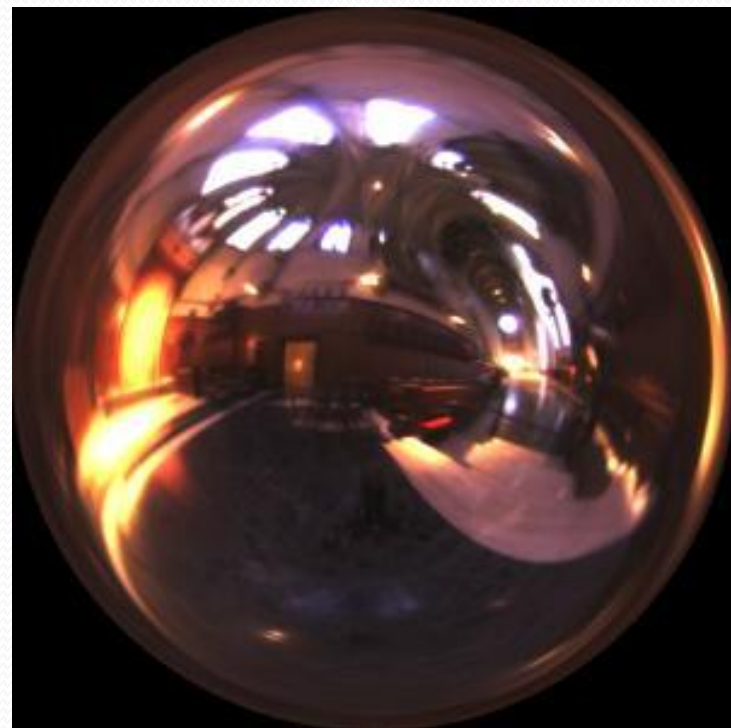


Illumination from Images

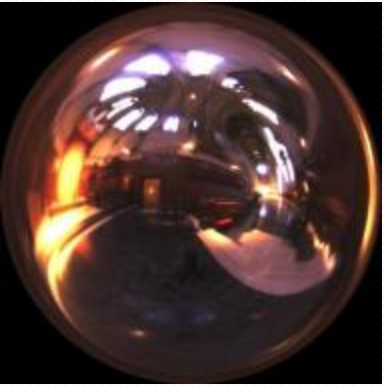
Chun-Po Wang

Scene Illumination

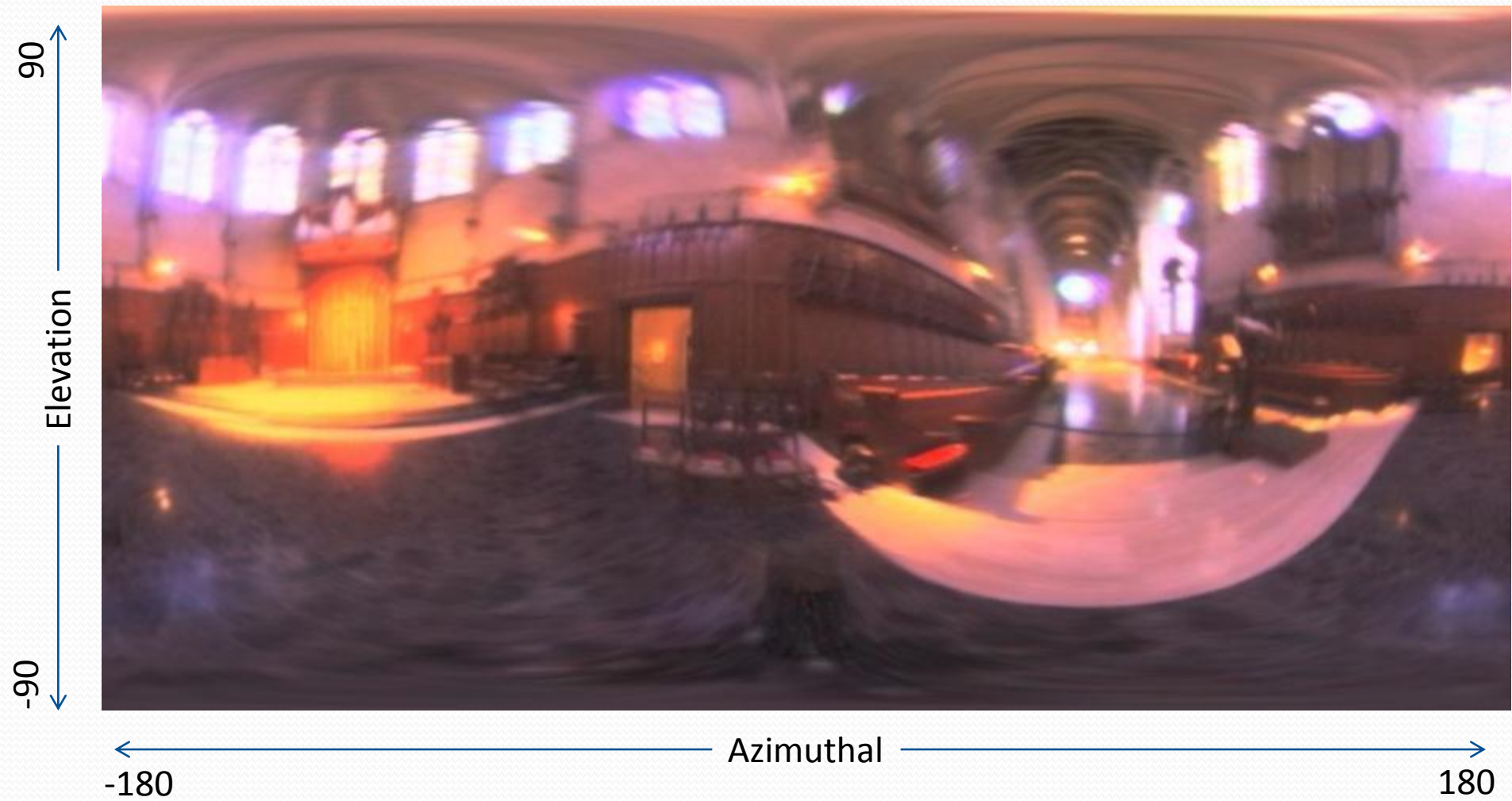
- What is it?
 - Environment map
 - A sphere **approximate** incident light from long distance
 - A 2D radiance function in sphere coordinates
- Assumptions
 - Far-field lighting
 - Independent to position



Grace Cathedral, San Francisco
Angular map format
<http://ict.debevec.org/~debevec/Probes/>



Unwarp



Applications

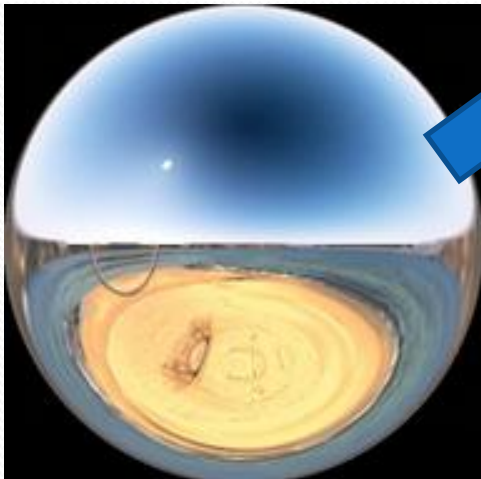
- Realistic 3D rendering/relighting



Applications (cont.)

- Insert 3D objects into photos

“Webcam Clipart”, <http://www.jflalonde.org/projects/webcamclipart/>



Applications (cont.)

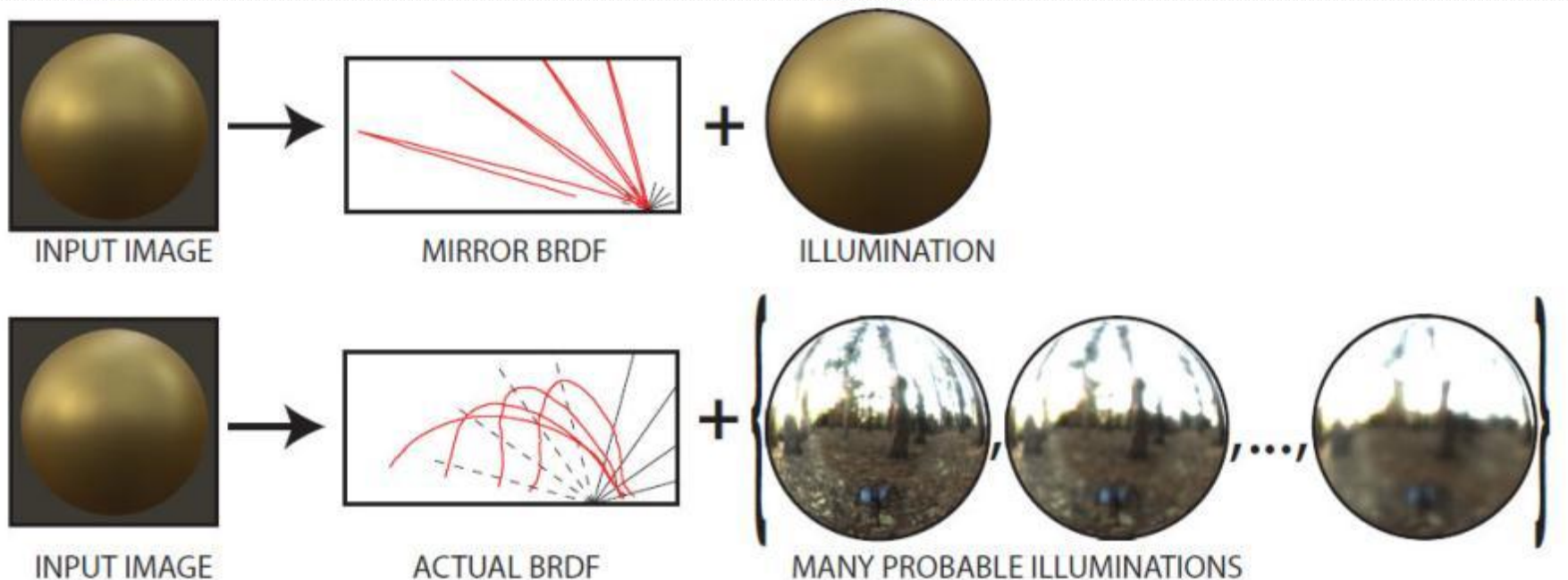
- Help scene understanding
 - Illumination vastly changes scene appearance
 - Solution 1: use illumination invariant features (e.g., SIFT)
 - Solution 2: utilize information about scene illumination



