

## Lecture 21

# Sensing & Perception

# Recall: Sense-Think-Act

- **Sense:**
  - Perceive the world
  - Reading the game state
  - **Example:** enemy near?
- **Think:**
  - Choose an action
  - Often merged with sense
  - **Example:** fight or flee
- **Act:**
  - Update the state
  - Simple and fast
  - **Example:** reduce health



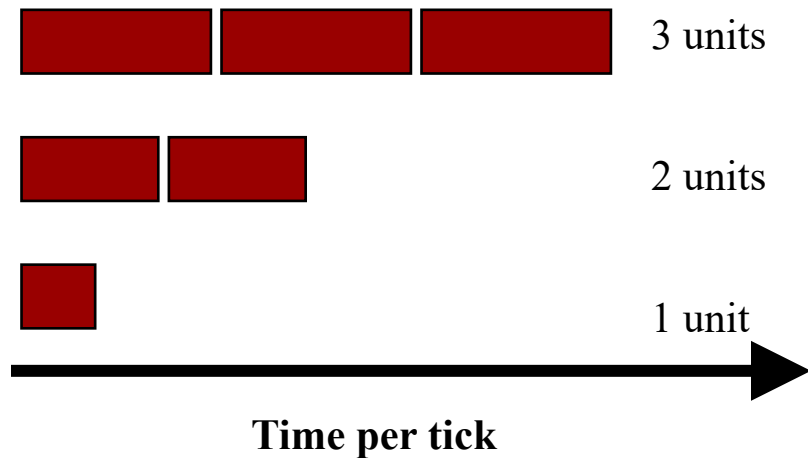
# Take Away for this Lecture

---

- Sensing as the primary bottleneck
  - Why is sensing so problematic?
  - What types of things can we do to improve it?
- Optimized sense computation
  - Can we improve sense computation performance?
  - Can we share sensing between NPCs?
- Sense event matching
  - What are events and how are they represented?
  - What is the advantage of an event system?

# Recall: Sensing Performance

- Sensing may be slow!
  - Consider *all* objects
- Example: morale
  - $n$  knights,  $n$  skeletons
  - Knights fear skeletons
  - Proportional to # seen
- Count skeletons in view
  - $O(n)$  to count skeletons
  - $O(n^2)$  for all units



# Recall: Sensing Performance

- Sensing may be slow!

- Consider *all* objects

- Example: morale

- $n$  knights,  $n$  skeletons

- 1

- $n$  seen

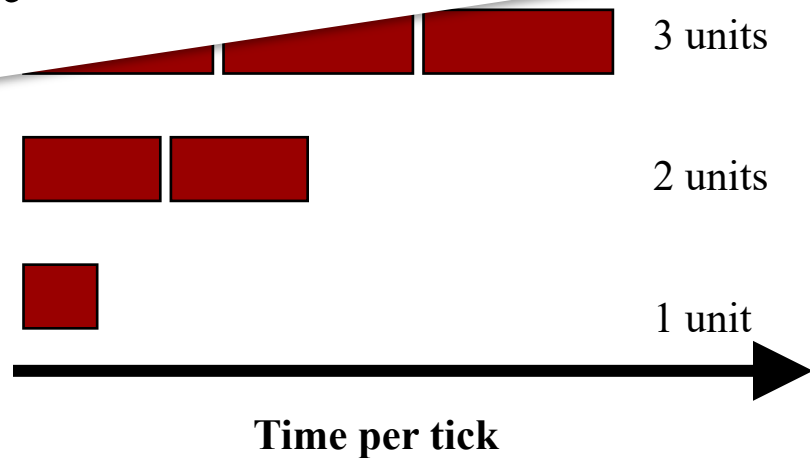
- Count skeletons in view

- $O(n)$  to count skeletons

- $O(n^2)$  for all units



How Do We Make it Faster?



# Example: Collision Detection

---

Naively  $O(n^2)$

---

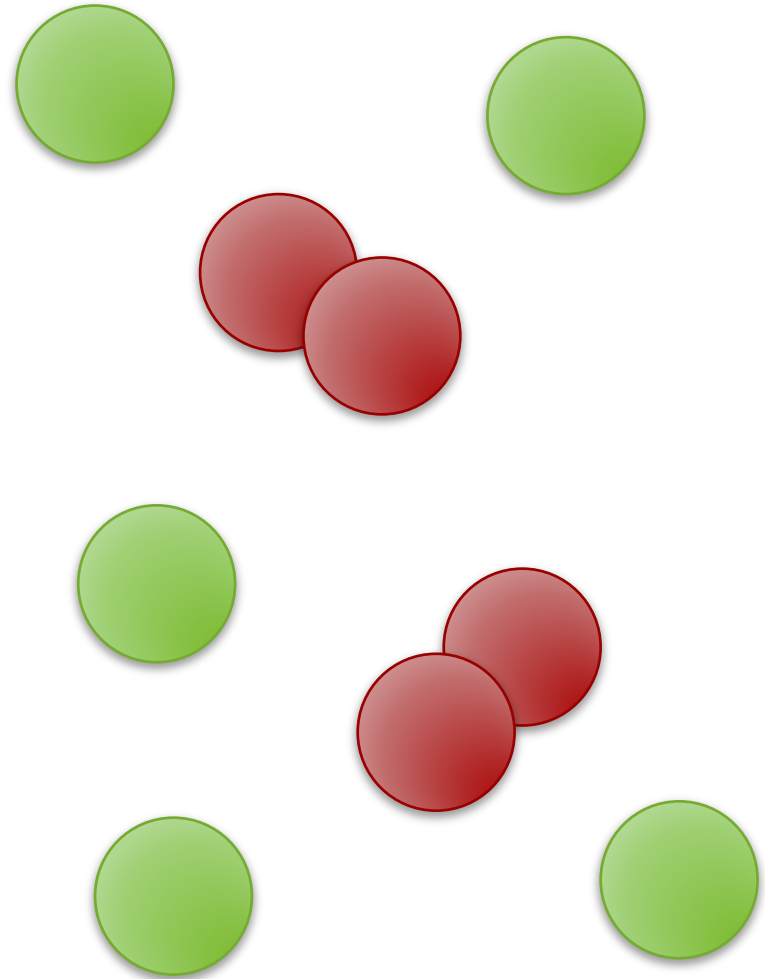
for each object x:

for each object y:

if x not y and x, y collide:

resolve collision of x, y

Checks objects obviously  
far apart from each other



# Example: Collision Detection

## Lab Optimization

for each object x:

put x into cell slot

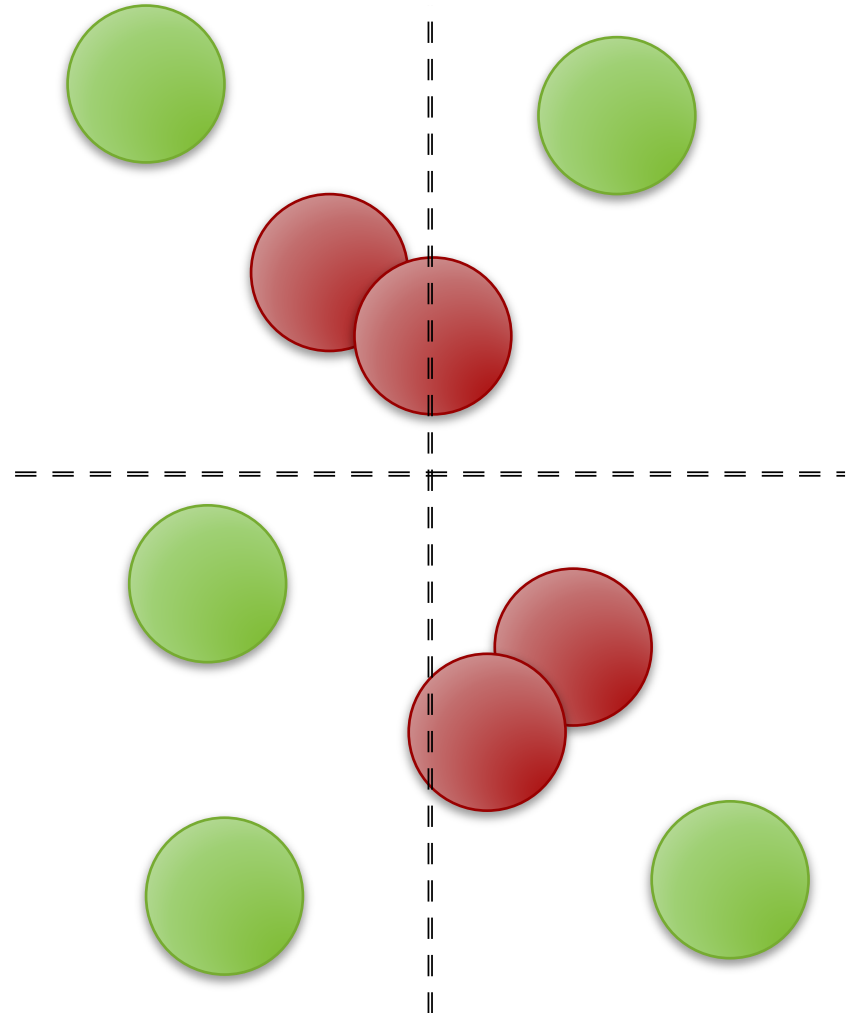
for each cell location:

for each object x:

for each object y:

if  $x \neq y$  and x, y collide:

resolve collision



# Similar Ideas Exist in AI

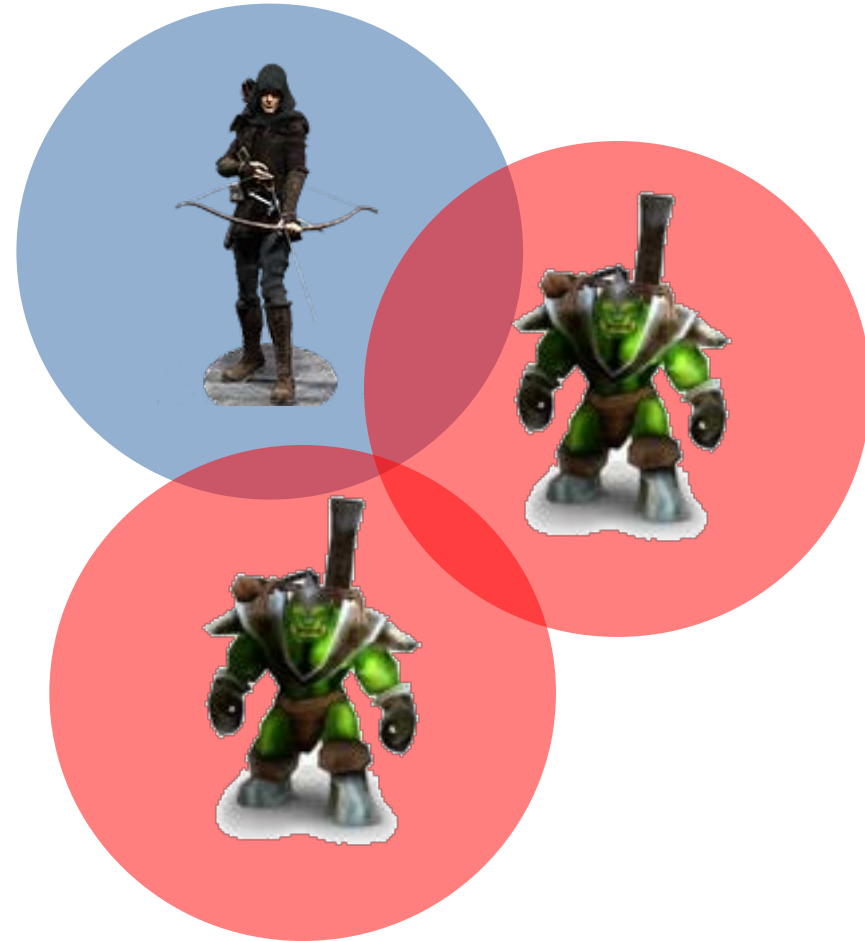
- **Area of Interest**
  - Limit the sensing range
  - Only “see” what in range
  - Used in targeting, stealth
- Works in both directions
  - **Nimbus**: “can see” radius
  - **Aura**: “can be seen” radius
- Can use cell optimization





# Similar Ideas Exist in AI

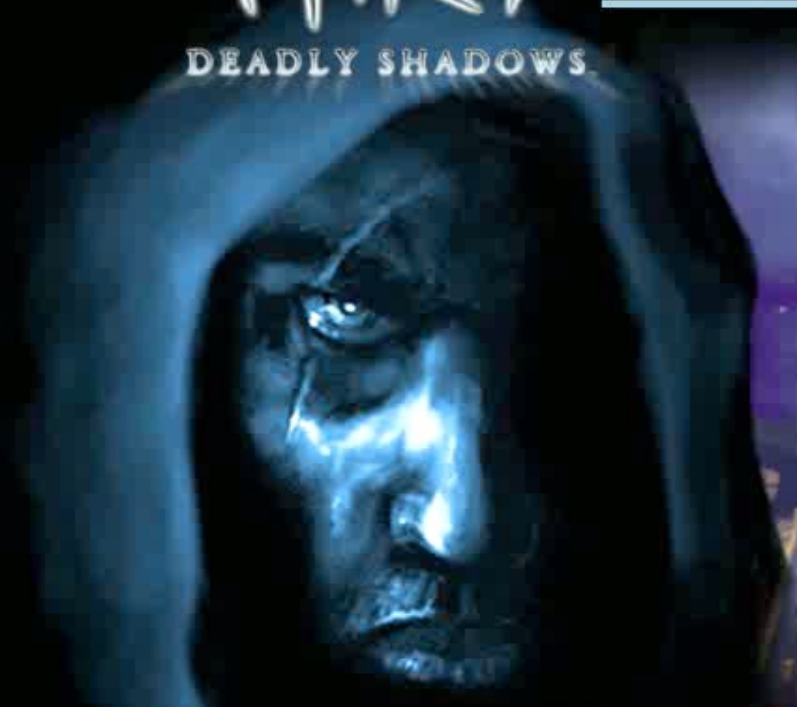
- **Area of Interest**
  - Limit the sensing range
  - Only “see” what in range
  - Used in targeting, stealth
- Works in both directions
  - **Nimbus**: “can see” radius
  - **Aura**: “can be seen” radius
- Can use cell optimization



# THIEF

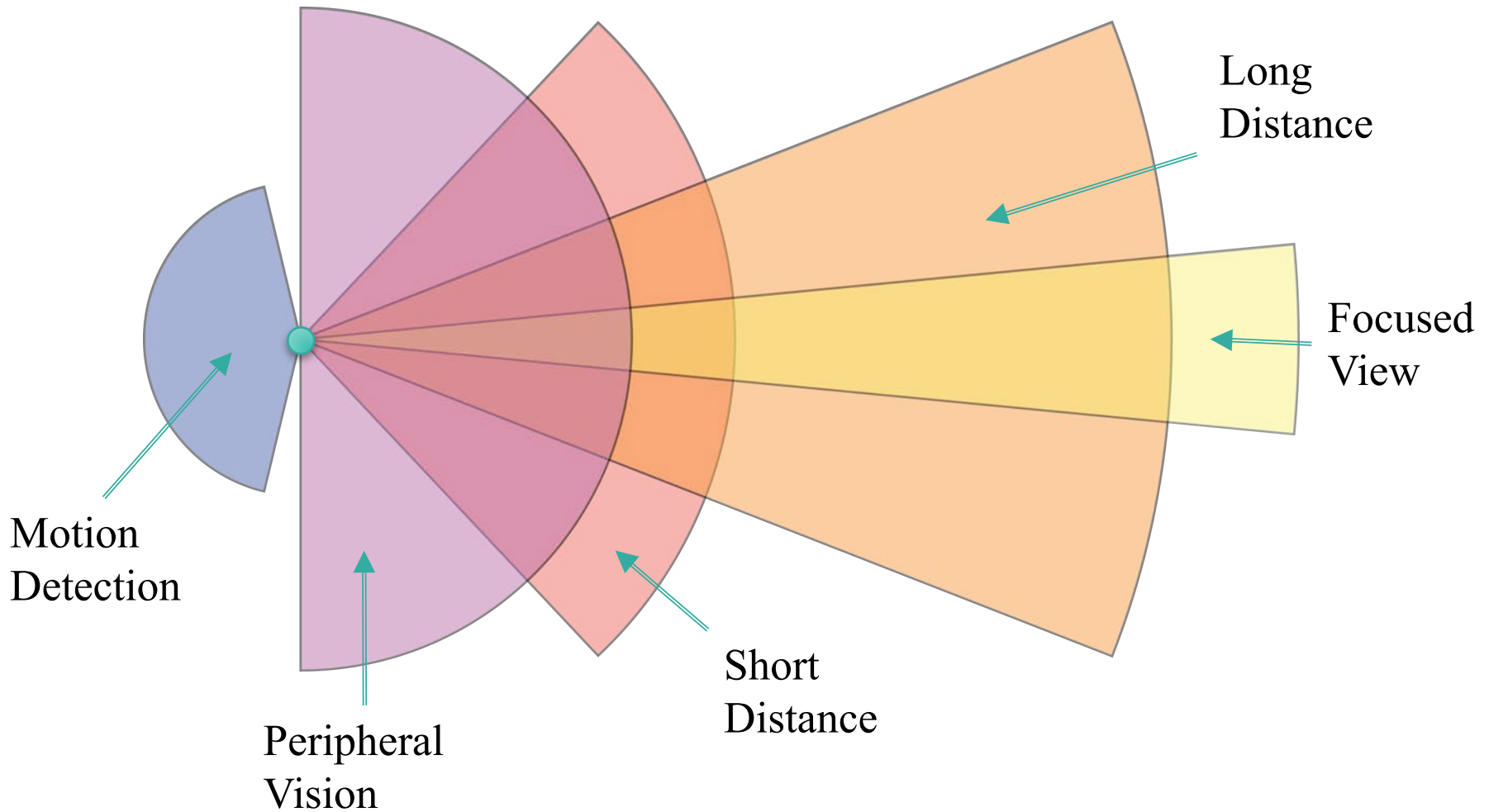
DEADLY SHADOWS

Loading...



