

CS 6241: Numerical Methods for Data Science

01/22/2019

Numerical Methods:

- algo that we put on a computer to "solve a problem"
- usually involves floating point cont. math + discrete math (PageRank)

Data Science

• ??

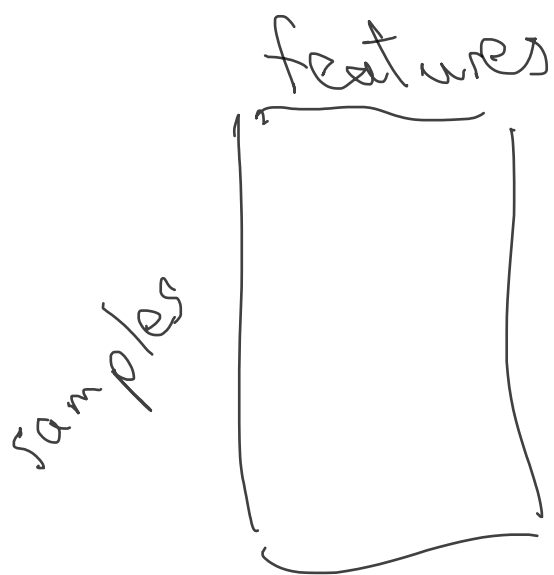
- analysis of some information that has already been collected

This class:

(1) Matrix (tensors)

(2) Network Science

Matrices



samples
users on FB

feats
friends
freq. of visits

prob
serve ads

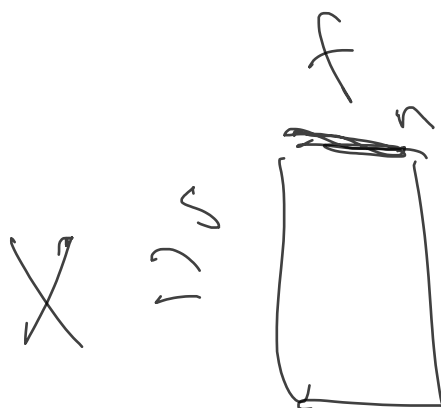
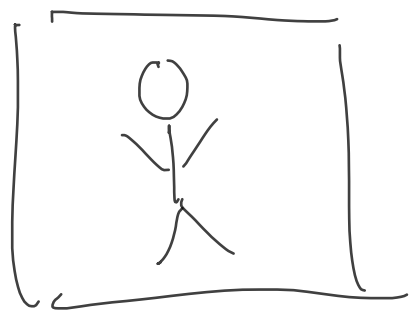
patients

prescriptions
corr. of prescr



sparse
↔
zero pattern
helps algos

image



$$\hat{z} = \frac{1}{n-1} \bar{X}^T \bar{X} \hat{z} = \bar{X}^T \left(\mathbf{I} - \frac{1}{n} \mathbf{1}\mathbf{1}^T \right) \hat{z}$$

Tensors are multi-dimensional array

(matrices are second-order tensors)



