

- Previous Lecture:
  - Linear search, binary search
  - Insertion sort
  - (Reading: Bubble Sort)
- Today's Lecture:
  - Merge Sort
  - What's next?
- Announcements
  - P6 due Thursday at 11pm
  - Final exam: Dec 17<sup>th</sup> 7pm, Barton Indoor Track WEST

# Announcements

- **P6** due Thursday at 11pm
- **Final exam:**
  - Dec 17<sup>th</sup>, 7pm, **Barton Hall Indoor Track WEST**
- Please fill out course evaluation on-line, see “Exercise 16”
- Revised office/consulting hours
- Pick up papers during consulting hours at Carpenter
- **Read announcements on course website!**

# Linear search and binary search

## ■ Linear search

- “Effort” is linearly proportional to  $n$ , the size of the search space (e.g., the length of the vector)
- Can represent effort by the number of comparisons against the search target done during the search

## ■ Binary search

- Effort is proportional to  $\log_2(n)$  where  $n$  is the size of the search space
- Saving of  $\log_2(n)$  over  $n$  is significant when  $n$  is large! But binary search requires sorted vector

Binary search is efficient, but we need to sort the vector in the first place so that we can use binary search

- Many different algorithms out there...
- We saw insertion sort (and read about bubble sort)
- Let's look at **merge sort**
- An example of the “divide and conquer” approach using recursion

Which task is “easier,” **sort a length 1000 array** or **merge\* two length 500 sorted arrays into one?**

A. Sort

B. Merge

\*Merge two sorted arrays so that the resultant array is sorted

Motivation: merging is an easier job than sorting!

If I have two helpers, I'd...

- Give each helper half the array to sort
- Then I get back the sorted subarrays and **merge** them.

What if those two helpers each had two sub-helpers?

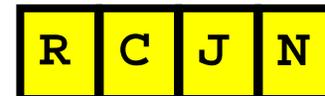
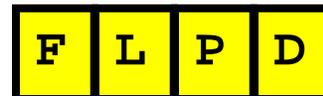
And the sub-helpers each had two sub-sub-helpers? And...

# Subdivide the sorting task

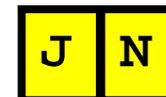
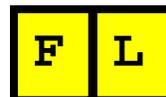
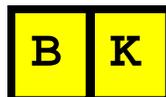
H	E	M	G	B	K	A	Q	F	L	P	D	R	C	J	N
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

H	E	M	G	B	K	A	Q	F	L	P	D	R	C	J	N
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

# Subdivide again



# And again



And one last time



**H** **E**

**M** **G**

**B** **K**

**A** **Q**

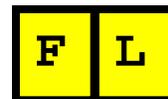
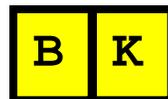
**F** **L**

**P** **D**

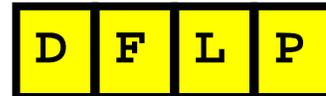
**R** **C**

**J** **N**

Now merge



# And merge again



# And again



## And one last time

A	B	C	D	E	F	G	H	J	K	L	M	N	P	Q	R
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

A	B	E	G	H	K	M	Q
---	---	---	---	---	---	---	---

C	D	F	J	L	N	P	R
---	---	---	---	---	---	---	---

Done!

A	B	C	D	E	F	G	H	J	K	L	M	N	P	Q	R
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

```

function y = mergeSort(x)
% x is a vector.  y is a vector
% consisting of the values in x
% sorted from smallest to largest.

n = length(x);
if n==1
    y = x;
else
    m = floor(n/2);
    yL = mergeSortL(x(1:m));
    yR = mergeSortR(x(m+1:n));
    y = merge(yL,yR);
end

```

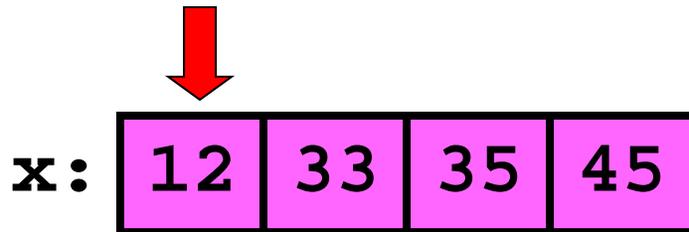
The central sub-problem is the **merging** of two sorted arrays into one single sorted array

12	33	35	45
----	----	----	----

15	42	55	65	75
----	----	----	----	----

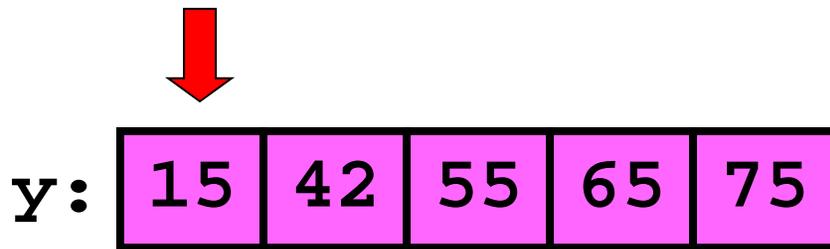
12	15	33	35	42	45	55	65	75
----	----	----	----	----	----	----	----	----

