

Even More ADTs

Lecture 18 CS211 - Fall 2006

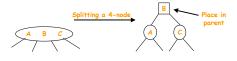
Announcements & Reminders

- Prelim 2
 - Tuesday, Nov 14
 - 7:30-9:00PM
 - If you have a conflict
 - Contact Kelly Patwell (Course Administrator) soon!
- Dictionary operations
 - void insert (key, value)
 - void update (key, value)
 - value find (key)
 - void remove (key)

- · Dictionary implementations
 - Linked lists & arrays
 - Too slow
 - Direct Address Tables • Limited usage
 - Hash Tables (using chaining
 - and table doubling) • O(1) expected time
 - BSTs
 - O(log n) expected time
 - Input in random order
 - Balanced BSTs
 - O(log n) worst-case time

Example Balancing Scheme: 234-Trees

- Nodes have 2, 3, or 4 children (and contain 1, 2, or 3 keys, respectively)
- · All leaves are at the same level
- · Basic rule for insertion: We hate 4-nodes
 - Split a 4-node whenever you find one while coming down the tree
- Note: this requires that parent is not a 4-node
- · Delete is harder than insert
 - For delete we hate 2-nodes
 - As in BSTs, cannot delete from a nonleaf so we use same BST trick: delete successor and recopy its data



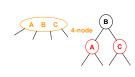
234-Tree Analysis

- Time for insert or get is proportional to tree's height
- How big is tree's height h? • Let n be the number of
- nodes in a tree of height h
 - n is large if all nodes are 4-
 - n is small if all nodes are 2-
- · Can use this to show $h = O(\log n)$
- Analysis of tree height:
- Let N be the number of nodes, n be the number of items, and h be
- Define h so that a tree consisting of a single node is height 0
- It's easy to see $1+2+4+...+2^h \le N \le 1+4+16+...+4^h$ • It's also easy to see $N \le n \le 3N$
- Using the above, we have $n \ge 1+2+4+...+2^h = 2^{h+1}-1$
- Rewriting, we have $h \le log(n+1) 1$
- Thus, Dictionary operations on 234-trees take time O(log n) in the worst case

234-Tree Implementation

- Can implement all nodes as 4-nodes
 - Wasted space
- Can allow various node sizes
 - Requires recopying of data whenever a node changes size
- Can use BST nodes to emulate 2-, 3-, or 4-nodes

Using BSTs to Emulate 234-Trees



- A 2-node can be represented with a standard BST node
- A 4-node can be represented with three BST nodes



• A 3-node can be represented with two BST nodes (in two different

Red-Black Trees

- We need a way to tell when an emulated 234-node starts and ends
- · We mark the nodes
 - Black: "root" of 234-node
 - Red: belongs to parent
- Requires one bit per node
- 234-tree rules become rules for rotations and color changes in red-black trees
- · Result:
 - One black node per 234node
 - Number of black nodes on path from root to leaf is same as height of 234-tree
 - On any path: at most one red node per black node
 - Thus tree height for redblack tree is O(log n)

Balanced Tree Schemes

- AVL trees [1962]
 - named for initials of Russian creators
- uses rotations to ensure heights of child trees differ by at most 1
- 23-Trees [Hopcroft 1970]
 - similar to 234-tree, but repairs have to move back up the tree
- B-Trees [Bayer & McCreight 1972]
- Red-Black Trees [Bayer 1972]
 - not the original name
- Red-black convention & relation to 234-trees [Guibas & Stolfi 1978]
- Splay Trees [Sleator & Tarjan 1983]
- Skip Lists [Pugh 1990]
 - developed at Cornell

Selecting a Dictionary Scheme

- Use an unordered array for small sets (< 20 or so)
- Use a Hash Table if possible
 Cannot efficiently do some ops that are easy with
 - Running times are expected rather than worst-case
- Use an ordered array if few changes after initialization
- B-Trees are best for large data sets, external storage
 - Widely used within data base software

- Otherwise, Red-Black Trees are current scheme of choice
- Skip Lists are supposed to be easier to implement
 - But shouldn't have to implement—use existing
- Splay trees are useful if some items are accessed more often than others
 - But if you know which items are most-commonly accessed, use a separate data structure

Possible Priority Queue Implementations

	Unordered List	Ordered List	Unordered Array	Ordered Array	BST*	Balanced BST
insert(item)	O(1)	O(n)	O(1)	O(n)	O(log n) expected	O(log n) worst-case
removeMax()	O(n)	O(1)	O(n)	O(1)	O(log n) expected	O(log n) worst-case

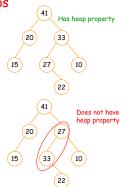
 \star BST becomes unbalanced as PQ is used

Can we do better than balanced trees? Well no, not in terms of big-O bounds, but...