Example: Blind Reflectometry

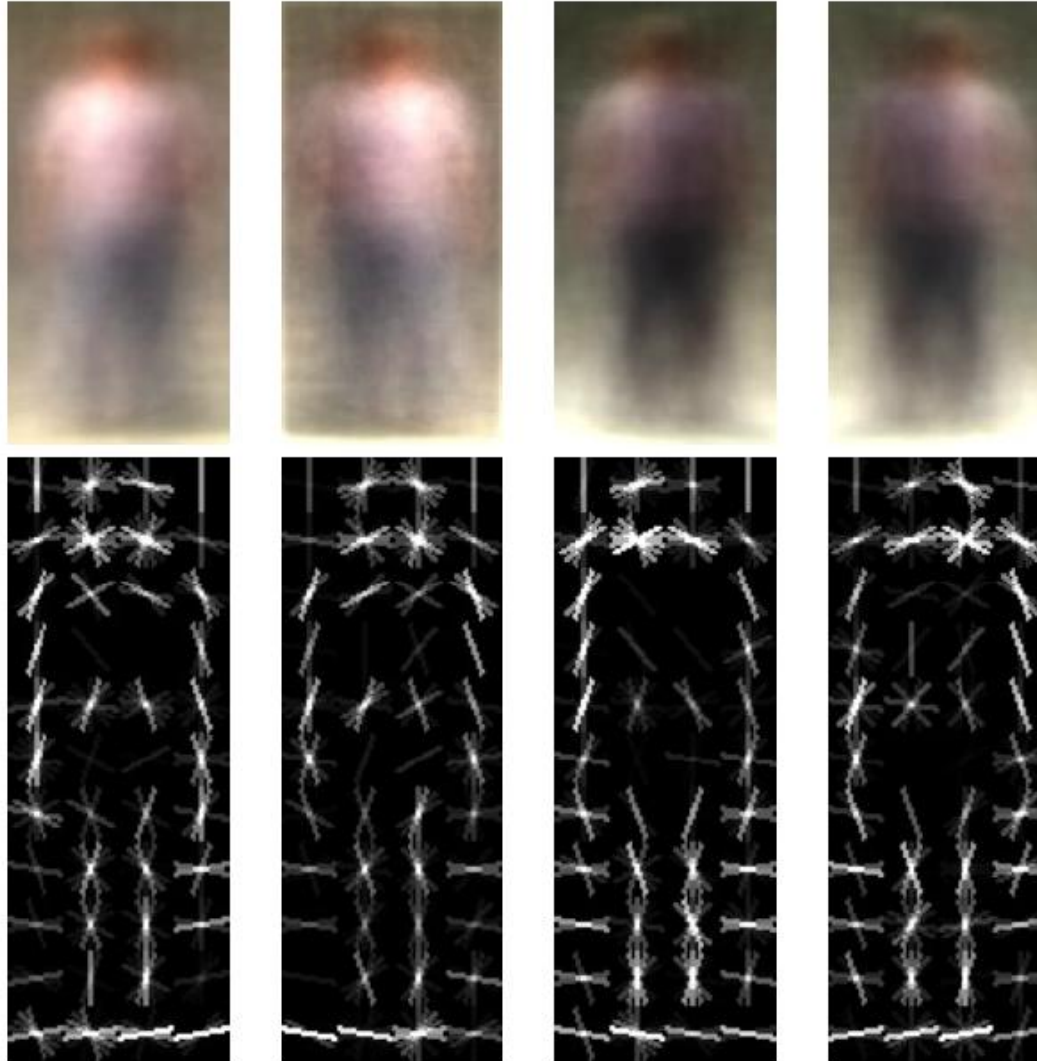
[Romeiro and Zickler, 2010]

- Ambiguity between illumination and reflectance
- Find material properties by
 - Choosing an appropriate BRDF representation
 - Find the statistics of outdoor environment maps
 - Select most likely BRDF parameters under that distribution of environment maps



Example: Illumination-Aware Pedestrian Detection

[Lalonde, PhD thesis, 2011]



(a) Back-left

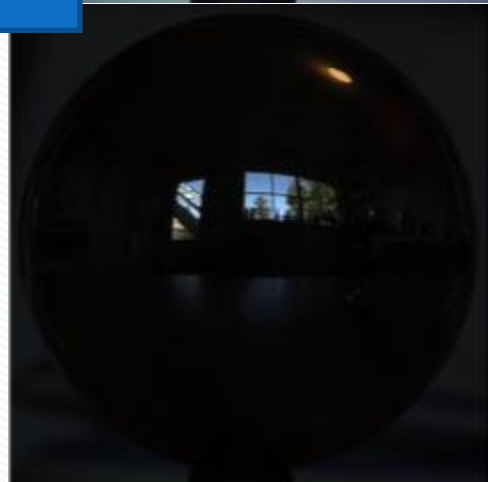
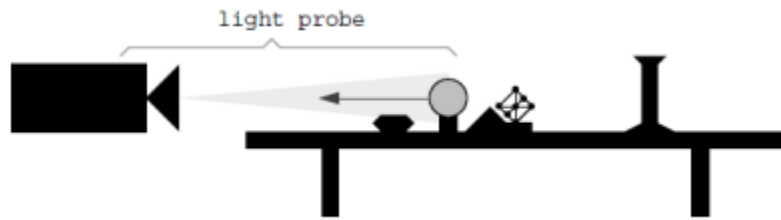
(b) Back-right

(c) Front-left

(d) Front-right

Estimating Scene Illumination

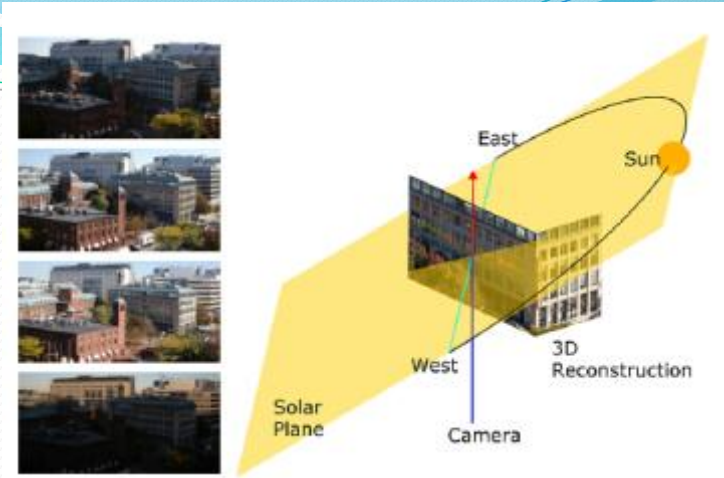
- Light Probe [Debevec et al., 1998]



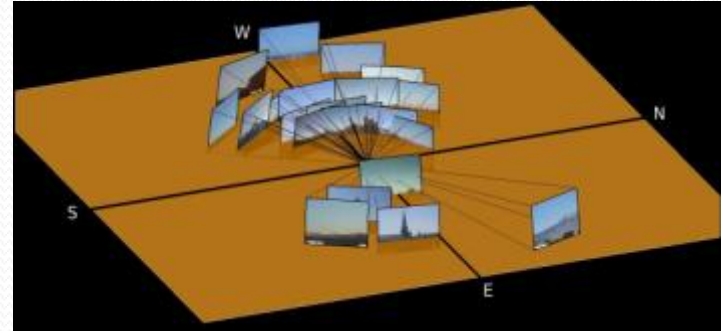
Outdoor Illumination from Image Sequence

- Webcam time lapsed video

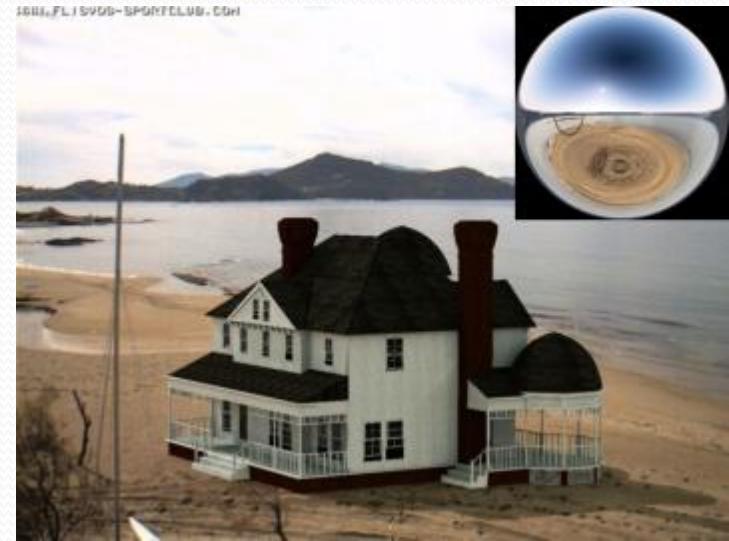
“What do color changes reveal about an outdoor scene?”
[Sunkavalli et al., 2008]



“What Do the Sun and the Sky Tell Us About the Camera?”
[Lalonde et al., 2008, 2010]



“Webcam Clip Art”
[Lalonde et al., 2009]



