

I/O

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See: P&H Chapter 6.5-6

Computer System =

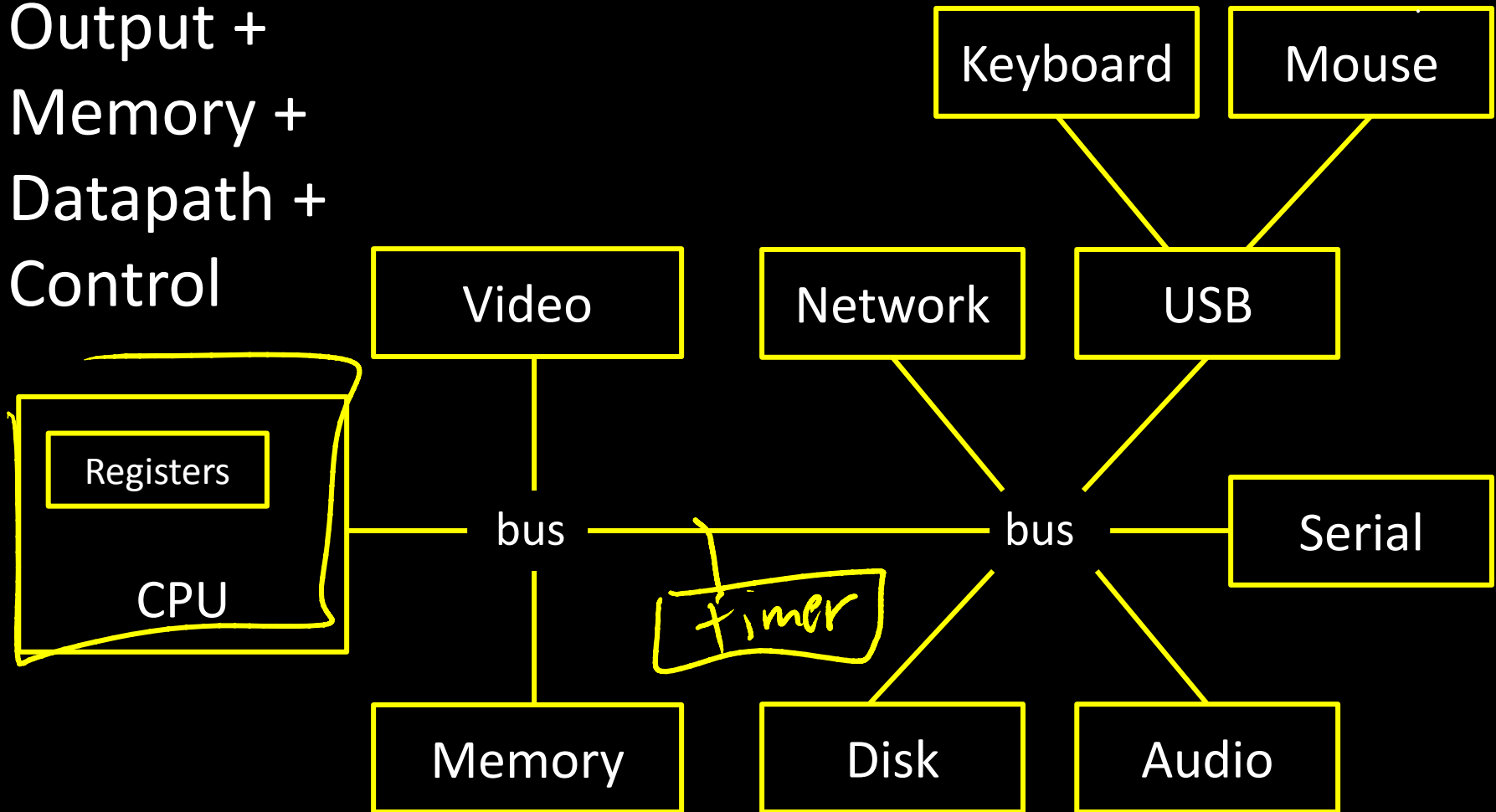
Input +

Output +

Memory +

Datapath +

Control

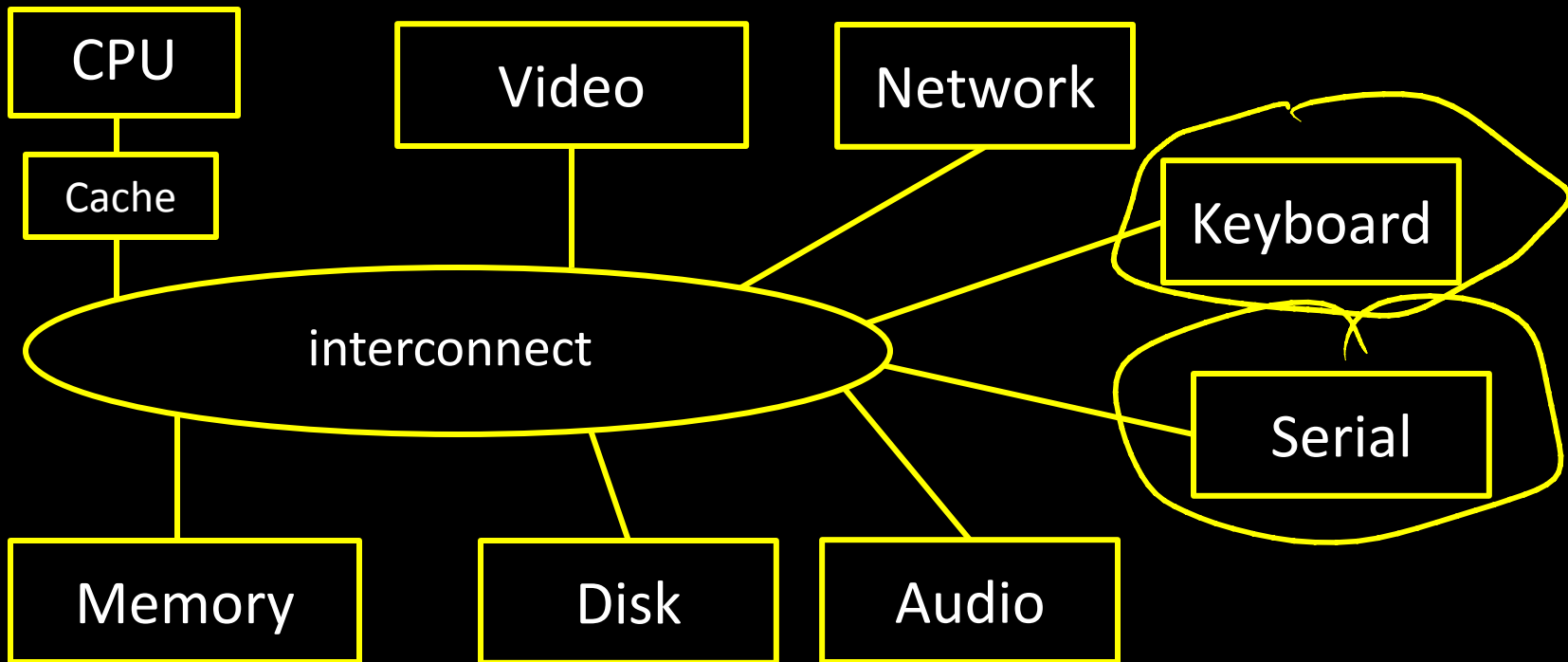


How do we interface to other devices

- Keyboard
- Mouse
- Disk
- Network
- Display
- Programmable Timer (for clock ticks)
- Audio
- Printer
- Camera
- iPod
- Scanner
- ...

Bad Idea #1: Put all devices on one interconnect

