

- Previous Lecture:

- Nested loops
- Developing algorithms and code

- Today's Lecture:

- Review nested loops
- User-defined functions

- Announcements:

- Discussion this week in Upson B7 lab. [Read \*Insight\* §3.2](#) before discussion.
- Project 2 due Thursday at 11pm

## Rational approximation of $\pi$

- $\pi = 3.141592653589793\dots$
- Can be closely approximated by fractions, e.g.,  $\pi \approx 22/7$
- Rational number: a quotient of two integers
- Approximate  $\pi$  as  $p/q$  where  $p$  and  $q$  are positive integers  $\leq M$
- Start with a straight forward solution:
  - Get  $M$  from user
  - Calculate quotient  $p/q$  for all combinations of  $p$  and  $q$
  - Pick best quotient  $\rightarrow$  smallest error

```
% Rational approximation of pi
```

```
M = input('Enter M: ');
```

```
% Check all possible denominators
```

```
% Rational approximation of pi
```

```
M = input('Enter M: ');
```

```
% Check all possible denominators
```

```
for q = 1:M
```

```
end
```

```
% Rational approximation of pi
```

```
M = input('Enter M: ');
```

```
% Check all possible denominators
```

```
for q = 1:M
```

For current q find best numerator p...  
Check all possible numerators

```
end
```

```
% Rational approximation of pi

M = input('Enter M: ');

% Check all possible denominators
for q = 1:M
    % At this q, check all possible numerators
    for p = 1:M

        end
    end
end
```

```
% Rational approximation of pi

M = input('Enter M: ');
% Best q, p, and error so far
qBest=1;  pBest=1;
err_pq = abs(pBest/qBest - pi);

% Check all possible denominators
for q = 1:M
    % At this q, check all possible numerators
    for p = 1:M

        end

    end

end

myPi = pBest/qBest;
```

```

% Rational approximation of pi

M = input('Enter M: ');
% Best q, p, and error so far
qBest=1;  pBest=1;
err_pq = abs(pBest/qBest - pi);

% Check all possible denominators
for q = 1:M
    % At this q, check all possible numerators
    for p = 1:M
        if abs(p/q - pi) < err_pq % best p/q found
            err_pq = abs(p/q - pi);
            pBest= p;
            qBest= q;
        end
    end
end

myPi = pBest/qBest;

```



```
% Complicated version in the book
```

```
M = input('Enter M: ');
```

```
% Best q, p, and error so far
```

```
qBest=1; pBest=1;
```

```
err_pq = abs(pBest/qBest - pi);
```

```
% Check all possible denominators
```

```
for q = 1:M
```

```
    % At this q, check all possible numerators
```

```
    p0=1; e0=abs(p0/q - pi); % best p & error so far
```

```
    for p = 1:M
```

```
        if abs(p/q - pi) < e0 % new best numerator found
```

```
            p0=p; e0 = abs(p/q - pi);
```

```
        end
```

```
    end
```

```
% Is best quotient for this q is best over all?
```

```
if e0 < err_pq
```

```
    pBest=p0; qBest=q; err_pq=e0;
```

```
end
```

```
end
```

```
myPi = pBest/qBest;
```

```

% Rational approximation of pi

M = input('Enter M: ');
% Best q, p, and error so far
qBest=1;  pBest=1;
err_pq = abs(pBest/qBest - pi);

% Check all possible denominators
for q = 1:M
    % At this q, check all possible numerators
    for p = 1:M
        if abs(p/q - pi) < err_pq % best p/q found
            err_pq = abs(p/q - pi);
            pBest= p;
            qBest= q;
        end
    end
end

myPi = pBest/qBest;

```

## Analyze the program for efficiency

- See Eg3\_1 and FasterEg3\_1 in the book

```
for a = 1:n
    disp('alpha')
    for b = 1:m
        disp('beta')
    end
end
```

How many times are “alpha”  
and “beta” displayed?

