

L28. Divide and Conquer Algorithms

Binary Search
Merge Sort
Mesh Generation
Recursion

Question

The Manhattan phone book has 1,000,000+ entries.



How is it possible to locate a name by examining just a tiny, tiny fraction of those entries?

Answer: Repeated Halving

To find the page containing Derek Jeter's number...

```
while (Phone book is longer than 1 page)
  Open to the middle page.
  if "Jeter" comes before the first name,
    Rip and throw away the 2nd half.
  else
    Rip and throw away the 1st half.
  end
end
end
```

What Happens to Phone Book Length...

Original: 3000 pages
After 1 rip: 1500 pages
After 2 rips: 750 pages
After 3 rips: 375 pages
After 4 rips: 188 pages
After 5 rips: 94 pages

After 12 rips: 1 page

Binary Search

The idea of repeatedly halving the size of the "search space" is the main idea behind the method of binary search.

An item in a sorted array of length n can be located with just $\log_2 n$ comparisons.

Problem

Search a Sorted Array
For a Given Value

(We assume that the array has no repeated elements.)

Binary Search: a = 70

	1	2	3	4	5	6	7	8	9	10	11	12
x:	12	15	33	35	42	45	51	62	73	75	86	98
	↑				↑						↑	

L: 1 $x(\text{Mid}) \leq a$
 Mid: 6 **So throw away the left half...**
 R: 12

Binary Search: a = 70

	1	2	3	4	5	6	7	8	9	10	11	12
x:	12	15	33	35	42	45	51	62	73	75	86	98
						↑		↑				↑

L: 6 $a < x(\text{Mid})$
 Mid: 9 **So throw away the right half...**
 R: 12

Binary Search: a = 70

	1	2	3	4	5	6	7	8	9	10	11	12
x:	12	15	33	35	42	45	51	62	73	75	86	98
						↑	↑		↑			

L: 6 $x(\text{Mid}) \leq a$
 Mid: 7 **So throw away the left half...**
 R: 9

Binary Search: a = 70

	1	2	3	4	5	6	7	8	9	10	11	12
x:	12	15	33	35	42	45	51	62	73	75	86	98
							↑	↑	↑			

L: 7 $x(\text{Mid}) \leq a$
 Mid: 8 **So throw away the left half...**
 R: 9

Binary Search: a = 70

	1	2	3	4	5	6	7	8	9	10	11	12
x:	12	15	33	35	42	45	51	62	73	75	86	98
								↑	↑			

L: 8 **Done because**
 Mid: 8 $R-L = 1$
 R: 9

```

function L = BinarySearch(a,x)
% x is a row n-vector with x(1) < ... < x(n)
% x(1) <= a <= x(n)

% x(L) <= a <= x(L+1)

L = 1; R = length(x);
% x(L) <= a <= x(R)
while R-L > 1
    mid = floor((L+R)/2);
    % Note that mid does not equal L or R.
    if a < x(mid)
        x(L) <= a <= x(mid)
        R = mid;
    else
        x(mid) <= a <= x(R)
        L = mid;
    end
end
end
    
```

Next Problem

Sort the values in an array so that they are arranged from smallest to biggest.

Chosen Method: Merge Sort

This technique is an excellent example of a divide and conquer procedure.

Motivation

A plan if you have two "helpers":

Split the array and have each helper sort his/her half.

Merge the two sorted subarrays.