Outdoor Illumination from Single Image

- Estimating Natural Illumination from a Single Outdoor Image [Lalonde et al., 2009]
 - Estimating sun position and sky color
 - Using image cues:
 - Sky color
 - Shadow lines
 - Shading of vertical surfaces



[Lalonde et al., ICCV 2009]



Geometric Context [Hoiem et al., 2005]

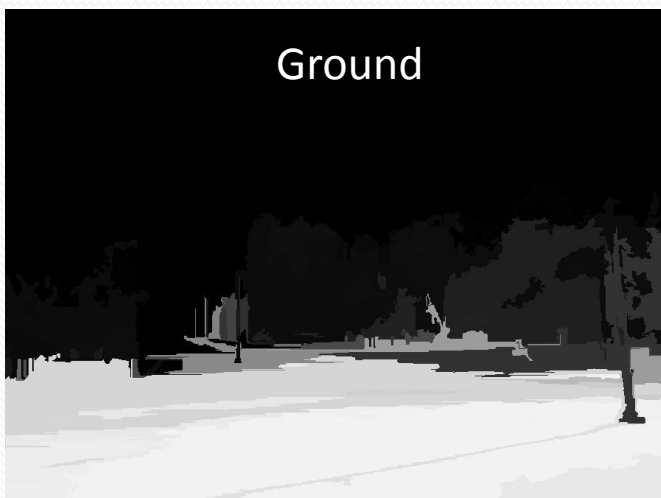
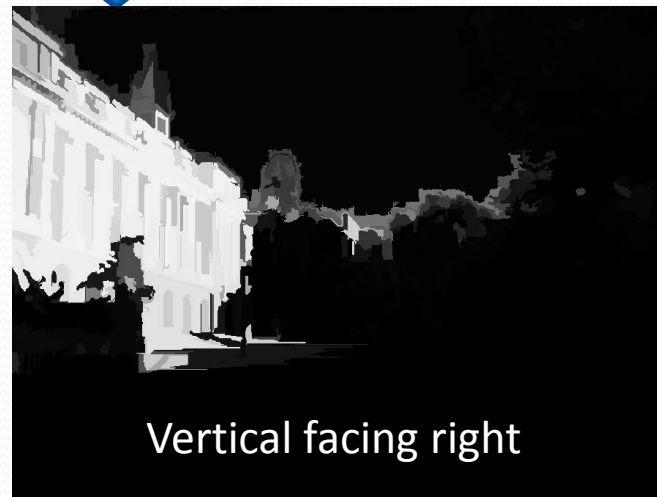
Pixel location

