

# CS 322: Prelim 1 Solution Guide

```
95-100
90-94  xxxxxxxxxxxx
85-89  xxxxxxxxxxxx
80-84  xxxxxxxxxxxx
75-79  xxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxx
70-74  xxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxx
65-69  xxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxx
60-64  xxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxx
55-59  xxxxxxxxxxxxxxxxxxxxxxxx
50-54  xxxxxxxxxxxx
45-49  xxx
40-44  xxxxxxxx
< 40  xxx
```

Median = 69. Rough Grade Guidelines: A = [80,100], B = [65,75], C = [50,60]

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1. Assume that  $x$  and  $y$  are given column vectors and that the command `plot(x,y)` results in the display of the first-quadrant portion of the ellipse

$$\left(\frac{x}{a}\right)^2 + \left(\frac{y}{b}\right)^2 = 1.$$

Without any sine, cosine, or, square root computations, show how to plot the entire ellipse

$$\left(\frac{x-h}{a}\right)^2 + \left(\frac{y-k}{b}\right)^2 = 1$$

assuming that  $h$ ,  $k$ ,  $x$ , and  $y$  are given. Do not worry about axis scaling. You may use `hold`. Express your solution in the form of a MATLAB script.

```
plot(x+h,y+k)
```

```
hold on
plot(-x+h,y+k)
plot(-x+h,-y+k)
plot(x+h,-y+k)
hold off
```

Or:

```
x = [x;-x;-x;x];
y = [y;y;-y;-y];
%plot(x,y) now would do the ellipse centered at (0,0)
plot(x+h,y+k)
```

- 5 if plot with -h and -k
- 3 if plot with some +h (or k) and some -h (or k)
- 2 if hold missing
- 10 if plot correctly at (0,0)
- 3 if fail to plot one quadrant

2. (a) (10 points) Assume that  $A \in \mathbb{R}^{n \times n}$  and  $C \in \mathbb{R}^{n \times n}$  are stored in  $n$ -by- $n$  arrays **A** and **C** and that  $x \in \mathbb{R}^n$  and  $y \in \mathbb{R}^n$  are stored in  $n$ -by-1 arrays **x** and **y**. Write a MATLAB 1-liner that efficiently evaluates  $z = xy^T AC$  and assigns the result to **z**.

% There are three operations and 5 possible algorithms:

```
z = ((x*y')*A)*C      % This is  $O(n^3)$  and the same as  $z = x*y'*A*C$       4 points for this
z = (x*y')*(A*C)      % This is  $O(n^3)$                                   4 points for this
z = (x*(y'*A))*C      % This is  $O(n^3)$                                   7 points for this
z = x*((y'*A)*C)      % This is  $O(n^2)$                                   10 points for this
z = x*(y'*(A*C))      % This is  $O(n^3)$                                   4 points for this
```

If the wrong answer was calculated (i.e.  $(A*x)'(C*y)$  calculation), then 2 further points were deducted. No points were deducted for failing to use correct Matlab syntax.

(b) (10 points) Suppose we are given the points  $(x_1, y_1), \dots, (x_n, y_n)$  with  $n \geq 3$  and  $x_1, \dots, x_n$  distinct. Assume that  $q$  and  $r$  are degree  $n - 2$  polynomials with the property that

$$\begin{aligned} q(x_i) &= y_i & i &= 1:n-1 \\ r(x_i) &= y_i & i &= 2:n \end{aligned}$$

Determine real numbers  $a$  and  $b$  so that  $p(x) = a(x - x_n)q(x) + b(x - x_1)r(x)$  interpolates  $(x_1, y_1), \dots, (x_n, y_n)$ . It must be clear from your answer that  $p$  interpolates all  $n$  points.

Since  $y_1 = p(x_1) = a(x_1 - x_n)q(x_1) = a(x_1 - x_n)y_1$  we must have  $a = 1/(x_1 - x_n)$ .

Since  $y_n = p(x_n) = b(x_n - x_1)r(x_1) = b(x_n - x_1)y_n$  we must have  $b = 1/(x_n - x_1)$ . Thus,

$$p(x) = \frac{(x - x_n)q(x) - (x - x_1)r(x)}{x_1 - x_n}$$

For  $i = 2:n - 1$  we have

$$p(x_i) = \frac{(x_i - x_n)q(x_i) - (x_i - x_1)r(x_i)}{x_1 - x_n} = y_i \frac{(x_i - x_n) - (x_i - x_1)}{x_1 - x_n} = y_i$$

3 points for getting the correct answer for  $a (= 1/(x_1 - x_n))$

3 points for getting the correct answer for  $b (= 1/(x_n - x_1))$

3 points for showing  $p(x_i) = y_i$

1 point for correctly stating the limitations on  $i$  when showing  $p(x_i) = y_i$  (i.e. the algebra only holds for  $i = 2:n - 1$ )

9 points maximum were given for a solution where a system of linear equations were presented. To get all 9 points, the student had to present the correct system of linear equations, and actually give some of the matrix equations

3. (a) (10 points) Assume that  $x$ ,  $y$ , and  $z$  are consecutive positive floating point numbers with  $x < y < z$ . If  $(x + z)/2 = y + 1/64$  in exact arithmetic then what is the value of  $y - x$  in exact arithmetic? Hint: the spacing between  $x$  and  $y$  is not the same as the spacing between  $y$  and  $z$ .

