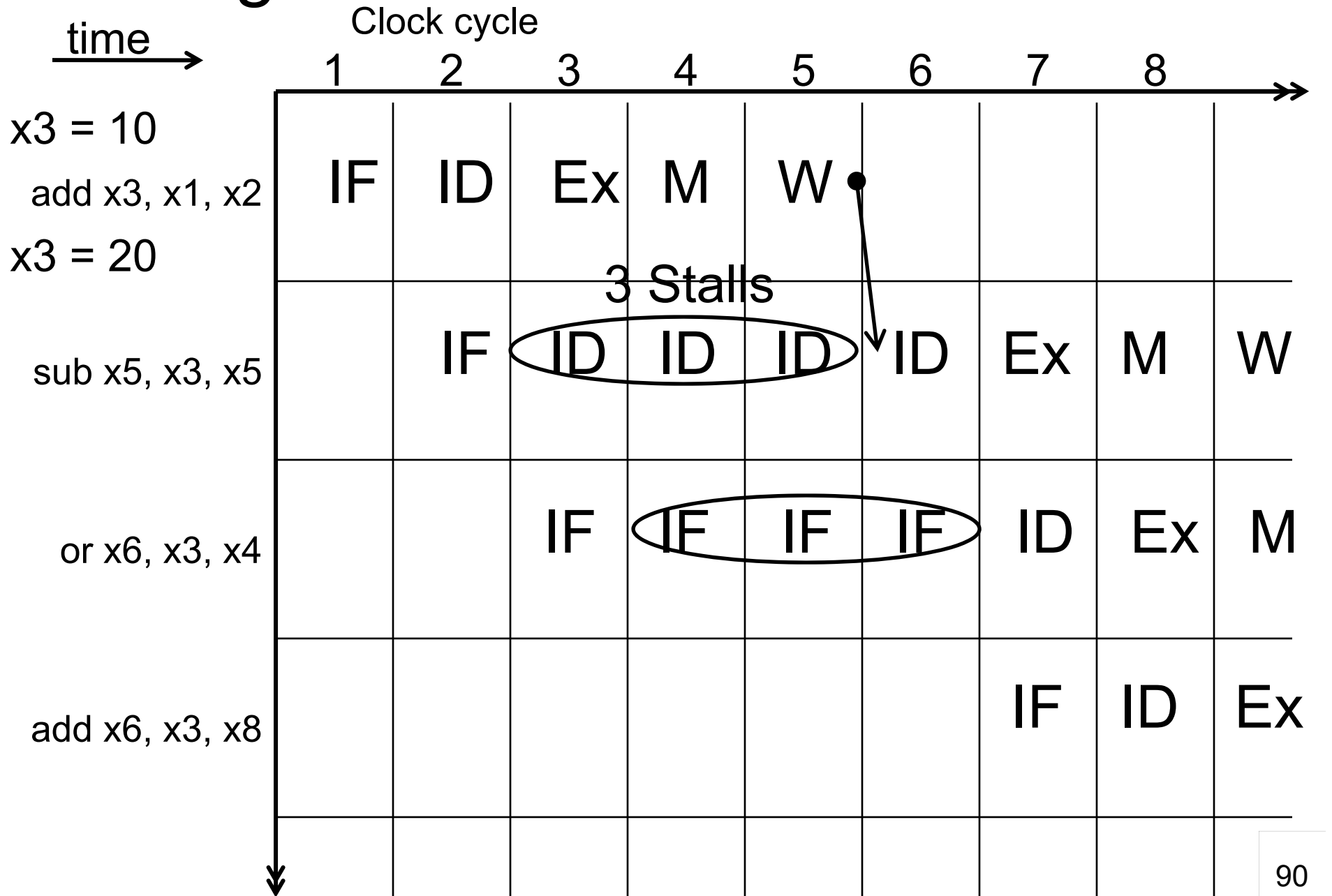
IF/ID.Rs1==M/W.Rd))

# Stalling



$$\text{NOP} = \text{If}(\text{IF/ID.Rs1} \neq 0 \ \&\& \\
\text{(IF/ID.Rs1==ID/Ex.Rd} \\
\text{IF/ID.Rs1==Ex/M.Rd} \\
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# Stalling



# Stalling

## How to stall an instruction in ID stage

- prevent IF/ID pipeline register update
  - stalls the ID stage instruction
- convert ID stage instr into nop for later stages
  - innocuous “bubble” passes through pipeline
- prevent PC update
  - stalls the next (IF stage) instruction

# Takeaway

Data hazards occur when an operand (register) depends on the result of a previous instruction that may not be computed yet. A pipelined processor needs to detect data hazards.

Stalling, preventing a dependent instruction from advancing, is one way to resolve data hazards.

Stalling introduces NOPs (“bubbles”) into a pipeline. Introduce NOPs by (1) preventing the PC from updating, (2) preventing writes to IF/ID registers from changing, and (3) preventing writes to memory and register file.  
\*Bubbles in pipeline significantly decrease performance.

# Possible Responses to Data Hazards

## 1. Do Nothing

- Change the ISA to match implementation
- “Compiler: don’t create code with data hazards!”

*(Nice try, we can do better than this)*

## 2. Stall

- Pause current and subsequent instructions till safe

## 3. Forward/bypass

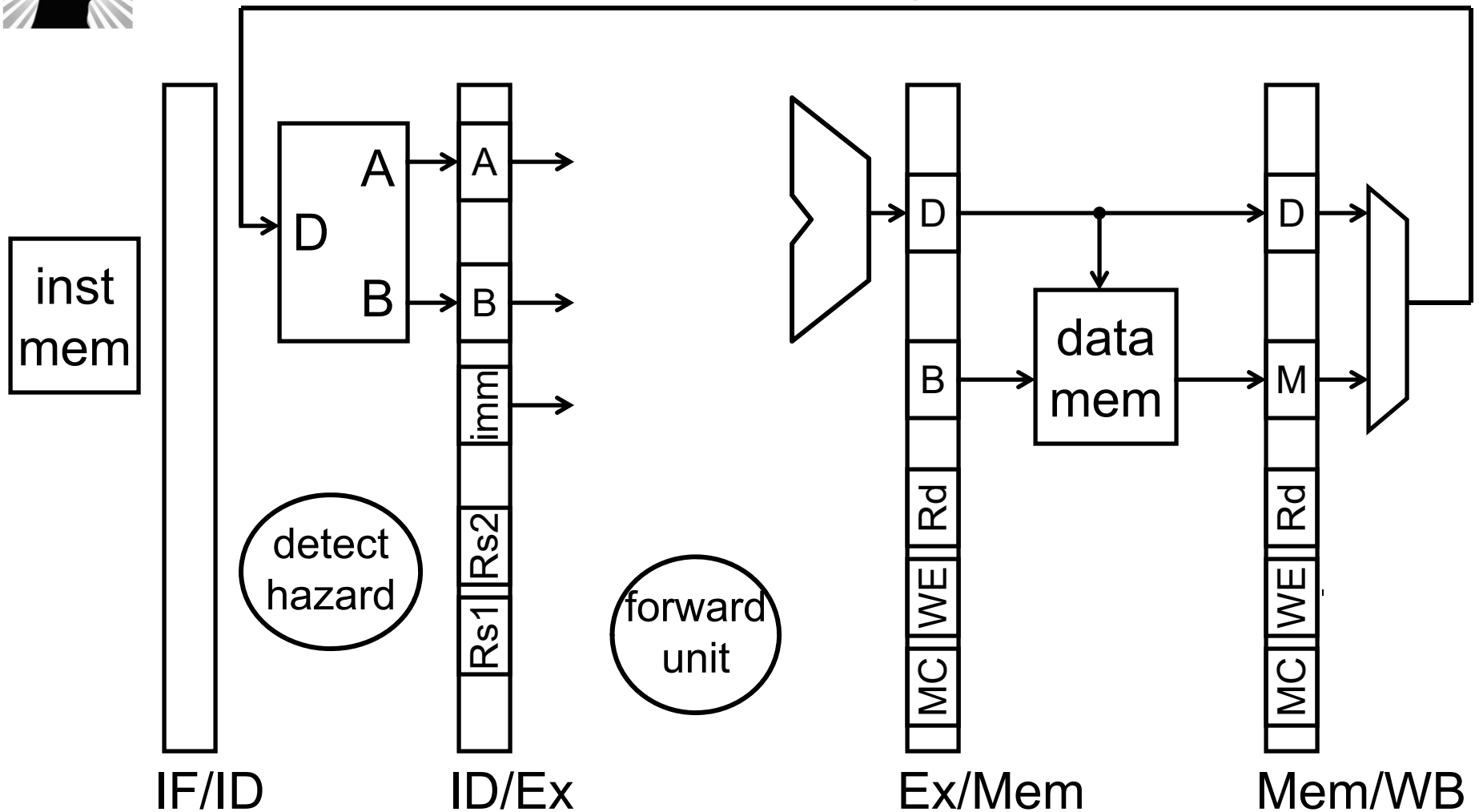
- Forward data value to where it is needed  
*(Only works if value actually exists already)*

# Forwarding

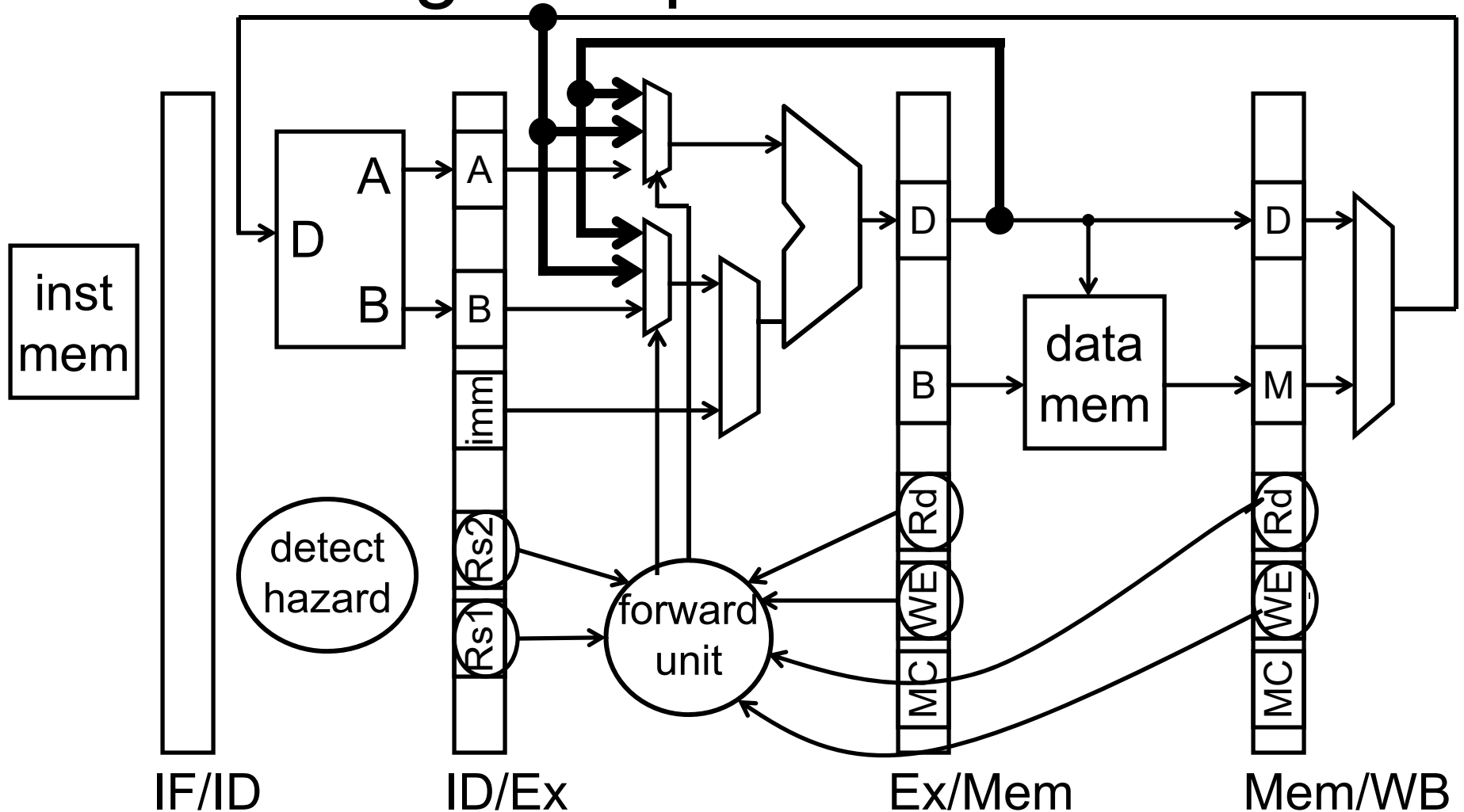
- Forwarding bypasses some pipelined stages forwarding a result to a dependent instruction operand (register).
- Three types of forwarding/bypass
  - Forwarding from Ex/Mem registers to Ex stage ( $M \rightarrow Ex$ )
  - Forwarding from Mem/WB register to Ex stage ( $W \rightarrow Ex$ )
  - RegisterFile Bypass