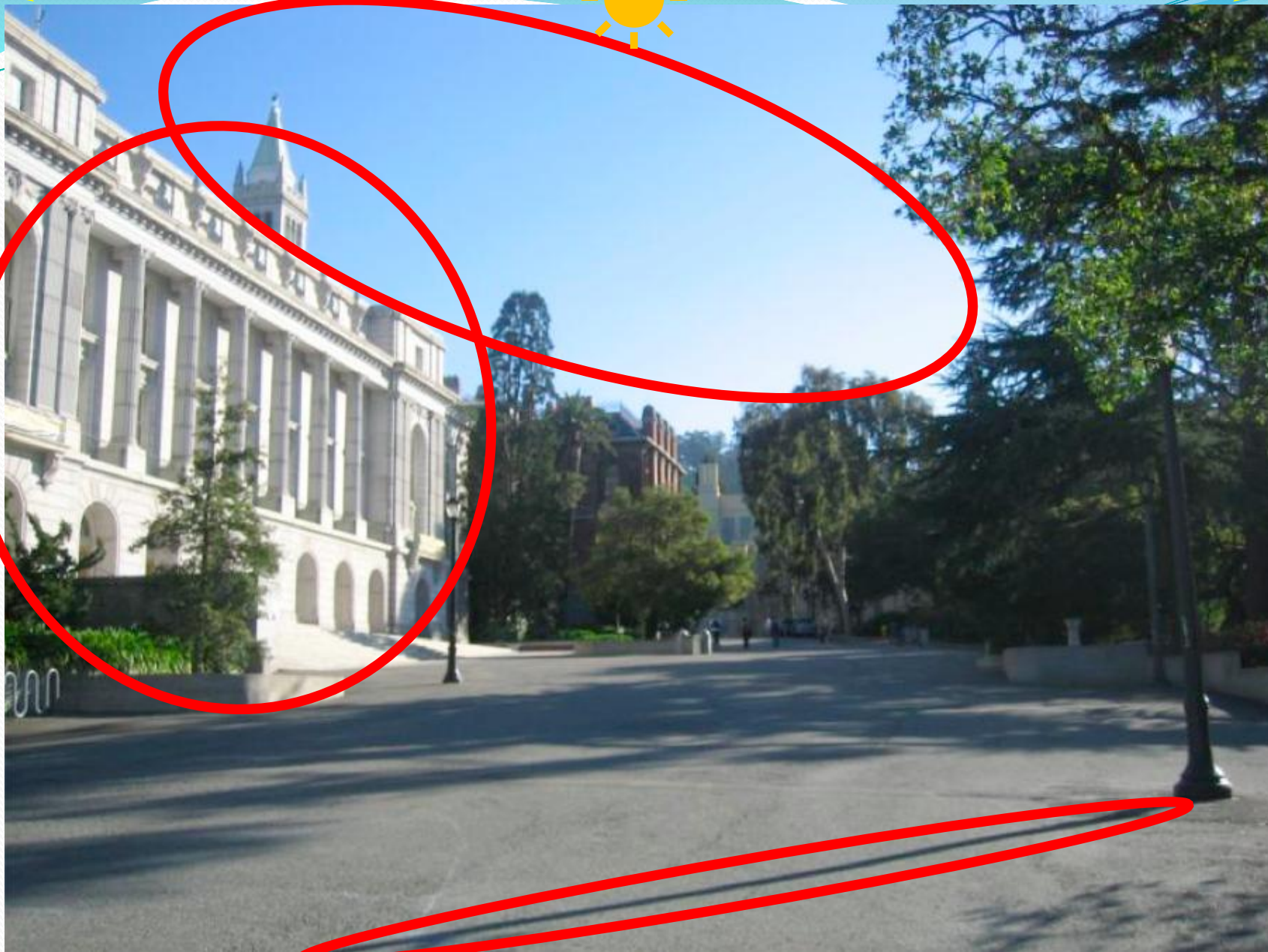
Color

Texture

Perspective

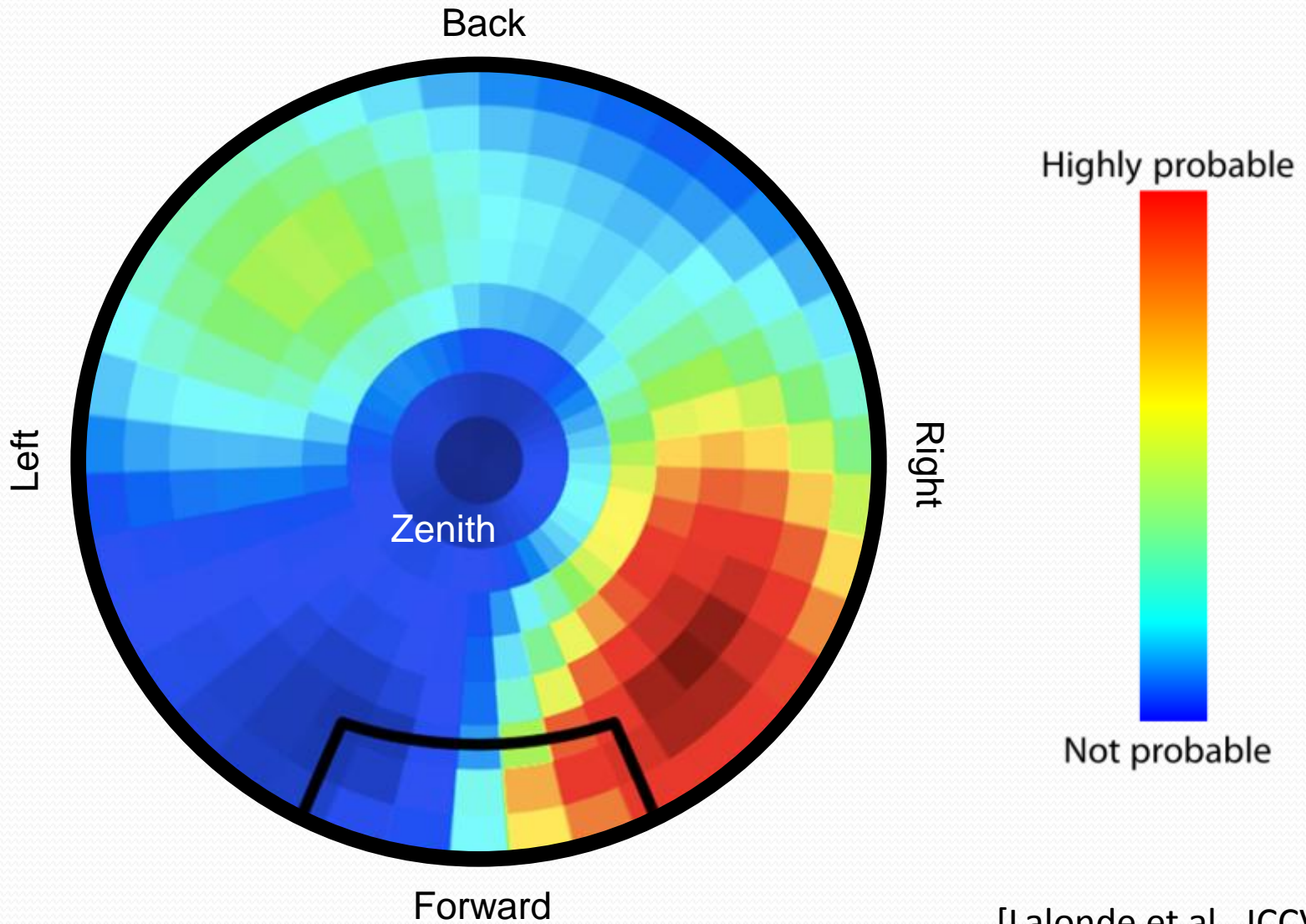
Classification/Labeling





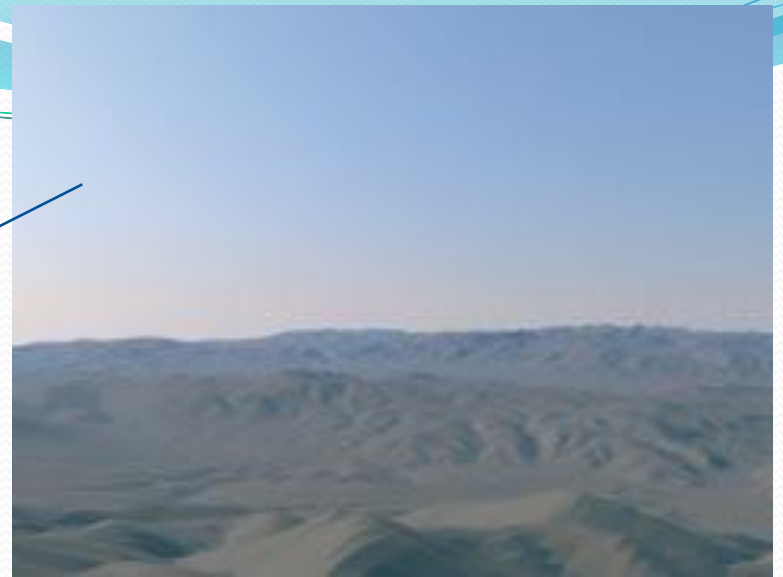
[Lalonde et al., ICCV 2009]

Sun probability distribution map



Sky Model

Sky luminance



$$l_p = f(\theta_p, \gamma_p) = [1 + a \exp(b / \cos \theta_p)] \times [1 + c \exp(d \gamma_p) + e \cos^2 \gamma_p]$$

zenith angle

angle with the sun

- [Perez et al., 1993] and [Preetham et al., 1999]
- a, b, c, d, e can be approximated with a linear function of a single parameter, **t (turbidity)**
- In this work, sky is assumed to be clear ($t = 2.17$)
- Cloud is segmented by clustering based on color

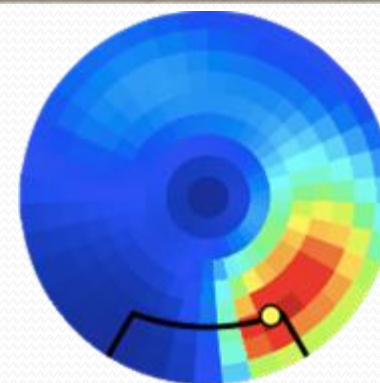
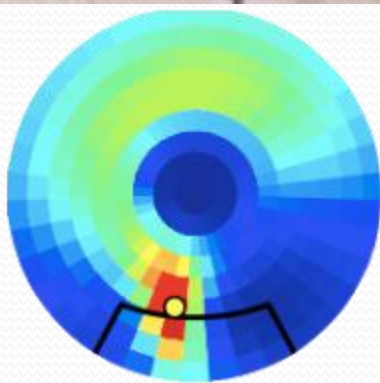


Predicted sky at current sun position



Original sky



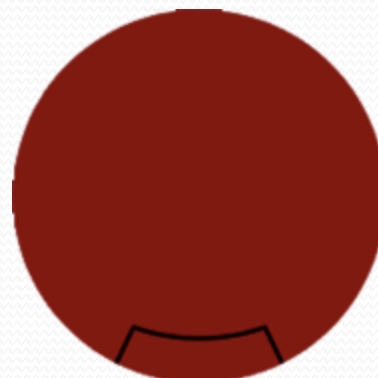
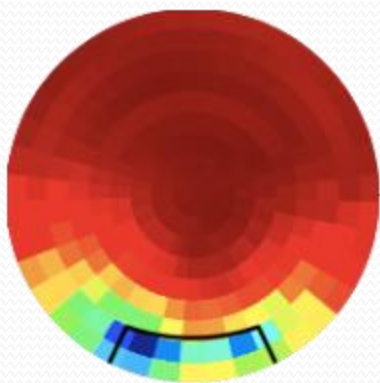


[Lalonde et al., ICCV 2009]