Stealth tip: Use WALK to move slowly and very quietly. Use CREEP to move even more slowly and be completely silent.

# Area of Interest Management *Thief*



# Problem with this Idea

## Cell-Based AI

for each entity x:

put x into cell slot

for each cell location:

for each entity x:

for each entity y:

if x can see y:

add y to sense of x

Sense &  
Think

incompatible

Act

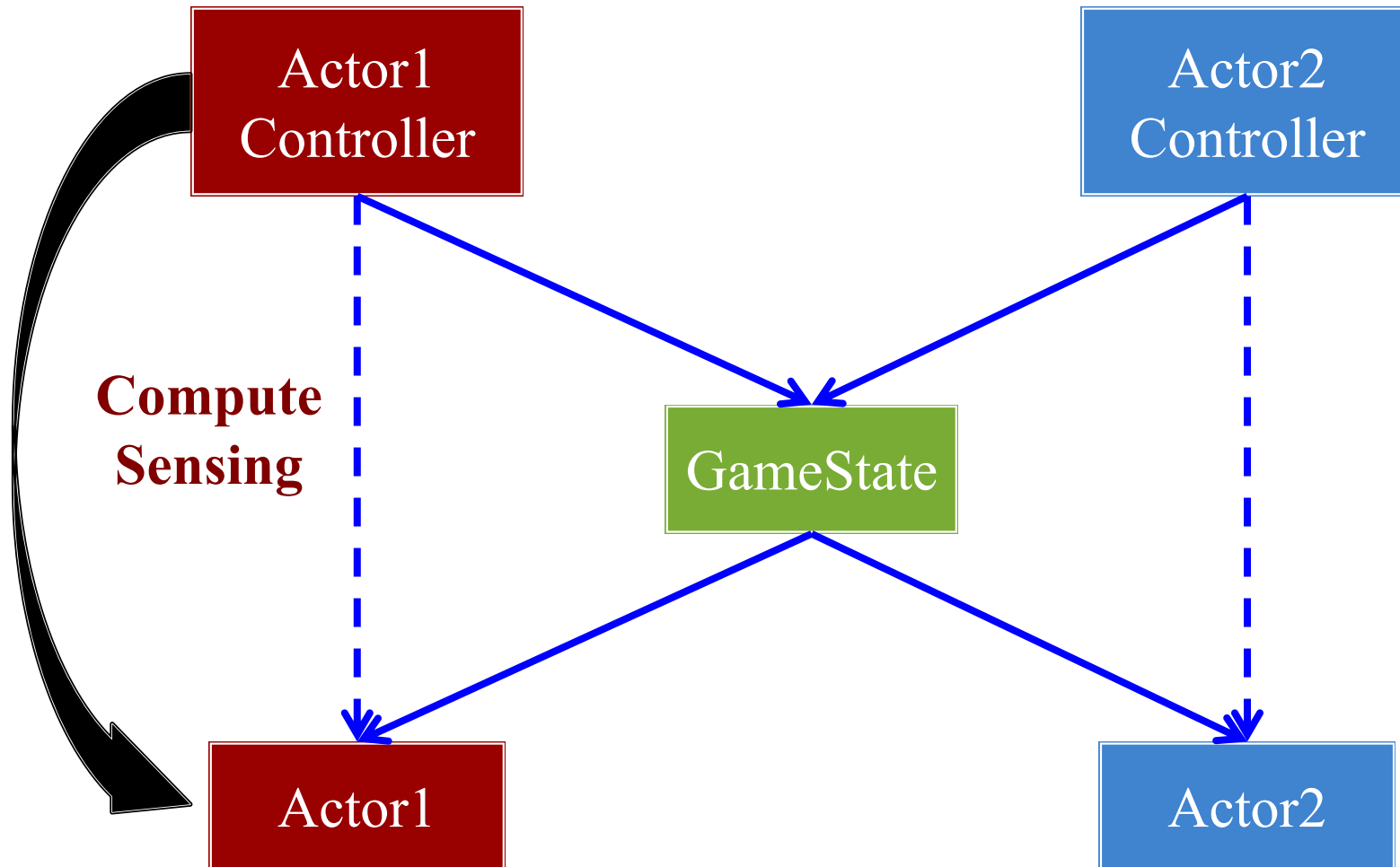
NPC 1

NPC 2

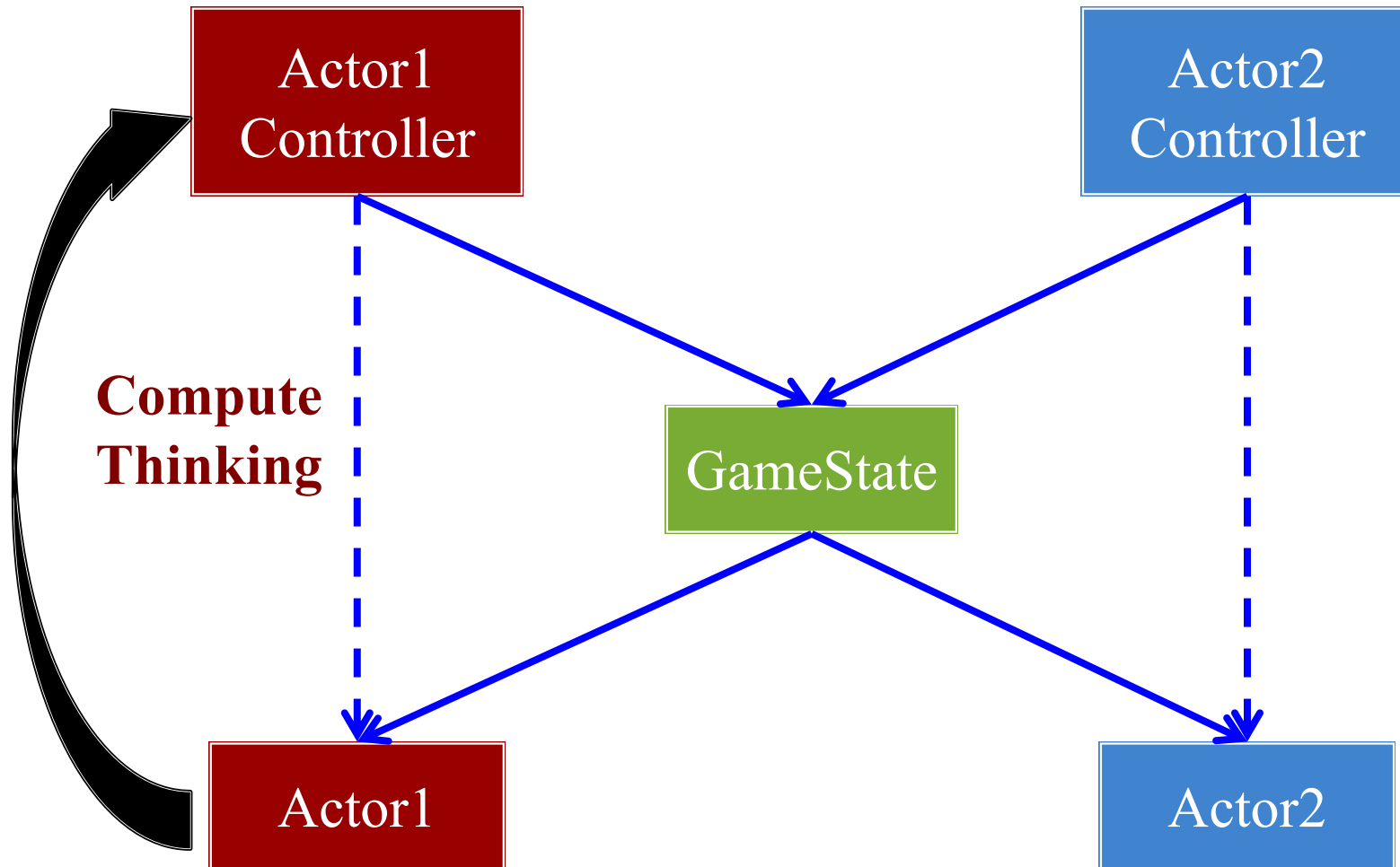
NPC 1

NPC 2

# Recall: Reducing Dependencies



# Recall: Reducing Dependencies

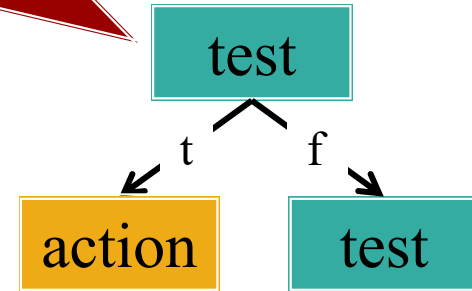
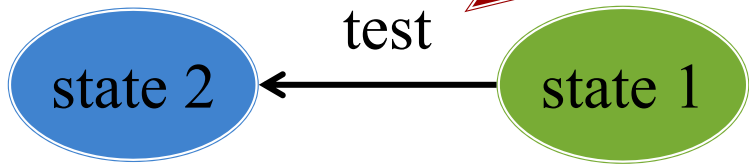


# Solution: Event Driven AI

## Finite State Machines

## Decision Trees

Can support arbitrary (boolean) functions here

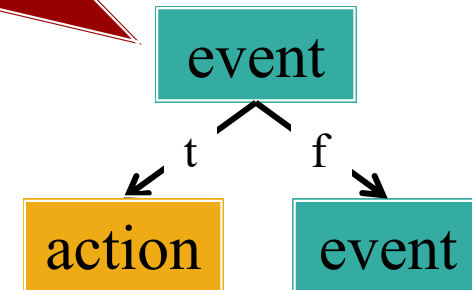


# Solution: Event Driven AI

## Finite State Machines

## Decision Trees

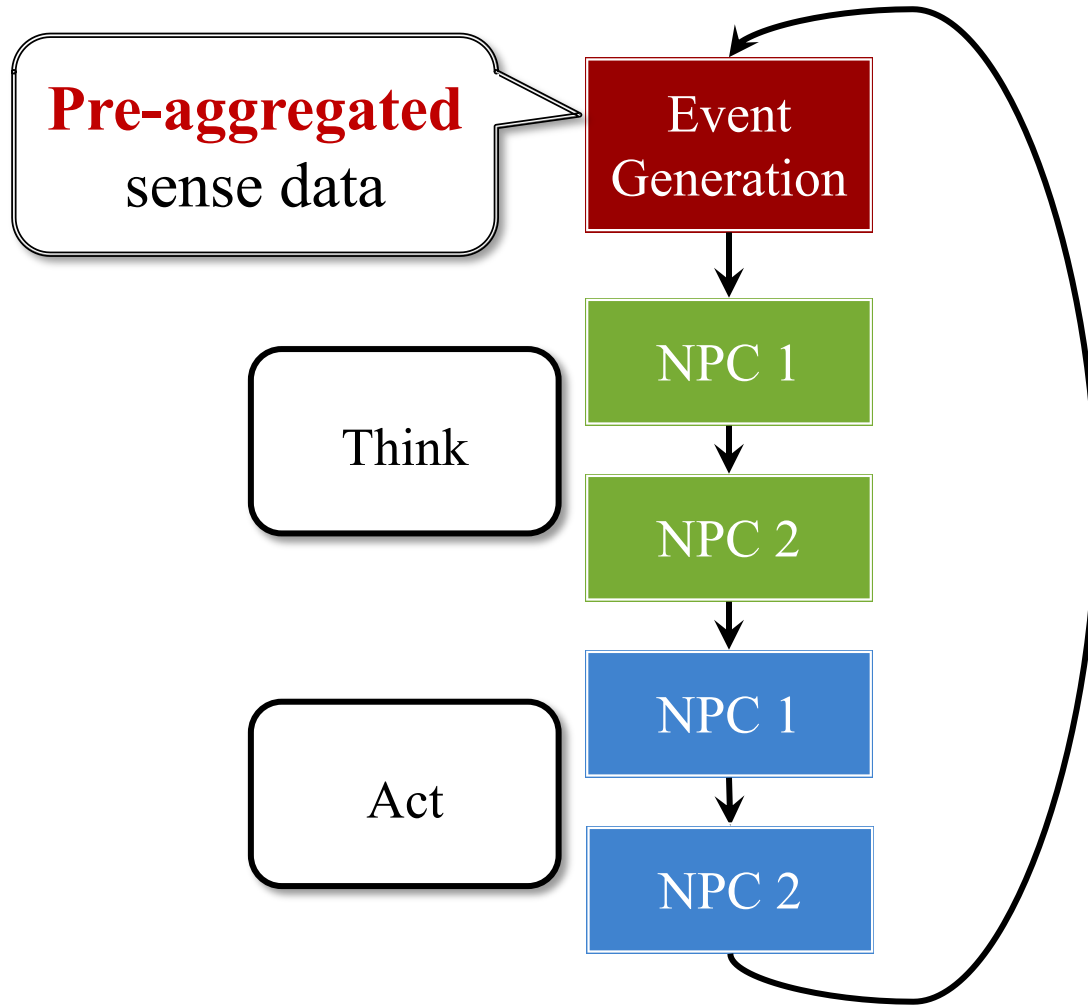
But we only want simple tests!



