

Lecture 20

Character Behavior

Classical AI vs. Game AI

- **Classical:** Design of *intelligent agents*
 - Perceives environment, maximizes its success
 - Established area of computer science
 - Subtopics: planning, machine learning
- **Game:** Design of *rational behavior*
 - Does not need to optimize (and often will not)
 - Often about “scripting” a personality
 - More akin to cognitive science

Take Away for This Lecture

- Review the **sense-think-act** cycle
 - How do we separate actions and thinking?
 - Delay the sensing problem to next time
- What is **rule-based** character AI?
 - How does it relate to sense-think-act?
 - What are its advantages and disadvantages?
- What **alternatives** are there to rule-based AI?
 - What is our motivation for using them?
 - How do they affect the game architecture?

Role of AI in Games

- **Autonomous Characters** (NPCs)
 - Mimics the “personality” of the character
 - May be opponent or support character
- **Strategic Opponents**
 - AI at the “player level”
 - Closest to classical AI
- **Character Dialog**
 - Intelligent commentary
 - Narrative management (e.g. Façade)

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Review: Sense-Think-Act

- **Sense:**

- Perceive the world
- Reading the game state
- **Example:** enemy near?

- **Think:**

- Choose an action
- Often merged with sense
- **Example:** fight or flee

- **Act:**

- Update the state
- Simple and fast
- **Example:** reduce health



S-T-A: Separation of Logic

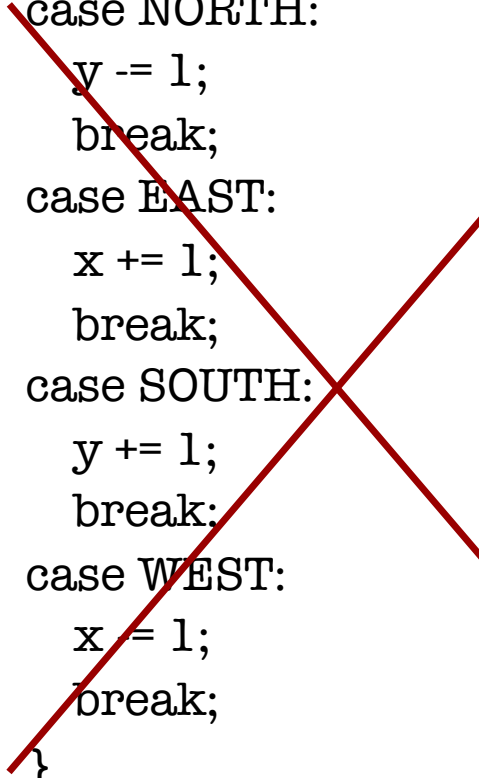
- **Loops** = sensing
 - Read other objects
 - *Aggregate* for thinking
 - **Example**: nearest enemy
- **Conditionals** = thinking
 - Use results of sensing
 - Switch between possibilities
 - **Example**: attack or flee
- **Assignments** = actions
 - Rarely need loops
