I/O

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CS 3410, Spring 2014

Computer Science

Cornell University

See: ***Online*** P&H Chapter 6.9 (5th edition):

http://booksite.elsevier.com/9780124077263/downloads/advance_contents_and_appendices/section_6.9.pdf

Also, ***Online*** P&H Chapter 6.5-6 (4th edition)

Administrivia

Project3 submit "*souped up*" bot to CMS

Project3 Cache Race Games night Monday, May 5th, 5pm

- **Come, eat, drink, have fun and be merry!**
- **Location: B11 Kimball Hall**

Prelim2: ***Today, Thursday***, May nd in evening

- Time: We will start at ***7:30pm sharp***, so come early
- **Two Locations: OLN155 and URSG01**
  - **If NetID *begins* with 'a' to 'g', then go to OLN155 (Olin Hall rm 155)**
  - **If NetID *begins* with 'h' to 'z', then go to URSG01 (Uris Hall rm G01)**

Project4:

- Design Doc due May 7th, bring design doc to mtg May 5-7
- Demos: May 13 and 14
- ***Will not be able to use slip days***

Administrivia

Next 2 weeks

- Prelim2 ***Today***, Thu May 1st : 7:30-9:30
  - Olin 155: Netid [a-g]*
  - Uris G01: Netid [h-z]*
- Proj3 tournament: Mon May 5 5pm-7pm (Pizza!)
  - Location: Kimball B11
- Proj4 design doc meetings May 5-7 (doc ready for mtg)

Final Project for class

- Proj4 due Wed May 14
- Proj4 demos: May 13 and 14
- Proj 4 release: in labs this week
- Remember: No slip days for PA4

Goals for Today

Computer System Organization

How does a processor interact with its environment?

- I/O Overview

How to talk to device?

- Programmed I/O or Memory-Mapped I/O

How to get events?

- Polling or Interrupts

How to transfer lots of data?

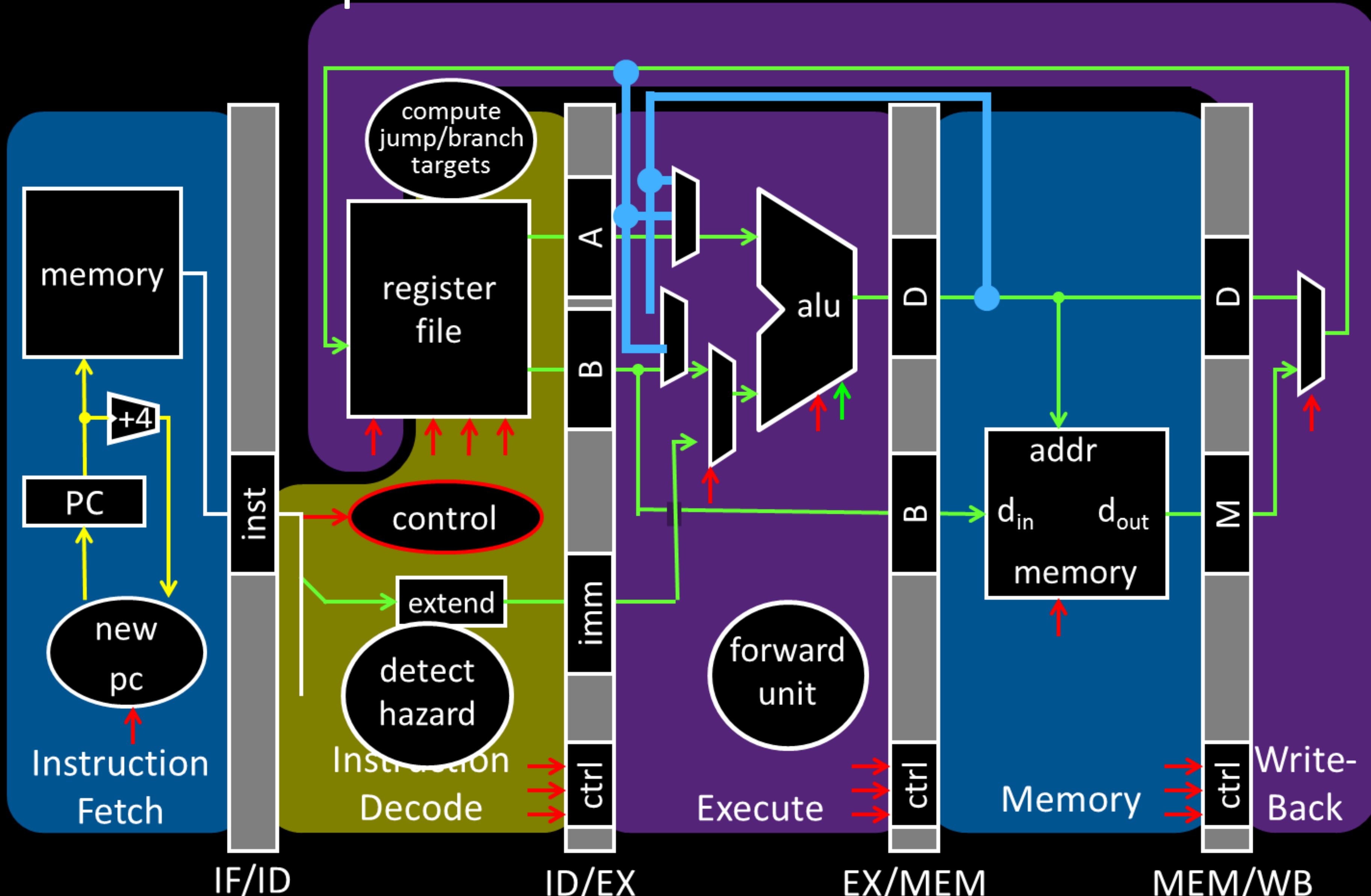
- Direct Memory Access (DMA)

Next Goal

How does a processor interact with its environment?

Big Picture: Input/Output (I/O)

How does a processor interact with its environment?



Big Picture: Input/Output (I/O)

How does a processor interact with its environment?

