Counterfactual Model for Learning

CS6780 – Advanced Machine Learning

Spring 2019

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Reading:

G. Imbens, D. Rubin, Causal Inference for Statistics …, 2015. Chapters 1,3,12.

Interactive System Schematic

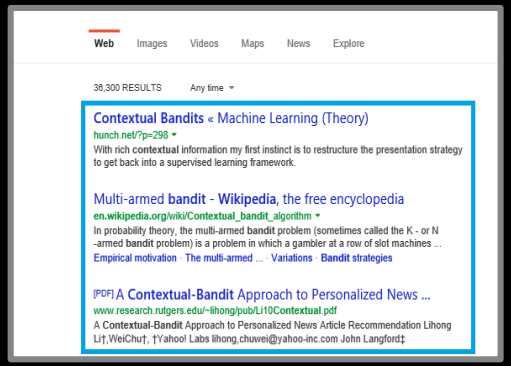
Context x

Feedback $\delta(x, y)$

System π_0

Utility: $U(\pi_0)$

Action y for x

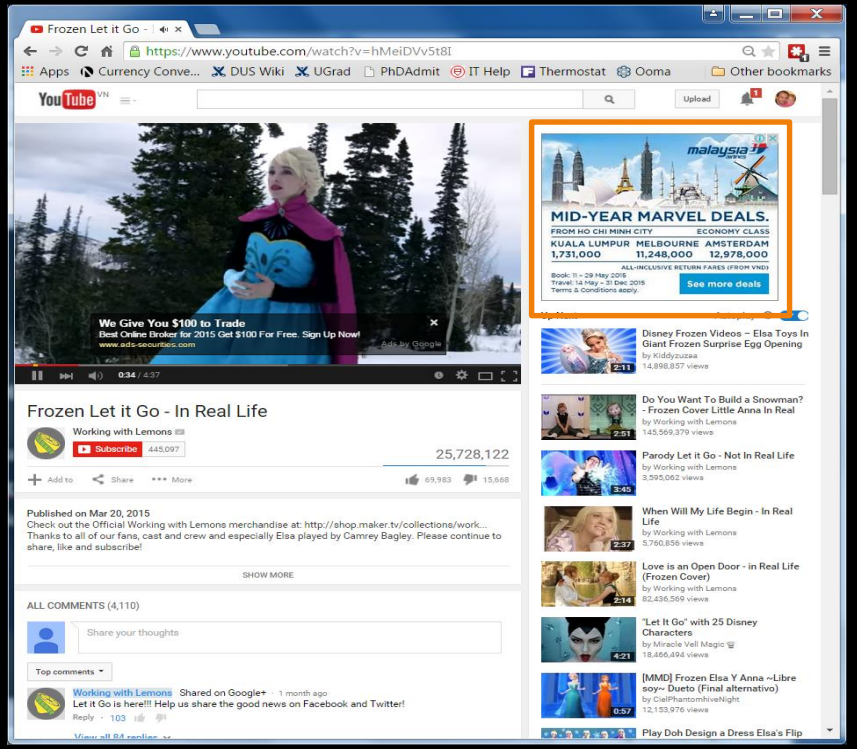


News Recommender

- Context x:
  - User
- Action y:
  - Portfolio of newsarticles
- Feedback $\delta(x, y)$:
  - Reading time in minutes

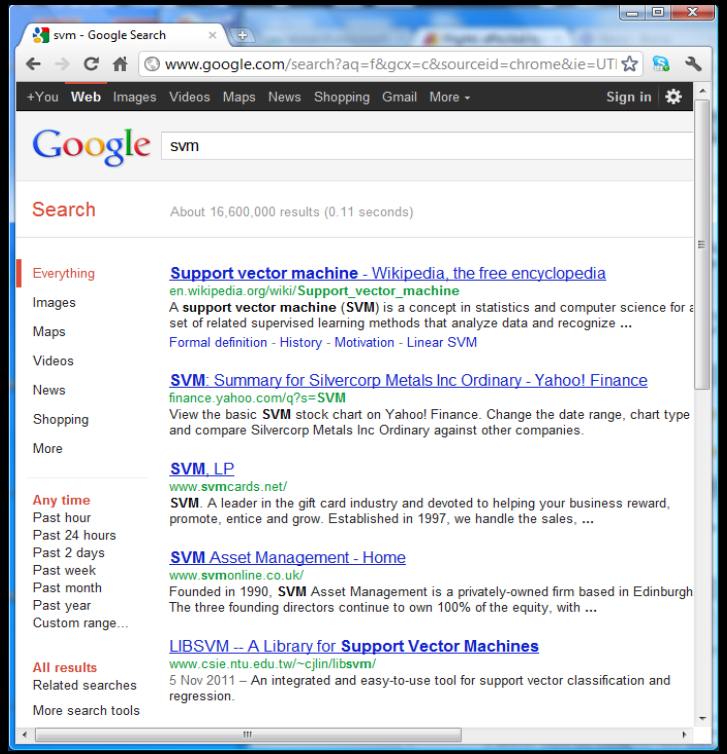
Ad Placement

- Context x:
  - User and page
- Action y:
  - Ad that is placed
- Feedback $\delta(x, y)$:
  - Click / no-click



Search Engine

- Context x:
  - Query
- Action y:
  - Ranking
- Feedback $\delta(x, y)$:
  - Click / no-click



Log Data from Interactive Systems

- Data

$$S = \left((x_1, y_1, \delta_1), \ldots, (x_n, y_n, \delta_n)\right)$$

→ Partial Information (aka "Contextual Bandit") Feedback

- Properties
  - Contexts x_i drawn i.i.d. from unknown $P(X)$
  - Actions y_i selected by existing system π_0: $X \rightarrow Y$
  - Feedback δ_i from unknown function $\delta: X \times Y \rightarrow \Re$

[Zadrozny et al., 2003] [Langford & Li], [Bottou, et al., 2014]

Goal

Use interaction log data

$$S = \left((x_1, y_1, \delta_1), \ldots, (x_n, y_n, \delta_n)\right)$$

- for evaluation of system π
  - Offline estimate of online performace of some system π.
  - System π can be different from π_0 that generated log.
- for learning new system π

Evaluation: Outline

- Offline Evaluating of Online Metrics
  - A/B Testing (on-policy)
    → Counterfactual estimation from logs (off-policy)
- Approach 1: “Model the world”
  - Imputation via reward prediction
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Online Performance Metrics

Example metrics

- CTR
- Revenue
- Time-to-success
- Interleaving
- Etc.