 - Avoid conditionals

```
move(int direction) {  
    switch (direction) {  
        case NORTH:  
            y -= 1;  
            break;  
        case EAST:  
            x += 1;  
            break;  
        case SOUTH:  
            y += 1;  
            break;  
        case WEST:  
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```

S-T-A: Separation of Logic

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S-T-A: Separation of Logic

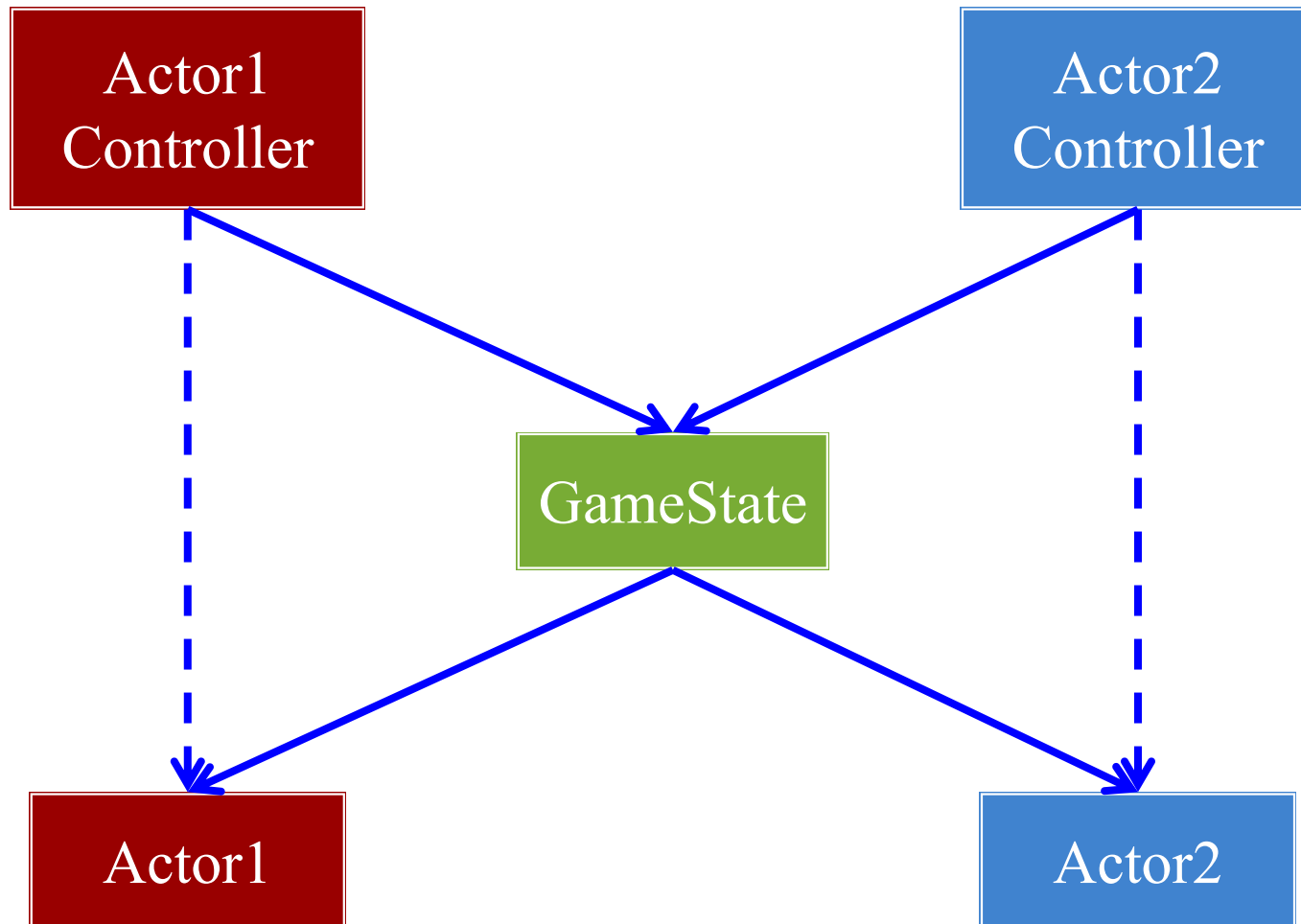
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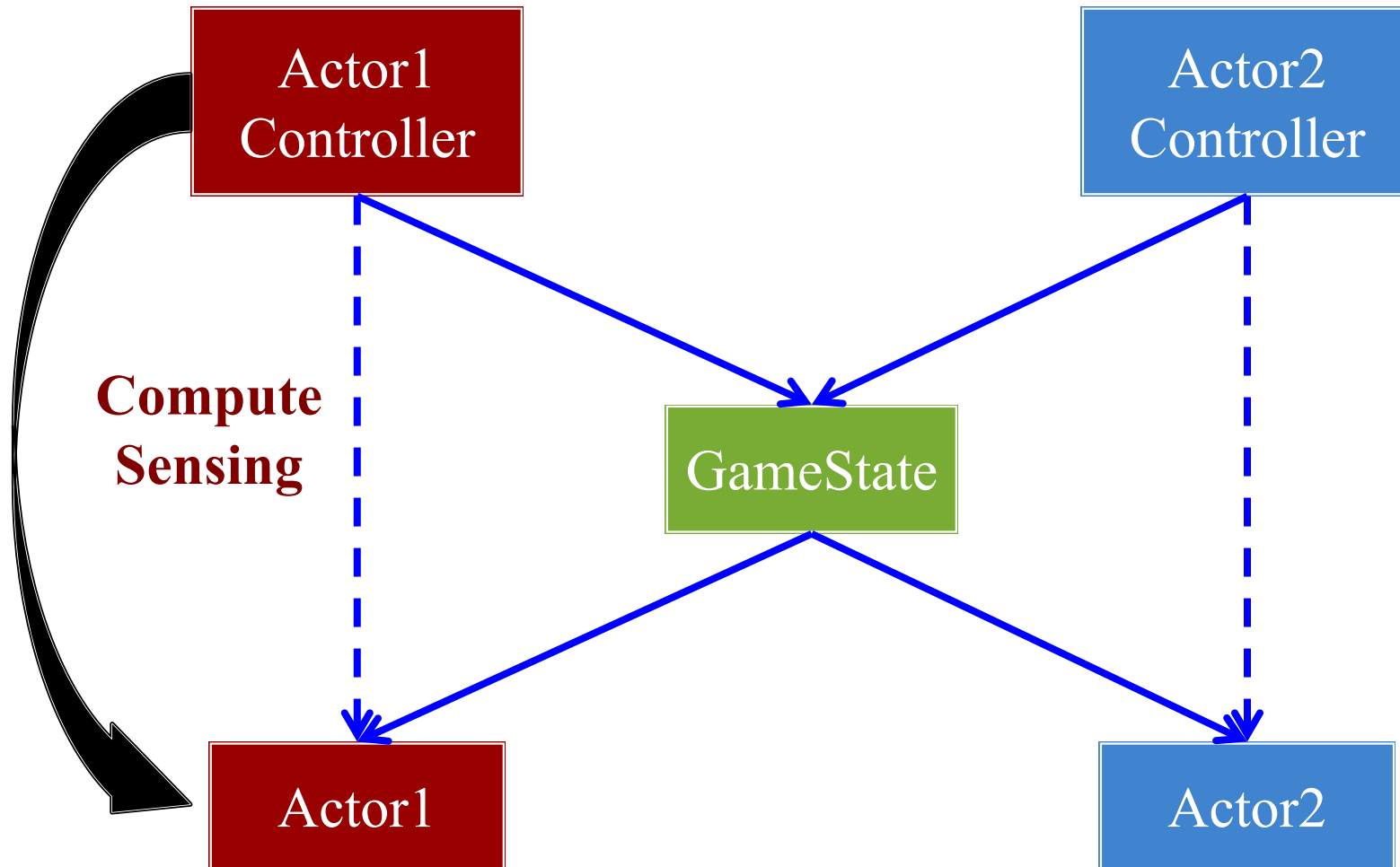
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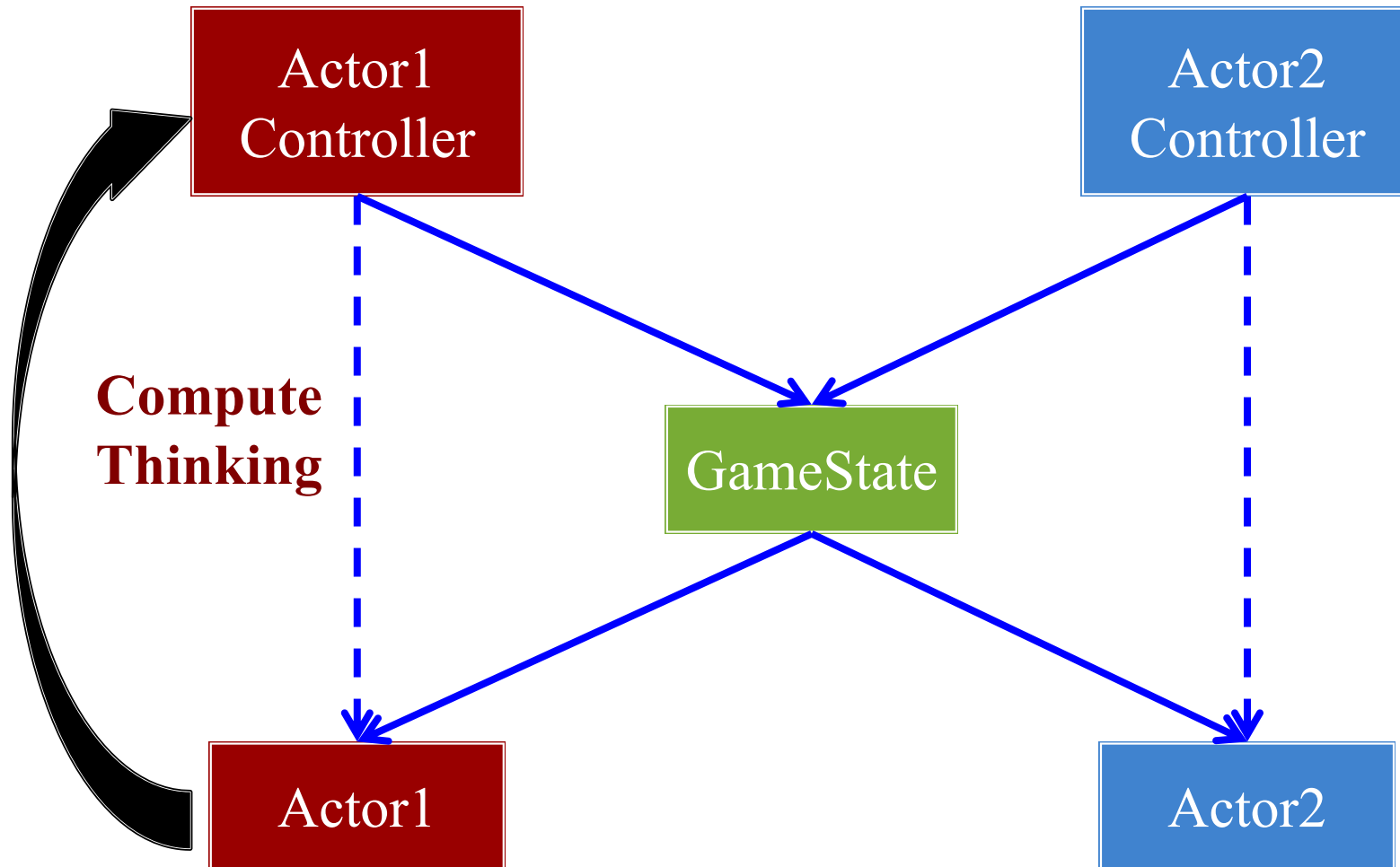
S-T-A: Reducing Dependencies



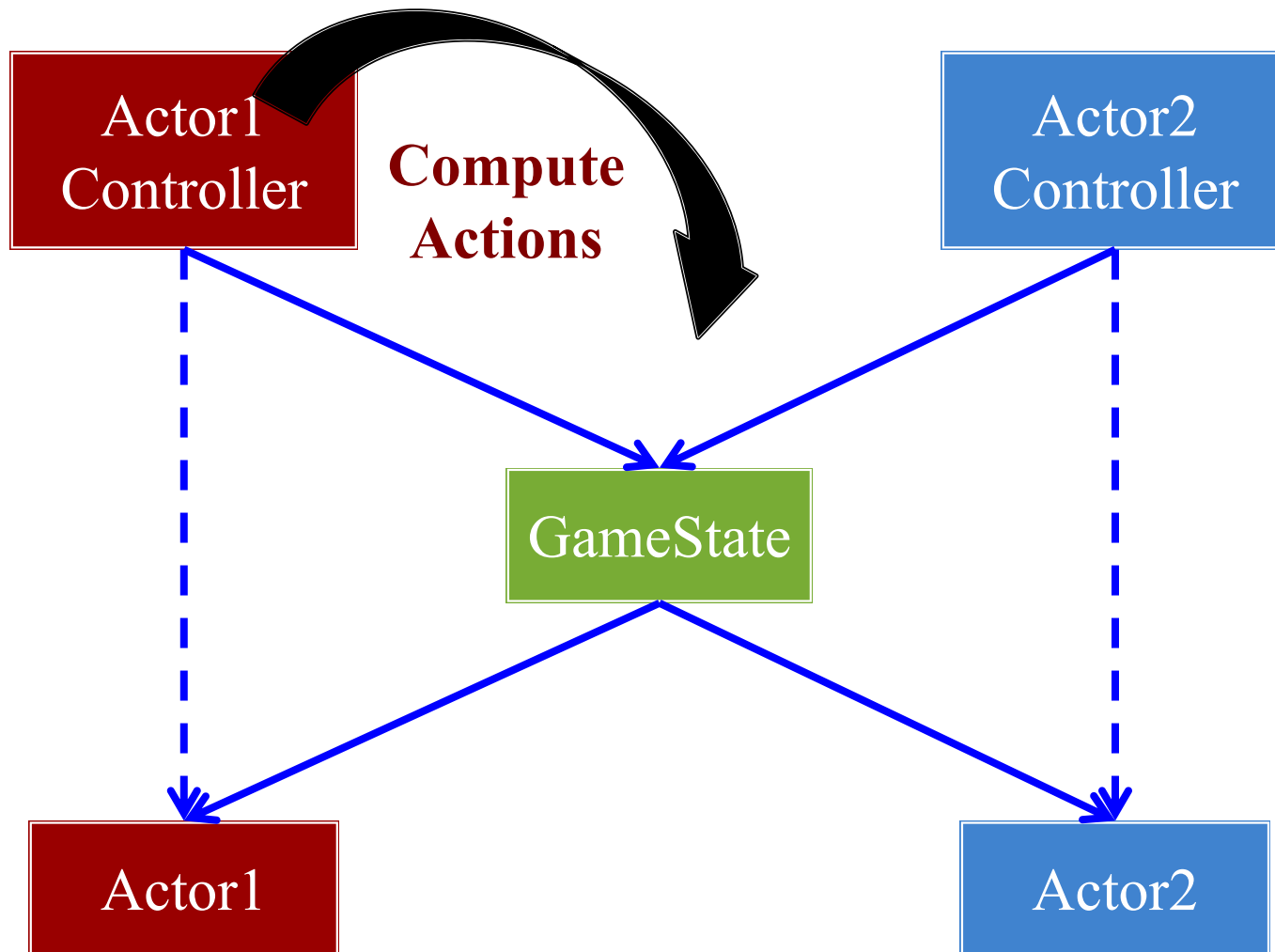
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S-T-A: Reducing Dependencies



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Actions: Short and Simple

- Mainly use **assignments**
 - Avoid loops, conditionals
 - Similar to getters/setters
 - Complex code in *thinking*
- Helps with **serializability**
 - Record and undo actions
- Helps with **networking**
 - Keep doing last action
 - Recall: *dead reckoning*

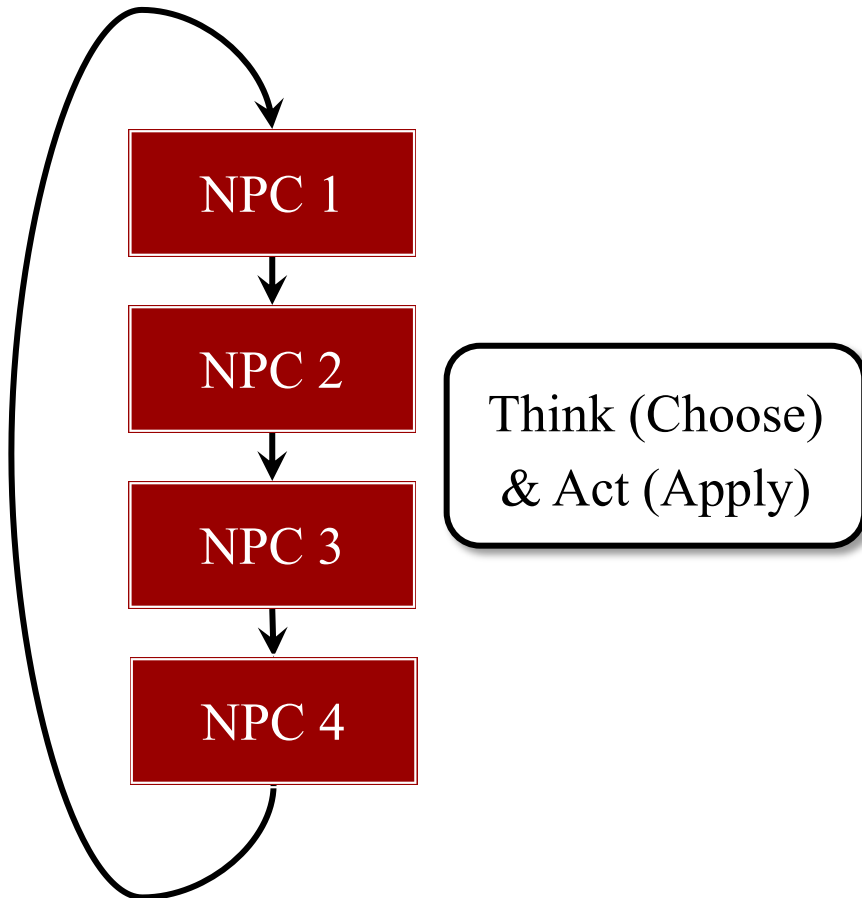
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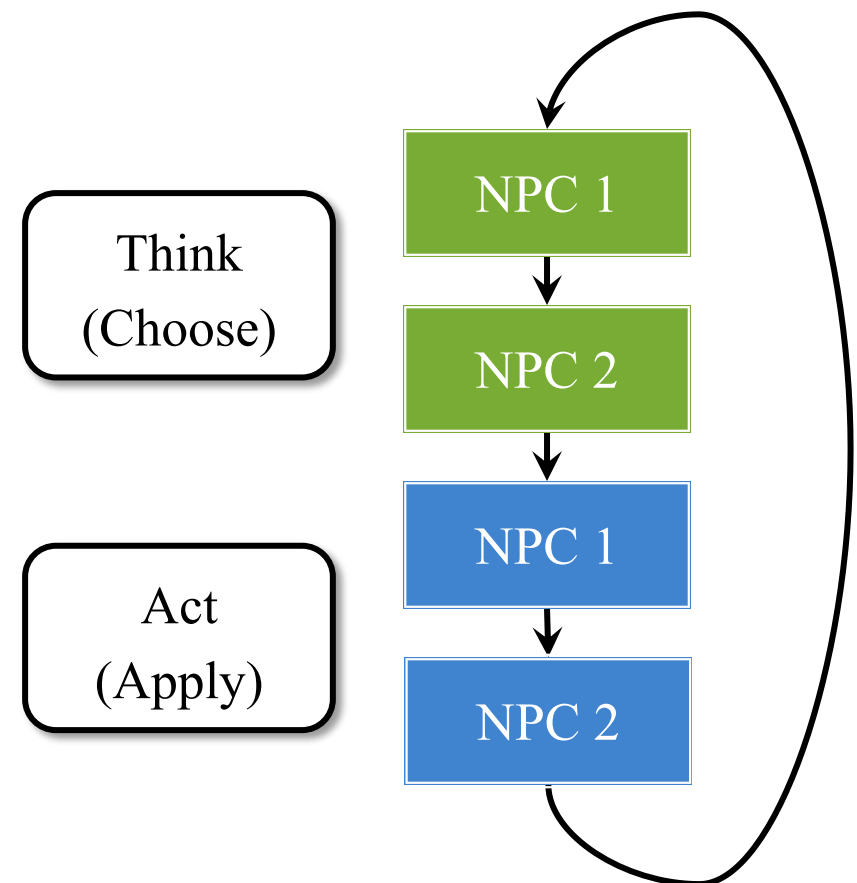
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Delaying Actions

Sequential Actions are Bad



Choose Action; Apply Later



Thinking: Primary Challenge

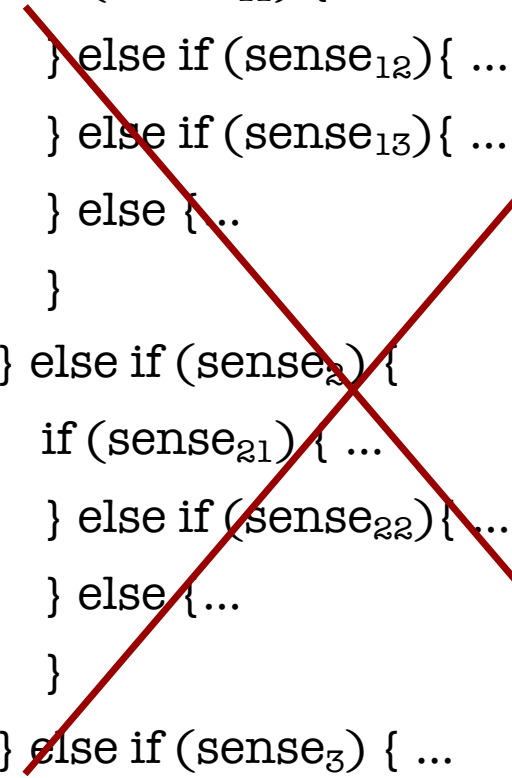
- A mess of conditionals
 - “Spaghetti” code
 - Difficult to modify
- Abstraction requirements:
 - Easy to visualize models
 - Mirror “cognitive thought”
- Want to separate talent
 - **Sensing:** Programmers
 - **Thinking:** *Designers*
 - **Actions:** Programmers