# Add the Forwarding Datapath



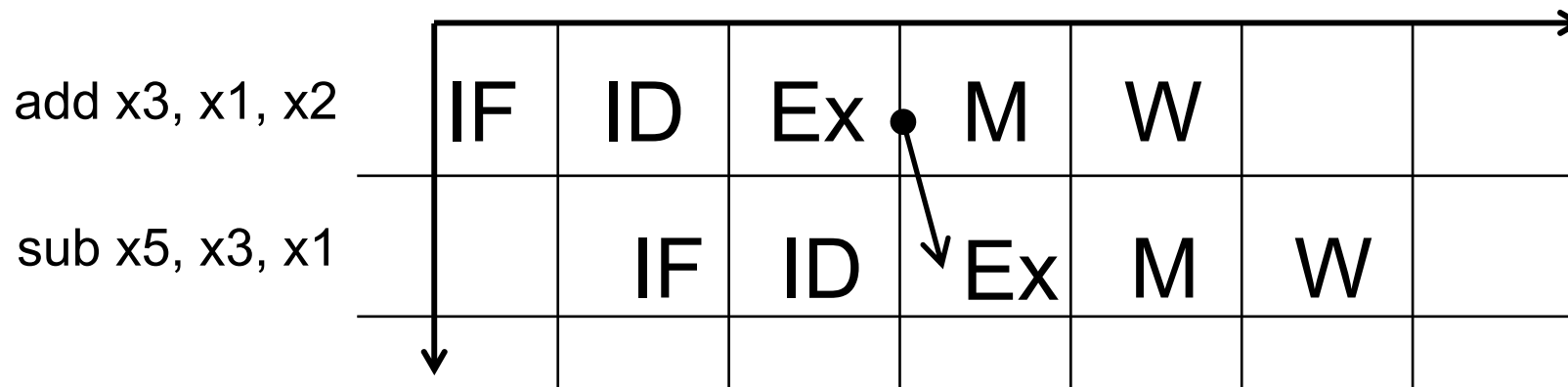
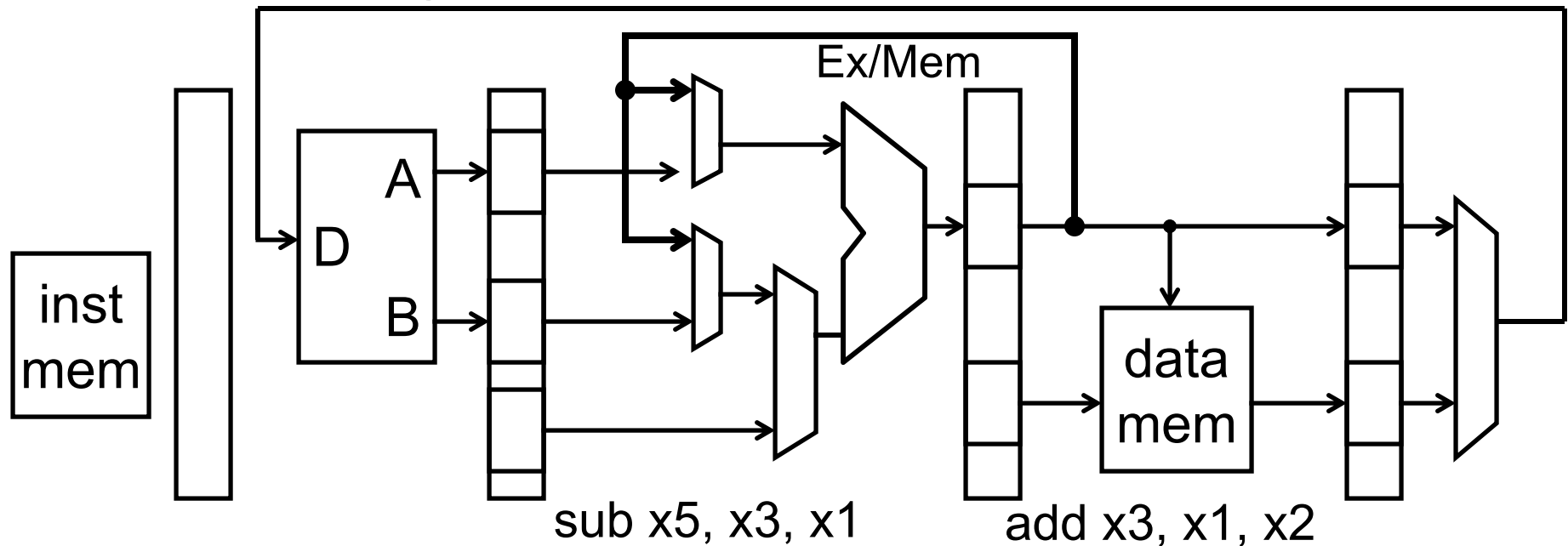
# Forwarding Datapath



Three types of forwarding/bypass

- Forwarding from Ex/Mem registers to Ex stage (M → Ex)
- Forwarding from Mem/WB register to Ex stage (W → Ex)
- RegisterFile Bypass

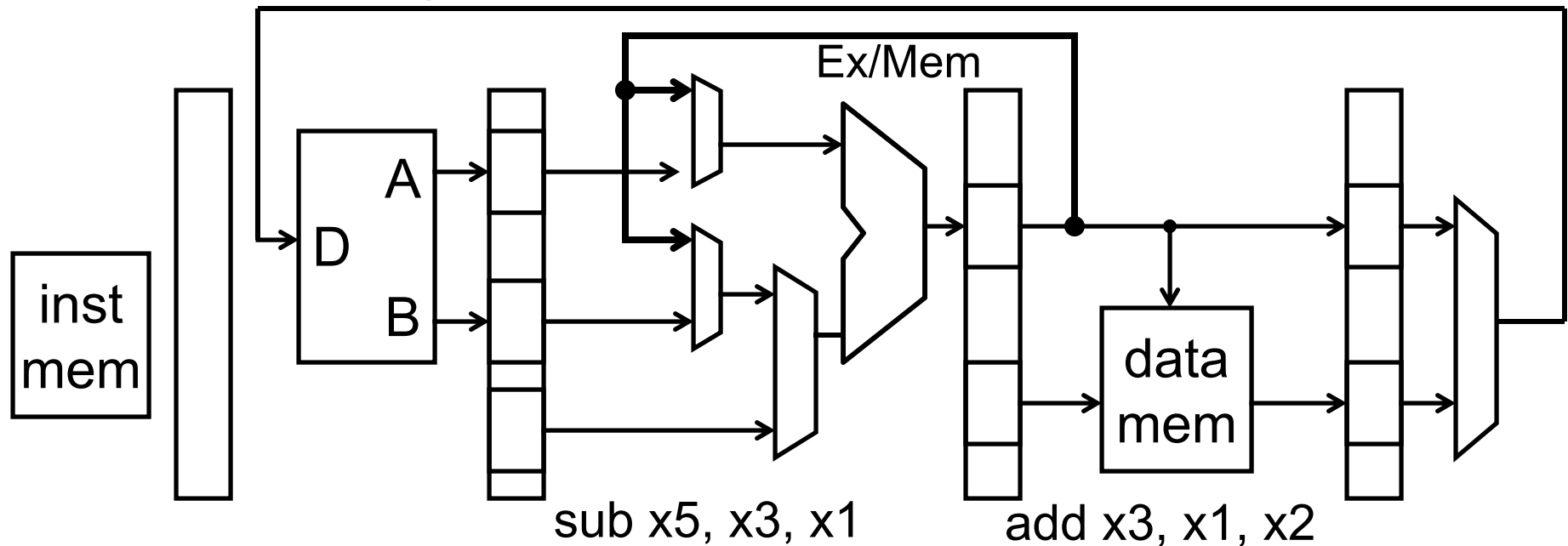
# Forwarding Datapath 1: Ex/MEM → EX



Problem: EX needs ALU result that is in MEM stage

Solution: add a bypass from EX/MEM.D to start of EX

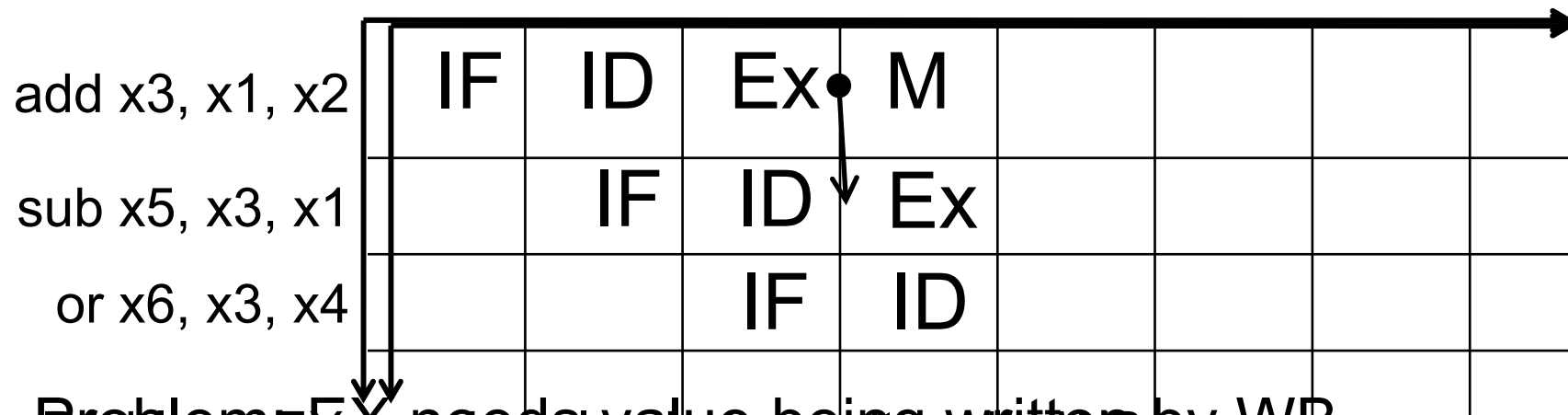
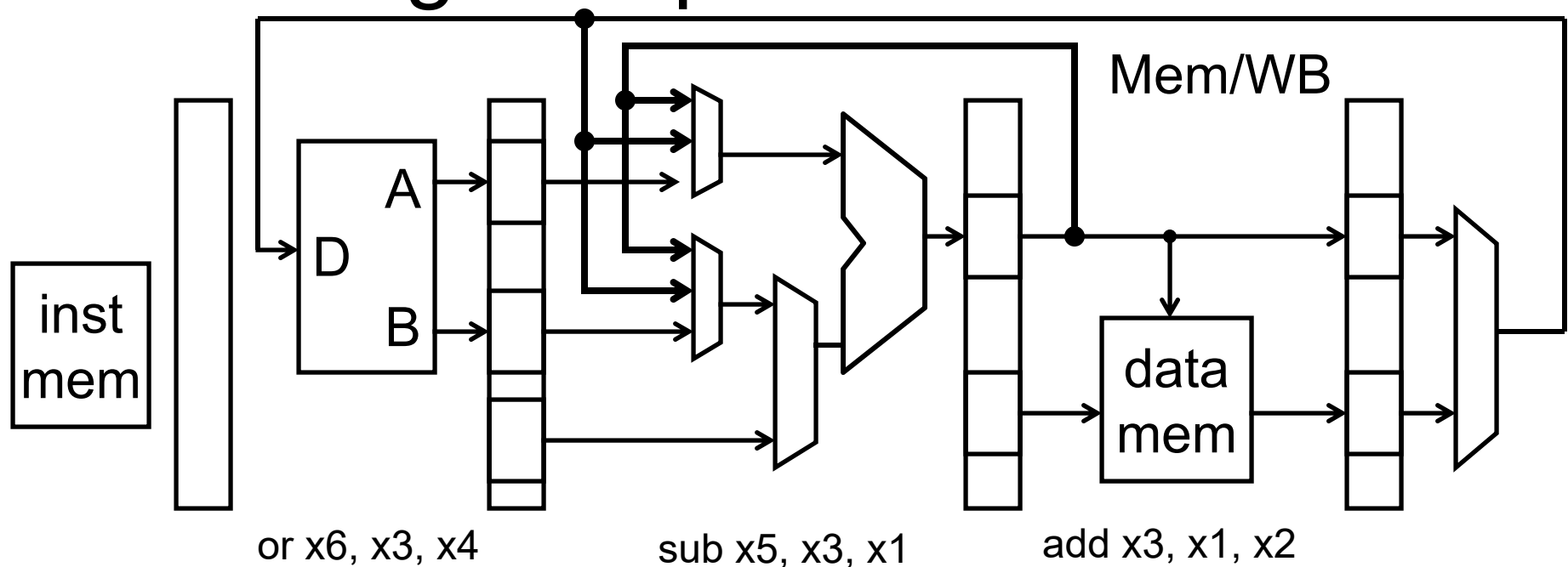
# Forwarding Datapath 1: Ex/MEM $\rightarrow$ EX



Detection Logic in Ex Stage:

$$\text{forward} = (\text{Ex/M.WE} \ \&\& \ \text{EX/M.Rd} \neq 0 \ \&\& \\ \text{ID/Ex.Rs1} == \text{Ex/M.Rd}) \\ \parallel \text{ (same for Rs2)}$$

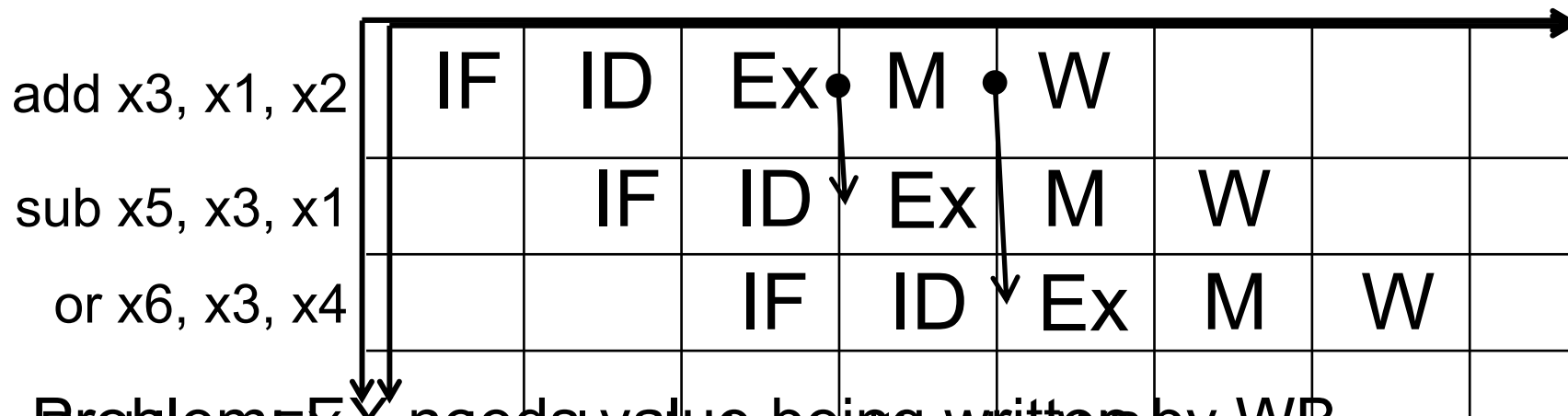
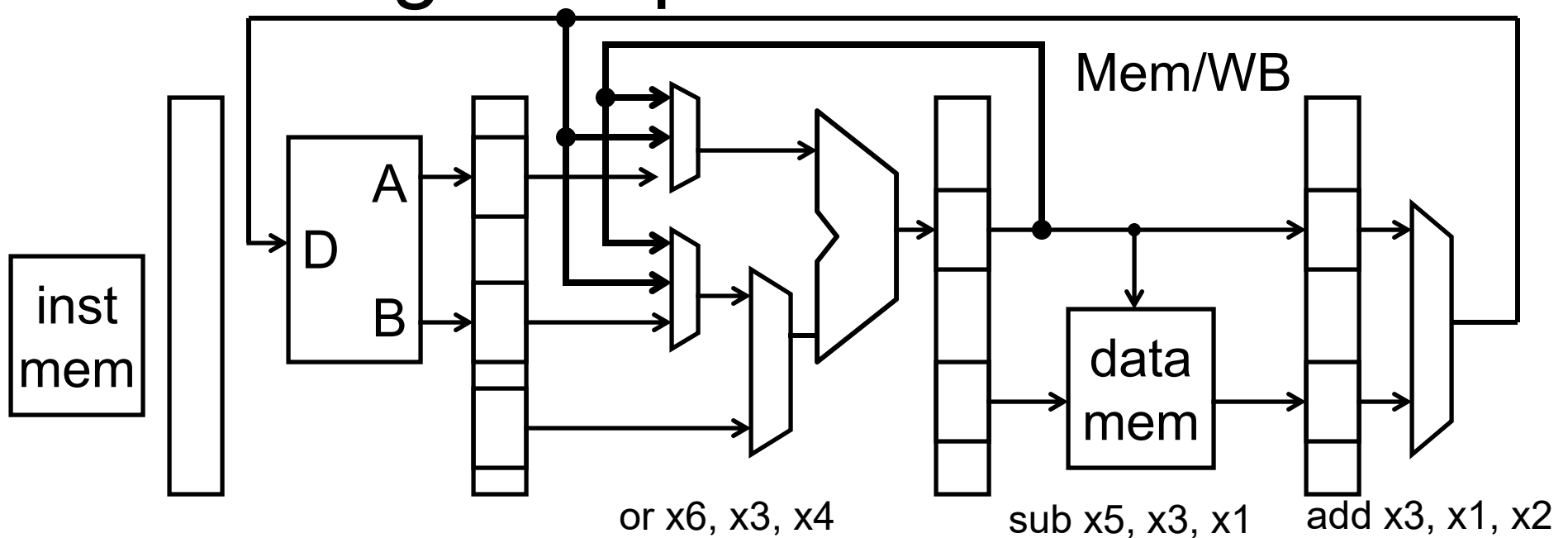
# Forwarding Datapath 2: Mem/WB → EX



