

```
Examples of functions that can work with arrays

x= linspace(0,1,200);
y= exp(x);
plot(x,y)

x= linspace(1,10,200);
y= log(x);
plot(x,y)
```

```
Does this assign to y the values
sin(0^{\circ}), sin(1^{\circ}), sin(2^{\circ}), ..., sin(90^{\circ})?
\mathbf{x} = linspace(0,pi/2,90);
\mathbf{y} = sin(\mathbf{x});
A: yes
B: no
```

Element-by-element arithmetic operations on arrays...

Also called "vectorized code"

x = linspace(-2,3,200);
y = sin(5*x).*exp(-x/2)./(1 + x.^2);

Contrast with scalar operations that we've used previously...

a = 2.1;
b = sin(5*a);

The operators are (mostly) the same; the operands may be scalars or vectors.

When an operand is a vector, you have "vectorized code."

you have "vectorized code."

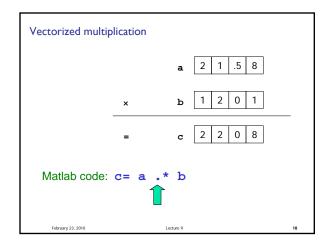
Vectorized code

—a Matlab-specific feature

Code that performs element-by-element arithmetic/relational/logical operations on array operands in one step

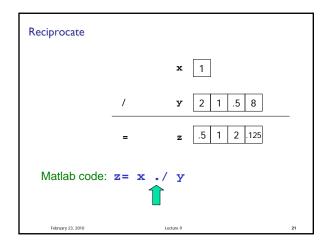
Scalar operation: x + y where x, y are scalar variables

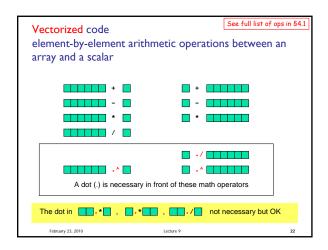
Vectorized code: x + y where x and/or y are vectors. If x and y are both vectors, they must be of the same shape and length



Vectorized code
element-by-element arithmetic operations
on arrays

A dot (.) is necessary in front of these math operators



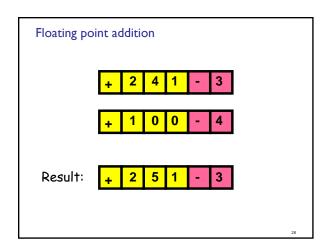


Computer Arithmetic—floating point arithmetic

Suppose you have a calculator with a window like this:

+ 2 4 1 - 3

representing 2.41 x 10-3



Floating point addition

+ 2 4 1 - 3

+ 1 0 0 - 6

Result: + 2 4 1 - 3

Not enough room to represent .002411

```
The loop DOES terminate given the limitations of floating point arithmetic!

k = 0;
while 1 + 1/2^k > 1
k = k+1;
end
disp(k)

1 + 1/2^53 is calculated to be just 1, so "53" is printed.
```

Patriot missile failure



In 1991, a Patriot Missile failed, resulting in 28 deaths and about 100 injured. The cause?



ura B

Computer arithmetic is inexact

- There is error in computer arithmetic—floating point arithmetic—due to limitation in "hardware." Computer memory is finite.
- What is $1 + 10^{-16}$?
 - 1.0000000000000001 in real arithmetic
 - I in floating point arithmetic (IEEE)
- Read Sec 4.3

.

Built-in functions

- We've used many Matlab built-in functions, e.g., rand, abs, floor, rem
- Example: abs(x-.5)
- Observations:
 - abs is set up to be able to work with any valid data
 - abs doesn't prompt us for input; it expects that we provide data that it'll then work on

February 23, 2010

Lecture 9

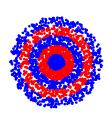
User-defined functions

- We can write our own functions to perform a specific task
 - Example: generate a random floating point number in a specified interval
 - Example: convert polar coordinates to x-y (Cartesian) coordinates

February 23, 2010

Lecture 9

Draw a bulls eye figure with randomly placed dots



- What are the main tasks?
- Accommodate variable number of rings—loop
- For each ring
 - Need many dots
 - For each dot
 - Generate random position
 - Choose color
 - Draw it

February 23, 2010

Lecture 9

Convert from polar to Cartesian coordinates x Polar coordinates Cartesian coordinates

```
c= input('How many concentric rings? ');
d= input('How many dots? ');
% Put dots btwn circles with radii rRing and (rRing-1)
for rRing= 1:c
  % Draw d dots
  for count= 1:d
    % Generate random dot location (polar coord.)
    theta=
    % Convert from polar to Cartesian
                              A common task! Create a
   y=
                              function polar2xy to do
                             this. polar2xy likely will
    % Use plot to draw dot
  end
                              be useful in other problems
end
                              as well.
    February 23, 2010
                            Lecture 9
```

```
function [x, y] = polar2xy(r,theta)
% Convert polar coordinates (r,theta) to
% Cartesian coordinates (x,y).
% theta is in degrees.

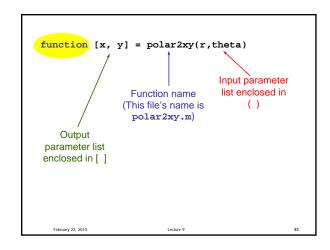
rads= theta*pi/180; % radian
x= r*cos(rads);
y= r*sin(rads);

Think of polar2xy as a factory

r
theta

x
y
```

```
function [x, y] = polar2xy(r,theta)
% Convert polar coordinates (r,theta) to
% Cartesian coordinates (x,y).
% theta is in degrees.
                                    A function file
rads= theta*pi/180; % radian
                                    polar2xy.m
x= r*cos(rads);
y= r*sin(rads);
r= input('Enter radius: ');
theta= input('Enter angle in degrees: ');
                                      (Part of) a
rads= theta*pi/180; % radian
                                       script file
x= r*cos(rads);
y= r*sin(rads);
```



```
Function header is the "contract" for how the function will be used (called)

You have this function:

function [x, y] = polar2xy(r, theta)
% Convert polar coordinates (r, theta) to
% Cartesian coordinates (x,y). Theta in degrees.
...

Code to call the above function:

% Convert polar (rl,tl) to Cartesian (xl,yl)
rl= l; tl= 30;
[xl, yl]= polar2xy(rl,tl);
plot(xl,yl,'b*')
...

retrumy 21,2010 Lecture 9 53
```

```
General form of a user-defined function

function [out!, out2, ...] = functionName (in!, in2, ...)

% I-line comment to describe the function

% Additional description of function

Executable code that at some point assigns values to output parameters out!, out2, ...

in!, in2, ... are defined when the function begins execution. Variables in!, in2, ... are called function parameters and they hold the function arguments used when the function is invoked (called).

out!, out2, ... are not defined until the executable code in the function assigns values to them.
```