- We would have to replace all devices as we improve/change the interconnect
- keyboard speed == main memory speed ?!



- fast/expensive busses when needed; slow/cheap elsewhere
- I/O controllers to connect end devices

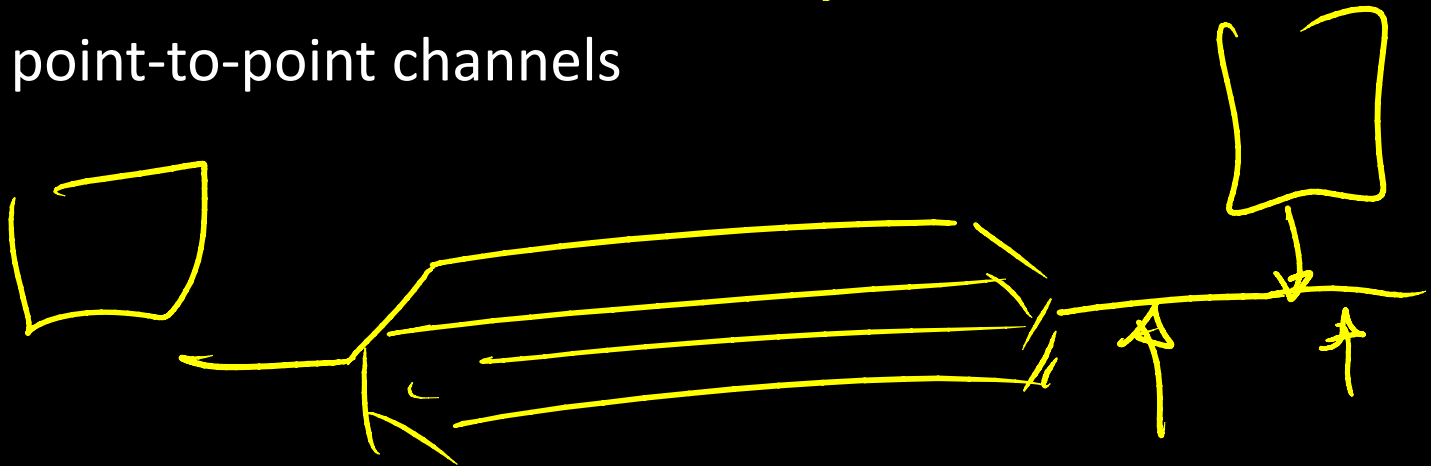


Interconnects are (were?) **busses**

- parallel set of wires for data and control
- **shared** channel
 - multiple senders/receivers ✓
 - everyone can see all bus transactions ✓
- bus protocol: rules for using the bus wires

