

April 16, 2020

Last time: graph convolutional networks

$$\left(\overset{n}{\square} \overset{\hat{A}}{A}, \overset{n}{\square} \overset{\hat{d}}{F} \right) \xrightarrow{f} \overset{n}{\square} \overset{k}{X} \xrightarrow{g} \overset{n}{\square} \overset{1}{\hat{Y}} \xrightarrow{\ell} (\hat{Y}_H, Q_H)$$

$$\hat{Y} = \begin{bmatrix} \hat{Y}_H \\ \hat{Y}_u \end{bmatrix}$$

predictions on unlabeled nodes

Smoothed features:

ith column $x_i \approx \underset{z}{\operatorname{argmin}} f(z) + \lambda \|z - f\|_2^2$

$$z^T L z \quad z^T N z \quad z^T (I - P) z$$

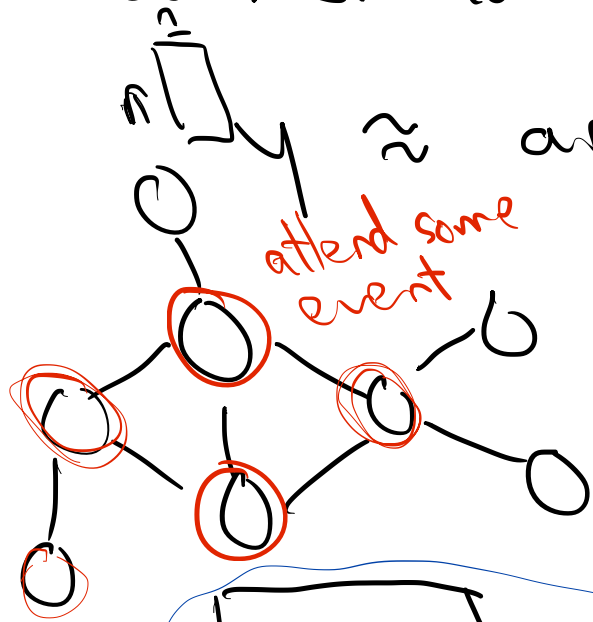
Each GD steps:

$$x_i^{(t+1)} \approx \underbrace{\left[\alpha P + (1 - \alpha) I \right]}_M x_i^{(t)}$$

$$X^{(t+1)} \approx M X^{(t)} \xRightarrow{\text{GCN}} X^{(t+1)} = \sigma(M X^{(t)} W^{(t)} + b^{(t)})$$

$W^{(t)}, b^{(t)}$ couples embedding and prediction task

Smoothed labels



attend some event

location, history, etc.

$$\approx \arg \min_z f(z) + \lambda \left\| \begin{pmatrix} y_H \\ y_u \end{pmatrix} - \begin{pmatrix} l_H \\ 0 \end{pmatrix} \right\|_2^2$$

seems like we should be using the label

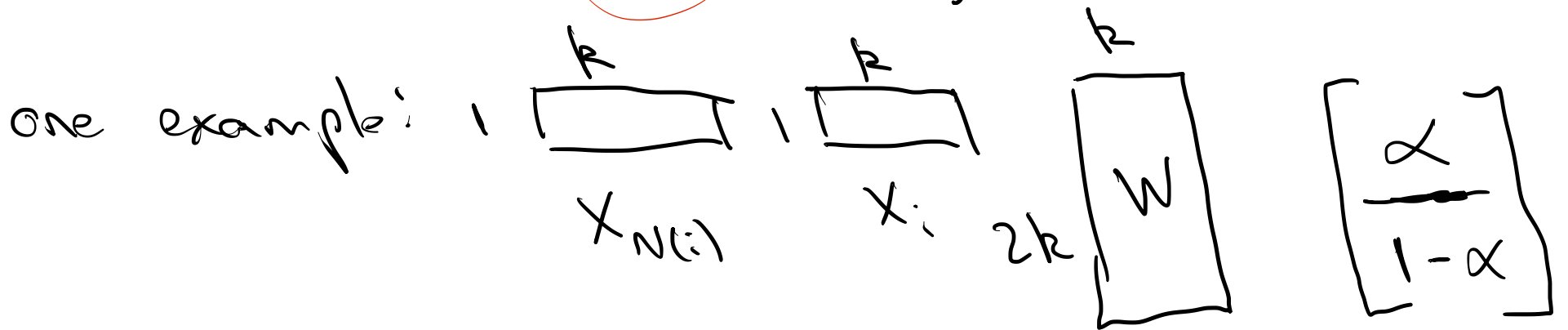
$$\left(\tilde{A}, \tilde{F}, \overset{\sim}{\begin{pmatrix} l_H \\ 0 \end{pmatrix}} \right) \text{ label as input feature!}$$