```
if (sense1) {  
    if (sense11) { ...  
    } else if (sense12) { ...  
    } else if (sense13) { ...  
    } else { ...  
}  
} else if (sense2) {  
    if (sense21) { ...  
    } else if (sense22) { ...  
    } else { ...  
}  
} else if (sense3) { ...  
}
```

Thinking: Primary Challenge

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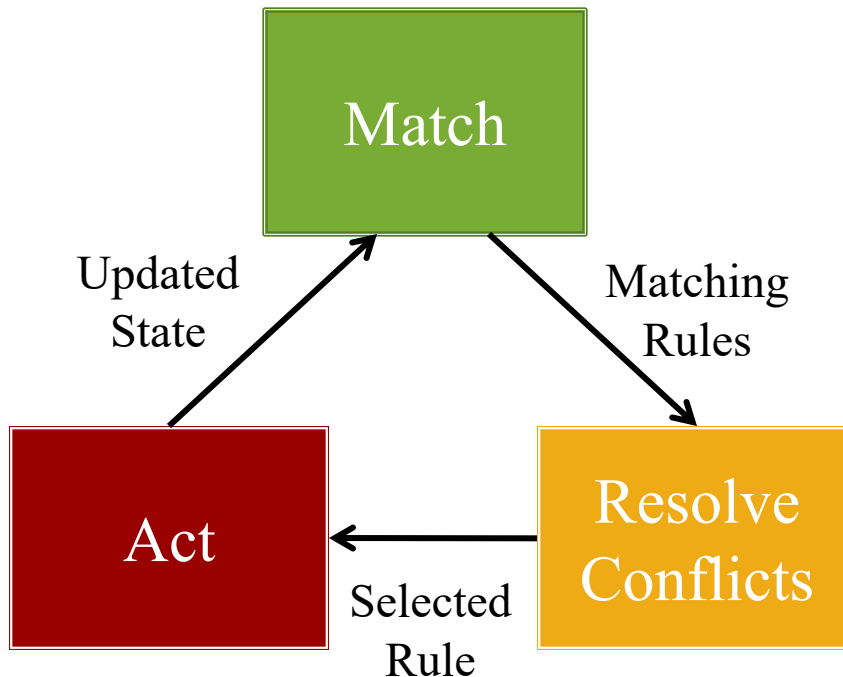
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```



Rule-Based AI

If X is true, Then do Y

Three-Step Process



- **Match**
 - For each rule, check **if**
 - Return *all* matches
- **Resolve**
 - Can only use one rule
 - Use metarule to pick one
- **Act**
 - Do **then**-part

Rule-Based AI

If ***X*** is true, Then do ***Y***

- **Thinking**: Providing a list of several rules
 - But what happens if there is more than one rule?
 - Which rule do we choose?

Rule-Based AI

Sensing

Acting

If **X** is true, Then do **Y**

- **Thinking**: Providing a list of several rules
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Simplicity of Rule-Based AI



Conflict Resolution

- Often **resolve by order**
 - Each rule has a priority
 - Higher priorities go first
 - “Flattening” conditionals
- **Problems:**
 - Predictable
Same events = same rules
 - Total order
Sometimes no preference
 - Performance
On average, go far down list

R_1 : if event₁ then act₁

R_2 : if event₂ then act₂

R_3 : if event₃ then act₃

R_4 : if event₄ then act₄

R_5 : if event₅ then act₅

R_6 : if event₆ then act₆

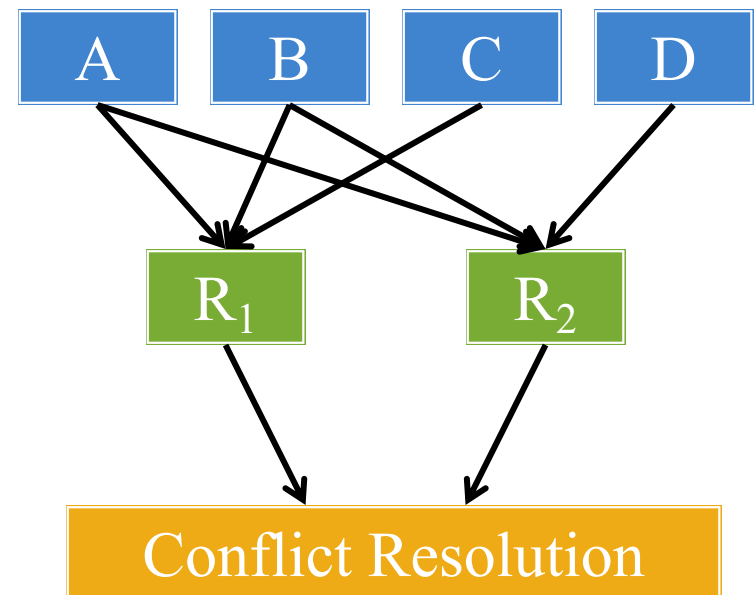
R_7 : if event₇ then act₇

Conflict Resolution

- **Specificity:**
 - Rule w/ most “components”
- **Random:**
 - Select randomly from list
 - May “weight” probabilities
- **Refractory Inhibition:**