Alternative (and increasingly common): ✓

- dedicated point-to-point channels



Width = number of wires

Transfer size = data words per bus transaction

Synchronous (with a bus clock)

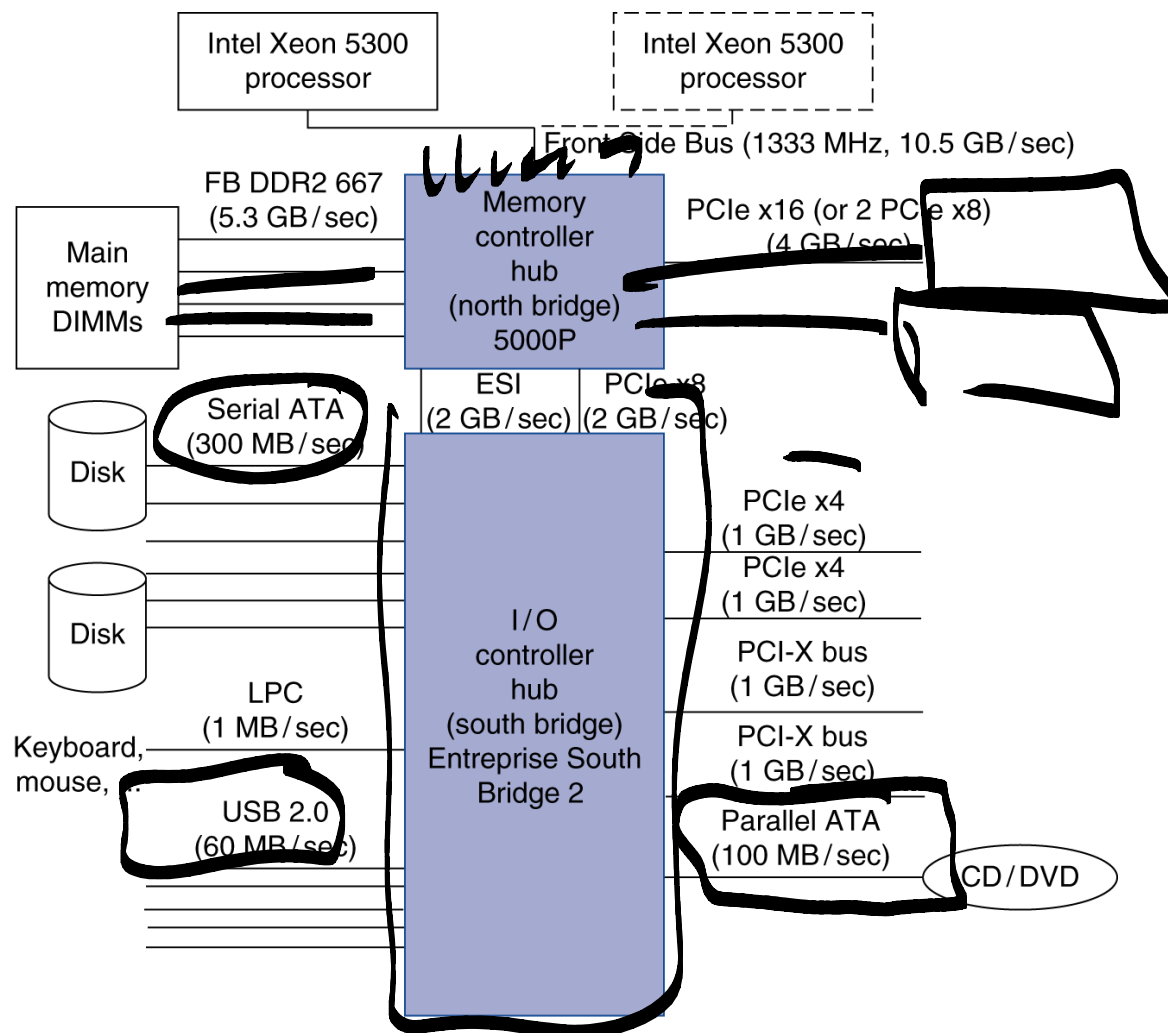
↗ or **asynchronous** (no bus clock / “self clocking”)
↗

Processor – Memory (“Front Side Bus”)

- Short, fast, & wide
- Mostly fixed topology, designed as a “chipset”
 - CPU + Caches + Interconnect + Memory Controller

I/O and Peripheral busses (PCI, SCSI, USB, LPC, ...)

