### 7.1 Proof of Expander Chernoff Bound

Let $G=(V, E)$ be an $(N, \gamma)$ spectral expander that is $D$-regular.
Define a random walk of length $t$ as $l_{1} \rightarrow l_{2} \ldots \rightarrow l_{t}$, such that $l_{1}$ is chosen randomly from $V$ and each $l_{i+1}$ is a random element of the neighbors of $l_{i}$.

Claim 7.1 For all $f:[N] \rightarrow[0,1], \operatorname{Pr}\left[\left|\frac{1}{t} \sum_{i} f\left(l_{i}\right)-\mu_{f}\right|>(\delta+\lambda)\right] \leq e^{-\Omega\left(\delta^{2} t\right)}$, where $\mu_{i}=\mathbb{E}_{j \sim[n]}(f(j))$.
Proof: Define $X_{i}=f\left(l_{i}\right)$. Define $X=\sum_{i}^{t} X_{i}$.
The goal of this proof will be to bound $\Delta=\operatorname{Pr}\left[X \geq\left(\delta+\lambda+\mu_{f}\right) t\right]$.
Mirroring the proof of the Chernoff bound, $\Delta=\operatorname{Pr}\left[e^{r x} \geq e^{r\left(\delta+\lambda+\mu_{f}\right) t}\right]$.
Applying Markov's inequality, $\operatorname{Pr}\left[e^{r x} \geq e^{r\left(\delta+\lambda+\mu_{f}\right) t}\right] \leq \frac{\mathbb{E}\left[e^{r x}\right]}{e^{r\left(\delta+\lambda+\mu_{f}\right) t}}$.
Next, the goal of this proof is to express $\mathbb{E}\left[e^{r x}\right]$ linear algebraically.
Define the diagonal matrix $D_{f}=\left(\begin{array}{cccc}e^{r f(1)} & & & \\ & e^{r f(2)} & & \\ & & \ddots & \\ & & & e^{r f(N)}\end{array}\right)$, with zeros elsewhere.
Let $u=\frac{1}{N} \overrightarrow{1} . \mathbb{E}\left[e^{r x}\right]=\left\|u D_{f}\left(A D_{f}\right)^{t-1}\right\|_{1}$ (this equality is a linear algebraic interpretation of expectation). Next, we will attempt to bound this quantity. $\left\|u D_{f}\left(A D_{f}\right)^{t-1}\right\|_{1}=\left\|u A D_{f}\left(A D_{f}\right)^{t-1}\right\|_{1}=\left\|u\left(A D_{f}\right)^{t}\right\|_{1}$ since $u A=A$, as $\overrightarrow{1}$ is an eigenvalue of this matrix.
Applying Cauchy-Schwarz and then the submultiplicativity of the $L_{2}$ norm:
$\left\|u\left(A D_{f}\right)^{t}\right\|_{1} \leq \sqrt{N}\left\|u\left(A D_{f}\right)^{t}\right\|_{2} \leq \sqrt{N}\|u\|_{2}\left\|\left(A D_{f}\right)^{t}\right\|_{2}=\sqrt{N} * \frac{1}{\sqrt{N}}\left\|\left(A D_{f}\right)^{t}\right\|_{2}=\left\|\left(A D_{f}\right)^{t}\right\|_{2}$. Next, applying submultiplicativity again: $\left\|\left(A D_{f}\right)^{t}\right\|_{2} \leq\left(\left\|A D_{f}\right\|_{2}\right)^{t}$. Now, we aim to bound $\left\|A D_{f}\right\|_{2}$.
We will apply the matrix decomposition lemma from a previous lecture:

Lemma 7.2 The adjacency matrix $A$ of a spectral expander with expansion $\gamma=1-\lambda$ can be decomposed as $A=\gamma J+\lambda E$. such that $J$ is $\frac{1}{N}$ times the all ones matrix, $\|E\|_{2} \leq 1$, and $\gamma, \lambda$ are scalars.
This lemma has an interesting interpretation in the context of expander graphs. Since $J$ is the normalized adjacency matrix of a fully connected graph, random walks on such a graph converge to uniformity very quickly. Since the adjacency matrix $A$ deviates from $J$ by a small amount (a matrix $E$ with spectral norm less than or equal to 1 ), this means that an expander is not far from one whose random walks converge to uniformity quickly.