**Event:** *Precomputed* result before AI thinking starts



# The True AI Loop



# Event: Encoded Sense Data

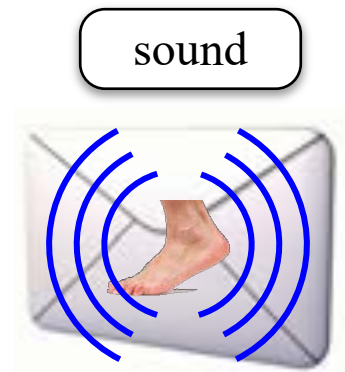
- **Sight Event**

- Type of entity seen
- *Location* of entity seen



- **Sound Event**

- Type of sound heard
- *Direction* of sound heard

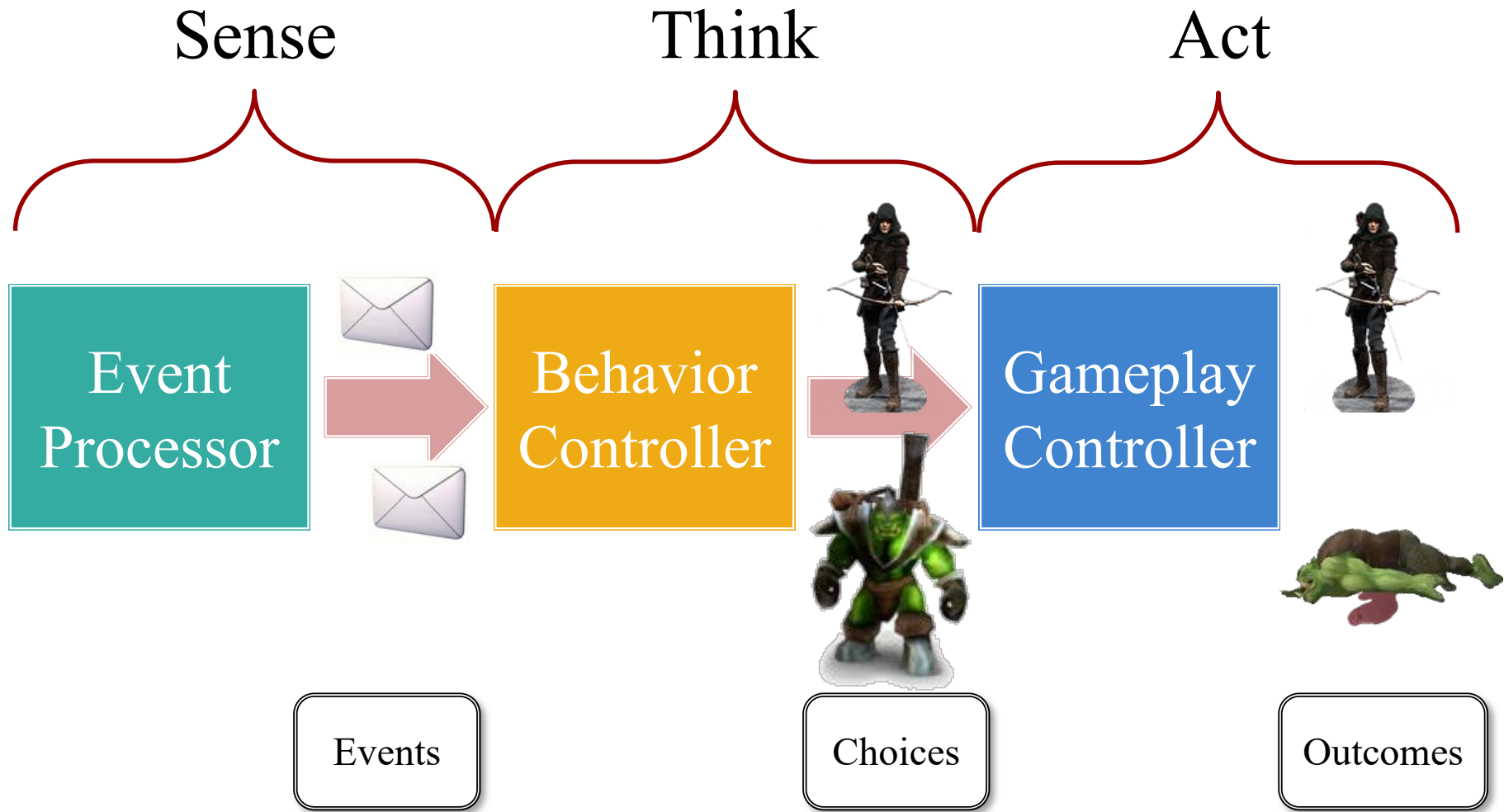


- **Smell Event**

- Type of smell perceived
- *Proximity* of the smell

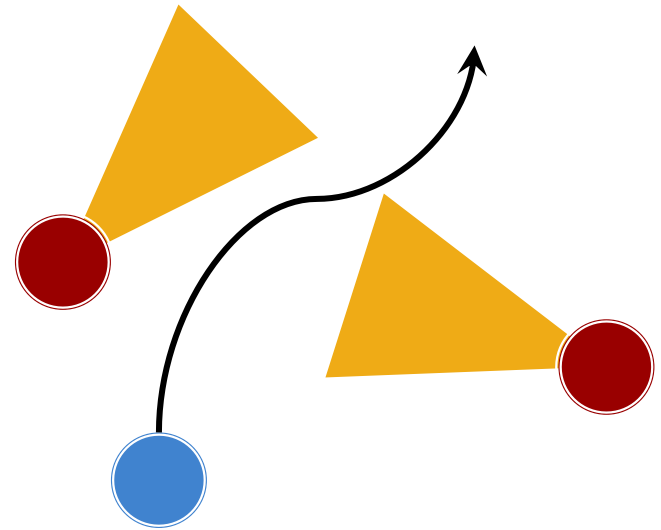


# Sense-Think-Act Revisited

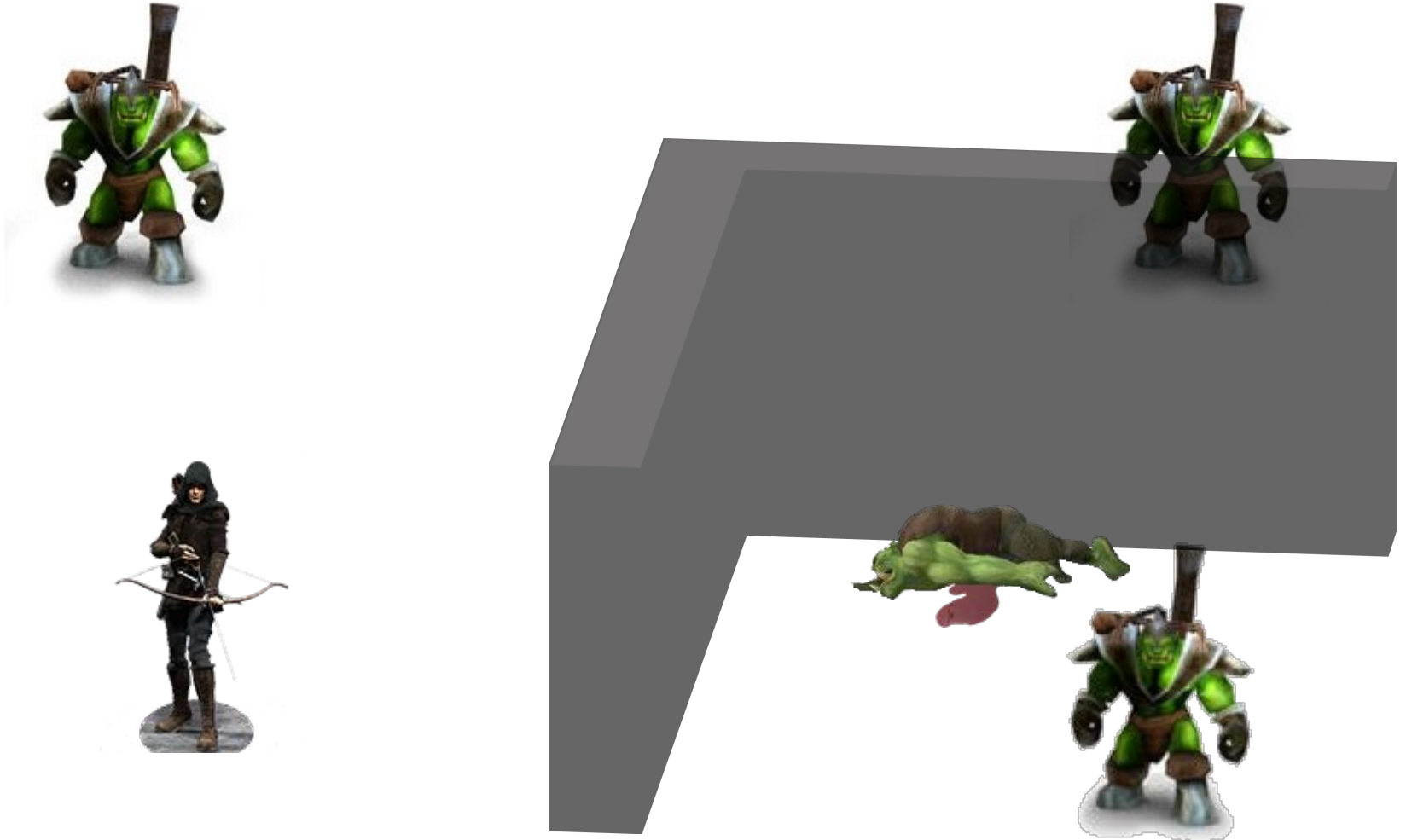


# Example: Line-of-Sight

- Use **Box2D** for sensing
  - Method rayCast in World
  - Provide a RayCastCallback
- Think about the **callback**
  - Happens *after* physics done
  - Often later than AI phase
- It should **generate an event**
  - Can be processed next phase
  - Keeps order of code clean