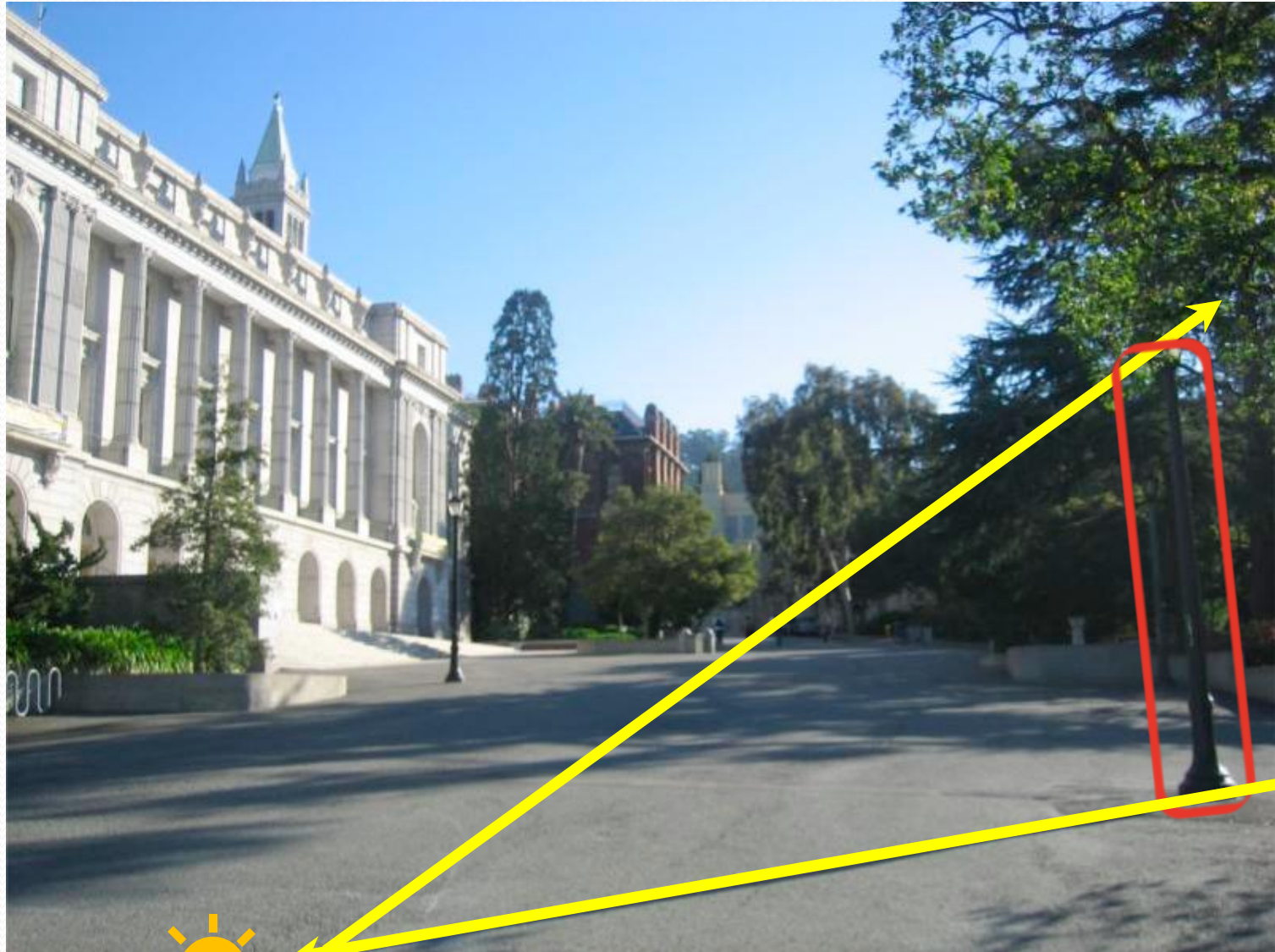
Sun behind camera



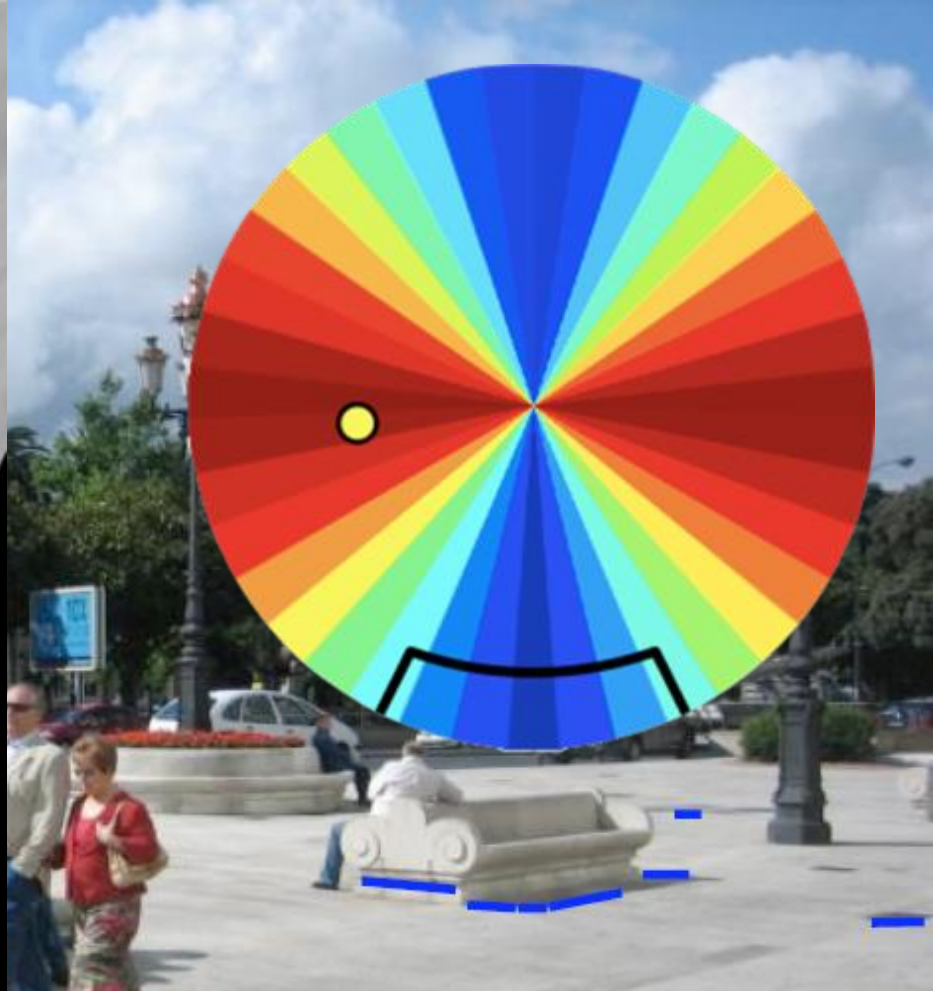
Sky not visible

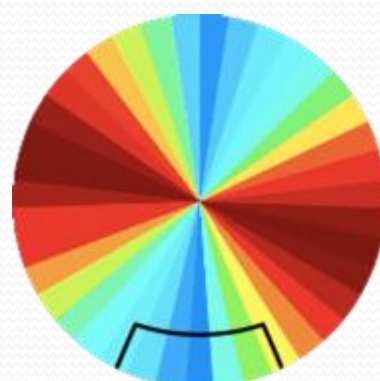
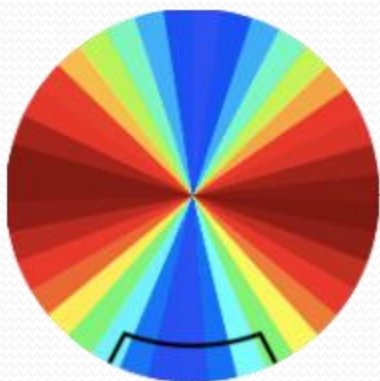


Ground shadows



[Lalonde et al., ICCV 2009]





[Lalonde et al., ICCV 2009]

Shadow detection



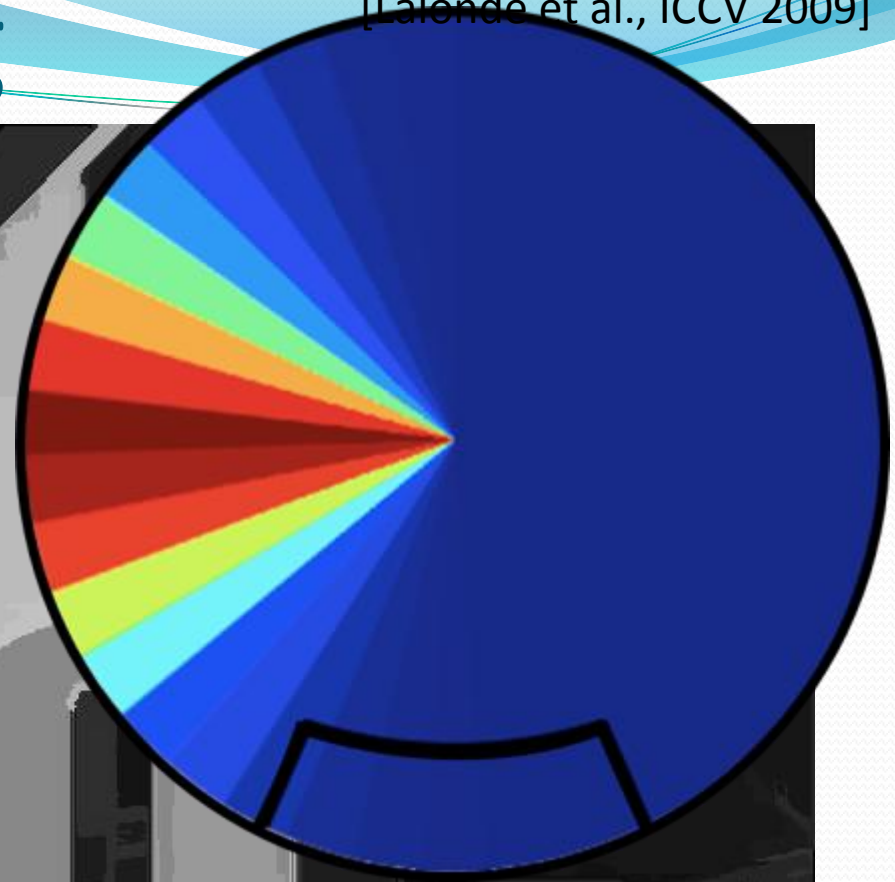
Non-vertical objects



Surfaces shading

[Lalonde et al., ICCV 2009]

