

# Structured Output Prediction: Generative Models

CS6780 – Advanced Machine Learning  
Spring 2015

Thorsten Joachims  
Cornell University

Reading:  
Murphy 17.3 , 17.4, 17.5.1

# Structured Output Prediction

- Supervised Learning from Examples
  - Find function from input space  $X$  to output space  $Y$

$$h: X \rightarrow Y$$

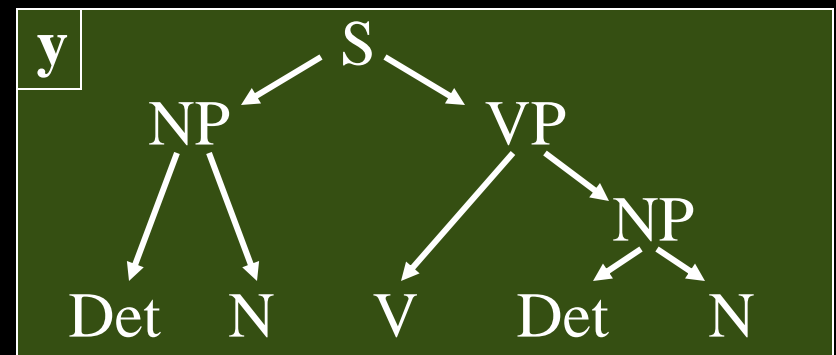
such that the prediction error is low.

- Typical
  - Output space is just a single number
    - Classification: -1,+1
    - Regression: some real number
- General
  - Predict outputs that are complex objects

# Examples of Complex Output Spaces

- Natural Language Parsing
  - Given a sequence of words  $x$ , predict the parse tree  $y$ .
  - Dependencies from structural constraints, since  $y$  has to be a tree.

$x$  The dog chased the cat



# Examples of Complex Output Spaces

- Multi-Label Classification

- Given a (bag-of-words) document  $x$ , predict a set of labels  $y$ .
- Dependencies between labels from correlations between labels (“iraq” and “oil” in newswire corpus)

**x** Due to the continued violence in Baghdad, the oil price is expected to further increase. OPEC officials met with ...