Heaps

• A heap is a tree that

- Has a particular shape (we'll come back to this) and
- Has the heap property
- Heap property
 - Each node's value (its priority) is ≤ the value of its parent
 - This version is for a maxheap (max value at the root)
 - There is a similar heap property for a min-heap (min at the root)

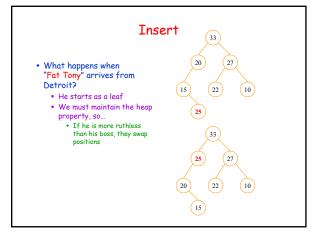


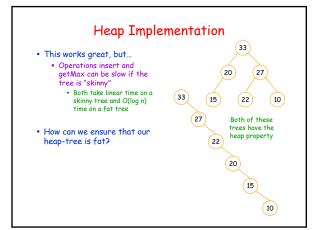
Heap Property Examples

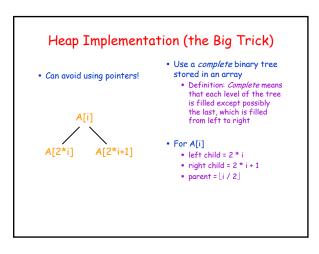
- Ages of people in a family tree
 - Child is younger than parent
 - But an aunt can be younger than her niece
- Salaries of people in an organization
 - A boss makes more money than a subordinate
 - But a 2nd level manager in one region may make more than a 1st level manager in another region
- Crime family ordered by "ruthlessness" (measured by number of murders each member is responsible for)
 - Max, the top crime boss, must be the most ruthless



GetMax · What would happen if someone were to "get" Max 20 33 (the top boss)? • This leaves a hole at the (15) (27) 10 root • We must maintain the heap property so... 22 The most ruthless subordinate moves up to 33 fill the hole This leaves another hole 20 that we fill in the same way 27 • We finally create an empty leaf which we delete 15







Insert and GetMax Pseudocode

insert (item):

Place item in a leaf (= next empty position in array); while (item > parent) {Swap item with parent;} // BubbleUp

getMax ():

max = root.value;

Swap root with last item (call it v) in heap; // Unchanging heap-shape
Decrease heap size by 1 (i.e., access less of the array);
while (v < one of its children) // BubbleDown

{Swap v with its largest child;}

return max;

To Build a Heap

- How long to construct a heap, given the items?
- Worst-case time for insert() is O(log n)
- Total time to build heap using insert() is O(log 1) + O(log 2) + ... + O(log n) or O(n log n)

Can we do better?

- We had two heap-fixing methods
 - bubbleUp: move up the tree as long as we're > our parent
 - bubbleDown: move down the tree as long as we're < one of our children
- If we build the heap from the bottom-up using bubbleDown then we can build it in time O(n) (Wow!)

Efficient Heap Building

- · Build from the bottom-up
- If there are n items in the heap then...
 - There are about n/2 miniheaps of height 1
 There are about n/4 minihima
 - There are about n/4 mines
 heaps of height 2
 - There are about n/8 miniheaps of height 3 and so on
- The time to fix up a miniheap is O(its height)
- Total time spent fixing heaps is thus bounded by n/2 + 2n/4 + 3n/8 +
- This can be rewritten as $n(1/2 + 2/4 + ... + i/2^{i} + ...)$
- Thus total heap-building time (using the bottom-up method) is O(n)

HeapSort

- Given a Comparable[] array of length n,
 - Put all n elements into a heap: O(n) or O(n log n)
 - Repeatedly get the min: O(n log n)

public static void heapSort(Comparable[] a) { PriorityQueue<Comparable> $p_i = new PriorityQueue<Comparable> <math>p_i = new PriorityQueue<Comparable> (); for (Comparable> <math>x = 0 \neq new PriorityQueue<Comparable> (); for (int i = 0; i < a.length; i++) { a[i] = pq.get(); }$

PQ Application: Simulation

- Example: Given a probabilistic model of bankcustomer arrival times and transaction times, how many tellers are needed
 - Assume we have a way to generate random interarrival times
 - Assume we have a way to generate transaction times
 - Can simulate the bank to get some idea of how long customers must wait

Time-Driven Simulation

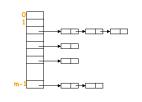
 Check at each tick to see if any event occurs

Event-Driven Simulation

- Advance clock to next event, skipping intervening ticks
- This uses a PQ!

Another PQ Implementation

- If there are only a few possible priorities then can use an array of queues
 - Each array position represents a priority (0..m-1 where m is the array size)
 - Each queue holds all items that have that priority
- One text [Skiena] calls this a bounded height priority queue
- Time for insert: O(1)
- Time for getMax:
- O(m) in the worst-case
- Example: airline check-in



Other PQ Operations

delete

a particular item

update

an item (change its priority)

join

two priority queues

- For delete and update, we need to be able to find the item
 - One way to do this: Use a Dictionary to keep track of the item's position in the heap
- Efficient joining of 2
 Priority Queues requires another data structure
 - Skew Heaps or Pairing Heaps
 - Chapter 23 in text
 - Not part of 211

Selecting a Priority Queue Scheme

- Use an unordered array for small sets (< 20 or so)
- Use a sorted array or sorted linked list if few insertions are expected
- Use an array of linked lists if there are few priorities
 - Each linked list is a queue of equal-priority items
 - Very easy to implement
- Otherwise, use a Heap if you can

- Heap + Hashtable
 - Allow change-priority operation to be done in O(log n) expected time
- Balanced tree schemes
 - Useful and practical
- There are a number of alternate implementations that allow additional operations
 - Skew heaps
 - Skew neapsPairing heaps
 - Fibonacci heaps
 - ...