# Merge



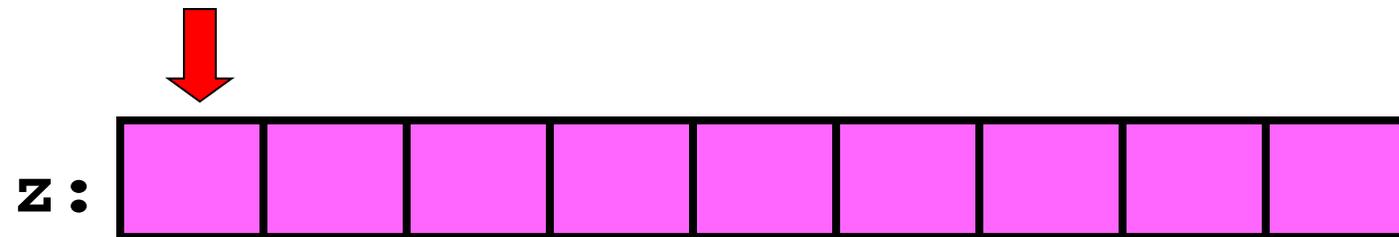
**ix:**

1
---



**iy:**

1
---



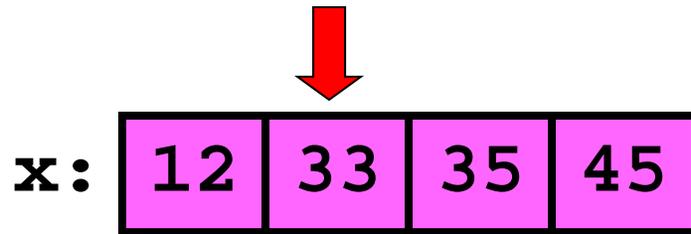
**iz:**

1
---

**ix** ≤ 4 and **iy** ≤ 5: **x**(**ix**) ≤ **y**(**iy**) ???

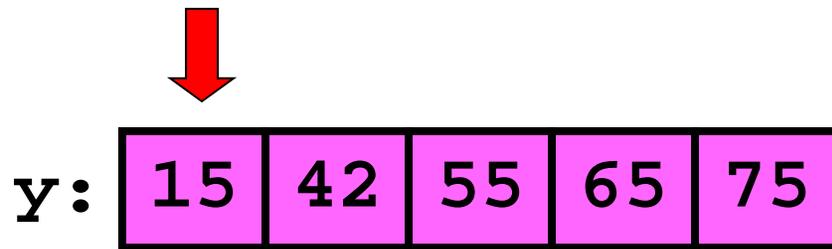


# Merge



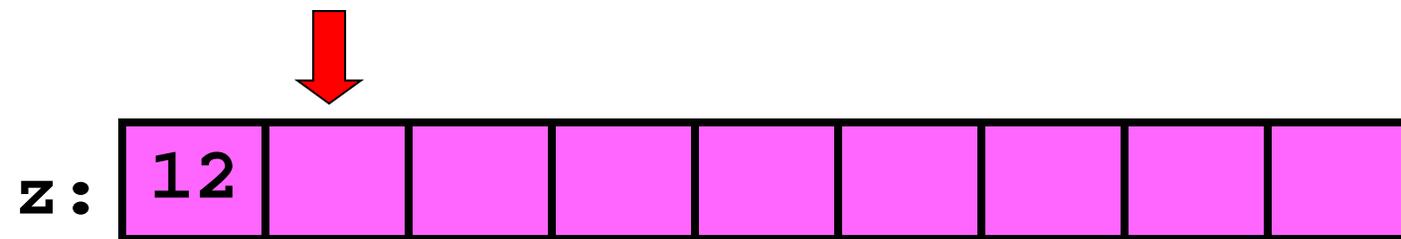
**ix:**

2
---



**iy:**

1
---

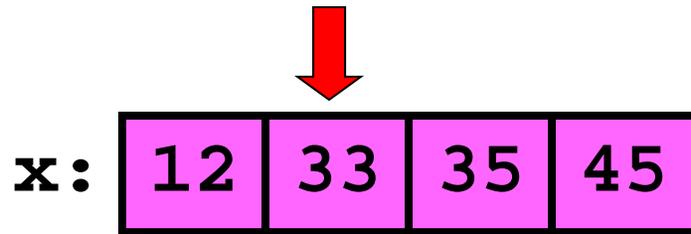


**iz:**

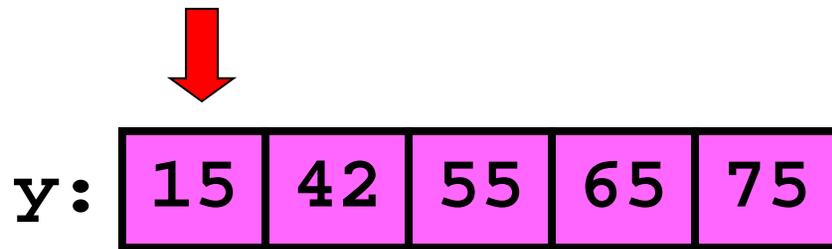
2
---

**ix** ≤ 4 and **iy** ≤ 5: **x**(**ix**) ≤ **y**(**iy**) ???

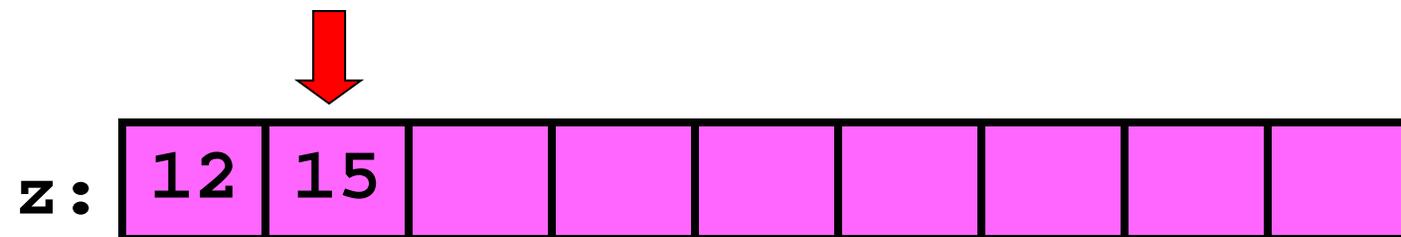
# Merge



ix: 2



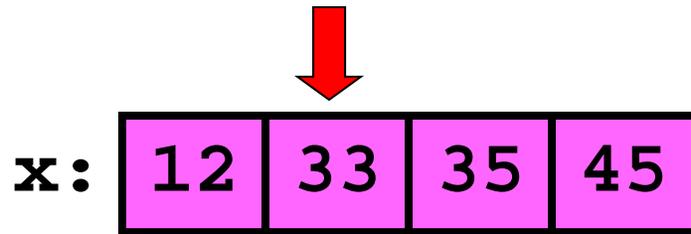
iy: 1



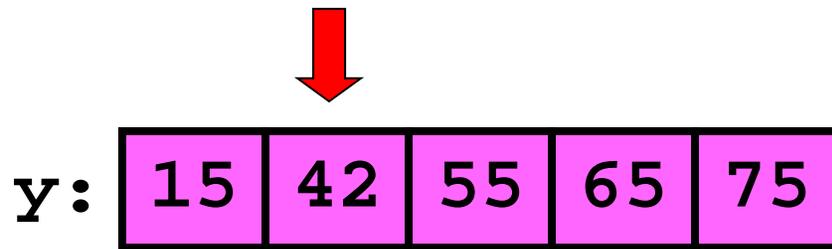
iz: 2