**Problem:** EX needs value being written by WB

**Solution:** Add bypass from WB final value to start of EX

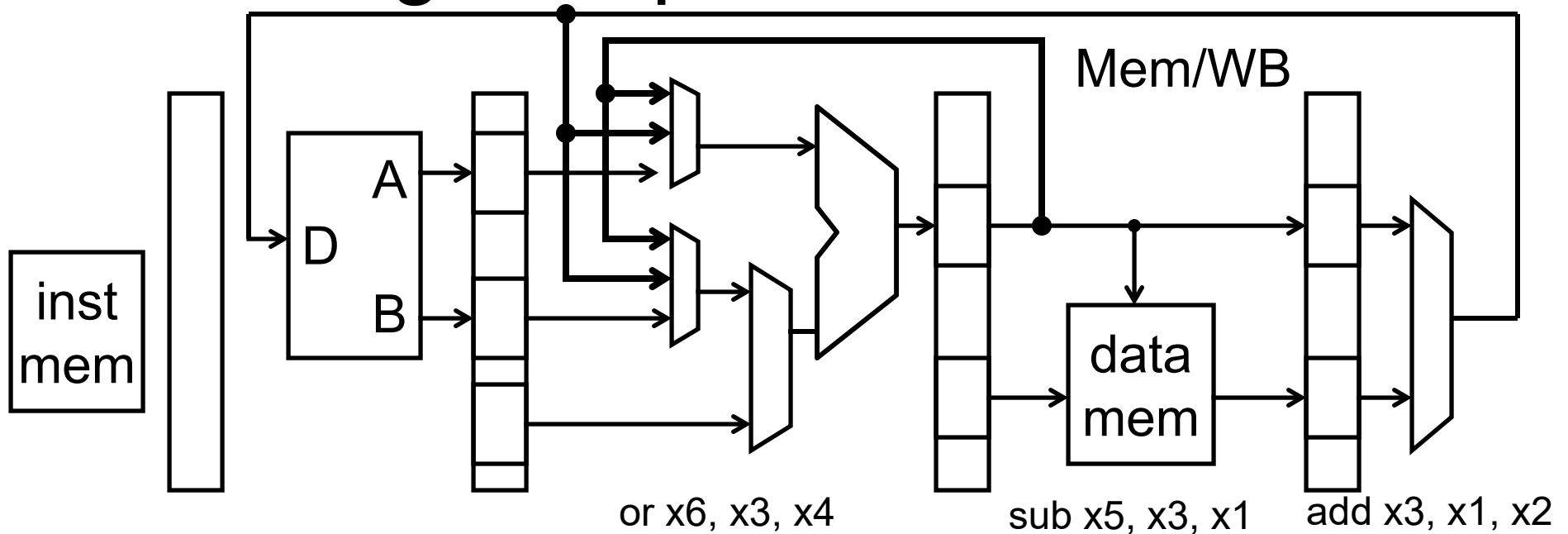
# Forwarding Datapath 2: Mem/WB → EX



**Problem:** EX needs value being written by WB

**Solution:** Add bypass from WB final value to start of EX

# Forwarding Datapath 2: Mem/WB → EX



Detection Logic:

$\text{forward} = (\text{M/WB.WE} \ \&\& \ \text{M/WB.Rd} \neq 0 \ \&\&$

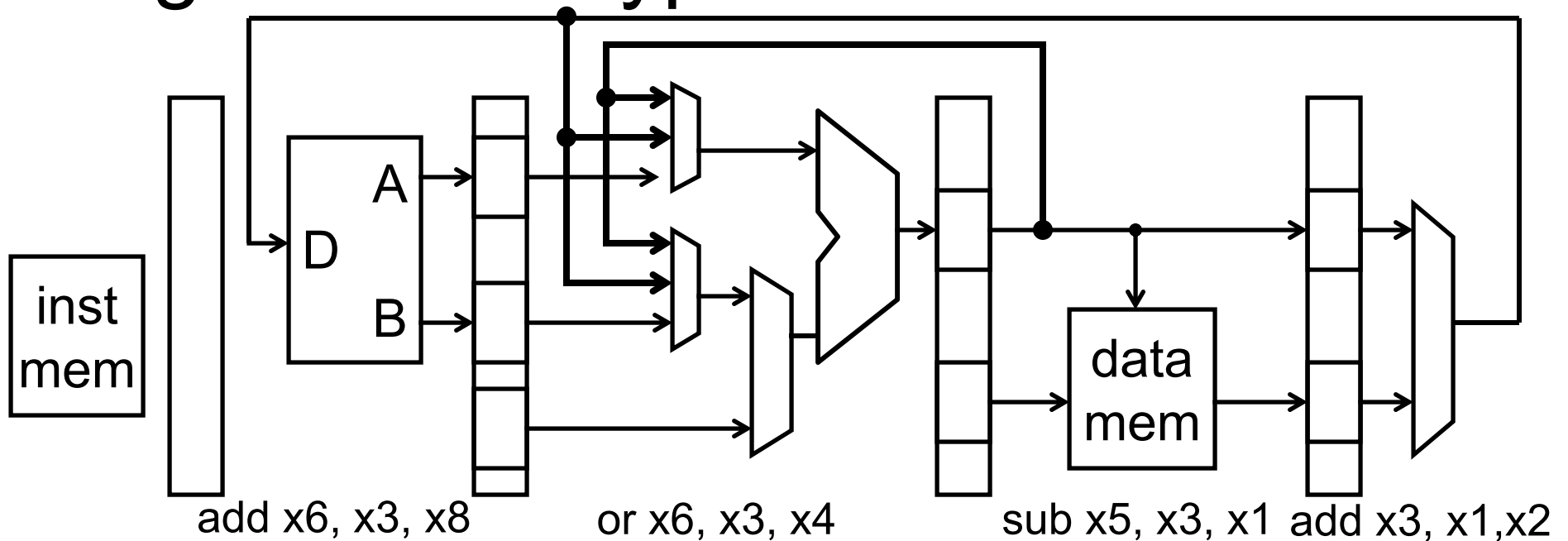
$\text{ID/Ex.Rs1} == \text{M/WB.Rd} \ \&\&$

$\text{not} (\text{Ex/M.WE} \ \&\& \ \text{Ex/M.Rd} \neq 0 \ \&\&$

$\text{ID/Ex.Rs1} == \text{Ex/M.Rd})$

$\parallel (\text{same for Rs2})$

# Register File Bypass

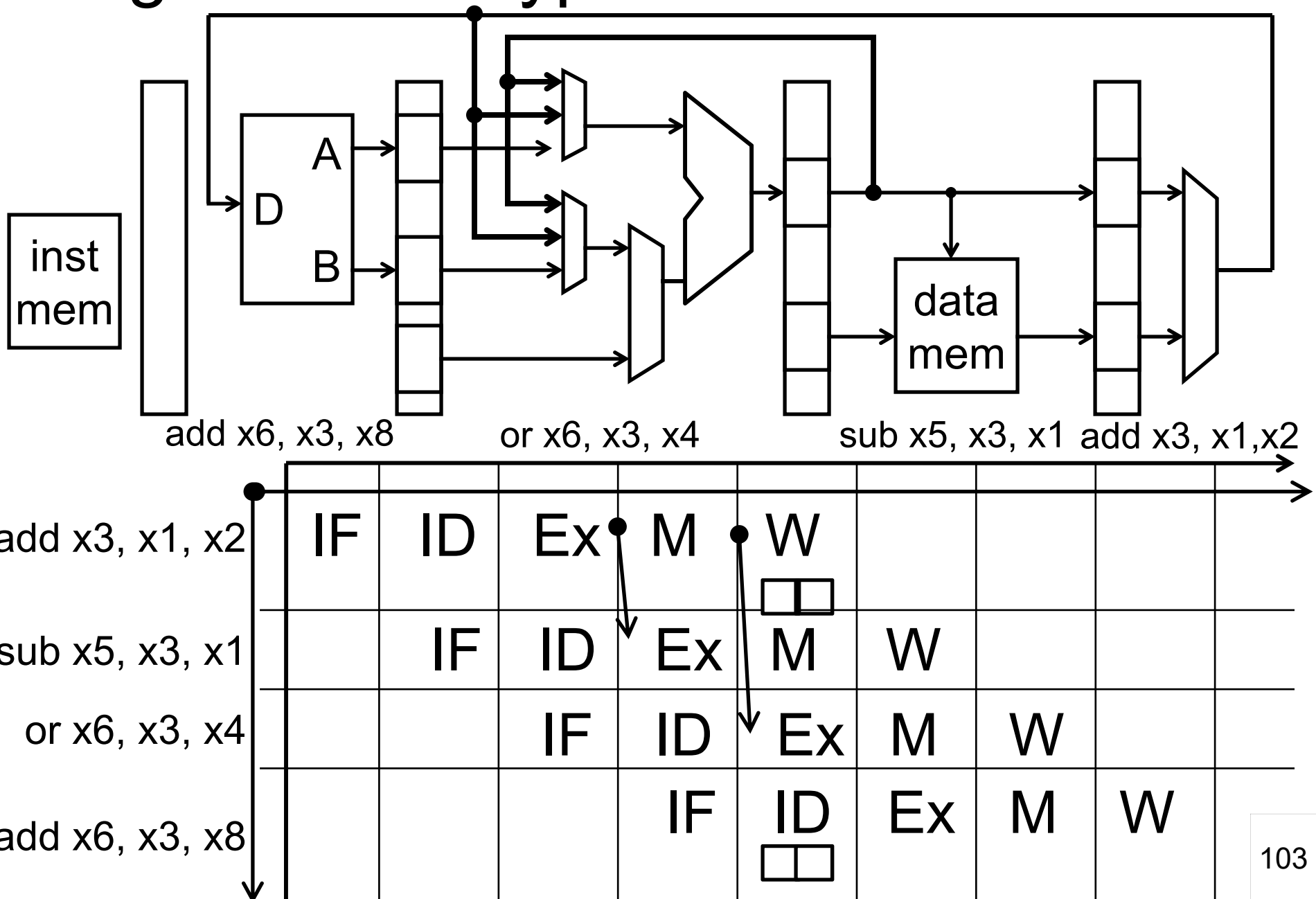


Problem: Reading a value that is currently being written

Solution: just negate register file clock

- writes happen at end of first half of each clock cycle
- reads happen during second half of each clock cycle

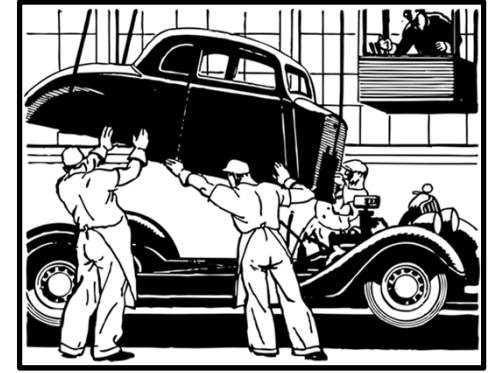
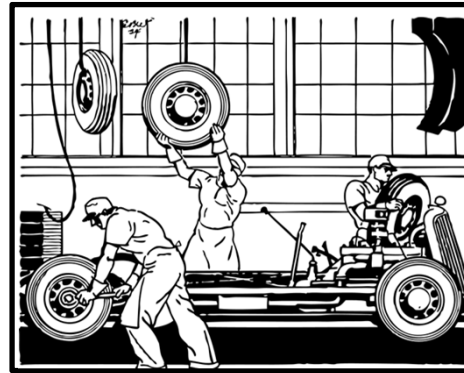
# Register File Bypass