And what if those two helpers each had two sub-helpers? Etc

Subdivide the Sorting Task

H E M G B K A Q F L P D R C J N

H E M G B K A Q F L P D R C J N

Subdivide Again

□ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □

H E M G B K A Q F L P D R C J N

H E M G B K A Q F L P D R C J N

And Again

□ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □

□ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □

H E M G B K A Q F L P D R C J N

H E M G B K A Q F L P D R C J N

And One Last Time

□ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □

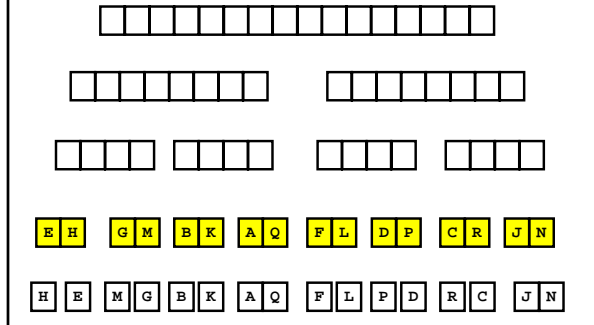
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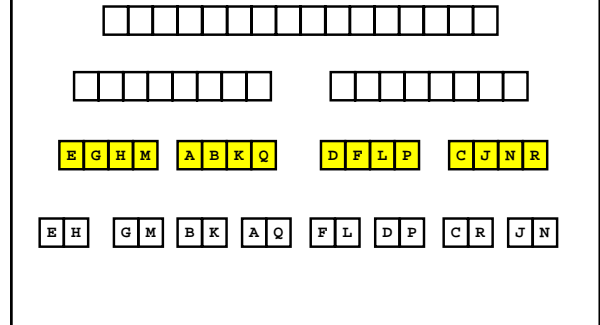
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H E M G B K A Q F L P D R C J N

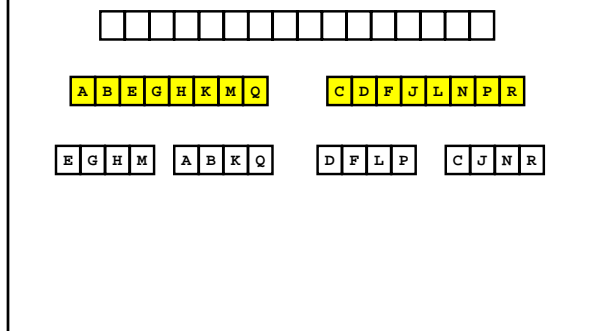
Now Merge



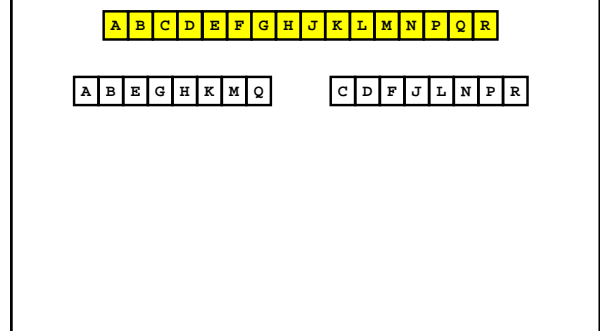
And Merge Again



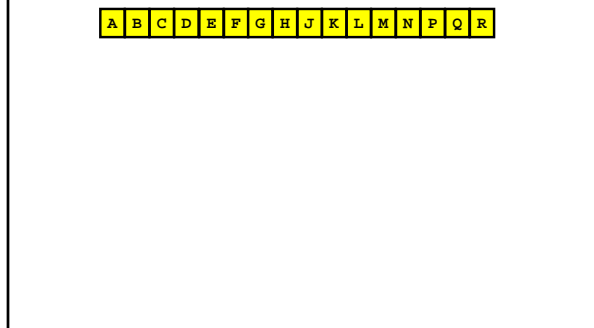
And Again



And One Last Time



Done!



```
function y = MergeSort(x)
% x is a column n-vector.
% y is a column n-vector consisting
% of the values in x sorted
% from smallest to largest.

n = length(x);
if n==1
    y = x;
else
    m = floor(n/2);
    y1 = MergeSort(x(1:m));
    y2 = MergeSort(x(m+1:n));
    y = Merge(y1,y2);
end
```