Computer System Organization =

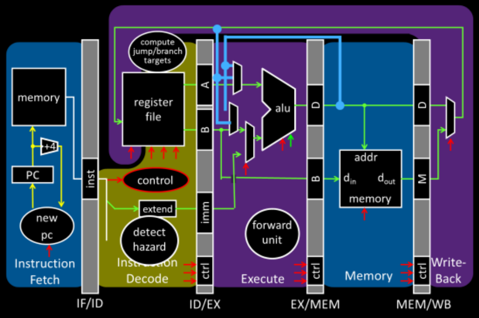
Memory +

Datapath +

Control +

Input +

Output



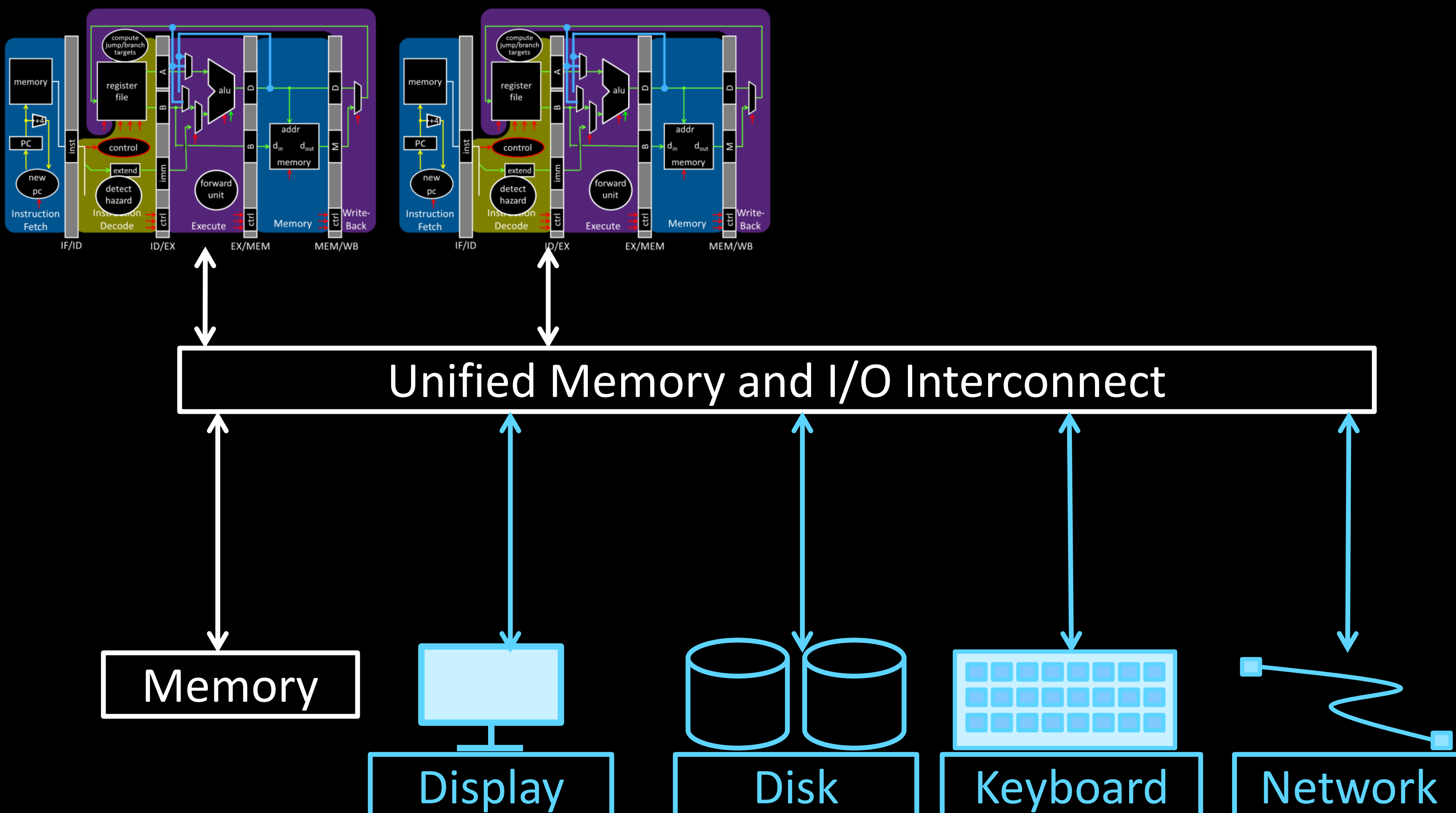
I/O Devices Enables Interacting with Environment

Device	Behavior	Partner	Data Rate (b/sec)
Keyboard	Input	Human	100
Mouse	Input	Human	3.8k
Sound Input	Input	Machine	3M
Voice Output	Output	Human	264k
Sound Output	Output	Human	8M
Laser Printer	Output	Human	3.2M
Graphics Display	Output	Human	800M – 8G
Network/LAN	Input/Output	Machine	100M – 10G
Network/Wireless LAN	Input/Output	Machine	11 – 54M
Optical Disk	Storage	Machine	5 – 120M
Flash memory	Storage	Machine	32 – 200M
Magnetic Disk	Storage	Machine	800M – 3G