- Longer, slower, & narrower
- Flexible topology, multiple/varied connections
- Interoperability standards for devices
- Connect to processor-memory bus through a bridge



Typical I/O Device API

- a set of read-only or read/write registers

Command registers

- writing causes device to do something

Status registers

- reading indicates what device is doing, error codes, ...

Data registers

- Write: transfer data to a device
- Read: transfer data from a device

Simple (old) example: AT Keyboard Device

0x55
0x5A
0x55

8-bit Status:

PE	TO	AUXB	LOCK	AL2	SYSF	IBS	OBS
----	----	------	------	-----	------	-----	-----

⌘

⌘

Input
Buffer
Status

8-bit Cmd:

0xAA = "self test"

0xAE = "enable kbd"

0xED = "set LEDs" ⌘

...

8-bit Data:

scancode (when reading) ⌘



LED state (when writing) or ...

Q: How does ~~program~~ ~~OS~~ code talk to device?

A: special instructions to talk over special busses

Programmed I/O

kbd status Reg.
kbd data Reg.

- `inb $a, 0x64` 
- `outb $a, 0x60` 
- Specifies: device, data, direction
- Protection: only allowed in kernel mode

*x86: \$a implicit; also `inw`, `outw`, `inh`, `outh`, ...

Q: How does ~~program~~ ~~OS~~ code talk to device?

A: special instructions to talk over special busses

Programmed I/O

- `inb $a, 0x64` ← *kbd status Reg.*
- `outb $a, 0x60` ← *kbd data Reg.*
- Specifies: *user* device, data, direction
- Protection: only *3* allowed in kernel mode

~~`inb $a, 0x64`~~
syscall

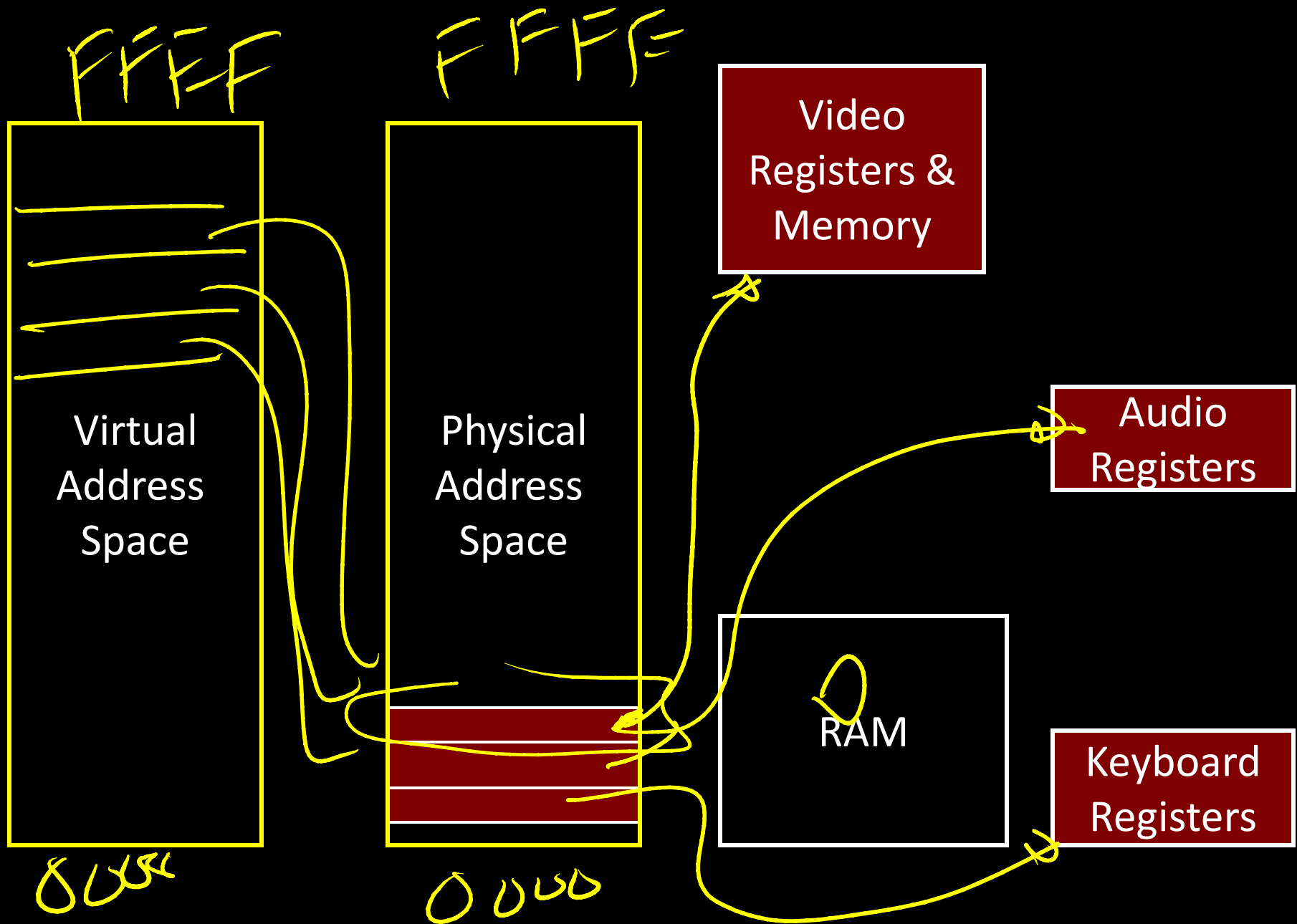
*x86: \$a implicit; also `inw`, `outw`, `inh`, `outh`, ...