Important Sub-Problem

Merging Two Sorted Arrays
Into a
Single Sorted Array

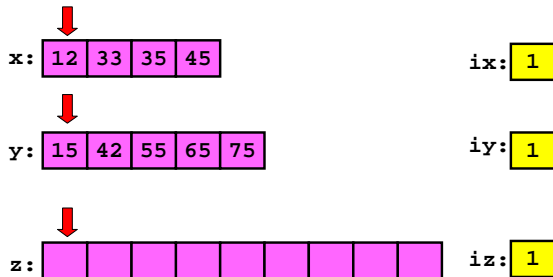
Example

12 33 35 45

15 42 55 65 75

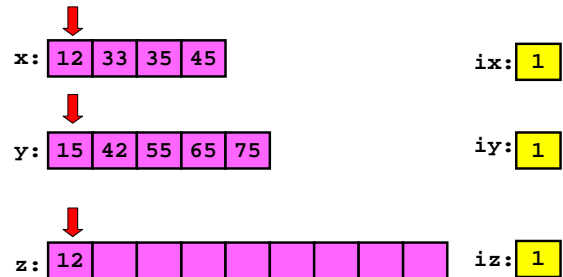
12 15 33 35 42 45 55 65 75

Merge



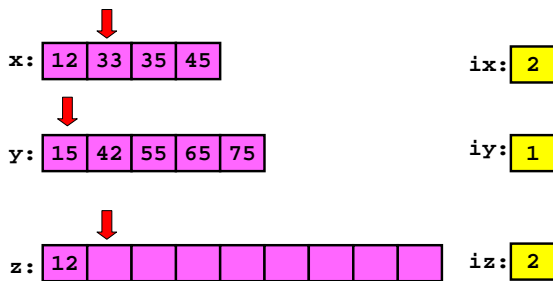
$x(ix) \leq y(iy)$???