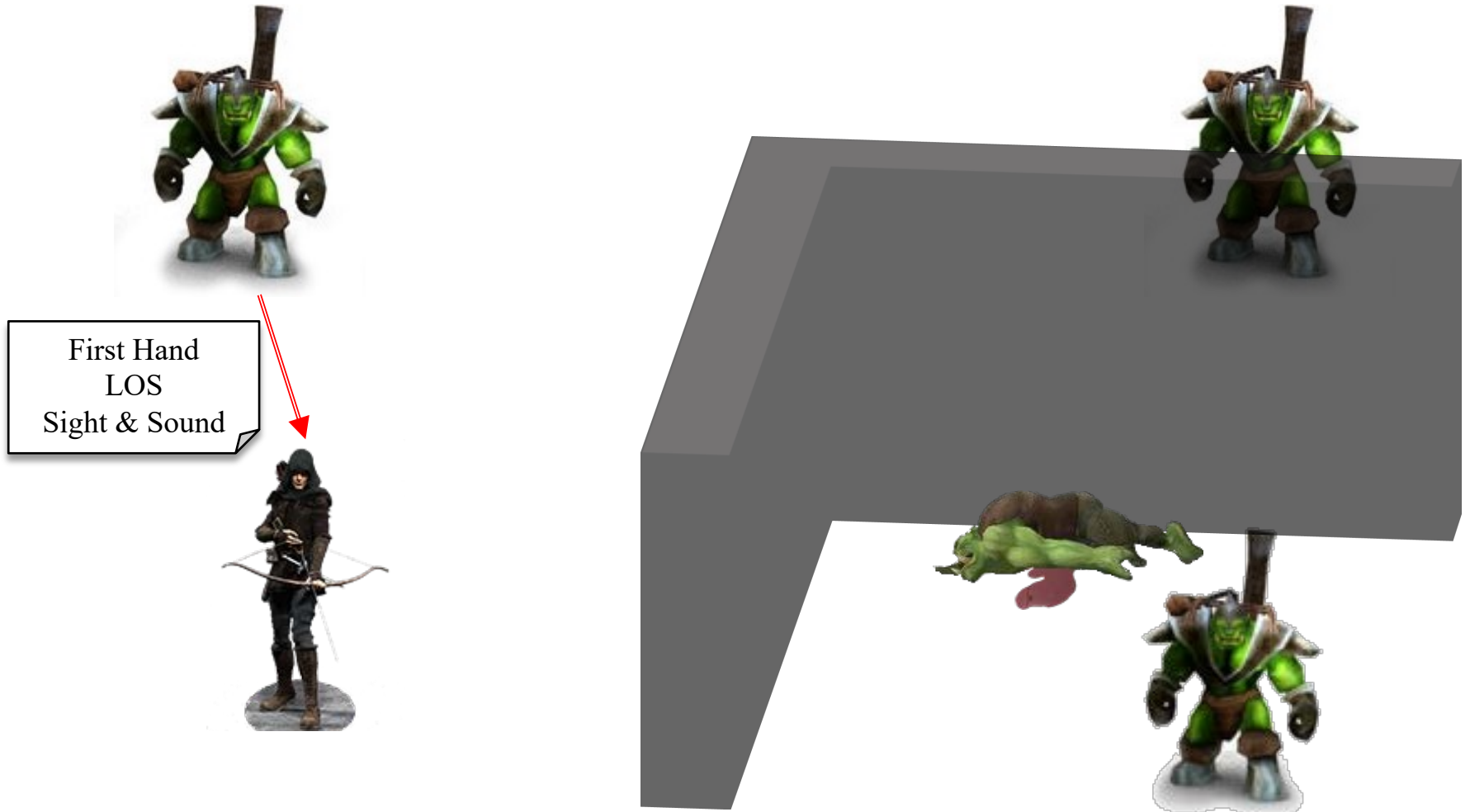


# Communicating Sense Events

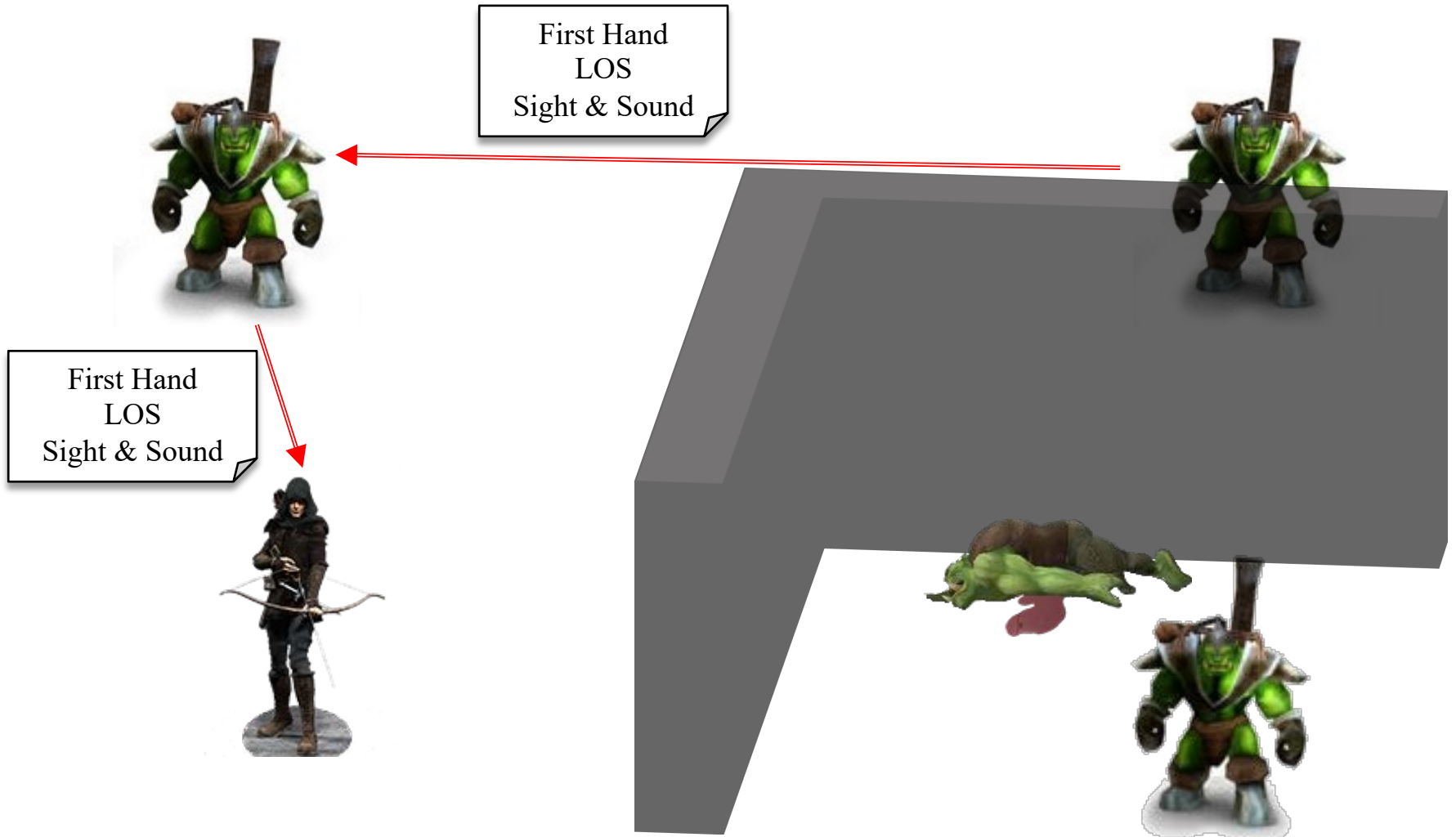


Sensing & Perception

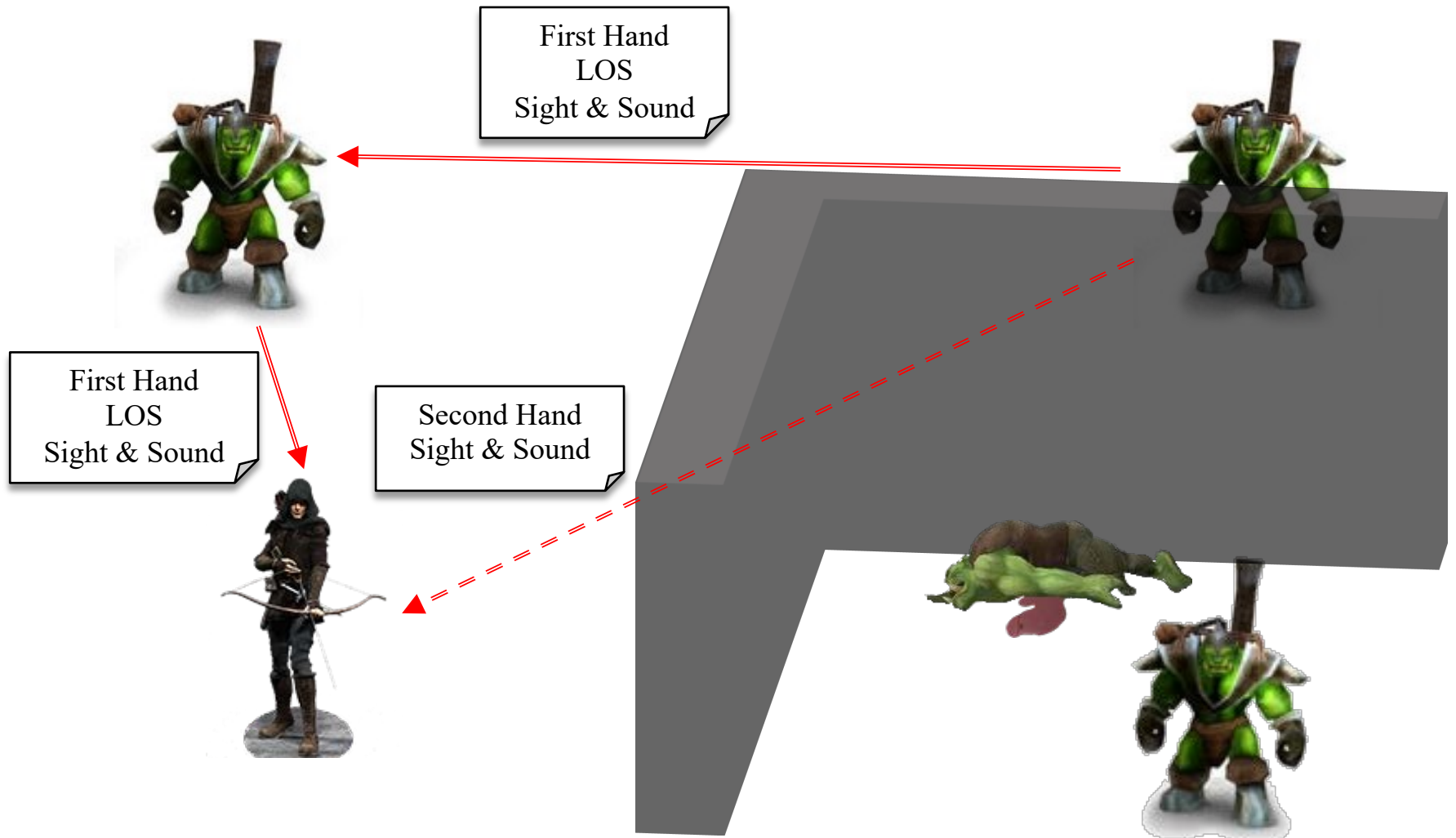
# Communicating Sense Events



# Communicating Sense Events

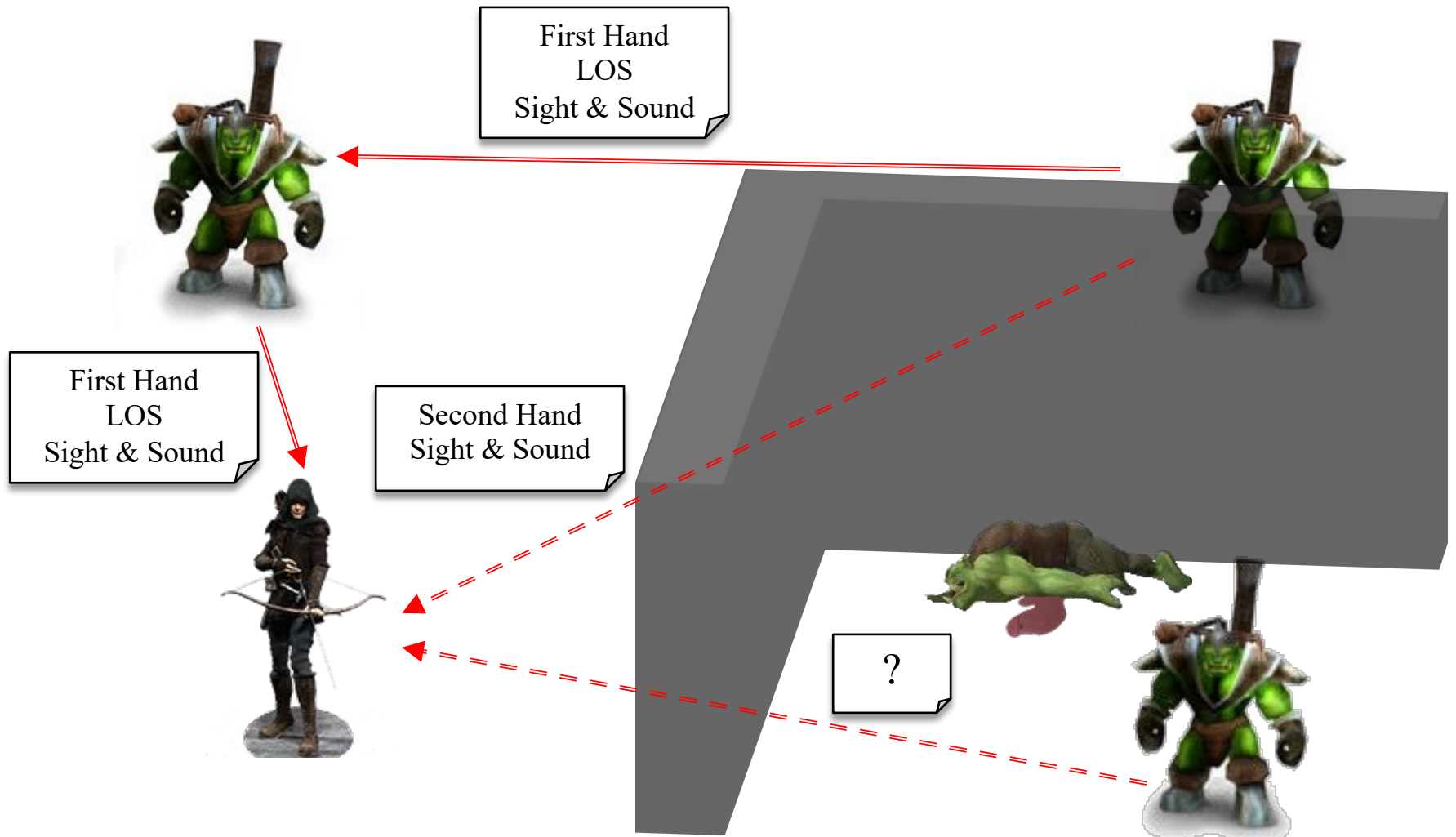


# Communicating Sense Events

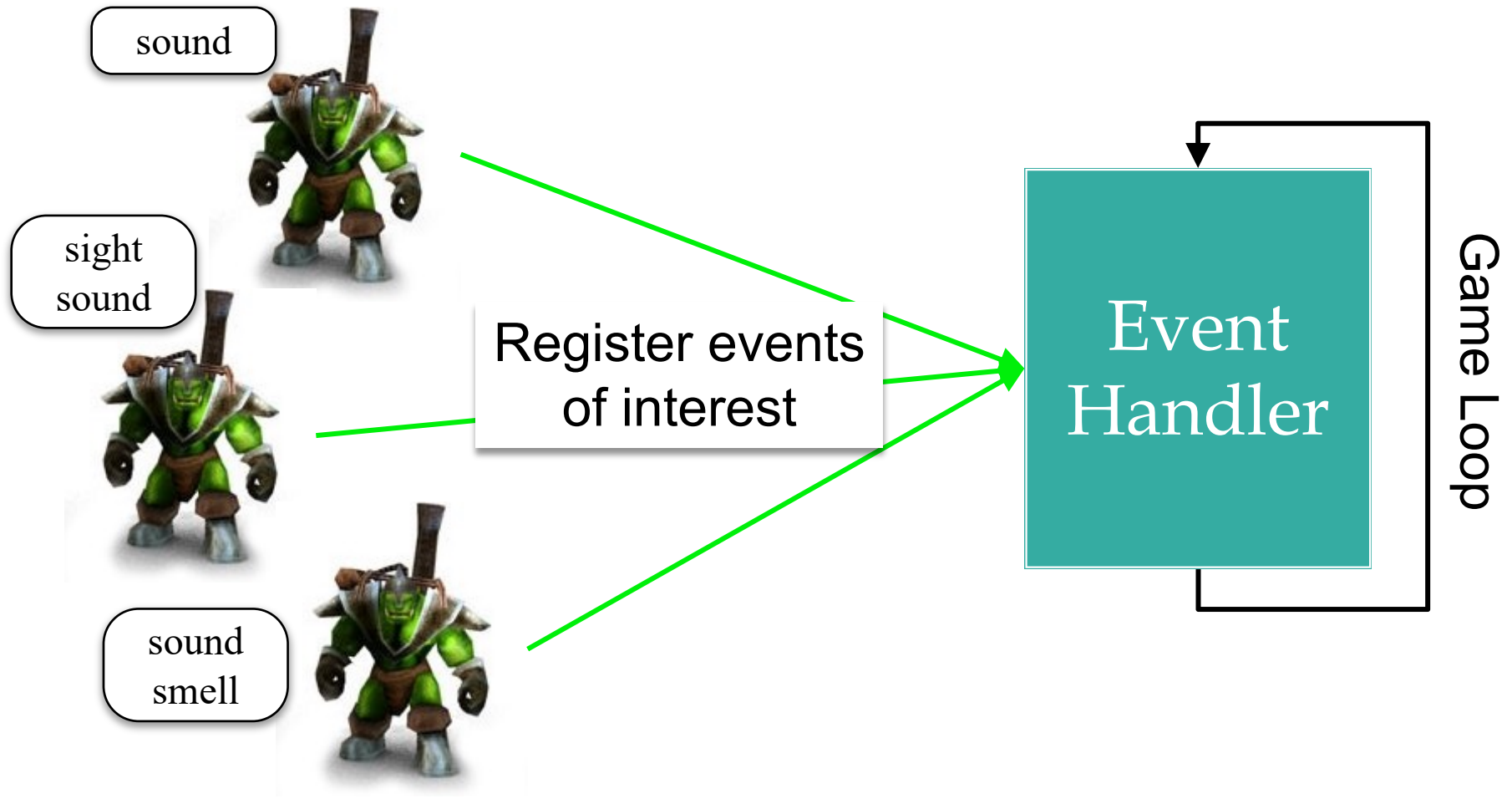




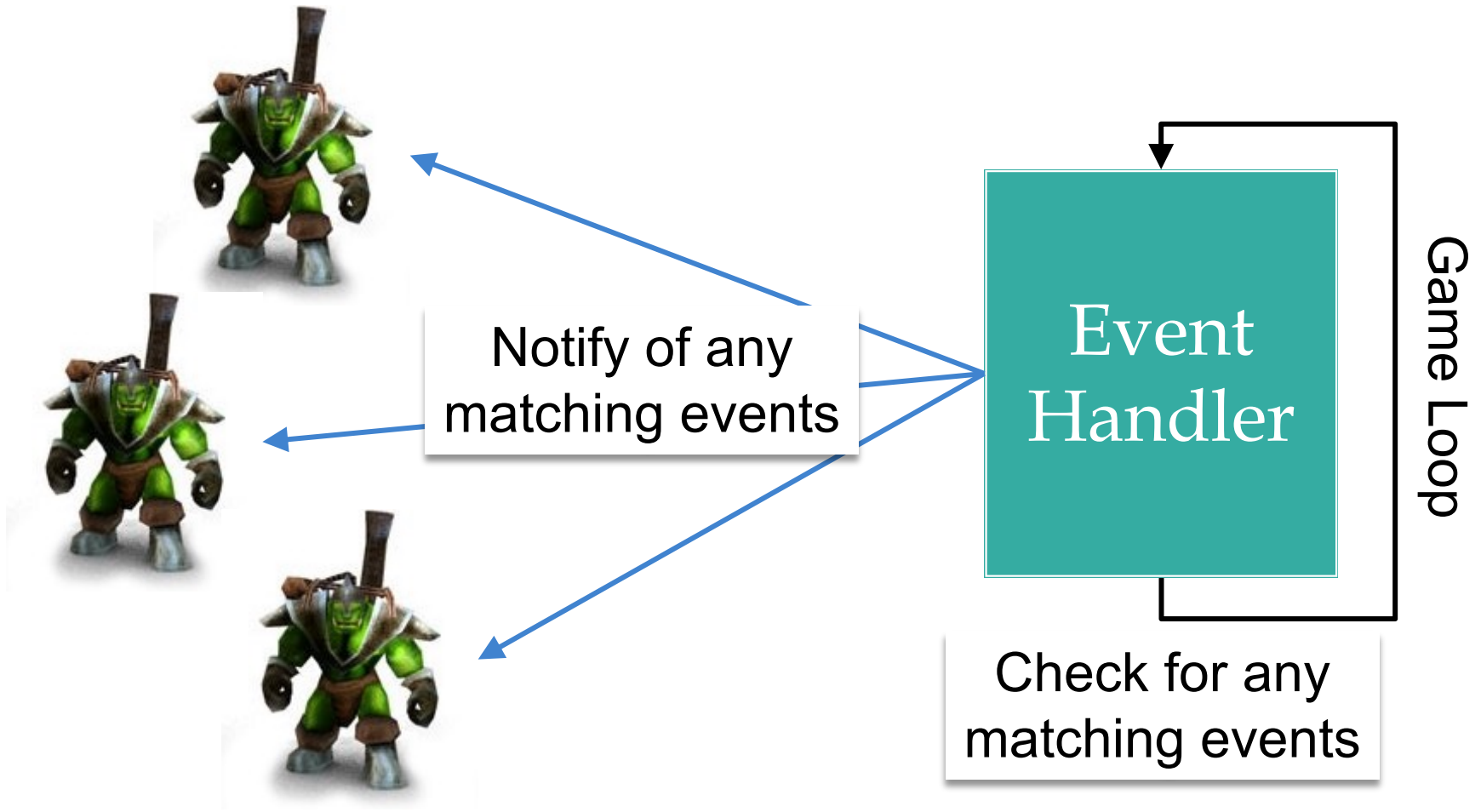
# Communicating Sense Events



# Sense Event Matching



# Sense Event Matching



# Event Communication in LibGDX

---

## MessageDispatcher

---

- Send with `dispatchMessage`
  - `delay` (0 if immediate)
  - `sender` (can be null)
  - `target` (null for subscribers)
  - `type` (user defined int code)
  - `data` (object, like Box2D)
- Subscribe with `addListener`
  - NPC to receive message
  - Type (int) to subscribe to

## Telegram

---

- Stores the event message
  - Entries of `dispatchMessage`
  - Except for the `delay` value
  - Preaggregated sense in `data`
- Received by `Telegraph`
  - Interface for the receiver
  - Implemented by the NPC
  - One method: `handleMessage`

# Event Communication in LibGDX

## MessageDispatcher

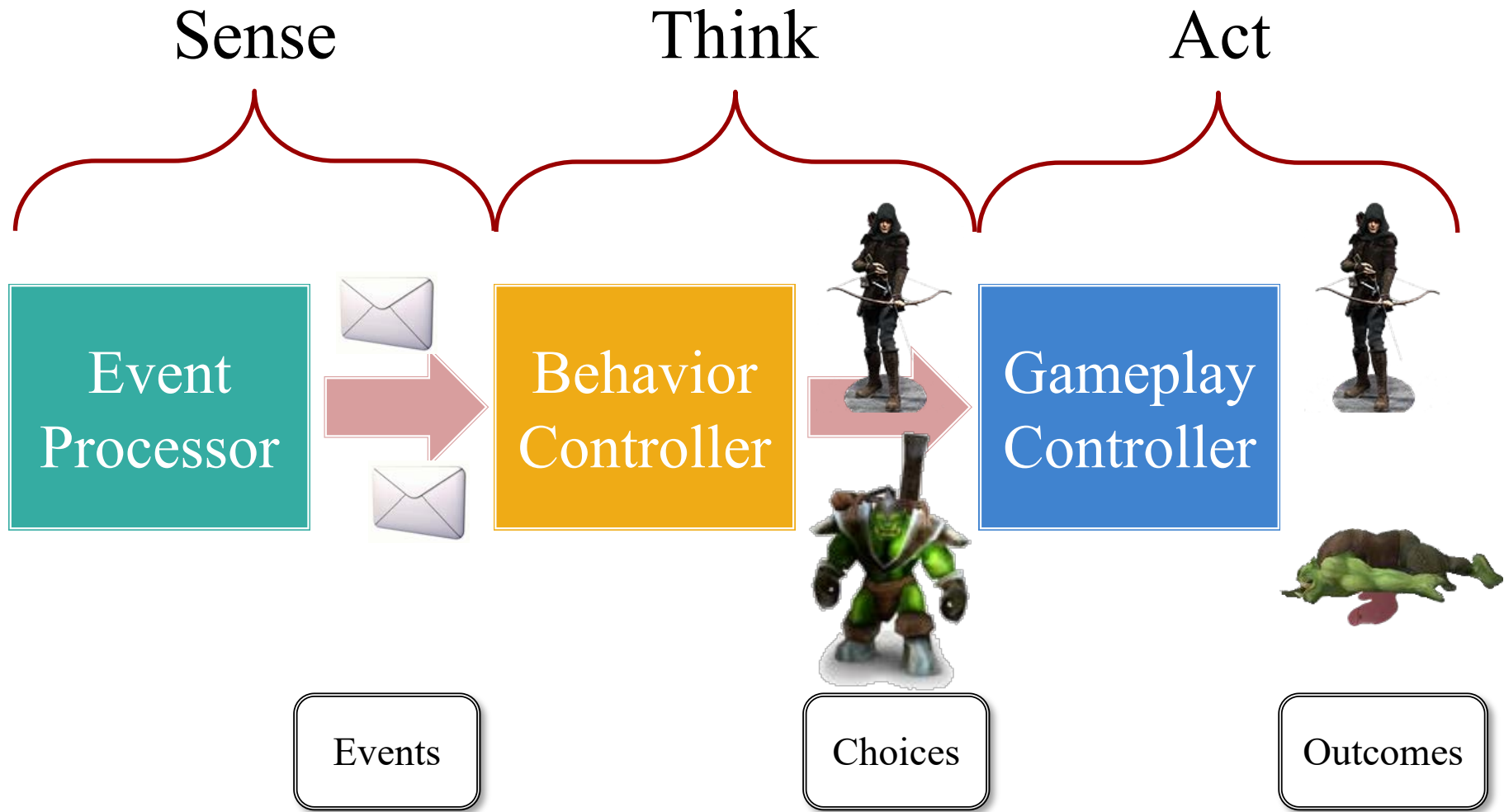
- Send with `dispatchMessage`
  - `delay` (0 if immediate)
  - `sender` (can be null)
  - `target` (null for subscribers)
  - `type` (user defined int code)
  - `data` (object, like Box2D)
- Subscribe with `addListener`
  - NPC to receive message
  - Type (int) to subscribe to