Attempt#1: All devices on one interconnect

Replace ***all*** devices as the interconnect changes

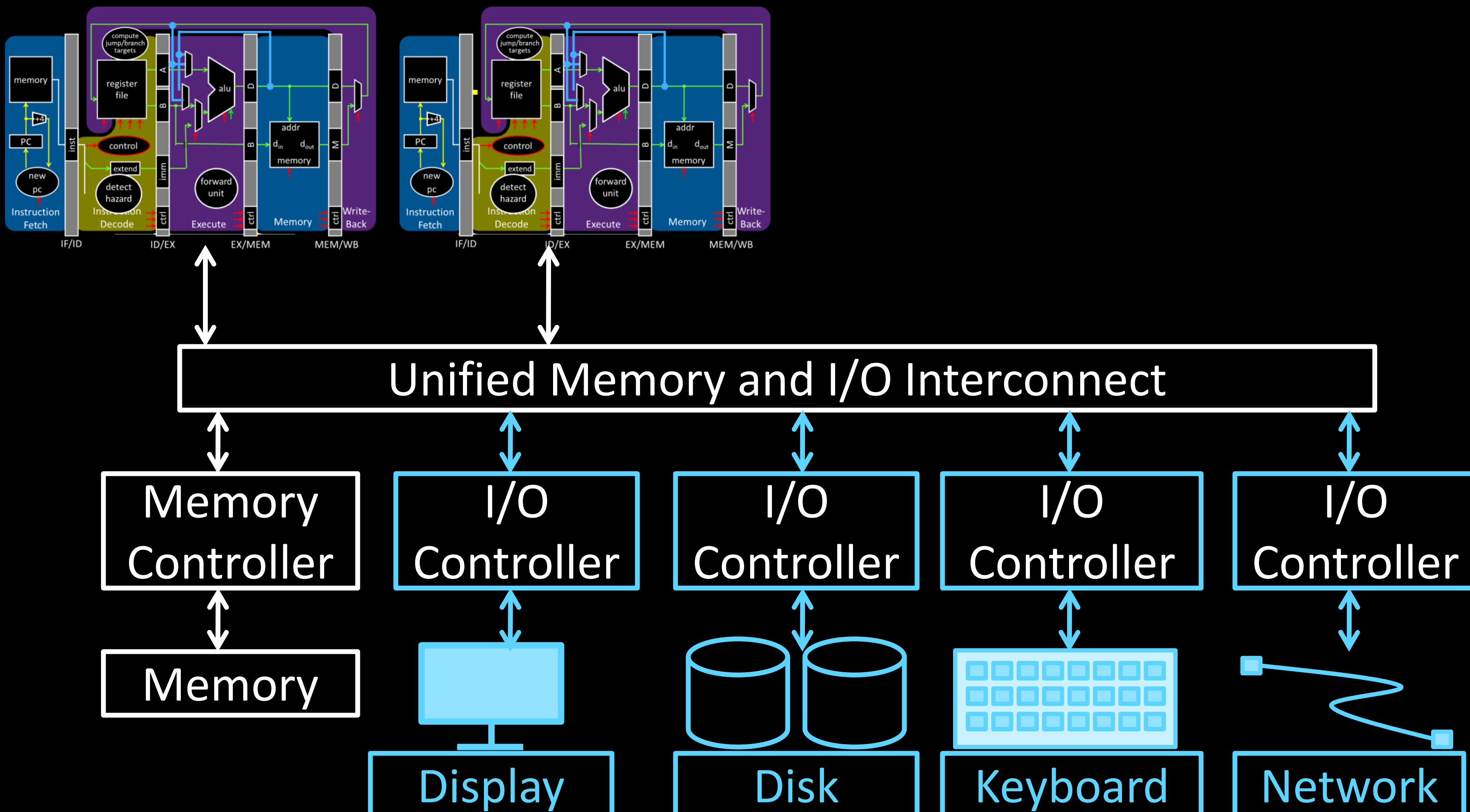
e.g. keyboard speed == main memory speed ?!



Attempt#2: I/O Controllers

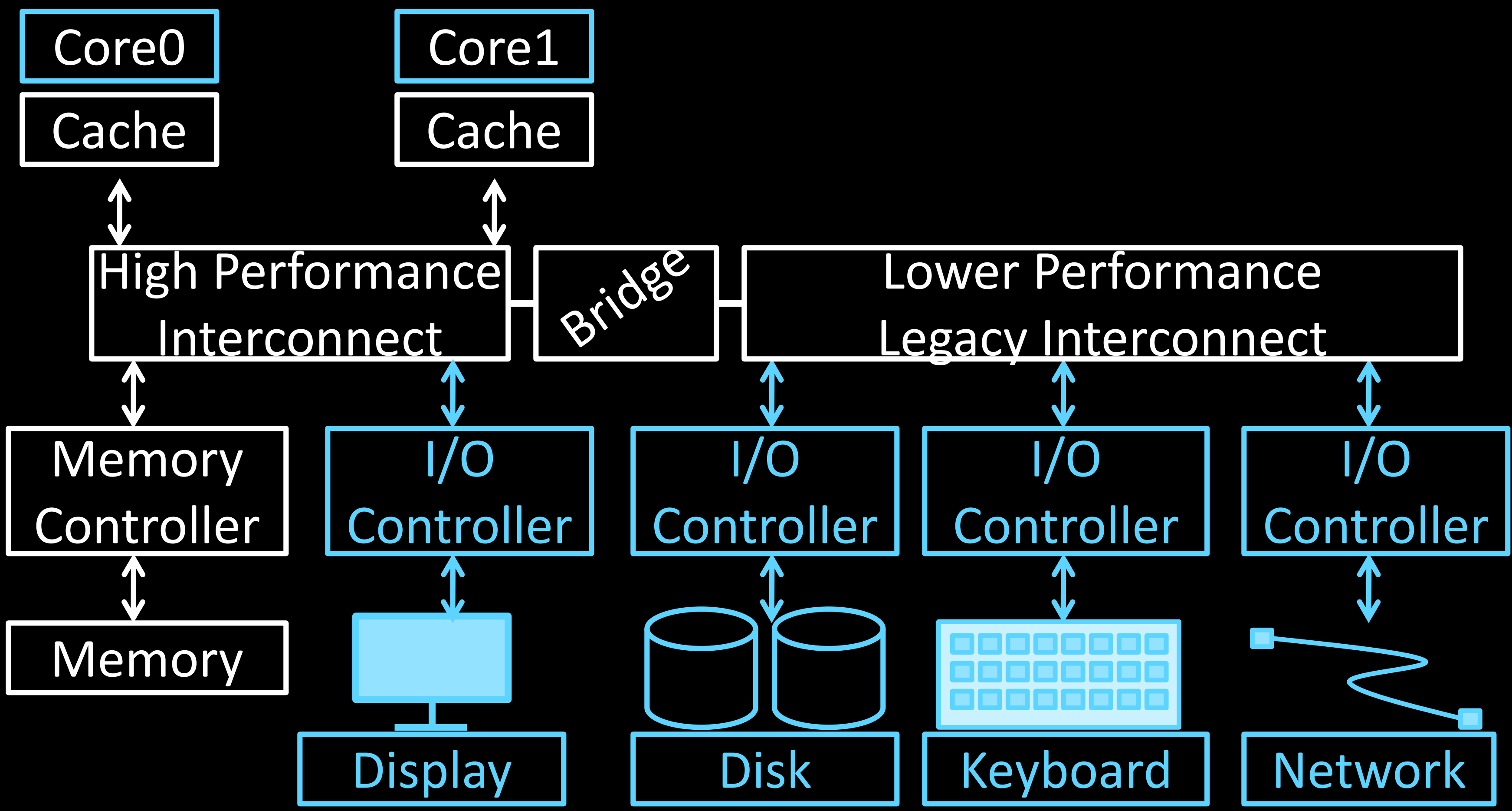
Decouple I/O devices from Interconnect

Enable smarter I/O interfaces



Attempt#3: I/O Controllers + Bridge

Separate high-performance processor, memory, display interconnect from lower-performance interconnect