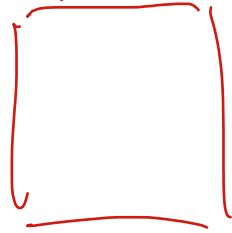
third-order tensor

hospital
time



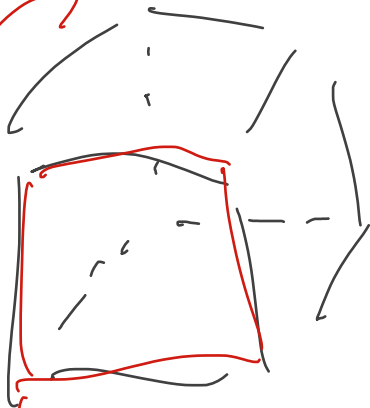
sample
x feature
x time

patient

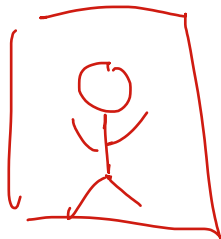


prescription

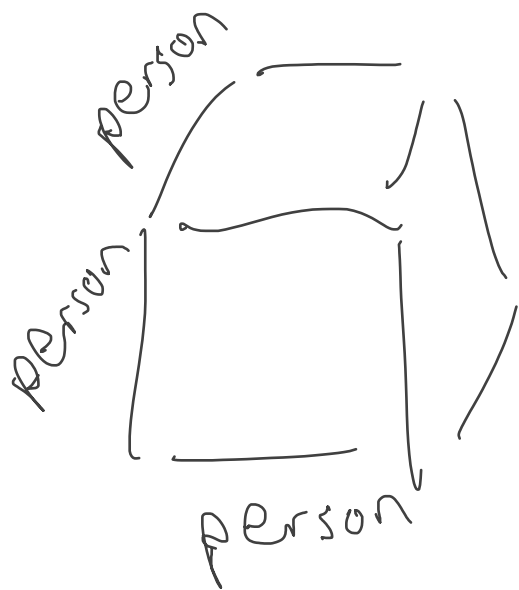
frame



movie
video



Social Network perception (David Krackhardt)



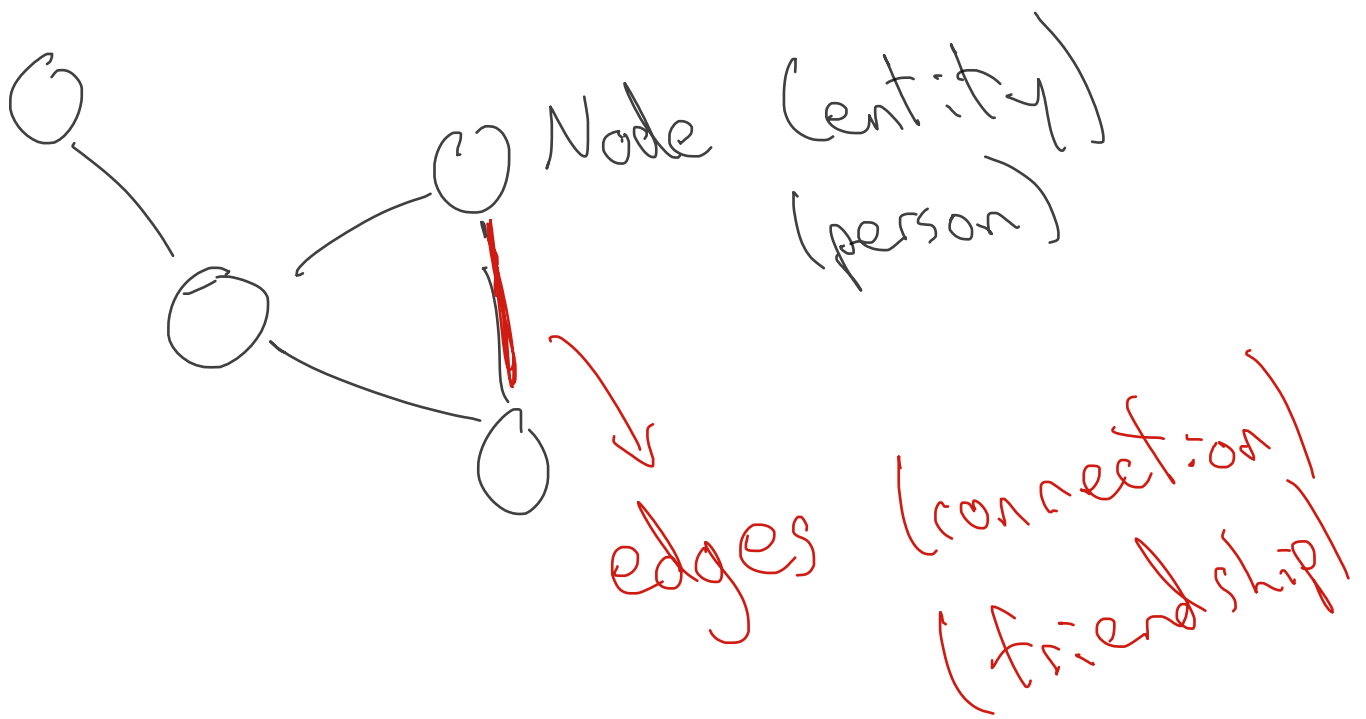
$A_{ijk} = \begin{cases} 1 & \text{person } k \\ & \text{thinks} \\ & \text{that} \\ & i \text{ \& } j \text{ are} \\ & \text{friends} \end{cases}$

