

Hyperparameter optimization

CS6787 Lecture 6 — Fall 2019

But First...

Final Project Parameters

CS 6787 — Fall 2019

Overview

- **Implement a machine learning system** to solve a problem
- Use one or more of the **techniques we discussed in class**
- To achieve an **improvement over some baseline method**
 - Measuring both statistical performance and hardware performance
 - Or at least evaluate and attempt to achieve such a speedup
- Otherwise, very **open-ended**
 - **Groups of up to three**

Project proposals due in two weeks

- The main body should be about one page in length.
- It should describe the project you intend to do.
- It should contain at least one citation of a relevant paper that we did not cover in class.
- It should include some preliminary or exploratory work you've already done, that helps to support the idea that your project is feasible.
 - Doesn't have to be much work at all, just a nonzero amount of work.
- In addition to the one-page text proposal, one short **experiment plan** per person

Experiment plan

- The hypothesis
- The proxy
- The protocol
- Expected results

In-class feedback activity

- On **Wednesday, October 16**
- Basically, breakout sessions to discuss your project ideas with your peers.
 - You are not committing to work on the specific project you present during the feedback activity. You can always change your ideas as a result of the feedback.
- Prepare a **two-minute verbal pitch** of your ideas.
- And try not to sit with others in your group.
 - To get a wider variety of feedback.

Questions?

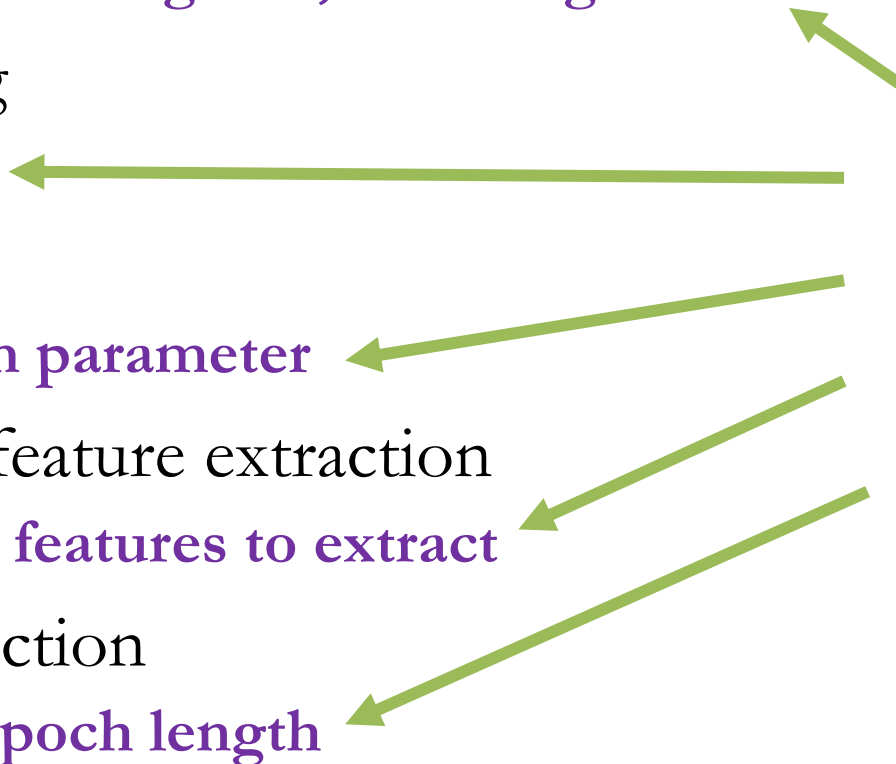
Hyperparameter optimization

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Review — We've covered many methods

- Stochastic gradient descent
 - Step size/learning rate, how long to run
- Mini-batching
 - Batch size
- Momentum
 - Momentum parameter
- Kernel trick/feature extraction
 - How many features to extract
- Variance reduction
 - Step size, epoch length

How do we
set these
parameters?

The text 'How do we set these parameters?' is positioned on the right side of the slide. Five green arrows originate from this text and point to specific parameters in the list above: one points to 'Step size/learning rate, how long to run', one points to 'Batch size', one points to 'Momentum parameter', one points to 'How many features to extract', and one points to 'Step size, epoch length'.