## Telegram

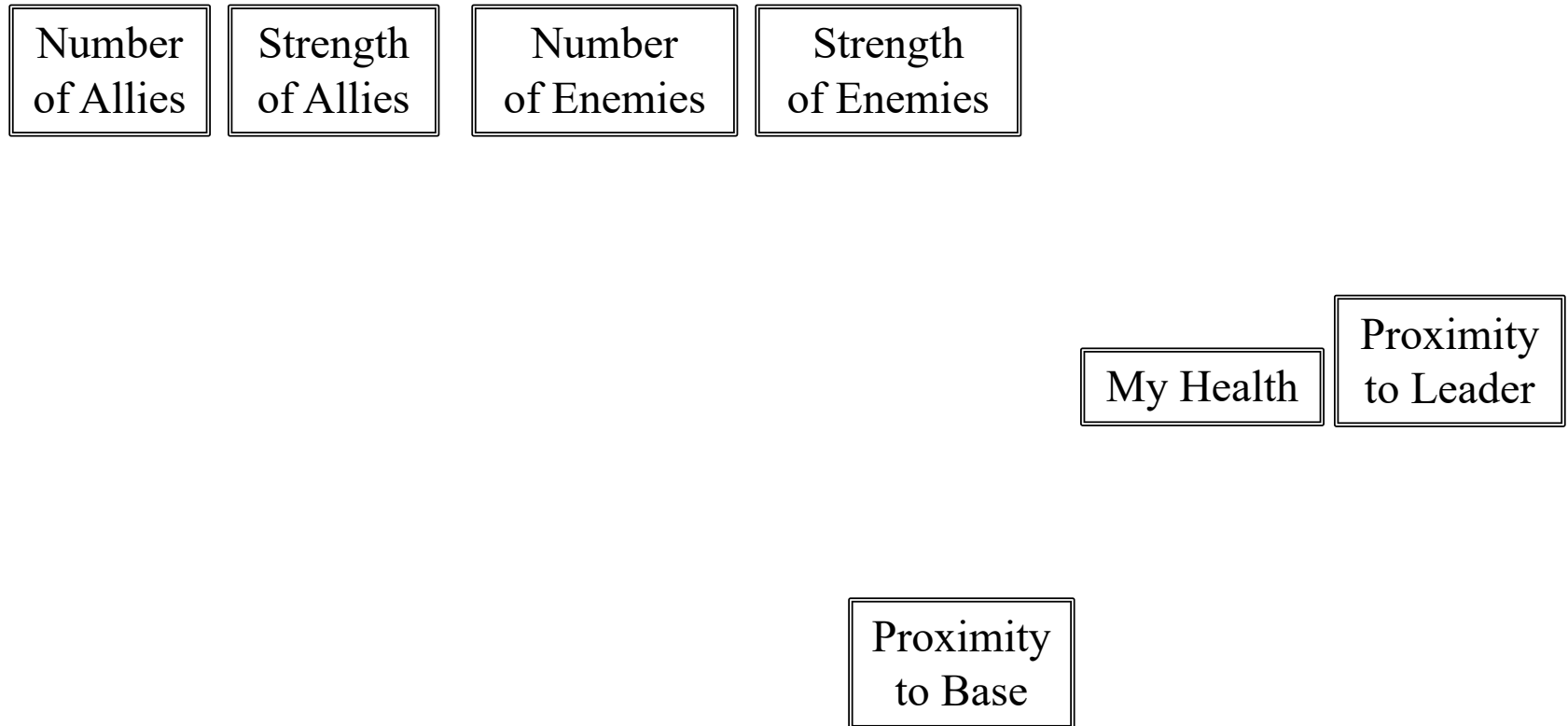
- Stores the event message
  - Entries of `dispatchMessage`
  - Except for the `delay` value
  - Preaggregated sense in `data`
- Received by `Telegraph`
  - Interface for the receiver
  - Implemented by the NPC
  - One method: `handleMessage`