$$X^{(t+1)} = M X^{(t)} = [\alpha P + (1-\alpha)I] X^{(t)}$$

i^{th} row $X_i^{(t+1)}$ = α $\left[\frac{1}{d_i} \sum_{(i,j) \in E} X_j^{(t)} \right]$ + $(1-\alpha) X_i^{(t)}$

next rep. average of neighbors $P = D^{-1}A$ row stochastic
current rep.

$$X_i^{(t+1)} = \phi \left(X_{N(i)}^{(t)}, X_i^{(t)} \right)$$



$$X^{(t+1)} = \sigma \left(n \left[\begin{array}{c} P X^{(t)} \\ X^{(t)} \end{array} \right] W^{(t)} \right)$$

$\underbrace{P X^{(t)}}_{X_{N(i)}^{(t)}}$

$\left[\begin{array}{c} 1 \\ 1 \\ \vdots \\ 1 \end{array} \right] \left[\begin{array}{c} b^{(t)} \\ \vdots \\ b^{(t)} \end{array} \right]$

i-th row: $P X^{(t)} = \frac{1}{d_i} \sum_{(i,j) \in E} X_j^{(t)} = X_{N(i)}^{(t)}$

GraphSAGE (Hamilton et al. 2017)

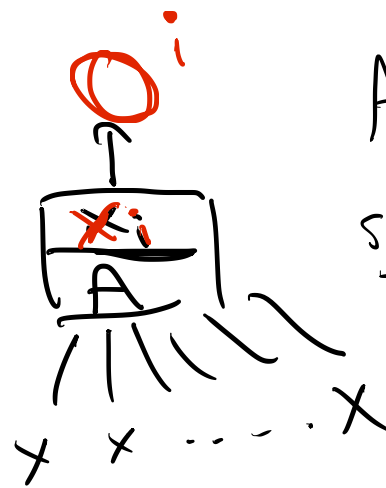
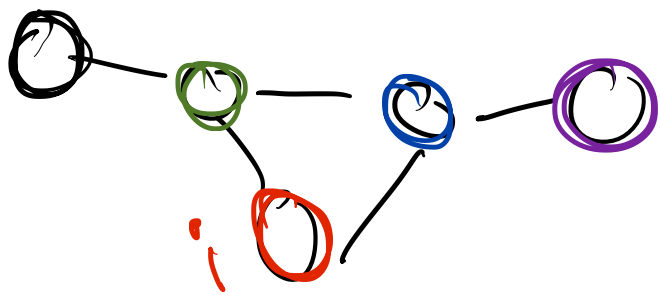
Idea: think of other "aggregation" methods