Merge



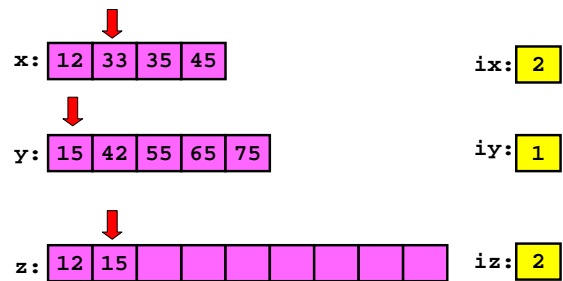
$x(ix) \leq y(iy)$ yes

Merge

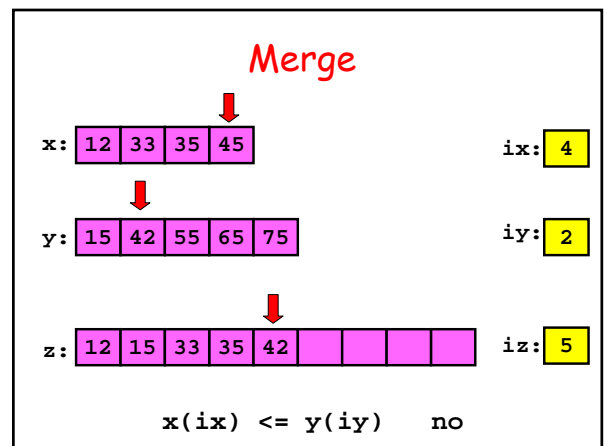
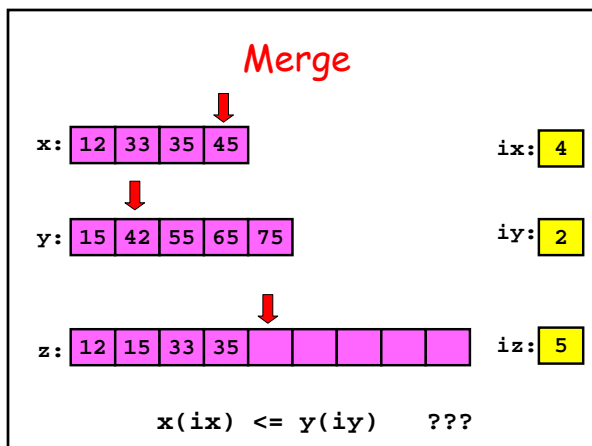
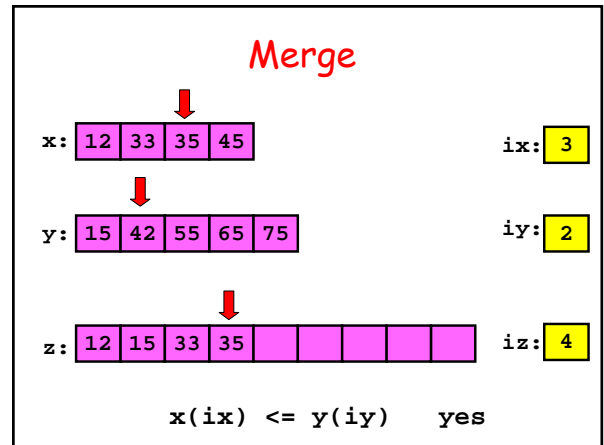
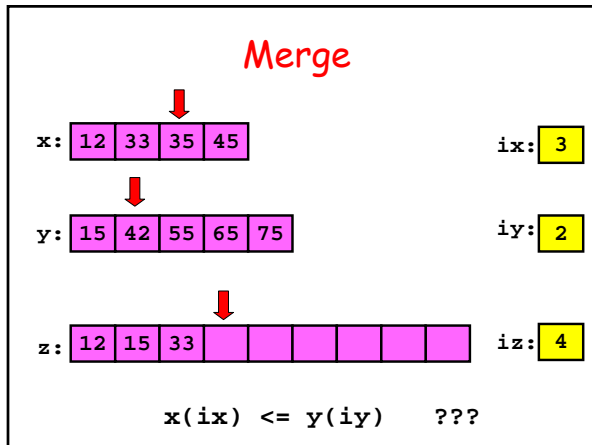
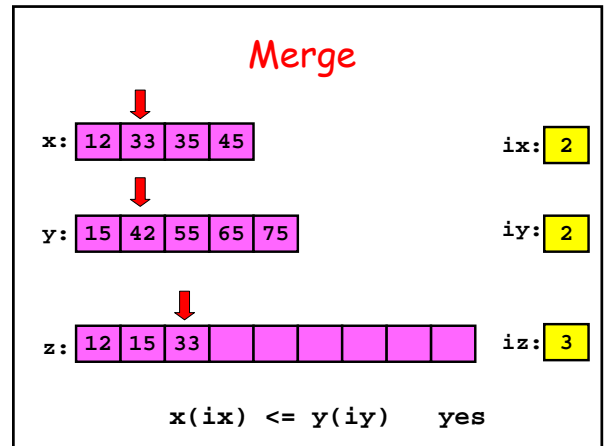
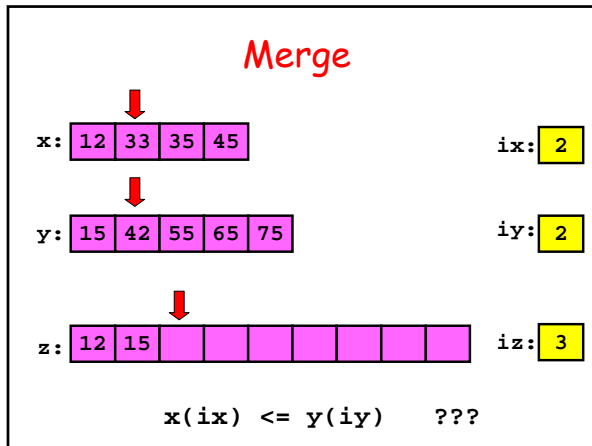


