Impossibility of Distributed Consensus with One Faulty Process

The Weakest Failure Detector for Solving Consensus

October 22, 2015

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- Validity : If all processes start with the same input value v, then the correct processes decide v

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 Asynchronous processing : A process can take arbitrarily long to execute its next step

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- Asynchronous processing : A process can take arbitrarily long to execute its next step
- Crash failures : A process cannot detect the failure of another process
- Every message is eventually delivered, but can take arbitrarily long to reach or delivered out of order

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- Event : (p, m). Denotes the receipt of message m (possibly Φ) by p.

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Theorem

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Theorem There is no consensus protocol that can tolerate the failure of one process

What does impossibility mean? Any consensus protocol that respects validity and agreement conditions, must have a possible run, in which no correct process terminates.

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Scenario 1:

Scenario 1:

p₁ starts with input 0

Scenario 1:

- p₁ starts with input 0
- p₂ fails without executing any step

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p1 decides 0 and terminates

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p1 decides 0 and terminates

Scenario 2:

Scenario 1:

- p₁ starts with input 0
- p₂ fails without executing any step
- p1 decides 0 and terminates

Scenario 2:

p1 fails without executing any step

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Scenario 1:

- p₁ starts with input 0
- p₂ fails without executing any step
- p1 decides 0 and terminates

Scenario 2:

p1 fails without executing any step

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p₂ starts with input 1

Scenario 1:

- p₁ starts with input 0
- p₂ fails without executing any step
- p1 decides 0 and terminates

Scenario 2:

p1 fails without executing any step

- p₂ starts with input 1
- p₂ decides 1 and terminates

Scenario 1:

- p₁ starts with input 0
- p₂ fails without executing any step
- p1 decides 0 and terminates

Scenario 2:

p1 fails without executing any step

- p₂ starts with input 1
- p₂ decides 1 and terminates

Scenario 3:

Scenario 1:

- p₁ starts with input 0
- p₂ fails without executing any step
- p1 decides 0 and terminates

Scenario 2:

- p1 fails without executing any step
- p₂ starts with input 1
- p₂ decides 1 and terminates

Scenario 3:

p₁ starts with 0 and p₂ stars with 1
Intuition : 2 process case

Scenario 1:

- p₁ starts with input 0
- p₂ fails without executing any step
- p1 decides 0 and terminates

Scenario 2:

- p1 fails without executing any step
- p₂ starts with input 1
- p₂ decides 1 and terminates

Scenario 3:

- p₁ starts with 0 and p₂ stars with 1
- Messages take a long time to reach, so p₁'s and p₂'s view of the system is same as Scenario 1 and 2, resp.

Intuition : 2 process case

Scenario 1:

- p₁ starts with input 0
- p₂ fails without executing any step
- p1 decides 0 and terminates

Scenario 2:

- p1 fails without executing any step
- p₂ starts with input 1
- p₂ decides 1 and terminates

Scenario 3:

- p₁ starts with 0 and p₂ stars with 1
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• p_1 decides 0 and p_2 decides 1

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The proof proceeds by contradiction. Suppose an algorithm P exists that solves consensus despite one failure

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▶ We show that *P* has a bivalent initial configuration

The proof proceeds by contradiction. Suppose an algorithm P exists that solves consensus despite one failure

- ▶ We show that *P* has a bivalent initial configuration
- Then we show that from every bivalent configuration, a possible sequence of events can again result in a bivalent configuration

There exists a bivalent initial configuration of P

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There exists a bivalent initial configuration of P Suppose not.

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There exists a bivalent initial configuration of PSuppose not.Initial configuration (0, 0, ..., 0 is 0-valent while (1, 1, ..., 1 is 1-valent.)

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Suppose not.Initial configuration (0, 0, ..., 0 is 0-valent while (1, 1, ..., 1 is 1-valent. Take a path

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Take a path

(0, 0, 0, ..., 0), (1, 0, 0, ..., 0), (1, 1, 0, ..., 0), ..., (1, 1, 1, ..., 1)There exists two adjacent configurations in the path that are of

different valency. And they differ in the input value of only one process i

Now construct a run where *i* crashes without taking any steps.

Then, processes < i decide on 0 and process > i decide on 1.

Let C be a bivalent configuration and e = (p, m) be an event applicable to C. Then, there exists a bivalent configuration reachable from C in which e has been applied.

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- Look for relaxation in the model or make extra assumptions

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One approach : Every process has access to a local failure detector module

- Even if there is no "perfect" protocol, cases when processes do not terminate may be rare
- Look for relaxation in the model or make extra assumptions

One approach : Every process has access to a local failure detector module

The module need not be perfect. It can suspect a correct process to have failed or not suspect a failed process

Strong Completeness : There is a time after which every process that crashes is suspected by all correct processes

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► A failure detector that suspects all the processes is complete

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- ► A failure detector that suspects all the processes is complete
- A failure detector that never suspects any process is accurate

- ► A failure detector that suspects all the processes is complete
- ► A failure detector that never suspects any process is accurate And both of these are useless!

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 [Weak Completeness] : After some time, every process that crashes is suspected by some correct process

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- [Weak Completeness] : After some time, every process that crashes is suspected by some correct process
- [Eventual Weak Accuracy] : After some time, some correct process is never suspected by any correct process

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These are examples of eventually forever properties : Properties that forever hold true after some finite amount of time

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What do we mean by the "weakest" failure detector?

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Theorem W is the weakest failure detector that solves consensus

What do we mean by the "weakest" failure detector? Any failure detector that solves consensus with n > 2f can emulate $\diamond W$

Every process sends "I am alive" messages periodically

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Works well in practice, but does not guarantee $\diamond W$

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 Proceeds in rounds. Each round has a coordinator that rotates among the set of processes

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Otherwise, the algorithm enters the next round

Instead of emulating $\diamond W$, we show that any failure detector can emulate Ω (defined below) which can in turn emulate $\diamond W$

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A failure detector $\boldsymbol{\Omega}$ satisfies the following properties :

Its output at a process p is a single process q that p trusts to be correct at that time

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- There is a time after which all correct processes trust the same correct process
- ► Easy to see that Ω is at least as strong as ◊W
- An emulator for ◊W using Ω outputs the set of processes that are not trusted in Ω

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 Every process maintains a DAG which models a causal relation between queries to the failure detector

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- After process q adds a node (p, d, k), all nodes corresponding to future queries of q to its failure detector take an edge from (p, d, k)
- Processes exchange and update their graphs
- A finite subgraph of this graph contains the node that every process should trust

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- We need to relax constraints that make extra assumptions about the system to solve consensus
- ▷ ◊W solves consensus algorithm by assuming weak properties about the failure detection module
- It is the weakest failure detection module using which we can solve consensus