# Agenda

## 5-stage Pipeline

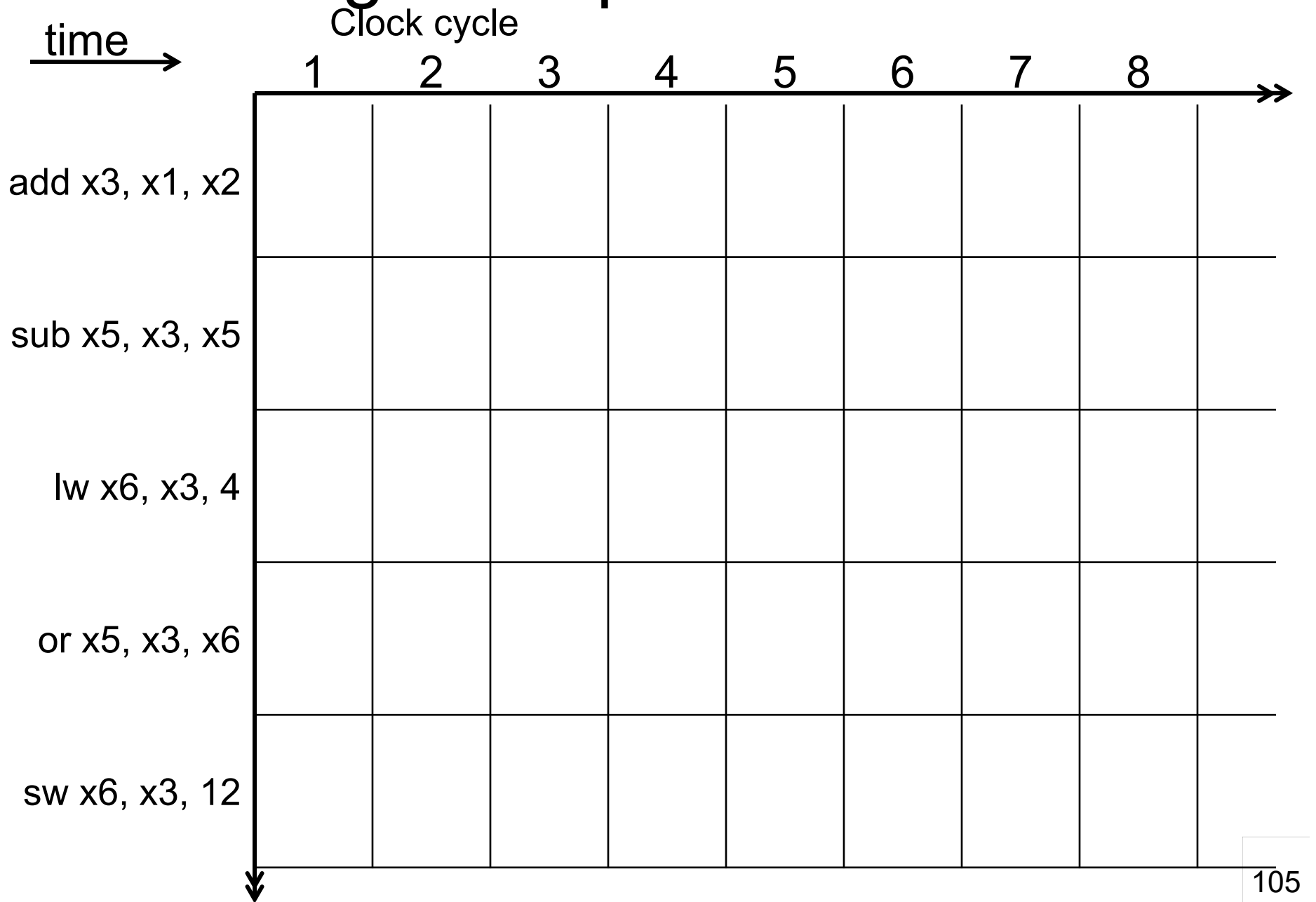
- Implementation
- Working Example



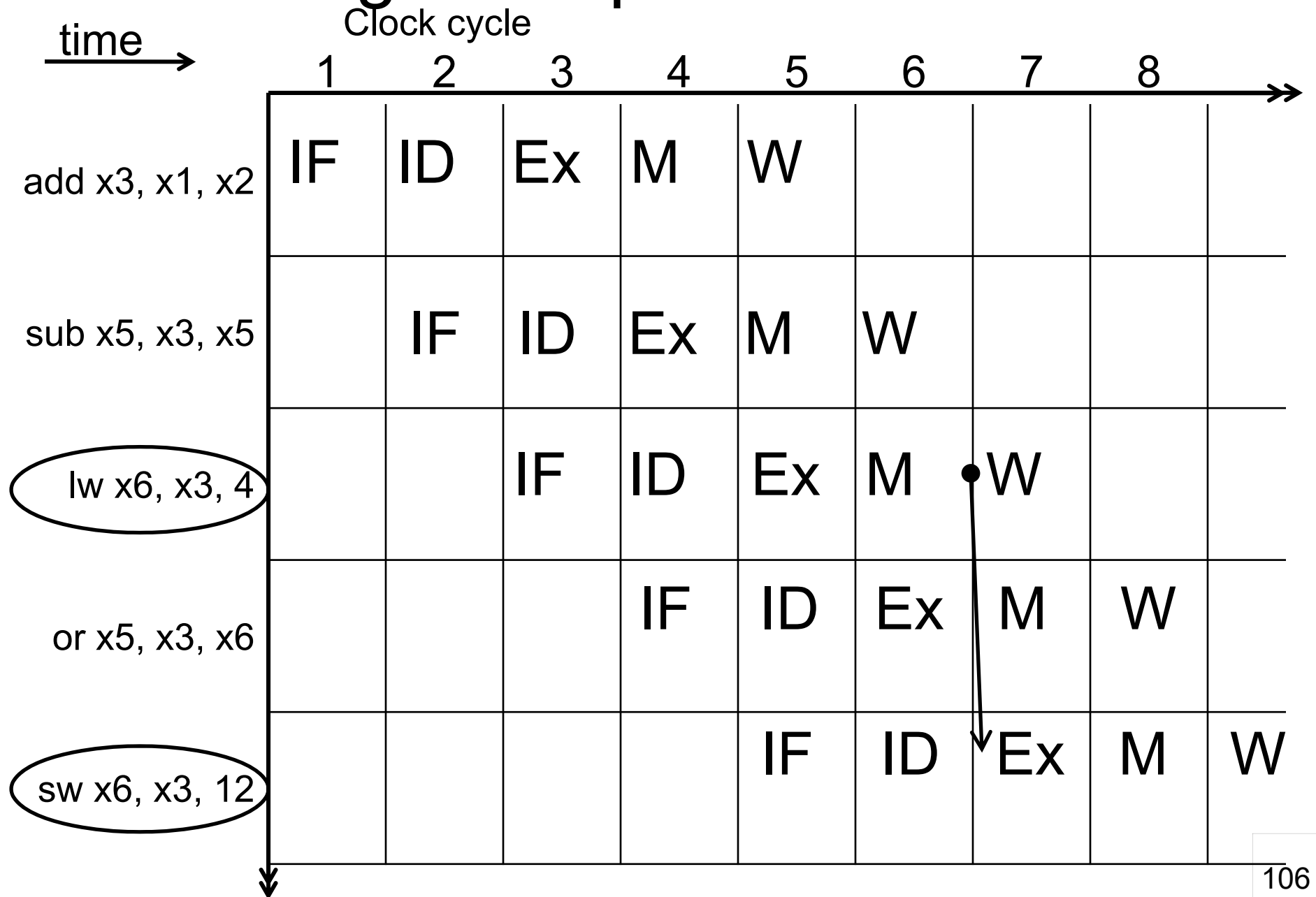
## Hazards

- Structural
- Data Hazards
- Control Hazards

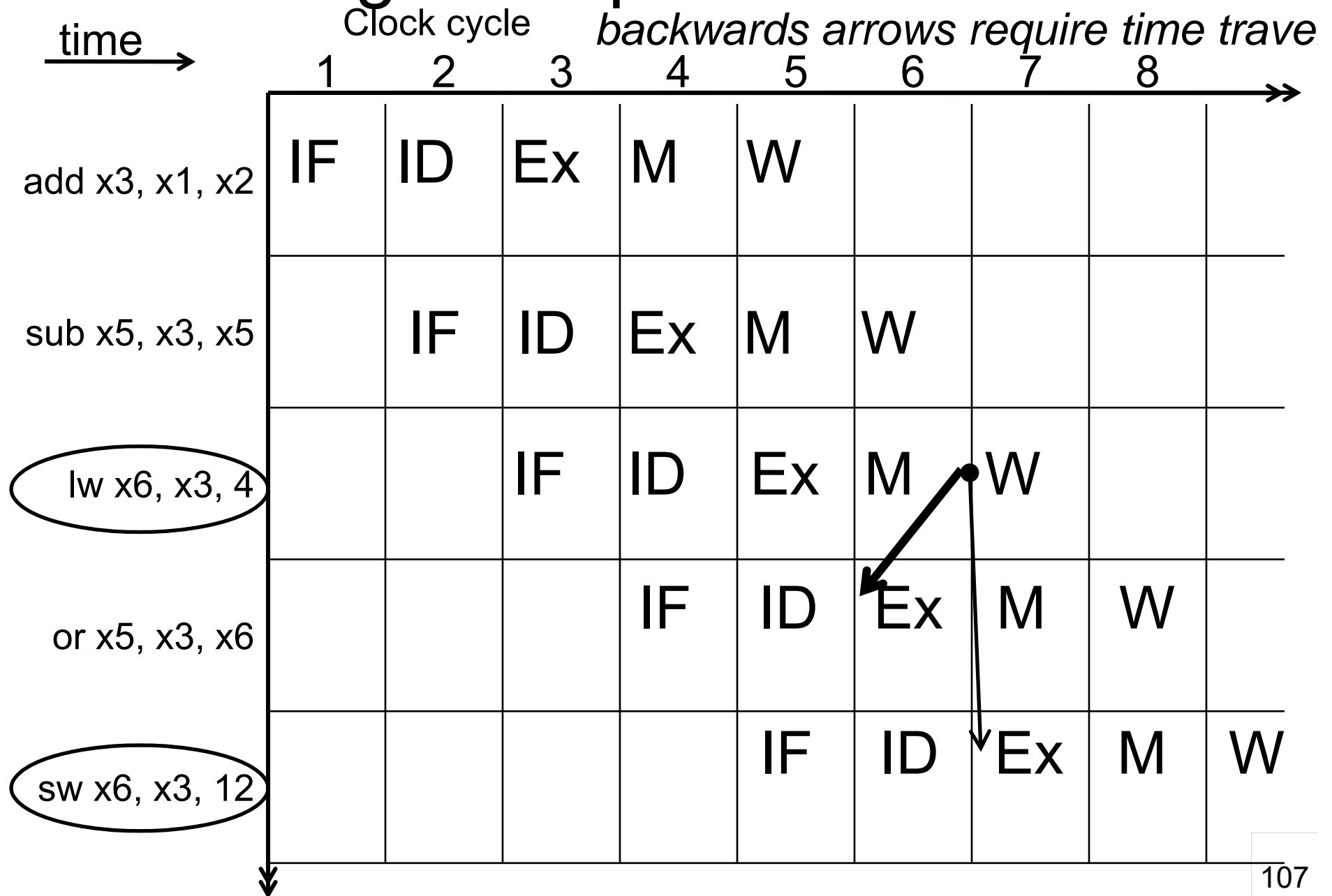
# Forwarding Example 2



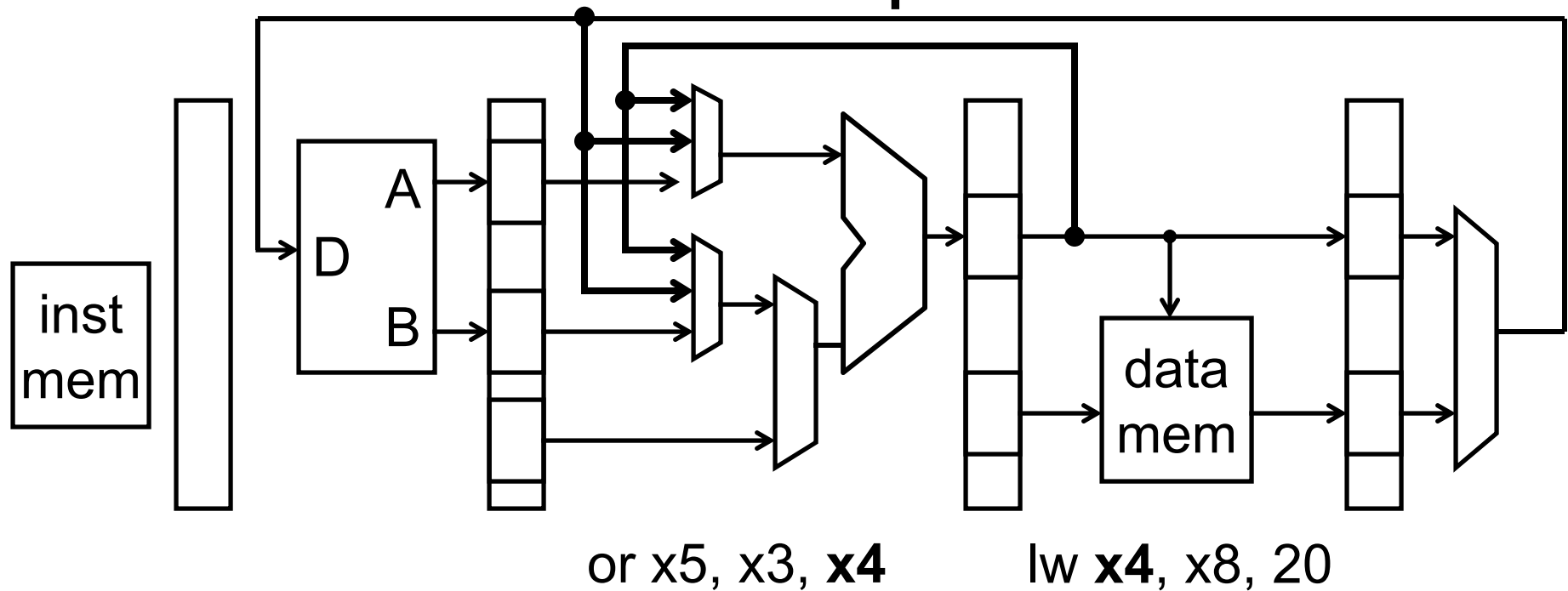
# Forwarding Example 2



# Forwarding Example 2



# Load-Use Hazard Explained

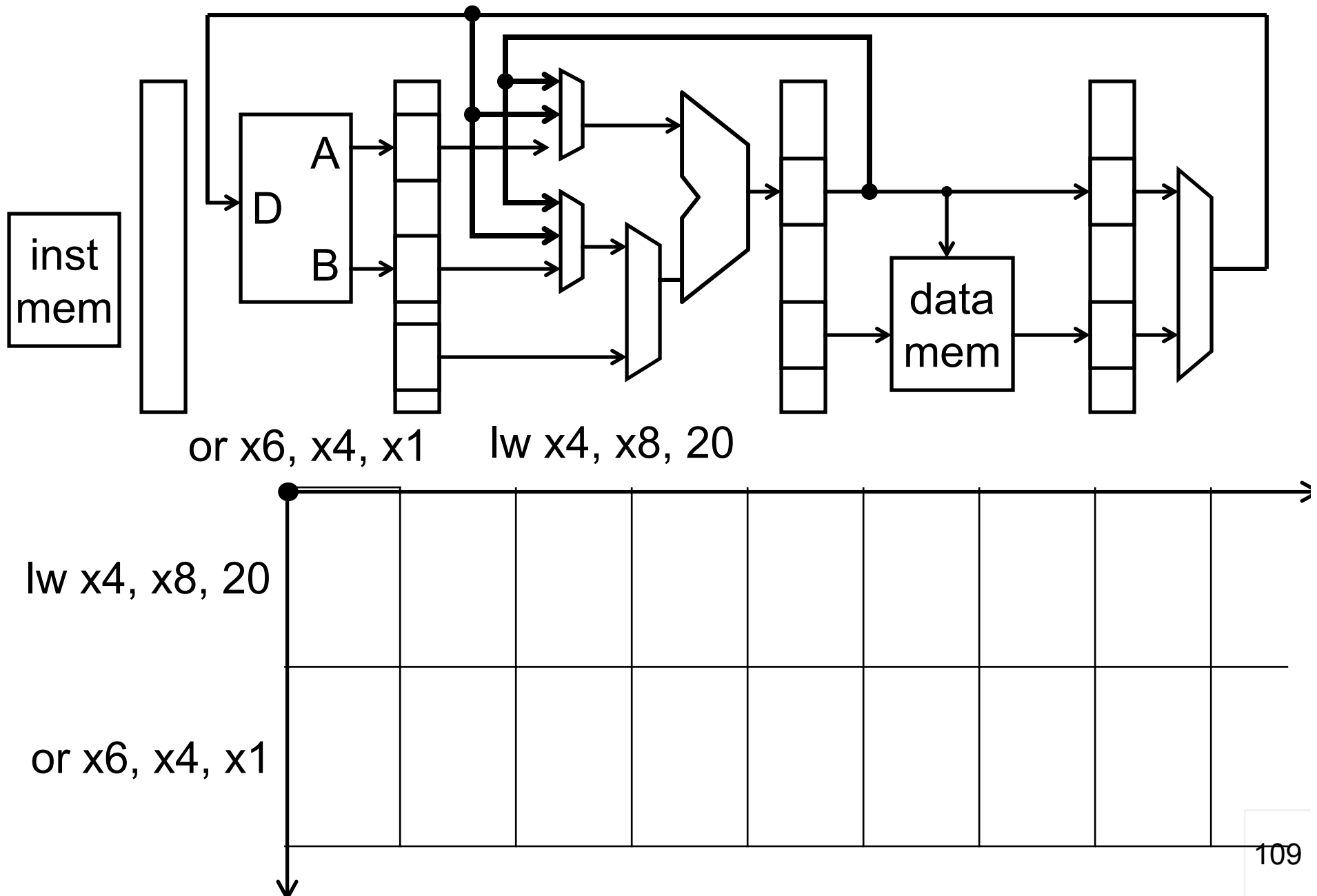