→ Correct choice depends on application and is not the focus of this lecture.

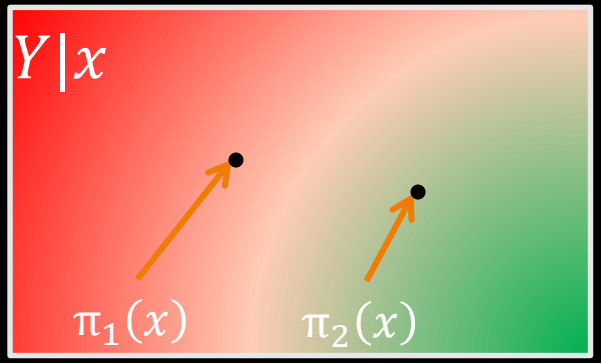
This lecture:

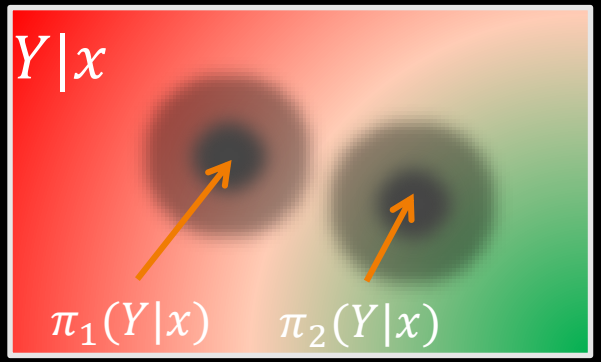
Metric encoded as $\delta(x, y)$ [click/payoff/time for (x,y) pair]

System

- Definition [Deterministic Policy]:
  Function
  $$y = \pi(x)$$
  that picks action y for context x.

- Definition [Stochastic Policy]:
  Distribution
  $$\pi(y|x)$$
  that samples action y given context x



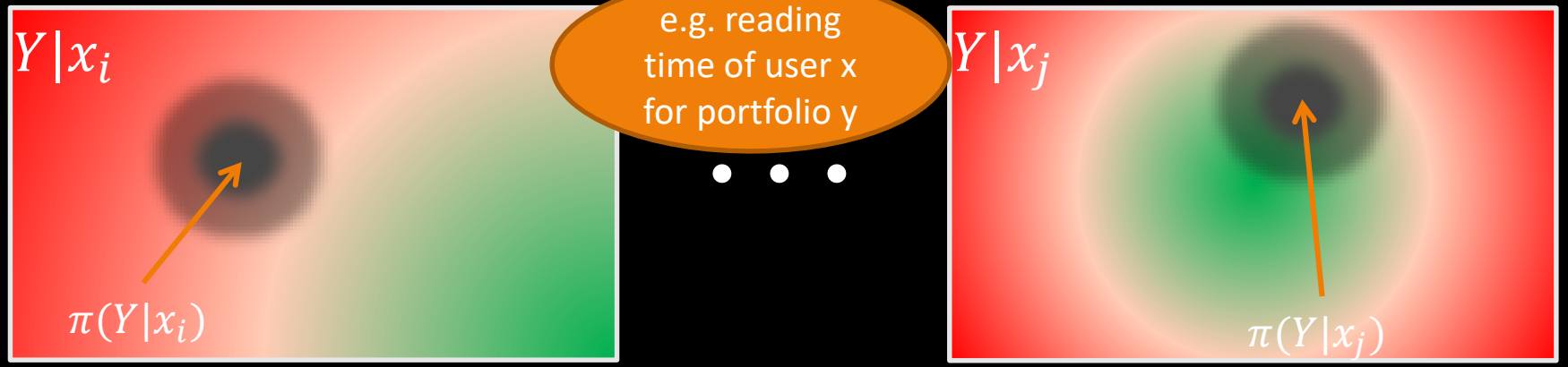


System Performance

Definition [Utility of Policy]:

The expected reward / utility $\mathrm{U}(\pi)$ of policy π is

$$\mathrm{U}(\pi) = \int \int \delta(x, y)\pi(y|x)P(x)\, dx\, dy$$



Online Evaluation: A/B Testing

Given $S = \big((x_1, y_1, \delta_1), \ldots, (x_n, y_n, \delta_n)\big)$ collected under π_0,

$$\widehat{U}(\pi_0) = \frac{1}{n}\sum_{i=1}^{n} \delta_i$$

→ A/B Testing

Deploy π_1: Draw $x \sim P(X)$, predict $y \sim \pi_1(Y|x)$, get $\delta(x, y)$

Deploy π_2: Draw $x \sim P(X)$, predict $y \sim \pi_2(Y|x)$, get $\delta(x, y)$

⋮

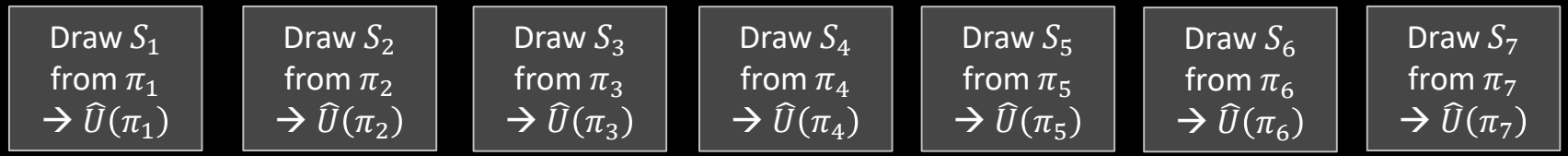
Deploy $\pi_{|H|}$: Draw $x \sim P(X)$, predict $y \sim \pi_{|H|}(Y|x)$, get $\delta(x, y)$