Q: How does ~~program~~ ~~OS~~ code talk to device?

A: Map registers into virtual address space

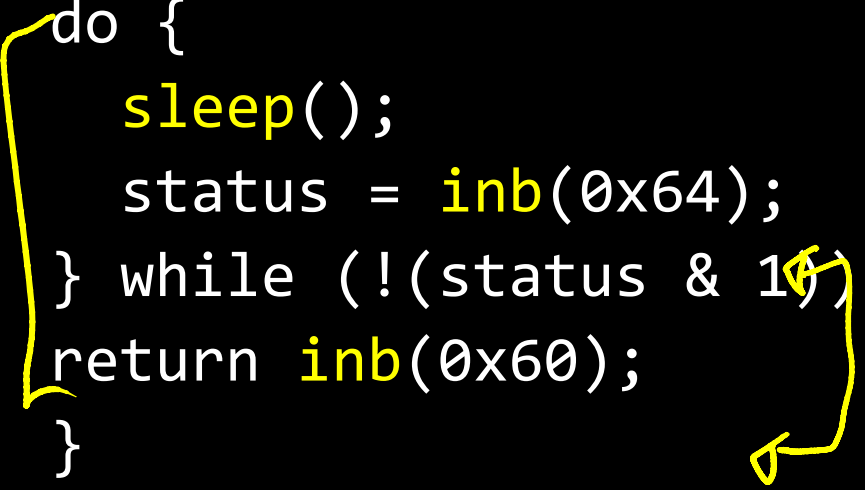
Memory-mapped I/O

- Accesses to certain addresses redirected to I/O devices
- Data goes over the memory bus
- Protection: via bits in pagetable entries
- OS+MMU+devices configure mappings




Programmed I/O

```
char read_kbd()
{
do {
    sleep();
    status = inb(0x64);
} while (!(status & 1));
return inb(0x60);
}
```



Memory Mapped I/O

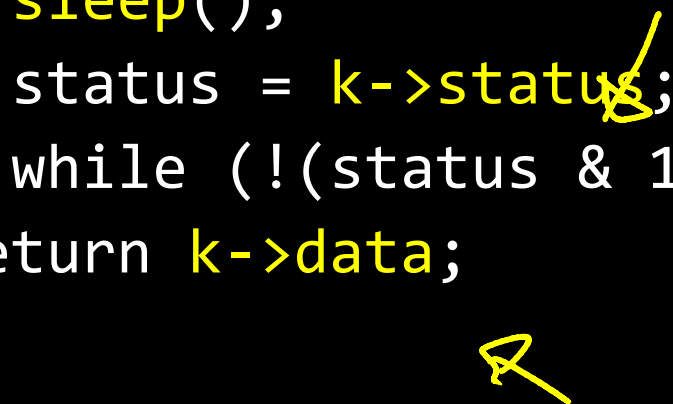
```
struct kbd {
    char status, pad[3];
    char data, pad[3];
};
```



```
kbd *k = mmap(...);
```



```
char read_kbd()
{
do {
    sleep();
    status = k->status;
} while (!(status & 1));
return k->data;
}
```



Q: How does program learn device is ready/done?

A: **Polling**: Periodically check I/O status register

- If device ready, do operation
- If device done, ...
- If error, take action

Pro? Con?

- Predictable timing & inexpensive
- But: wastes CPU cycles if nothing to do
- Efficient if there is always work to do

Common in small, cheap, or real-time embedded systems

Sometimes for very active devices too...