 - Do not repeat recent rule
 - Can combine with ordering
- **Data Recency:**
 - Select most recent update

R_1 : if A, B, C, then

R_2 : if A, B, D, then



Impulses

- Correspond to certain events
 - **Global**: not tied to NPC
 - Must also have duration
- Used to **reorder** rules
 - Event makes rule important
 - Temporarily up the priority
 - Restore when event is over
- Preferred conflict resolution
 - Simple but flexible
 - Used in *Halo 3* AI.

R_1 : if event₁ then act₁

R_2 : if event₂ then act₂

R_3 : if event₃ then act₃

R_4 : if event₄ then act₄

R_5 : if event₅ then act₅

R_6 : if event₆ then act₆

R_7 : if event₇ then act₇

Impulses

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R_3 : if event₃ then act₃

R_4 : if event₄ then act₄

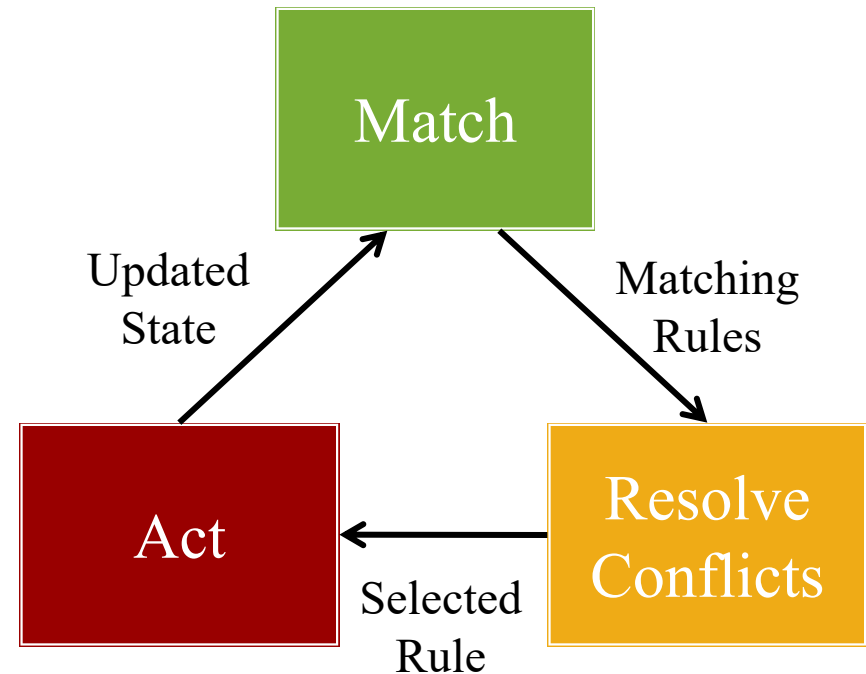
R_6 : if event₆ then act₆

R_7 : if event₇ then act₇



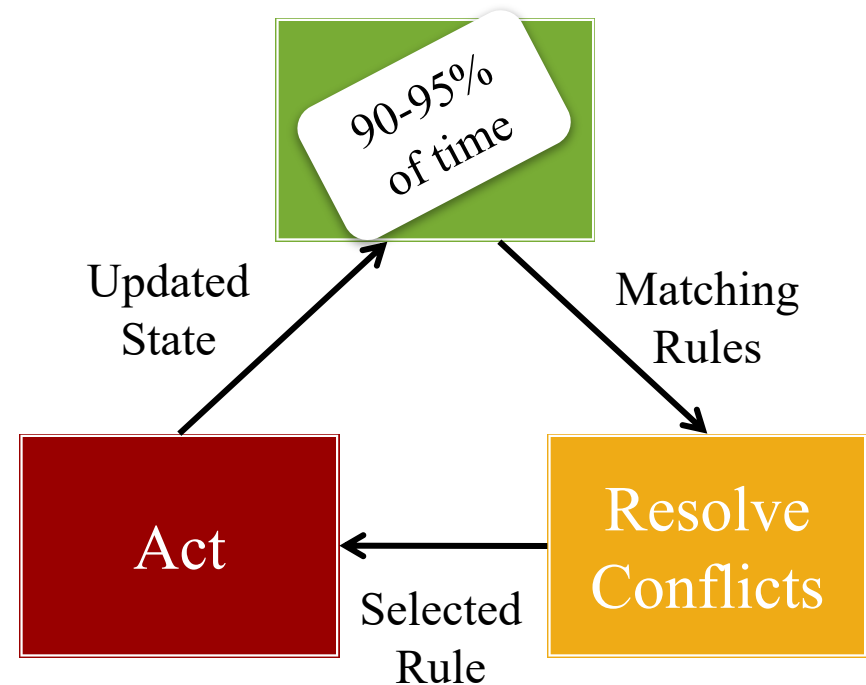
Rule-Based AI: Performance

- Matching = **sensing**
 - If-part is expensive
 - Test *every* condition
 - Many unmatched rules
- Improving performance
 - Optimize sensing (make if-part cheap)
 - Limit number of rules
 - Other solutions?
- Most games limit rules
 - Reason for *state machines*



Rule-Based AI: Performance

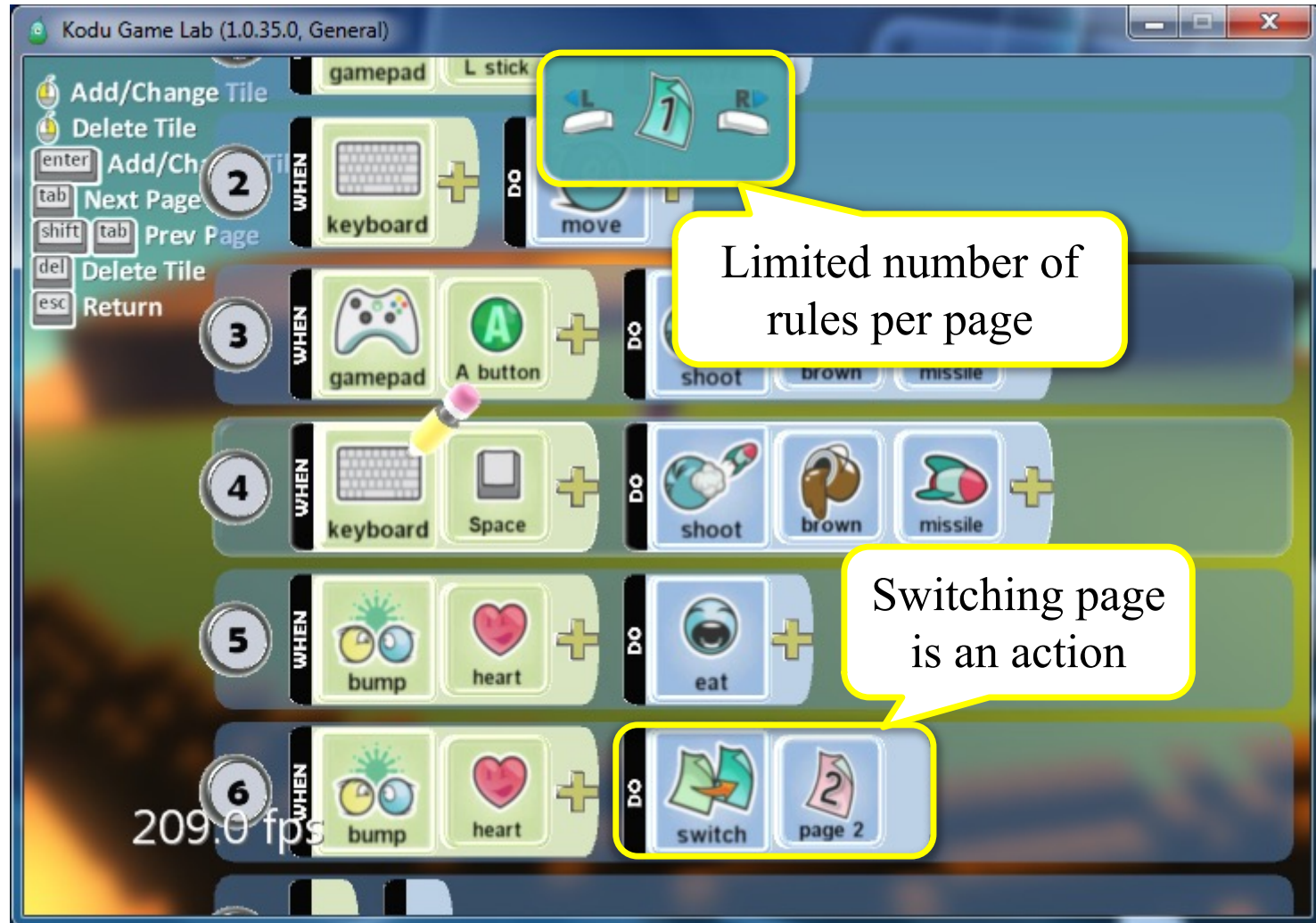
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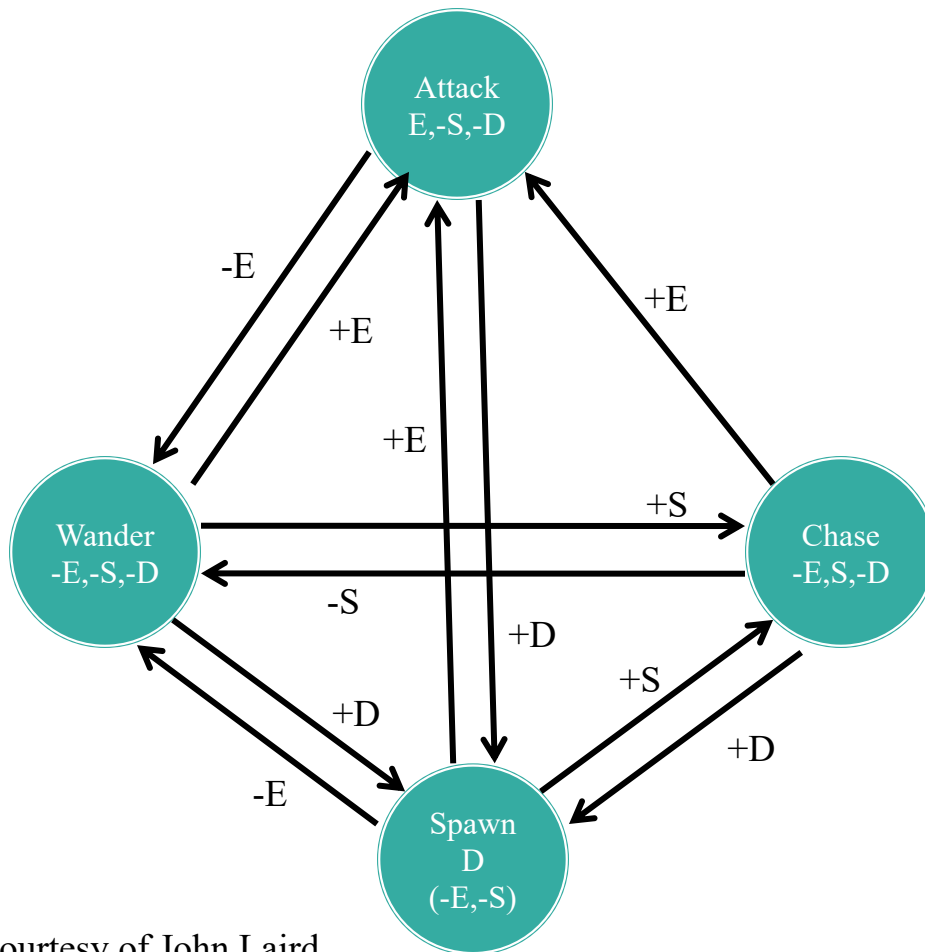
Making the Rules Manageable



Making the Rules Manageable



Finite State Machines



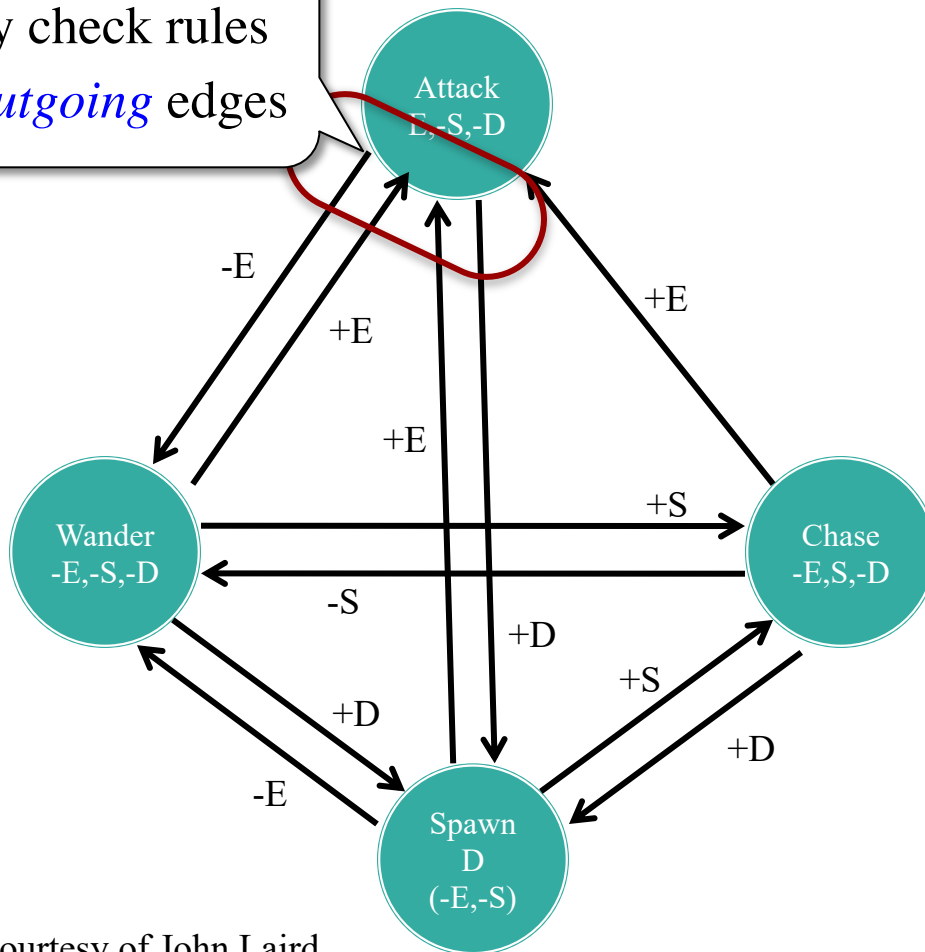
Events

- **E**=Enemy Seen
- **S**=Sound Heard
- **D**=Die

Slide courtesy of John Laird

Finite State Machines

Only check rules
for *outgoing* edges



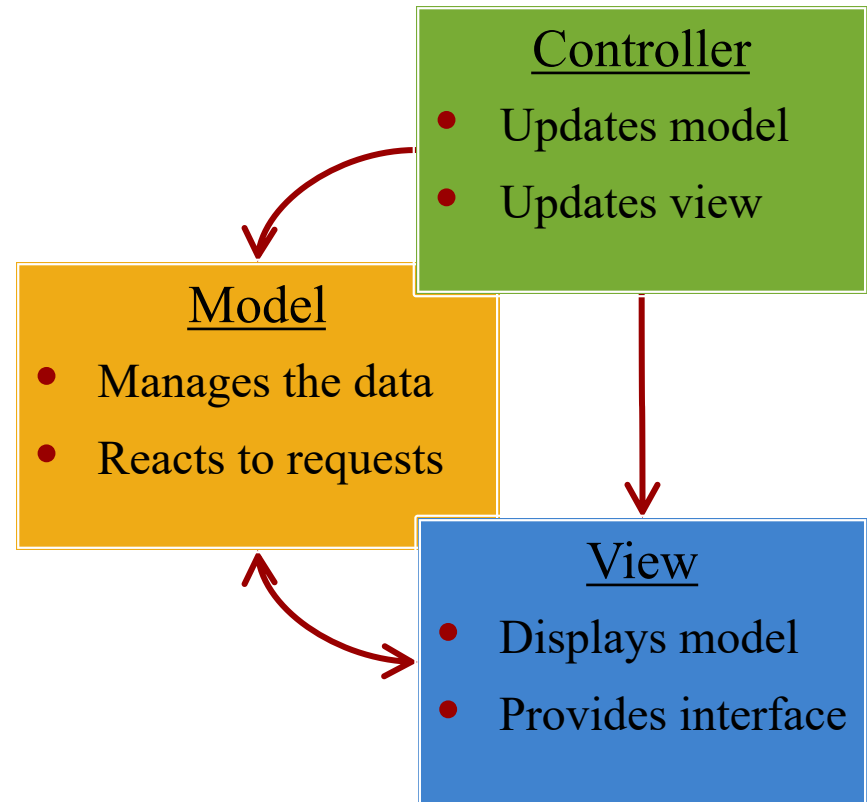