$$X_{N(i)}^{(t+1)} = \frac{1}{d_i} \sum_{(i,j)} X_j^{(t)} \quad (\text{mean})$$

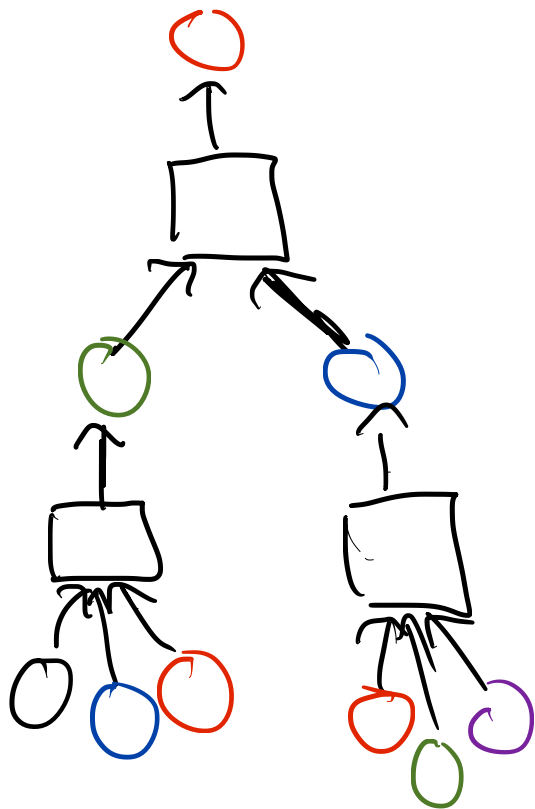
$$X_{N(i)}^{(t+1)} = \frac{1}{\sqrt{d_i}} \sum_{(i,j)} X_j^{(t)} / \sqrt{d_j}$$

$$X_{N(i)}^{(t+1)} = \max \left\{ \sum_{j \in N(i)} X_j^{(t)} \right\} \quad (\text{max-pooling})$$

entry-wise

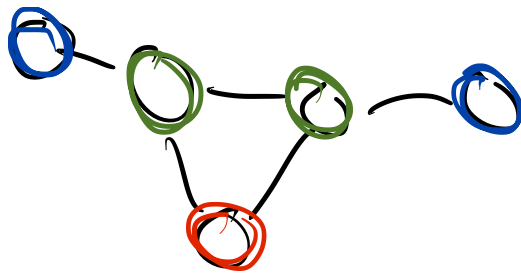


A: aggregation
set function



Extreme case:

all nodes had same features
 \Rightarrow learn nothing



Augment features?
degree?

combine with spectral, node/edge cost?

Types of problems:

- (1) clustering / node predict
- (2) link prediction

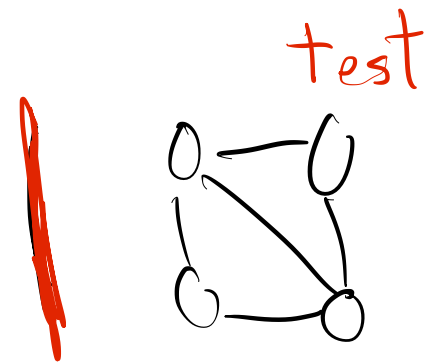
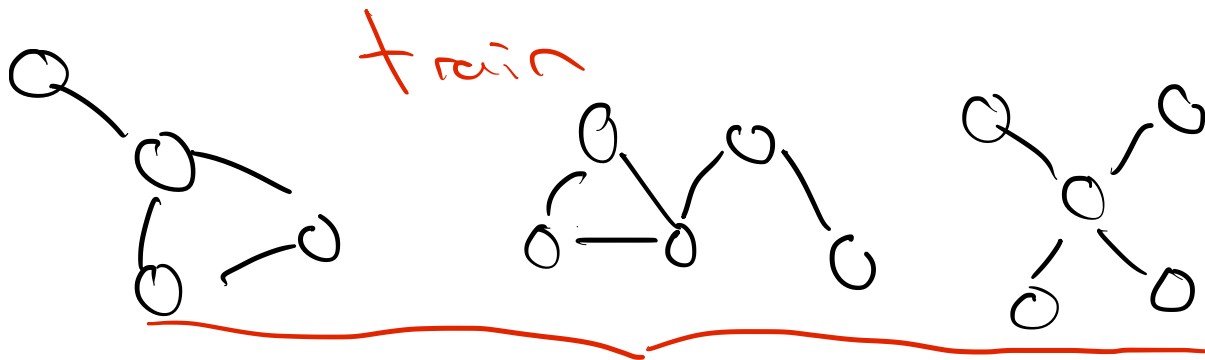
Might want to do this across graphs