So Far: Theory

- Theoretical analysis of convex problems gives us a **recipe** for assigning hyperparameters
 - Also gives **guarantees** that the algorithm will converge with some optimal rate
- Often based on strong-convexity/Lipschitz constants μ , L , etc.
 - Parameters that we can **bound analytically**, regardless of the data
- This is usually enough to get an **asymptotically optimal rate**
 - Certainly in the worst case

The Worst-Case Perspective

- Essentially, the theory I showed you is doing

$$\arg \min_{\text{parameters}} \max_{\text{data}} (\text{objective})$$

- We're **not using the training data** at all to set the parameters
 - Or if we are, we're only using it to compute constants like μ and \mathbf{L}
- Question: **can we use the data to improve our choice of parameters over what the theory gives us?**

Demo

What happened?

- Theory only **minimizes an upper bound** on the objective.
- But actual algorithm can **do much better than the bound**.
 - As we saw in the demo.
- Problem: in the demo, to find the best parameter setting, we had to first solve the problem exactly, then run the algorithm many times.
 - **Computationally intractable** in practice!
- **Can we use a cheaper heuristic to set the parameters?**

Hyperparameter Optimization

Hyperparameter Optimization

- Also called **metaparameter optimization**
- Also called **tuning**
- Any system that chooses hyperparameters automatically
- **What's the difference between the model parameters, and the hyperparameters?**

Many Settings; Many Strategies

- In some settings, just care about the model accuracy
 - Just want to set things like the learning rate
- In other settings, also want to make the hardware fast
 - Want to choose what hardware to run on, how many cores, etc.
- In all settings, there's **many ways to do hyperparameter optimization**

Simplest Strategy: The Null Hyperparameter Optimizer

- Simplest thing to do is to **just set the parameters based on folklore.**
- Minibatch size: $\mathbf{b} =$
- Momentum: $\beta =$
- SVRG: epoch length = x Training Set Size

The Effect of Using Folklore

- **Folklore can lead you astray!**
 - Can actually find **simple cases where the folklore settings are wrong.**
 - This is a good way to start a research paper.
- ...but **folklore is folklore for a reason!**
 - It exists where people have found empirically that they get good results.
 - So when you try something new, the **first thing to compare to is folklore.**
- To be honest, the results you get from just using the folklore settings are really not that bad for a lot of practical purposes.

From the simplest strategy to... The Most Complicated Strategy

- Spend **twenty-five years training a Strong AI on custom hardware**, then have it set your hyperparameters.
- ...more explicitly, just **get a human to set your hyperparameters**.
- Fortunately, we happen to have a lot of humans
 - But human effort, particularly expert human effort, doesn't scale.

Tuning By Hand

- Just fiddle with the parameters until you get the results you want
- Probably **the most common type of hyperparameter optimization**
- Upsides: the results are generally pretty good...
- Downsides: **lots of effort**, and no theoretical guarantees
 - Although there's nothing fundamental that prevents us from having theory here

Demo

Grid Search

- Define some grid of parameters you want to try
- Try all the parameter values in the grid
 - By **running the whole system** for each setting of parameters
- Then **choose the setting with the best result**
- Essentially a **brute force method**

Downsides of Grid Search

- As the number of parameters increases, the cost of grid search **increases exponentially!**
 - **Why?**
- Still need some way to choose the grid properly
 - Something this can be as hard as the original hyperparameter optimization
- Can't take advantage of any **insight** you have about the system!

Making Grid Search Fast

- **Early stopping to the rescue**

- Can run all the grid points for one epoch, then discard the half that performed worse, then run for another epoch, discard half, and continue.

- Can **take advantage of parallelism**

- Run all the different parameter settings independently on different servers in a cluster.
- An **embarrassingly parallel task**.
- Downside: **doesn't reduce the energy cost**.