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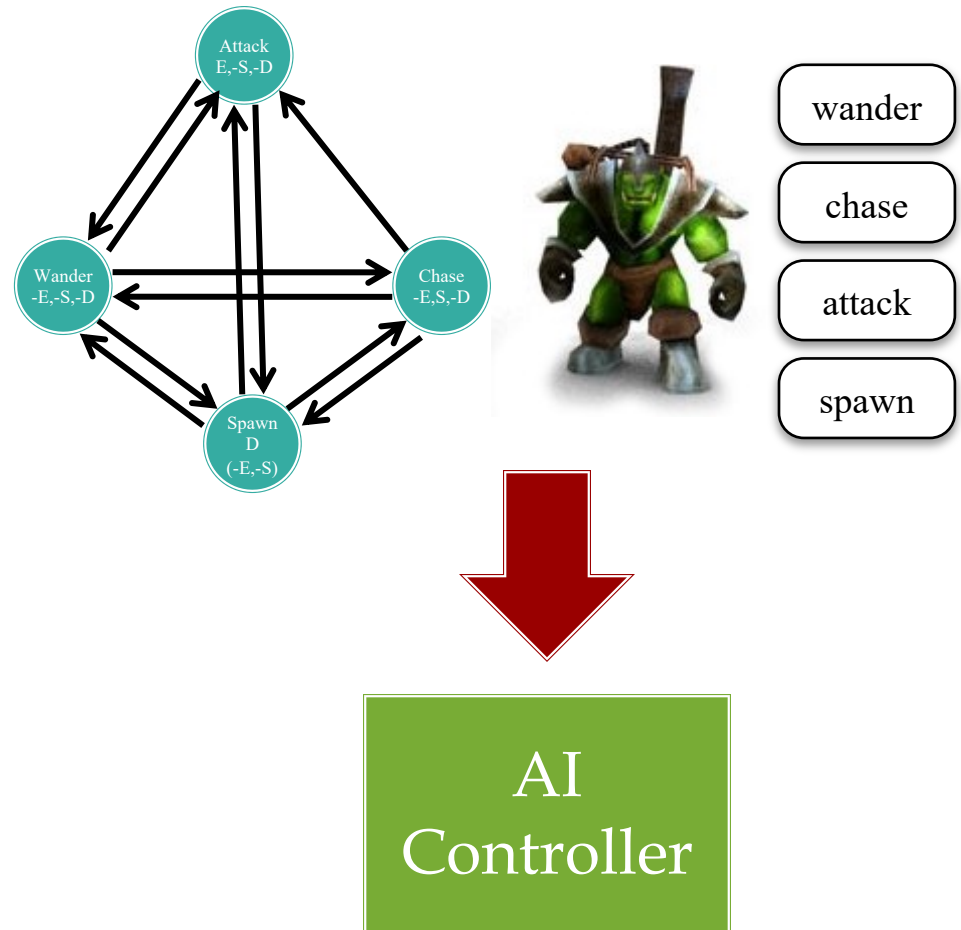
Implementation: Model-View-Controller

- Games have **thin** models
 - Methods = get/set/update
 - Controllers are heavyweight
- AI is a **controller**
 - Uniform process over NPCs
- But behavior is *personal*
 - Diff. NPCs = diff. behavior
 - Do not want unique code
- What can we do?
 - Data-Driven Design



Implementation: Model-View-Controller

- **Actions** go in the model
 - Lightweight updates
 - Specific to model or role
- Controller is framework for general **sensing, thinking**
 - Standard FSM engine
 - Or FSM alternatives (later)
- **Process** stored in a model
 - Represent thinking as *graph*
 - Controller processes graph



An Aside: Animations

Landing Animation



- AI may need many actions
 - Run, jump, duck, slide
 - Fire weapons, cast spells
 - Fidget while idling

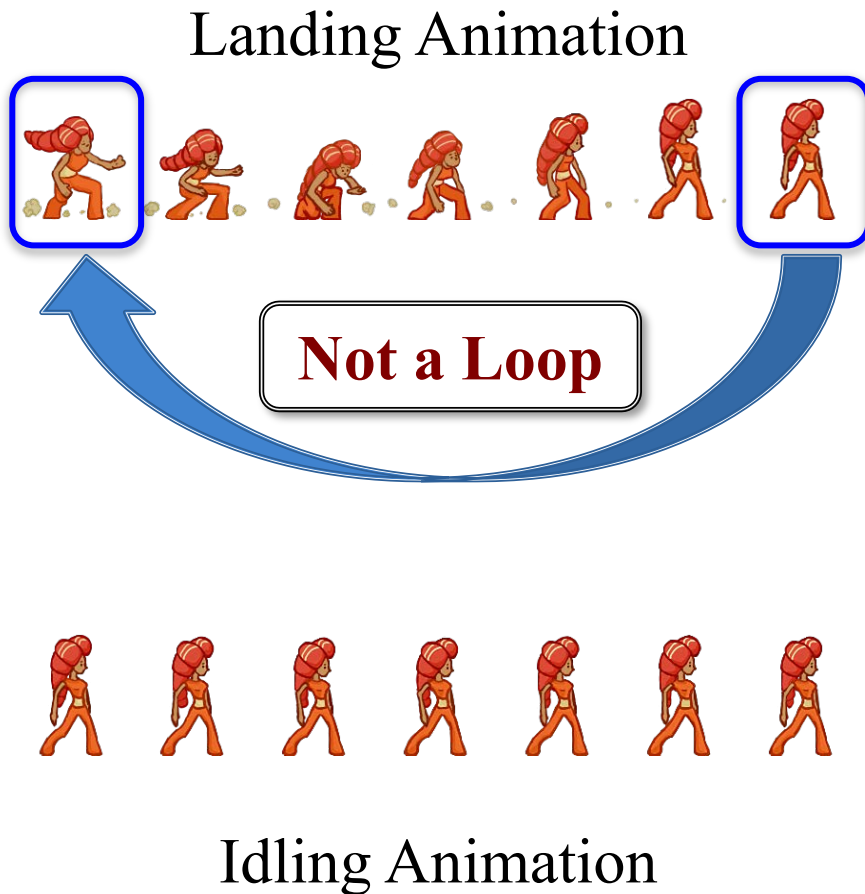
- Want animations for all
 - Is loop appropriate for each?
 - How do we transition?



Idling Animation

- **Idea:** shared boundaries
 - End of loop = start of another
 - Treat like advancing a frame

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An Aside: Animations

Landing Animation



Transition

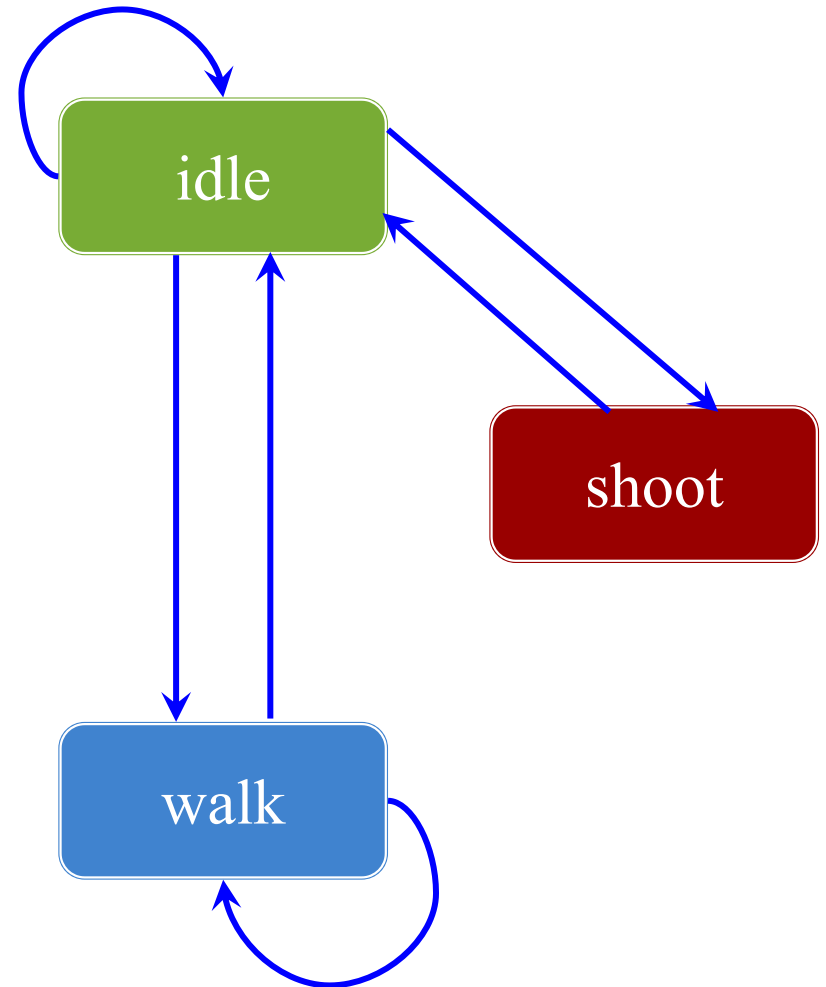


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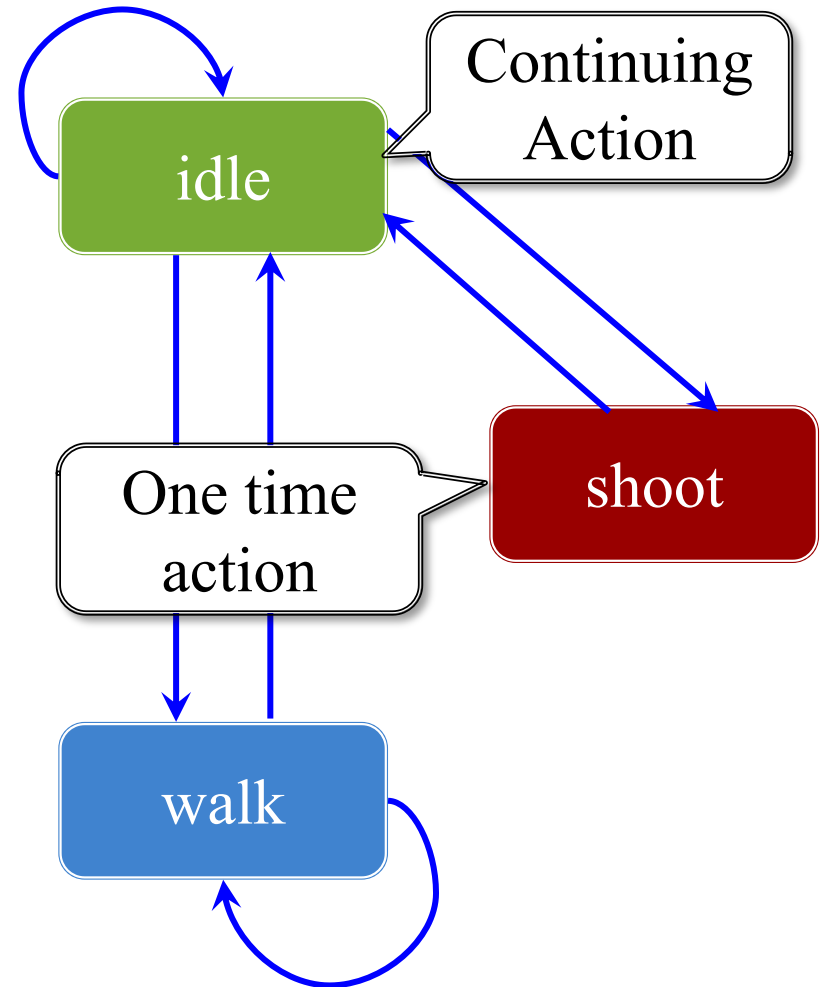
Animation and State Machines

- **Idea:** Each sequence a state
 - Do sequence while in state
 - Transition when at end
 - Only loop if loop in graph
- A graph edge means...
 - Boundaries match up
 - Transition is allowable
- Similar to data driven AI
 - Created by the designer
 - Implemented by programmer
 - Modern engines have tools

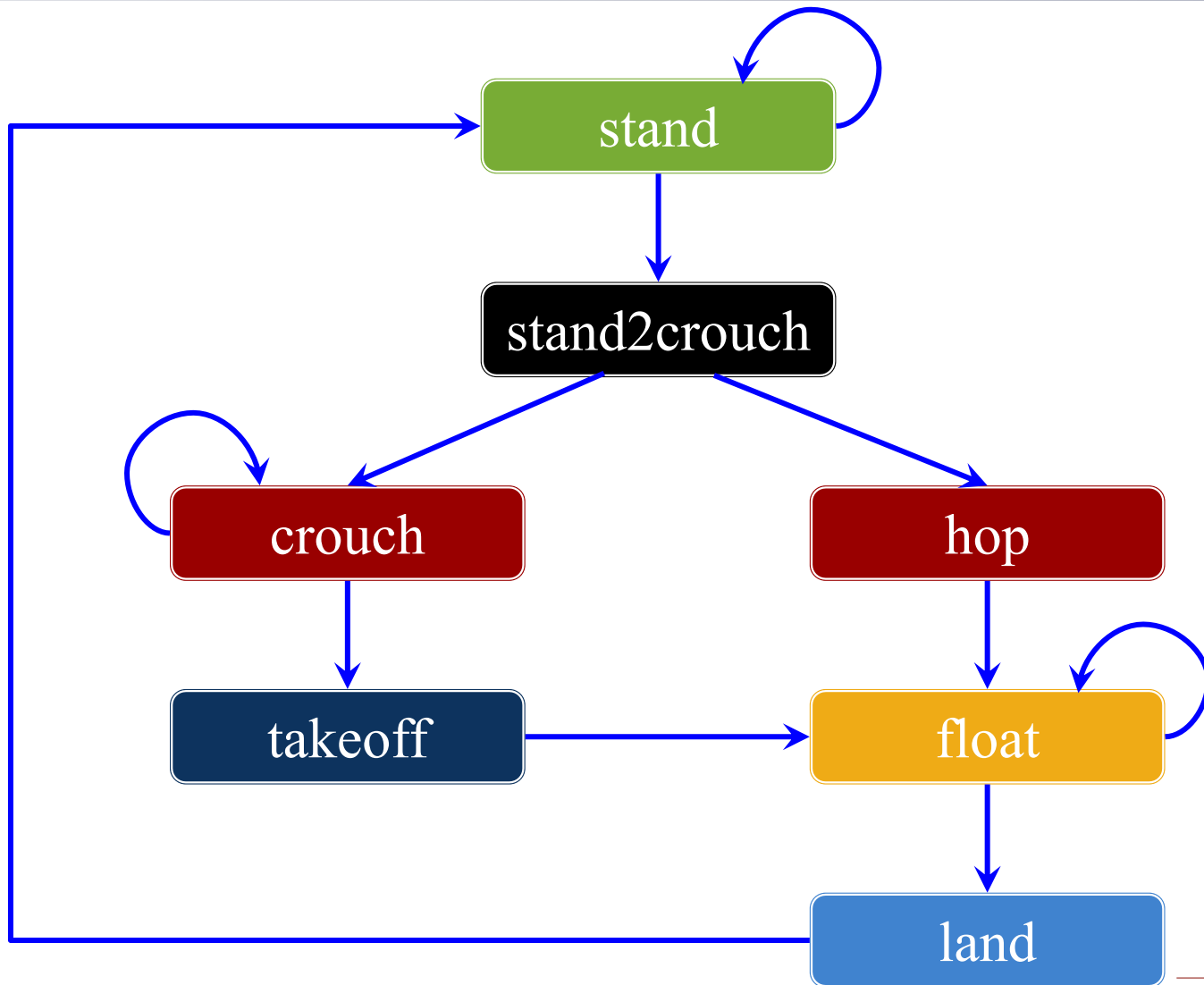