A:  $n, m$

B:  $m, n$

C:  $n, n+m$

D:  $n, n*m$

E:  $m*n, m$

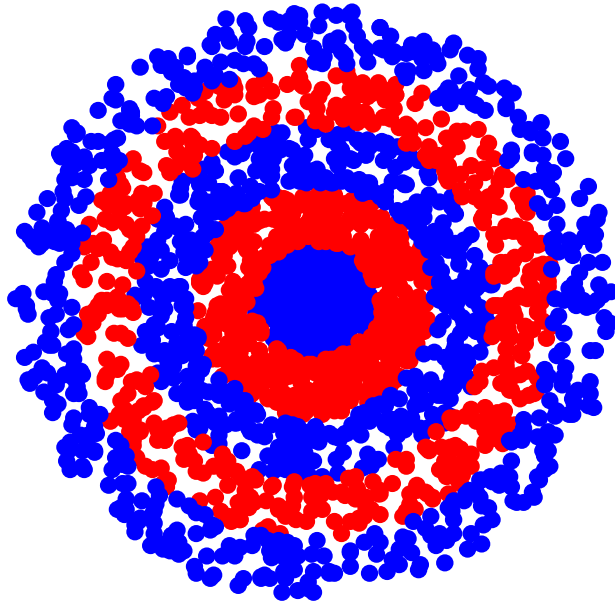
## Built-in functions

- We've used many Matlab built-in functions, e.g., **rand**, **abs**, **floor**, **rem**
- Example: **abs(x - .5)**
- Observations:
  - **abs** is set up to be able to work with any valid data
  - **abs** doesn't prompt us for input; it expects that we provide data that it'll then work on

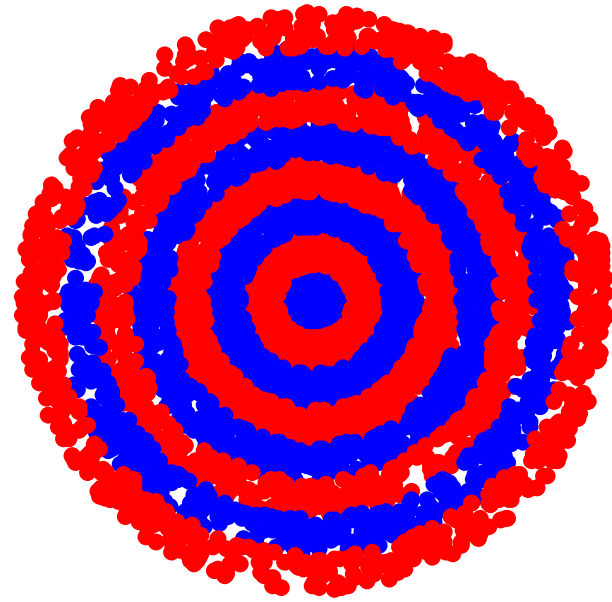
# User-defined functions

- We can write our own functions to perform a specific task
  - **Example:** draw a disk with specified radius, color, and center coordinates
  - **Example:** generate a random floating point number in a specified interval
  - **Example:** convert polar coordinates to x-y (Cartesian) coordinates

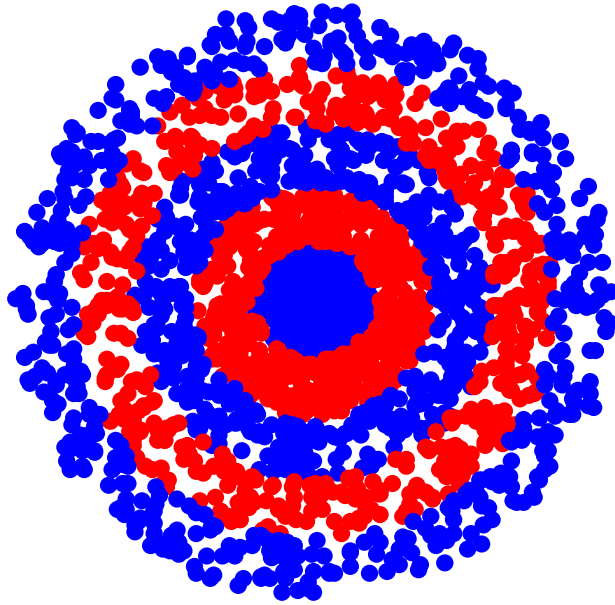
# Draw a bulls eye figure with randomly placed dots



- Dots are randomly placed within concentric rings
- User decides how many rings, how many dots