Pros and Cons of A/B Testing

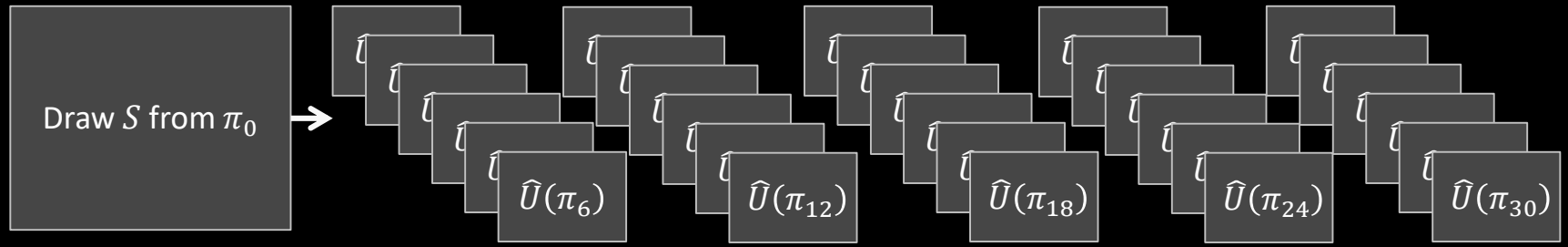
- Pro
  - User centric measure
  - No need for manual ratings
  - No user/expert mismatch
- Cons
  - Requires interactive experimental control
  - Risk of fielding a bad or buggy π_i
  - Number of A/B Tests limited
  - Long turnaround time

Evaluating Online Metrics Offline

- Online: On-policy A/B Test



- Offline: Off-policy Counterfactual Estimates



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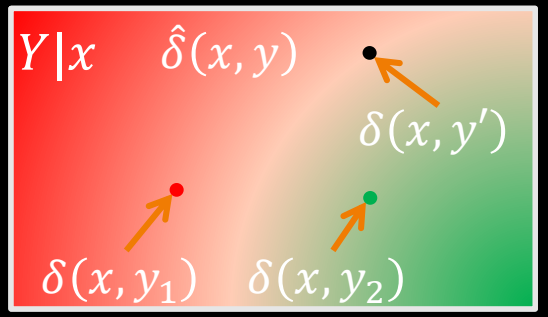
Approach 1: Reward Predictor

- Idea:
  - Use $S = \big((x_1, y_1, \delta_1), \dots, (x_n, y_n, \delta_n)\big)$ from π_0 to estimate reward predictor $\hat{\delta}(x, y)$

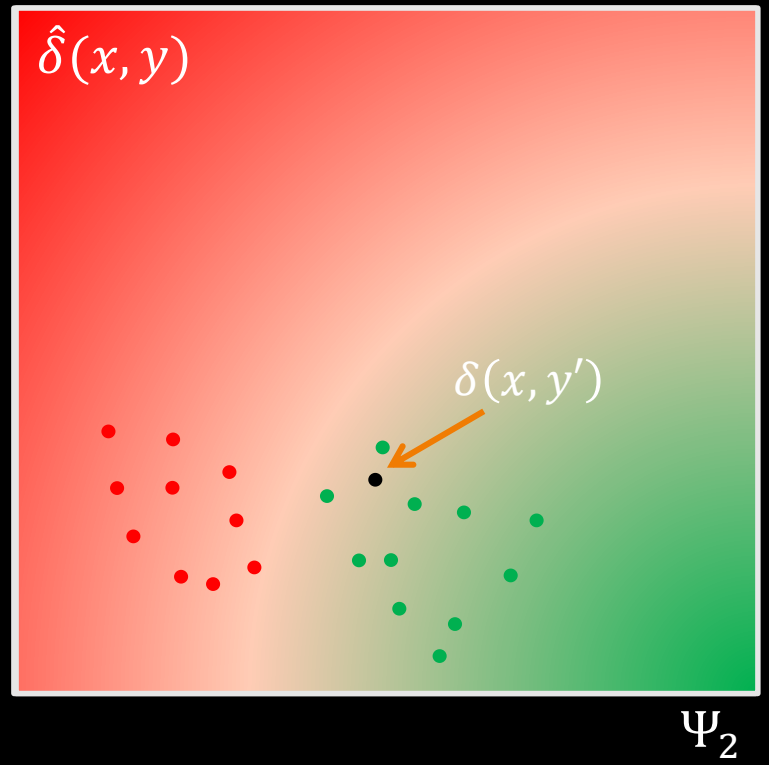


- Deterministic π: Simulated A/B Testing with predicted $\hat{\delta}(x, y)$
  - For actions $y_i' = \pi(x_i)$ from new policy π, generate predicted log $S' = \Big(\big(x_1, y_1', \hat{\delta}(x_1, y_1')\big), \dots, \big(x_n, y_n', \hat{\delta}(x_n, y_n')\big)\Big)$
  - Estimate performace of π via $\widehat{U}_{rp}(\pi) = \frac{1}{n}\sum_{i=1}^{n} \hat{\delta}(x_i, y_i')$
- Stochastic π: $\widehat{U}_{rp}(\pi) = \frac{1}{n}\sum_{i=1}^{n} \sum_{y} \hat{\delta}(x_i, y)\, \pi(y|x_i)$

Regression for Reward Prediction

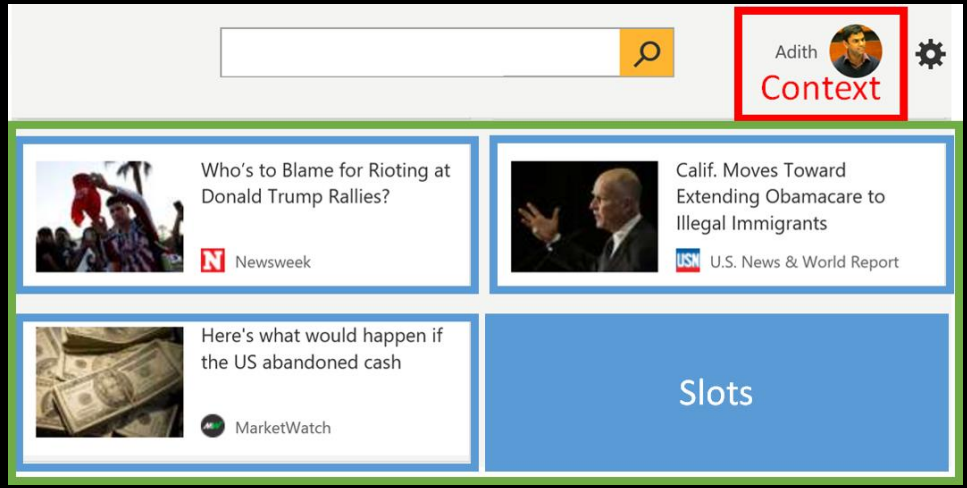
Learn $\hat{\delta}: x \times y \rightarrow \Re$