Animation and State Machines

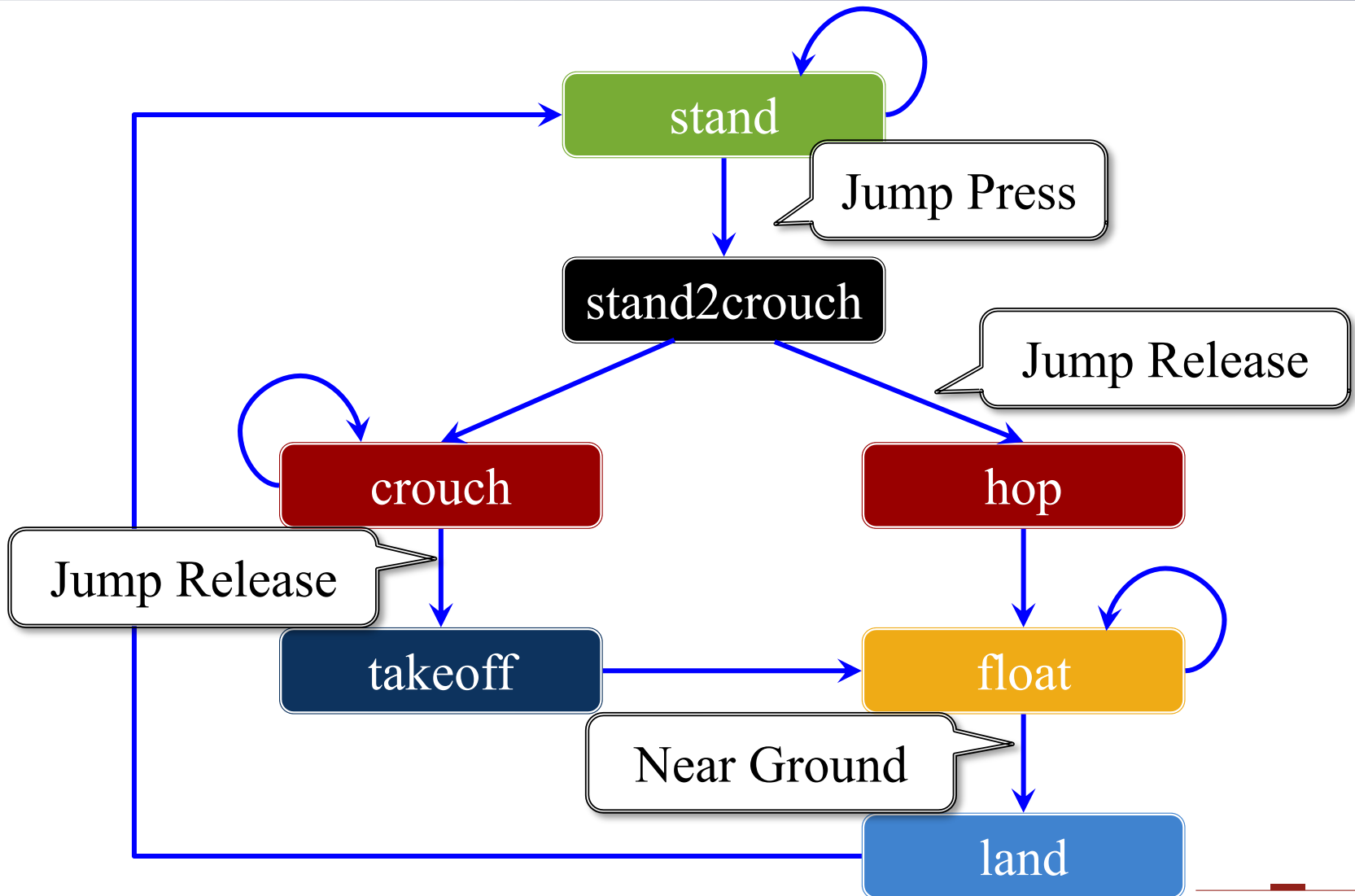
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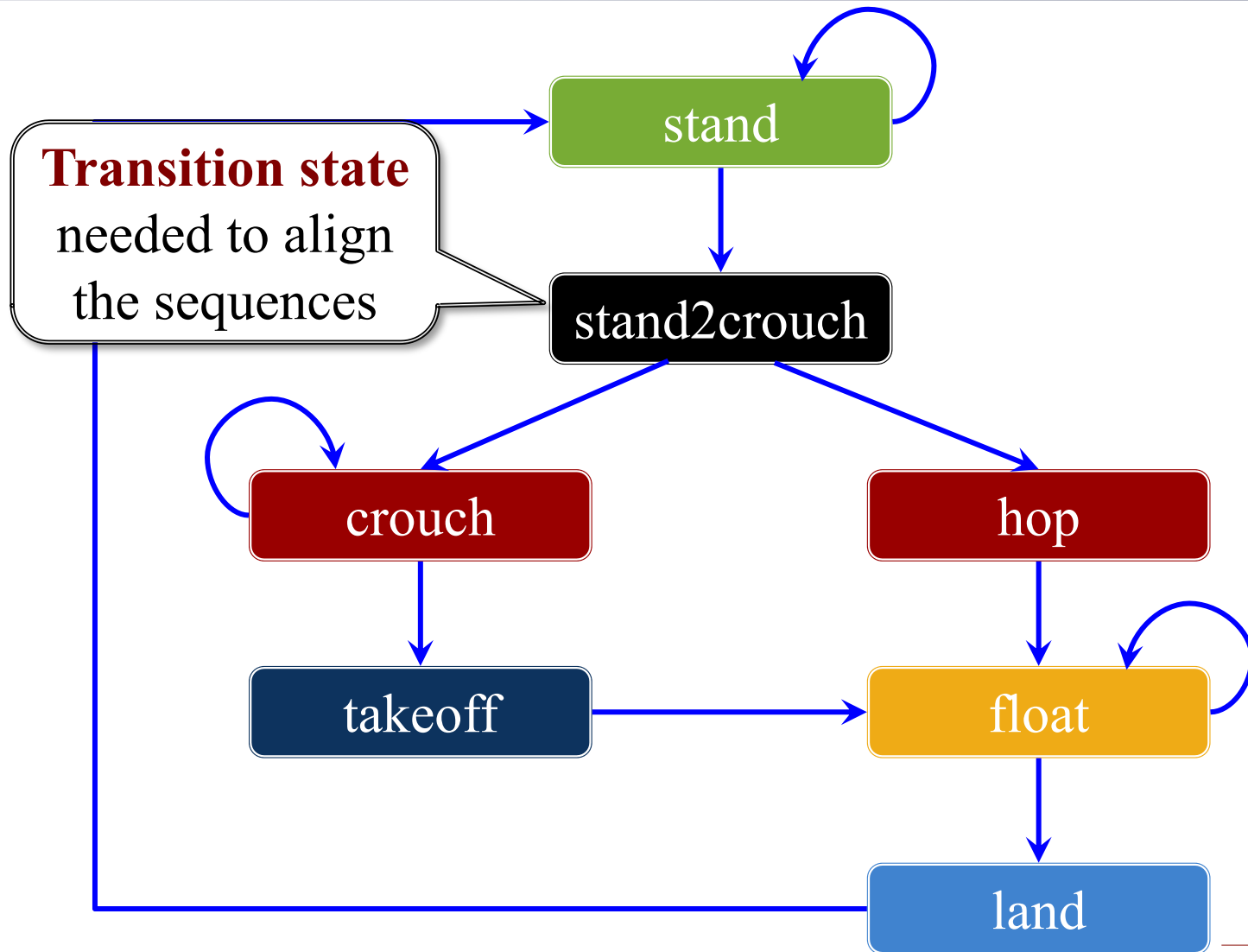
Complex Example: Jumping



Complex Example: Jumping



Complex Example: Jumping



LibGDX Interfaces

StateMachine<E>

- Attached to an entity
 - Set the entity in constructor
 - New entity, new state machine
- Must implement methods
 - `update()`
 - `changeState(State<A> state)`
 - `revertToPreviousState()`
 - `getCurrentState()`
 - `isInState(State<A> state)`
- `DefaultStateMachine` provided

State<E>

- Not attached to an entity
 - StateMachine sets state
 - StateMachine passes entity
- Must implement methods
 - `enter(E entity)`
When machine enters state
 - `exit(E entity)`
When machine enters state
 - `update(E entity)`
When machine stays in state

LibGDX Interfaces

StateMachine<E>

- Attached to an entity

Updates current state.
Does not transition!

- Must implement methods
 - `update()`
 - `changeState(State<A> state)`
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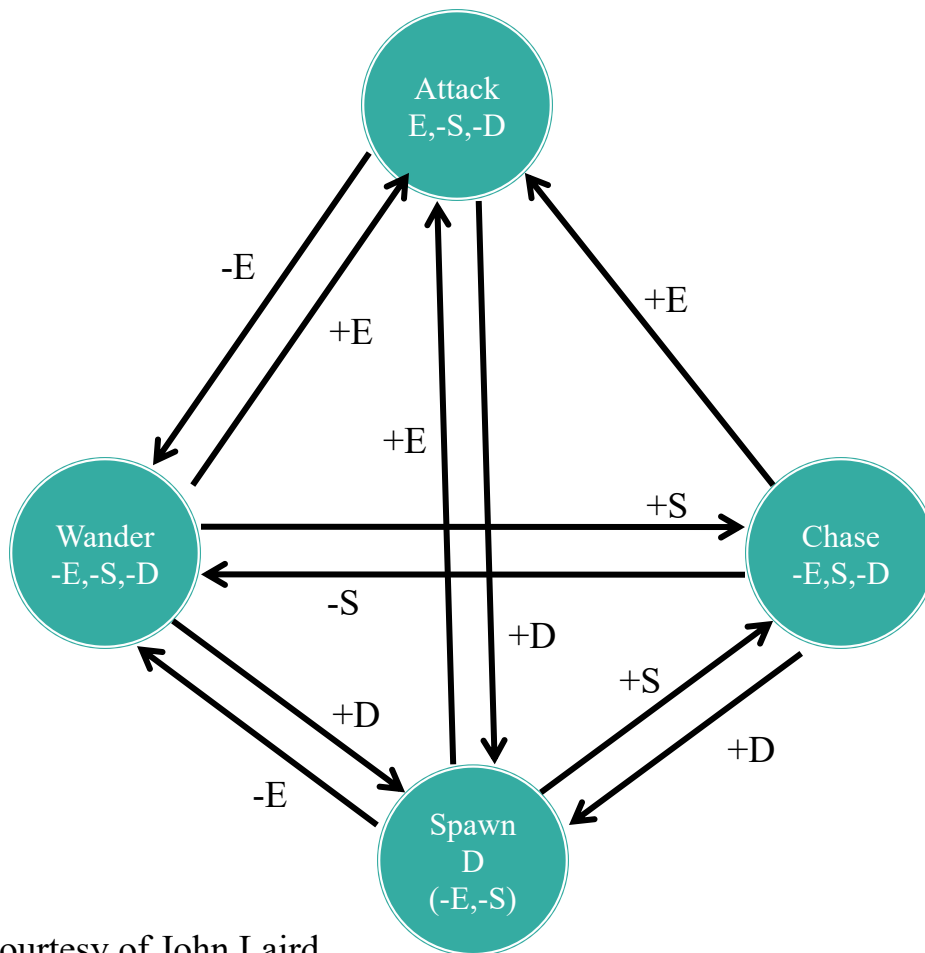
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- `StateMachine` sets state
- `StateMachine` passes entity
- Implement methods

Transition logic
external to the
state machine.

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When machine enters state
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When machine enters state
- `update(E entity)`
When machine stays in state

Problems with FSMs



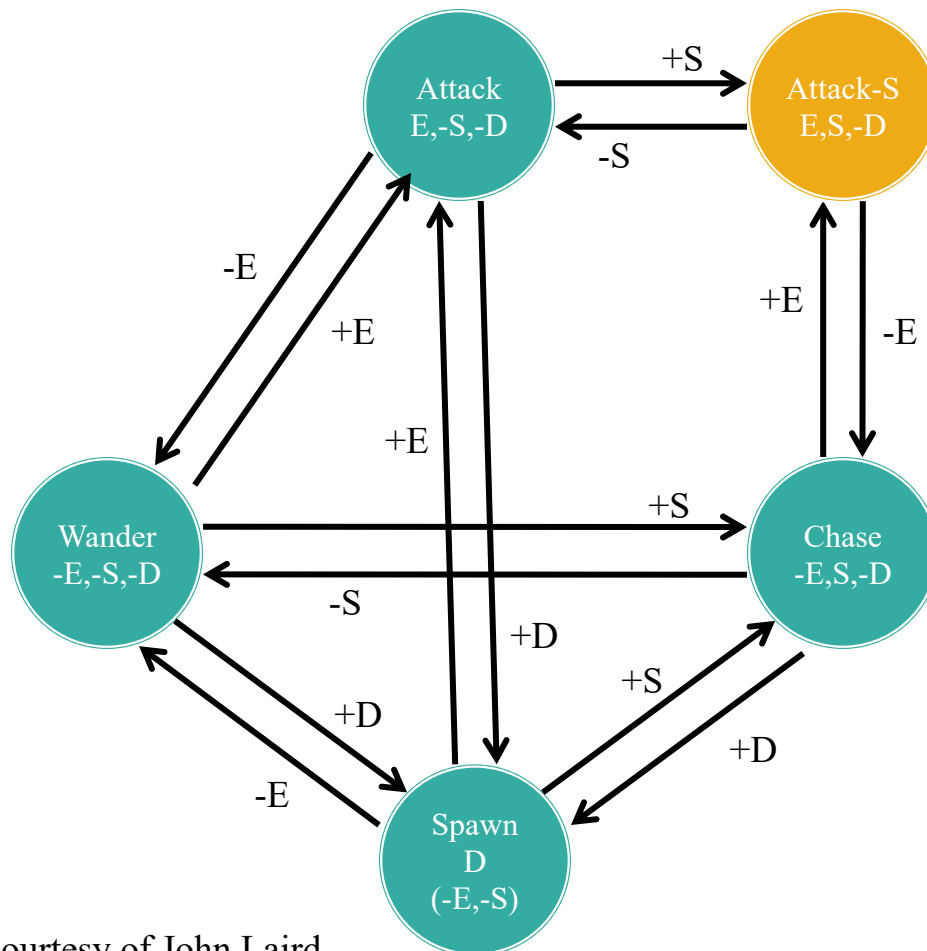
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No edge from **Attack** to **Chase**

Slide courtesy of John Laird

Problems with FSMs



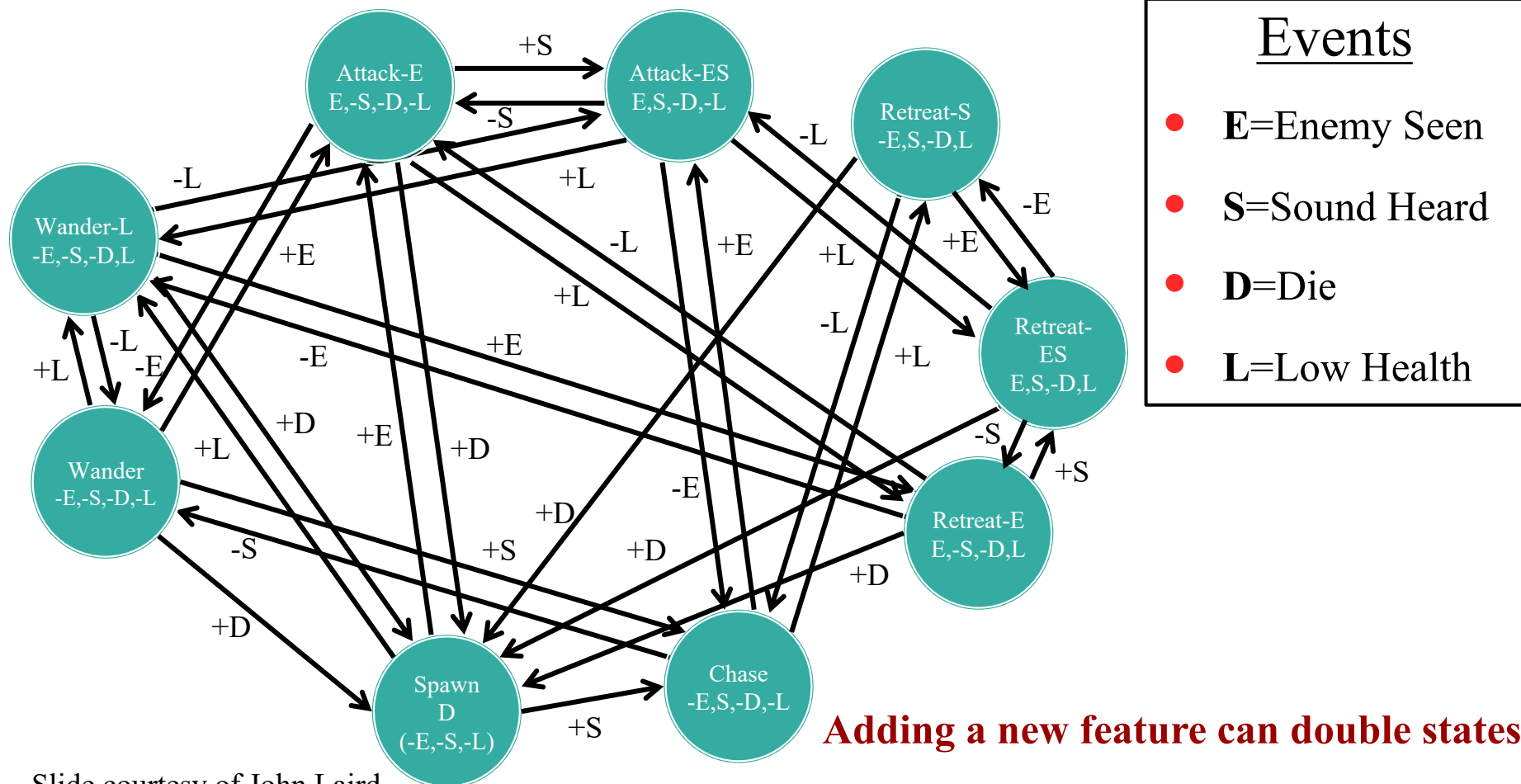
