Spanning Trees, greedy algorithms

Lecture 21
CS2110 – Spring 2019

About A6, Prelim 2

Prelim 2: Thursday, 23 April.
Visit exams page of course website and read carefully to find
out when you take it (5:30 or 7:30) and what to do if you have
a conflict.

Time assignments the opposite of Prelim 1!
Time assignments the opposite of Prelim 1!
Time assignments the opposite of Prelim 1!
Time assignments the opposite of Prelim 1!

Hey, sign up for lunch. Lots of openings.

JavaHyperText material

Look at entries
spanning
This one gives you a .zip file that contains a Java app to
create random mazes.
greedy

We go over two algorithms for generating a spanning tree of a
graph. You have to know them only at a high level of
abstraction.

Amortized time

Visit JavaHyperText, put “amort” into Filter Field, read
the first — one page — pdf file.
In A5 – Heap.java, insert takes amortized time O(1).
WHAT DOES THAT MEAN?

Undirected trees

An undirected graph is a tree if there is exactly
one simple path between any pair of vertices

What’s the root?
It doesn’t matter!
Any vertex can be root.

Facts about trees

• #E = #V – 1
• connected
• no cycles

Any two of these
properties imply the
third and thus imply
that the graph is a tree

Tree with #V = 1, #E = 0

Tree with #V = 3, #E = 2
Facts about trees

• \#E = \#V − 1
• connected
• no cycles

Any two of these properties imply the third and thus imply that the graph is a tree.

Spanning trees

A spanning tree of a connected undirected graph \((V, E)\) is a subgraph \((V, E')\) that is a tree.

- Same set of vertices \(V\)
- \(E' \subseteq E\)
- \((V, E')\) is a tree

- Same set of vertices \(V\)
- Maximal set of edges that contains no cycle

- Same set of vertices \(V\)
- Minimal set of edges that connect all vertices

Three equivalent definitions

Spanning trees: examples

http://mathworld.wolfram.com/SpanningTree.html

Aside: Test whether an undirected graph has a cycle

/** Visit all nodes reachable along unvisited paths from u. *
* Pre: u is unvisited. */
public static void dfs(int u) {
    Stack s = (u);
    // inv: All nodes to be visited are reachable along an unvisited path from a node in s.
    while (!s.isEmpty()) {
        u = s.pop();
        if (u has not been visited) {
            visit u;
            for each edge \((u, v)\) leaving u: s.push(v);
        }
    }
}

Aside: Test whether an undirected graph has a cycle

/** Return true if the nodes reachable from \(u\) have a cycle. */
public static boolean hasCycle(int u) {
    Stack s = (u);
    // inv: All nodes to be visited are reachable along an unvisited path from a node in s.
    while (!s.isEmpty()) {
        u = s.pop();
        if (u has been visited) return true;
        visit u;
        for each edge \((u, v)\) leaving u: s.push(v);
    }
    return false;
}
Finding a spanning tree: Subtractive method

• Start with the whole graph – it is connected
• While there is a cycle:
  Pick an edge of a cycle and throw it out
  – the graph is still connected (why?)

Maximal set of edges that contains no cycle

How many edges have to be discarded?

Starts with e edges
Get down to n-1 edge.
Throw out e – (n-1) edges.

Dense graph? Throw out O(n^2) edges!
In general, too many to throw out!
Don’t use!

Finding a spanning tree: Additive method

• Start with no edges
• While the graph is not connected:
  Choose an edge that connects 2 connected components and add it
  – the graph still has no cycle (why?)

Minimal set of edges that connect all vertices

Tree edges will be red.
Dashed lines show original edges.
Left tree consists of 5 connected components, each a node

Adding n-1 edges

Minimum spanning trees

• Suppose edges are weighted (> 0)
• We want a spanning tree of minimum cost (sum of edge weights)
• Some graphs have exactly one minimum spanning tree. Others have several trees with the same minimum cost, each of which is a minimum spanning tree
• Useful in network routing & other applications. For example, to stream a video

Greedy algorithm

A greedy algorithm follows the heuristic of making a locally optimal choice at each stage, with the hope of finding a global optimum.

Example. Make change using the fewest number of coins.
Make change for n cents, n < 100 (i.e. < $1)
Greedy: At each step, choose the largest possible coin
If n >= 50 choose a half dollar and reduce n by 50;
If n >= 25 choose a quarter and reduce n by 25;
As long as n >= 10, choose a dime and reduce n by 10;
If n >= 5, choose a nickel and reduce n by 5;
Choose n pennies.

Greediness works here
You’re standing at point x. Your goal is to climb the highest mountain.
Two possible steps: down the hill or up the hill. The greedy step is to walk up hill. That is a local optimum choice, not a global one. Greediness works in this case.

Greediness doesn’t work here
You’re standing at point x, and your goal is to climb the highest mountain.
Two possible steps: down the hill or up the hill. The greedy step is to walk up hill. But that is a local optimum choice, not a global one. Greediness fails in this case.
Greedy algorithm — doesn’t always work!

A greedy algorithm follows the heuristic of making a locally optimal choice at each stage, with the hope of finding a global optimum. Doesn’t always work.

Example. Make change using the fewest number of coins. Coins have these values: 7, 5, 1
Greedy: At each step, choose the largest possible coin
Consider making change for 10.
The greedy choice would choose: 7, 1, 1, 1.
But 5, 5 is only 2 coins.

