Machine Learning Theory (CS 6783)

Lecture 2 : Learning Frameworks, Minimax Rates, No Free Lunch Theorem and ERM

1 Setting up learning problems

1. $\mathcal{X}$ **: instance space or input space**
   Examples:
   - Computer Vision: Raw $M \times N$ image vectorized $\mathcal{X} = [0, 255]^{M \times N}$, SIFT features (typically $\mathcal{X} \subseteq \mathbb{R}^d$)
   - Speech recognition: Mel Cepstral co-efficients $\mathcal{X} \subset \mathbb{R}^{12 \times \text{length}}$
   - Natural Language Processing: Bag-of-words features ($\mathcal{X} \subset \mathbb{N}^{\text{document size}}$), n-grams
2. $\mathcal{Y}$**: Outcome space, label space**
   Examples: Binary classification $\mathcal{Y} = \{\pm 1\}$, multiclass classification $\mathcal{Y} = \{1, \ldots, K\}$, regression $\mathcal{Y} \subset \mathbb{R}$)
3. $\ell : \mathcal{Y} \times \mathcal{Y} \mapsto \mathbb{R}$**: loss function** (measures prediction error)
   Examples: Classification $\ell(y', y) = \mathbb{1}_{\{y' \neq y\}}$, Support vector machines $\ell(y', y) = \max\{0, 1 - y' \cdot y\}$, regression $\ell(y', y) = (y - y')^2$
4. $\mathcal{F} \subset \mathcal{Y}^{\mathcal{X}}$**: Model/ Hypothesis class** (set of functions from input space to outcome space)
   Examples:
   - Linear classifier: $\mathcal{F} = \{x \mapsto \text{sign}(f^\top x) : f \in \mathbb{R}^d\}$
   - Linear SVM: $\mathcal{F} = \{x \mapsto f^\top x : f \in \mathbb{R}^d, \|f\|_2 \leq R\}$
   - Neural Netoworks (deep learning): $\mathcal{F} = \{x \mapsto \sigma(W_{out}\sigma(W_K\sigma(\ldots\sigma(W_2(W_1\sigma(W_{in}x)))))\}$ where σ is some non-linear transformation (Eg. ReLU)

Learner observes sample: $S = (x_1, y_1), \ldots, (x_n, y_n)$

Learning Algorithm : (forecasting strategy, estimation procedure)

$$\hat{\mathbf{y}} : \mathcal{X} \times \bigcup_{t=1}^{\infty} (\mathcal{X} \times \mathcal{Y})^t \mapsto \mathcal{Y}$$

Given new input instance x the learning algorithm predicts $\hat{\mathbf{y}}(x, S)$. When context is clear (ie. sample S is understood) we will fudge notation and simply use notation $\hat{\mathbf{y}}(\cdot) = \hat{\mathbf{y}}(\cdot, S)$. $\hat{\mathbf{y}}$ is the predictor returned by the learning algorithm.

Example: linear SVM Learning algorithm solves the optimization problem:

$$\mathbf{w}_{\text{SVM}} = \underset{\mathbf{w}}{\text{argmin}} \sum_{t=1}^{n} \max\{0, 1 - y_t \mathbf{w}^\top x_t\} + \lambda \|\mathbf{w}\|$$

and the predictor is $\hat{\mathbf{y}}(x) = \hat{\mathbf{y}}(x, S) = \mathbf{w}_{\text{SVM}}^\top x$

1.1 PAC framework

$$\mathcal{Y} = \{\pm 1\}, \quad \ell(y', y) = \mathbb{1}_{\{y' \neq y\}}$$

Input instances generated as $x_1, \ldots, x_n \sim D_X$ where D_X is some unknown distribution over input space. The labels are generated as

$$y_t = f^*(x_t)$$

where target function $f^* \in \mathcal{F}$. Learning algorithm only gets sample S and does not know f^* or D_X.