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Requires a *redundant* state

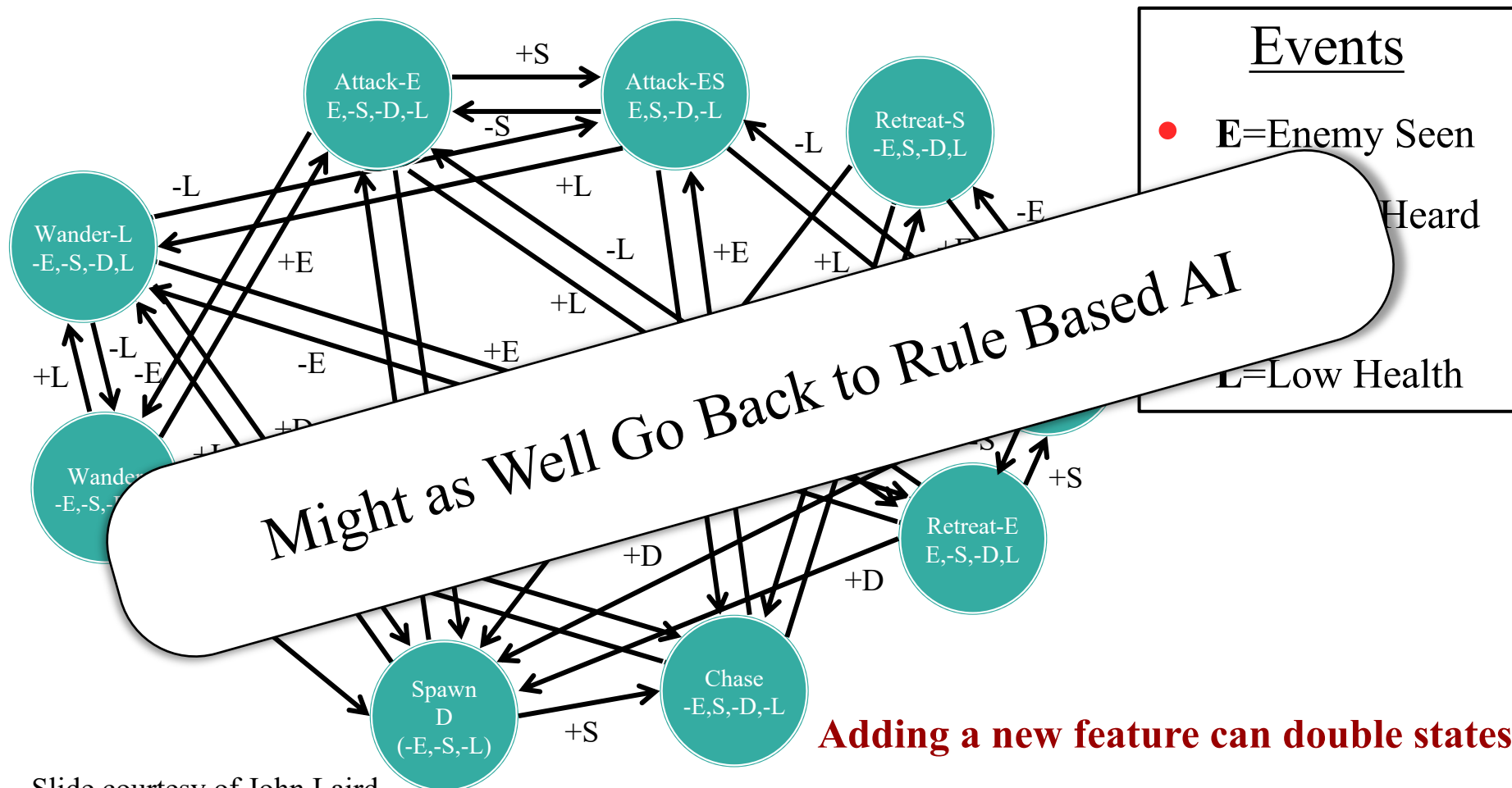
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Problems with FSMs



Slide courtesy of John Laird

Problems with FSMs



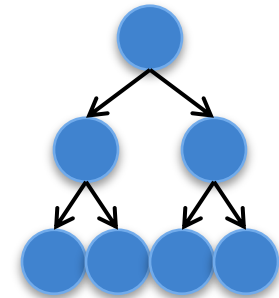
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An Observation

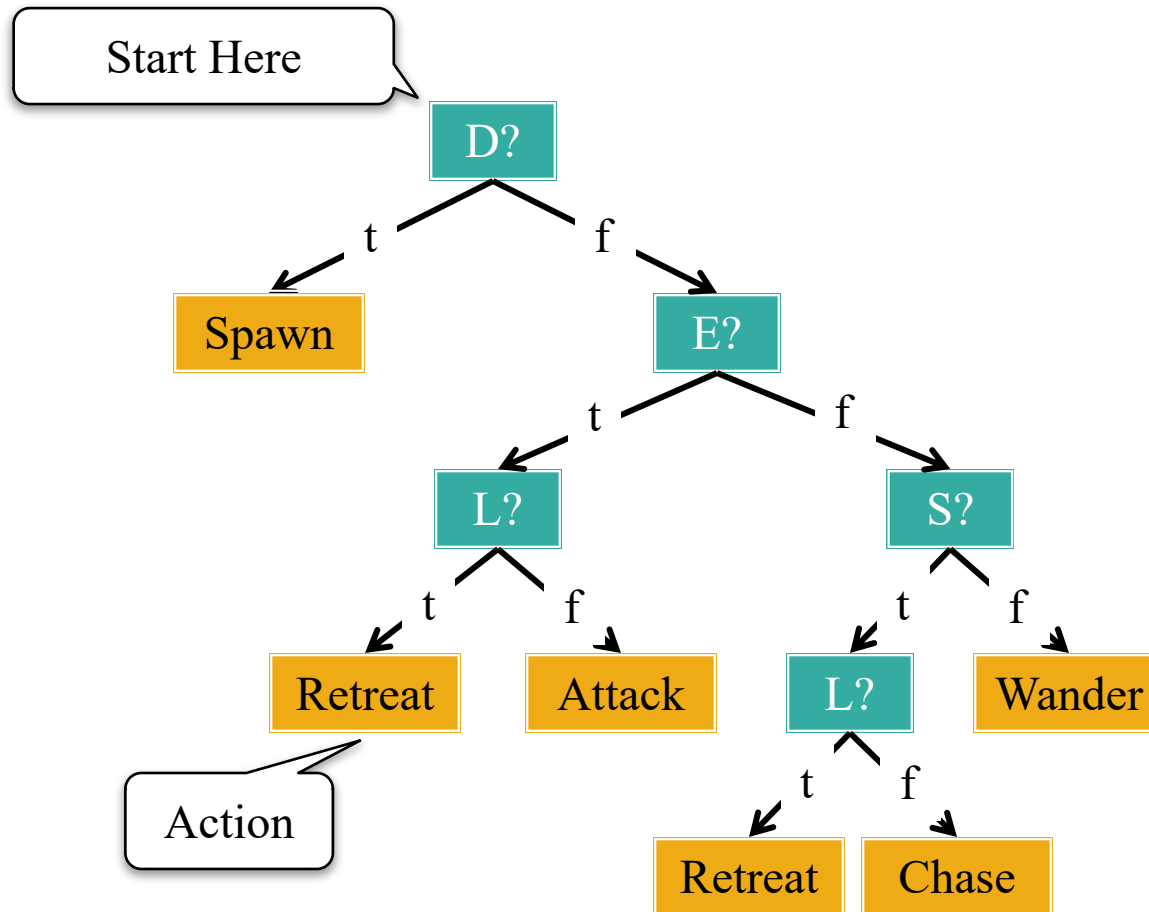
- Each state has a set of **global attributes**
 - Different attributes may have same actions
 - Reason for redundant behavior
- Currently just cared about attributes
 - Not really using the full power of a FSM
 - Why don't we just check attributes directly?
- Attribute-based selection: *decision trees*

Decision Trees

- Thinking **encoded as a tree**
 - Attributes = tree nodes
 - Left = true, right = false
 - Actions = leaves (reach from the root)
- Classify by **descending** from root to a leaf
 - Start with the test at the root
 - Descend the branch according to the test
 - Repeat until a leaf is reached

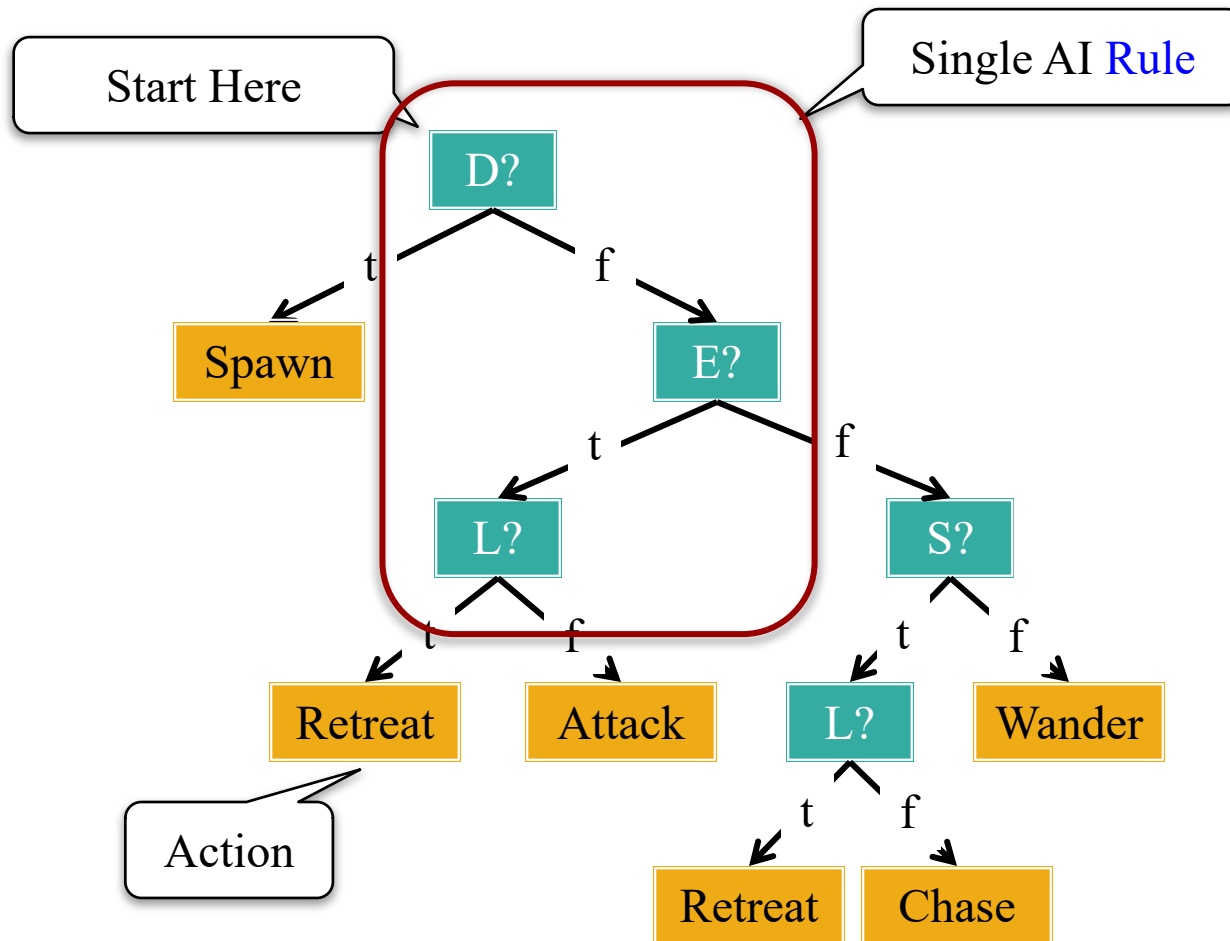


Decision Tree Example



Slide courtesy of John Laird

Decision Tree Example

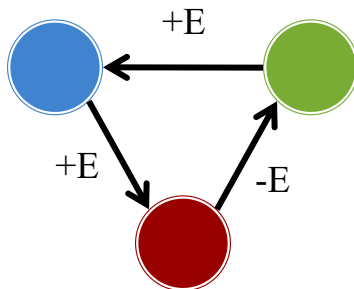


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FSMs vs. Decision Trees

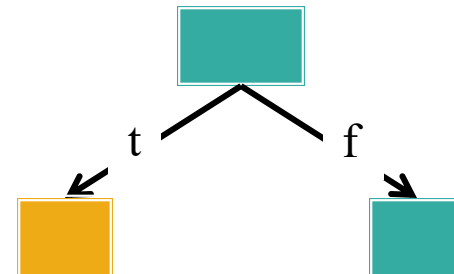
Finite State Machines

- Not limited to attributes
- Allow “arbitrary” behavior
- Explode in size very fast

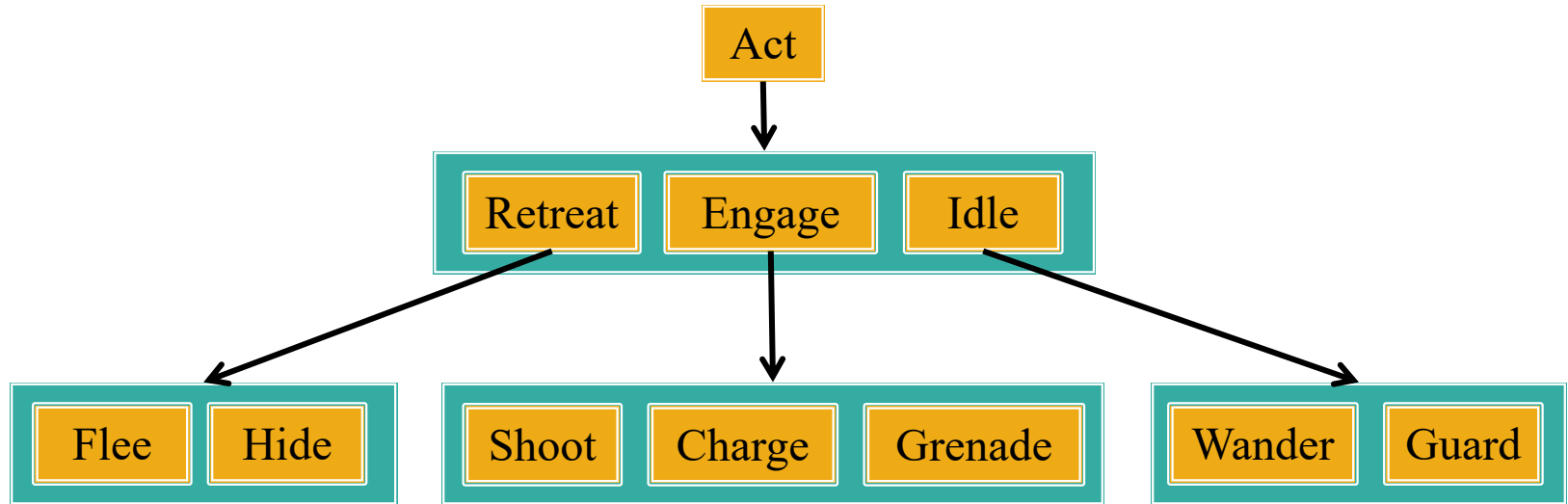


Decision Trees

- Only attribute selection
- Much more manageable
- Mixes w/ machine learning

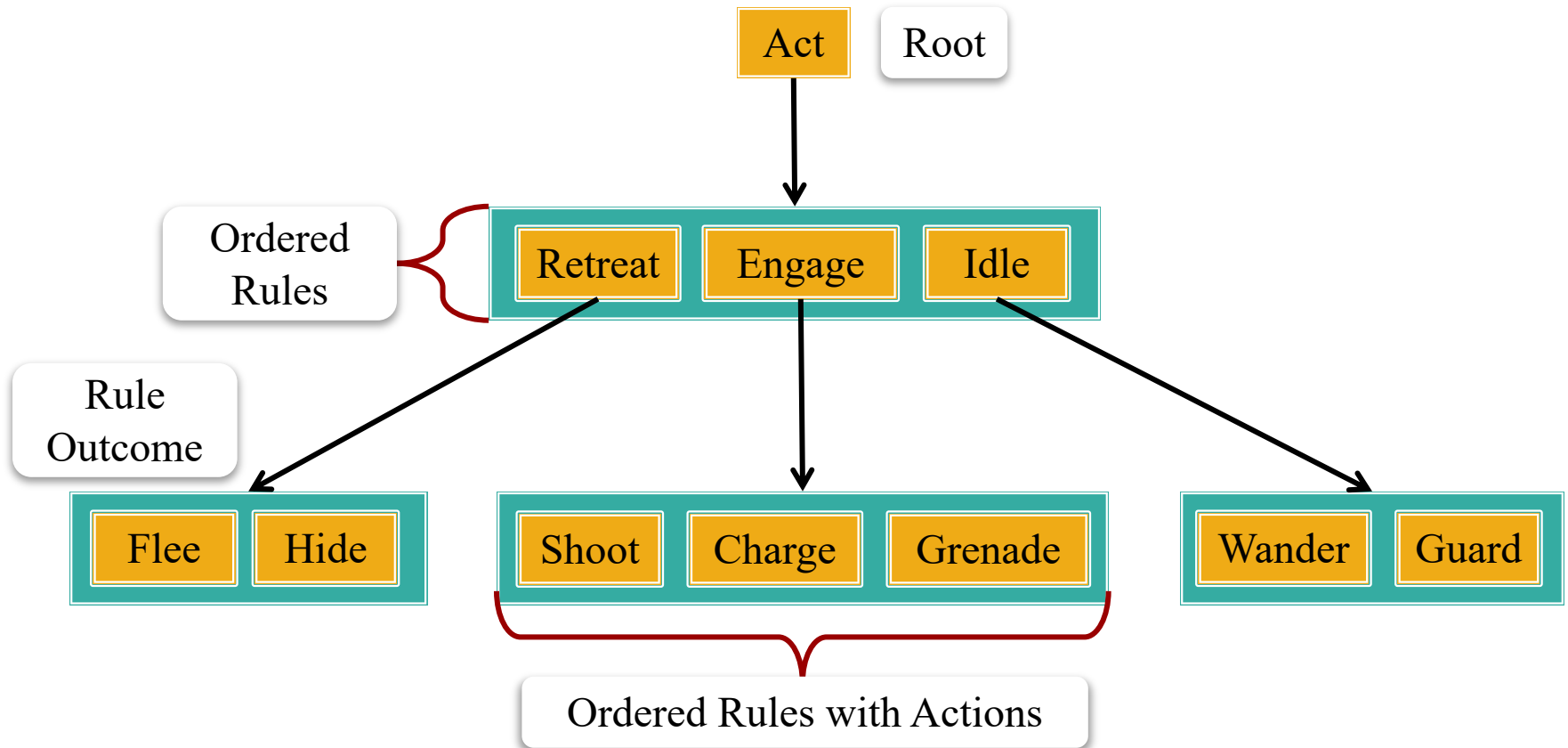


Behavior Trees

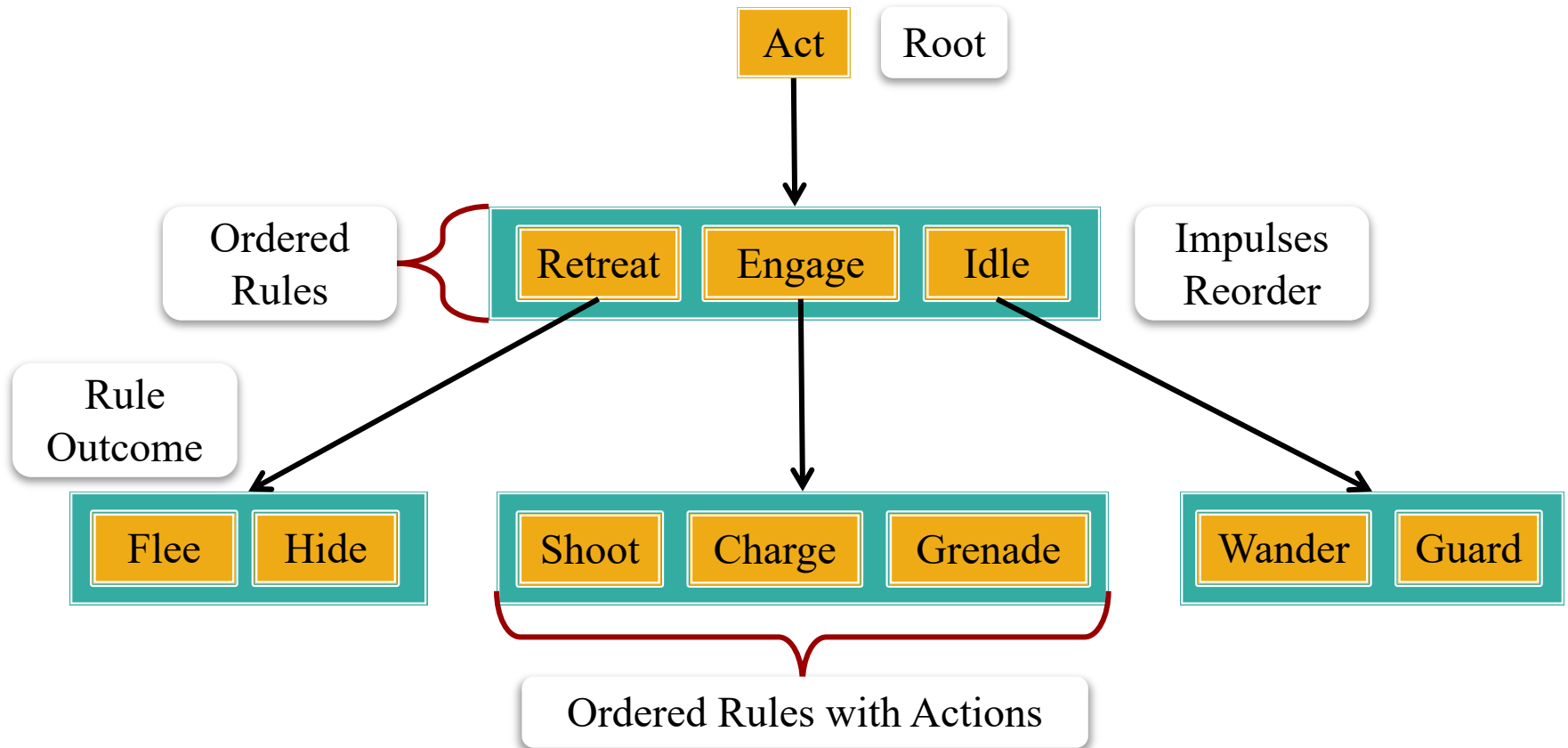


- Part rule-based
- Part decision tree
- Freedom of FSM (almost)
- Node is a list of *actions*