0 or w

Network analysis / science

Applied graph theory

Example: social network
analysis



graphs \leftrightarrow networks

Ecology: nodes species
edges who-eats-whom

Roads: cities
highways

Citation papers
citations

Flight

airports
direct flights

Graph \Leftrightarrow Matrix

$$A_{ij} = \begin{cases} 1 & \text{if } i \text{ connects to } j \\ 0 & \text{otherwise} \end{cases}$$

A^R
 A_{ij}

Networks can also be represented

by tensors



$$A_{ijk} = \begin{cases} 1 & \text{if tags } i, j, k \text{ appear} \\ & \text{in a question} \\ 0 & \text{otherwise} \end{cases}$$

Administrivia

cs.cornell.edu / courses /
cs6241 /
2019sp

CMS, piazza

Coursemosk

teams
1, 2, 3

- 2 HWs (10% each)
- Reaction paper (20%)
- Project (60%)
 - proposal (15%)
 - progress report (15%)
 - final report (30%)

① math
② code
③ data analysis

Optimization

Nocebal +
Wright

$$\min f(x)$$

$$\text{subject to } x \in \Omega$$

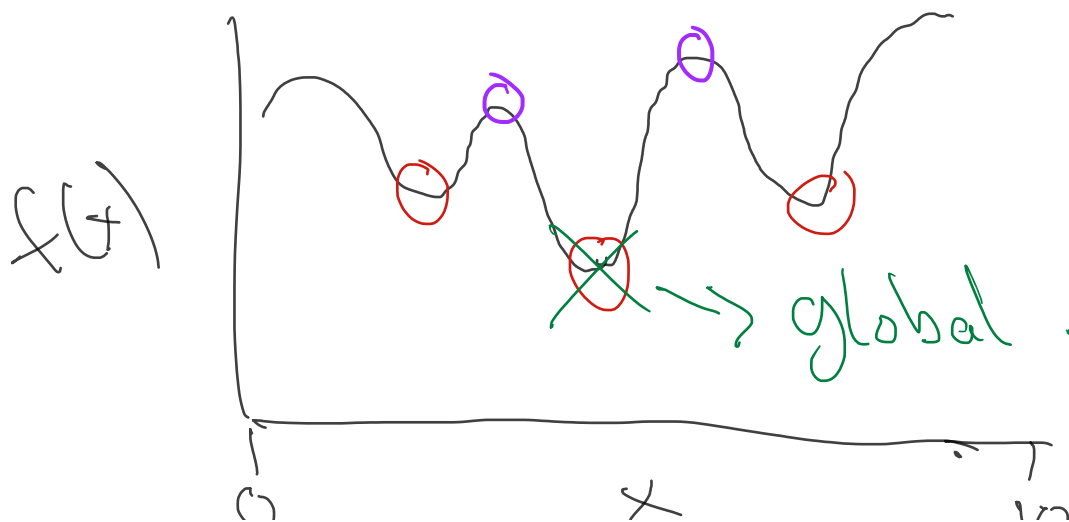
$$\Omega \subseteq \mathbb{R}^n$$

$$f: \mathbb{R}^n \rightarrow \mathbb{R}$$

f usually continuous

Ω nice in some way

$n=1$



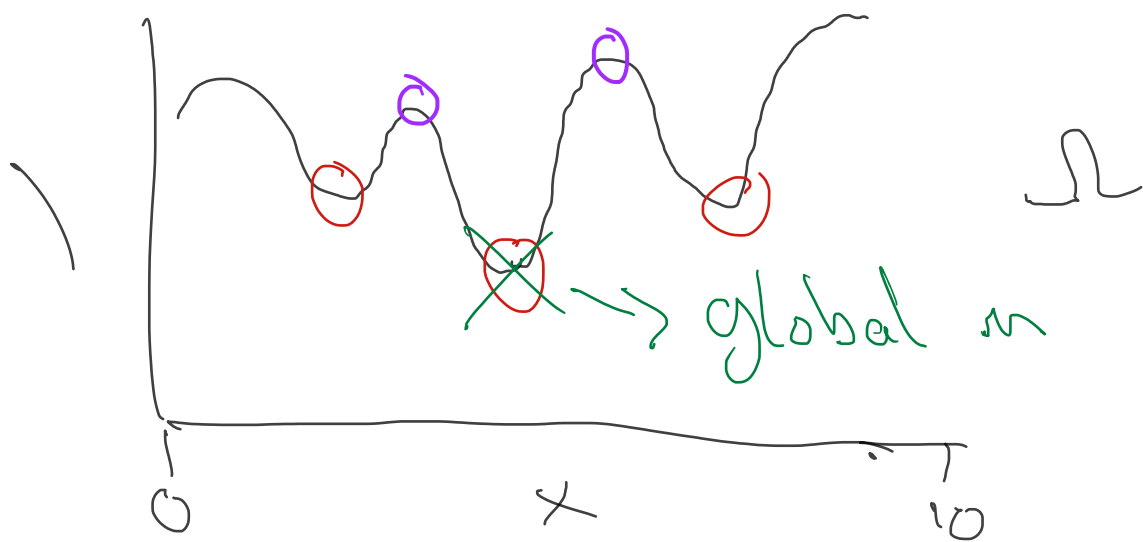
$$\Omega = [a, b]$$

global minimizer

How do we know we are
at a local minimizer x^* \circ

Necessary condition:
(unconstrained)

$$\nabla f(x^*) = 0$$



$H(x)$ = Hessian at x

$$[H(x)]_{ij} = \frac{\partial^2}{\partial x_i \partial x_j} f(x)$$

Suppose H is cont. near x^*

