# Today slide credits

- Best algorithms book:
   Slides c/o Kevin Wayne
  - With slight changes





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### Two basic algorithms

- Exhaustive search: try everything

   Always works. Always slow.
- Greedy method: act locally – Sometimes works. Always fast.
- Today: a triumph of greed
   Plus a nice induction proof
- First: pirate grammar

### Pirate grammar

• What is a pirate's favorite sentence?



### Problem: shortest paths

- Underlying problem for examples
  - Not completely obvious
    - Pirate favorite sentence?
    - Photoshopping images??
- General version: given a graph with edge weights, a starting node s and a target t, find shortest path from s to t
- Claim: this problem is impossible – Proof?

# Cycles

- Consider a cycle A-B-C-A
   Where the weight sum is negative
- Go around this multiple times
   Always makes an even shorter path!
- Does the presence of a negative weight cycle imply no shortest path?
   – Almost, but not quite
- Let's assume positive edge weights

   Can detect negative cycles

# Key property

- Suppose the shortest path from s to t goes via v
  - -I.e., s ... t shortest s-v path
  - Otherwise, we would take that "shortcut" instead, and create an even shorter path
  - Parse this statement carefully!
- When considering s-v-t paths, we only need the shortest s-v path
  - Don't need to try everything!

### Idea: Dijkstra (1959)



**Figure 4.7** A snapshot of the execution of Dijkstra's Algorithm. The next node that will be added to the set *S* is *x*, due to the path through *u*.

Can think of expanding a ball
 Actually a variant of BFS!

#### Shortest path example



Cost of path s-2-3-5-t = 9 + 23 + 2 + 16 = 48.

# Dijkstra's algorithm

- On each recursive call we will have an explored set S
  - For each node u in S we hold the shortest path from s to u, write this as d(u)
    - Both the distance and the actual path
    - Easiest to just think about the distance d(u)
       Can easily extend this to add path
  - Add an unexplored node v to S
    - But, which one to choose?
    - Adjacent to S, so we add just one edge

# Choice of edge for a node

- The new node v can be adjacent to several nodes in S
  - -v is at the "fringe" of the set S
  - If we choose to add v, we need to pick the right node in S to connect it to



## Choice of node

- If we pick v to add to S, we will connect it to the u in S that minimizes d(u) + the length of the (u,v) edge Call this shortest path length π(v)
  - But can we pick an arbitrary v to add?
- Can prove that this would break our invariant about S!
- Need to pick v with smallest  $\pi(v)$ , then add it to S with  $d(v) = \pi(v)$

# Algorithm

- Start with S={s}, all other nodes in Q
   -d(s) = 0, else d(v) = ∞ (i.e. upper bound)
- Pick v on fringe of S that minimizes  $\pi(v)$  I.e., a v in Q with a neighbor in S
- On recursive call, we will have  $-d(v) = \pi(v)$ 
  - v is in S, and no longer in Q
- Done when we pick target t
   Computes more than shortest s-t path!

Find shortest path from s to t. Blue arrows are shortest path to a node within S. Green arrows are how we would add for each vertex.













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Note: we've built a tree that "spans" the graph!



# Correctness proof (sketch)

- Induction on the size of the graph
- P[n] = "algorithm works for all graphs with n nodes"



**Figure 4.8** The shortest path  $P_v$  and an alternate *s*-*v* path *P* through the node *y*.

## **Applications and extensions**

- Pirate's favorite sentence?
  - Is there a challenge in just using the probabilities as edge lengths?
  - How do we solve it, legitimately?
- All-pairs shortest paths
  - Easy solution: run from each source!
  - In practice, this is often best
    - But there are better asymptotic solutionsi