1. Represent via features $\Psi(x, y)$
2. Learn regression based on $\Psi(x, y)$ from S collected under π_0
3. Predict $\hat{\delta}(x, y')$ for $y' = \pi(x)$ of new policy π



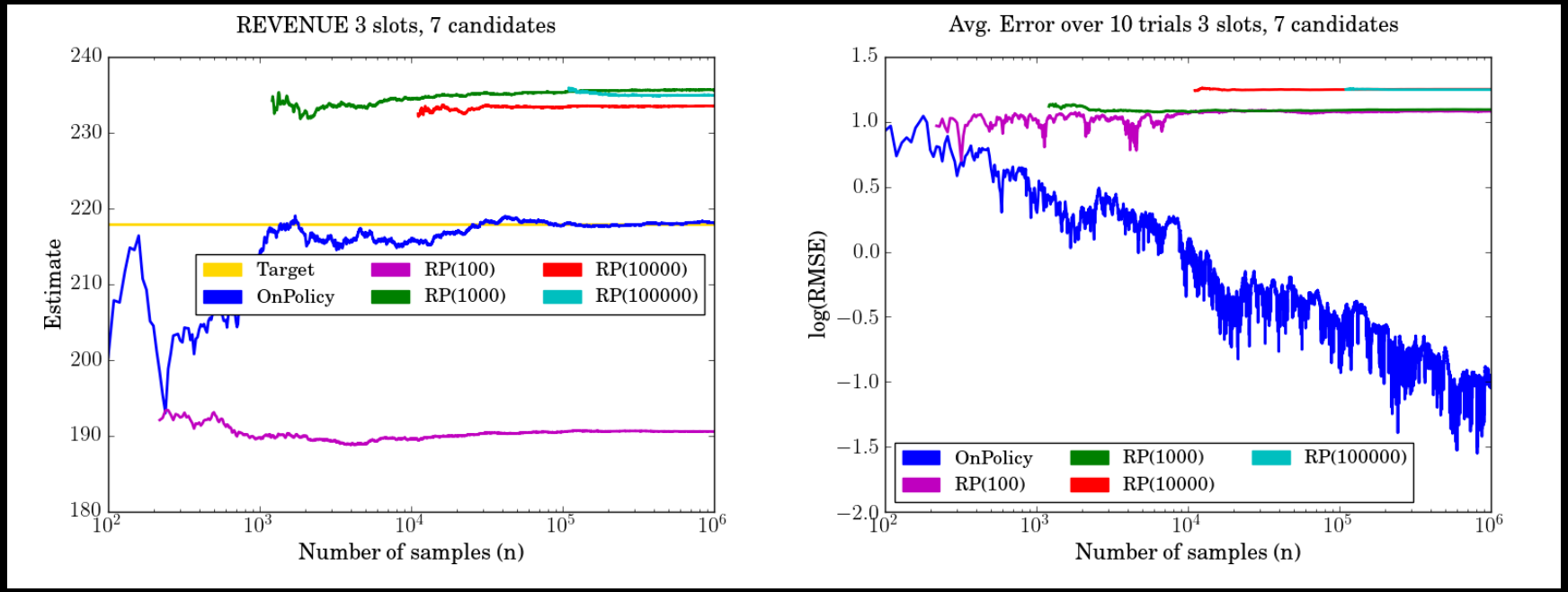
News Recommender: Exp Setup

- Context x: User profile
- Action y: Ranking
  - Pick from 7 candidates to place into 3 slots
- Reward δ: "Satisfaction"
  - Complicated hidden function



- Logging policy π_0: Non-uniform randomized logging system
  - Placket-Luce "explore around current production ranker"

News Recommender: Results



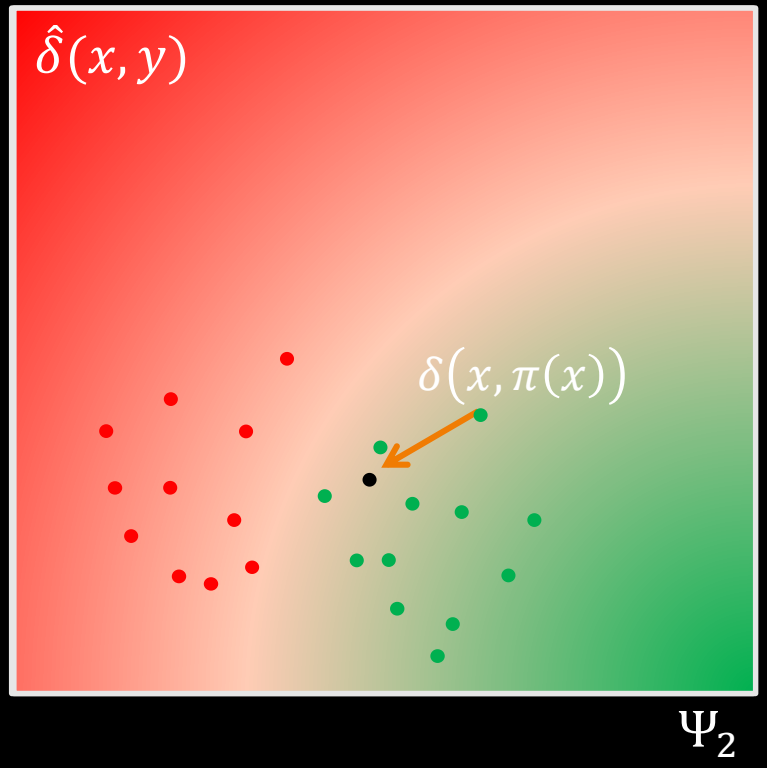
RP is inaccurate even with more training and logged data

Problems of Reward Predictor

- Modeling bias
  - choice of features and model
- Selection bias
  - π_0's actions are over-represented

$$\rightarrow \hat{U}_{rp}(\pi) = \frac{1}{n}\sum_i \hat{\delta}\left(x_i, \pi(x_i)\right)$$