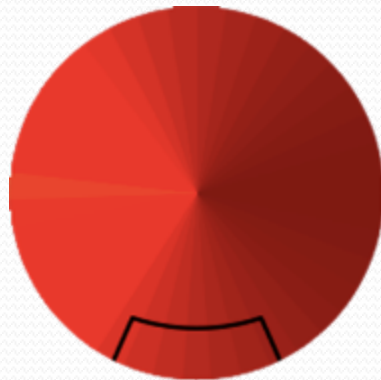
Vertical facing left





[Lalonde et al., ICCV 2009]

No flat surface



Cue Combination

Sun position

Sky pixels

Ground pixels

Vertical surface pixels

$$P(I | S, G, V)$$



Bayes rule

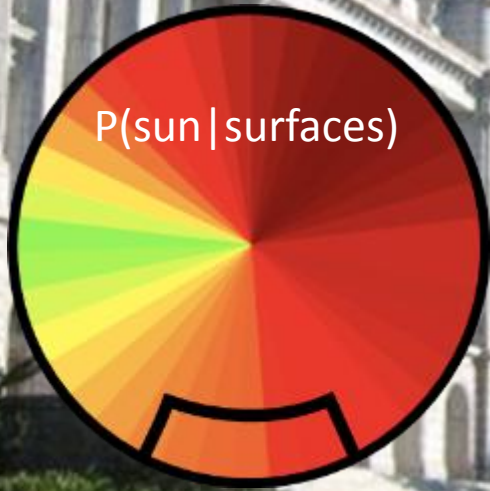
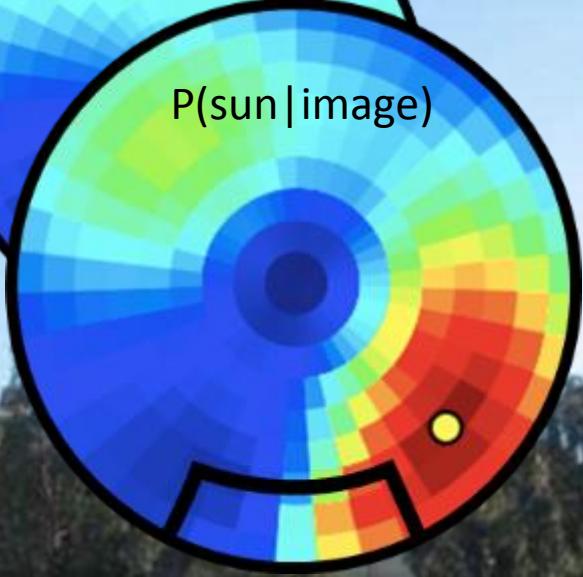
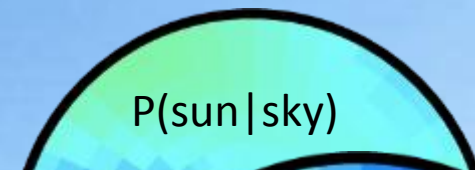
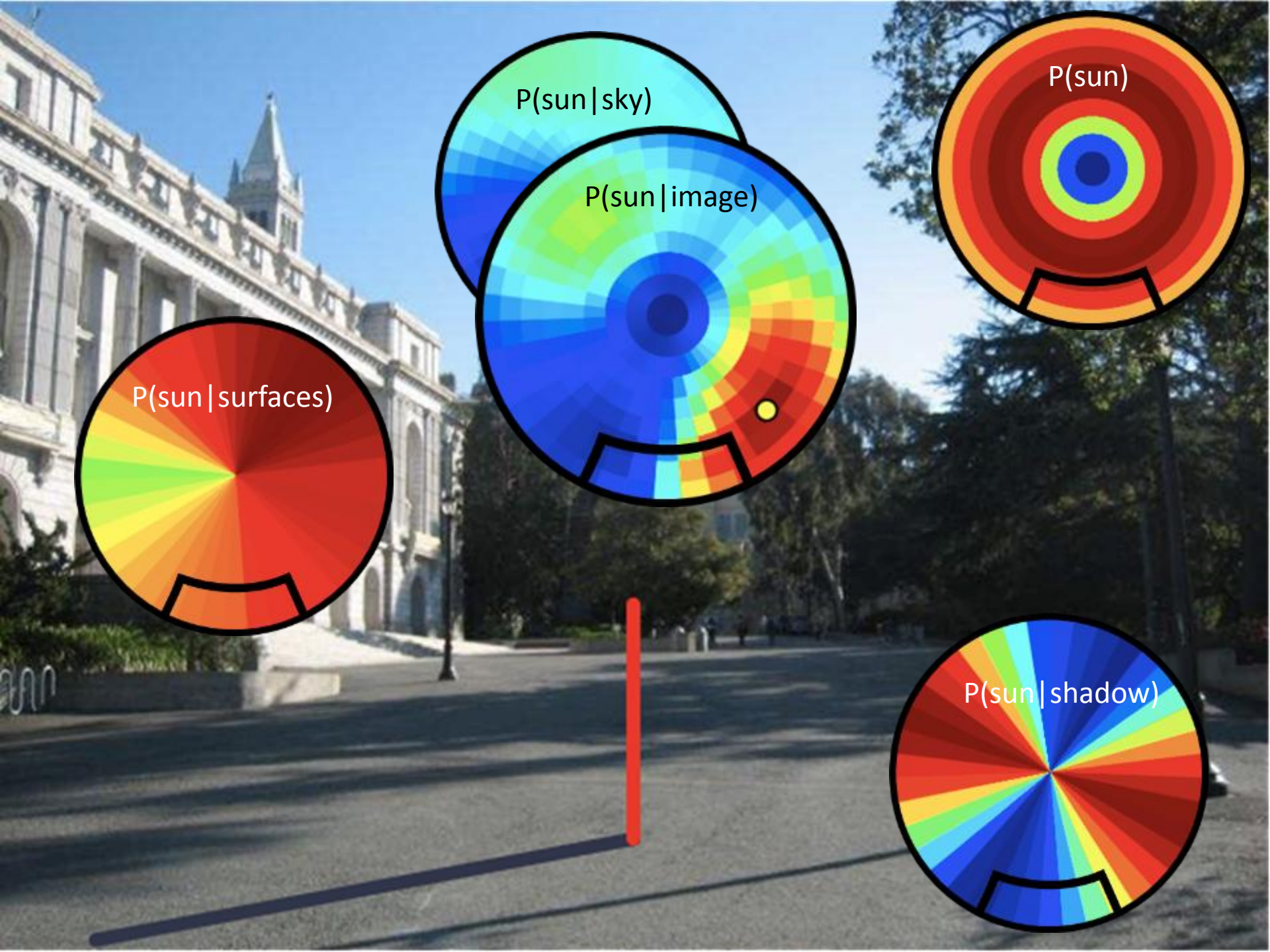
$$P(I | S, G, V) \propto P(I | S) P(I | G) P(I | V) P(I)$$