Continuing with the proof of the Expander Chernoff bound, and specifically bounding $\left\|A D_{f}\right\|_{2},\left\|A D_{f}\right\|_{2} \leq$ $\gamma\left\|J D_{f}\right\|_{2}+\lambda\left\|E D_{f}\right\|_{2}$ (using the triangle inequality and the matrix decomposition lemma). $\left\|J D_{f}\right\|_{2},\left\|E D_{f}\right\|_{2}$ will be bound individually to bound $\left\|A D_{f}\right\|$.
$\left\|E D_{f}\right\|_{2} \leq\left\|E_{2}\right\|_{2}\left\|D_{f}\right\|_{2} \leq 1 *\left\|D_{f}\right\|_{2} \leq \max _{i \in[N]}\left(e^{r f(i)}\right)$. Since $f(i) \in\{0,1\}, e^{r * f(i)} \leq e^{r} \leq 1+r+O\left(r^{2}\right)$ using a Taylor expansion.
$\left\|J D_{f}\right\|_{2}=\max _{x \in R_{n},\|x\|_{2}=1}\left\|J D_{f} x\right\|_{2}$. Looking at $J D_{f} x$, it is equal to $J *\left(x_{1} e^{r f(1)}, x_{2} e^{r f_{2}}, \ldots x_{n} e^{r f(n)}\right)=$ $\frac{1}{N} \sum_{i=1}^{N} x_{i} e^{r f(i)} \cdot \overrightarrow{1}$. Hence, $\left|\left|J D_{f} x \|_{2} \leq \frac{1}{N}\right| \sum_{i=1}^{N} x_{i} e^{r f(i)}\right| * \sqrt{N}=\frac{1}{\sqrt{N}}\left|\sum_{i=1}^{N} x_{i} e^{r f(i)}\right|$. This is bounded above by $\frac{1}{\sqrt{N}}\left(\sum_{i} x_{i}^{2}\right)^{\frac{1}{2}}\left(\sum e^{2 r f(i)}\right)^{\frac{1}{2}}$. Applying a Taylor expansion, this is bounded above by $\frac{1}{\sqrt{N}}\left(\sum_{i=1}^{N}(1+2 r f(i)+\right.$ $\left.\left.O\left(r^{2}\right)\right)\right)^{\frac{1}{2}}$. Since $f(i) \in[0,1]$, this can be again bounded by $\frac{1}{\sqrt{N}}\left(N+2 r \mu_{f} N+N O\left(r^{2}\right)\right)^{\frac{1}{2}} \leq 1+r \mu_{f}+O\left(r^{2}\right)$ (the last step is justified by the Taylor series for $f(x)=\sqrt{x}$.

Using these bounds (and that $\lambda+\gamma=1)\left\|A D_{f}\right\|_{2} \leq \gamma\left(1+r \mu_{f}\right)+\lambda(1+r)+O\left(r^{2}\right) . \leq 1+r\left(\lambda+\mu_{f}\right)+O\left(r^{2}\right)$.
Next, $\mathbb{E}\left[e^{r x}\right] \leq\left(\left\|A D_{f}\right\|_{2}\right)^{t} \leq e^{r t\left(\lambda+\mu_{f}\right)+O\left(r^{2}\right) t}$. Plugging this bound into the bound from Markov's inequality, $\Delta \leq \frac{\mathbb{E}\left[e^{r x}\right]}{e^{r\left(\delta+\lambda+\mu_{f}\right) t}} . \leq \frac{e^{r t\left(\lambda+\mu_{f}\right)+O\left(t r^{2}\right)}}{e^{r t\left(\lambda+\mu_{f}\right)+r t \delta}}=e^{O\left(r^{2} t\right)-r t \delta}$. Choosing $r=\frac{\delta}{C}$, such that $C$ is a large constant, this yields the desired bound of $e^{-\Omega\left(\delta^{2} t\right)}$.

### 7.2 Using the Expander Mixing Lemma for Error reduction in BPP

Let A be an algorithm for $L \in B P P$ that uses $R$ bits of randomness and time $T$. Remember that $\forall x \in$ $L, y \sim[0,1]^{R}, \operatorname{Pr}[A(x, y)=1] \geq \frac{2}{3}$, and $\forall x \notin L, y \sim[0,1]^{R}, \operatorname{Pr}[A(x, y)=0] \geq \frac{2}{3}$
Take an expander $G$ on $\left[2^{R}\right]$ nodes, $\lambda=\delta=\frac{1}{20}$ (and $D=O(1)$ probabilistically). Now, for a fixed $x$, define the function $f:\left[2^{R}\right] \rightarrow[0,1]$, where $f(y)$ returns 1 if $A(x, y)$ is correct, and 0 otherwise. Since the two sided success probability of $A$ is $\frac{2}{3}, f(y)=1$ for at least $\frac{2}{3}$ of random bit strings, so $\mu_{f} \geq \frac{2}{3}$.
Define $A^{\prime}$ to run $A\left(x, l_{1}\right), A\left(x, l_{2}\right), \ldots A\left(x, l_{t}\right)$, where $l_{1}, l_{2}, \ldots, l_{t}$ are random bitstrings of length $R$ taken from a random walk of expander $G$, and output the majority answer from these $t$ executions.
Now, since $\delta, \lambda$, are constant, $\mu_{f} \geq \frac{2}{3}$, and $\mu_{f}-\delta-\lambda \geq \frac{1}{2}$, the error probability of $A^{\prime}$ is bounded by $e^{-\Omega(t)}$. Defining this error probability as $\epsilon$, reducing the error probability to $\epsilon$ requires $O\left(\log \left(\frac{1}{\epsilon}\right)\right)$ executions of $A$. The random bits required for this algorithm are $R$ bits to sample the first vertex in the walk, and then $O\left(\log \left(\frac{1}{e}\right)\right)$ random bits (a constant number of bits per iteration of the $A$ to take a step in the expander walk.)