Can be unreliable and biased



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Approach “Model the Bias”

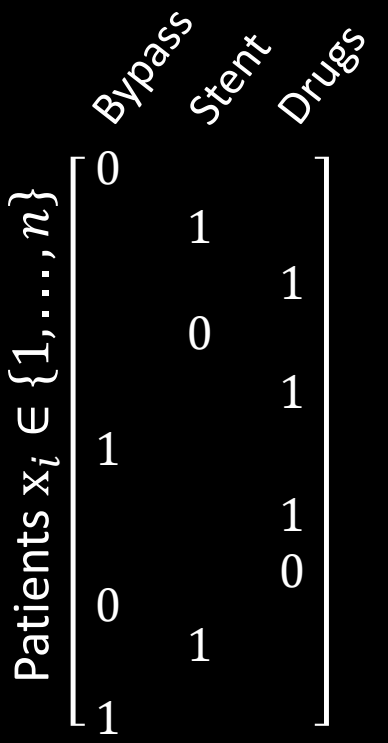
- Idea:

  Fix the mismatch between the distribution $\pi_0(Y|x)$ that generated the data and the distribution $\pi(Y|x)$ we aim to evaluate.

$$\mathrm{U}(\pi) = \int\int \delta(x,y)\frac{\pi(y|x)}{\pi_0(y|x)}P(x)\,dx\,dy$$

Counterfactual Model

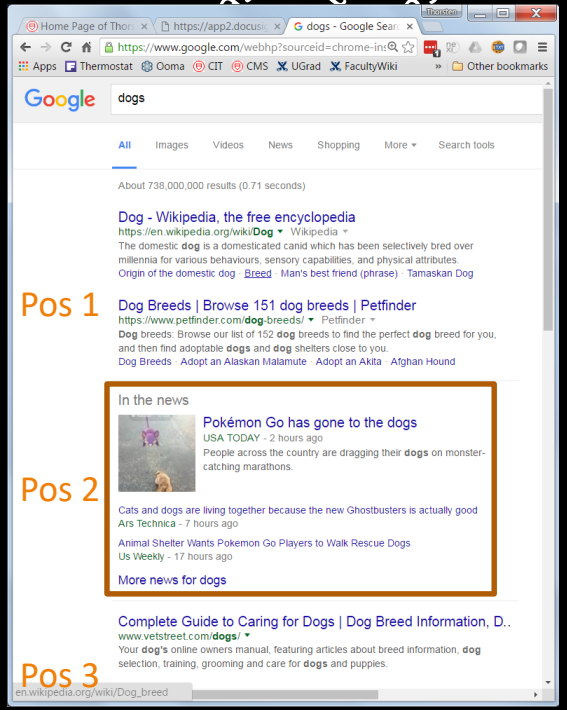
- Example: Treating Heart Attacks
  - Treatments: Y
    - Bypass / Stent / Drugs
  - Chosen treatment for patient x_i: y_i
  - Outcomes: δ_i
    - 5-year survival: 0 / 1
  - Which treatment is best?



Counterfactual Model

Placing Vertical

- Example: ~~Treating Heart Attacks~~
  - Treatments: Y
    - ~~Bypass / Stent / Drugs~~ Pos 1 / Pos 2/ Pos 3
  - Chosen treatment for patient x_i: y_i
  - Outcomes: δ_i
    - ~~5-year survival: 0 / 1~~ Click / no Click on SERP
  - Which treatment is best?



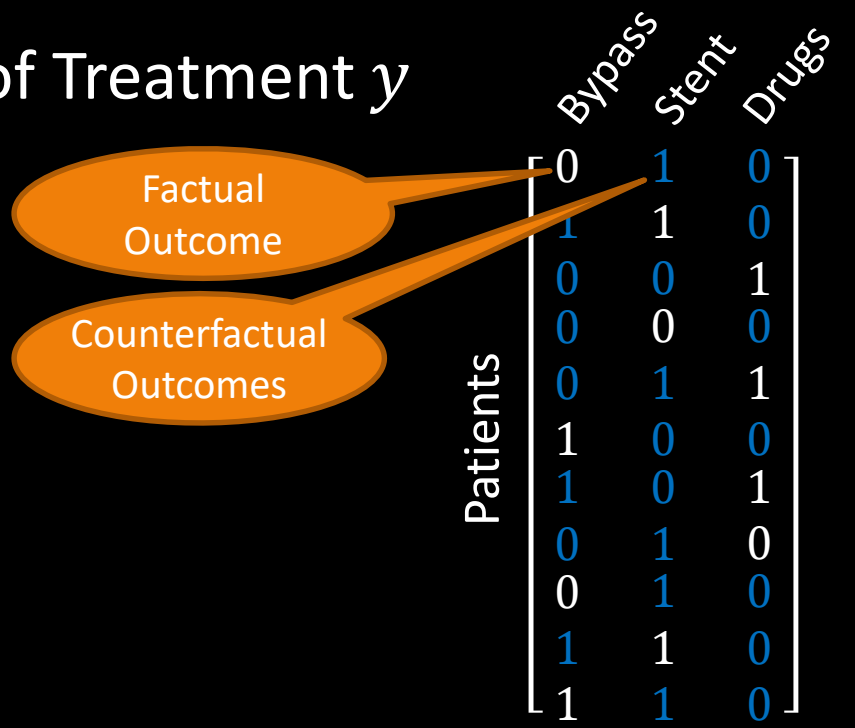
Counterfactual Model

- Example: Treating Heart Attacks
  - Treatments: Y
    - Bypass / Stent / Drugs
  - Chosen treatment for patient x_i: y_i
  - Outcomes: δ_i
    - 5-year survival: 0 / 1
  - Which treatment is best?
    - Everybody Drugs
    - Everybody Stent
    - Everybody Bypass

    → Drugs 3/4, Stent 2/3, Bypass 2/4 – really?