Data dependency after a load instruction:

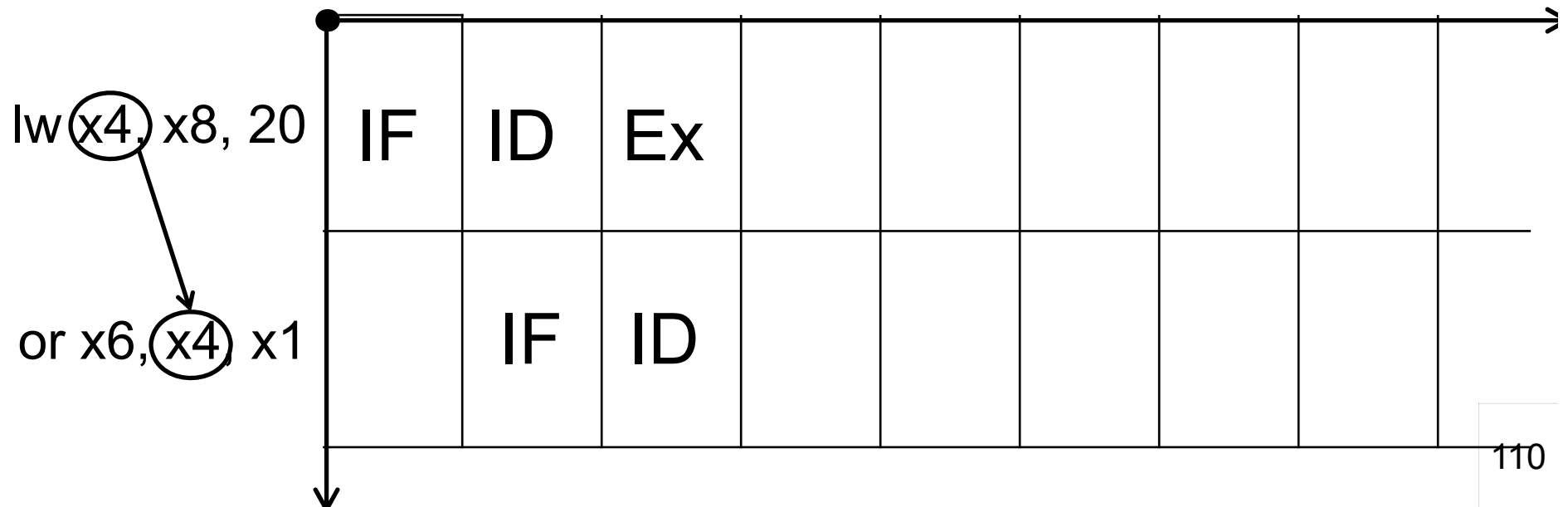
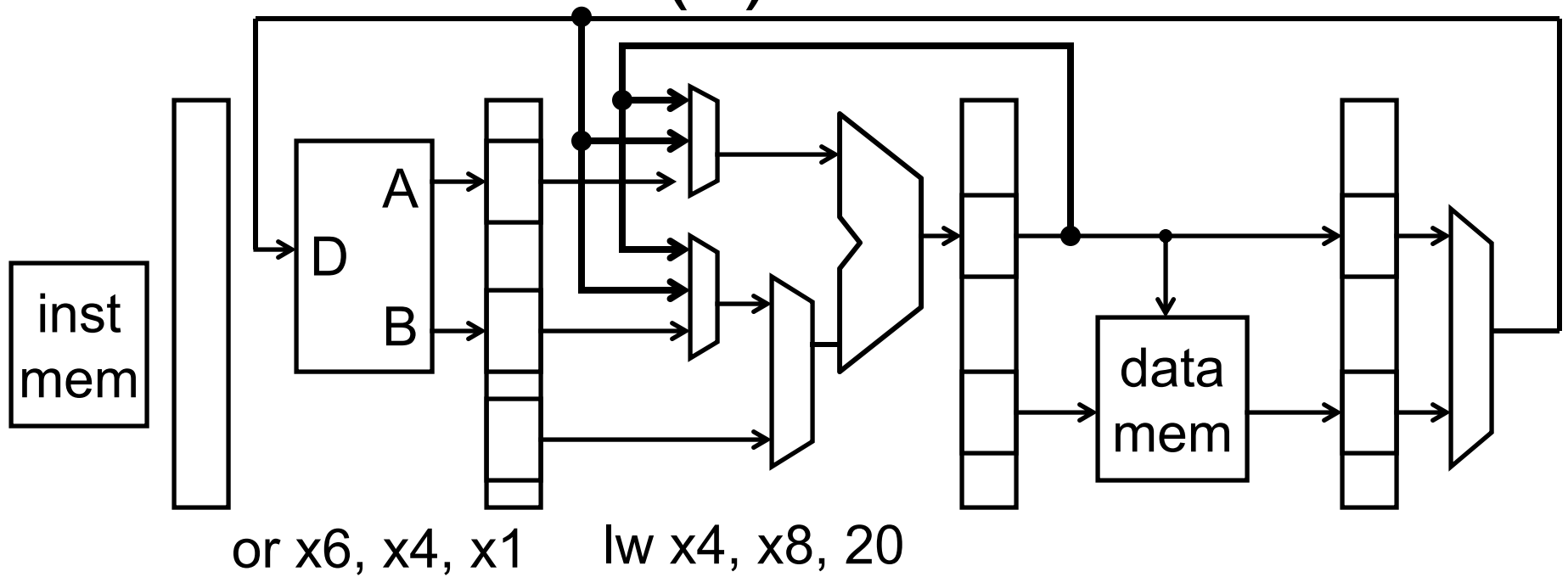
- Value not available until **after** the M stage  
→ Next instruction cannot proceed if dependent

***THE KILLER HAZARD***

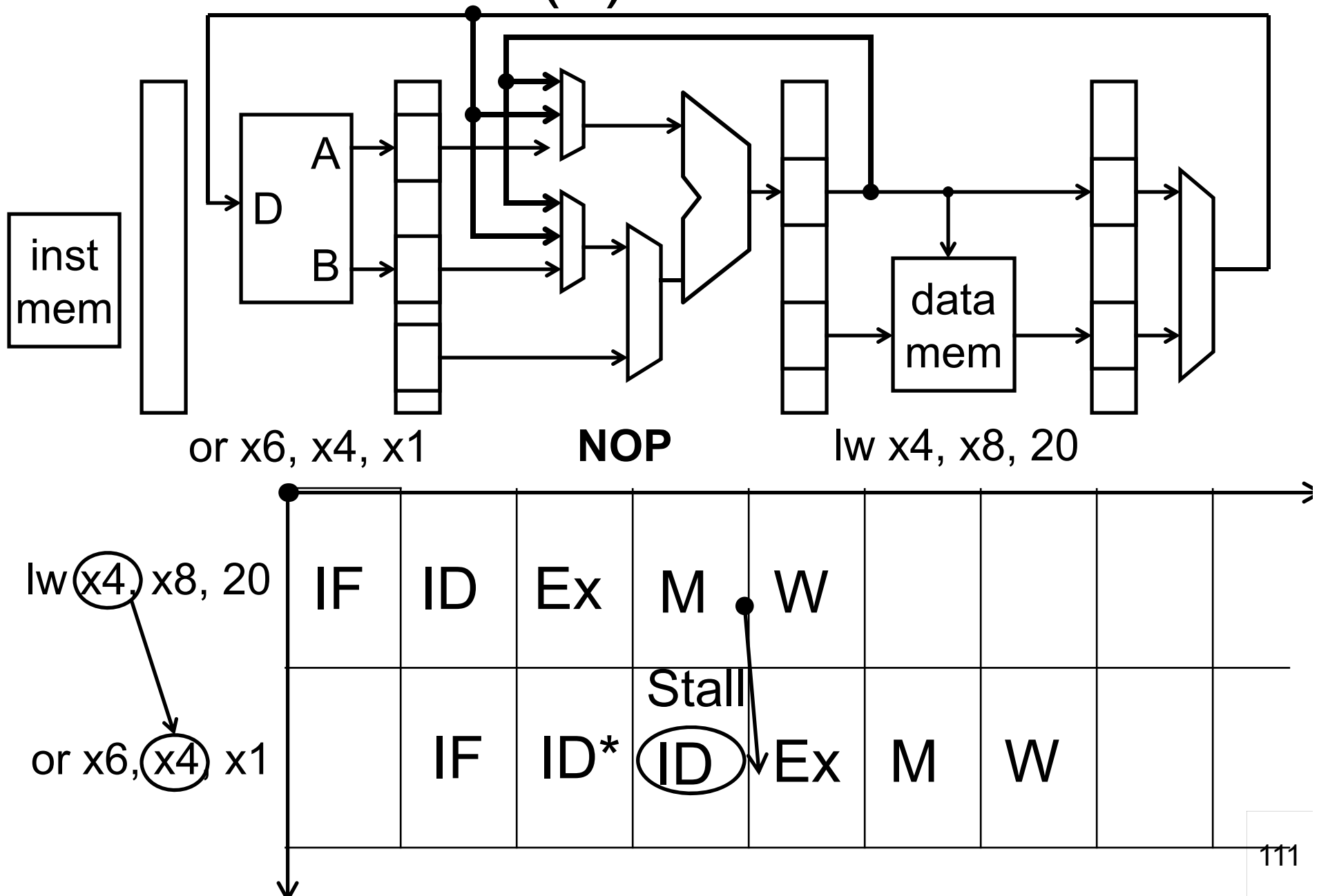
# Load-Use Stall



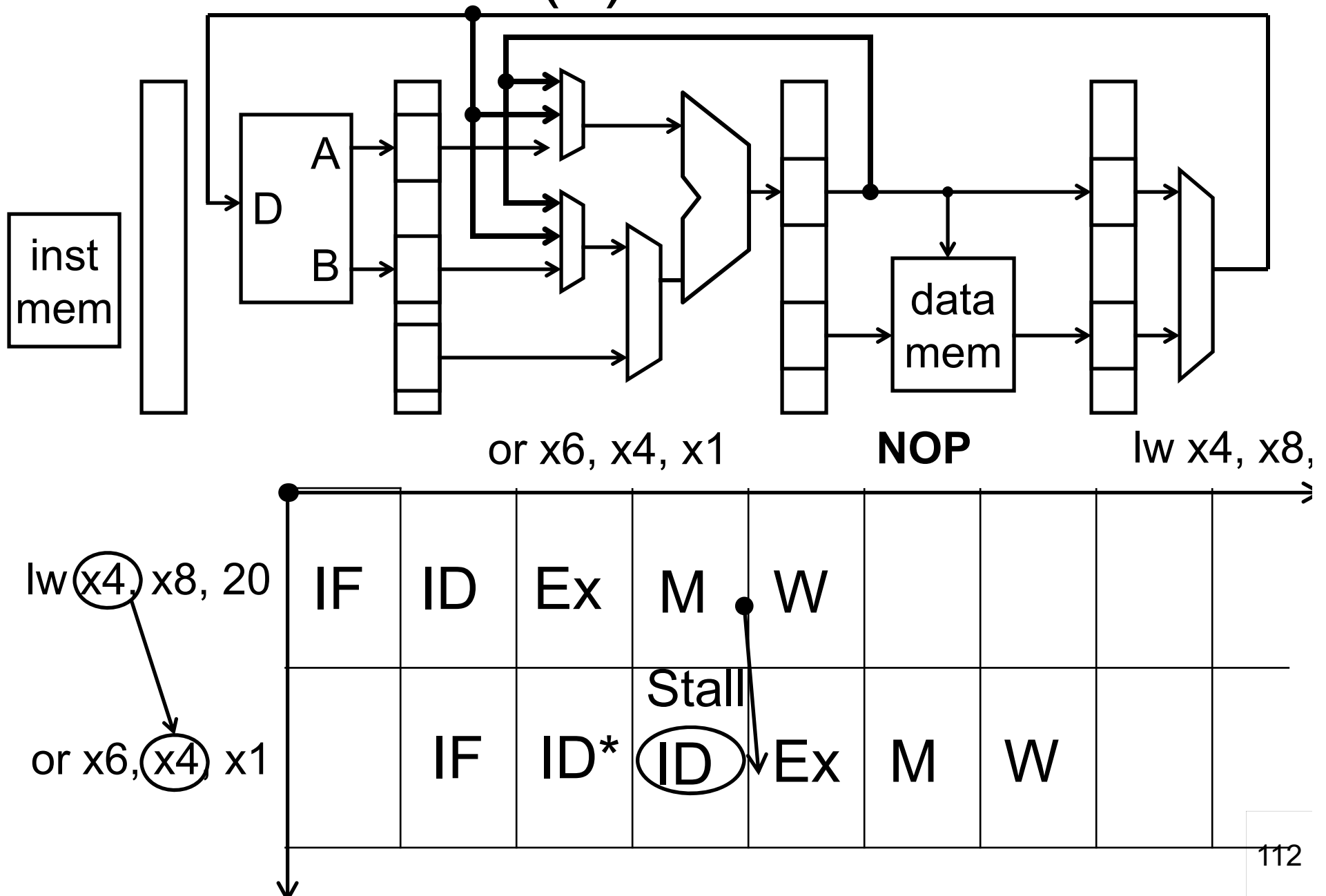
# Load-Use Stall (1)