# Separation Allows Many Optimizations



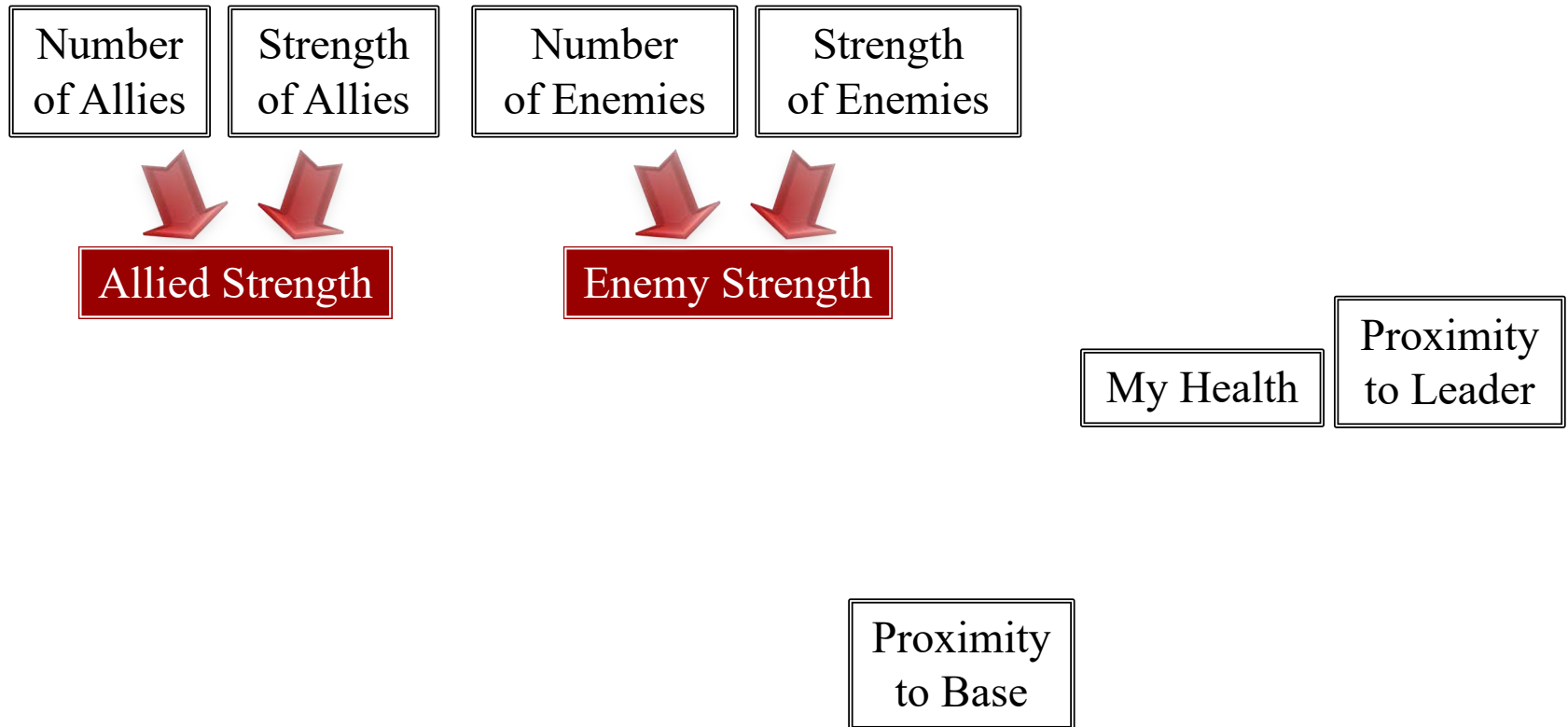
# Compression: Aggregation Trees

Slide courtesy of Dave Mark



# Compression: Aggregation Trees

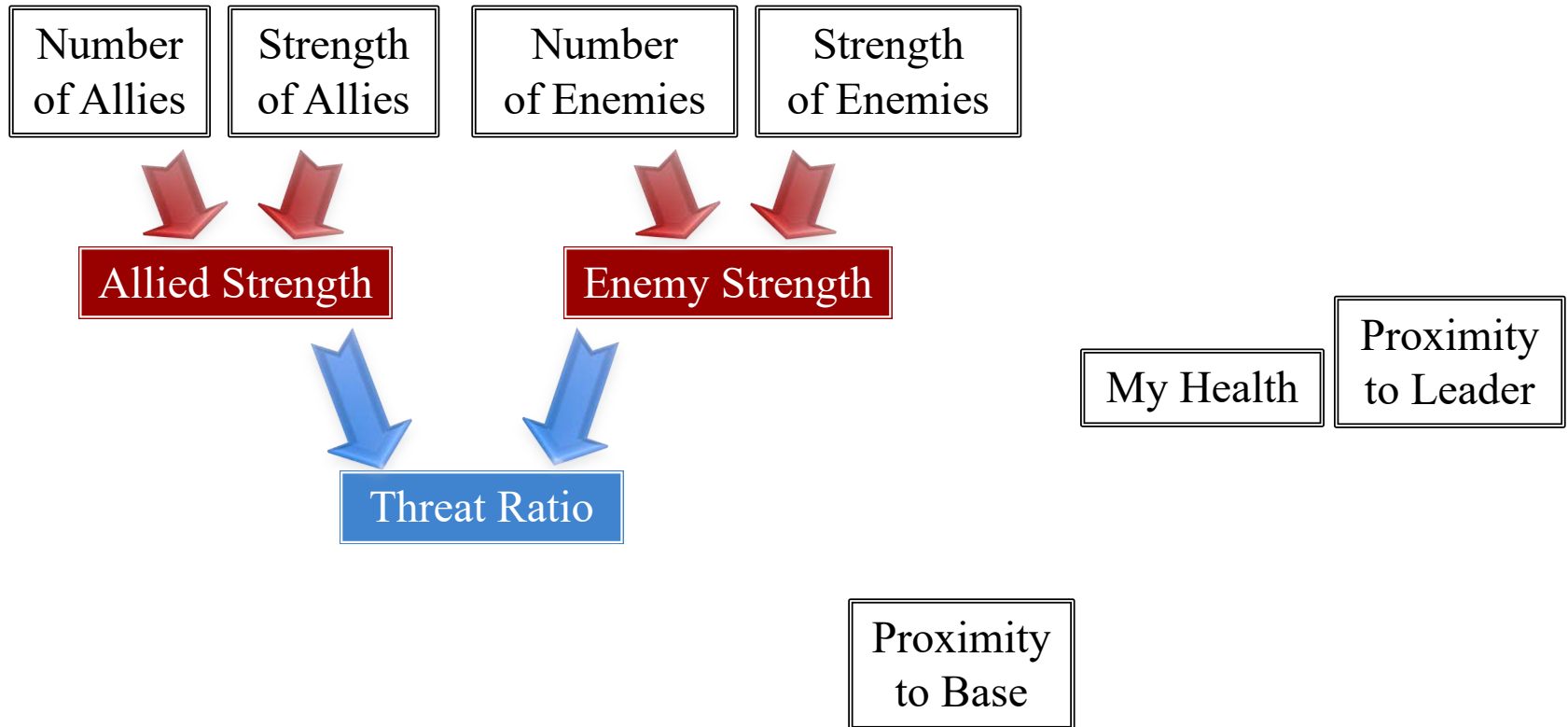
Slide courtesy of Dave Mark





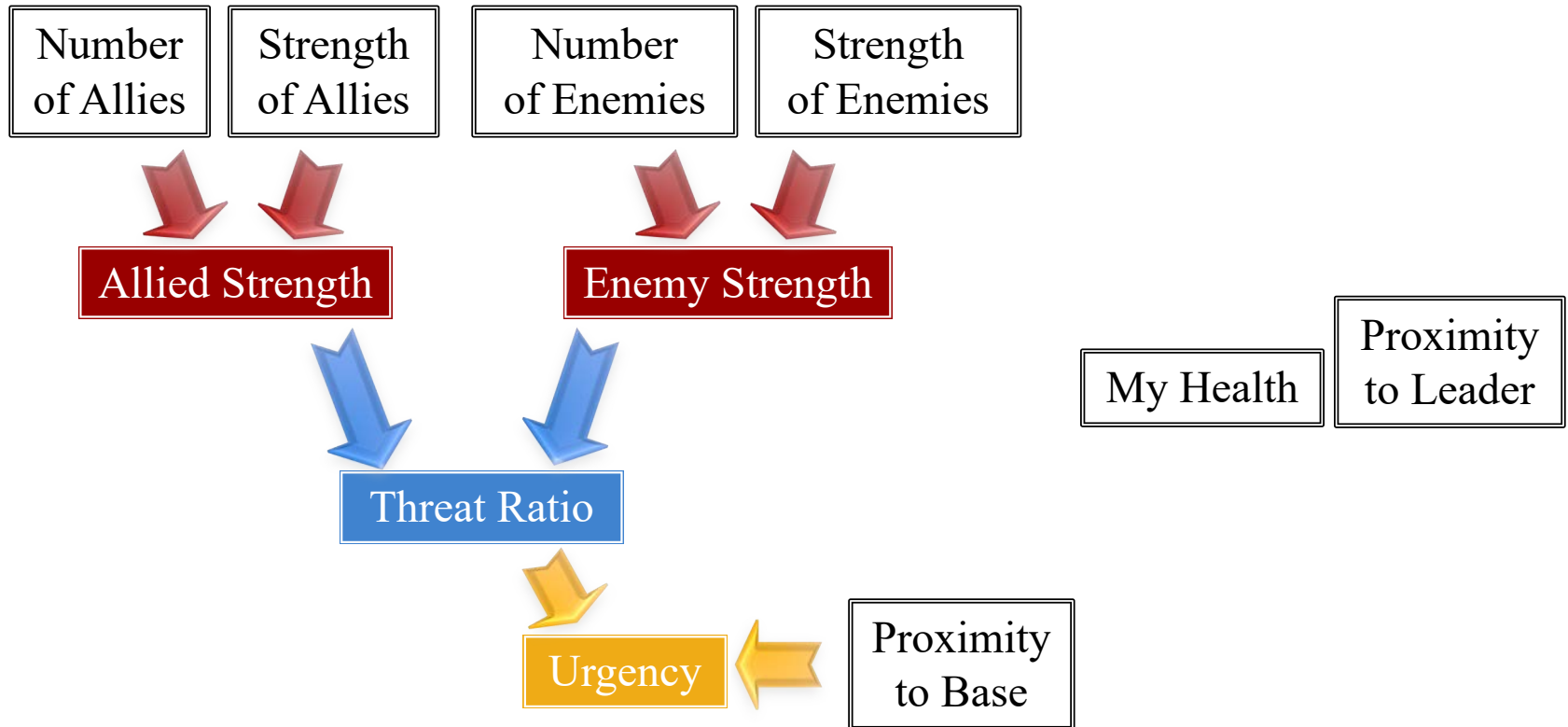
# Compression: Aggregation Trees

Slide courtesy of Dave Mark



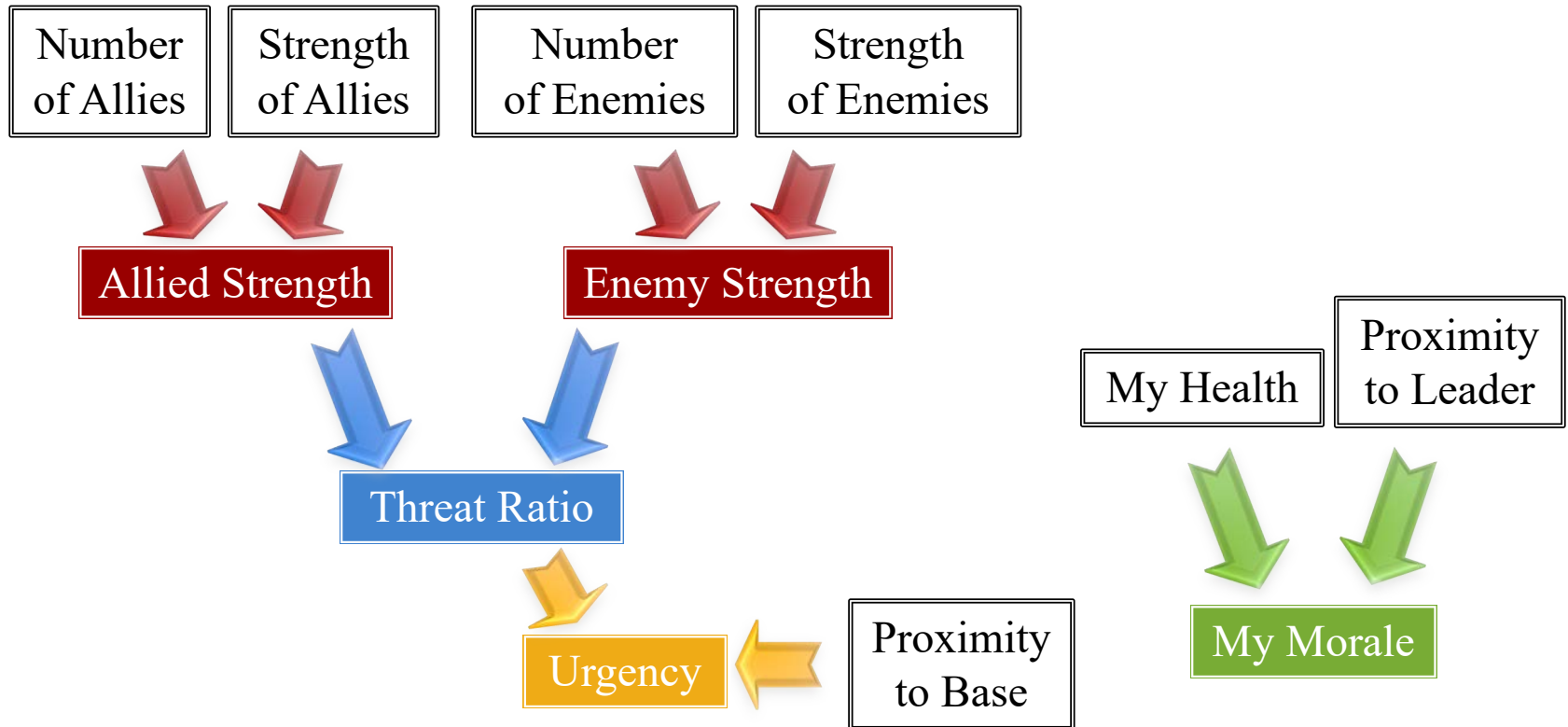
# Compression: Aggregation Trees

Slide courtesy of Dave Mark



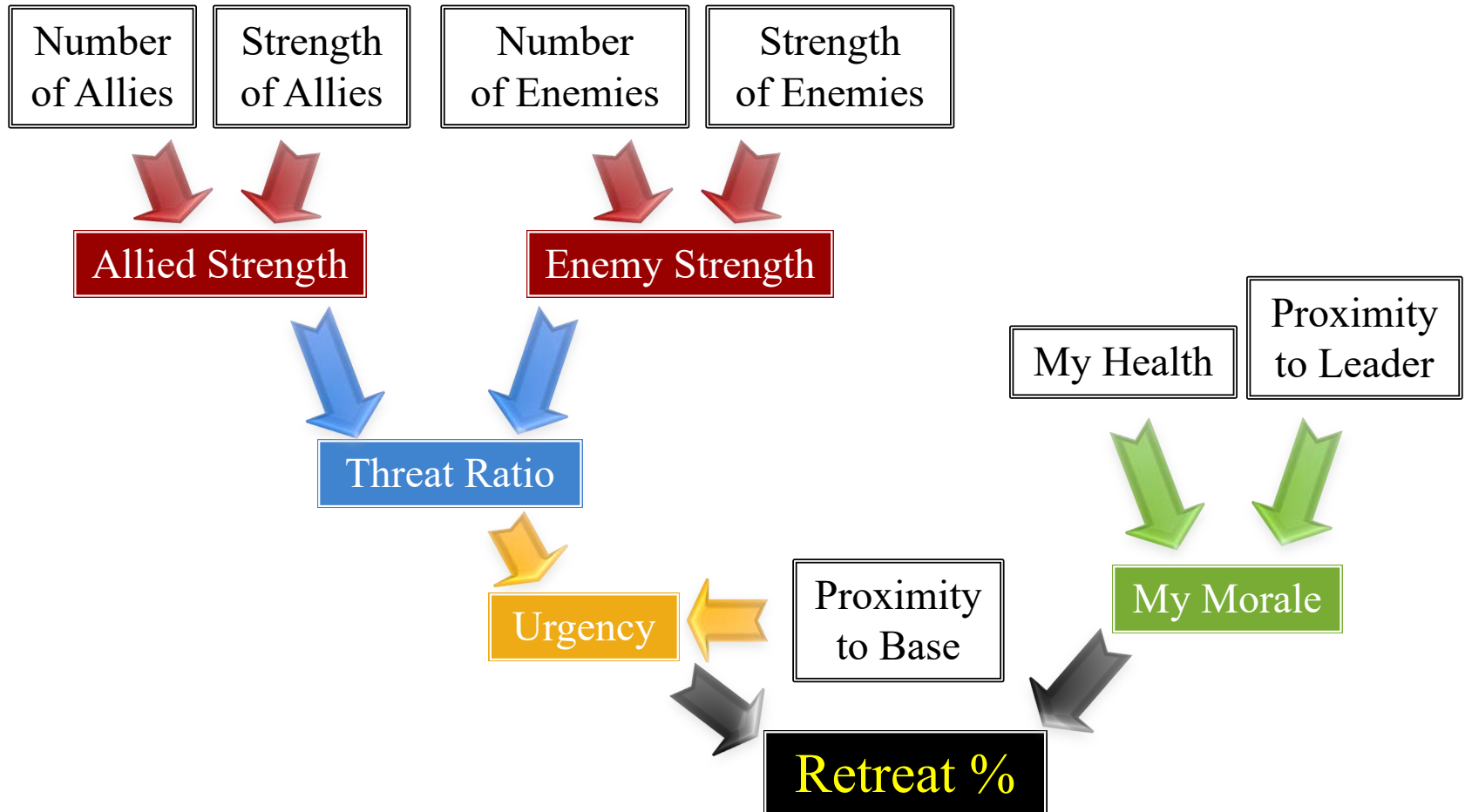
# Compression: Aggregation Trees

Slide courtesy of Dave Mark



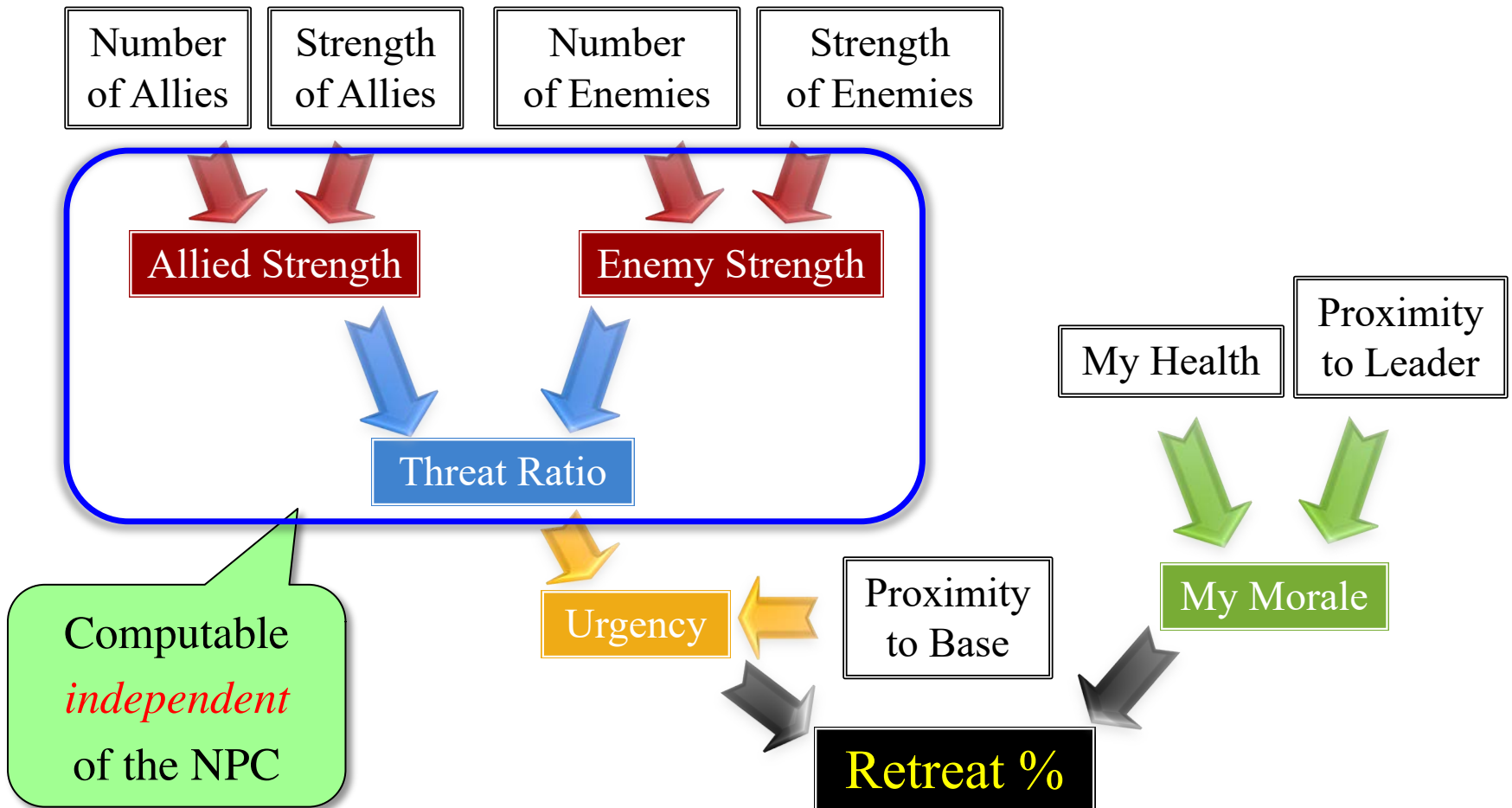
# Compression: Aggregation Trees

Slide courtesy of Dave Mark



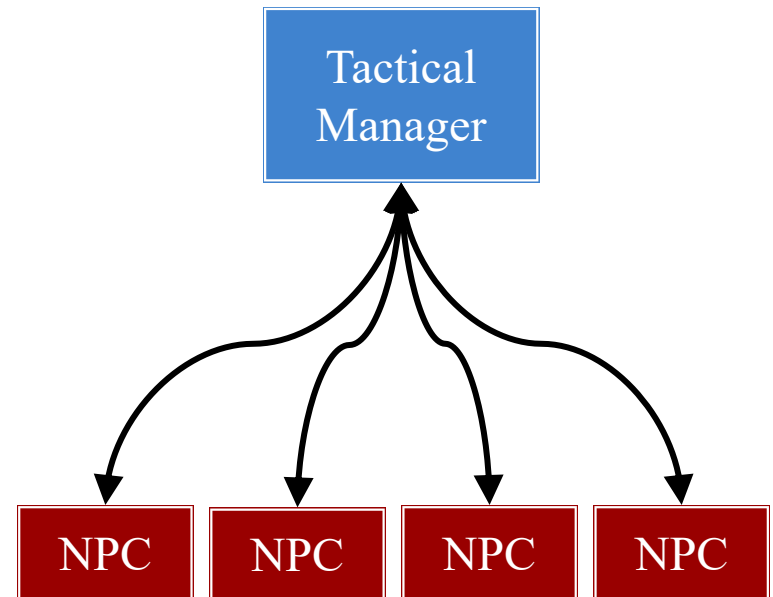
# Compression: Aggregation Trees

Slide courtesy of Dave Mark



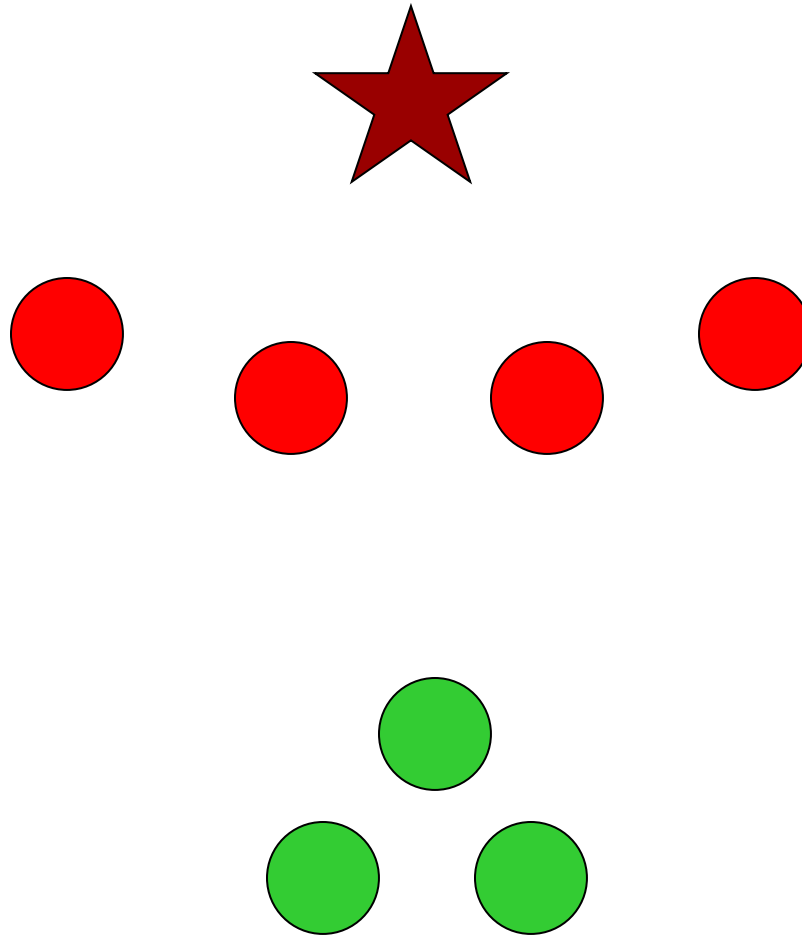
# Delegation: Tactical Managers

- “Invisible NPC”
  - Assigned to NPC Group
  - Both *senses* and *thinks*
  - Sends *commands* as events
- **Applications**
  - Protecting special units
  - Flanking
  - Covering fire
  - Leapfrogging advance