Sky color

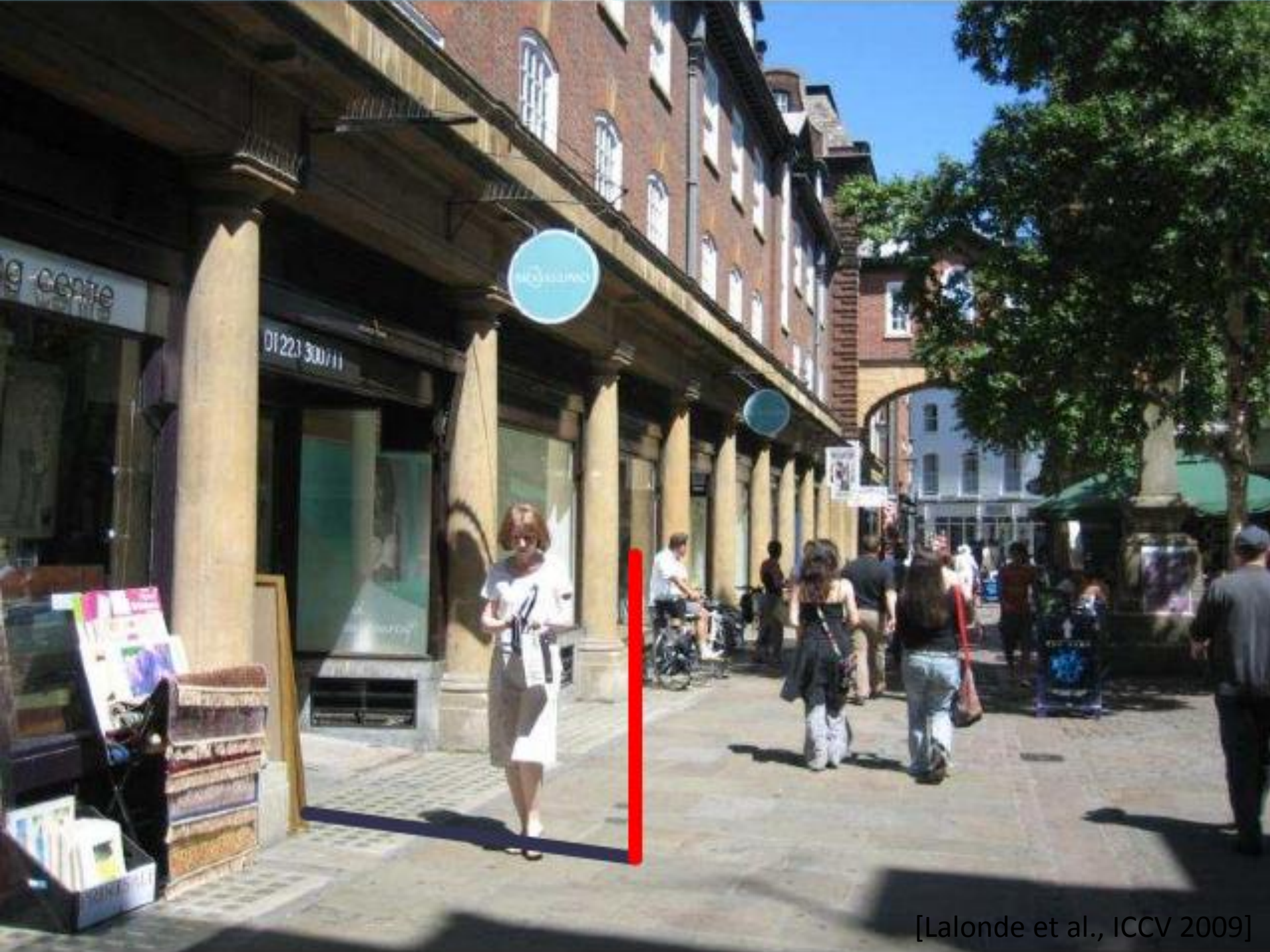
Ground shadow

Vertical surface

Sun position prior





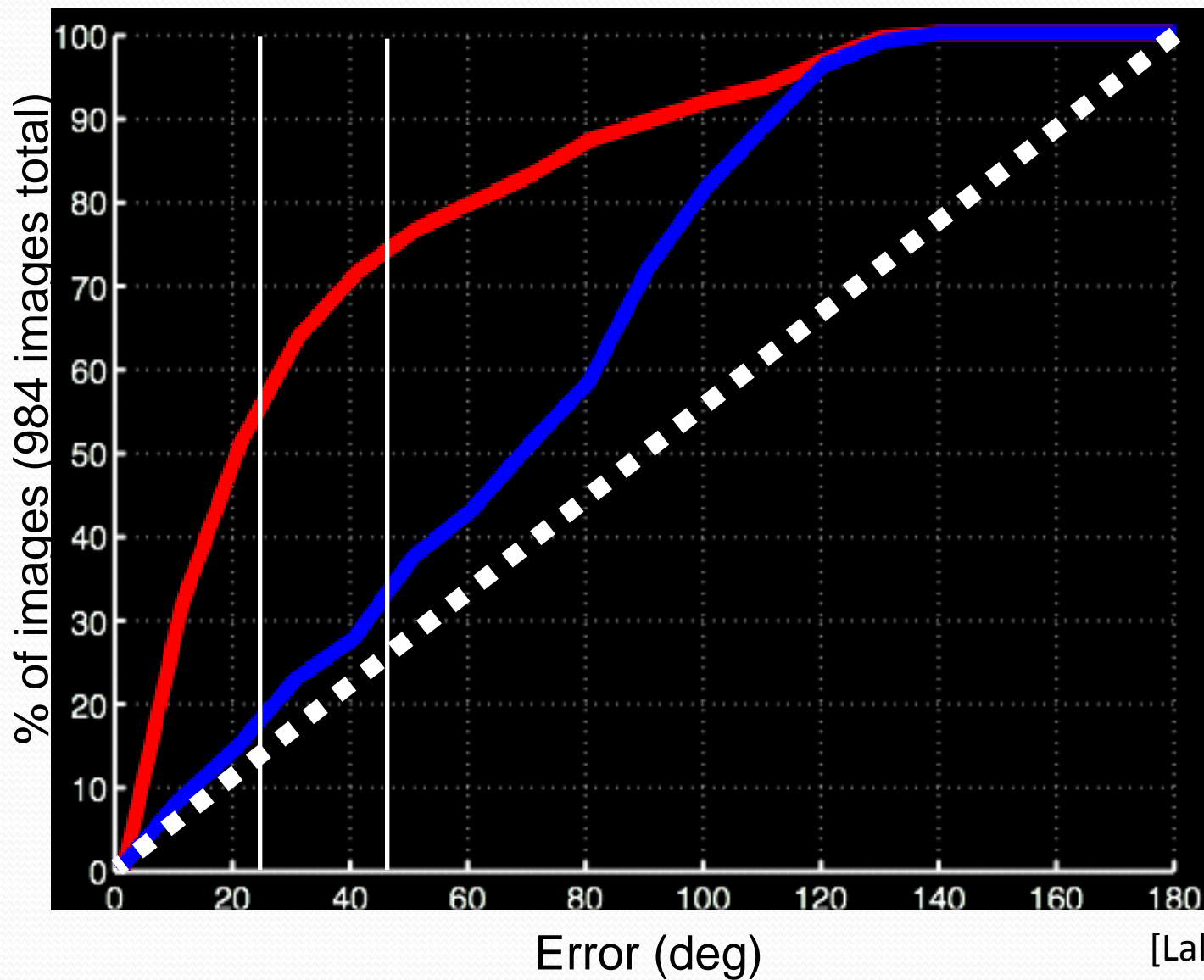




Quantitative evaluation



Quantitative evaluation



Data-driven prior



Scene cues + data





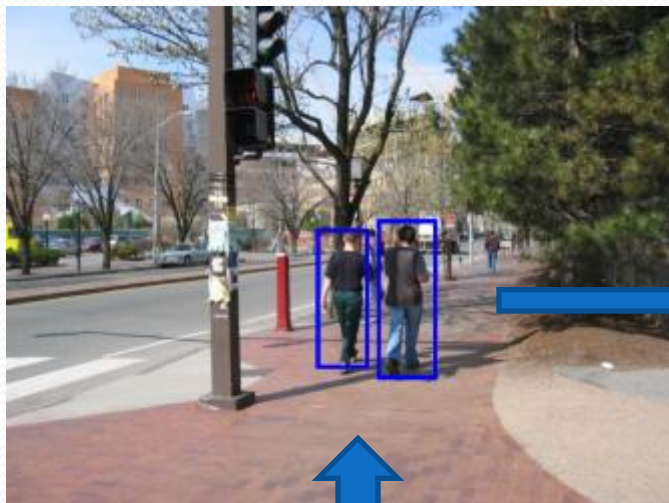
- Code and Dataset

- <http://www.jflalonde.org/projects/outdoorIllumination/>

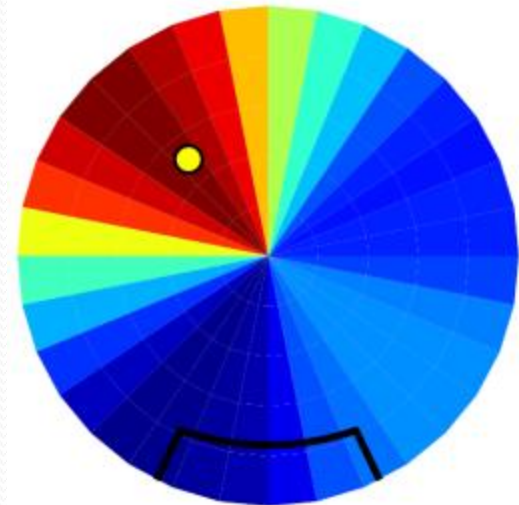
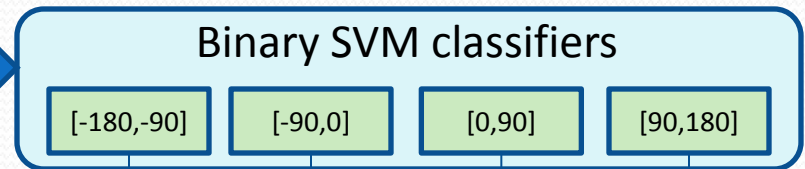
- Currently only the code for the Sky model is available

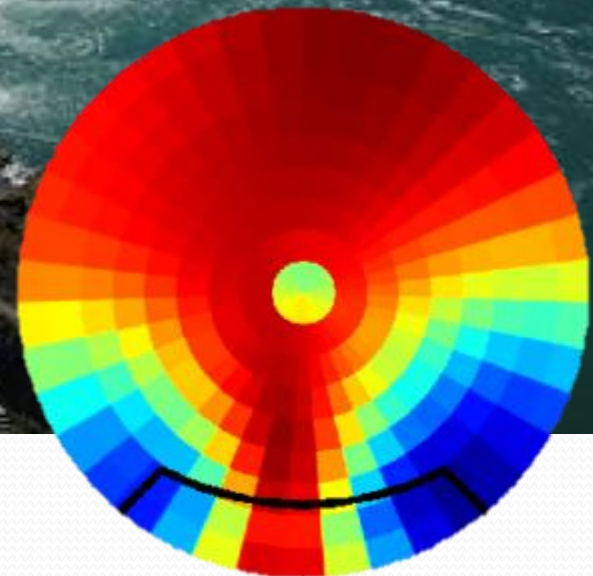
- Extension in Lalonde's PhD thesis [2011]

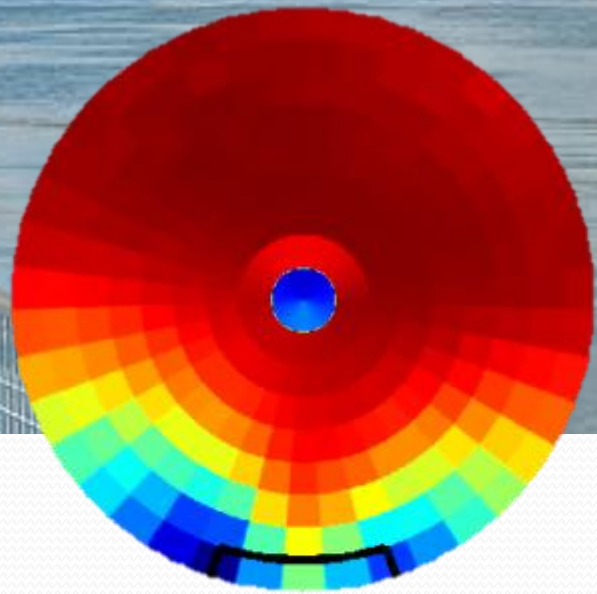
- Find sun direction by person appearance



Person Detector
[Felzenszwalb et al., 2010]







Shadow Detection

- Application
 - Estimating outdoor illumination
 - Shadow removal
 - Detecting Ground Shadows in Outdoor Consumer Photographs [Lalonde et al., ECCV 2010]
 - Single-Image Shadow Detection and Removal using Paired Regions [Guo et al., CVPR 2011]

Detecting Ground Shadows in Outdoor Consumer Photographs

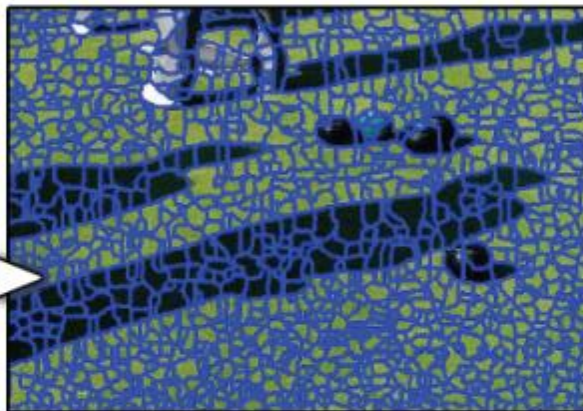
- [Lalonde et al., ECCV 2010]
- **Observation:** photometric methods do not work well on consumer images (not linear, lossy compression)
- **Hypothesis:** appearances of shadows *on the ground* are less varied than shadows in general, and *can be learned* from labeled images.

Learning shadow appearance

Input



Oversegmentation
(watershed)



Strong boundaries
(Canny)



CRF



$P(\text{shadow})$



Feature extraction

Local classifier
(boosted decision trees)