Assume that  $y = x + d$ , i.e.,  $d$  is the spacing between  $x$  and  $y$ . Since the average of  $x$  and  $z$  is bigger than  $y$ , we must have  $z = y + 2d = x + 3d$ . Thus,  $y + 1/64 = (x + z)/2 = x + (3/2)d = y + d/2$ . Thus,  $d = 1/32 = y - x$ .

3 points for recognizing that spacing between  $y$  and  $z$  is twice the spacing between  $x$  and  $y$ .

(b) (10 points)  $S(x)$  is the not-a-knot cubic spline interpolant of the points  $(x_1, y_1), \dots, (x_4, y_4)$  with  $x_1 < x_2 < x_3 < x_4$ . Assume that

$$S(x) = \begin{cases} p_1(x) = c_{11}(x - x_1)^3 + c_{12}(x - x_1)^2 + c_{13}(x - x_1) + c_{14} & \text{if } x_1 \leq x \leq x_2 \\ p_2(x) = c_{21}(x - x_2)^3 + c_{22}(x - x_2)^2 + c_{23}(x - x_2) + c_{24} & \text{if } x_2 \leq x \leq x_3 \\ p_3(x) = c_{31}(x - x_3)^3 + c_{32}(x - x_3)^2 + c_{33}(x - x_3) + c_{34} & \text{if } x_3 \leq x \leq x_4 \end{cases}$$

Explain why  $c_{11} = c_{21} = c_{31}$ .

For the not-a-knot spline,  $p_1'''(x_2) = p_2'''(x_2)$  and so  $6c_{11} = 6c_{21}$ . Likewise,  $p_2'''(x_3) = p_3'''(x_3)$  and so  $6c_{21} = 6c_{31}$ .

-2 if you don't correctly differentiate the cubics three times

-1 confusing  $f'''$  and  $s'''$

3 pts for understanding that  $s, s'$  and  $s''$  are all continuous.

4. Suppose  $f(x)$  is always positive with the property that  $f(-x) = f(x)$  for all  $x$ . How would you compute

$$I = \int_{-a}^b f(x) dx \quad 0 < a < b$$

with relative error  $10^{-6}$  or less? Make effective use of QUAD. Assume that the function  $f$  is implemented in `f.m` and recall that if `numI = QUAD('f',L,R,tol)`, then we (usually) have

$$\left| \text{numI} - \int_L^R f(x) dx \right| \leq \text{tol} \cdot \int_L^R f(x) dx.$$

express your answer in the form of a MATLAB script and explain why your choice of the tolerances works.

Since

$$I = \int_{-a}^b f(x) dx = \int_{-a}^0 f(x) dx + \int_0^a f(x) dx + \int_a^b f(x) dx = 2 \int_0^a f(x) dx + \int_a^b f(x) dx$$

`numI = 2*QUAD('f',0,a,tol1) + QUAD('f',a,b,tol2)`

$$\begin{aligned} |I - \text{numI}| &= \left| \left( 2 \int_0^a f(x) dx - 2\text{QUAD}('f',0,a,tol1) \right) + \left( \int_a^b f(x) dx - \text{QUAD}('f',a,b,tol2) \right) \right| \\ &\leq 2\text{tol1} \int_0^a f(x) dx + \text{tol2} \int_a^b f(x) dx \end{aligned}$$

Note that by setting `tol1 = tol2 = tol = 10-8` we obtain the required result:

$$|I - \text{numI}| \leq \text{tol} \int_{-a}^b f(x) dx$$

matlab script:

+14 for `numI = 2*quad('f',0,a,tol1) + quad('f',a,b,tol2)`

+12 if use min/max to determine if `a < b` or `b < a` (given in problem statement) and everything else with above line is correct

explanation:

+3 correct argument

+3 correct reasoning

5. The 2-point Gauss-Legendre rule is given by

$$\int_a^b f(x)dx \approx \frac{b-a}{2} (f(x_1) + f(x_2))$$

where

$$x_1 = \frac{a+b}{2} - \frac{b-a}{2\sqrt{3}}$$

$$x_2 = \frac{a+b}{2} + \frac{b-a}{2\sqrt{3}}$$

Complete the following function so that it performs as specified

```
function alfa = SectorArea(A,P,theta)
% A and P are scalars with A >= P > 0 and theta is a column n-vector
% with n > 2 and theta(1) < theta(2) < ... < theta(n).
%
% alfa is a column (n-1)-vector with the property that for k=1:n-1
% alfa(k) is the 2-point Gauss-Legendre approximation of the integral
% of the function f(x) from x = theta(k) to x = theta(k+1) where
% f(x)= .5( A*P/( P*(1 - cos(x)) + A*(1 + cos(x)) ) )^2.
```

Vectorize and avoid redundant computation.

```
u = (theta(1:n-1) + theta(2:n))/2;           % 4pts
v = (theta(2:n) - theta(1:n-1))/(2*sqrt(3)); % 4 pts

x1 = u - v; f1 = .5*(A*P./(P+A+(A-P)*cos(x1))).^2; % 3 pts
x2 = u + v; f2 = .5*(A*P./(P+A+(A-P)*cos(x2))).^2; % 3 pts

alfa = (theta(2:n) - theta(1:n-1)).*(f1 + f2)/2 % 6pts
```

It is possible to combine the u and v steps and the f1 and f2 steps, but not required for full credit