# Protecting Special Units

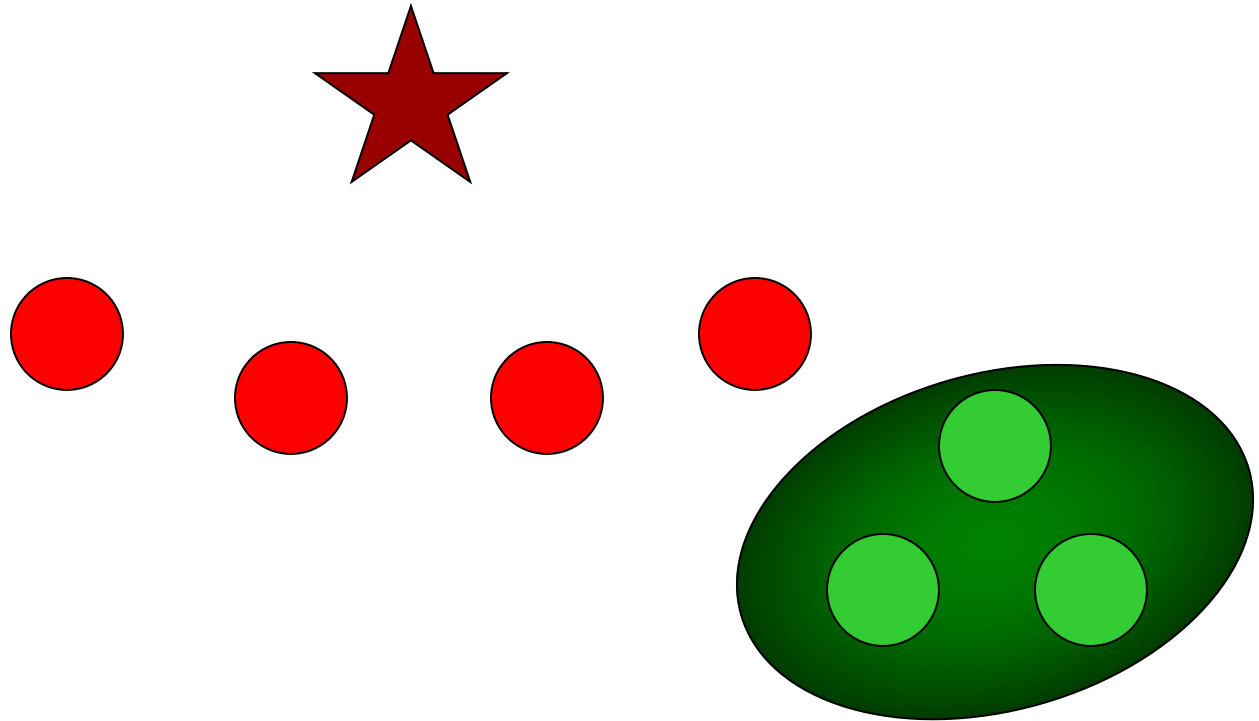
---



Slide courtesy of Dave Mark

# Protecting Special Units

---

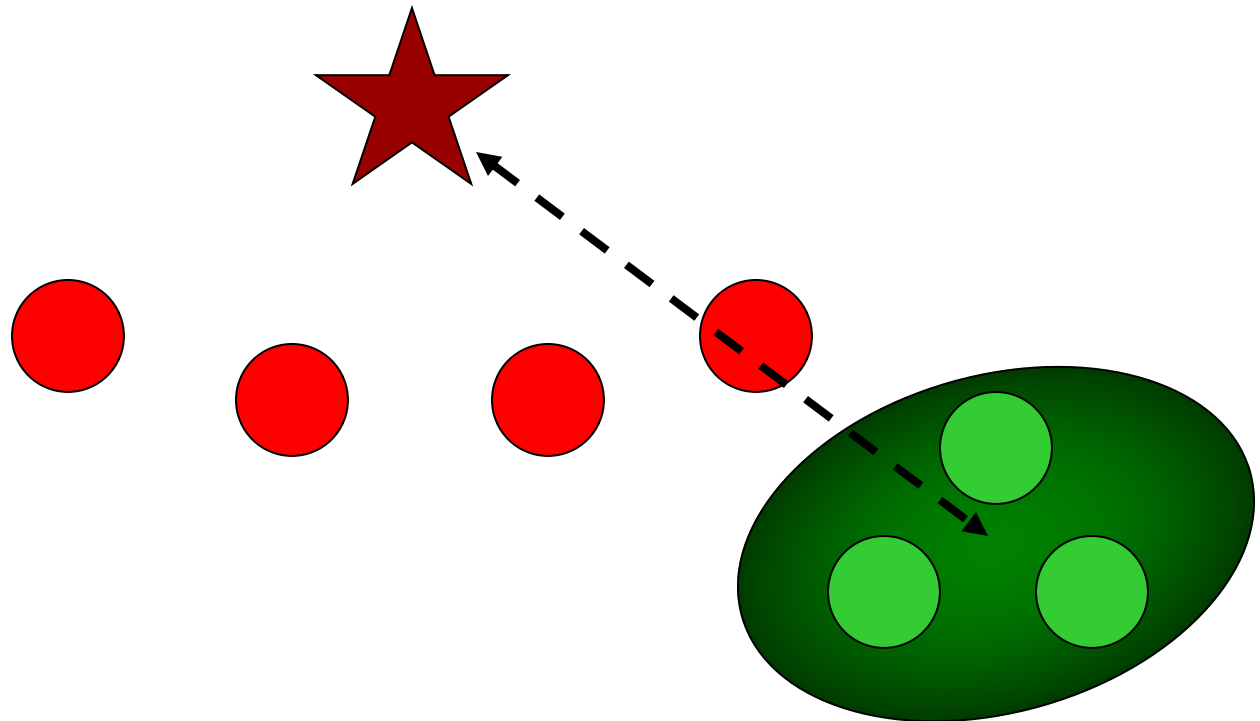


Slide courtesy of Dave Mark



# Protecting Special Units

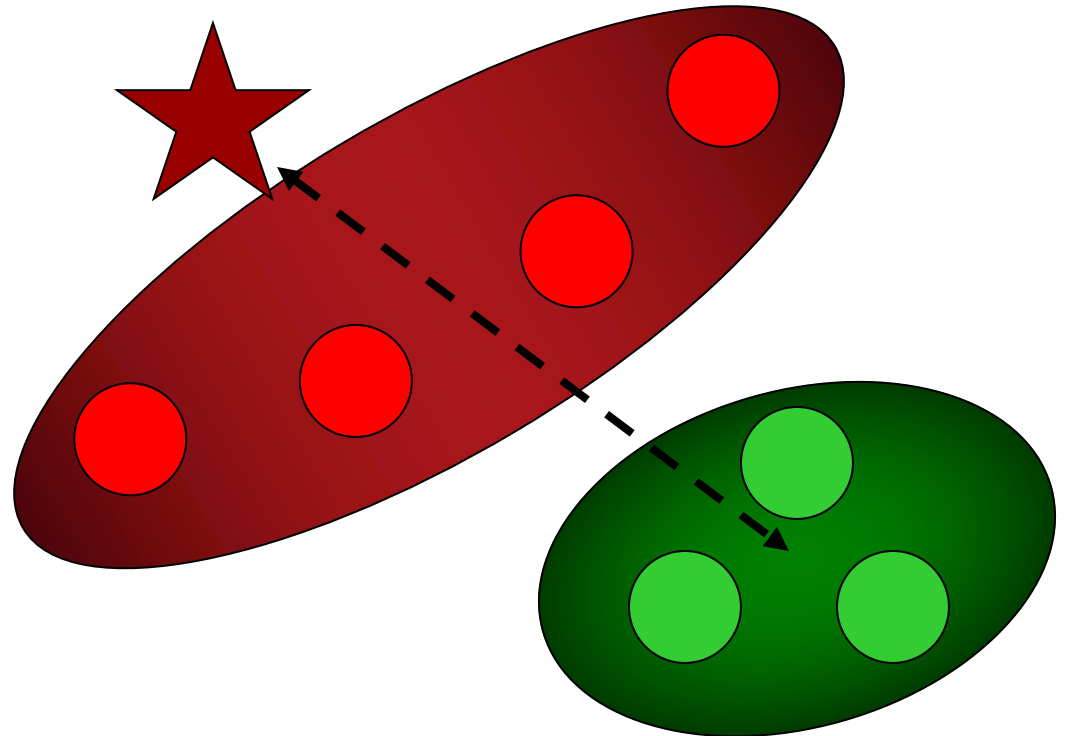
---



Slide courtesy of Dave Mark

# Protecting Special Units

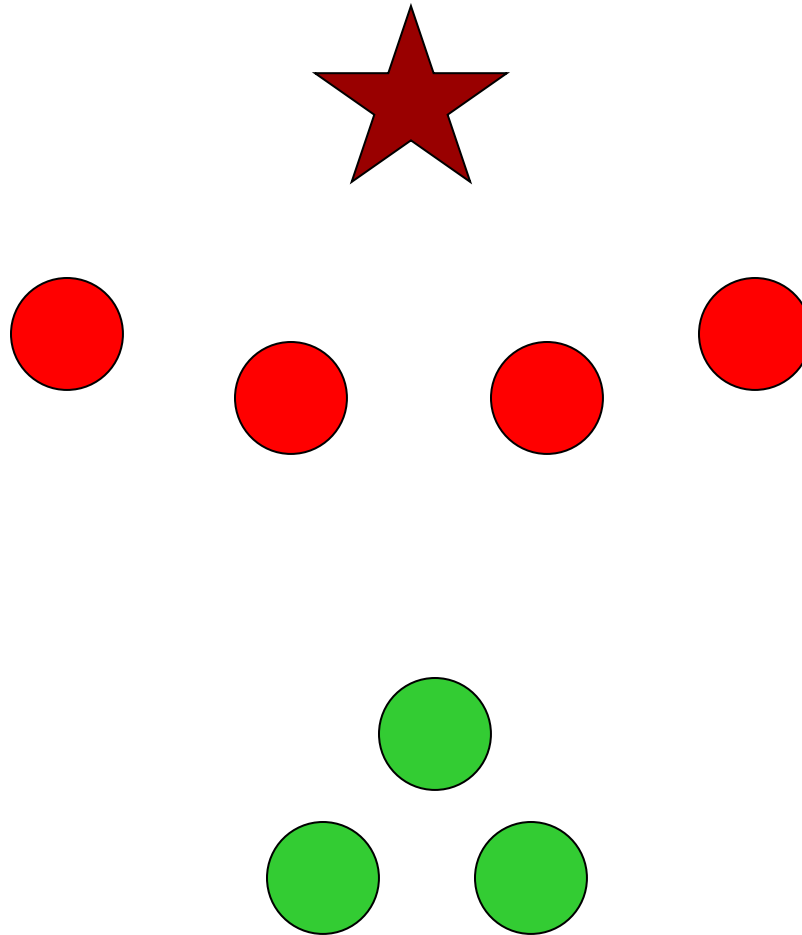
---



Slide courtesy of Dave Mark

# Protecting Special Units

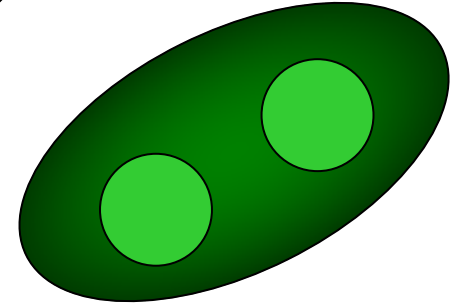
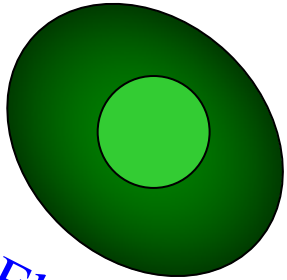
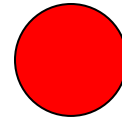
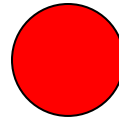
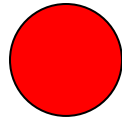
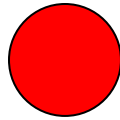
---