Goal: Find $\hat{\mathbf{y}}$ that minimizes

$$\mathbb{P}_{x \sim D_X} \left(\hat{\mathbf{y}}(x) \neq f^*(x) \right)$$

1.2 Non-parametric Regression

$$\mathcal{Y} \subseteq \mathbb{R}, \quad \ell(y', y) = (y' - y)^2$$

Input instances generated as $x_1, \ldots, x_n \sim D_X$ where D_X is some unknown distribution over input space. The labels are generated as

$$y_t = f^*(x_t) + \varepsilon_t \qquad \text{where } \varepsilon_t \sim N(0, \sigma)$$

where target function $f^* \in \mathcal{F}$. Learning algorithm only gets sample S and does not know f^* or D_X.

Goal: Find $\hat{\mathbf{y}}$ that minimizes

$$\mathbb{E}_{x \sim D_X} \left[(\hat{\mathbf{y}}(x) - f^*(x))^2 \right] =: \|\hat{\mathbf{y}} - f^*\|_{L_2(D_X)}$$

1.3 Statistical Learning (Agnostic PAC)

Generic $\mathcal{X}$, $\mathcal{Y}$, ℓ and $\mathcal{F}$

Samples generated as $(x_1, y_1), \ldots, (x_n, y_n) \sim D$ where D is some unknown distribution over $\mathcal{X} \times \mathcal{Y}$. Goal: Find $\hat{\mathbf{y}}$ that minimizes

$$\mathbb{E}_{(x,y) \sim D} \left[\ell(\hat{\mathbf{y}}(x), y) \right] - \inf_{f \in \mathcal{F}} \mathbb{E}_{(x,y) \sim D} \left[\ell(f(x), y) \right]$$

For any mapping $g : \mathcal{X} \mapsto \mathcal{Y}$ we shall use the notation $L_D(g) = \mathbb{E}_{(x,y) \sim D} \left[\ell(g(x), y) \right]$ and so our goal is to minimize:

$$L_D(\hat{\mathbf{y}}) - \inf_{f \in \mathcal{F}} L_D(f)$$

Remarks: $\hat{\mathbf{y}}$ is a random quantity as it depends on the sample

2 Minimax Rate

How well does the best learning algorithm do in the worst case scenario?

$$\text{Minimax Rate} = \text{“Best Possible Guarantee”}$$

PAC framework:

$$\mathcal{V}_n^{PAC}(\mathcal{F}) := \inf_{\hat{\mathbf{y}}} \sup_{D_X, f^* \in \mathcal{F}} \mathbb{E}_{S:|S|=n} \left[\mathbb{P}_{x \sim D_x} \left(\hat{\mathbf{y}}(x) \neq f^*(x) \right) \right]$$

A problem is “PAC learnable” if $\mathcal{V}_n^{PAC} \to 0$. That is, there exists a learning algorithm that converges to 0 expected error as sample size increases.

Non-parametric Regression:

$$\mathcal{V}_n^{NR}(\mathcal{F}) := \inf_{\hat{\mathbf{y}}} \sup_{D_X, f^* \in \mathcal{F}} \mathbb{E}_{S:|S|=n} \left[\mathbb{E}_{x \sim D_X} \left[(\hat{\mathbf{y}}(x) - f^*(x))^2 \right] \right]$$

A statistical estimation problem is consistent if $\mathcal{V}_n^{NR} \to 0$.

Statistical learning:

$$\mathcal{V}_n^{stat}(\mathcal{F}) := \inf_{\hat{\mathbf{y}}} \sup_{D} \mathbb{E}_{S:|S|=n} \left[L_D(\hat{\mathbf{y}}) - \inf_{f \in \mathcal{F}} L_D(f) \right]$$

A problem is “statistically learnable” if $\mathcal{V}_n^{stat} \to 0$.

A statement in expectation implies statement in high probability by Markov inequality but more generally one can also easily convert to exponentially high probability.