Bus Parameters

Width = number of wires

Transfer size = data words per bus transaction

Synchronous (with a bus clock)
or asynchronous (no bus clock / "self clocking")

Bus Types

Processor – Memory ("Front Side Bus". Also QPI)

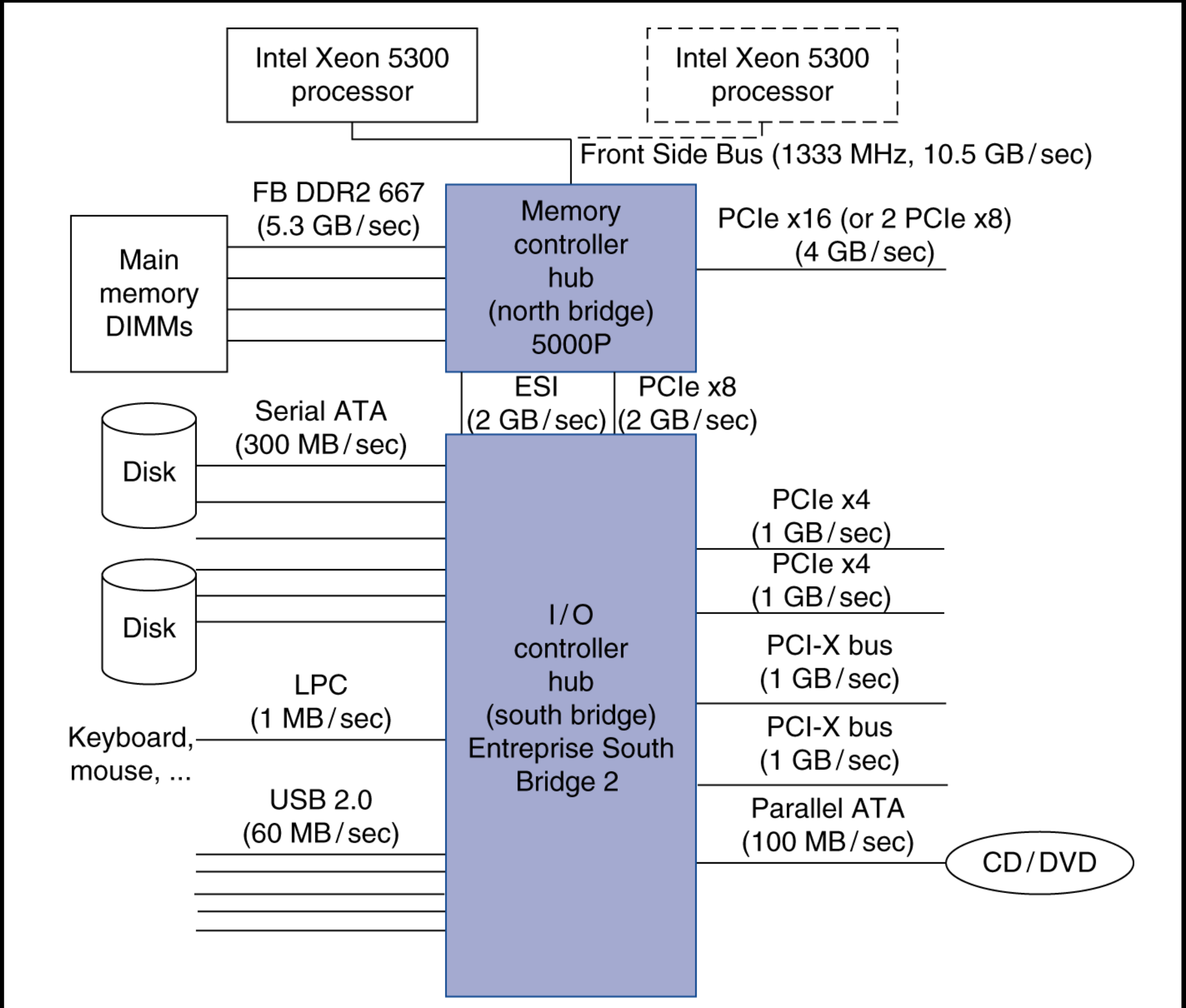
- Short, fast, & wide
- Mostly fixed topology, designed as a "chipset"
  - CPU + Caches + Interconnect + Memory Controller

I/O and Peripheral busses (PCI, SCSI, USB, LPC, …)

- Longer, slower, & narrower
- Flexible topology, multiple/varied connections
- Interoperability standards for devices
- Connect to processor-memory bus through a bridge

Attempt#3: I/O Controllers + Bridge

Separate high-performance processor, memory, display interconnect from lower-performance interconnect



Example Interconnects

Name	Use	Devics per channel	Channel Width	Data Rate (B/sec)
Firewire 800	External	63	4	100M
USB 2.0	External	127	2	60M
USB 3.0	External	127	2	625M
Parallel ATA	Internal	1	16	133M
Serial ATA (SATA)	Internal	1	4	300M
PCI 66MHz	Internal	1	32-64	533M
PCI Express v2.x	Internal	1	2-64	16G/dir
Hypertransport v2.x	Internal	1	2-64	25G/dir
QuickPath (QPI)	Internal	1	40	12G/dir

Interconnecting Components

Interconnects are (were?) busses

- parallel set of wires for data and control
- shared channel
  - multiple senders/receivers
  - everyone can see all bus transactions
- bus protocol: rules for using the bus wires

e.g. Intel Xeon

Alternative (and increasingly common):

