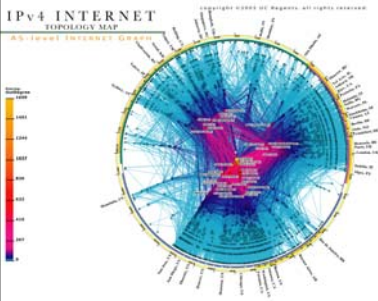


## Graphs & Graph Algorithms

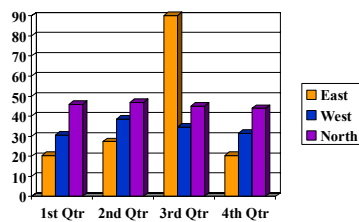
Lecture 20  
CS211 – Fall 2005



## Announcements

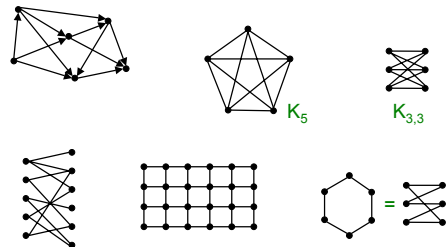
- Upcoming talk
  - “The Many Careers of a Computer Scientist”
    - Or how a Computer Science degree empowers you to do much more than code
  - Dan Huttenlocher, Professor in the Department of Computer Science and Johnson Graduate School of Management
  - 5:00 PM, Wednesday, November 9th
  - Upsilon Lounge
  - FREE PIZZA!
- ACSU (Association of Computer Science Undergraduates)

## This is not a Graph



...not the kind we mean, anyway

## These are Graphs



## Applications of Graphs

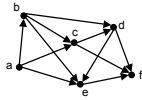
- Communication networks
- Routing and shortest path problems
- Commodity distribution (flow)
- Traffic control
- Resource allocation
- Geometric modeling
- ...

## Graph Definitions

- A *directed graph* (or *digraph*) is a pair  $(V, E)$  where
  - $V$  is a set
  - $E$  is a set of ordered pairs  $(u, v)$  where  $u, v \in V$ 
    - Usually require  $u \neq v$  (no self-loops)
- An element of  $V$  is called a *vertex* (pl. *vertices*) or *node*
- An element of  $E$  is called an *edge* or *arc*
- $|V|$  = size of  $V$ , often denoted  $n$
- $|E|$  = size of  $E$ , often denoted  $m$

## Example *Directed* Graph

Example:



$V = \{a,b,c,d,e,f\}$

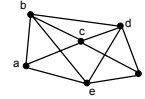
$E = \{(a,b), (a,c), (a,e), (b,c), (b,d), (b,e), (c,d), (c,f), (d,e), (d,f), (e,f)\}$

$|V| = 6, |E| = 11$

## Example *Undirected* Graph

An *undirected graph* is just like a directed graph, except the edges are *unordered pairs (sets)*  $\{u,v\}$

Example:

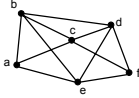
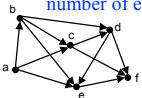


$V = \{a,b,c,d,e,f\}$

$E = \{\{a,b\}, \{a,c\}, \{a,e\}, \{b,c\}, \{b,d\}, \{b,e\}, \{c,d\}, \{c,f\}, \{d,e\}, \{d,f\}, \{e,f\}\}$

## Some Graph Terminology

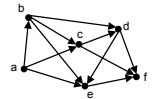
- Vertices  $u$  and  $v$  are called the *source* and *sink* of the directed edge  $(u,v)$ , respectively
- Vertices  $u$  and  $v$  are called the *endpoints* of  $(u,v)$
- Two vertices are *adjacent* if they are connected by an edge
- The *outdegree* of a vertex  $u$  in a directed graph is the number of edges for which  $u$  is the source
- The *indegree* of a vertex  $v$  in a directed graph is the number of edges for which  $v$  is the sink
- The *degree* of a vertex  $u$  in an *undirected* graph is the number of edges of which  $u$  is an endpoint



## More Graph Terminology



- A *path* is a sequence  $v_0, v_1, v_2, \dots, v_p$  of vertices such that  $(v_i, v_{i+1}) \in E, 0 \leq i \leq p-1$
- The *length* of a path is its number of edges
  - In this example, the length is 5
- A path is *simple* if it does not repeat any vertices
- A *cycle* is a path  $v_0, v_1, v_2, \dots, v_p$  such that  $v_0 = v_p$
- A cycle is *simple* if it does not repeat any vertices except the first and last
- A graph is *acyclic* if it has no cycles
- A *directed acyclic graph* is called a *dag*



## Is this a dag?



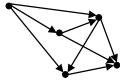
- Intuition: If it's a dag, there should be a "first" vertex (i.e., a vertex with indegree zero)
- This idea leads to an algorithm
  - A digraph is a dag if and only if we can iteratively delete indegree-0 vertices until the graph disappears

## Is this a dag?



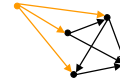
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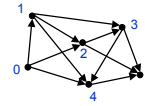
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## Topological Sort

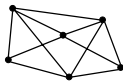
- Just computed a *topological sort* of the dag
  - A numbering of the vertices such that all edges go from lower- to higher-numbered vertices



- Useful in job scheduling with precedence constraints

## Graph Coloring

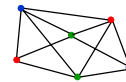
- A *coloring* of an undirected graph is an assignment of a color to each node such that no two adjacent vertices get the same color



- How many colors are needed to color this graph?