Slide courtesy of Dave Mark

# Protecting Special Units

---

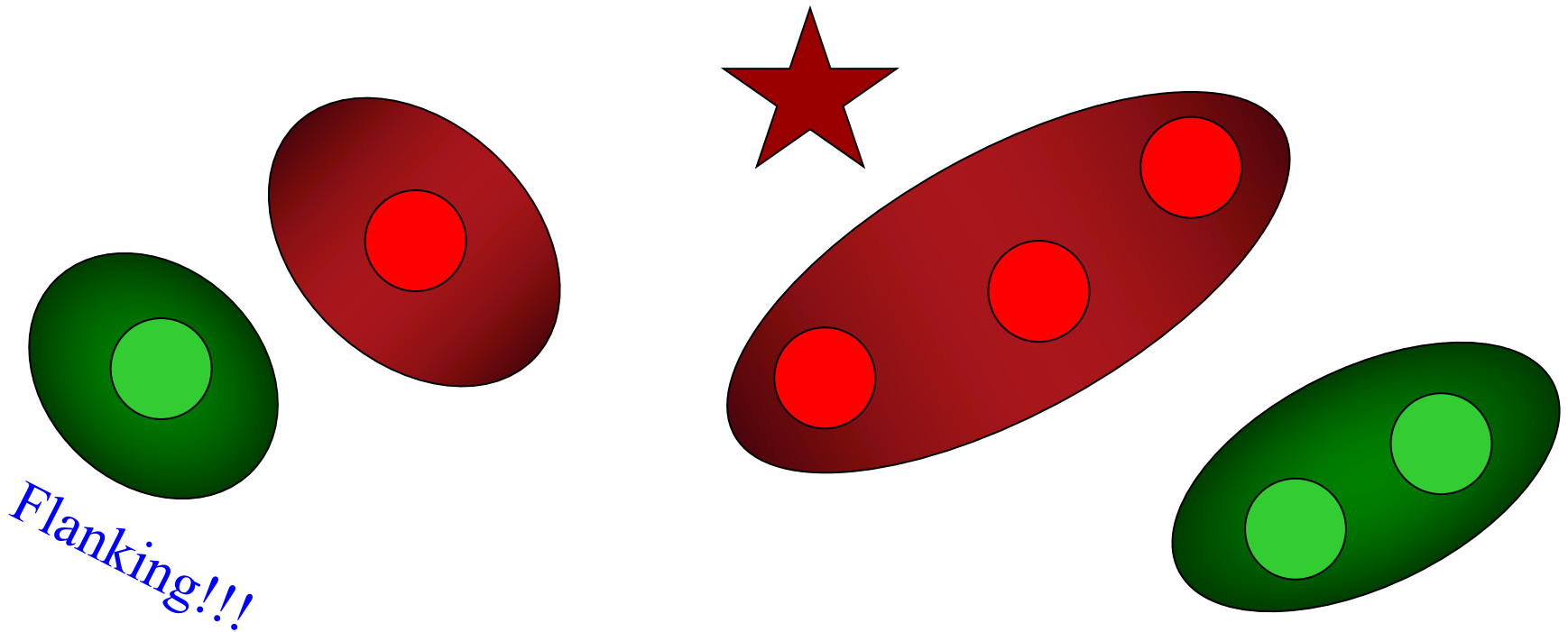


*Flanking!!!*

Slide courtesy of Dave Mark

# Protecting Special Units

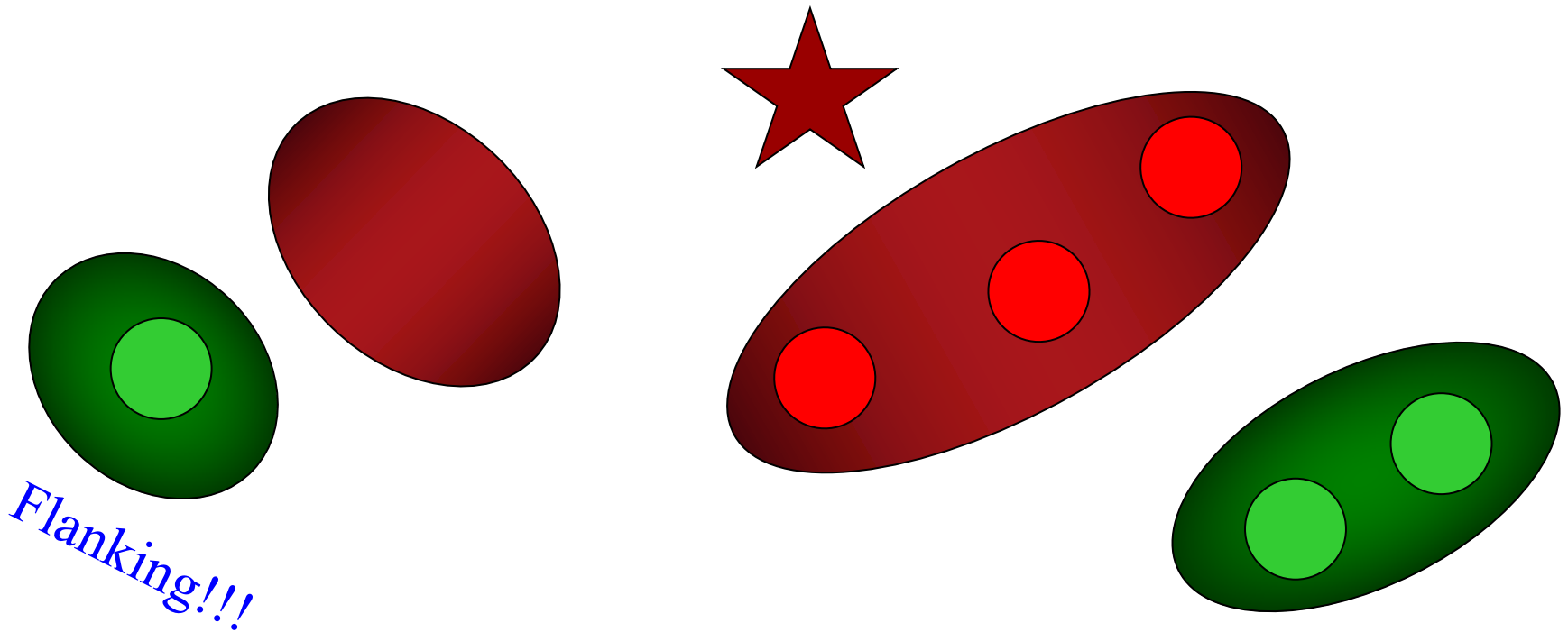
---



Slide courtesy of Dave Mark

# Protecting Special Units

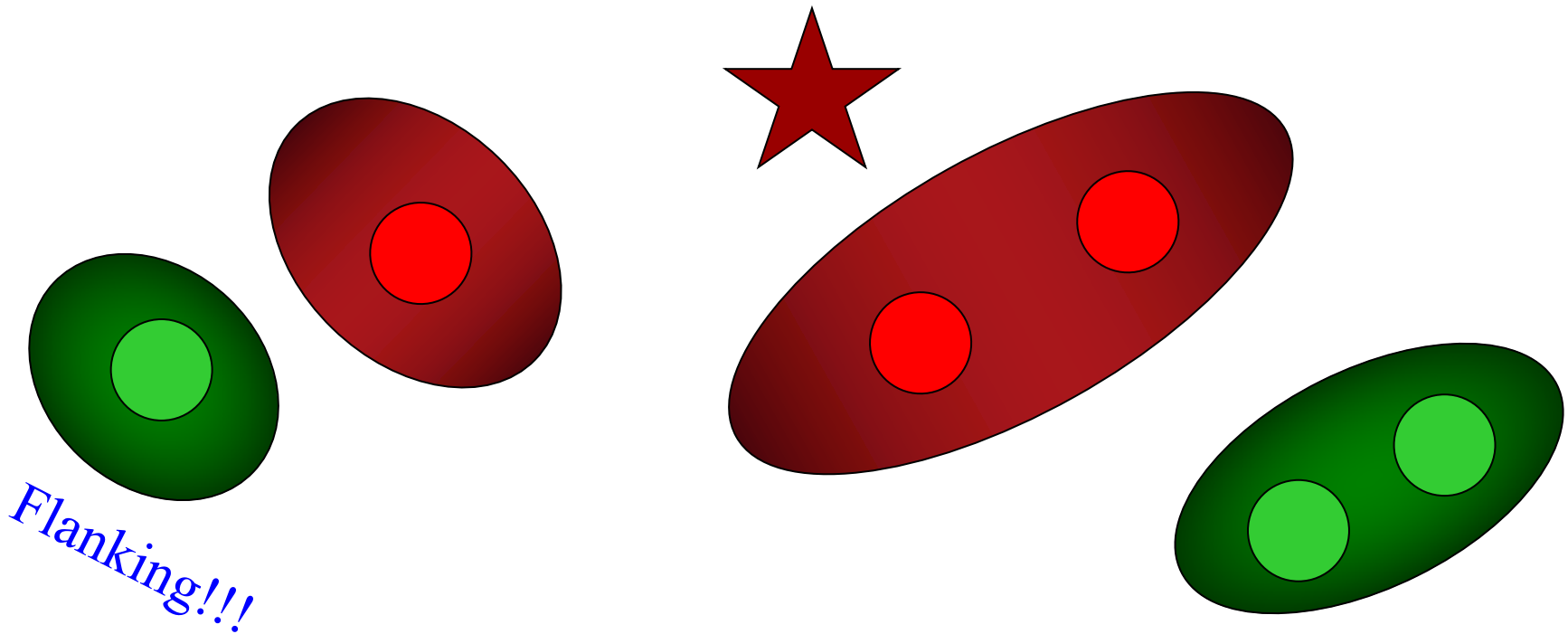
---



Slide courtesy of Dave Mark

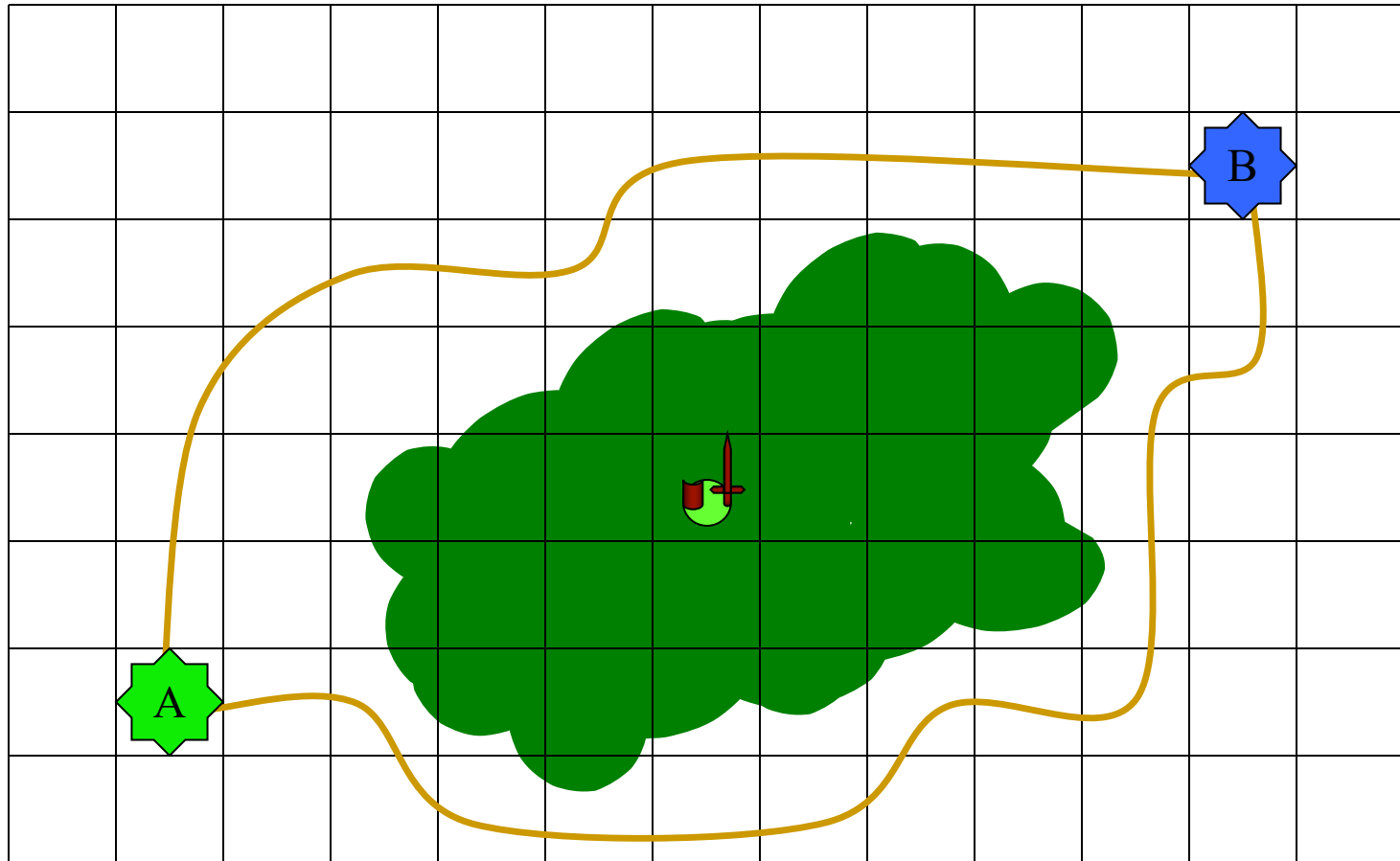
# Protecting Special Units

---



Slide courtesy of Dave Mark

# Inversion: Influence Maps



Slide courtesy of Dave Mark

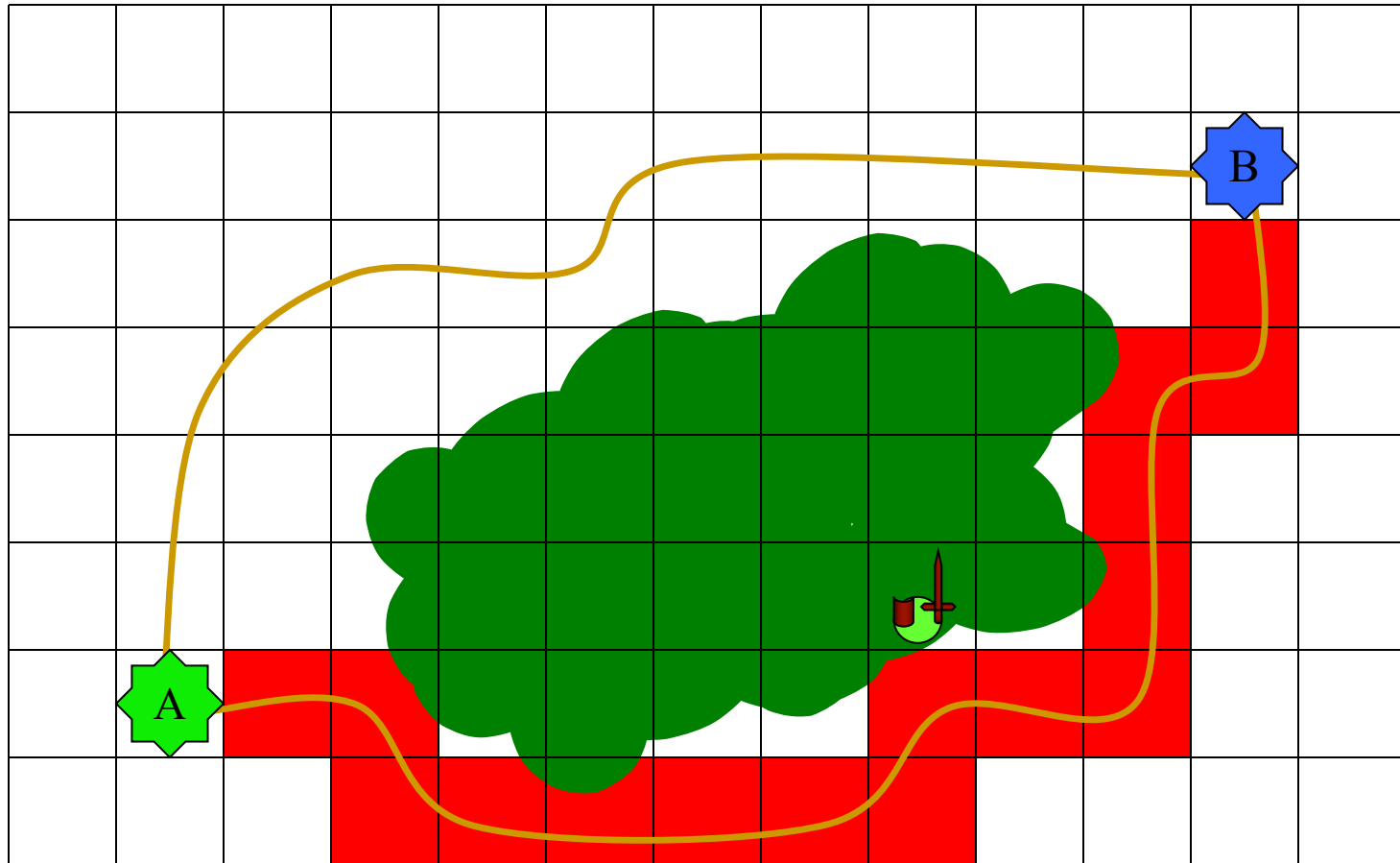






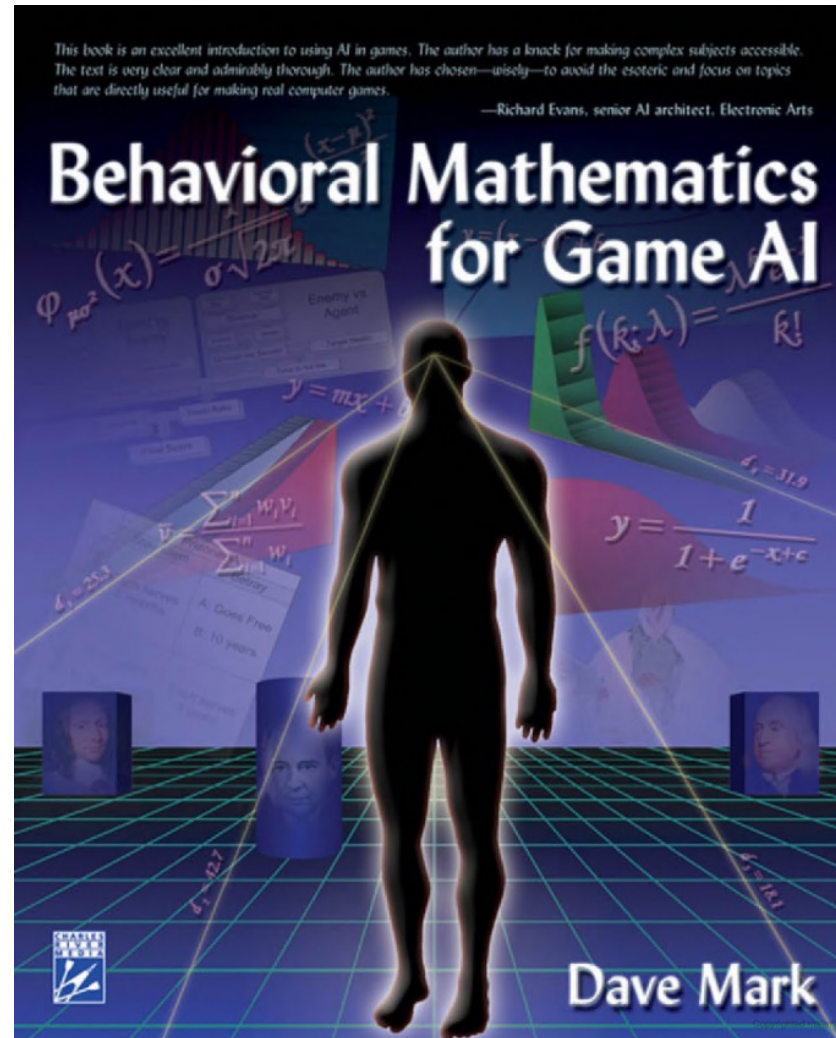


# Inversion: Influence Maps



Slide courtesy of Dave Mark

# Resource for Sense Optimization



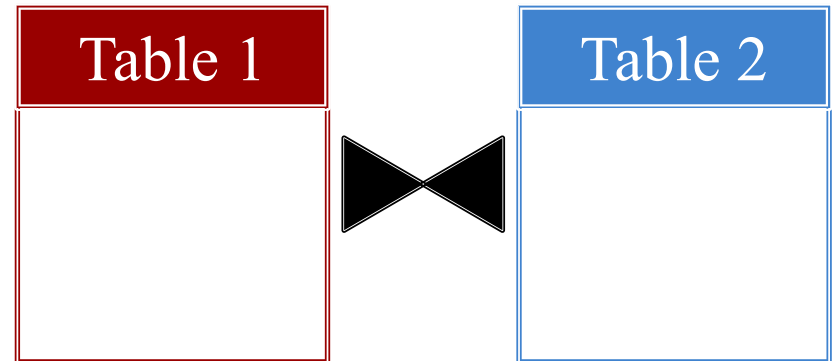
# A Final Observation

for each entity x:

for each entity y:

if x senses y:

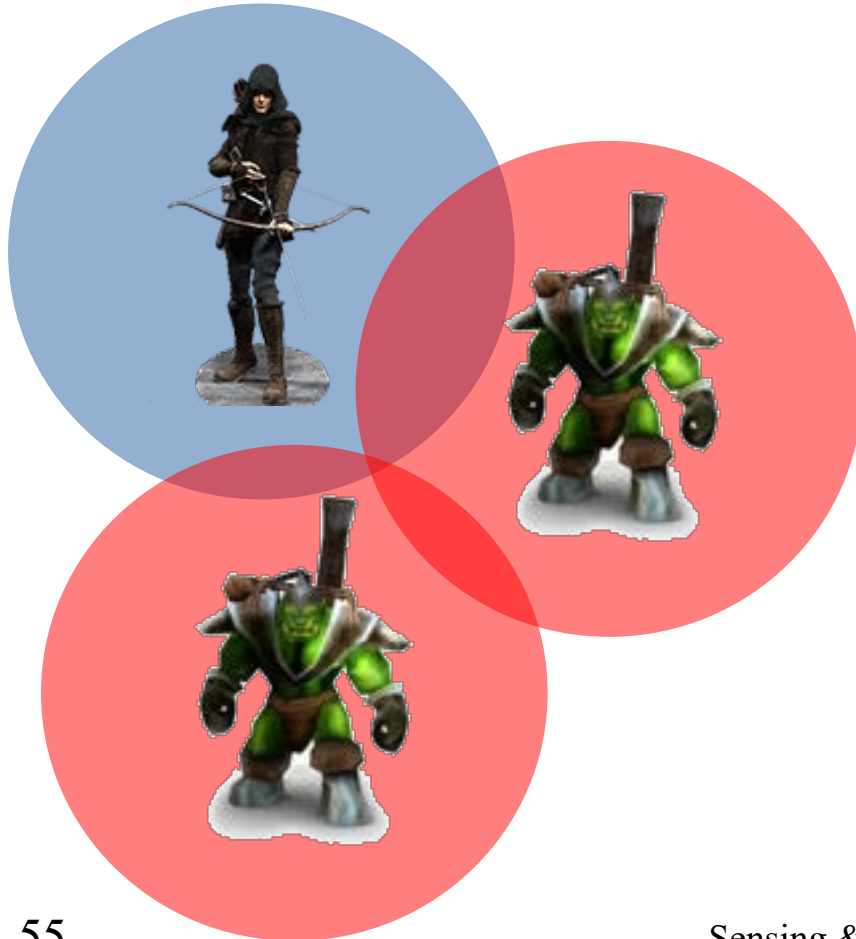
output event



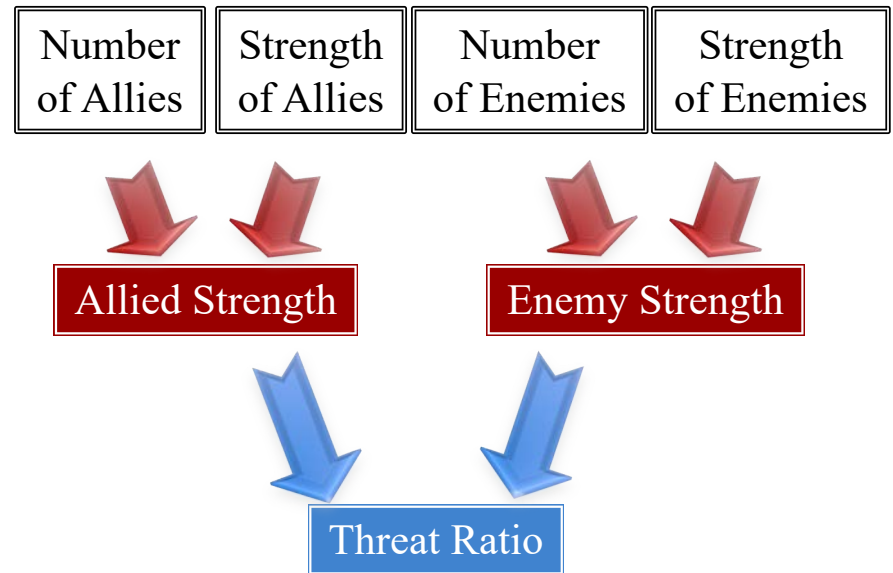
Sensing is a database **table join**

# These are all DB Optimizations

## Selection Pushing



## Aggregation Pushing







# And This is Where it All Began

---

- *Scaling Games to Epic Proportions (SIGMOD 2007)*
  - Allow designers to write code naively as  $O(n^2)$  loop
  - Use DB technology to optimize processing
- Requires that **behaviors**  $\ll$  **NPCs**
  - NPCs have different state, but use similar scripts
  - Each NPC is a tuple in database query
- **Challenge:** Making the language user-friendly
  - Requires major restrictions to language
  - Similar issue with Microsoft LINQ