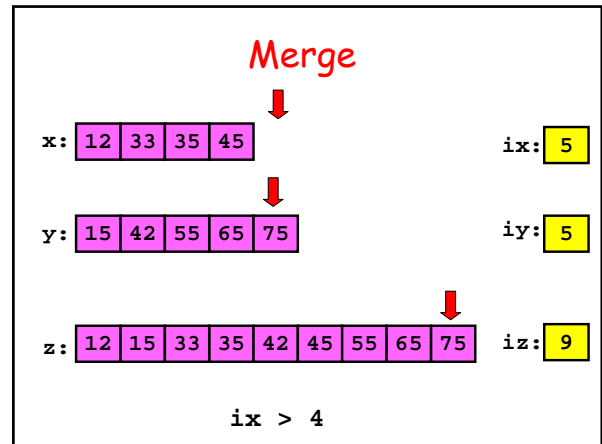
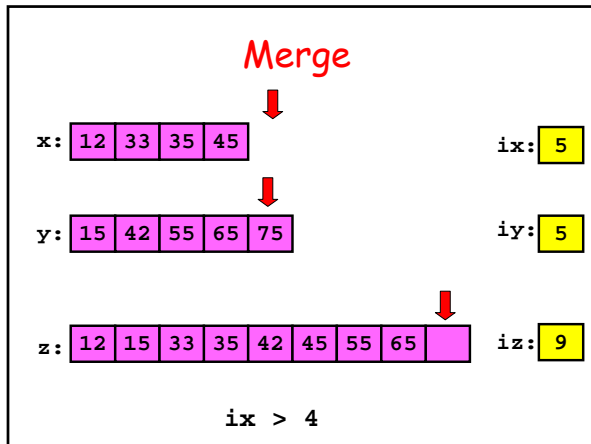
$x(ix) \leq y(iy)$???

Merge



$x(ix) \leq y(iy)$ no





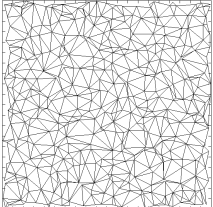
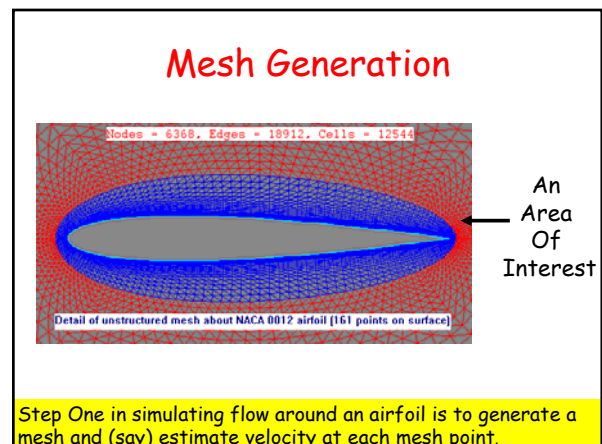
```
function z = Merge(x,y)
n = length(x); m = length(y);
z = zeros(1,n+m);
ix = 1; iy = 1;
for iz=1:(n+m)
    if ix > n
        z(iz) = y(iy); iy = iy+1;
    elseif iy>m
        z(iz) = x(ix); ix = ix + 1;
    elseif x(ix) <= y(iy)
        z(iz) = x(ix); ix = ix + 1;
    else
        z(iz) = y(iy);iy = iy + 1;
    end
end
end
```

New Problem

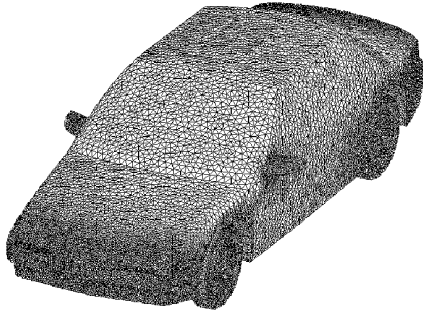
Recursive Mesh Generation

**Divide and Conquer
Methods Also Show Up
in Geometric Situations**

Chop a Region
up into triangles
with smaller
triangles
in "areas of interest".