$ix \leq 4$  and  $iy \leq 5$ :  $x(ix) \leq y(iy)$  NO

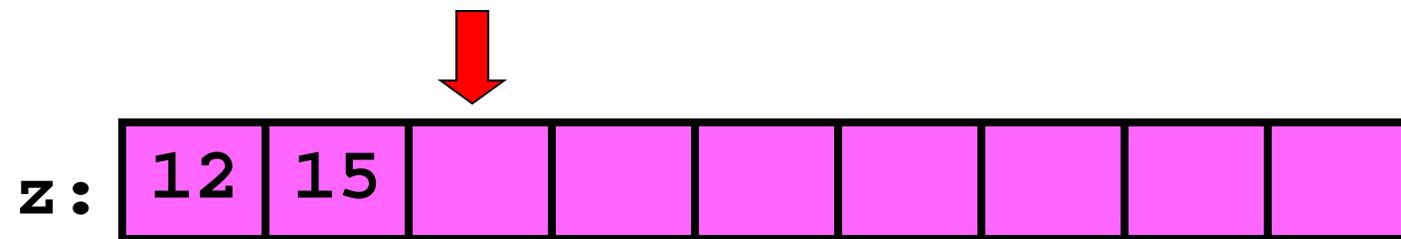
# Merge



**ix:** [ 2 ]



**iy:** [ 2 ]



**iz:** [ 3 ]

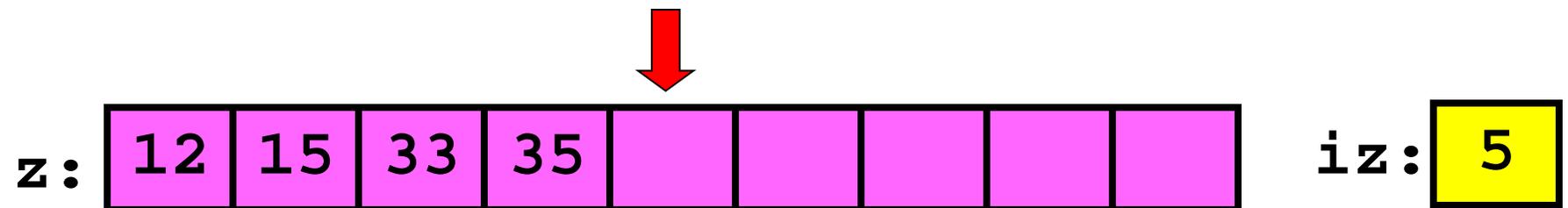
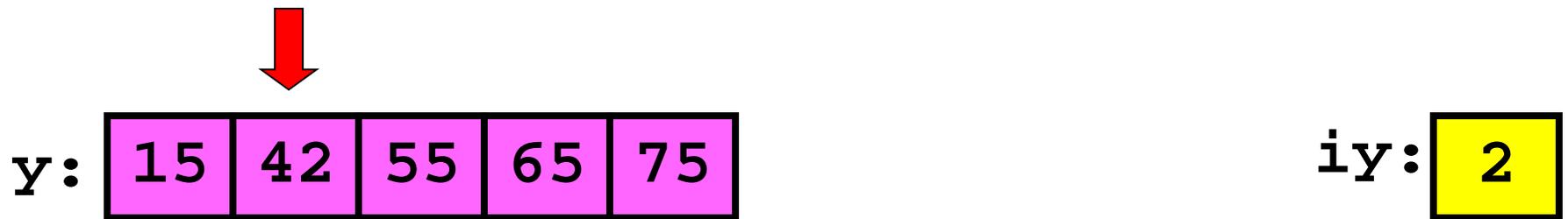
**ix** ≤ 4 and **iy** ≤ 5: **x**(**ix**) ≤ **y**(**iy**) ???





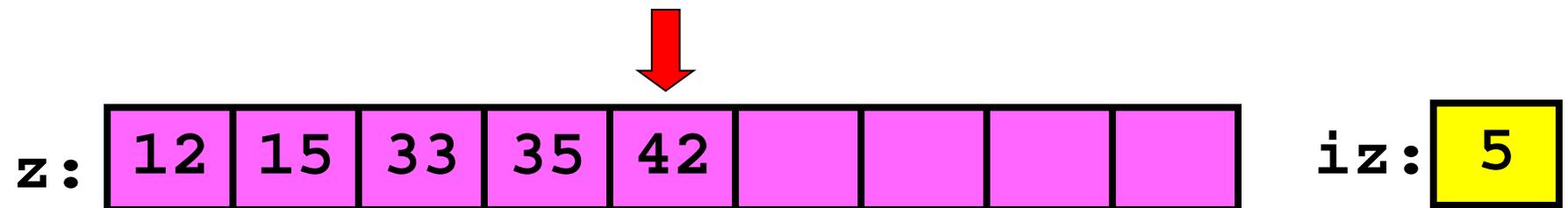
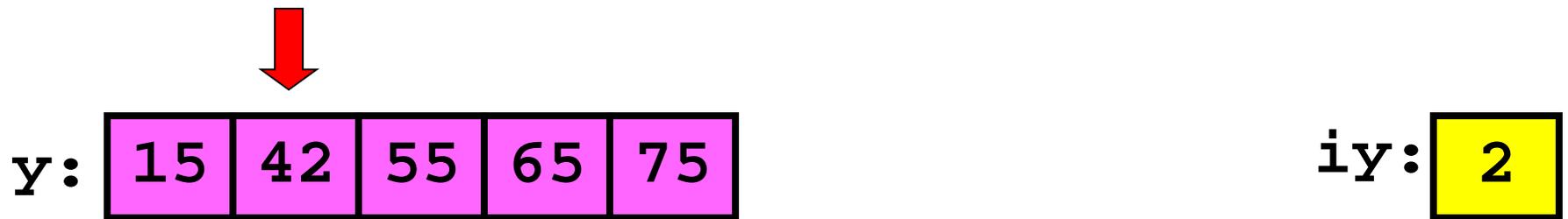


# Merge



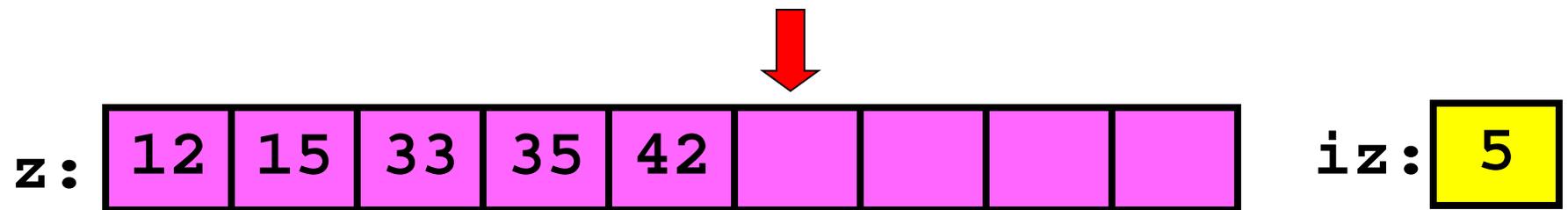
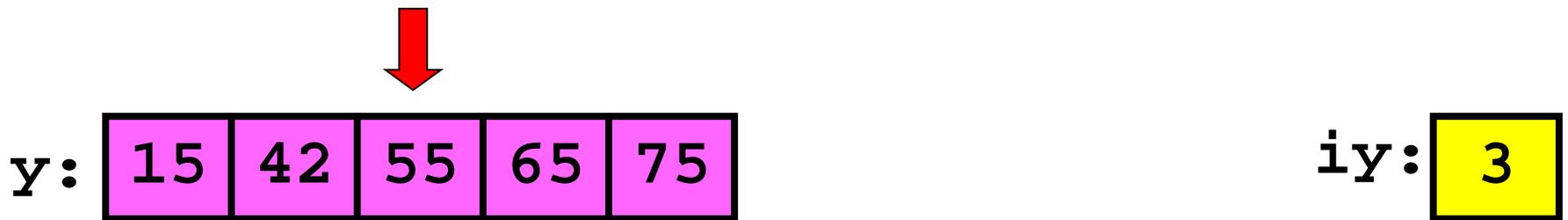
**ix** ≤ 4 and **iy** ≤ 5: **x**(**ix**) ≤ **y**(**iy**) ???

# Merge



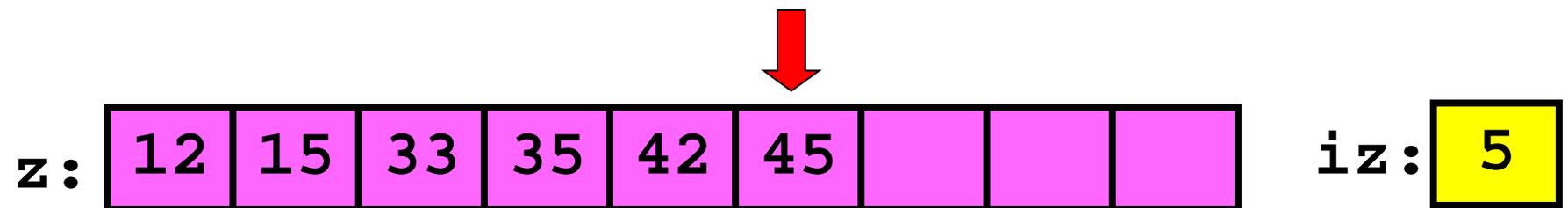
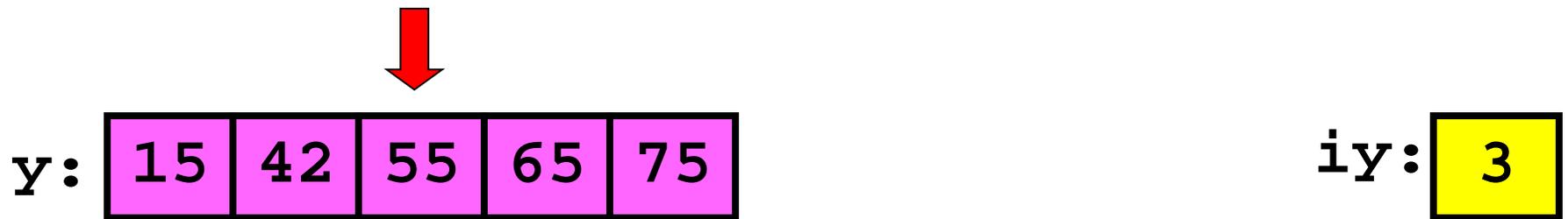
$ix \leq 4$  and  $iy \leq 5$ :  $x(ix) \leq y(iy)$  **NO**