$$\nabla f(x^*) = 0$$

$H(x^*)$ positive def.

$$\forall y \quad y^T H(x^*) y > 0$$

then x^* is a local minimizer

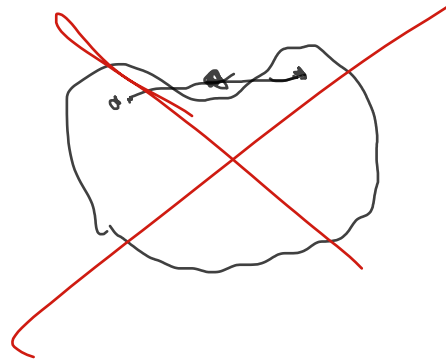
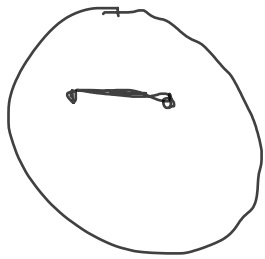
Structure: convexity

$$\min f(x)$$

$$\text{s.t. } x \in \Omega$$

convex if $\forall x, y \in \Omega, \alpha \in (0, 1)$

$$\alpha x + (1-\alpha)y \in \Omega$$



$$f(\alpha x + (1-\alpha)y) \leq \alpha f(x) + (1-\alpha)f(y)$$

Example: $\min \frac{1}{2} \|x\|_2^2$
 $\text{s.t. } Ax = b$

Convex \Rightarrow every local minimum
is a global minimum

Poly time global minimizers

- least squares (Thurs)
- linear programs
- SDPs

Doesn't always help! co positive
matrices

$$\Omega^0 = \left\{ M \in \mathbb{R}^{n \times n} \mid \begin{array}{l} x^T M x \geq 0, \\ x \geq 0 \end{array} \right\}$$

$$\begin{array}{ll} \min & \|M\|_F^2 \\ \text{s.t.} & M \in \Omega^0 \end{array}$$

Numerical Linear Algebra

notes on web site
Trefethen & Bau

① Norms $\|x\|_2$

② Eigenvalues $Ax = \lambda x$
 $\lambda \neq 0$

③ $Ax = b$
known

$$A \text{ sym} \Rightarrow A = V \Lambda V^T$$

$$V^T V = I \quad \left(\begin{array}{c} \downarrow \\ \text{---} \\ \downarrow \end{array} \right)$$

$$AV = \Lambda V$$

Any matrix A has SVD

$$A = U \Sigma V^T$$

$$U^T U = I = V^T V$$

$$\Sigma = \begin{pmatrix} \sigma_1 & & \\ & \ddots & \\ & & \sigma_n \\ & & & 0 \end{pmatrix} \quad \sigma_i \geq 0$$