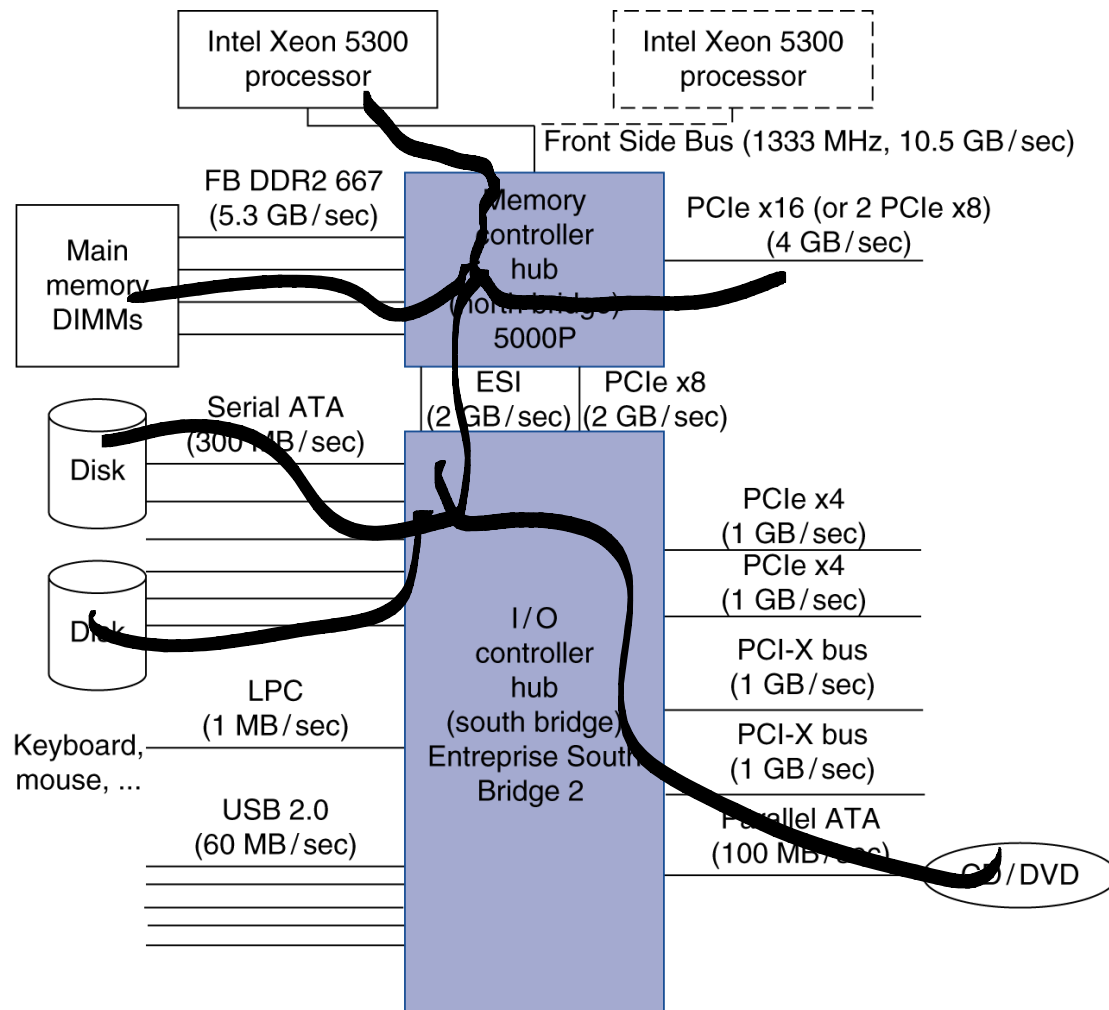
Q: How does program learn device is ready/done?

A: **Interrupts**: Device sends interrupt to CPU

- Cause identifies the interrupting device
- interrupt handler examines device, decides what to do

Priority interrupts

- Urgent events can interrupt lower-priority interrupt handling
- OS can ~~disable~~ defer interrupts



How to talk to device?

Programmed I/O or Memory-Mapped I/O

How to get events?

Polling or Interrupts

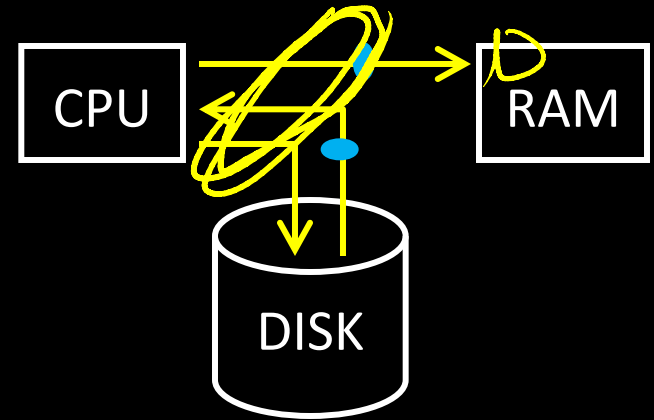
How to transfer lots of data?

```
disk->cmd = READ_4K_SECTOR;
disk->data = 12;
while (!(disk->status & 1) { }
for (i = 0..4k)
    buf[i] = disk->data;
```

Programmed I/O xfer: Device \leftrightarrow CPU \leftrightarrow RAM

for ($i = 1 \dots n$)

- CPU issues read request
- Device puts data on bus & CPU reads into registers
- CPU writes data to memory



Q: How to transfer lots of data efficiently?