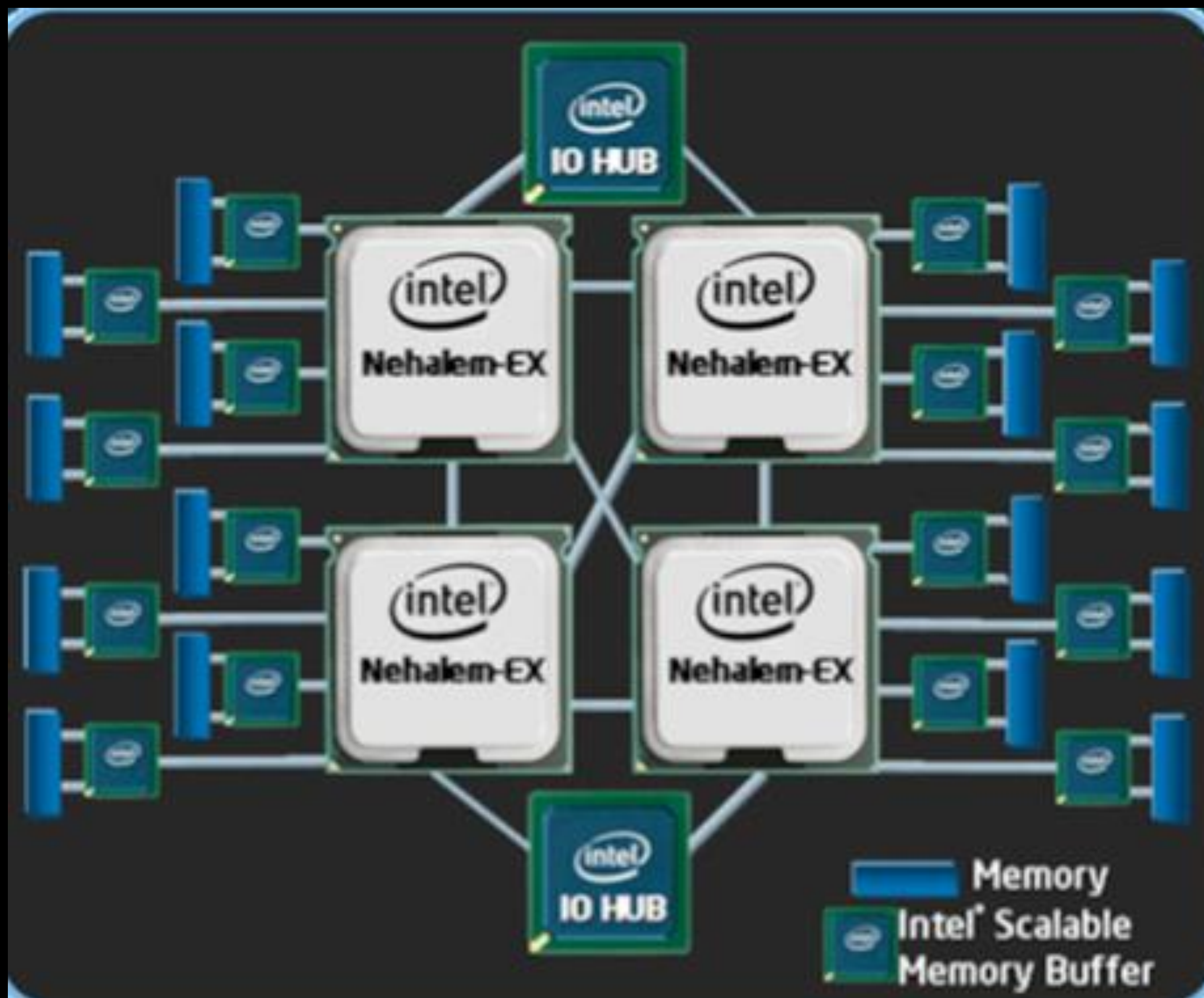
- dedicated point-to-point channels

e.g. Intel Nehalem

Attempt#4: I/O Controllers+Bridge+ NUMA

Remove bridge as bottleneck with Point-to-point interconnects

E.g. Non-Uniform Memory Access (NUMA)



Takeaways

Diverse I/O devices require hierarchical interconnect which is more recently transitioning to point-to-point topologies.

Next Goal

How does the processor interact with I/O devices?

I/O Device Driver Software Interface

Set of methods to write/read data to/from device and control device

Example: Linux Character Devices

```
// Open a toy " echo " character device
int fd = open("/dev/echo", O_RDWR);

// Write to the device
char write_buf[] = "Hello World!";
write(fd, write_buf, sizeof(write_buf));

// Read from the device
char read_buf [32];
read(fd, read_buf, sizeof(read_buf));

// Close the device
close(fd);

// Verify the result
assert(strcmp(write_buf, read_buf)==0);
```

I/O Device API

Typical I/O Device API

- a set of read-only or read/write registers

Command registers

- writing causes device to do something

Status registers

- reading indicates what device is doing, error codes, …

Data registers

- Write: transfer data to a device
- Read: transfer data from a device

Every device uses this API

I/O Device API

Simple (old) example: AT Keyboard Device

8-bit Status:

PE	TO	AUXB	LOCK	AL2	SYSF	IBS	OBS

IBS: Input Buffer Stats

OBS: Input Buffer Stats

8-bit Command:

0xAA = “self test”

0xAE = “enable kbd”

0xED = “set LEDs”

…

8-bit Data:

scancode (when reading)

LED state (when writing) or …

Communication Interface

Q: How does ~~program~~ ~~OS~~ code talk to device?