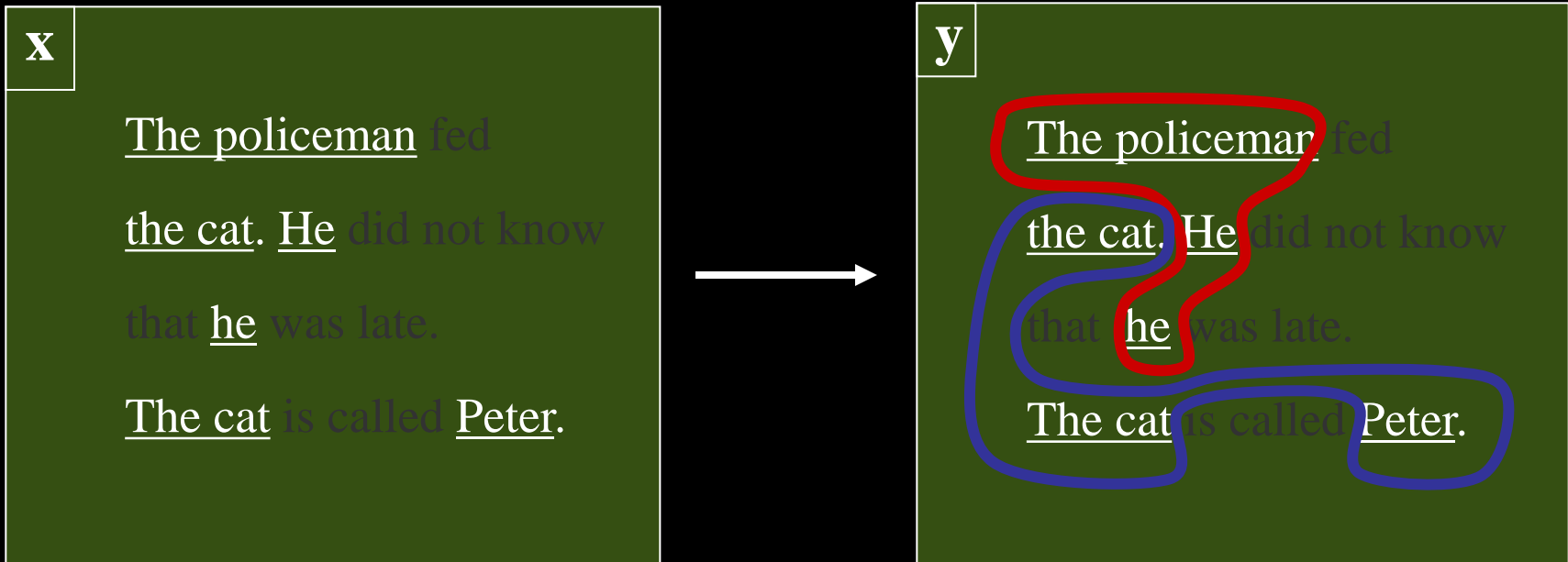


**y**

-1	antarctica
-1	benelux
-1	germany
+1	iraq
+1	oil
-1	coal
-1	trade
-1	acquisitions

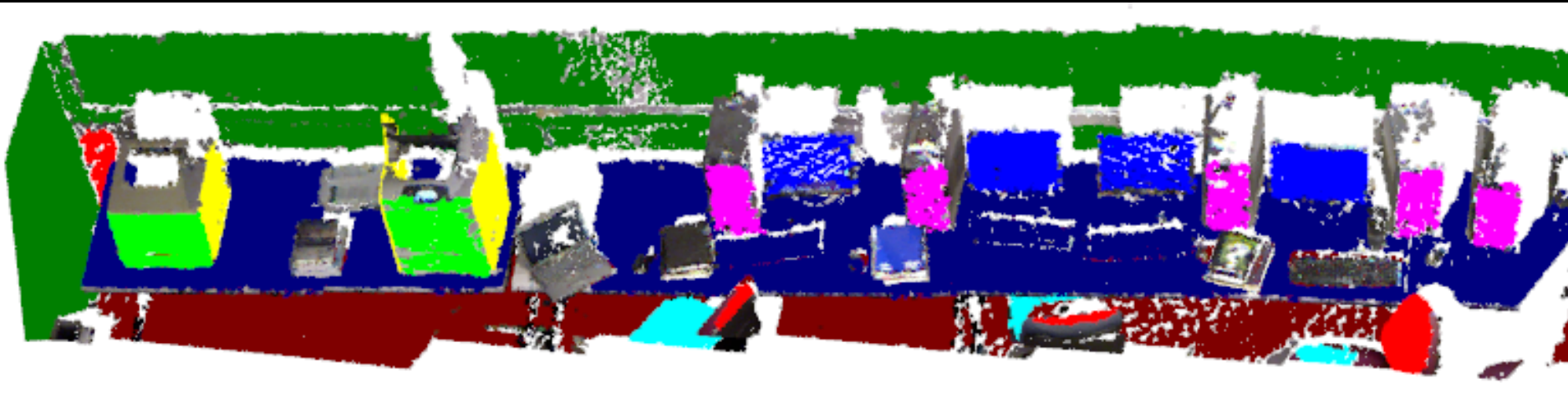
# Examples of Complex Output Spaces

- Noun-Phrase Co-reference
  - Given a set of noun phrases  $x$ , predict a clustering  $y$ .
  - Structural dependencies, since prediction has to be an equivalence relation.
  - Correlation dependencies from interactions.



# Examples of Complex Output Spaces

- Scene Recognition
  - Given a 3D point cloud with RGB from Kinect camera
  - Segment into volumes
  - Geometric dependencies between segments (e.g. monitor usually close to keyboard)



# Part-of-Speech Tagging Task

- Assign the correct part of speech (word class) to each word in a document

“The/DT planet/NN Jupiter/NNP and/CC its/PRP moons/NNS are/VBP in/IN effect/NN a/DT mini-solar/JJ system/NN ,/, and/CC Jupiter/NNP itself/PRP is/VBZ often/RB called/VBN a/DT star/NN that/IN never/RB caught/VBN fire/NN ./.”

