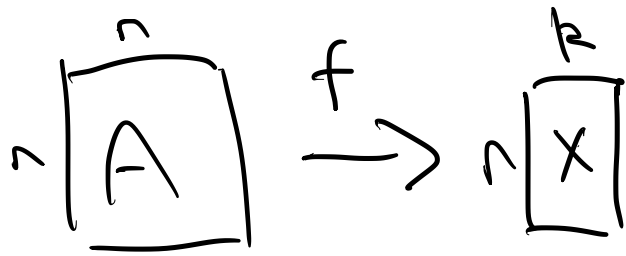


April 14, 2026

Last time: "representation" learning on graphs



- generative modeling
- data interpretation / vis
- "downstream" ML tasks

① Clustering / node prediction \rightarrow unsupervised \rightarrow semi-supervised

$$\begin{matrix} k \\ \boxed{\begin{matrix} X_H \\ X_U \end{matrix}} = X \end{matrix}$$

Ex: gender protein function

$$\min_z \|X_H z - y\|_2^2 + \text{regularization } \|z\|_2^2$$

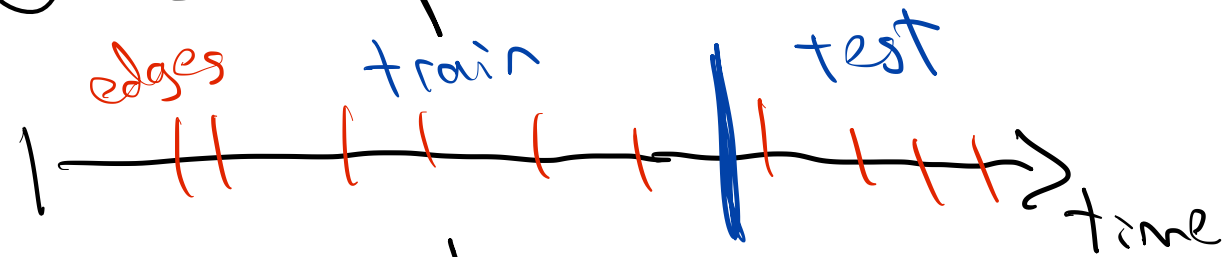
$$\Pr(y=1 | x) = \frac{1}{1 + \exp(-z^T x)}$$

$$z^* \quad X_U z^*$$

$$\max_z \prod_{h \in H} \Pr(y_h | z, x_h)$$

Ex: age
page views
traffic flow

② Link prediction / recommendation Ex:



friend rec FB/Twitter
co-purchase
co-view

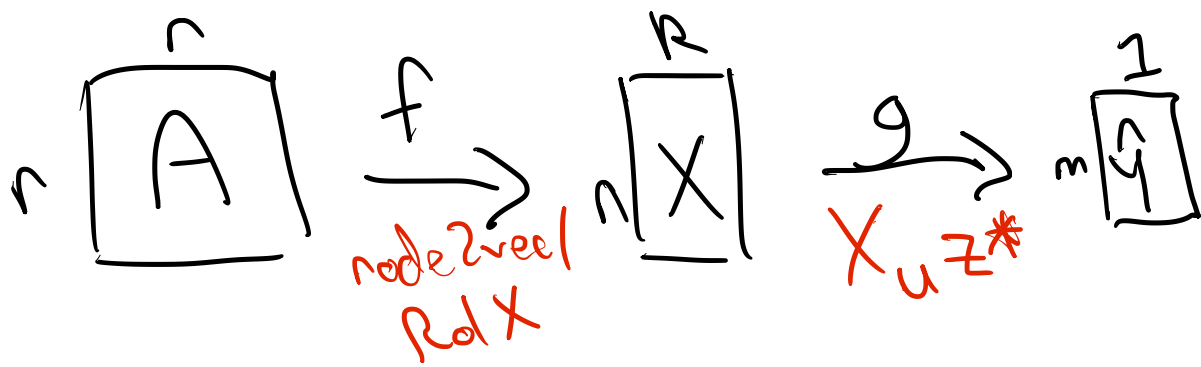
$$n \times n \begin{bmatrix} A \end{bmatrix} \rightarrow n \times k \begin{bmatrix} X \end{bmatrix}$$