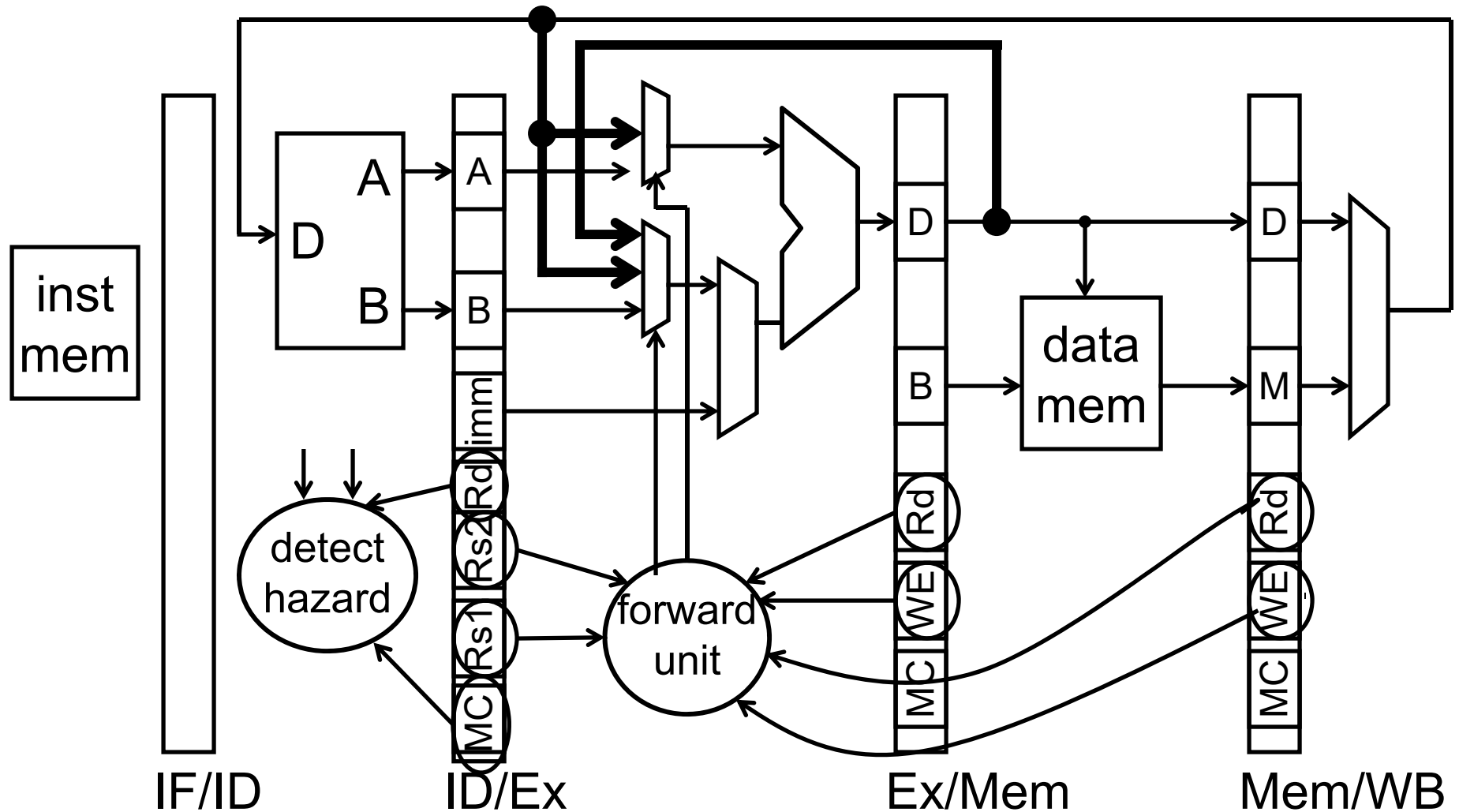
# Load-Use Stall (2)



# Load-Use Stall (3)

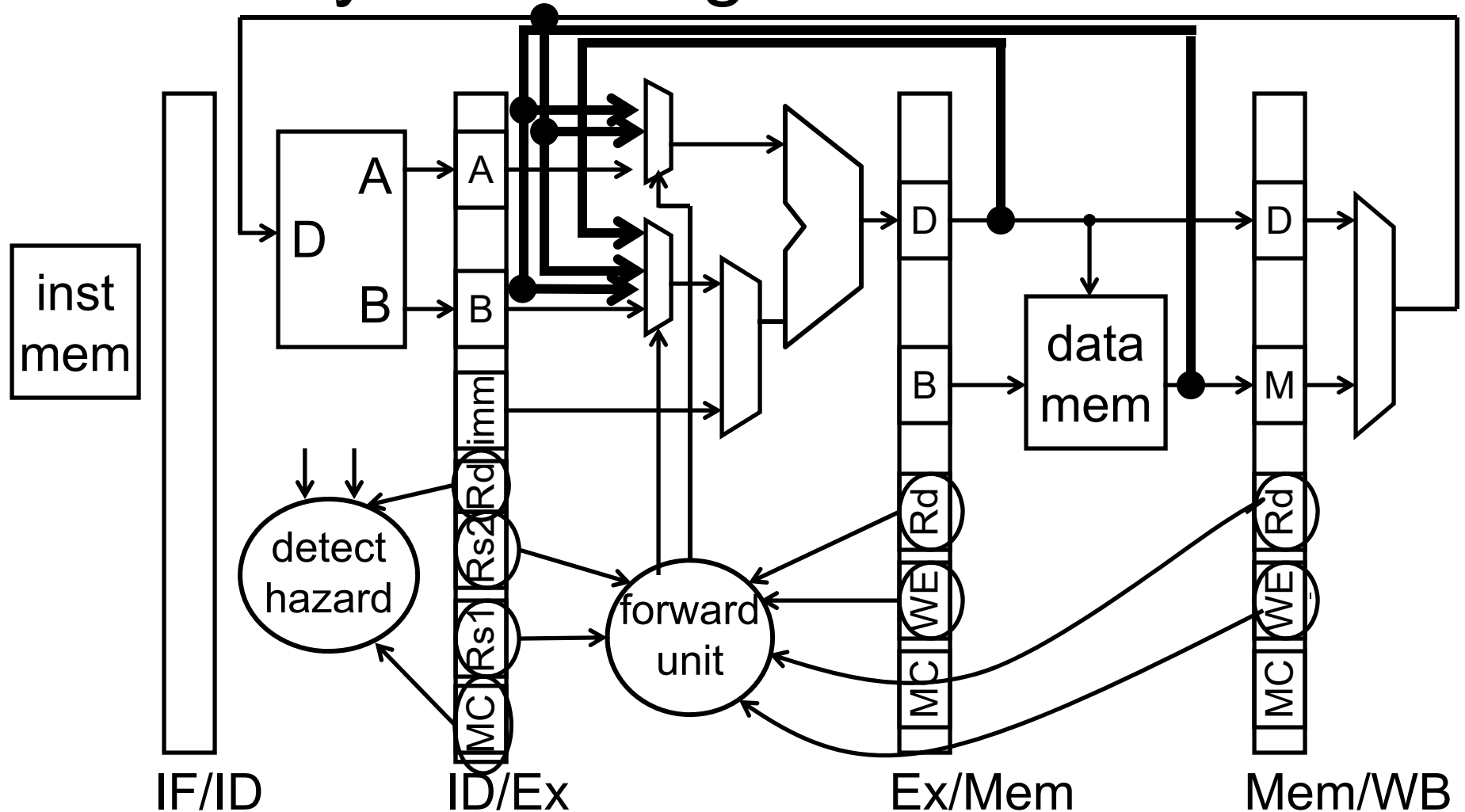


# Load-Use Detection



Stall = If(ID/Ex.MemRead &&  
IF/ID.Rs1 == ID/Ex.Rd

# Incorrectly Resolving Load-Use Hazards



## Most frequent 3410 **non-solution** to load-use hazards

# Why is this “solution” so so so so so so so awful?

# iClicker Question

Forwarding values directly from Memory to the Execute stage without storing them in a register first:

- A. Does not remove the need to stall.
- B. Adds one too many possible inputs to the ALU.
- C. Will cause the pipeline register to have the wrong value.
- D. Halves the frequency of the processor.
- E. Both A & D

# iClicker Question

Forwarding values directly from Memory to the Execute stage without storing them in a register first:

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- D. Halves the frequency of the processor.
- E. Both A & D

# Resolving Load-Use Hazards

## RISC-V Solution : Load-Use Stall

- Stall must be inserted so that load instruction can go through and update the register file.
- Forwarding from RAM is not an option.
- In some cases, real world compilers can optimize to avoid these situations.

# Takeaway

Data hazards occur when an operand (register) depends on the result of a previous instruction that may not be computed yet. A pipelined processor needs to detect data hazards.

Stalling, preventing a dependent instruction from advancing, is one way to resolve data hazards. Stalling introduces NOPs (“bubbles”) into a pipeline. Introduce NOPs by (1) preventing the PC from updating, (2) preventing writes to IF/ID registers from changing, and (3) preventing writes to memory and register file. Bubbles (nops) in pipeline significantly decrease performance.

Forwarding bypasses some pipelined stages forwarding a result to a dependent instruction operand (register). Better performance than stalling.

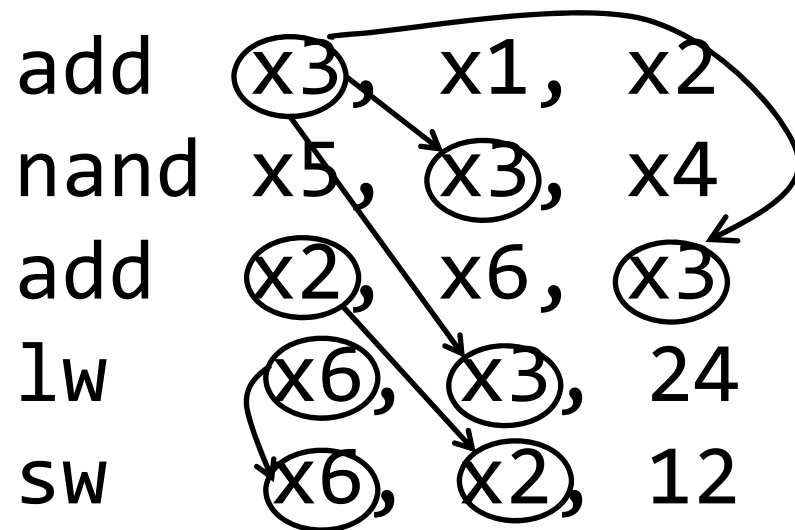
# Quiz

Find all hazards, and say how they are resolved:

```
add    x3, x1, x2
nand   x5, x3, x4
add    x2, x6, x3
lw     x6, x3, 24
sw     x6, x2, 12
```

# Quiz

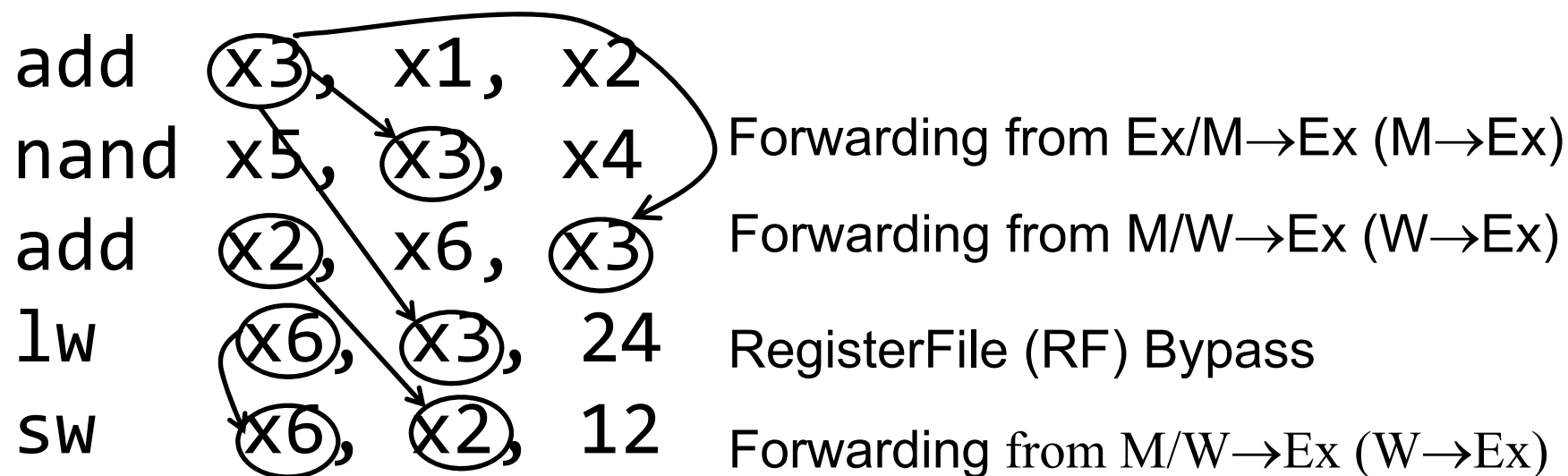
Find all hazards, and say how they are resolved:



5 Hazards

# Quiz

Find all hazards, and say how they are resolved:



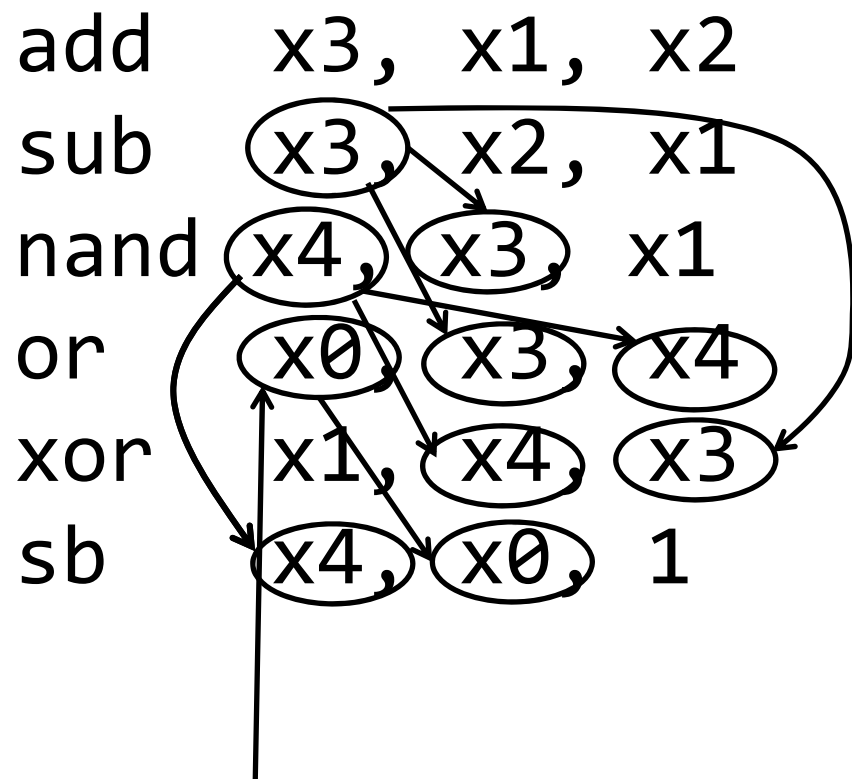
***Stall***

+ Forwarding from M/W→Ex (W→Ex)

**5 Hazards**

# Quiz

Find all hazards, and say how they are resolved:



Hours and hours of debugging!