Incorporating scene layout

Input



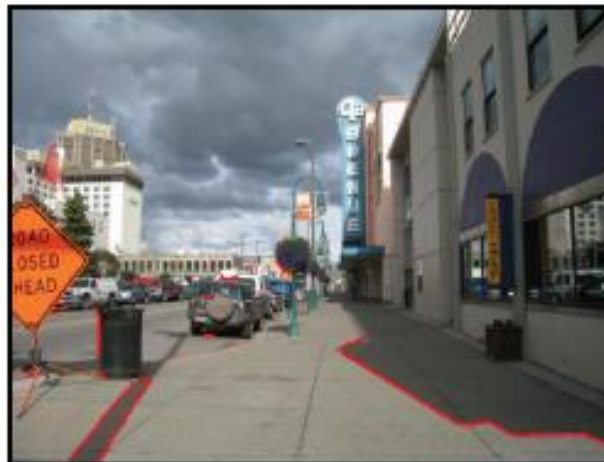
Shadows



$P(\text{ground})$

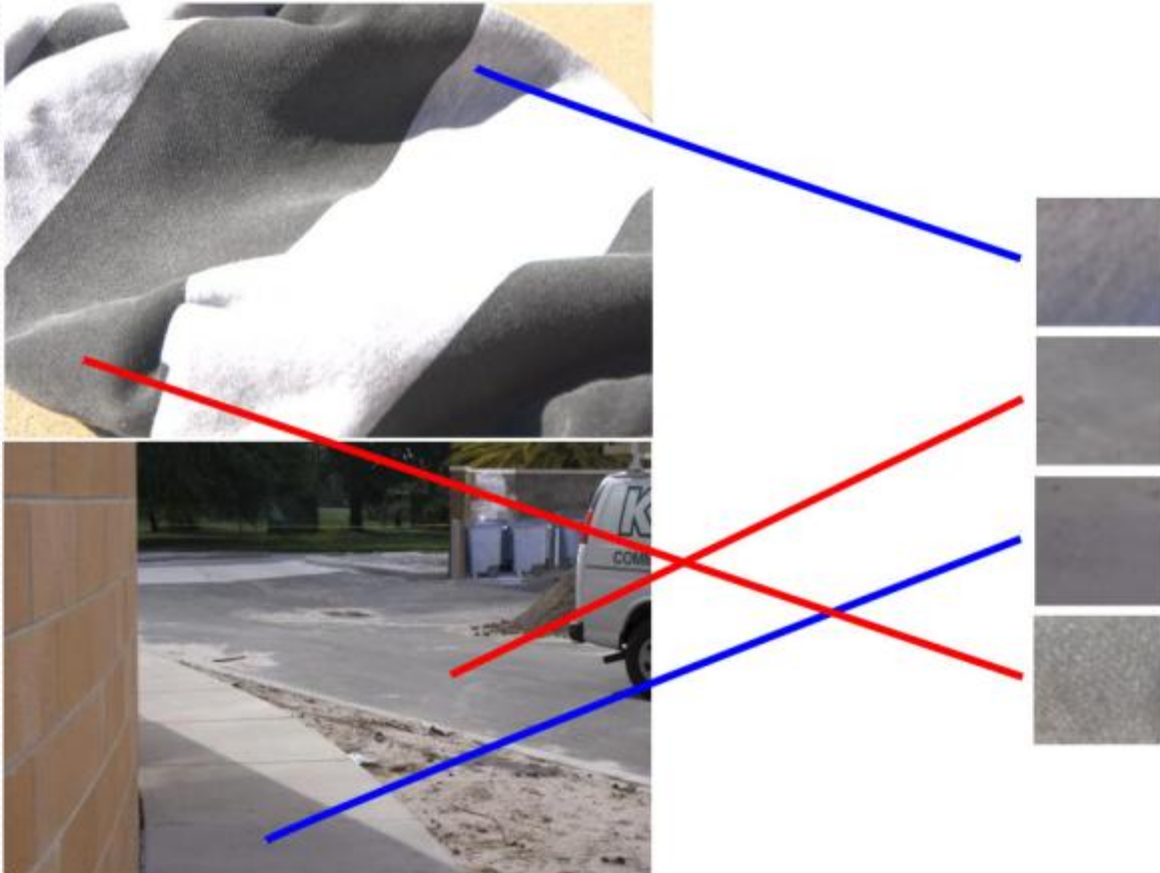


Ground shadows



Single-Image Shadow Detection and Removal using Paired Regions

- [Guo et al., CVPR 2011]



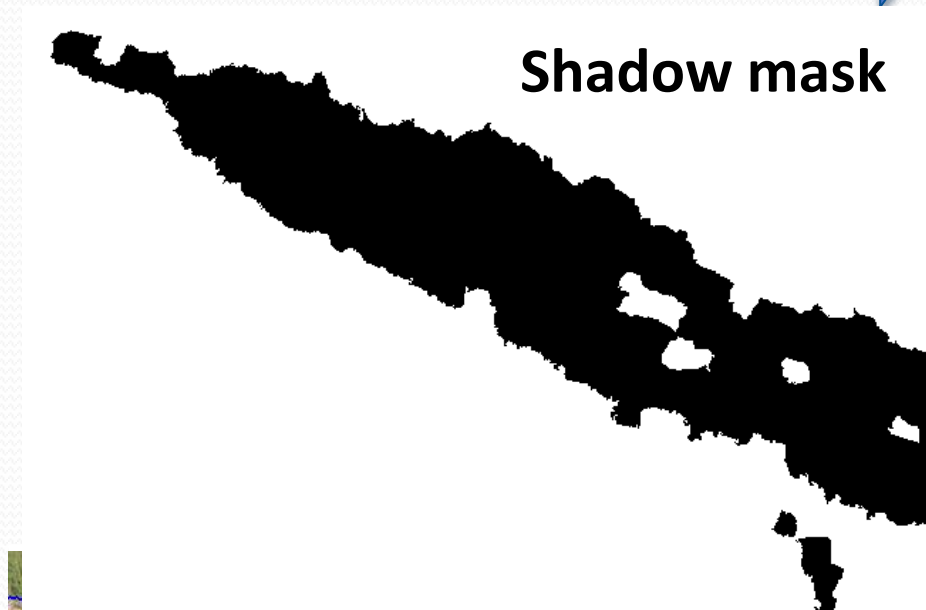
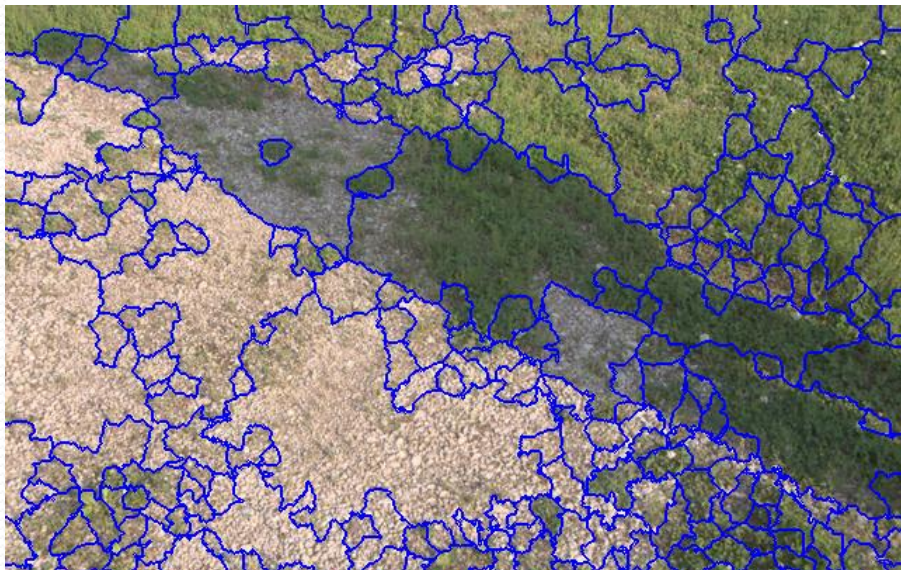
Segmentation

Single/Pairwise
region classification

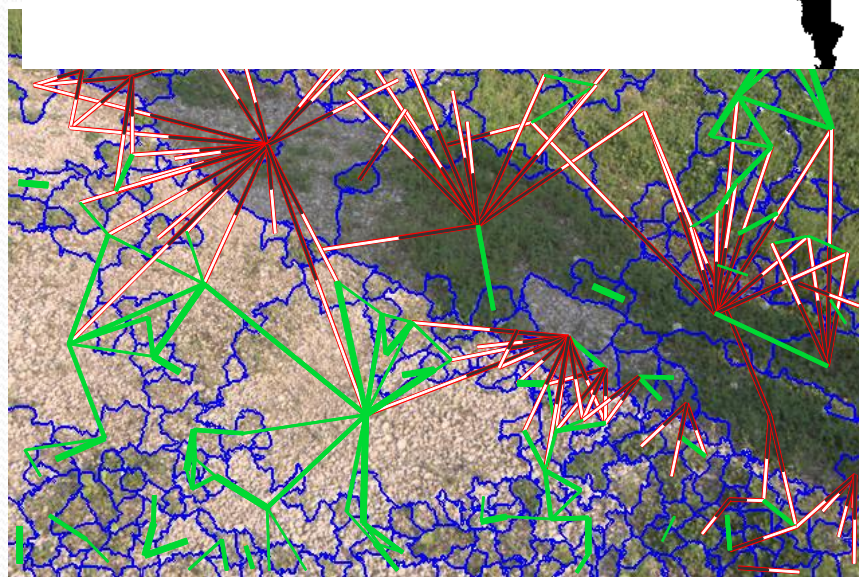
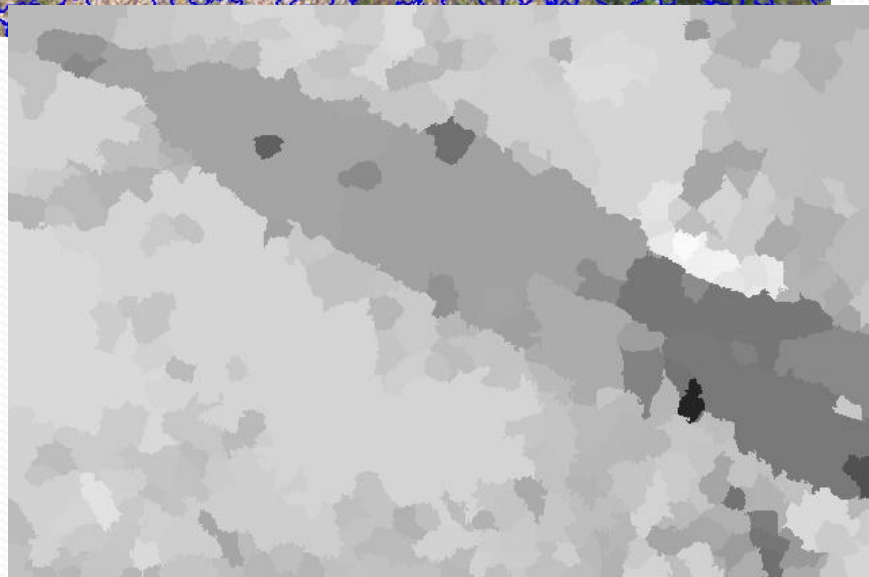
Shadow
Labeling

Soft shadow
matting

Shadow removal



Shadow mask





Lalonde's method



Guo's method



Lalonde's method

Guo's method



Practical Issues

- Applying to outdoor illumination estimation
 - Segmentation (region based)
 - => does not work well on thin shadows



Lalonde's method



Guo's method



Thank you

- Questions?

Question

I: illumination (sun direction)

S: sky pixels

G: ground pixels

V: vertical surface pixels

S,G,V: input image

$$P(I | S, G, V) = \frac{P(S, G, V | I) P(I)}{P(S, G, V)} \quad \text{Bayes rule}$$

$$\Rightarrow P(I | S, G, V) \propto P(S, G, V | I) P(I)$$

$$\Rightarrow P(I | S, G, V) \propto P(S | I) P(G | I) P(V | I) P(I) \quad \text{Assuming conditional independence}$$

$$P(S | I) = \frac{P(I | S) P(S)}{P(I)} \quad \begin{array}{l} \text{Bayes rule} \\ \text{Can we ignore this?} \end{array}$$

$$\Rightarrow P(S | I) \propto P(I | S) P(S)$$

$$\Rightarrow P(S | I) \propto P(I | S)$$

$$P(I | S, G, V) \propto P(I | S) P(I | G) P(I | V) P(I)$$