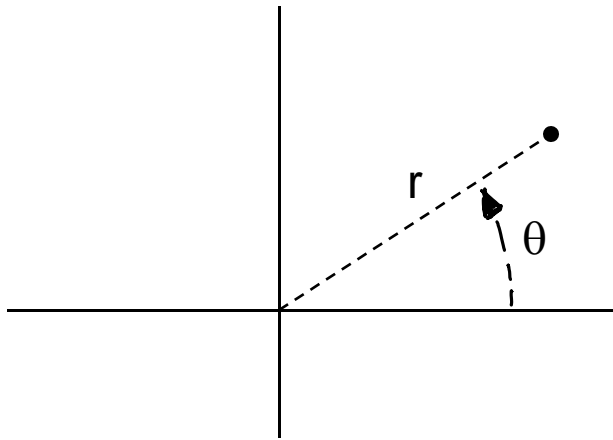


# Draw a bulls eye figure with randomly placed dots

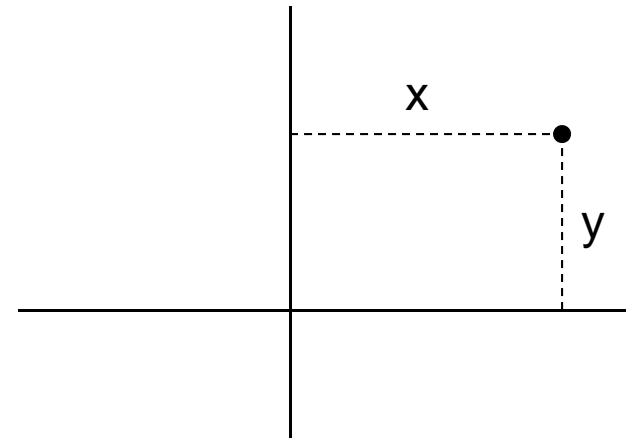
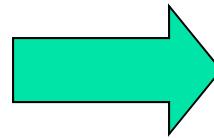


- What are the main tasks?
- Accommodate variable number of rings—loop
- For each ring
  - Need many dots
  - For each dot
    - Generate random position
    - Choose color
    - Draw it

# Convert from polar to Cartesian coordinates



Polar coordinates



Cartesian coordinates



```

c= input('How many concentric rings? ');
d= input('How many dots? ');

% Put dots btwn circles with radii rRing and (rRing-1)
for rRing= 1:c
    % Draw d dots
    for count= 1:d

        % Generate random dot location (polar coord.)
        theta= _____
        r= _____

        % Convert from polar to Cartesian
        x= _____
        y= _____

        % Use plot to draw dot
    end
end
end

```

A common task! Create a function `polar2xy` to do this. `polar2xy` likely will be useful in other problems as well.

```
% Generate random dot location (polar)
```

```
theta= _____
```

```
r= _____
```

```
% Convert from polar to Cartesian
```

```
rads= theta*pi/180; % radian
```

```
x= r*cos(rads);
```

```
y= r*sin(rads);
```

*Part of a script*

```
function [x, y] = polar2xy(r,theta)
% Convert polar coordinates (r,theta) to
% Cartesian coordinates (x,y).
% theta is in degrees.

rads= theta*pi/180; % radian
x= r*cos(rads);
y= r*sin(rads);
```

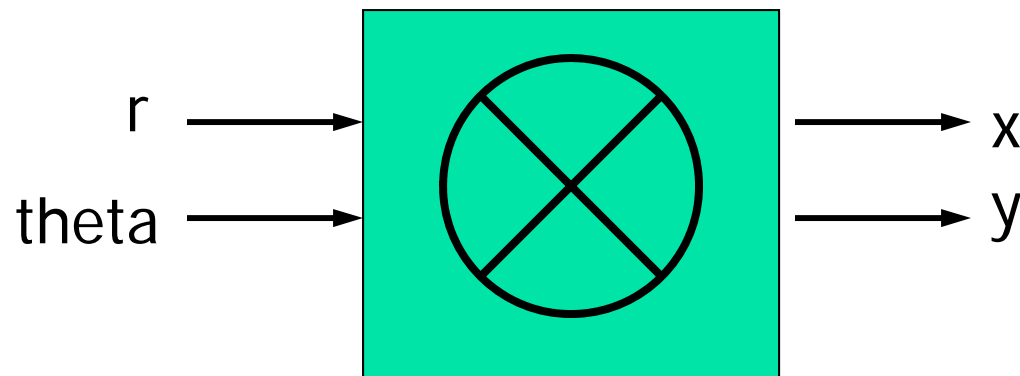
A function file  
polar2xy.m

```
function [x, y] = polar2xy(r,theta)
% Convert polar coordinates (r,theta) to
% Cartesian coordinates (x,y).
% theta is in degrees.

rads= theta*pi/180; % radian
x= r*cos(rads);
y= r*sin(rads);
```

A function file  
`polar2xy.m`

Think of `polar2xy` as a factory



```
function [x, y] = polar2xy(r,theta)
% Convert polar coordinates (r,theta) to
% Cartesian coordinates (x,y).
% theta is in degrees.

rads= theta*pi/180; % radian
x= r*cos(rads);
y= r*sin(rads);
```