- Needed as an initial processing step for a number of language technology applications
  - Information extraction
  - Answer extraction in QA
  - Base step in identifying syntactic phrases for IR systems
  - Critical for word-sense disambiguation (WordNet apps)
  - ...

# Why is POS Tagging Hard?

- Ambiguity
  - He will **race**/VB the car.
  - When will the **race**/NN end?
  - I **bank**/VB at CFCU.
  - Go to the **bank**/NN!
- Average of ~2 parts of speech for each word
  - The number of tags used by different systems varies a lot. Some systems use < 20 tags, while others use > 400.



# The POS Learning Problem

- Example

sentence	POS
$\bar{x}_1 = (I, bank, at, CFCU)$	$\bar{y}_1 = (PRP, V, PREP, N)$
$\bar{x}_2 = (Go, to, the, bank)$	$\bar{y}_2 = (V, PREP, DET, N)$

# Markov Model

- Definition
  - Set of States:  $s_1, \dots, s_k$
  - Start probabilities:  $P(S_1=s)$
  - Transition probabilities:  $P(S_i=s \mid S_{i-1}=s')$
- Random walk on graph
  - Start in state  $s$  with probability  $P(S_1=s)$
  - Move to next state with probability  $P(S_i=s \mid S_{i-1}=s')$
- Assumptions
  - Limited dependence: Next state depends only on previous state, but no other state (i.e. first order Markov model)
  - Stationary:  $P(S_i=s \mid S_{i-1}=s')$  is the same for all  $i$

# Hidden Markov Model for POS Tagging

- States
  - Think about as nodes of a graph
  - One for each POS tag
  - special start state (and maybe end state)
- Transitions
  - Think about as directed edges in a graph
  - Edges have transition probabilities
- Output
  - Each state also produces a word of the sequence
  - Sentence is generated by a walk through the graph

# Hidden Markov Model

- States:  $y \in \{s_1, \dots, s_k\}$
  - Outputs symbols:  $x \in \{o_1, \dots, o_m\}$
  - Starting probability  $P(Y_1 = y_1)$ 
    - Specifies where the sequence starts
  - Transition probability  $P(Y_i = y_i \mid Y_{i-1} = y_{i-1})$ 
    - Probability that one states succeeds another
  - Output/Emission probability  $P(X_i = x_i \mid Y_i = y_i)$ 
    - Probability that word is generated in this state
- => Every output+state sequence has a probability

$$\begin{aligned} P(x, y) &= P(x_1, \dots, x_l, y_1, \dots, y_l) \\ &= P(y_1)P(x_1|y_1) \prod_{i=2}^l P(x_i|y_i)P(y_i|y_{i-1}) \end{aligned}$$

# Estimating the Probabilities

- Fully observed data:
  - input/output sequence pairs

$$P(Y_i = a | Y_{i-1} = b) = \frac{\text{\# of times state } a \text{ follows state } b}{\text{\# of times state } b \text{ occurs}}$$

$$P(X_i = a | Y_i = b) = \frac{\text{\# of times output } a \text{ is observed in state } b}{\text{\# of times state } b \text{ occurs}}$$

- Smoothing the estimates:
    - See Naïve Bayes for text classification
- Partially observed data ( $Y_i$  unknown):
  - Expectation-Maximization (EM)

# HMM Prediction (Decoding)

Question: What is the most likely state sequence given an output sequence?

$$\begin{aligned} y^* &= \operatorname{argmax}_{y \in \{y_1, \dots, y_l\}} P(x_1, \dots, x_l, y_1, \dots, y_l) \\ &= \operatorname{argmax}_{y \in \{y_1, \dots, y_l\}} \left\{ P(y_1) P(x_1 | y_1) \prod_{i=2}^l P(x_i | y_i) P(y_i | y_{i-1}) \right\} \end{aligned}$$

# Going on a trip

- Deal: trip to any 3 cities in  
Germany -> Italy -> Spain  
for one low low price



# Going on a trip

- Deal: trip to any 3 cities in  
Germany -> Italy -> Spain  
for one low low price