$$\Pr((i,j) \text{ forms edge}) = \frac{1}{1 + \exp(\|x_i - x_j\|_2^2)}$$

Test: (i,j) positive
 (k,l) negative (artificial)

$$\uparrow \\ = x_i^T x_j$$

\Rightarrow accuracy



web page views:
 text
 PageRank
 ;

traffic flow:
 sensors
 locations
 temporal

Latent space ✓
 Row X ✓
 node2vec: concatenate
 $n \times (X \parallel F)$

② Couple f, g , loss l

$$l \circ g \circ f(\hat{A}, \hat{F}) \rightarrow l(\hat{Y})$$

Ex:
 $\|\hat{Y} - Y_H\|_2^2$

So far: decoupled

$$\text{ReLU}(\hat{A}, \hat{F}) \rightarrow \hat{X}$$

$$\log(X) = \| \underbrace{X_H Z}_{g(X)} - Y_H \|_2^2$$

$$\hat{Y} = X_H Z^*$$

Latent space model

node 2 vee

implicitly defining log

- $\text{Pr}(i, j | x_i, x_j)$

- $\text{Pr}(N_S(i) | x_i)$

Enabled by systems

TensorFlow

PyTorch

Back to April 7...

min_x "unsmoothness" $f(x)$
 + "stay close to known labels"

$x^T L x$ $x^T N x$
 " $\sum_{(i,j) \in E} (x_i - x_j)^2$

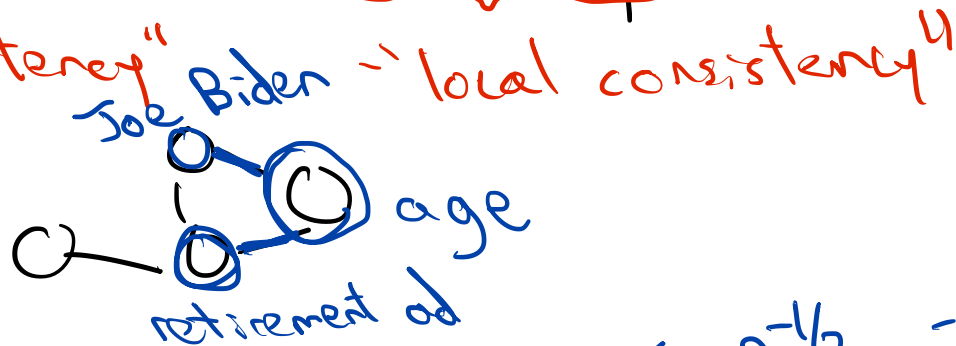
$\lambda \left\| \begin{pmatrix} x_H \\ x_U \end{pmatrix} - \begin{pmatrix} y_H \\ 0 \end{pmatrix} \right\|_2^2$

$x_i \Leftrightarrow$ node i

GD step size $\alpha < 1$, $\Sigma \lambda = \frac{1-\alpha}{\alpha}$, $x^T N x$

$x^{(t+1)} = \alpha \underbrace{(D^{-1/2} A D^{-1/2})}_{\text{"global consistency"}} x^{(t)} + \underbrace{(1-\alpha)y}_{\text{"local consistency"}}$

Set $y = F(:, i)$
 i -th feature



$x^{(t+1)} = \alpha \Sigma x^{(t)} + (1-\alpha) F$

$\Sigma = D^{-1/2} A D^{-1/2}$

$x^{(0)} = 0 \Rightarrow x^{(1)} = (1-\alpha) F$

$$X^{(2)} = \alpha S X^{(1)} + (1-\alpha)F = \alpha S X^{(1)} + X^{(1)}$$

$$= [\alpha S + I] X^{(1)} \quad [\alpha S + I] X^{(t)}$$

$$X^{(3)} = \alpha S X^{(2)} + (1-\alpha)F X^{(2)}$$

$$X^{(2)} = \bar{X}^{(2)}$$

$$X^{(1)} = \bar{X}^{(1)}$$

$$= [\alpha S + (1-\alpha)I] X^{(2)}$$

$$\bar{X}^{(t+1)} = [\alpha S + (1-\alpha)I] X^{(t)} \quad X^{(0)} = (1-\alpha)F$$