## Graph Coloring

- A *coloring* of an undirected graph is an assignment of a color to each node such that no two adjacent vertices get the same color



- How many colors are needed to color this graph?
  - 3

## An Application of Coloring

- Vertices are jobs
- Edge  $(u,v)$  is present if jobs  $u$  and  $v$  each require access to the same shared resource, and thus cannot execute simultaneously
- Colors are time slots to schedule the jobs
- Minimum number of colors needed to color the graph = minimum number of time slots required



## Planarity

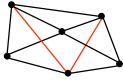
- A graph is *planar* if it can be embedded in the plane with no edges crossing



- Is this graph planar?

## Planarity

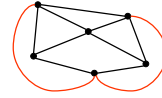
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- Is this graph planar?
  - Yes

## Planarity

- A graph is *planar* if it can be embedded in the plane with no edges crossing



- Is this graph planar?
  - Yes

## Detecting Planarity

### Kuratowski's Theorem



$K_5$



$K_{3,3}$

A graph is planar if and only if it does not contain a copy of  $K_5$  or  $K_{3,3}$  (possibly with other nodes along the edges shown)

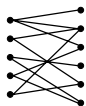
## The Four-Color Theorem

Every planar graph is 4-colorable  
(Appel & Haken, 1976)



## Bipartite Graphs

- A directed or undirected graph is *bipartite* if the vertices can be partitioned into two sets such that all edges go between the two sets

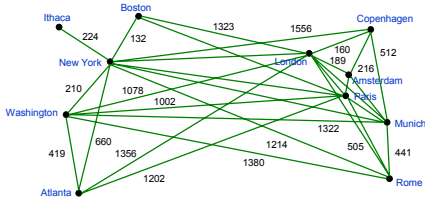


## Bipartite Graphs

- The following are equivalent
  - $G$  is bipartite
  - $G$  is 2-colorable
  - $G$  has no cycles of odd length



## Traveling Salesperson



Find a path of minimum distance that visits every city

## Implementing Digraphs

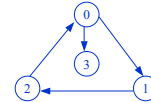
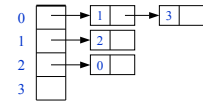
### Adjacency Matrix

$g[u][v]$  is true iff there is an edge from  $u$  to  $v$

	0	1	2	3
0		T		T
1				
2	T			
3				

### Adjacency List

The list for  $u$  contains  $v$  iff there is an edge from  $u$  to  $v$



## Implementing Weighted Digraphs

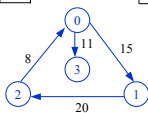
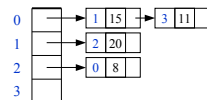
### Adjacency Matrix

$g[u][v]$  is  $c$  iff there is an edge of cost  $c$  from  $u$  to  $v$

	0	1	2	3
0		15		11
1			20	
2	8			
3				

### Adjacency List

The list for  $u$  contains  $v, c$  iff there is an edge from  $u$  to  $v$  that has cost  $c$



## Implementing Undirected Graphs

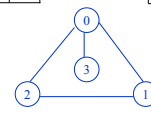
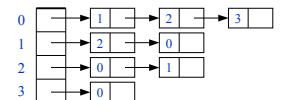
### Adjacency Matrix

$g[u][v]$  is true iff there is an edge from  $u$  to  $v$

	0	1	2	3
0		T	T	T
1	T			
2	T	T		
3	T			

### Adjacency List

The list for  $u$  contains  $v$  iff there is an edge from  $u$  to  $v$



## Adjacency Matrix or Adjacency List?

$n$  = number of vertices

$m$  = number of edges

$m_u$  = number of edges leaving  $u$

### Adjacency Matrix

- Uses space  $O(n^2)$
- Can iterate over all edges in time  $O(n^2)$
- Can answer "Is there an edge from  $u$  to  $v$ ?" in  $O(1)$  time
- Better for *dense* (i.e., lots of edges) graphs

### Adjacency List

- Uses space  $O(m+n)$
- Can iterate over all edges in time  $O(m+n)$
- Can answer "Is there an edge from  $u$  to  $v$ ?" in  $O(m_u)$  time
- Better for *sparse* (i.e., fewer edges) graphs

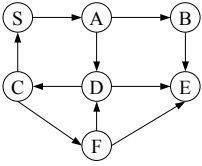
## Goal: Find Shortest Path in a Graph

• Finding the shortest (min-cost) path in a graph is a problem that occurs often

- Find the least-cost route between Ithaca and Detroit
- Result depends on our notion of cost
  - least mileage
  - least time
  - cheapest
  - least boring
- All of these "costs" can be represented as edge costs on a graph

• How do we find a shortest path?