A: special instructions to talk over special busses

Programmed I/O ← Interact with cmd, status, and data device registers directly

- inb $a, 0x64 ← kbd status register
- outb $a, 0x60 ← kbd data register
- Specifies: device, data, direction
- Protection: only allowed in kernel mode

Kernel boundary crossinging is expensive

*x86: $a implicit; also inw, outw, inh, outh, …

Communication Interface

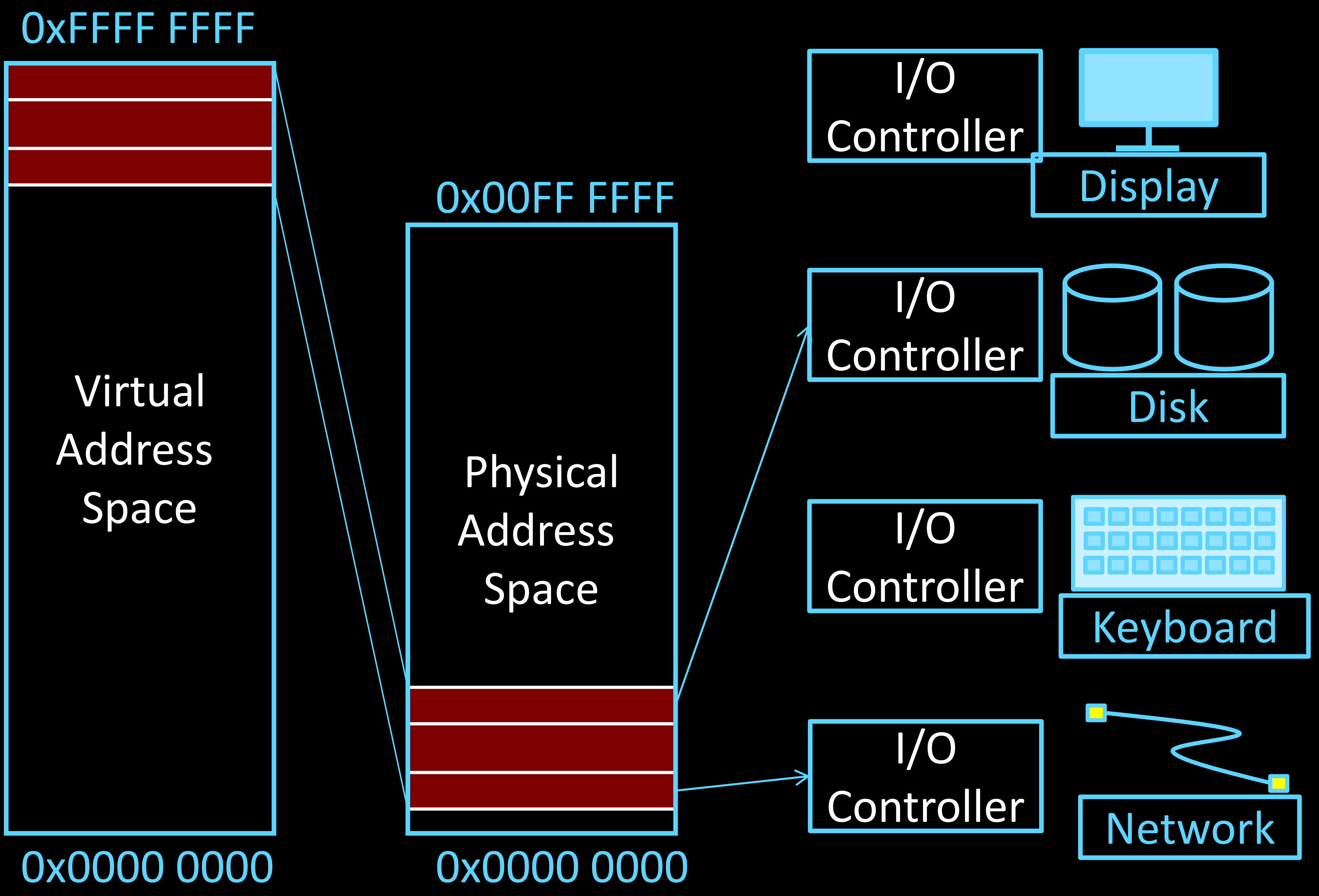
Q: How does ~~program~~ ~~OS~~ code talk to device?

A: Map registers into virtual address space

Memory-mapped I/O ← Faster. Less boundary crossing

- Accesses to certain addresses redirected to I/O devices
- Data goes over the memory bus
- Protection: via bits in pagetable entries
- OS+MMU+devices configure mappings

Memory-Mapped I/O



Device Drivers

Programmed I/O

Polling examples,
But mmap I/O more efficient

```
char read_kbd()
{
do {
    sleep();
    status = inb(0x64);
  } while(!(status & 1));

  return inb(0x60);
}
```

syscall

Memory Mapped I/O

```
struct kbd {
  char status, pad[3];
  char data, pad[3];
};
kbd *k = mmap(...);
```

syscall

```
char read_kbd()
{
  do {
    sleep();
    status = k->status;
  } while(!(status & 1));
  return k->data;
}
```

NO syscall

Comparing Programmed I/O vs Memory Mapped I/O

Programmed I/O

- Requires special instructions
- Can require dedicated hardware interface to devices
- Protection enforced via kernel mode access to instructions
- Virtualization can be difficult

Memory-Mapped I/O

- Re-uses standard load/store instructions
- Re-uses standard memory hardware interface
- Protection enforced with normal memory protection scheme
- Virtualization enabled with normal memory virtualization scheme

Takeaways

Diverse I/O devices require hierarchical interconnect which is more recently transitioning to point-to-point topologies.

Memory-mapped I/O is an elegant technique to read/write device registers with standard load/stores.

Next Goal

How does the processor know device is ready/done?

Communication Method

Q: How does program learn device is ready/done?

Takeaways

Diverse I/O devices require hierarchical interconnect which is more recently transitioning to point-to-point topologies.

Memory-mapped I/O is an elegant technique to read/write device registers with standard load/stores.

Interrupt-based I/O avoids the wasted work in polling-based I/O and is usually more efficient

Next Goal

How do we transfer a ***lot*** of data ***efficiently***?

I/O Data Transfer

How to talk to device?

- Programmed I/O or Memory-Mapped I/O

How to get events?