# Merge



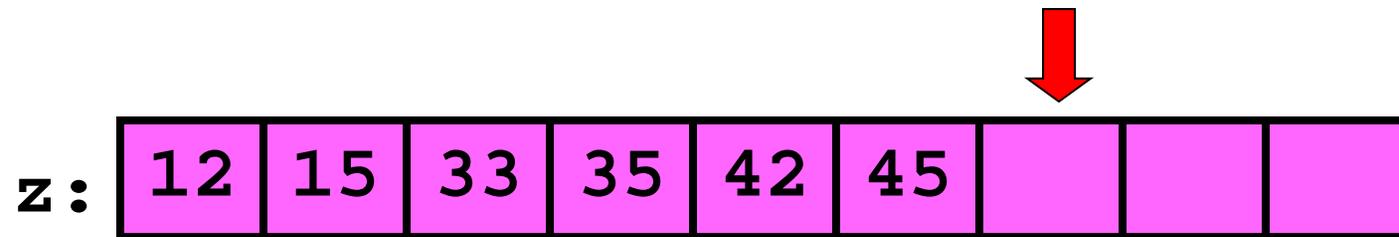
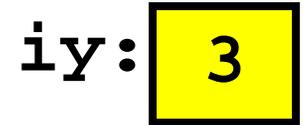
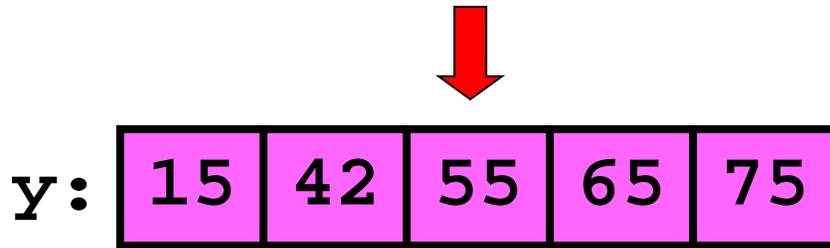
$ix \leq 4$  and  $iy \leq 5$ :  $x(ix) \leq y(iy)$  ???

# Merge



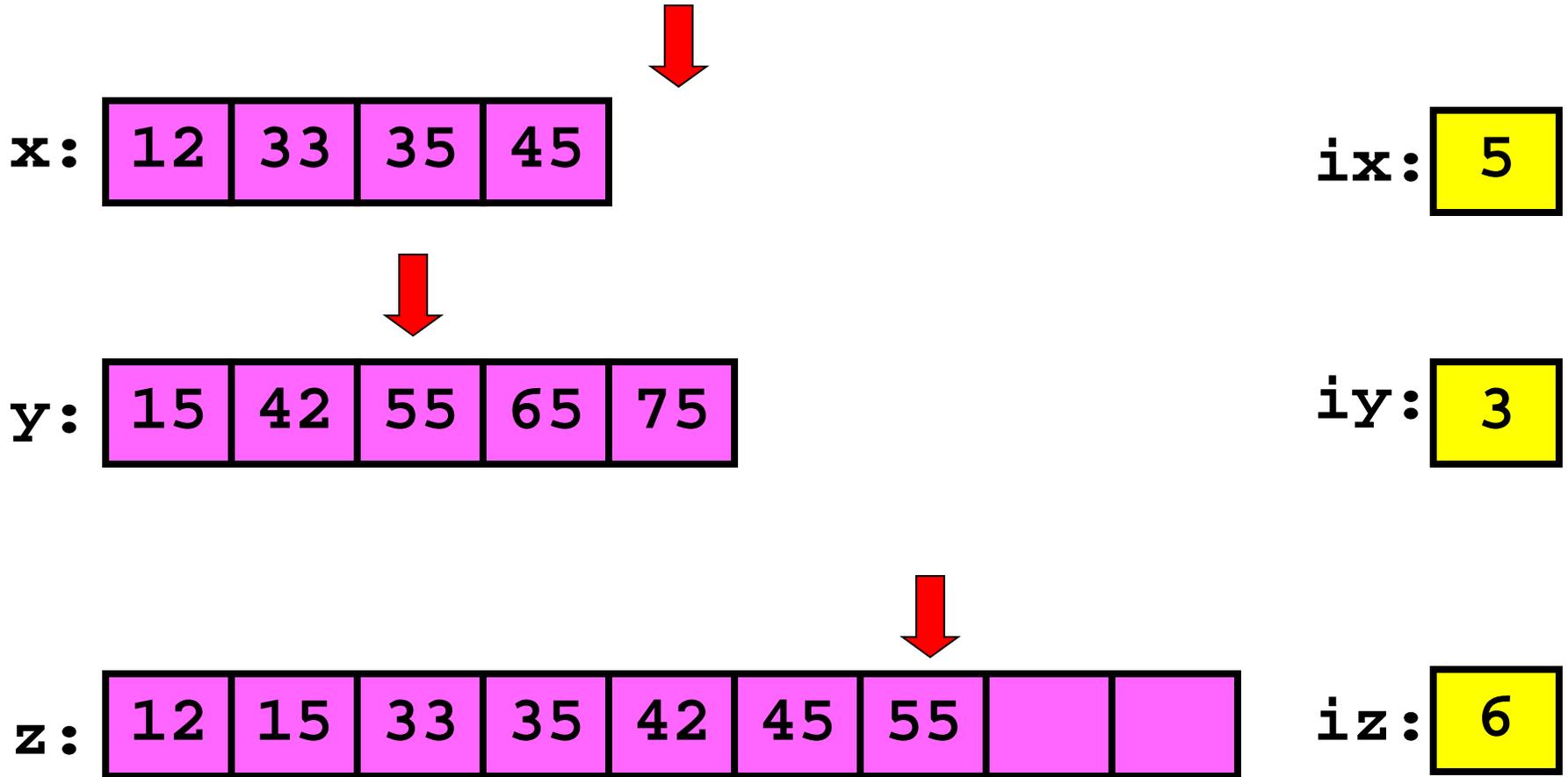
**ix** ≤ 4 and **iy** ≤ 5: **x(ix)** ≤ **y(iy)** **YES**

Merge



$ix > 4$

# Merge



**ix > 4: take y(iy)**

Merge



x: 

12	33	35	45
----	----	----	----

ix: 

5
---



y: 

15	42	55	65	75
----	----	----	----	----

iy: 

4
---



z: 

12	15	33	35	42	45	55		
----	----	----	----	----	----	----	--	--

iz: 

8
---

$iy \leq 5$

Merge



x: 

12	33	35	45
----	----	----	----

ix: 

5
---



y: 