One Variant: Random Search

- This is just grid search, but with randomly chosen points instead of points on a grid.
- **This solves the curse of dimensionality**
 - Don't need to increase the number of grid points exponentially as the number of dimensions increases.
- Problem: with random search, **not necessarily going to get anywhere near the optimal parameters** in a finite sample.

One Variant: Best Ball

- Works with epochs.
- At each epoch, do a small grid search **around the current hyperparameter settings**
- Then evaluate the objective and choose the **“best ball”**
 - The choice of parameters that gave the best objective for that epoch
- And repeat until a solution of desired quality is achieved.

An Alternative: Bayesian Optimization

- Statistical approach for **minimizing noisy black-box functions**.
- Idea: **learn a statistical model** of the function from hyperparameter values to the loss function
 - Then choose parameters to minimize the loss under this model
- Main benefit: choose the hyperparameters to test not at random, but in a way that gives the **most information about the model**
 - This lets it learn faster than grid search

Effect of Bayesian Optimization

- Downside: it's a pretty **heavyweight method**
 - The updates are not as simple-to-implement as grid search
- Upside: empirically it has been demonstrated to **get better results in fewer experiments**
 - Compared with grid search and random search
- Pretty widely used method
 - Lots of research opportunities here.

A related method: DFO

- **Derivative-free optimization**
- Also called **zeroth-order optimization**
- These methods optimize a function using only evaluations, no derivatives
- Ideal for use with hyperparameter optimization
 - Also ideal for **reinforcement learning**

The opposite of DFO

Gradient-based optimization

- These strategies say: **“I’m doing SGD to learn, I may as well use it to optimize my hyperparameters.”**
- When we can efficiently differentiate with respect to the hyperparameters, this strategy actually works pretty well.
- But generally, we **can’t do it.**

Methods that Look at the Data

- Many methods look at curvature/variance info to decide how to set hyperparameters, and update their settings throughout the algorithm
- Example: **ADAGRAD**
- Example: **Adam**
 - Which you will be reading in a few weeks.

Evaluating the Hyperparameter Optimization

How to evaluate the hyperparameters?

- Unlike the model parameters, we're **not given a loss function**
- **Can't we just use the training loss?**
- **Not always:** we don't want to **overfit the hyperparameters**
 - Especially not when they are things that affect the model

Cross-Validation

- Partition part of the available data to create an **validation dataset** that we don't use for training.
- Then **use that set to evaluate the hyperparameters.**
- Typically, **multiple rounds of cross-validation** are performed using different partitions
 - Can get a very good sense of how good the hyperparameters are
 - But at a **significant computational cost!**

Evaluating the System Cost

- In practice we **don't just care about the statistics**
 - Not just about the accuracy after a fixed number of iterations
- We care about wall-clock **time**, and we care about **energy**
 - How much did solving this problem **actually cost**?
- The parameters we chose can affect these systems properties
 - As we saw with our SVRG demo!
- Need to **include systems cost as part of the metric!**

Hardware efficiency

- **How long does an iteration take, on average?**
- Hardware efficiency measures the systems cost of doing a single update.
- Key point: many hyperparameters do not affect hardware efficiency
 - **Which ones?**
- **Which hyperparameters do affect hardware efficiency?**

Statistical Efficiency

- **How many iterations do we need to get to a specified level of accuracy?**
- Statistical efficiency measures how many updates we need to get an answer of the quality that we want.
- **Which hyperparameters affect statistical efficiency?**
 - **And which ones don't?**

Total performance

- Total cost of running the algorithm is:

HARDWARE EFFICIENCY \times STATISTICAL EFFICIENCY

- We can estimate these quantities separately, then use their product to evaluate our hyperparameters.
- For example, we can use theory to evaluate statistical efficiency and a hardware model to evaluate hardware efficiency.

Benefits of Looking at Both

- Looking at **both statistical and hardware efficiency together** has some important benefits!
- Many times the **optimal parameter settings are different** than if you set the parameters to optimize hardware efficiency or statistical efficiency individually.
- There's a lot of **open research opportunities** here!

One example: YellowFin Tuner

- System that among other things tunes the **momentum**
 - As well as using **asynchronous parallelism**, which we'll talk about later.