A: Have device access memory directly

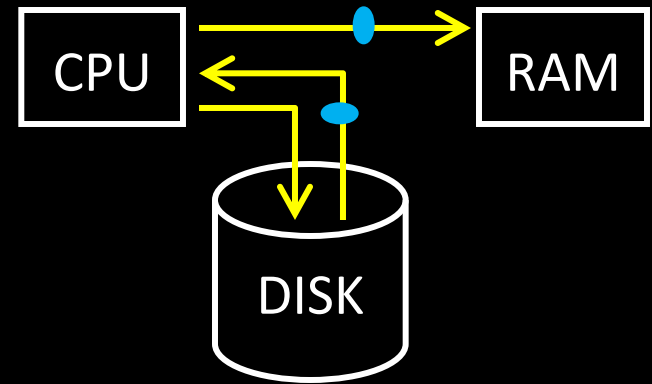
Direct memory access (DMA)

- OS provides starting address, length
- controller (or device) transfers data autonomously
- Interrupt on completion / error

Programmed I/O xfer: Device \leftrightarrow CPU \leftrightarrow RAM

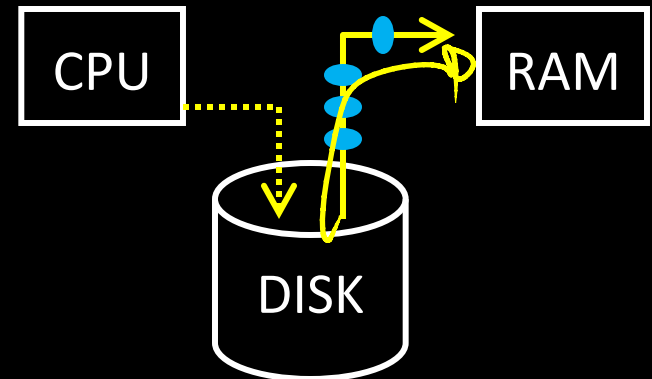
for ($i = 1 \dots n$)

- CPU issues read request
- Device puts data on bus & CPU reads into registers
- CPU writes data to memory



DMA xfer: Device \leftrightarrow RAM

- CPU sets up DMA request
- for ($i = 1 \dots n$)
Device puts data on bus & RAM accepts it



DMA example: reading from audio (mic) input

- DMA engine on audio device... or I/O controller ... or ...

```
int dma_size = 4*PAGE_SIZE;
```

```
voidint*buf = alloc_dma(dma_size);
```

```
...
```

```
dev->mic_dma_baseaddr = (int)buf;
```

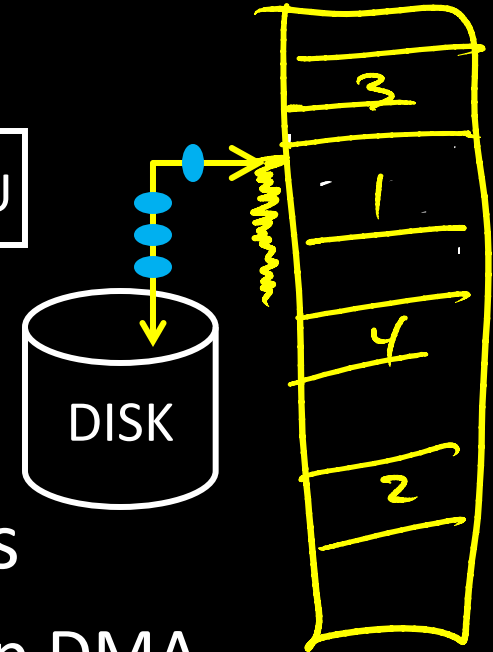
```
dev->mic_dma_count = dma_len;
```

```
dev->cmd = DEV_MIC_INPUT |  
         DEV_INTERRUPT_ENABLE | DEV_DMA_ENABLE;
```


Issue #1: DMA meets Virtual Memory

RAM: physical addresses

Programs: virtual addresses



Solution: DMA uses physical addresses

- OS uses physical address when setting up DMA
- OS allocates contiguous physical pages for DMA
- Or: OS splits xfer into page-sized chunks
(many devices support DMA “chains” for this reason)

DMA example: reading from audio (mic) input

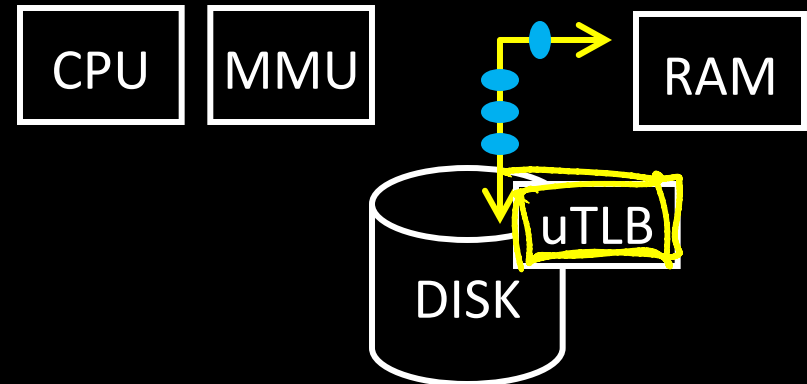
- DMA engine on audio device... or I/O controller ... or ...

```
int dma_size = 4*PAGE_SIZE;  
void *buf = alloc_dma(dma_size);  
...  
dev->mic_dma_baseaddr = virt_to_phys(buf);  
dev->mic_dma_count = dma_len;  
dev->cmd = DEV_MIC_INPUT |  
         DEV_INTERRUPT_ENABLE | DEV_DMA_ENABLE;
```