- Select action using *rules*
- Action leads to *subactions*

Behavior Trees

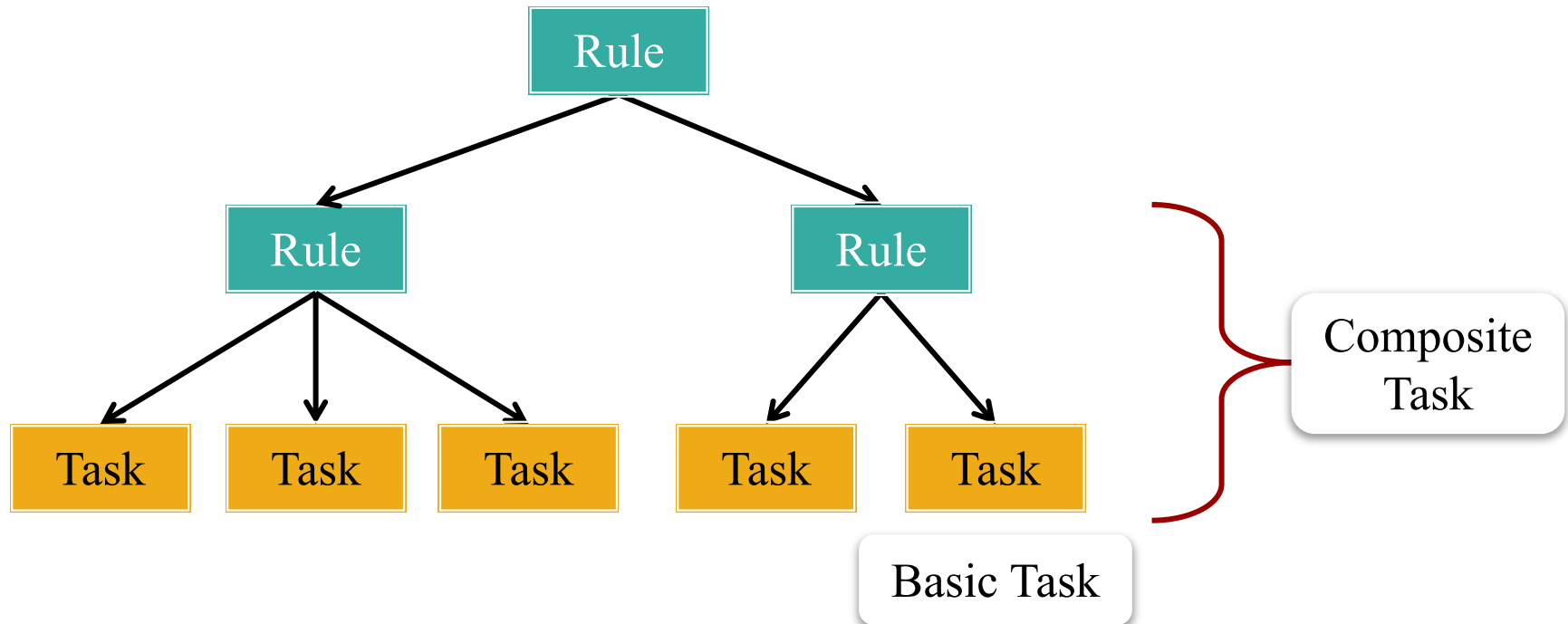


Behavior Trees



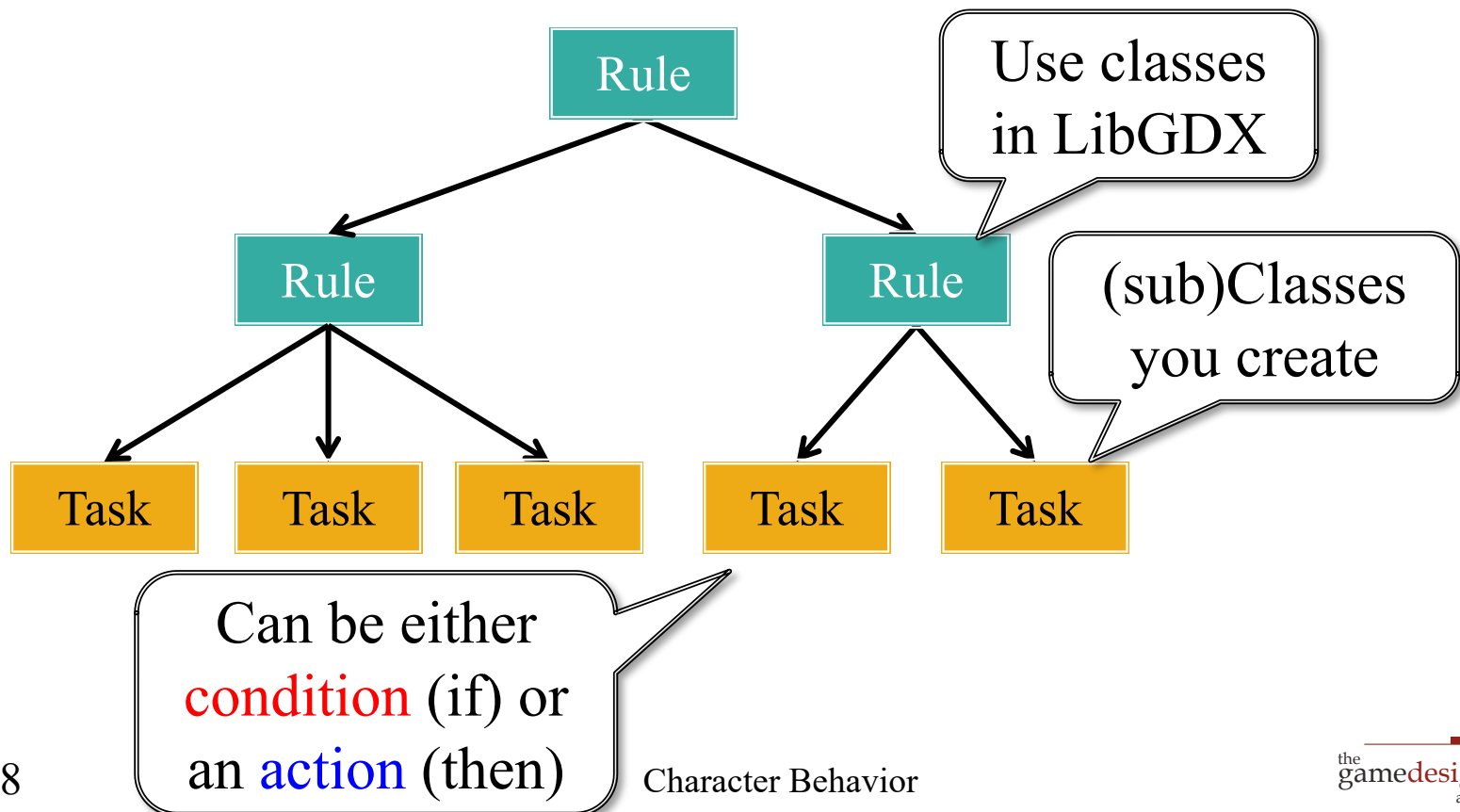
LibGDX Behavior Trees

- Base actions are defined at the leaves
- Internal nodes to **select** or even **combine** tasks

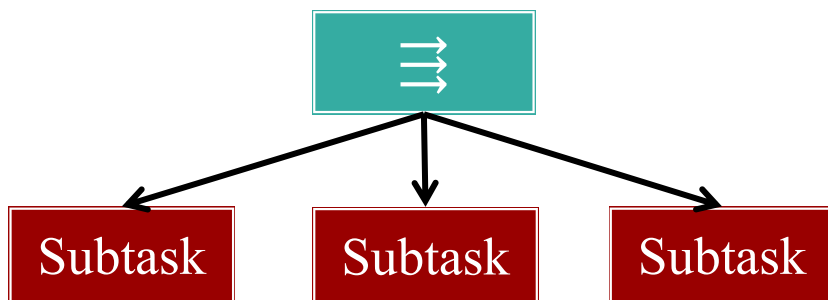
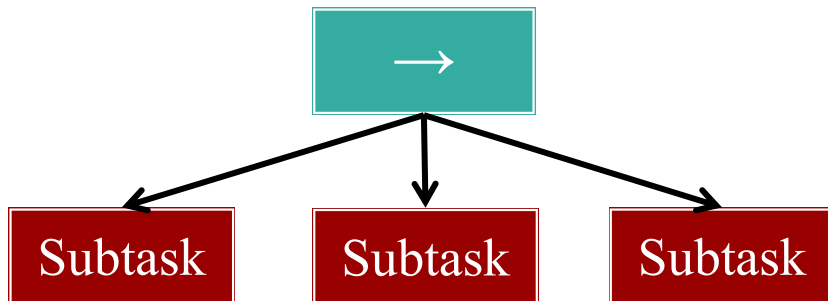
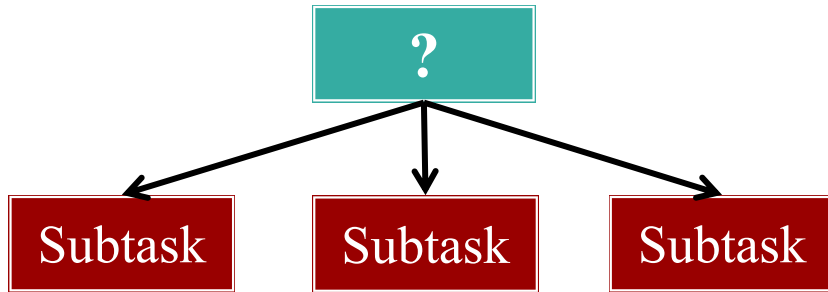


LibGDX Behavior Trees

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LibGDX Rules



- **Selector** rules

- Tests each subtask for success
- Tasks are tried independently
- Chooses first one to succeed

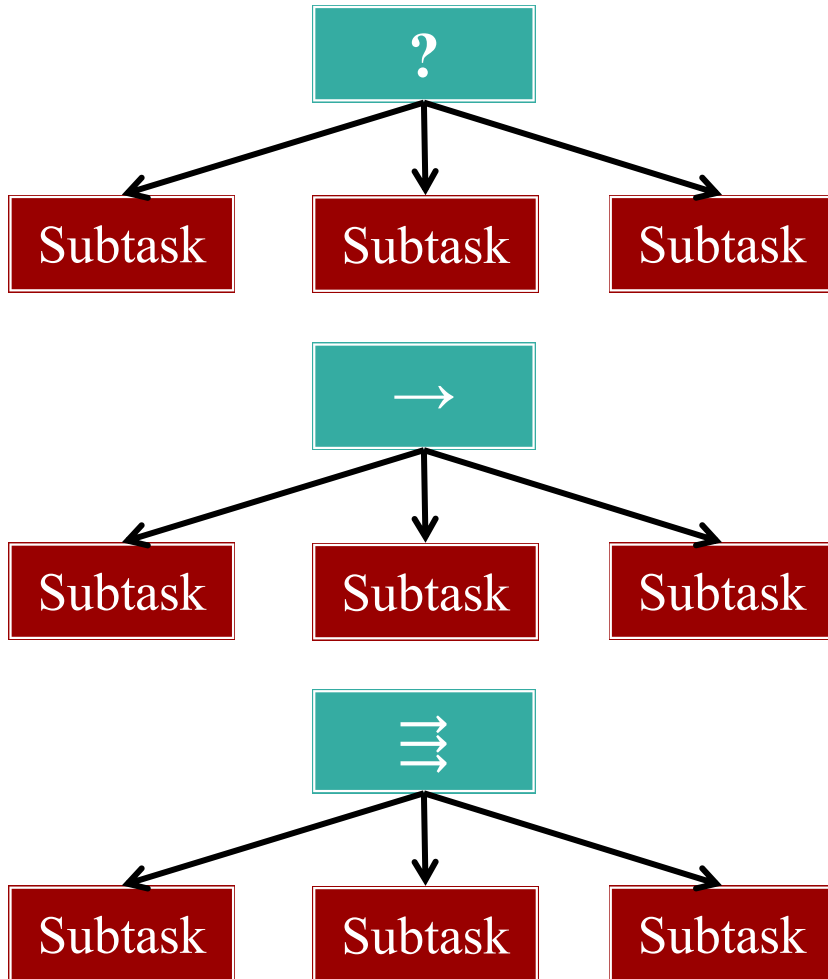
- **Sequence** rules

- Tests each subtask for success
- Tasks are tried in order
- Does all if succeeds; else none

- **Parallel** rules

- Tests each subtask for success
- Tasks are tried simultaneously
- Does all if succeeds; else none

This is the **Wrong** Model



- **Conflates** actions/selection
 - Want way to pick subtask
 - Distinct from performing it
- Actions must be **instant**
 - Can switch each frame
 - Action unaware of switch
 - No way to suspend/recover
- 4152 has **experimental API**
 - Still being tested in class
 - Bring to 3152 eventually

Summary

- Character AI is a **software engineering** problem
 - Sense-think-act aids code reuse and ease of design
 - Least standardized aspect of game architecture
- **Rule-based AI** is the foundation for all character AI
 - Simplified variation of sense-think-act
 - Alternative systems made to limit number of rules
- Games use **graphical models** for data-driven AI
 - Controller outside of NPC model processes AI
 - Graph stored in NPC model tailors AI to individuals