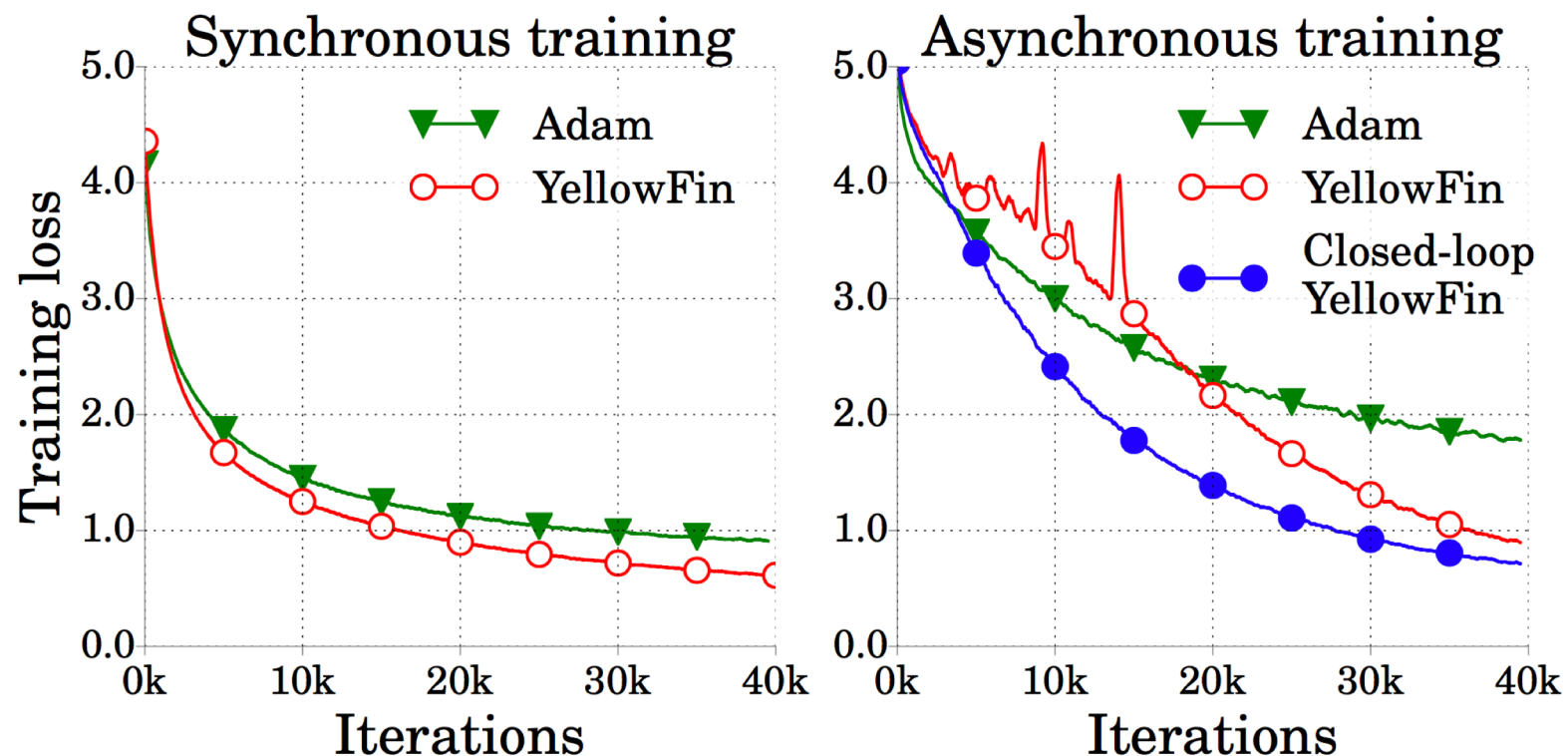


Figure 1 from
“YellowFin and the Art of Momentum Tuning”
Zhang et al, 2017.

Questions?

- Upcoming things
 - Fall break next Monday — **no lecture**
 - Paper review 4a or 4b **due Today**
 - Paper Presentation #5 **on Wednesday**
 - In class discussion of project ideas **the following Wednesday**