15	42	55	65	75
----	----	----	----	----

iy: 

4
---



z: 

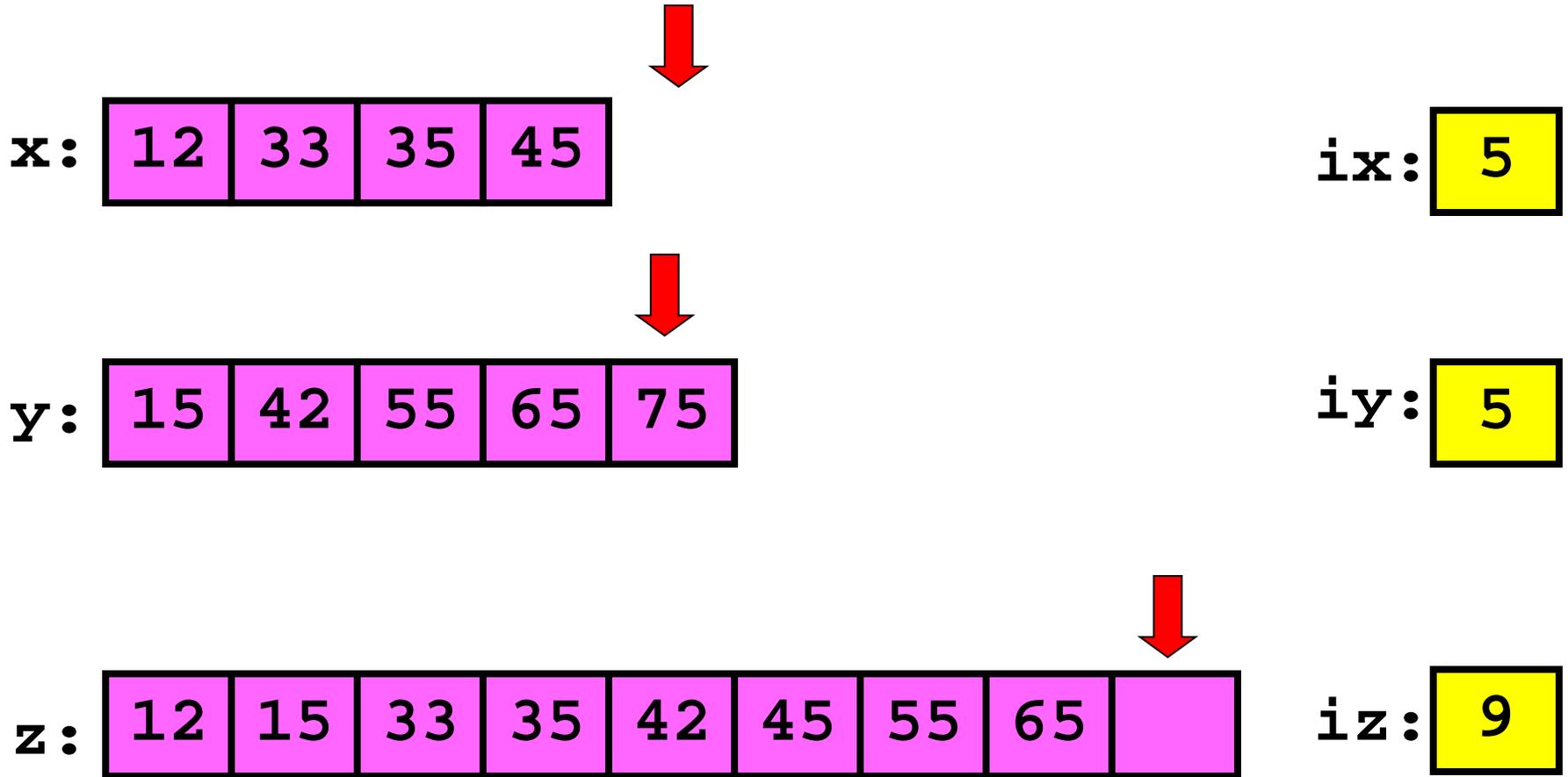
12	15	33	35	42	45	55	65	
----	----	----	----	----	----	----	----	--

iz: 