Embedding: $\bar{X}^{(3)}$

Started with $N = D^{-1/2} L D^{-1/2} = I - S$

Could use L , $D^{-1} L = \underbrace{I - P}$

$$\bar{X}^{(t+1)} = [\alpha P + (1-\alpha)I] \bar{X}^{(t)}$$

① no coupling b/w f, g, l

② $\bar{X}^{(t+1)} = [\alpha S + (1-\alpha)I] \bar{X}^{(t)} \quad t \rightarrow \infty?$

$$\tilde{X}_i^{(t)} = \bar{X}_i^{(t)} / \|\bar{X}_i^{(t)}\|_2 \quad (\text{per column})$$

$$x^{(t+1)} = \frac{Ax^{(t)}}{\|Ax^{(t)}\|_2} \quad \bar{X} \rightarrow [v_1, \dots, v_n]$$

$$\underline{\underline{\alpha = 1/2}}$$



$$X^{(0)} = \frac{1}{2} \mathbb{I}$$

$$X^{(1)} = \frac{1}{2} [S + \mathbb{I}] X^{(0)}$$

$$X^{(2)} = \frac{1}{2} M X^{(1)}$$

$$M = D^{-1/2} A D^{-1/2} + \mathbb{I}$$

$$\tilde{A} = A + \mathbb{I}$$

$$M = \tilde{D}^{-1/2} \tilde{A} \tilde{D}^{-1/2}$$

Graph convolutional network: (GCN)

$$X^{(t+1)} = \sigma \left(\frac{1}{2} M X^{(t)} W^{(t)} + b^{(t)} \right)$$

entrywise nonlinearity

$$\sigma(x) = \max(x, 0)$$

$$\sigma(x) = \tanh(x)$$

GCN (two "layers")

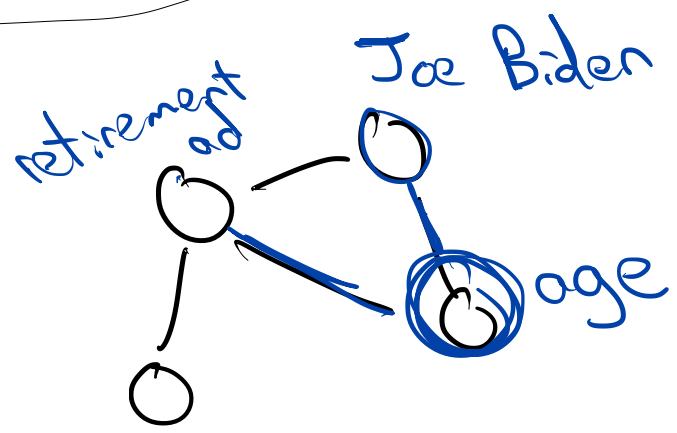
$$M_{(W^{(t)}, b^{(t)})}(X^{(t)}) = \sigma(\underbrace{M}_{S+I} X^{(t)} W^{(t)} + b^{(t)})$$

$D^{-1/2} A D^{-1/2} + I$

$$\hat{y} = M_{(W_1, b_1)}(M_{(W_0, b_0)}(F))$$

$\begin{matrix} \sim [F] \text{ features} \\ \sim Z \\ \sim [k] \\ X^{(0)} = F \end{matrix}$

min $\| \hat{y} - y \|_2^2$
 W_1, b_1, W_0, b_0



Why not use age as a feature itself?

$$X^{(1)} = \sigma(MFW^{(0)} + b^{(0)})$$

$$F = I \quad \hat{\square} \quad MFW^{(0)} = MW^{(0)}$$

learn embedding directly

What if no objective?

Make one up: example: link prediction

self-supervision

Neighborhood agg. embedding