2.1 Comparing the Minimax Rates

Proposition 1. *For any class $\mathcal{F} \subset \{\pm 1\}^{\mathcal{X}}$,*

$$4\mathcal{V}_n^{PAC}(\mathcal{F}) \leq \mathcal{V}_n^{NR}(\mathcal{F}) \leq \mathcal{V}_n^{stat}(\mathcal{F})$$

and for any $\mathcal{F} \subset \mathbb{R}^{\mathcal{X}}$,

$$\mathcal{V}_n^{NR}(\mathcal{F}) \leq \mathcal{V}_n^{stat}(\mathcal{F})$$

That is, if a class is statistically learnable then it is learnable under either the PAC model or the statistical estimation setting

Proof. Let us start with the PAC learning objective. Note that, $\mathbb{1}_{\{\hat{\mathbf{y}}(x) \neq f^*(x)\}} = \frac{1}{4}(\hat{\mathbf{y}}(x) - f^*(x))^2$. Now note that,

$$\mathbb{P}_{x \sim D_x} \left(\hat{\mathbf{y}}(x) \neq f^*(x) \right) = \mathbb{E}_{x \sim D_X} \left[\mathbb{1}_{\{\hat{\mathbf{y}}(x) \neq f^*(x)\}} \right] = \frac{1}{4} \mathbb{E}_{x \sim D_X} \left[(\hat{\mathbf{y}}(x) - f^*(x))^2 \right]$$

Thus we conclude that

$$4\mathcal{V}_n^{PAC}(\mathcal{F}) \leq \mathcal{V}_n^{NR}(\mathcal{F})$$

Now to conclude the proposition we prove that the minimax rate for non-parametric regression is upper bounded by minimax rate for the statistical learning problem (under squared loss).

To this end, in NR we assume that $y = f^*(x) + \varepsilon$ for zero-mean noise ε. Now note that, Now note that, for any $\hat{\mathbf{y}}$,

$$\begin{aligned}
(\hat{\mathbf{y}}(x) - f^*(x))^2 &= (\hat{\mathbf{y}}(x) - y - \varepsilon)^2 \\
&= (\hat{\mathbf{y}}(x) - y)^2 - 2\varepsilon(\hat{\mathbf{y}}(x) - y) + \varepsilon^2 \\
&= (\hat{\mathbf{y}}(x) - y)^2 - (f^*(x) - y)^2 + (f^*(x) - y)^2 - 2\varepsilon(\hat{\mathbf{y}}(x) - y) + \varepsilon^2 \\
&= (\hat{\mathbf{y}}(x) - y)^2 - (f^*(x) - y)^2 + 2\varepsilon^2 - 2\varepsilon(\hat{\mathbf{y}}(x) - y) \\
&= (\hat{\mathbf{y}}(x) - y)^2 - (f^*(x) - y)^2 + 2\varepsilon^2 - 2\varepsilon(\hat{\mathbf{y}}(x) - f^*(x) - \varepsilon) \\
&= (\hat{\mathbf{y}}(x) - y)^2 - (f^*(x) - y)^2 - 2\varepsilon(\hat{\mathbf{y}}(x) - f^*(x))
\end{aligned}$$

Taking expectation w.r.t. y (or ε) we conclude that,

$$\begin{aligned}
\mathbb{E}_{x\sim D_X}\left[(\hat{\mathbf{y}}(x) - f^*(x))^2\right] &= \mathbb{E}_{(x,y)\sim D}\left[(\hat{\mathbf{y}}(x) - y)^2\right] - \mathbb{E}_{(x,y)\sim D}\left[(f^*(x) - y)^2\right] - \mathbb{E}_{x\sim D_X}\left[\mathbb{E}_{\varepsilon}\left[2\varepsilon(\hat{\mathbf{y}}(x) - f^*(x))\right]\right] \\
&= \mathbb{E}_{(x,y)\sim D}\left[(\hat{\mathbf{y}}(x) - y)^2\right] - \mathbb{E}_{(x,y)\sim D}\left[(f^*(x) - y)^2\right] \\
&= L_D(\hat{y}) - \inf_{f\in\mathcal{F}} L_D(f)
\end{aligned}$$

where in the above distribution D has marginal D_X over $\mathcal{X}$ and the conditional distribution $D_{Y|X=x} = N(f^*(x), \sigma)$. Hence we conclude that

$$\mathcal{V}_n^{NR}(\mathcal{F}) \leq \mathcal{V}_n^{stat}(\mathcal{F})$$

when we consider statistical learning under square loss. □