Treatment Effects

- Average Treatment Effect of Treatment y
  - $\mathrm{U}(y) = \frac{1}{n}\sum_i \delta(x_i, y)$
- Example
  - $\mathrm{U}(bypass) = \frac{4}{11}$
  - $\mathrm{U}(stent) = \frac{6}{11}$
  - $\mathrm{U}(drugs) = \frac{3}{11}$



Assignment Mechanism

- Probabilistic Treatment Assignment
  - For patient i: $\pi_0(Y_i = y|x_i)$
  - Selection Bias
- Inverse Propensity Score Estimator
  - $\widehat{U}_{ips}(y) = \frac{1}{n}\sum_i \frac{\mathbb{I}\{y_i = y\}}{p_i}\delta(x_i, y_i)$
  - Propensity: $\mathrm{p_i} = \pi_0(Y_i = y_i|x_i)$
  - Unbiased: $E\left[\widehat{U}(y)\right]$=$U(y)$, if $\pi_0(Y_i = y|x_i) > 0$ for all i
- Example
  - $\widehat{U}(drugs) = \frac{1}{11}\left(\frac{1}{0.8} + \frac{1}{0.7} + \frac{1}{0.8} + \frac{0}{0.1}\right)$
    $= 0.36 < 0.75$

$\pi_0(Y_i = y|x_i)$

0.3	0.6	0.1
0.5	0.4	0.1
0.1	0.1	0.8
0.6	0.3	0.1
0.2	0.5	0.7
0.7	0.2	0.1
0.1	0.1	0.8
0.1	0.8	0.1
0.3	0.3	0.4
0.3	0.6	0.1
0.4	0.4	0.2

Patients

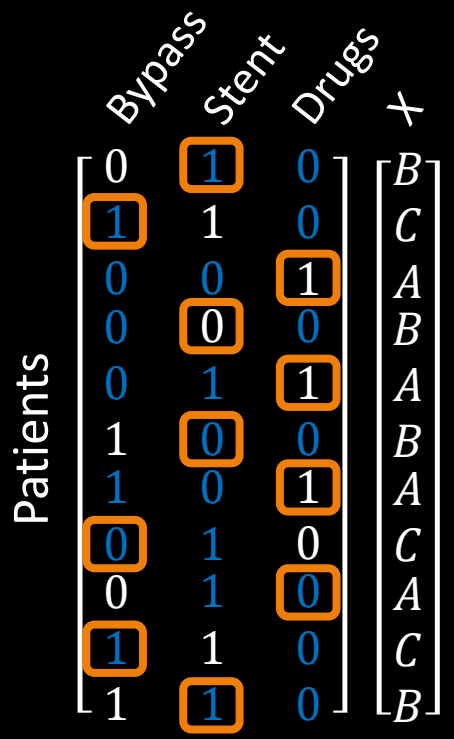
Bypass	Stent	Drugs
0	1	0
1	1	0
0	0	1
0	0	0
0	1	1
1	0	0
1	0	1
0	1	0
0	1	0
1	1	0
1	1	0

Experimental vs Observational

- Controlled Experiment
  - Assignment Mechanism under our control
  - Propensities $p_i = \pi_0(Y_i = y_i|x_i)$ are known by design
  - Requirement: $\forall y: \pi_0(Y_i = y|x_i) > 0$ (probabilistic)
- Observational Study
  - Assignment Mechanism not under our control
  - Propensities p_i need to be estimated
  - Estimate $\hat{\pi}_0(Y_i|z_i) = \pi_0(Y_i|x_i)$ based on features z_i
  - Requirement: $\hat{\pi}_0(Y_i|z_i) = \hat{\pi}_0(Y_i|\delta_i, z_i)$ (unconfounded)

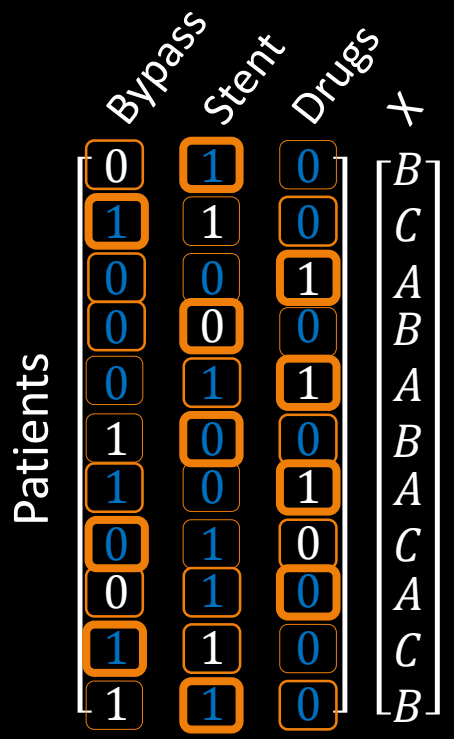
Conditional Treatment Policies

- Policy (deterministic)
  - Context x_i describing patient
  - Pick treatment y_i based on x_i: $\mathrm{y_i} = \pi(x_i)$
  - Example policy:
    - $\pi(A) = drugs, \pi(B) = stent, \pi(C) = bypass$
- Average Treatment Effect
  - $U(\pi) = \frac{1}{n}\sum_i \delta(x_i, \pi(x_i))$
- IPS Estimator
  - $\widehat{U}_{ips}(\pi) = \frac{1}{n}\sum_i \frac{\mathbb{I}\{y_i = \pi(x_i)\}}{p_i}\delta(x_i, y_i)$