# Data Hazard Recap

## Delay Slot(s)

- Modify ISA to match implementation

## Stall

- Pause current and all subsequent instructions

## Forward/Bypass

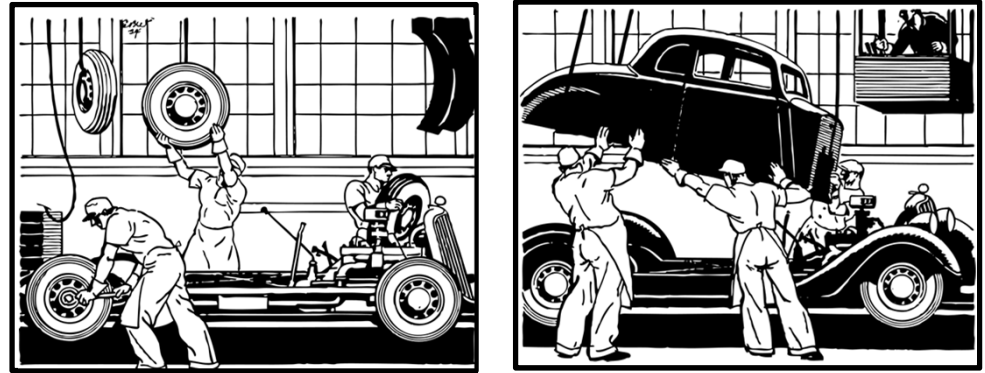
- Try to steal correct value from elsewhere in pipeline
- Otherwise, fall back to stalling or require a delay slot

## Tradeoffs?

# Agenda

## 5-stage Pipeline

- Implementation
- Working Example



## Hazards

- Structural
- Data Hazards
- Control Hazards

# A bit of Context

```
i = 0;
do {
    n += 2;
    i++;
} while(i < max)
i = 7;
n--;
```

*i* → x1

*Assume:*

*n* → x2

*max* → x3

x10	addi x1, x0, 0	# i=0
x14	Loop: addi x2, x2, 2	# n += 2
x18	addi x1, x1, 1	# i++
x1C	blt x1, x3, Loop	# i<max?
x20	addi x1, x0, 7	# i = 7
x24	subi x2, x2, 1	# n--

# Control Hazards

## Control Hazards

- instructions are fetched in stage 1 (IF)
- branch and jump decisions occur in stage 3 (EX)
  - next PC not known until **2 cycles** after branch/jump

```
x1C    blt    x1, x3, Loop
x20    addi   x1, x0, 7
x24    subi   x2, x2, 1
```

Branch **not** taken?

No Problem!

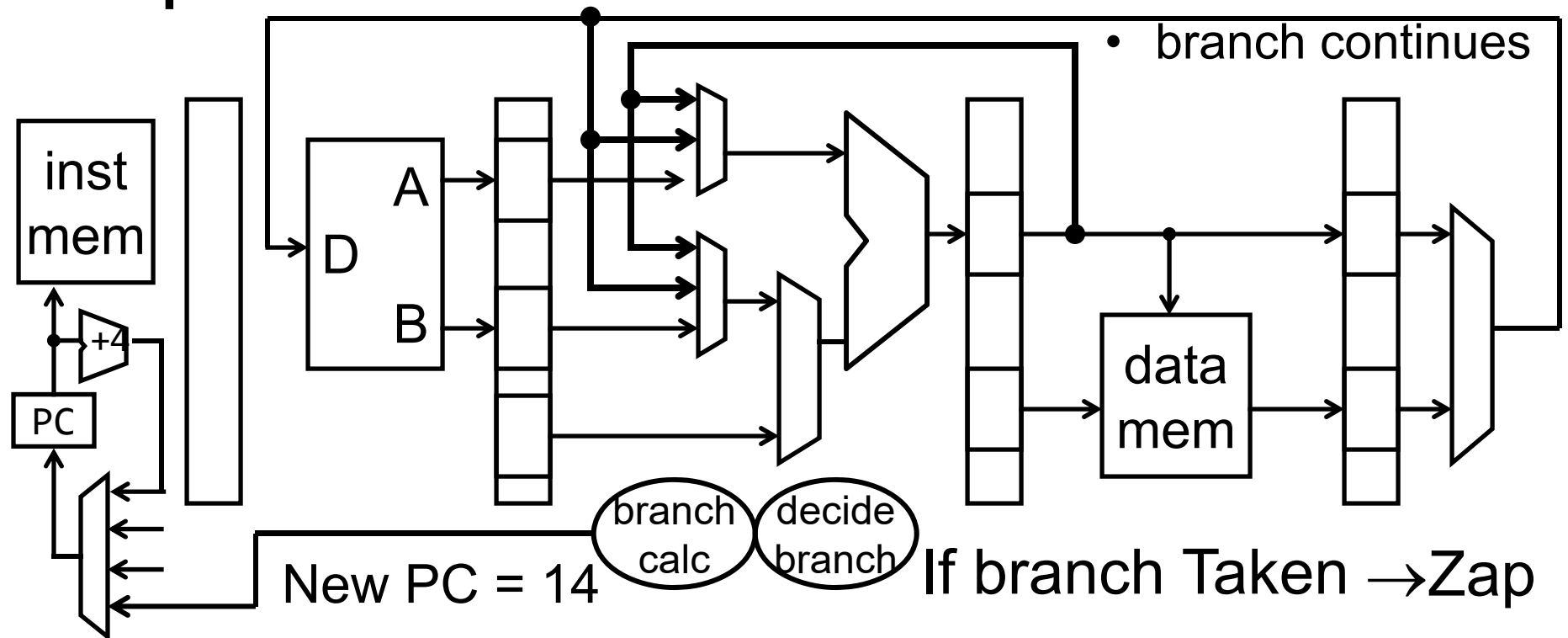
Branch taken?

Just fetched 2 insns

→ **Zap & Flush**

# Zap & Flash

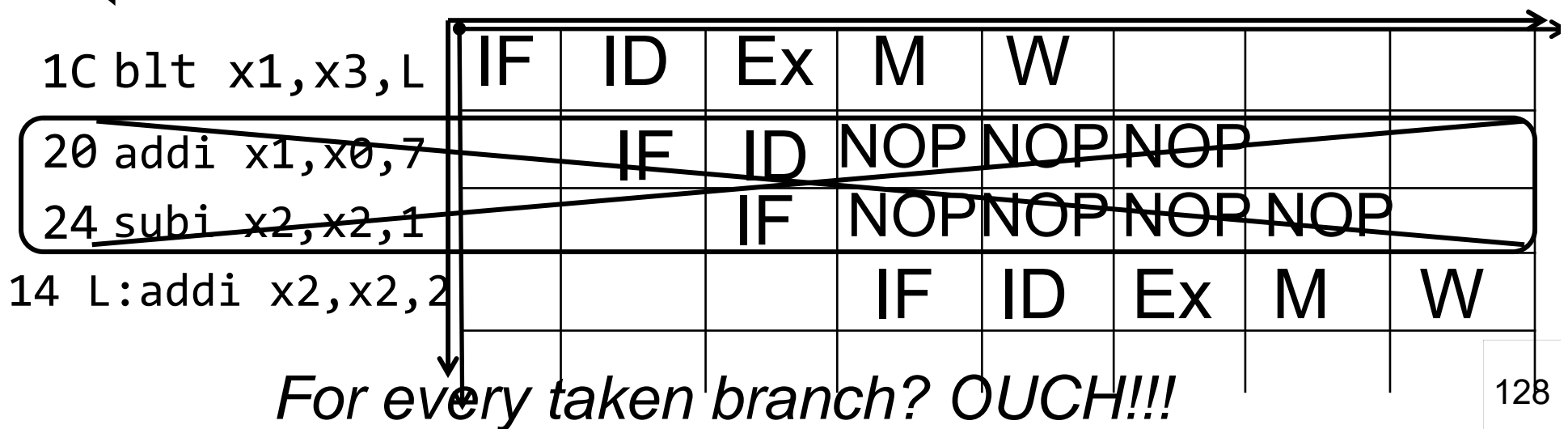
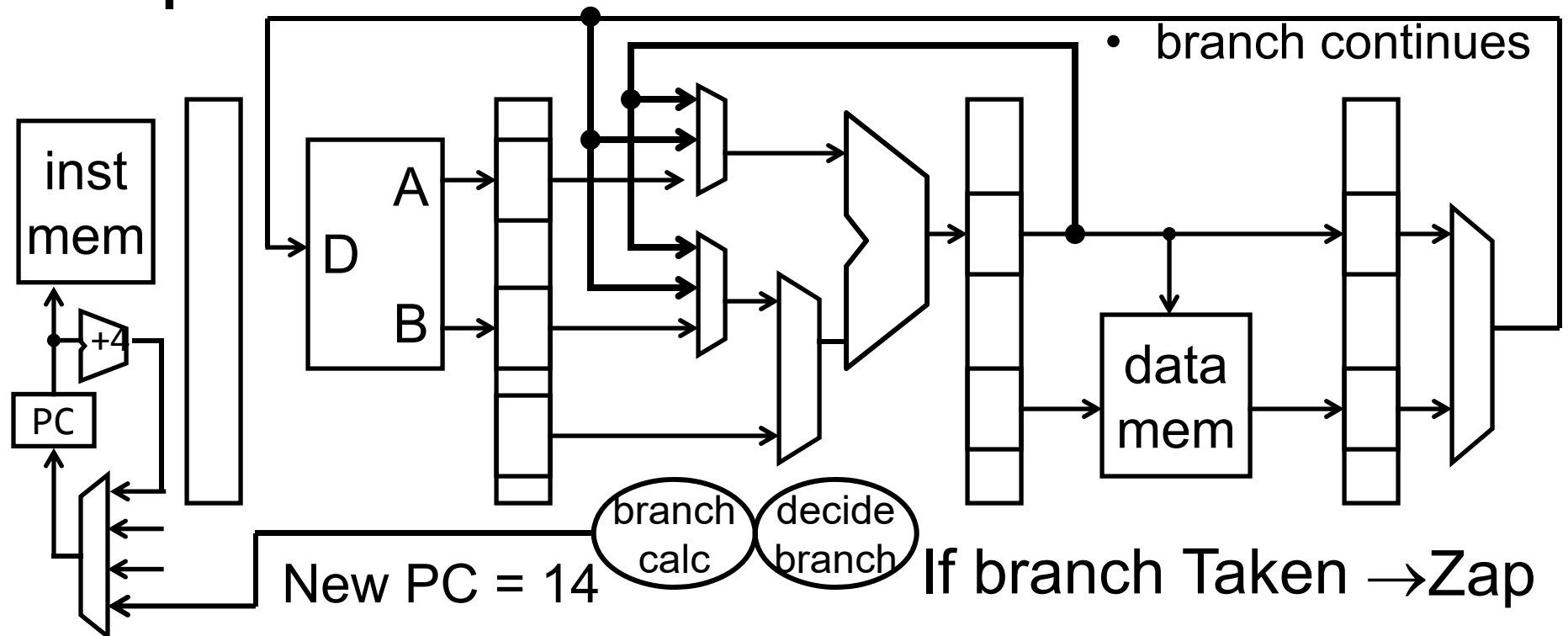
- prevent PC update
- clear IF/ID latch
- branch continues



1C blt x1,x3,L	IF	ID	Ex	M	W			
20 addi x1,x0,7		IF	ID	NOP	NOP	NOP		
24 subi x2,x2,1			IF	NOP	NOP	NOP	NOP	
14 L:addi x2,x2,2				IF	ID	Ex	M	W