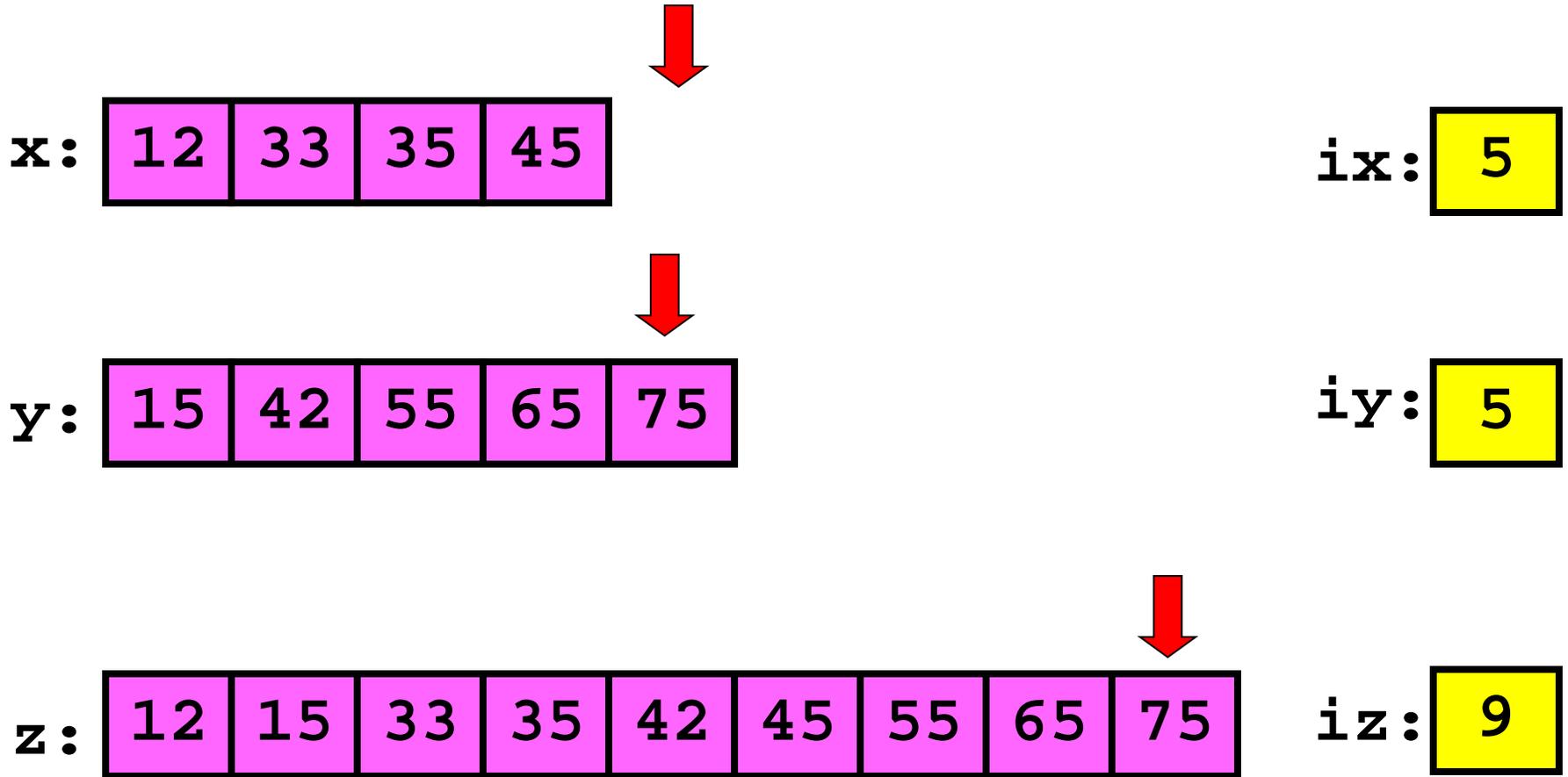
8
---

$iy \leq 5$

# Merge



# Merge



$iy \leq 5$

```
function z = merge(x,y)
nx = length(x); ny = length(y);
z = zeros(1, nx+ny);
ix = 1; iy = 1; iz = 1;
```

```
function z = merge(x,y)
nx = length(x); ny = length(y);
z = zeros(1, nx+ny);
ix = 1; iy = 1; iz = 1;
while ix<=nx && iy<=ny

end
% Deal with remaining values in x or y
```

```
function z = merge(x,y)
nx = length(x); ny = length(y);
z = zeros(1, nx+ny);
ix = 1; iy = 1; iz = 1;
while ix<=nx && iy<=ny
    if x(ix) <= y(iy)
        z(iz)= x(ix); ix=ix+1; iz=iz+1;
    else
        z(iz)= y(iy); iy=iy+1; iz=iz+1;
    end
end
end
% Deal with remaining values in x or y
```

```
function z = merge(x,y)
nx = length(x); ny = length(y);
z = zeros(1, nx+ny);
ix = 1; iy = 1; iz = 1;
while ix<=nx && iy<=ny
    if x(ix) <= y(iy)
        z(iz)= x(ix); ix=ix+1; iz=iz+1;
    else
        z(iz)= y(iy); iy=iy+1; iz=iz+1;
    end
end
while ix<=nx % copy remaining x-values
    z(iz)= x(ix); ix=ix+1; iz=iz+1;
end
while iy<=ny % copy remaining y-values
    z(iz)= y(iy); iy=iy+1; iz=iz+1;
end
```

```

function y = mergeSort(x)
% x is a vector.  y is a vector
% consisting of the values in x
% sorted from smallest to largest.

n = length(x);
if n==1
    y = x;
else
    m = floor(n/2);
    yL = mergeSortL(x(1:m));
    yR = mergeSortR(x(m+1:n));
    y = merge(yL,yR);
end

```

```

function y = mergeSortL(x)
% x is a vector.  y is a vector
% consisting of the values in x
% sorted from smallest to largest.

n = length(x);
if n==1
    y = x;
else
    m = floor(n/2);
    yL = mergeSortL_L(x(1:m));
    yR = mergeSortL_R(x(m+1:n));
    y = merge(yL,yR);
end

```

```

function y = mergeSortL_L(x)
% x is a vector.  y is a vector
% consisting of the values in x
% sorted from smallest to largest.

n = length(x);
if n==1
    y = x;
else
    m = floor(n/2);
    yL = mergeSortL_L_L(x(1:m));
    yR = mergeSortL_L_R(x(m+1:n));
    y = merge(yL,yR);
end

```

```

function y = mergeSort(x)
% x is a vector.  y is a vector
% consisting of the values in x
% sorted from smallest to largest.

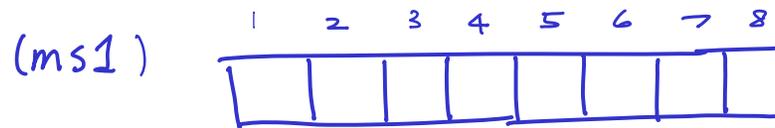
n = length(x);
if n==1
    y = x;
else
    m = floor(n/2);
    yL = mergeSort(x(1:m));
    yR = mergeSort(x(m+1:n));
    y = merge(yL,yR);
end

```

```
function y=mergeSort(x)
n=length(x);
if n==1
    y=x;
else
    m=floor(n/2);
    yL=mergeSort(x(1:m));
    yR=mergeSort(x(m+1:n));
    y=merge(yL,yR);
end
```

```
function y=mergeSort(x)
n=length(x);
if n==1
    y=x;
else
    m=floor(n/2);
    yL=mergeSort(x(1:m));
    yR=mergeSort(x(m+1:n));
    y=merge(yL,yR);
end
```

mergeSort — 1<sup>st</sup> call

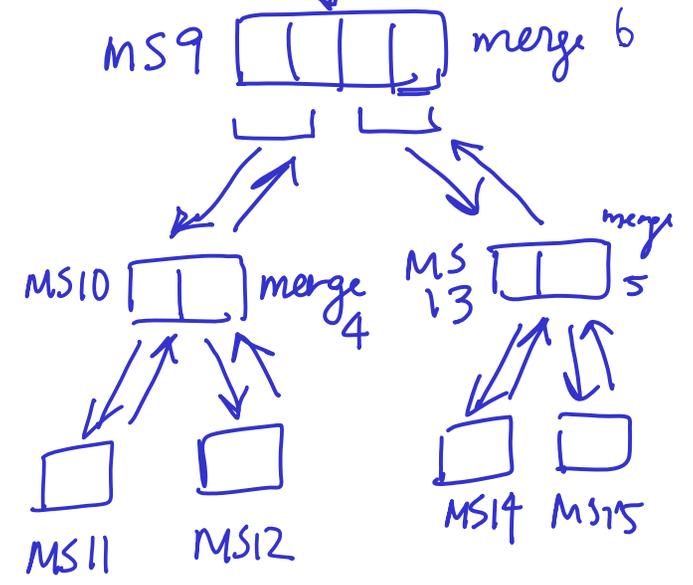
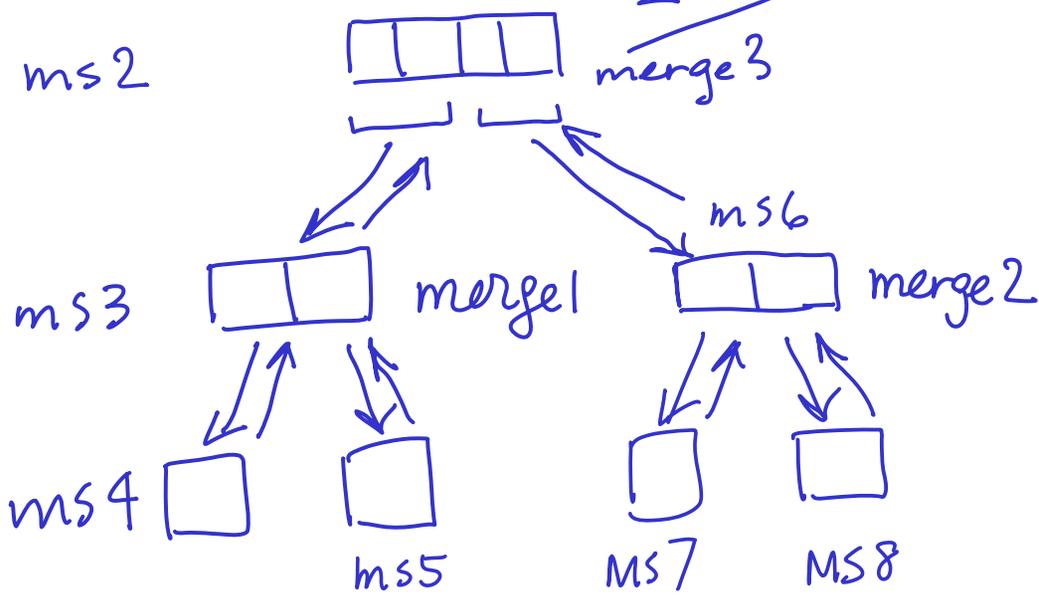
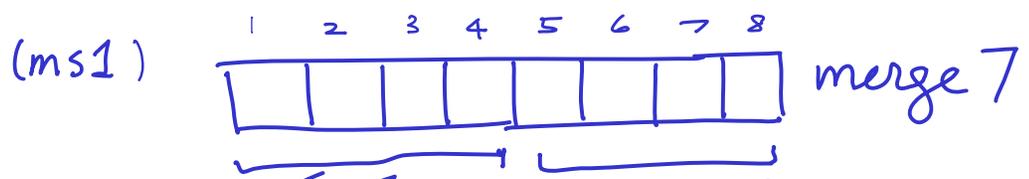


```

function y=mergeSort(x)
n=length(x);
if n==1
    y=x;
else
    m=floor(n/2);
    yL=mergeSort(x(1:m));
    yR=mergeSort(x(m+1:n));
    y=merge(yL,yR);
end