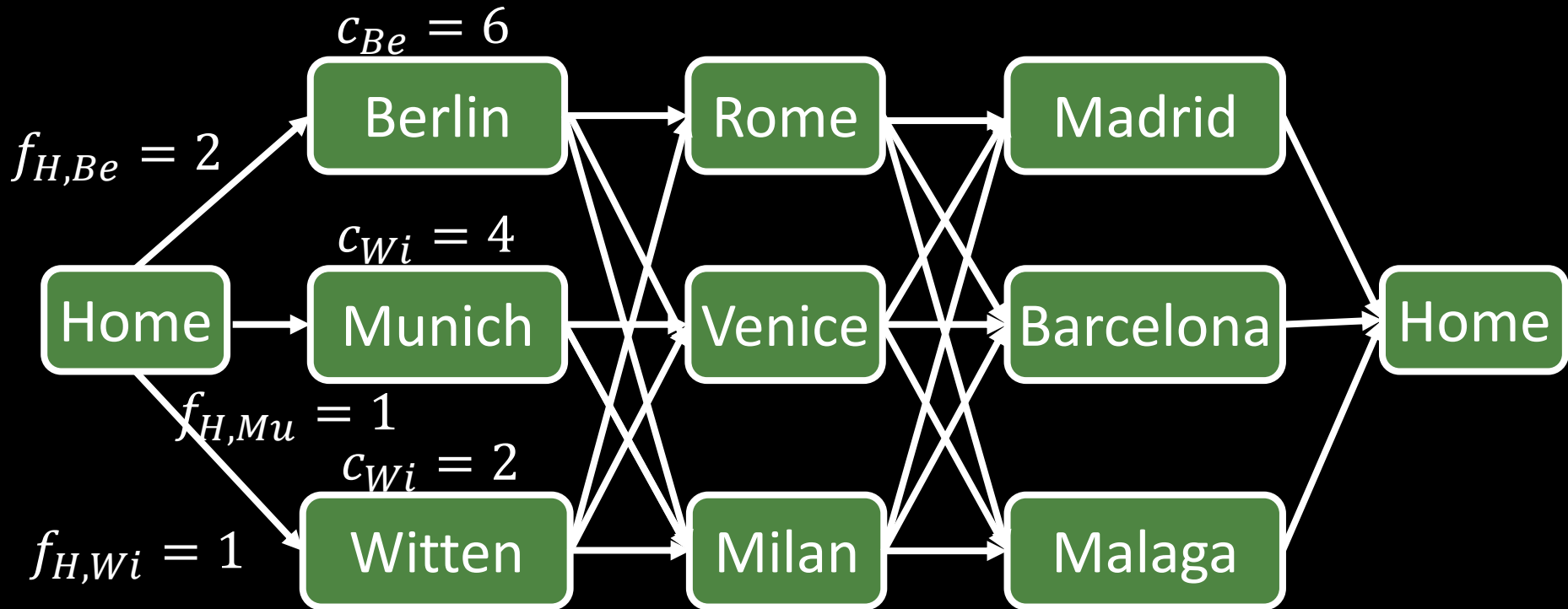
Country	City options
Germany	Berlin/Munich/Witten
Italy	Rome/Venice/Milan
Spain	Madrid/Barcelona/Malaga