## Shortest Paths for Unweighted Graphs



```

bfsDistance(s):
    // s is the start vertex
    // dist[v] is length of s-to-v path
    // Initially dist[v] = ∞ for all v
    dist[s] = 0;
    Q.insert(s);

    while (Q nonempty) {
        v = Q.get();
        for (each w adjacent to v) {
            if (dist[w] == ∞) {
                dist[w] = dist[v]+1;
                Q.insert(w);
            }
        }
    }
    }
    
```

## Analysis for bfsDistance

- How many times can a vertex be placed in the queue?
- How much time for the for-loop?

- Depends on representation
  - Adjacency Matrix:  $O(n)$
  - Adjacency List:  $O(m_v)$

- Time:
  - $O(n^2)$  for adj matrix
  - $O(m+n)$  for adj list

```

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            }
        }
    }
    }
    
```

## If There are Edge Costs?

- Idea #1
  - Add false nodes so that all edge costs are 1
  - But what if edge costs are large?
  - What if the costs aren't integers?
- Idea #2
  - Nothing "interesting" happens at the false nodes
    - Can't we just jump ahead to the next "real" node
  - Rule: always do the closest (real) node first
  - Use the array `dist[]` to
    - Report answers
    - Keep track of what to do next

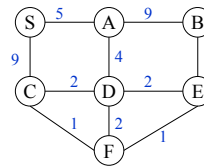
## Dijkstra's Algorithm

- Intuition
  - Edges are threads; vertices are beads
  - Pick up at `s`; mark each node as it leave the table
- Note: Negative edge-costs are *not allowed*

- `s` is the start vertex
- `c(i,j)` is the cost from `i` to `j`
- Initially, vertices are unmarked
- `dist[v]` is length of `s-to-v` path
- Initially, `dist[v] = ∞`, for all `v`

```

dijkstra(s):
    dist[s] = 0;
    while (some vertices are unmarked) {
        v = unmarked vertex with
            smallest dist;
        Mark v;
        for (each w adj to v) {
            dist[w] = min
                ( dist[w], dist[v] + c(v,w) );
        }
    }
    }
    
```



## Dijkstra's Algorithm using Adj Matrix

- While-loop is done  $n$  times
- Within the loop
  - Choosing `v` takes  $O(n)$  time
    - Could do this faster using PQ, but no reason to
  - For-loop takes  $O(n)$  time
- Total time =  $O(n^2)$

```

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        }
    }
    }
    
```

## Dijkstra's Algorithm using Adj List

- Looks like we need a PQ
  - Problem: priorities are updated as algorithm runs
  - Can insert pair  $(v, dist[v])$  in PQ whenever `dist[v]` is updated
  - At most  $m$  things in PQ
- Time  $O(n + m \log m)$
- Using a more complicated PQ (e.g., Pairing Heap), time can be brought down to  $O(m + n \log n)$

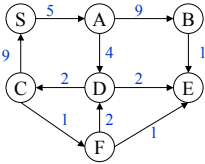
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    }
    
```

## Dijkstra's Algorithm for Digraphs

- Algorithm works on both undirected and directed graphs without modification
- As before: Negative edge-costs are *not allowed*

- $s$  is the start vertex
- $c(i,j)$  is the cost from  $i$  to  $j$
- Initially, vertices are unmarked
- $dist[v]$  is length of  $s$ -to- $v$  path
- Initially,  $dist[v] = \infty$ , for all  $v$



```
dijkstra(s):
dist[s] = 0;
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  v = unmarked vertex with
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  Mark v;
  for (each w adj to v) {
    dist[w] = min
    ( dist[w], dist[v] + c(v,w) );
  }
}
```

## Greedy Algorithms

- Dijkstra's Algorithm is an example of a *Greedy Algorithm*
- The Greedy Strategy is an algorithm design technique
  - Like Divide & Conquer
- The Greedy Strategy is used to solve optimization problems
  - The goal is to find the best solution
- Works when the problem has the *greedy-choice property*
  - A global optimum can be reached by making locally optimum choices
- Problem: Given an amount of money, find the smallest number of coins to make that amount
- Solution: Use a Greedy Algorithm
  - Give as many large coins as you can
- This greedy strategy produces the optimum number of coins for the US coin system
- Different money system  $\Rightarrow$  greedy strategy may fail
  - For example: suppose the US introduces a 4¢ coin