A function file  
polar2xy.m

```
r= input('Enter radius: ');
theta= input('Enter angle in degrees: ');

rads= theta*pi/180; % radian
x= r*cos(rads);
y= r*sin(rads);
```

(Part of) a  
script file

```
function [x, y] = polar2xy(r,theta)
% Convert polar coordinates (r,theta) to
% Cartesian coordinates (x,y).
% theta is in degrees.

rads= theta*pi/180; % radian
x= r*cos(rads);
y= r*sin(rads);
```

A function file  
polar2xy.m

```
r= input('Enter radius: ');
theta= input('Enter angle in degrees: ');
```

```
rads= theta*pi/180; % radian
x= r*cos(rads);
y= r*sin(rads);
```

(Part of) a  
script file

```

c= input('How many concentric rings? ');
d= input('How many dots? ');

% Put dots btwn circles with radii rRing and (rRing-1)
for rRing= 1:c
    % Draw d dots
    for count= 1:d

        % Generate random dot location (polar coord.)
        theta= _____
        r= _____

        % Convert from polar to Cartesian
        x= _____
        y= _____

        % Use plot to draw dot
    end
end
end

```

A common task! Create a function `polar2xy` to do this. `polar2xy` likely will be useful in other problems as well.

```

c= input('How many concentric rings? ');
d= input('How many dots? ');

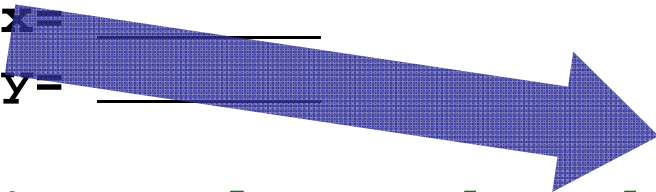
% Put dots btwn circles with radii rRing and (rRing-1)
for rRing= 1:c
    % Draw d dots
    for count= 1:d

        % Generate random dot location (polar coord.)
        theta= _____
        r= _____

        % Convert from polar to Cartesian
        x= _____
        y= _____
        [x,y] = polar2xy(r,theta);

        % Use plot to draw dot
    end
end
end

```





**function** [x, y] = polar2xy(r, theta)

Output  
parameter list  
enclosed in [ ]

Function name  
(This file's name is  
polar2xy.m)

Input parameter  
list enclosed in  
( )

Function header is the “contract” for how the function will be used (called)

You have this function:

```
function [x, y] = polar2xy(r, theta)
% Convert polar coordinates (r, theta) to
% Cartesian coordinates (x,y). Theta in degrees.
...
```

Code to call the above function:

```
% Convert polar (r1,t1) to Cartesian (x1,y1)
r1 = 1; t1 = 30;
[x1, y1] = polar2xy(r1, t1);
plot(x1, y1, 'b*')
...
```

Function header is the “contract” for how the function will be used (called)

You have this function:

```
function [x, y] = polar2xy(r, theta)
% Convert polar coordinates (r, theta) to
% Cartesian coordinates (x,y). Theta in degrees.
...
```

Code to call the above function:

```
% Convert polar (r1,t1) to Cartesian (x1,y1)
r1 = 1; t1 = 30;
[x1, y1] = polar2xy(r1, t1);
plot(x1, y1, 'b*')
...
```

Function header is the “contract” for how the function will be used (called)

You have this function:

```
function [x, y] = polar2xy(r, theta)
```

```
% Convert polar coordinates (r,theta) to  
% Cartesian coordinates (x,y) Theta in degrees.  
...
```

Code to call the above function:

```
% Convert polar (r1,t1) to Cartesian (x1,y1)  
r1=1; t1=30;  
[x1, y1]= polar2xy(r1, t1);  
plot(x1, y1, 'b*')  
...
```

## General form of a user-defined function

```
function [out1, out2, ...]= functionName (in1, in2, ...)
```

```
% 1-line comment to describe the function
```

```
% Additional description of function
```

*Executable code that at some point assigns values to output parameters out1, out2, ...*

- *in1, in2, ...* are defined when the function begins execution. Variables *in1, in2, ...* are called function *parameters* and they hold the function *arguments* used when the function is invoked (called).
- *out1, out2, ...* are not defined until the executable code in the function assigns values to them.

## dotsInRings.m

(functions with multiple input parameters)

(functions with a single output parameter)

(functions with multiple output parameters)

(functions with no output parameter)