```

mergeSort - 1<sup>st</sup> call

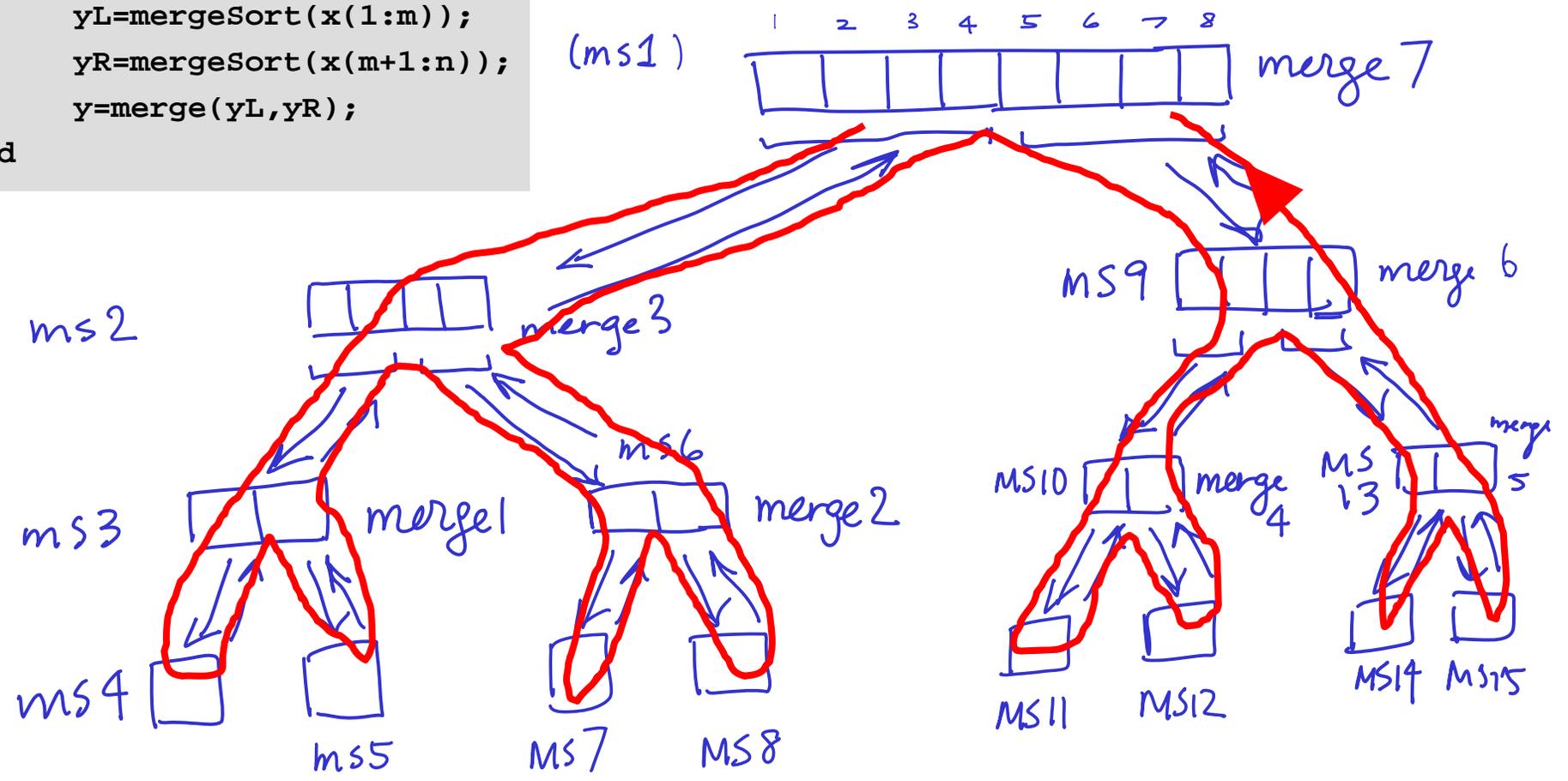


```

function y=mergeSort(x)
n=length(x);
if n==1
    y=x;
else
    m=floor(n/2);
    yL=mergeSort(x(1:m));
    yR=mergeSort(x(m+1:n));
    y=merge(yL,yR);
end

```

mergeSort - 1<sup>st</sup> call



How do merge sort, insertion sort, and bubble sort compare?

- Insertion sort and bubble sort are similar
  - Both involve a series of comparisons and swaps
  - Both involve nested loops
- Merge sort uses recursion

`See InsertionSort.m`

```

function x = insertSort(x)
% Sort vector x in ascending order with insertion sort

n = length(x);
for i= 1:n-1

    % Sort x(1:i+1) given that x(1:i) is sorted
    j= i;
    while  j>0 && x(j+1)<x(j)

        % swap x(j+1) and x(j)
        temp= x(j);
        x(j)= x(j+1);
        x(j+1)= temp;

        j= j-1;

    end
end
end

```

## How do merge sort and insertion sort compare?

- Insertion sort: (worst case) makes  $k$  comparisons to insert an element in a sorted array of  $k$  elements. For an array of length  $N$ :

$$1+2+\dots+(N-1) = N(N-1)/2, \text{ say } N^2 \text{ for big } N$$

- Merge sort:

```
function y = mergeSort(x)
% x is a vector.  y is a vector
% consisting of the values in x
% sorted from smallest to largest.
```

```
n = length(x);
if n==1
    y = x;
else
    m = floor(n/2);
    yL = mergeSort(x(1:m));
    yR = mergeSort(x(m+1:n));
    y = merge(yL,yR);
end
```