- Polling or Interrupts

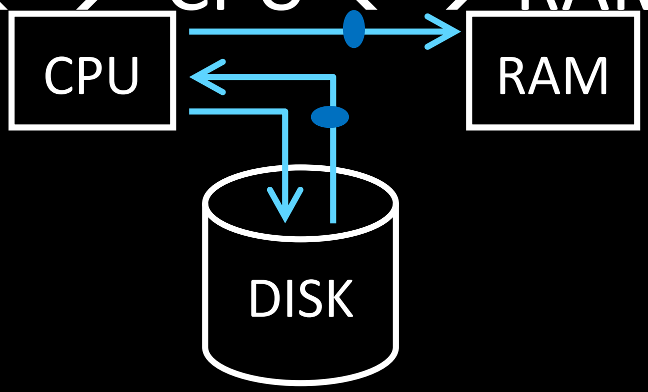
How to transfer lots of data?

```
disk->cmd = READ_4K_SECTOR;
disk->data = 12;
while (!(disk->status & 1) { }
for (i = 0..4k)
    buf[i] = disk->data;
```

Very, ***Very,*** Expensive

I/O Data Transfer

Programmed I/O xfer: Device ←→ CPU ←→ RAM



for (i = 1 .. n)

- CPU issues read request
- Device puts data on bus
  & CPU reads into registers
- CPU writes data to memory
- ***Not*** efficient

Read from Disk
Write to Memory
Everything interrupts CPU
Wastes CPU

I/O Data Transfer

Q: How to transfer lots of data ***efficiently***?

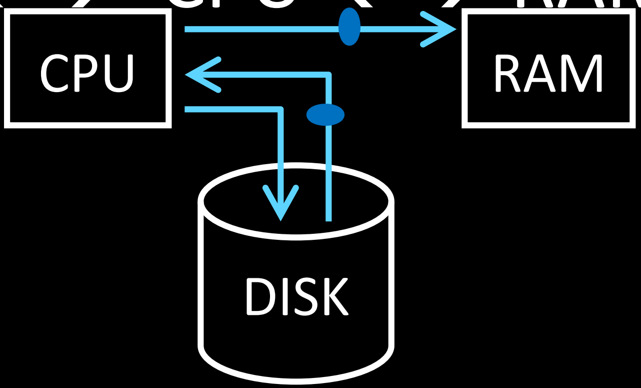
A: Have device access memory directly

Direct memory access (DMA)

- 1) OS provides starting address, length
- 2) controller (or device) transfers data autonomously
- 3) Interrupt on completion / error

DMA: Direct Memory Access

Programmed I/O xfer: Device ←→ CPU ←→ RAM



for (i = 1 .. n)

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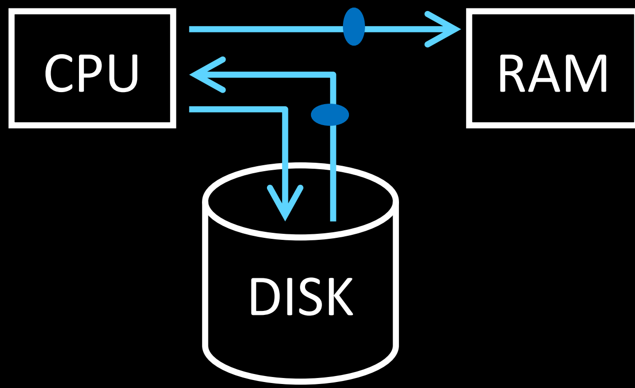
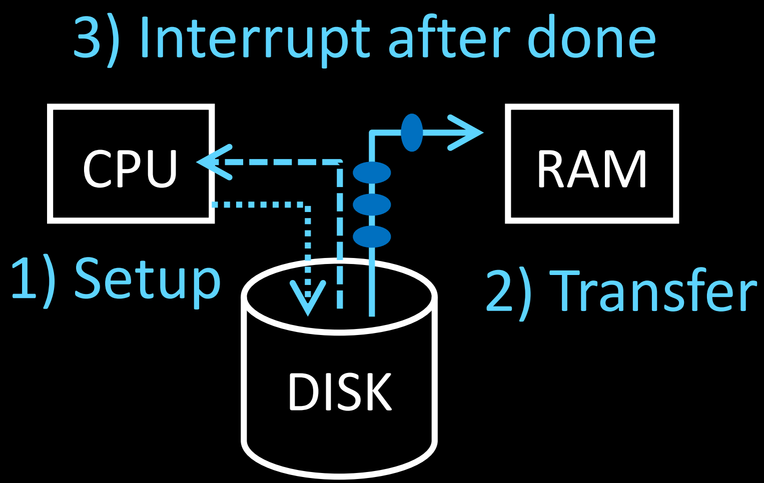


for (i = 1 .. n)

- CPU issues read request
- Device puts data on bus & CPU reads into registers
- CPU writes data to memory



DMA xfer: Device ←→ RAM

- CPU sets up DMA request
- for (i = 1 ... n)
  Device puts data on bus
  & RAM accepts it
- Device interrupts CPU after done

DMA Example

DMA example: reading from audio (mic) input

- DMA engine on audio device… or I/O controller … or …

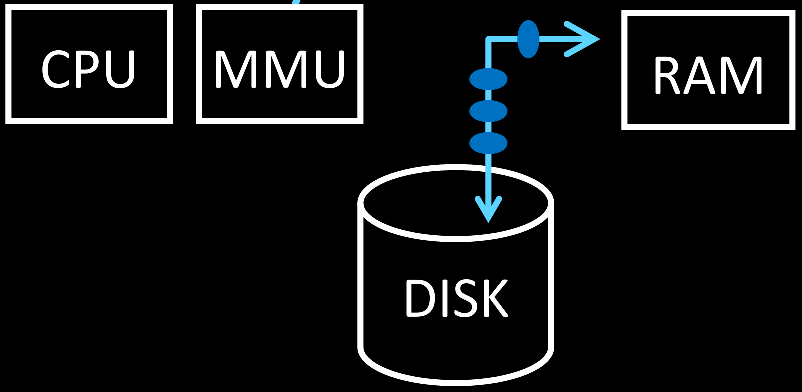
```
int dma_size = 4*PAGE_SIZE;
int *buf = alloc_dma(dma_size);
...
dev->mic_dma_baseaddr = (int)buf;
dev->mic_dma_count = dma_len;
dev->cmd = DEV_MIC_INPUT |
DEV_INTERRUPT_ENABLE | DEV_DMA_ENABLE;
```