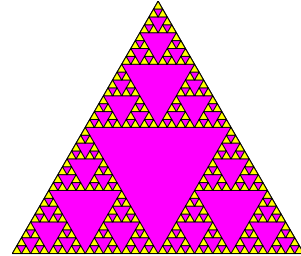



Mesh Generation in 3D



Why is Mesh Generation a Divide & Conquer Process?

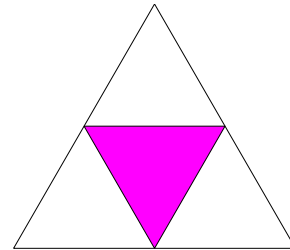
Let Us Draw
this Graphic:



The Basic Operation

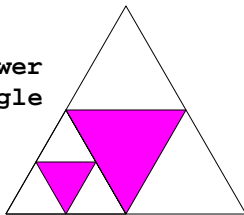
```
if the triangle is big enough  
  
    Connect the midpoints.  
    Color the interior triangle mauve.  
else  
    Color the whole triangle yellow.  
end
```

At the Start...

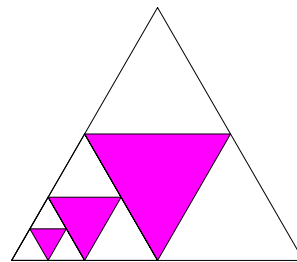


Recur On this Idea

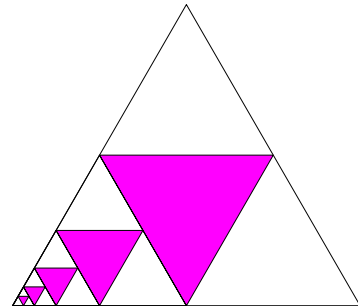
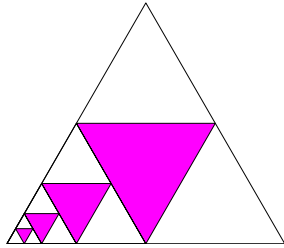
Apply same
idea to lower
left triangle



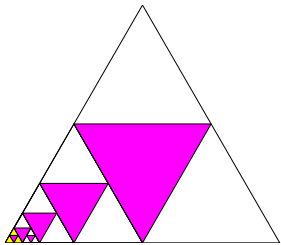
Recur Again



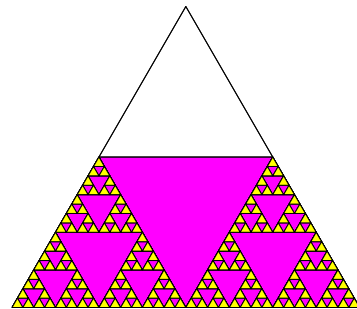
Recursion And Again



Now, Climb Your Way Out.



Etc



```
function MeshTriangle(x,y,L)
if L==0
% No subdivision required...
fill(x,y,'y','linewidth',1.5)
else
% A subdivision is called for. Get midpoints...
a = [(x(1)+x(2))/2 (x(2)+x(3))/2 (x(3)+x(1))/2];
b = [(y(1)+y(2))/2 (y(2)+y(3))/2 (y(3)+y(1))/2];
% Color the interior triangle magenta...
fill(a,b,'m','linewidth',1.5)
% Apply the process to the three "outer" triangles...
MeshTriangle([x(1) a(1) a(3)], [y(1) b(1) b(3)], L-1)
MeshTriangle([x(2) a(2) a(1)], [y(2) b(2) b(1)], L-1)
MeshTriangle([x(3) a(3) a(2)], [y(3) b(3) b(2)], L-1)
end
```