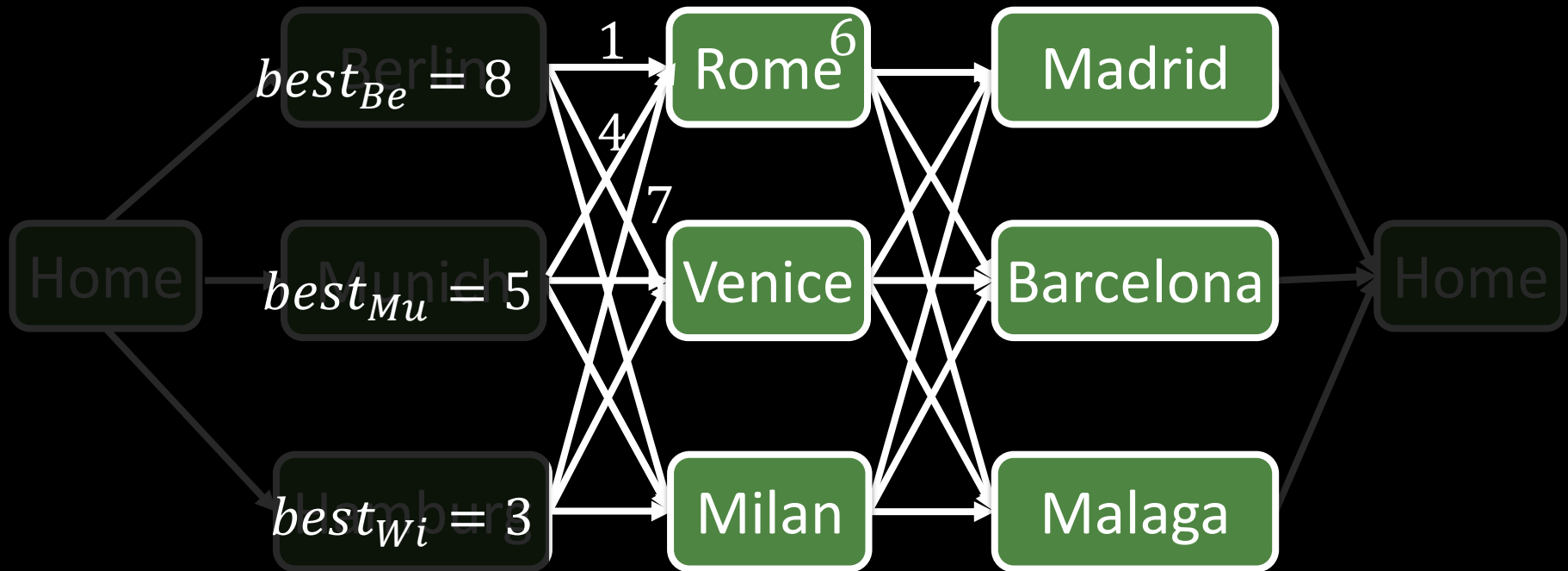
# Going on a trip

- Deal:
  - Each city  $i$  has an attractiveness score  $c_i \in [0, 10]$
  - Each flight has an comfort score  $f_{i,j} \in [0, 10]$
  
- Find the best trip!

# Going on a trip



# Going on a trip



# Going on a trip



# Viterbi Algorithm for Decoding

- Efficiently compute most likely sequence

$$\hat{y} = \operatorname{argmax}_{y \in \{y_1, \dots, y_l\}} \left\{ P(y_1)P(x_1|y_1) \prod_{i=2}^l P(x_i|y_i)P(y_i|y_{i-1}) \right\}$$

- Viterbi Algorithm:

$$\delta_y(1) = P(Y_1 = y)P(X_1 = x_1|Y_1 = y)$$

$$\delta_y(i+1) = \max_{v \in \{s_1, \dots, s_k\}} \delta_v(i)P(Y_{i+1} = y|Y_i = v)P(X_{i+1} = x_{i+1}|Y_{i+1} = y)$$

# Viterbi Example

$P(X_i Y_i)$	I	bank	at	CFCU	go	to	the
DET	0.01	0.01	0.01	0.01	0.01	0.01	0.94
PRP	0.94	0.01	0.01	0.01	0.01	0.01	0.01
N	0.01	0.4	0.01	0.4	0.16	0.01	0.01
PREP	0.01	0.01	0.48	0.01	0.01	0.47	0.01
V	0.01	0.4	0.01	0.01	0.55	0.01	0.01

$P(Y_1)$	
DET	0.3
PRP	0.3
N	0.1
PREP	0.1
V	0.2

$P(Y_i Y_{i-1})$	DET	PRP	N	PREP	V
DET	0.01	0.01	0.96	0.01	0.01
PRP	0.01	0.01	0.01	0.2	0.77
N	0.01	0.2	0.3	0.3	0.19
PREP	0.3	0.2	0.3	0.19	0.01
V	0.2	0.19	0.3	0.3	0.01