PPI graphs : predict function, links

- different tissues
- different species

Traffic networks: predict flow

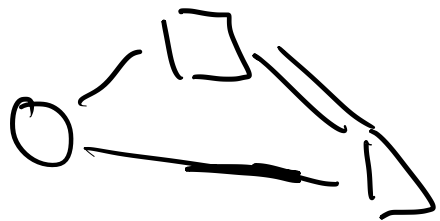
- different days, locations



one big graph, disjoint components

Another task: graph classification

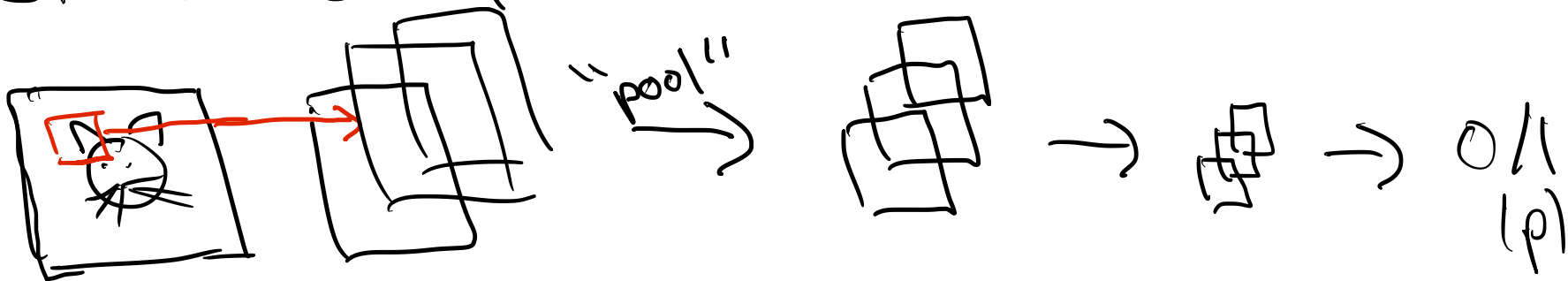
Molecular graphs:

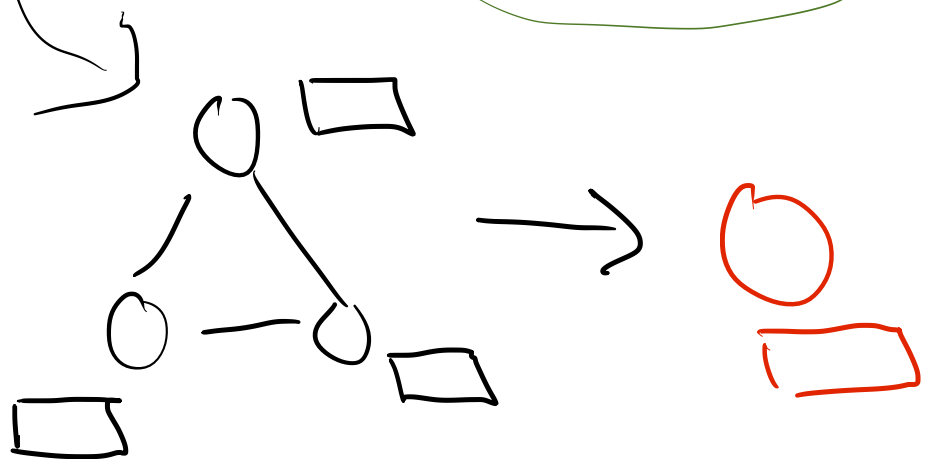
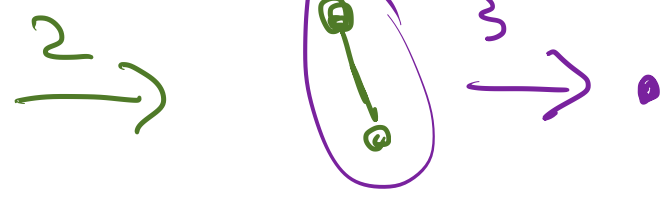
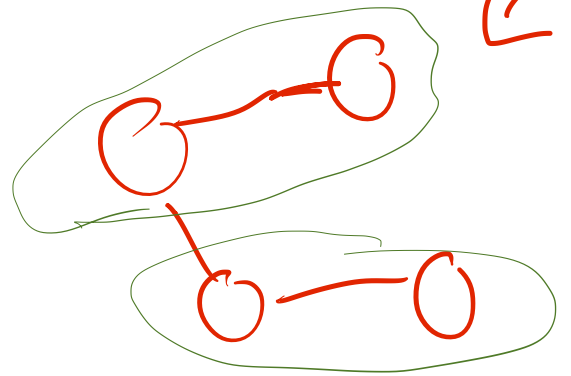
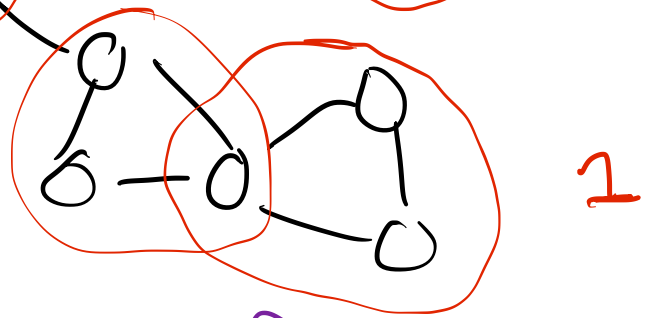
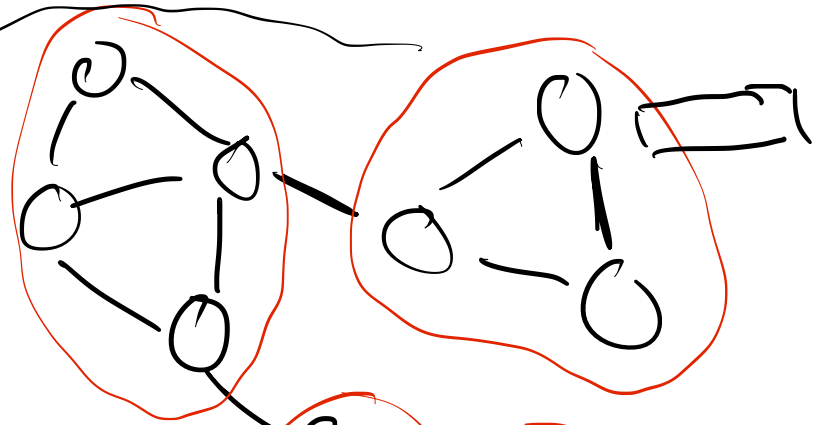
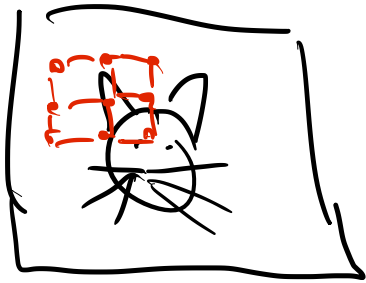


taste good?
effective drug?

$$\left\{ \left(\tilde{A}, \tilde{F} \right) \right\}_i \rightarrow \{0/1\}_i (p)$$

Bruna et al. (2014)





Apply some "filters"
(learn from data)
then pool

$$\left(\overset{n}{\square} \overset{p}{A}, \overset{n}{\square} \overset{d}{F} \right) \xrightarrow{F} \overset{n}{\square} \overset{k}{X} \xrightarrow{\text{pool}} z^T \Rightarrow \text{logit}(z^T \beta)$$

Idea: pool rows of X

Set function $\{x_i\} \rightarrow z$

$$z = \frac{1}{n} \sum x_i$$

$z = \max(\{x_i\})$ entrywise

$$z \overset{k}{\square} \overset{1}{\square}$$