Making a table of time vs random bits required for various error reduction techniques for $B P P$ algorithms shows that this approach is both efficient in terms of random bits and time.

| Error Reduction Technique | Time | Random Bits |
| :---: | :---: | :---: |
| Expander Walk | $T \cdot O\left(\log \left(\frac{1}{\epsilon}\right)\right)$ | $R+O\left(\log \left(\frac{1}{\epsilon}\right)\right)$ |
| I.i.d Repetitions | $T \cdot O\left(\log \left(\frac{1}{\epsilon}\right)\right)$ | $R \cdot O\left(\log \left(\frac{1}{\epsilon}\right)\right)$ |
| Pairwise Independent Repetitions | $T \cdot O\left(\frac{1}{\epsilon}\right)$ | $R+2 \log \left(\frac{1}{\epsilon}\right)+O(1)$ |

### 7.3 Bounds on Expansion of Graphs

Definition 7.3 The spectral gap, $\gamma$ of a graph is $1-\lambda$, where $\lambda$ is the second largest eigenvalue of the graph's normalized adjacency matrix.

Theorem 7.4 [Alon-Boppana]: $\lambda \geq \frac{1}{D} 2 \sqrt{D-1}-o_{N}(1)$, where $G$ is $D$ regular.
A result of Ramanujan is that there exist graphs (Ramanujan expanders) for which $\lambda \leq \frac{2 \sqrt{D-1}}{D}$, which nearly achieve the bound of Alon and Boppana.

Claim 7.5 We will show a weaker result, that $\lambda \geq \sqrt{D-1}-o_{N}(1)$.
Let $M$ be the unnormalized adjacency matrix of expander $G$. By inspection, $\operatorname{tr}\left(M^{2}\right)$ is equal to the number of length 2 walks that start and end at the same vertex of $G$. This quantity is bounded above by $N D$, since each vertex can have a maximum of $D$ length 2 walks for each of the $D$ vertices leaving it.

By the properties of eigenvalues, $\operatorname{tr}\left(M^{2}\right)=D^{2} \sum_{i=1}^{N} \lambda_{i}^{2}$, where $\lambda_{i}$ is the $i$ th eigenvalue of $A$, the normalized adjacency matrix of $G$.

Combining these bounds, $\operatorname{tr}\left(M^{2}\right)=D^{2} \sum_{i+1}^{N} \lambda_{i}^{2} \leq N D$. Subtracting the largest eigenvalue and dividing yields $D^{2} \sum_{i=2}^{N} \lambda_{i}^{2} \leq N D-D^{2}$ and $\sum_{i=2}^{N} \lambda_{i}^{2} \leq \frac{N-D}{D}$. Finally, bounding each eigenvalue by $\lambda_{2}$ yields that $\lambda_{2} \geq \sqrt{\frac{N-D}{D N}}$.

Finally, if $D \ll N$ (which is achievable since $D$ can be $O(1)$ ), this yields the desired bound.

### 7.4 Explicit Constructions of Expanders

Definition 7.6 The Margulis-Gabbard-Galil Construction is a graph where $V=\mathbb{Z}_{m} \times \mathbb{Z}_{m}$, and the edges satisfy $(x, y) \rightarrow(x \pm y, y),(x, y) \rightarrow(x \pm(y+1), y),(x, y) \rightarrow(x, x \pm y)$, or $(x, y) \rightarrow(x, y \pm(x+1))$.

This construction achieves $\left(m^{2}, \gamma\right)$ expansion, where $\gamma$ is a constant greater than 0 . This graph is 8 -regular and strongly-explicit (see definition below). The proof that this is an expander is beyond the scope of this class.

Definition 7.7 We will say that the construction of a graph on $N$ nodes is strongly explicit if there exists an algorithm that determines whether there is an edge between any two vertices in poly $(\log (N))$ time.

Definition 7.8 We will say that the construction of a graph on $N$ nodes is mildly explicit if there exists an algorithm that runs in time poly $(N)$ and outputs the adjacency matrix of the graph.

We will study a more combinatorial construction of an expander. The approach will be to start with a constant sized expander (which we know exists from the probabilistic method, and hence can be found by a brute-force search in constant time) and create larger expanders graphs via using various graph products, such as graph squaring, the tensor product, and the zig-zag product.