Stochastic Treatment Policies

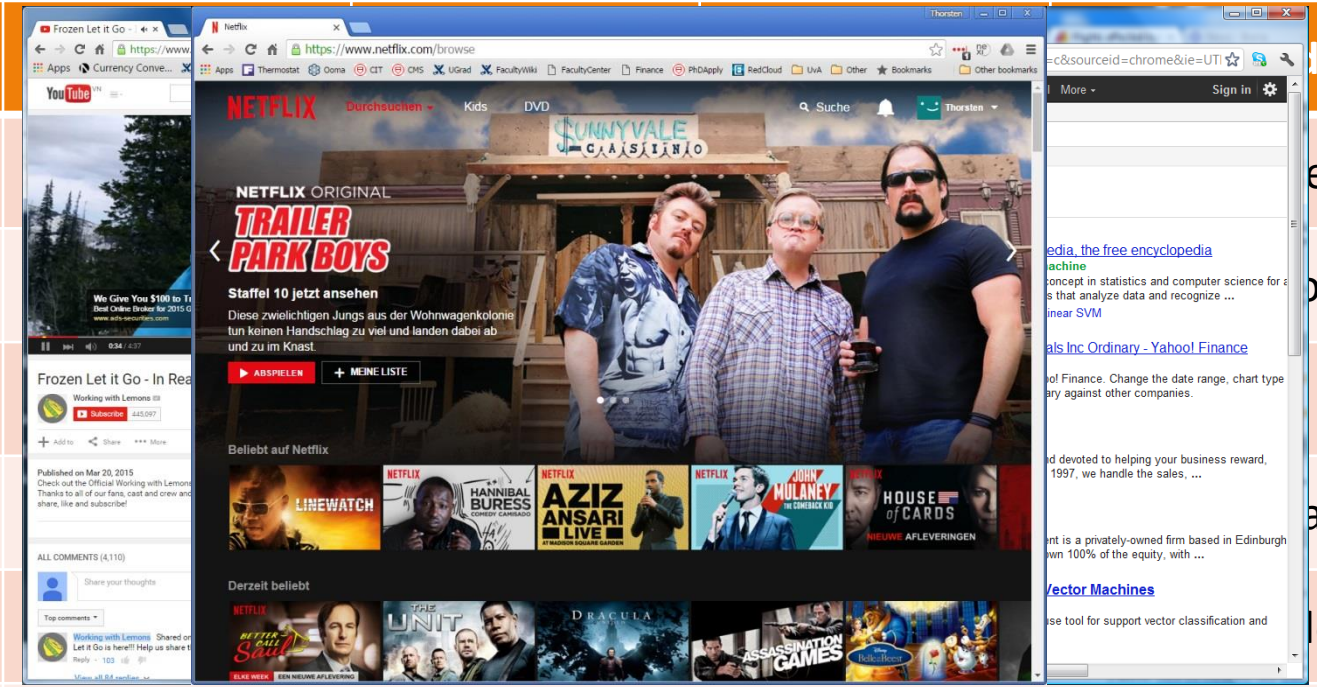
- Policy (stochastic)
  - Context x_i describing patient
  - Pick treatment y based on x_i: $\pi(Y|x_i)$
- Note
  - Assignment Mechanism is a stochastic policy as well!
- Average Treatment Effect
  - $U(\pi) = \frac{1}{n}\sum_i \sum_y \delta(x_i, y)\pi(y|x_i)$
- IPS Estimator
  - $\widehat{U}(\pi) = \frac{1}{n}\sum_i \frac{\pi(y_i|x_i)}{p_i}\delta(x_i, y_i)$



Counterfactual Model = Logs

Recorded in Log

Context x_i	
Treatment y_i	
Outcome δ_i	
Propensities p_i	
New Policy π	
T-effect $U(\pi)$	Average quality of new policy.



Evaluation: Outline

- Evaluating Online Metrics Offline
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System Evaluation via Inverse Propensity Score Weighting

Definition [IPS Utility Estimator]:
Given $S = \big((x_1, y_1, \delta_1), \dots, (x_n, y_n, \delta_n)\big)$ collected under π_0,

$$\widehat{U}_{ips}(\pi) = \frac{1}{n} \sum_{i=1}^{n} \delta_i \frac{\pi(y_i|x_i)}{\pi_0(y_i|x_i)}$$

Propensity p_i

→ Unbiased estimate of utility for any π, if propensity nonzero whenever $\pi(y_i|x_i) > 0$.

Note:

If $\pi = \pi_0$, then online A/B Test with $\widehat{U}_{ips}(\pi_0) = \frac{1}{n} \sum_i \delta_i$

→ Off-policy vs. On-policy estimation.

[Horvitz & Thompson, 1952] [Rubin, 1983] [Zadrozny et al., 2003] [Li et al., 2011]

Illustration of IPS

IPS Estimator:

$$\widehat{U}_{IPS}(\pi) = \frac{1}{n}\sum_i \frac{\pi(y_i|x_i)}{\pi_0(y_i|x_i)}\delta_i$$

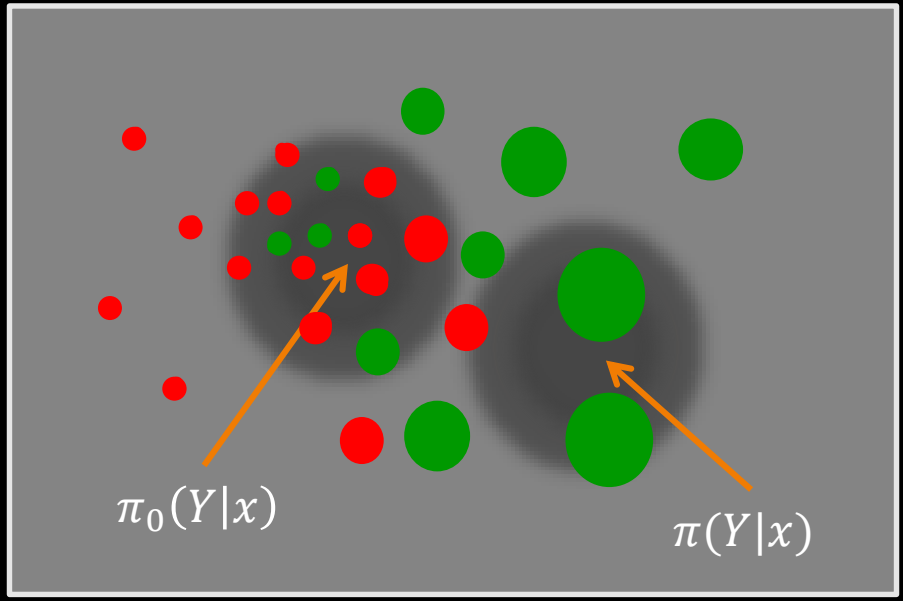
Unbiased:

If

$$\forall x, y: \pi(y|x)P(x) > 0 \rightarrow \pi_0(y|x) > 0$$

then

$$\mathrm{E}\left[\widehat{U}_{IPS}(\pi)\right] = U(\pi)$$



IPS Estimator is Unbiased

$$E\left[\widehat{U}_{IPS}(\pi)\right] = \frac{1}{n}\sum_{x_1,y_1}\dots\sum_{x_n,y_n}\left[\sum_i \frac{\pi(y_i|x_i)}{\pi_0(y_i|x_i)}\delta(x_i,y_i)\right]\pi_0(y_1|x_1)\dots\pi_0(y_n|x_n)P(x_1)\dots P(x_n)$$

independent

$$= \frac{1}{n}\sum_{x_1,y_1}\pi_0(y_1|x_1)P(x_1)\dots\sum_{x_n,y_n}\pi_0(y_n|x_n)P(x_n)\left[\sum_i \frac{\pi(y_i|x_i)}{\pi_0(y_i|x_i)}\delta(x_i,y_i)\right]$$

$$= \frac{1}{n}\sum_i\sum_{x_1,y_1}\pi_0(y_1|x_1)P(x_1)\dots\sum_{x_n,y_n}\pi_0(y_n|x_n)P(x_n)\left[\frac{\pi(y_i|x_i)}{\pi_0(y_i|x_i)}\delta(x_i,y_i)\right]$$

marginal

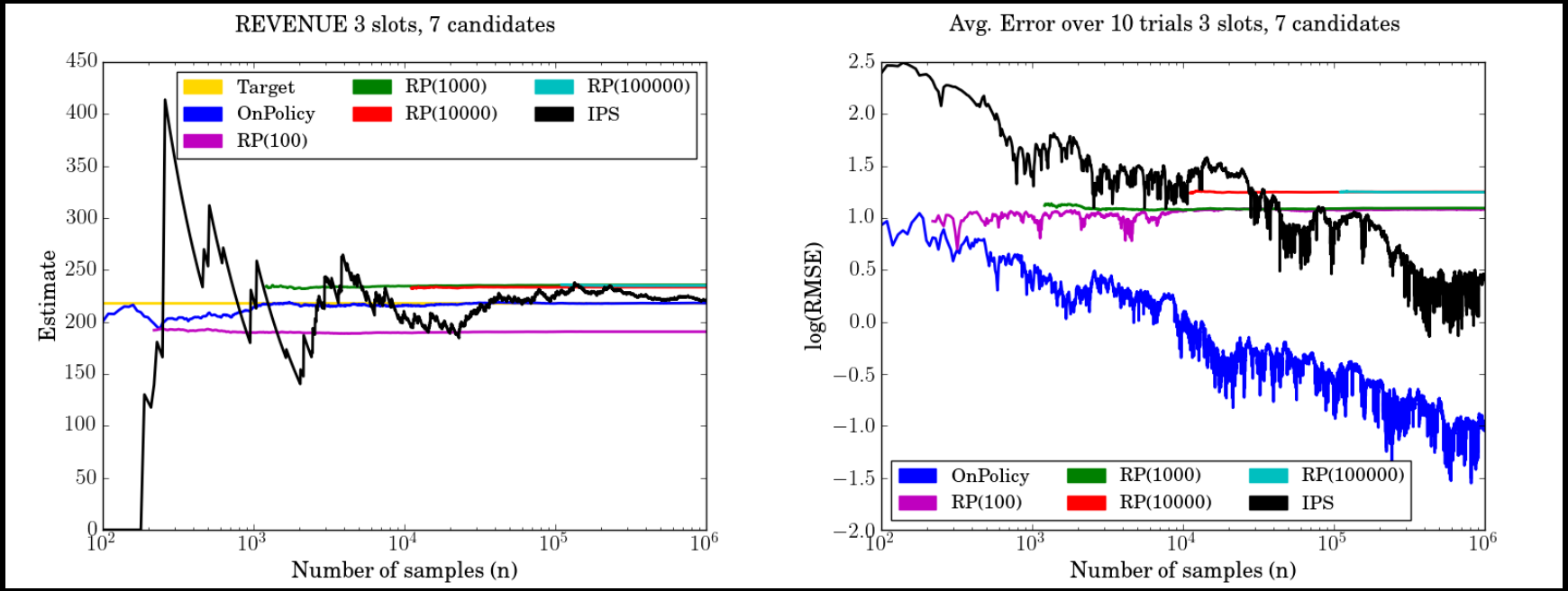
$$= \frac{1}{n}\sum_i\sum_{x_i,y_i}\pi_0(y_i|x_i)P(x_i)\left[\frac{\pi(y_i|x_i)}{\pi_0(y_i|x_i)}\delta(x_i,y_i)\right]$$

full support

$$= \frac{1}{n}\sum_i\sum_{x_i,y_i}P(x_i)\pi(y_i|x_i)\delta(x_i,y_i) = \frac{1}{n}\sum_i \mathrm{U}(\pi) = U(\pi)$$

identical x,y

News Recommender: Results



IPS eventually beats RP; variance decays as $O\left(\frac{1}{\sqrt{n}}\right)$

Counterfactual Policy Evaluation

- Controlled Experiment Setting:
  - Log data: $D = \big((x_1, y_1, \delta_1, p_1), \dots, (x_n, y_n, \delta_n, p_n)\big)$
- Observational Setting:
  - Log data: $D = \big((x_1, y_1, \delta_1, z_1), \dots, (x_n, y_n, \delta_n, z_n)\big)$
  - Estimate propensities: $p_i = P(y_i|x_i, z_i)$ based on x_i and other confounders z_i

→ Goal: Estimate average treatment effect of new policy π.

- IPS Estimator

$$\widehat{U}(\pi) = \frac{1}{n}\sum_i \delta_i \frac{\pi(y_i|x_i)}{p_i}$$

or many others.

Evaluation: Summary

- Offline Evaluation of Online Metrics
  - A/B Testing (on-policy)
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- Approach 1: “Model the world”
  - Estimation via reward prediction
  - Pro: low variance
  - Con: model mismatch can lead to high bias
- Approach 2: “Model the bias”
  - Counterfactual Model
  - Inverse propensity scoring (IPS) estimator
  - Pro: unbiased for known propensities
  - Con: large variance

From Evaluation to Learning

- Naïve "Model the World" Learning:
  - Learn: $\hat{\delta}: x \times y \rightarrow \Re$
  - Derive Policy:

$$\pi(y|x) = \underset{y'}{\operatorname{argmin}}\left[\hat{\delta}(x, y')\right]$$

- Naïve "Model the Bias" Learning:
  - Find policy that optimizes IPS training error

$$\pi = \underset{\pi'}{\operatorname{argmin}}\left[\sum_i \frac{\pi'(y_i|x_i)}{\pi_0(y_i|x_i)}\delta_i\right]$$