DMA Issues (1): Addressing

Issue #1: DMA meets Virtual Memory

RAM: physical addresses

Programs: virtual addresses



DMA Example

DMA example: reading from audio (mic) input

- DMA engine on audio device… or I/O controller … or …

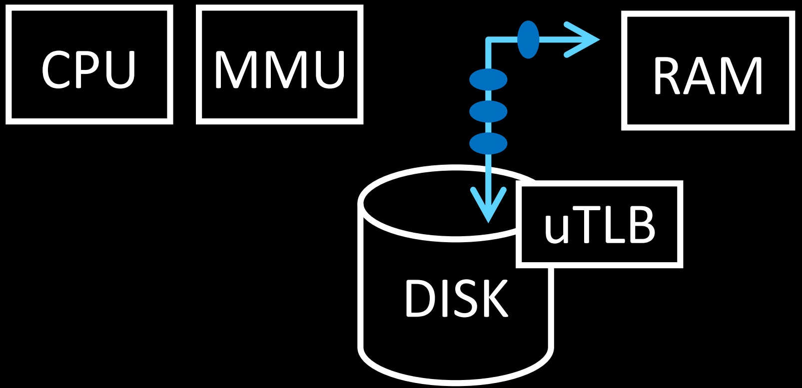
```
int dma_size = 4*PAGE_SIZE;
void *buf = alloc_dma(dma_size);
...
dev->mic_dma_baseaddr = virt_to_phys(buf);
dev->mic_dma_count = dma_len;
dev->cmd = DEV_MIC_INPUT |
DEV_INTERRUPT_ENABLE | DEV_DMA_ENABLE;
```

DMA Issues (1): Addressing

Issue #1: DMA meets Virtual Memory

RAM: physical addresses

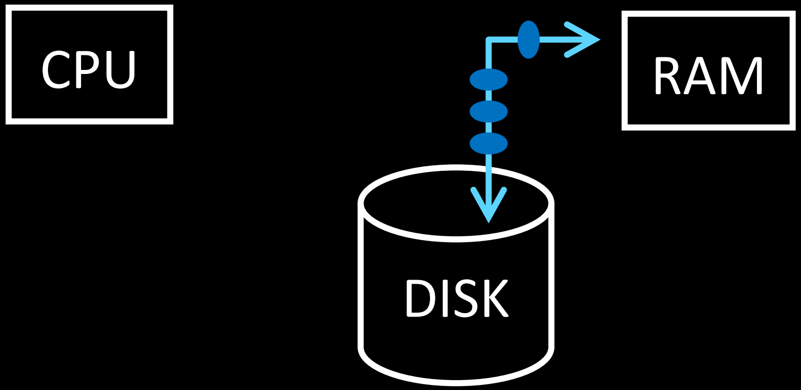
Programs: virtual addresses



DMA Issues (2): Virtual Mem

Issue #2: DMA meets *Paged* Virtual Memory

DMA destination page may get swapped out

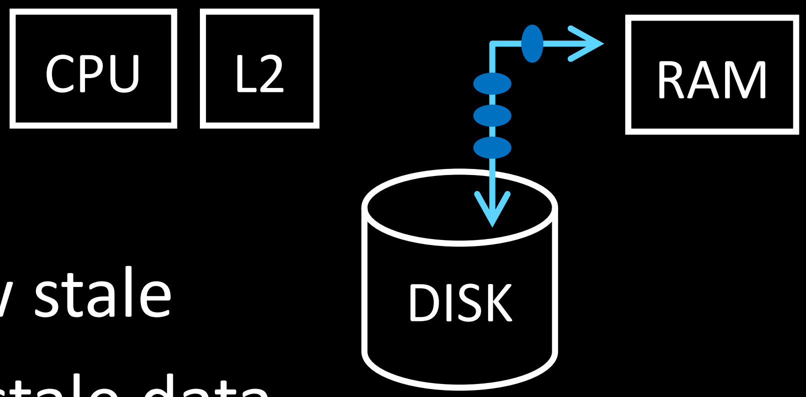


DMA Issues (4): Caches

Issue #4: DMA meets Caching

DMA-related data could be cached in L1/L2

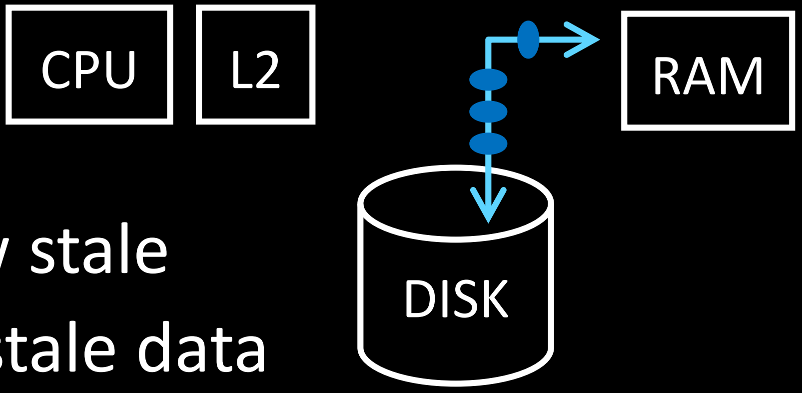
- DMA to Mem: cache is now stale
- DMA from Mem: dev gets stale data



DMA Issues (4): Caches

Issue #4: DMA meets Caching

DMA-related data could be cached in L1/L2



- DMA to Mem: cache is now stale
- DMA from Mem: dev gets stale data

Solution 2: (hardware coherence aka snooping)

- cache listens on bus, and conspires with RAM
- DMA to Mem: invalidate/update data seen on bus
- DMA from mem: cache services request if possible, otherwise RAM services

Takeaways

Diverse I/O devices require hierarchical interconnect which is more recently transitioning to point-to-point topologies.

Memory-mapped I/O is an elegant technique to read/write device registers with standard load/stores.

Interrupt-based I/O avoids the wasted work in polling-based I/O and is usually more efficient.

Modern systems combine memory-mapped I/O, interrupt-based I/O, and direct-memory access to create sophisticated I/O device subsystems.

I/O Summary

How to talk to device?

Programmed I/O or Memory-Mapped I/O

How to get events?

Polling or Interrupts

How to transfer lots of data?

DMA