Issue #1: DMA meets Virtual Memory

RAM: physical addresses

Programs: virtual addresses

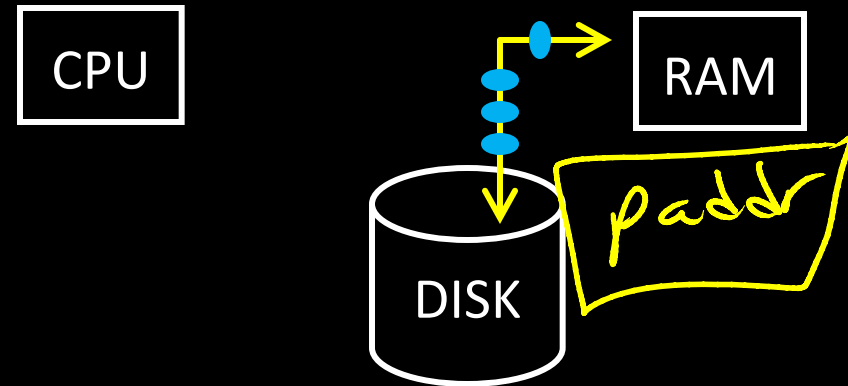


Solution 2: DMA uses virtual addresses

- OS sets up mappings on a mini-TLB ←

Issue #2: DMA meets *Paged* Virtual Memory

DMA destination page
may get swapped out



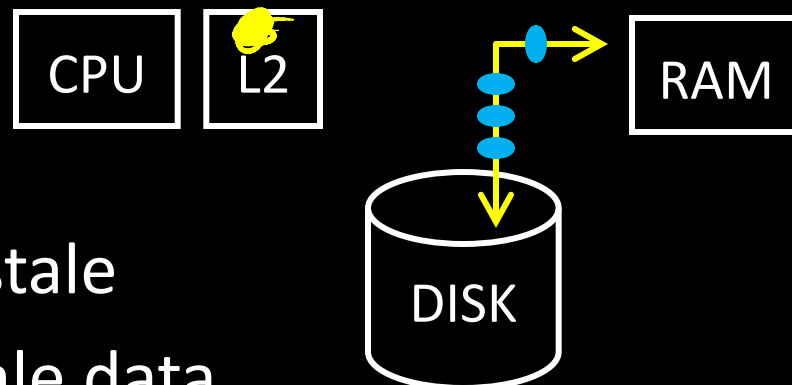
Solution: **Pin** the page before initiating DMA

Alternate solution: **Bounce Buffer**

- DMA to a pinned kernel page, then memcpy elsewhere

Issue #4: DMA meets Caching

DMA-related data could
be cached in L1/L2



- DMA to Mem: cache is now stale
- DMA from Mem: dev gets stale data

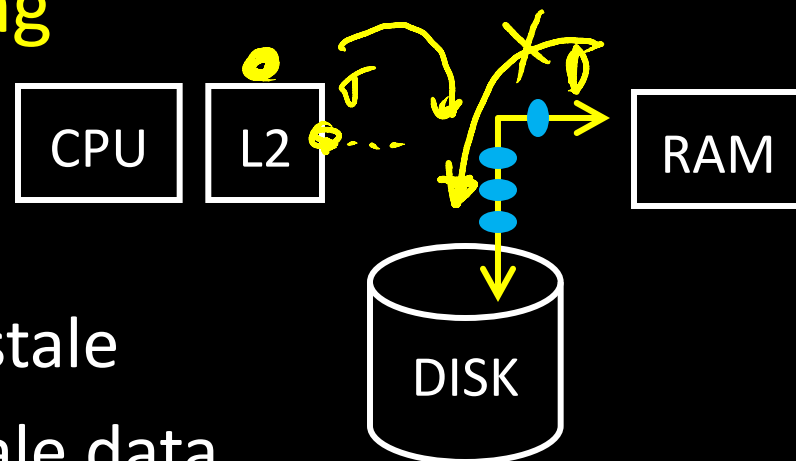
Solution: (software enforced coherence)

- OS flushes some/all cache before DMA begins
- Or: don't touch pages during DMA
- Or: mark pages as **uncacheable** in page table entries
 - (needed for Memory Mapped I/O too!)

Issue #4: DMA meets Caching

DMA-related data could be cached in L1/L2

- DMA to Mem: cache is now stale
- DMA from Mem: dev gets stale data



Solution 2: (hardware coherence aka snooping)

- cache listens on bus, and conspires with RAM
- Dma to Mem: invalidate/update data seen on bus
- DMA from mem: cache services request if possible, otherwise RAM services

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Programmed I/O or Memory-Mapped I/O

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DMA