# Zap & Flash

- prevent PC update
- clear IF/ID latch
- branch continues



# Reducing the cost of control hazard

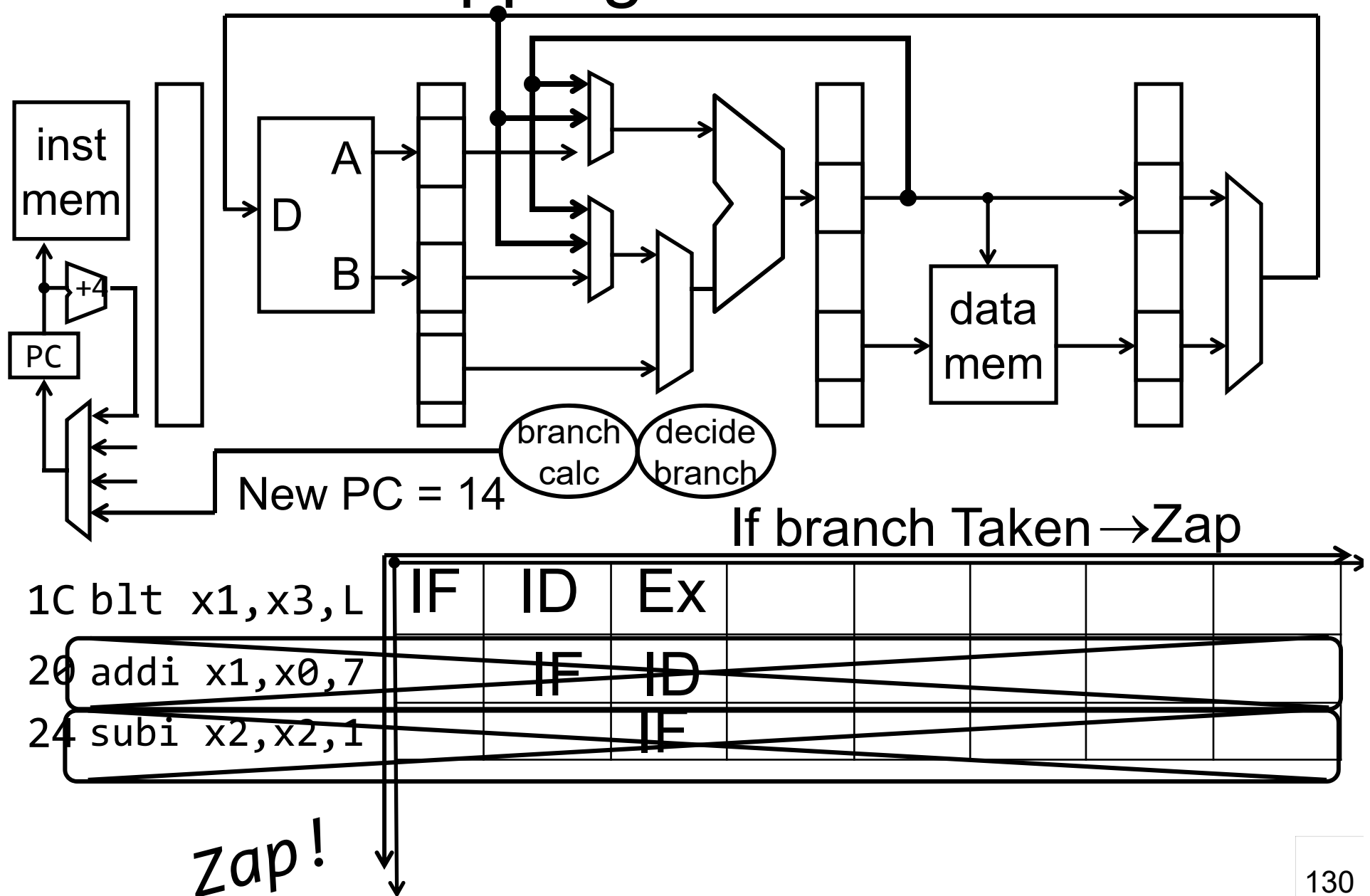
## 1. Resolve Branch at Decode

- Some groups do this for Project 3, your choice
- Move branch calc from EX to ID
- Alternative: just zap 2<sup>nd</sup> instruction when branch taken

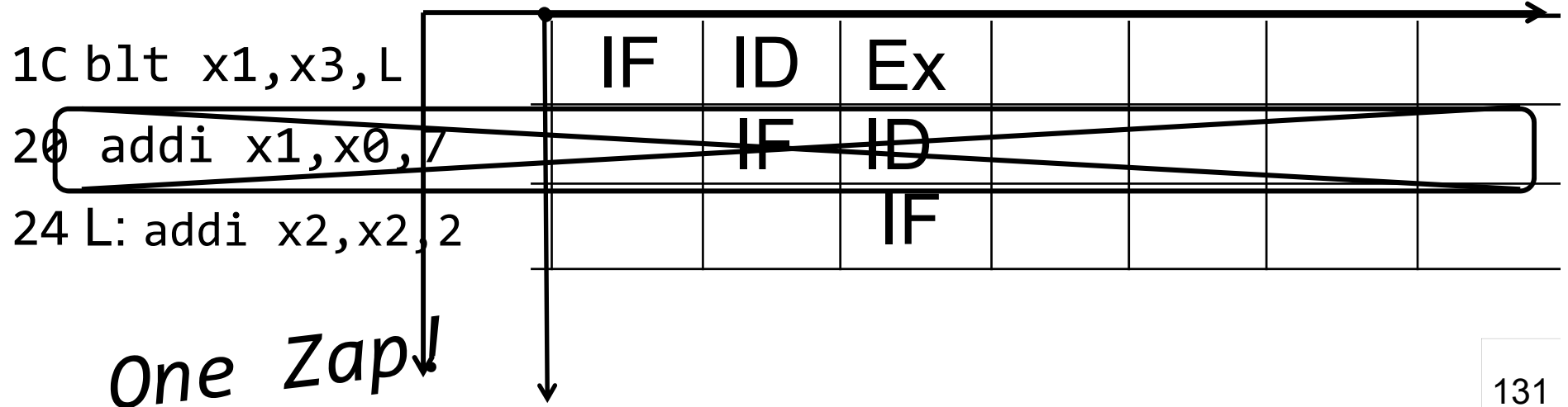
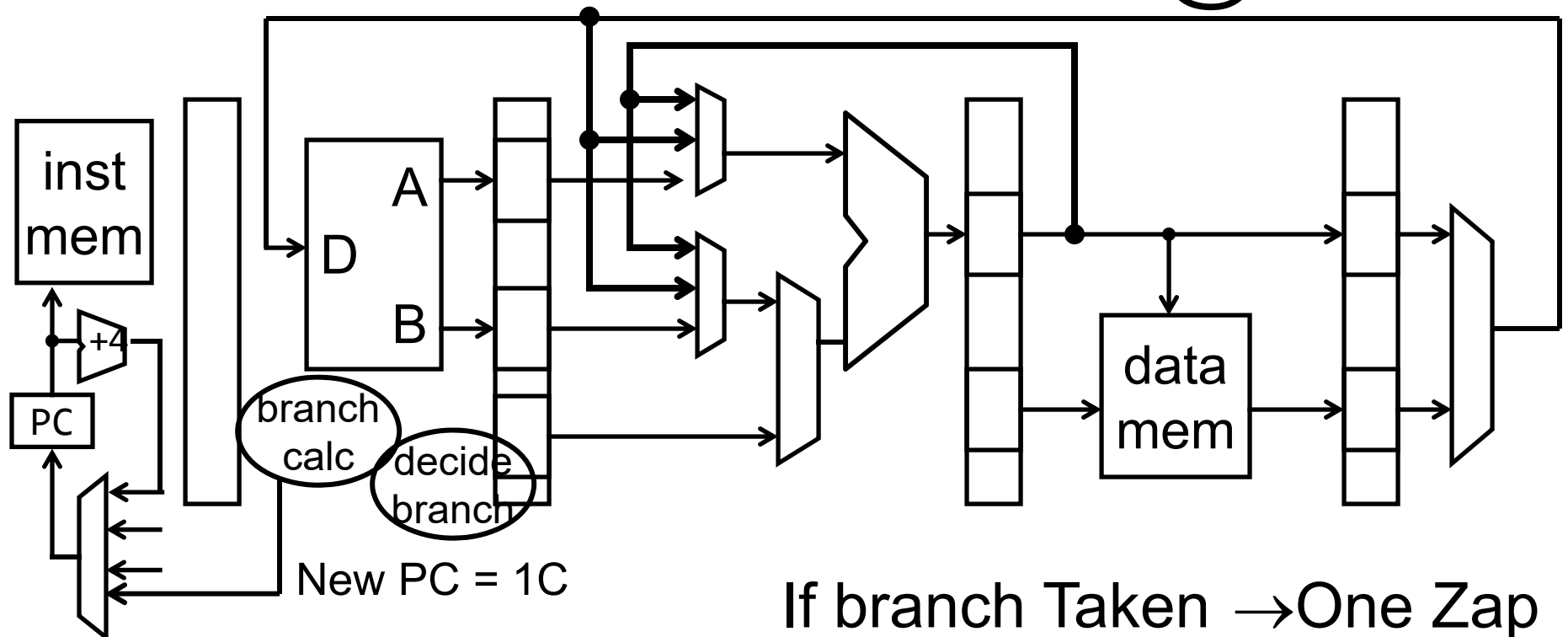
## 2. Branch Prediction

- Not in 3410, but every processor worth *anything* does this (*no offense!*)

# Problem: Zapping 2 insns/branch



# Soln #1: Resolve Branches @ Decode



# Branch Prediction

Most processor support **Speculative Execution**

- *Guess* direction of the branch
  - Allow instructions to move through pipeline
  - Zap them later if guess turns out to be wrong
- *A must* for long pipelines

# Speculative Execution: Loops

## Pipeline so far

- “Guess” (predict) that the branch will not be taken

## We can do better!

- Make prediction based on last branch
- Predict “take branch” if last branch “taken”
- Or Predict “do not take branch” if last branch “not taken”
- Need one bit to keep track of last branch

# Speculative Execution: Loops

What is accuracy of  
branch predictor?

Wrong twice per  
loop!

Once on loop enter  
and exit

We can do better  
with 2 bits

While (x3  $\neq$  0) {.... x3--;}

Top: BEQ x3, x0, End



J Top

End:

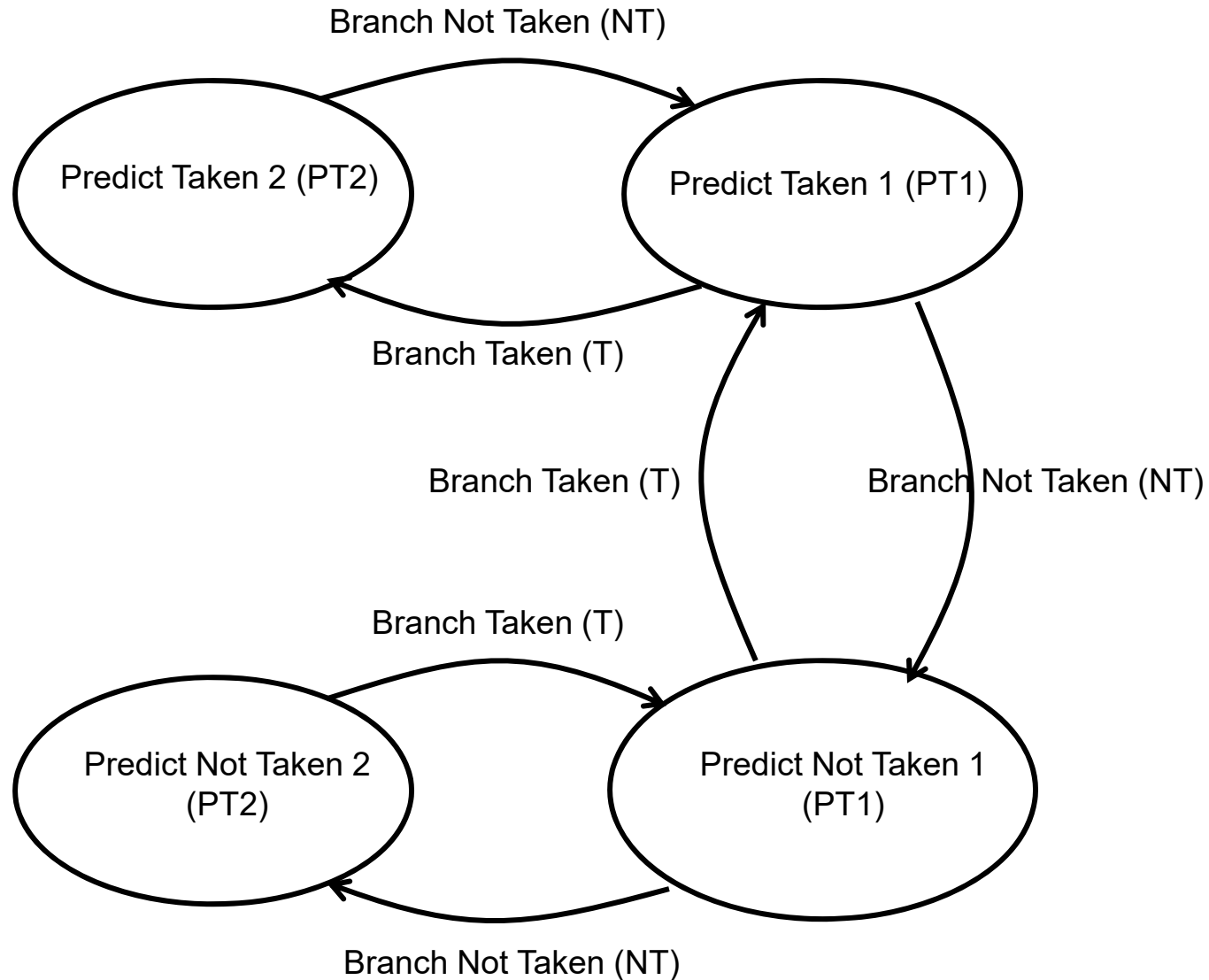
While (r3  $\neq$  0) {.... r3--;}

Top2: BEQ x3, x0, End2

J Top

End2:

# Speculative Execution: Branch Execution



# Summary

## Control hazards

- Is branch taken or not?
- Performance penalty: stall and flush

## Reduce cost of control hazards

- Move branch decision from Ex to ID
  - 2 nops to 1 nop
- **Branch prediction**
  - Correct. Great!
  - Wrong. Flush pipeline. Performance penalty



# Hazards Summary

Data hazards

Control hazards

Structural hazards

- resource contention
- so far: impossible because of ISA and pipeline design



# Hazards Summary

## Data hazards

- register file reads occur in stage 2 (IF)
- register file writes occur in stage 5 (WB)
- next instructions may read values soon to be written

## Control hazards

- branch instruction may change the PC in stage 3 (EX)
- next instructions have already started executing

## Structural hazards

- resource contention
- so far: impossible because of ISA and pipeline design



# Data Hazard Takeaways

Data hazards occur when an operand (register) depends on the result of a previous instruction that may not be computed yet. Pipelined processors need to detect data hazards.

Stalling, preventing a dependent instruction from advancing, is one way to resolve data hazards. Stalling introduces NOPs (“bubbles”) into a pipeline. Introduce NOPs by (1) preventing the PC from updating, (2) preventing writes to IF/ID registers from changing, and (3) preventing writes to memory and register file. Nops significantly decrease performance.

Forwarding bypasses some pipelined stages forwarding a result to a dependent instruction operand (register). Better performance than stalling.

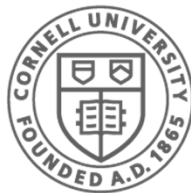
# Control Hazard Takeaways

Control hazards occur because the PC following a control instruction is not known until control instruction is executed. If branch is taken → need to zap instructions. 1 cycle performance penalty.

We can reduce cost of a control hazard by moving branch decision and calculation from Ex stage to ID stage.



# Have a great February Break!!



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