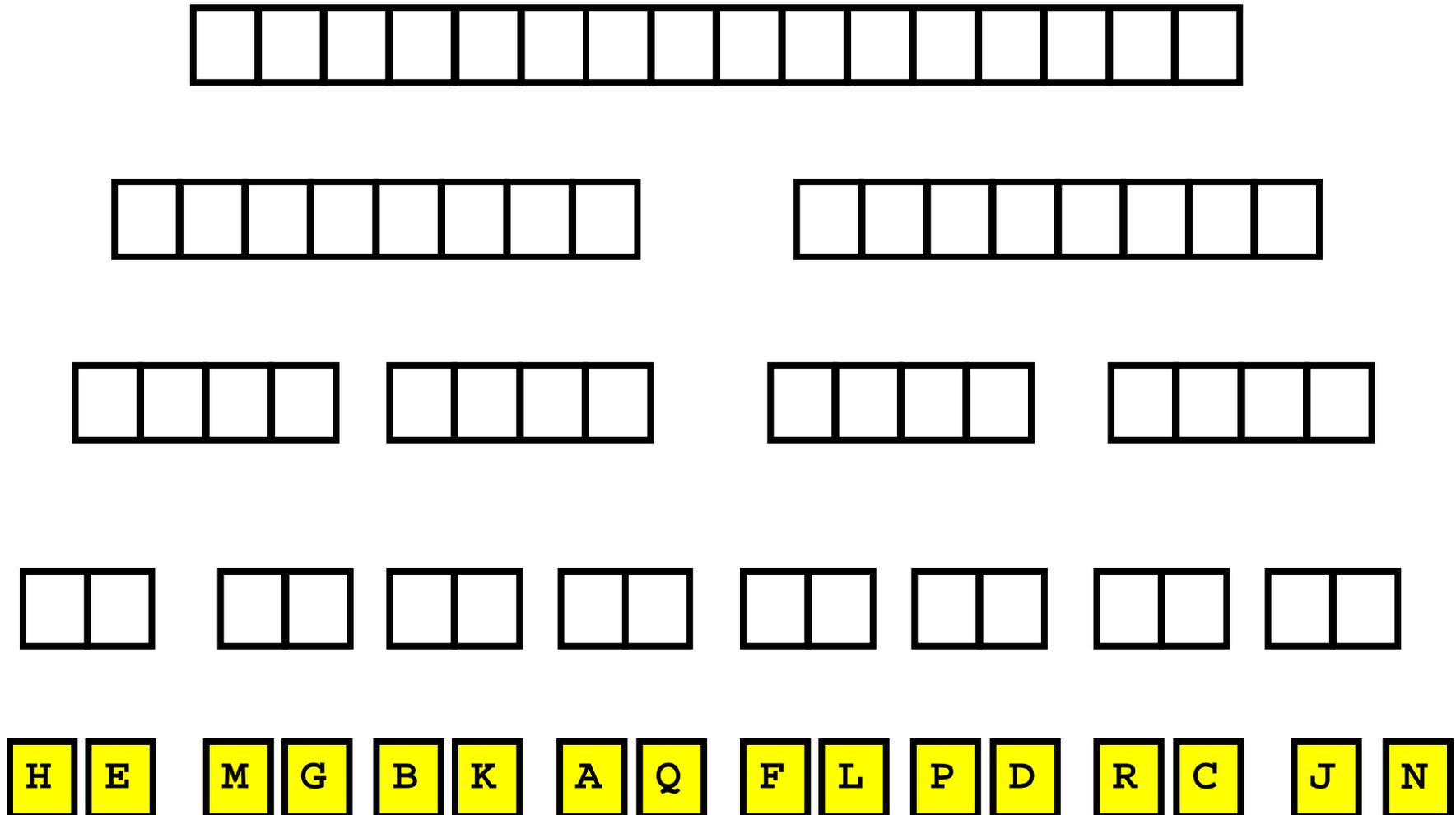
All the comparisons between  
vector values are done in merge

```

function z = merge(x,y)
nx = length(x); ny = length(y);
z = zeros(1, nx+ny);
ix = 1; iy = 1; iz = 1;
while ix<=nx && iy<=ny
    if x(ix) <= y(iy)
        z(iz)= x(ix); ix=ix+1; iz=iz+1;
    else
        z(iz)= y(iy); iy=iy+1; iz=iz+1;
    end
end
while ix<=nx % copy remaining x-values
    z(iz)= x(ix); ix=ix+1; iz=iz+1;
end
while iy<=ny % copy remaining y-values
    z(iz)= y(iy); iy=iy+1; iz=iz+1;
end

```

Merge sort:  $\log_2(N)$  “levels”;  $N$  comparisons each level



## How do merge sort and insertion sort compare?

- Insertion sort: (worst case) makes  $i$  comparisons to insert an element in a sorted array of  $i$  elements. For an array of length  $N$ :

$$1+2+\dots+(N-1) = N(N-1)/2, \text{ say } N^2 \text{ for big } N$$

$O(N^2)$

- Merge sort:  $N \cdot \log_2(N)$

$O(N \log_2(N))$

Order of magnitude

- Insertion sort is done *in-place*; merge sort (recursion) requires much more memory

See `compareInsertMerge.m`

## How to choose??

- Depends on application
- Merge sort is especially good for sorting **large data set** (but watch out for memory usage)
- Insertion sort is “order  $N^2$ ” at **worst case**, but what about an **average case**? If the application requires that you *maintain* a sorted array, insertion sort may be a good choice

# Why not just use Matlab's sort function?

- **Flexibility**
- E.g., to maintain a sorted list, just write the code for insertion sort
- E.g., sort strings or other complicated structures
- Sort according to some criterion set out in a function file
  - Observe that we have the comparison  $x(j+1) < x(j)$
  - The comparison can be a function that returns a **boolean** value
- Can combine different sort/search algorithms for specific problem

## We've reached the end of CS1112... now what?

- Continue practicing your problem solving—  
problem decomposition—skills, in programming  
and other arenas!
- Interested in further study?
  - ENGRD/CS 2110 Object-oriented programming and  
data structure

# ENGRG/CS 2110 OOP and Data Structures

- Learn new programming concepts and further explores those you've seen in CS1112
  - OOP, program design and development
  - Recursion
  - Complex data structures and related algorithms
- Taught in **Java**
- Optional **CS 2111** meets 1 hr/week; additional practice with OOP, Java, and other course topics
- During break, check out this website:  
<http://www.cs.cornell.edu/courses/CS1130/2014sp/>

## We've reached the end of CS112... now what?

- Continue practicing your problem solving—problem decomposition—skills, in programming and other arenas!
- Interested in further study?
  - ENGRD/CS 2110 Object-oriented programming and data structure
  - Short courses in Python (CS 1133), C++ (CS 2024), ..., etc.
  - More general CS courses: CS 2800 Discrete structures, CS 2850 Networks

## What we learned...

- Develop/implement **algorithms** for problems
- Develop programming skills
  - Design, implement, document, test, and debug
- Programming “tool bag”
  - Functions for reducing redundancy
  - Control flow (if-else; loops)
  - Recursion
  - Data structures
  - Graphics
  - File handling

## What we learned... (cont'd)

- Applications and concepts
  - Image processing
  - Object-oriented programming
  - Sorting and searching—you should know the algorithms covered
  - Divide-and-conquer strategies
  - Approximation and error
  - Simulation
  - Computational effort and efficiency

# Computing gives us *insight* into a problem

- Computing is not about getting one answer!
- We build models and write programs so that we can “play” with the models and programs, learning—gaining insights—as we vary the parameters and assumptions
- Good models require domain-specific knowledge (and experience)
- Good programs ...
  - are modular and cleanly organized
  - are well-documented
  - use appropriate data structures and algorithms
  - are reasonably efficient in time and memory

# Final Exam

- Dec 17, 7-9:30pm, Barton Hall indoor tracks WEST
- Covers entire course; some emphasis on material after Prelim 2
- Closed-book exam, no calculators
- Bring student ID card
  
- Check for announcements on webpage:
  - Study break office/consulting hours
  - Review session time and location
  - Review questions
  - List of potentially useful functions

## Final Exam

- Dec 17, 7-9:30pm, Barton Hall indoor tracks WEST
- Covers entire course; some emphasis on material of Prelim 2
- Closed-book exam
- Bring

Best wishes  
and  
good luck with all your exams!

List of potentially useful functions