Finding a minimal spanning tree

Suppose edges have > 0 weights

Minimal spanning tree: sum of weights is a minimum

We show two greedy algorithms for finding a minimal spanning tree. They are abstract, at a high level.

They are versions of the basic additive method we have already seen: at each step add an edge that does not create a cycle.

Kruskal: add an edge with minimum weight. Can have a forest of trees.
Prim (JPD): add an edge with minimum weight but so that the added edges (and the nodes at their ends) form one tree

MST using Kruskal's algorithm

At each step, add an edge (that does not form a cycle) with minimum weight
edge with weight 2
edge with weight 3
One of the 4’s
The 5
Red edges need not form tree (until end)

Kruskal

Start with all the nodes and no edges, so there is a forest of trees, each of which is a single node (a leaf).
At each step, add an edge (that does not form a cycle) with minimum weight
We do not look more closely at how best to implement Kruskal’s algorithm — which data structures can be used to get a really efficient algorithm.
Leave that for later courses, or you can look them up online yourself.
We now investigate Prim’s algorithm

MST using “Prim’s algorithm” (should be called “JPD algorithm”)


Help: IPA for Czech
From Wikipedia, the free encyclopedia
Vojtěch Jarník (Czech pronunciation: [ˈvojtoʃ ˈjarɲik])

Prim’s algorithm

At each step, add an edge (that does not form a cycle) with minimum weight, but keep added edge connected to the start (red) node
edge with weight 3
edge with weight 5
One of the 4’s
The 2

Here, Prim chooses (0, 1)
Kruskal chooses (3, 4)

Here, Prim chooses (0, 2)
Kruskal chooses (3, 4)

Prim requires that the constructed red tree always be connected.
Kruskal doesn’t

But: Both algorithms find a minimal spanning tree

If the edge weights are all different, the Prim and Kruskal algorithms construct the same tree.

Implement JPD to create a maze
The graph is a grid. Each node is connected by an edge to its neighbors.

There is no need to implement edges. Each node has an edge to its North, East, West, and South neighbors: N, E, W, S

If being drawn in a GUI, draw a black line between adjacent nodes.

Choose beginning node b randomly, make it white.
Implement JPD to create a maze

The graph is a grid. Each node is connected by an edge to its neighbors.

All nodes that have been added to the spanning tree are white. They have in them a letter b, N, E, W, or S --- as will be seen later.

Implement JPD to create a maze

Here’s ONE step of the algorithm.

1. Choose a random Frontier (blue) node,
2. Make it white (put in spanning tree), remove it from Frontier.
3. Put in it a letter to indicate edge to the white node to which it was adjacent.
4. Remove black line between the two nodes.
5. Add adjacent nodes to the Frontier

(Remember, don’t add a cycle)

Implement JPD to create a maze

You know about backpointers from the shortest path algorithm.

Think of start node b as the root of the tree. The N is a backpointer for the path from root b of the tree to this node. It point to the node’s parent.

Implement JPD to create a maze

Here’s ONE step of the algorithm.

1. Choose a random Frontier (blue) node,
2. Make it white (put in spanning tree), remove it from Frontier.
3. Put in it a letter to indicate edge to the white node to which it was adjacent.
4. Remove black line between the two nodes.
5. Add adjacent nodes to the Frontier
**Implement JPD to create a maze**

Important points about implementation:
- No implementation of edges.
- They are in our head.
- Nodes with a letter in them are in the spanning tree.
- N indicates an edge of spanning tree to node to North (similar for E, W, S).
- Frontier set (blue nodes) is an ArrayList. Efficient to choose one at random and to remove it from set.

**Maze generation using Prim’s algorithm**

The generation of a maze using Prim’s algorithm on a randomly weighted grid graph that is 30x20 in size.

https://en.wikipedia.org/wiki/Maze_generation_algorithm

jonathanzong.com/blog/2012/11/06/maze-generation-with-prims-algorithm

**Greedy algorithms**

Suppose the weights are all 1. Then Dijkstra’s shortest-path algorithm does a breadth-first search!

Dijkstra’s and Prim’s algorithms look similar. The steps taken are similar, but at each step:
- Dijkstra’s chooses an edge whose end node has a minimum path length from start node.
- Prim’s chooses an edge with minimum length.

**Breadth-first search, Shortest-path, Prim**

Greedy algorithm: An algorithm that uses the heuristic of making the locally optimal choice at each stage with the hope of finding the global optimum.

Dijkstra’s shortest-path algorithm makes a locally optimal choice: choosing the node in the Frontier with minimum L value and moving it to the Settled set. And, it is proven that it is not just a hope but a fact that it leads to the global optimum.

Similarly, Prim’s and Kruskal’s locally optimum choices of adding a minimum-weight edge have been proven to yield the global optimum: a minimum spanning tree.

BUT: Greediness does not always work!

**Similar code structures**

while (a vertex is unmarked) {
    v = best unmarked vertex
    mark v;
    for (each w adj to v)
        update D[w];
}

- Breadth-first-search (bfs)
- best: next in queue
- update: D[w] = D[v]+1

- Dijkstra's algorithm
- best: next in priority queue
- update: D[w] = min(D[w], D[v]+c(v,w))

- Prim's algorithm
- best: next in priority queue
- update: D[w] = min(D[w], c(v,w))

**Graph Algorithms**

- Search
  - Depth-first search
  - Breadth-first search
- Shortest paths
  - Dijkstra’s algorithm
- Minimum spanning trees
  - Prim’s algorithm
  - Kruskal’s algorithm